ZEMING CHEN

☐ github.com/eric11eca Google Scholar chenz16@rose-hulman.edu

♀ 5500 Wabash Ave, Terre Haute, IN **८**(318)-560-4573

RESEARCH INTEREST

Broad: Natural Language Processing, Deep Learning, Computational Semantics

Specific: natural language understanding and reasoning, neural language model, few-shot and continual learning

commonsense reasoning, neural-symbolic inference

EDUCATION

Rose-Hulman Institute of Technology, Terre Haute

Sep 2018 - May 2022

Bachelor of Science in Computer Science & Mathematics

PUBLICATION

Probing Linguistic Information For Logical Inference In Pre-trained Language Models

Zeming Chen*, Qiyue Gao

36th AAAI Conference on Artificial Intelligence 2022 (Accepted)

NeuralLog: Natural Language Inference with Joint Neural and Logical Reasoning

Zeming Chen*, Qiyue Gao*, Lawrence S. Moss

10th Joint Conference on Lexical and Computational Semantics (*SEM) 2021, Association of Computational Linguistics

Monotonicity Marking from Universal Dependency Trees

Zeming Chen*, Qiyue Gao

14th International Conference on Computational Semantics (IWCS) 2021, Association of Computational Linguistics

Attentive Tree Network for Monotonicity Reasoning

Zeming Chen*

1st workshop on Natural Logic meets Machine Learning (NALOMA) 2020, Association of Computational Linguistics

AWARD

- IWCS 2021 Outstanding Paper Award
- Dean's List

RESEARCH EXPERIENCE

Indiana University June 2021 - Present

Advisor: Lawrence S. Moss

- · CURRICULUM: A broad-coverage benchmark and task augmentation suite for linguistic phenomena.
- Inference Information Probes: Methodology and datasets for probing linguistic information in contextualized embeddings.

Indiana University sep 2020 - May 2021

Advisor: Lawrence S. Moss

- NeuralLog: A neural-symbolic inference engine targeting syntactic variation.
- Udep2Mono: A system for automatic monotonicity polarity annotation.

WORK EXPERIENCE

Sunshine Import Export Inc

June 2019 - Sep 2019

Full-stack Software Consultant

- Developed and deployed an Enterprise Resources Planning system
- Built an enterprise-level product and user database

PROGRAMMING SKILLS

Programming: Python, C/C++, Java, JavaScript/Typescript, Lisp, SQL, HTML/CSS, C#

Software Tools & Libraries: Deep Learning: Pytorch, Tensorflow, Pytorch-lightning, Learn2Learn

NLP: Transformers, AllenNLP, JIANT, CoreNLP **Robotics:** ROS, OpenCV, LabView, MATLAB

Full Stack: Spring Boot, React JS, Angular, electron.js Database: MongoDB, Microsoft SQL Server, Neo4j, MySQL

OPEN-SOURCE PROJECTS

Automatic Social Distance Monitoring

Summer 2020

- Real-time pedestrian detection and social distance analyzing.
- C++, OpenCV, YOLOv3

RHIT Rover System

fall 2020 - Winter 2021

- Main software framework for RHTI mars rover.
- Control, simulation, navigation, perception, mapping & localization, communication
- ROS, Python, C++

SERVICE

AAAI Magazine 2021 2 reviews

TEACHING ASSISTANCE EXPERIENCE

CSSE 413 Artificial Intelligence Fall 2021
CSSE 374 Software Design Winter 2020

EXTRACURRICULAR

University Rover Challenge Team (Rose-Hulman)

sep 2018 - Present

Captain of Software Development

- Autonomous path planning and trajectory optimization
- Simultaneously Localization and Mapping (SLAM)
- Visual perception with OpenCV
- Robotic software design and development with ROS