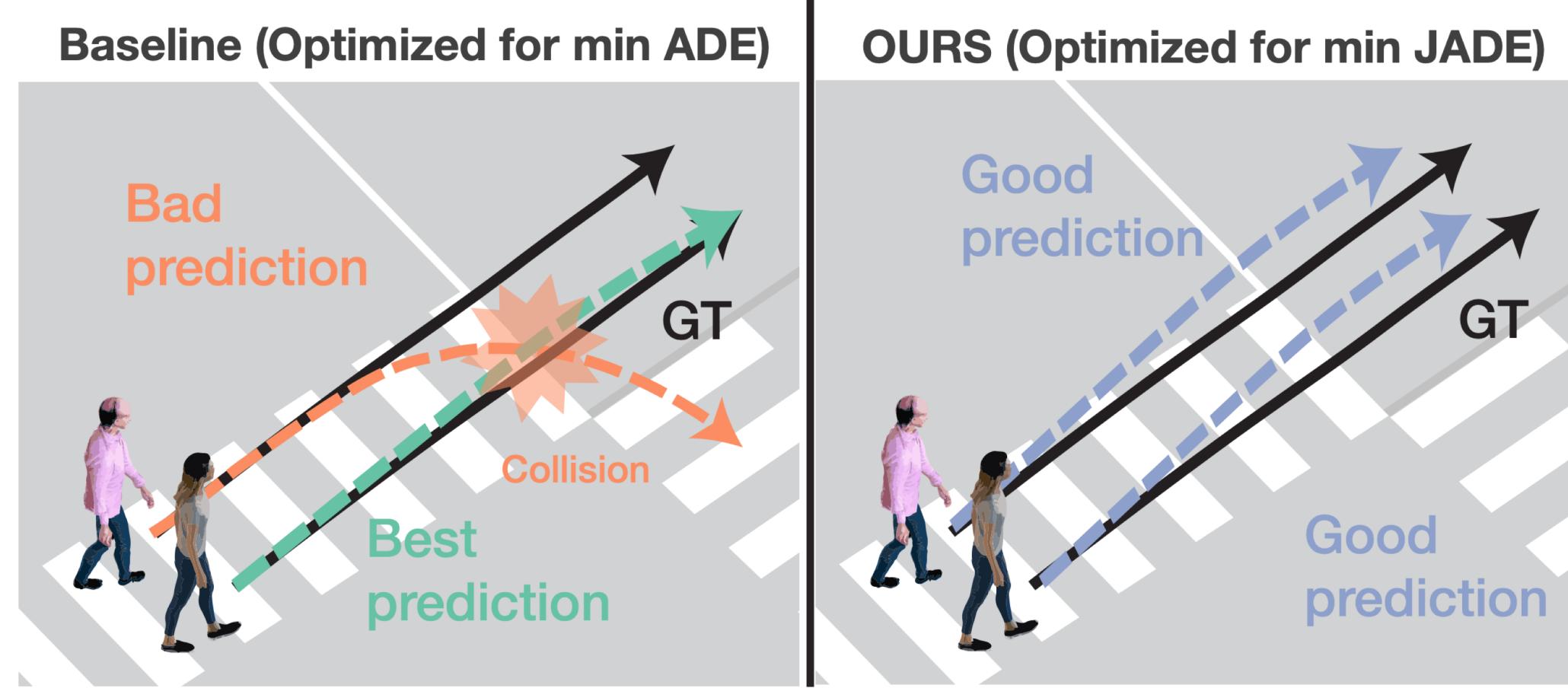


Joint Metrics Matter: A Better Standard for Trajectory Forecasting

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Motivation



- SOTA trajectory forecasting methods optimize wrt **marginal** metrics, resulting in optimal *per-agent* predictions but suboptimal **joint** multi-agent predictions
- We introduce a loss function addition based on **joint** metrics that can be applied to many forecasting methods, achieving **better multi-agent performance** and **lower collision rate**

Marginal vs. Joint Metrics

$$ADE(\mathbf{y}, \mathbf{y}^*) = \frac{1}{TN} \sum_{n=1}^N \min_{k=1}^K \sum_{t=1}^T \left\| \mathbf{y}_{t,n}^{(k)} - \mathbf{y}_{t,n}^* \right\|_2^2$$

$$JADE(\mathbf{y}, \mathbf{y}^*) = \frac{1}{TN} \min_{k=1}^K \sum_{n=1}^N \sum_{t=1}^T \left\| \mathbf{y}_{t,n}^{(k)} - \mathbf{y}_{t,n}^* \right\|_2^2$$

$$FDE(\mathbf{y}, \mathbf{y}^*) = \frac{1}{N} \sum_{n=1}^N \min_{k=1}^K \left\| \mathbf{y}_{T,n}^{(k)} - \mathbf{y}_{T,n}^* \right\|_2^2$$

$$JFDE(\mathbf{y}, \mathbf{y}^*) = \frac{1}{N} \min_{k=1}^K \sum_{n=1}^N \left\| \mathbf{y}_{T,n}^{(k)} - \mathbf{y}_{T,n}^* \right\|_2^2$$

Loss Modification

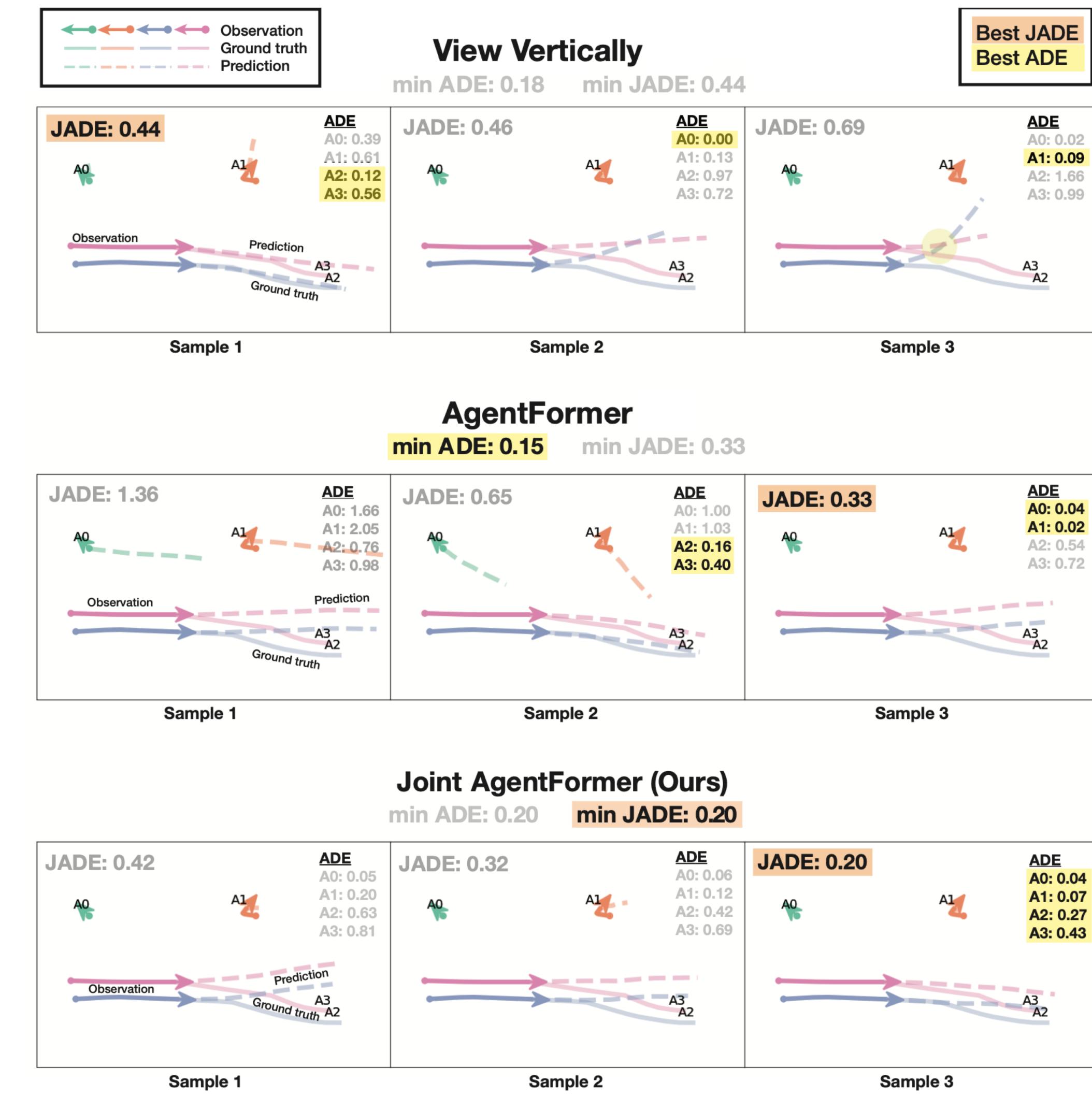
$$\begin{aligned} \mathcal{L}_{elbo} &= \sum_n \left\| \mathbf{y}_n^{(0)} - \mathbf{y}^* \right\|^2 + \sum_n \min_{k=1}^K \left\| \mathbf{y}_n^{(k)} - \mathbf{y}_n^* \right\|^2 \\ &+ KL(q_\phi(\mathbf{z}|\mathbf{y}, \mathbf{x}) || p_\theta(\mathbf{z}|\mathbf{x})) + \min_{k=1}^K \sum_n \left\| \mathbf{y}_n^{(k)} - \mathbf{y}_n^* \right\|^2 \end{aligned}$$

AgentFormer

$$\begin{aligned} \mathcal{L}_{coarse} &= \frac{1}{N_{way} N_{agents}} \sum_n^K \min_{m=1}^{N_{way}} \left\| \mathbf{y}_{m,n}^{(k)} - \mathbf{y}_{m,n}^* \right\|^2 \\ &+ \omega \cdot \frac{1}{N_{way} N_{agents}} \sum_n^K \min_{m=1}^{N_{way}} \sum_{m=1}^{N_{way}} \left\| \mathbf{y}_{m,n}^{(k)} - \mathbf{y}_{m,n}^* \right\|^2 \end{aligned}$$

Better Joint Predictions

Dataset (mean # peds) →	min JADE ₂₀ /JFDE ₂₀ ↓ (m), K = 20 samples						
	ETH (1.4)	HOTEL (2.7)	UNIV (25.7)	ZARA1 (3.3)	ZARA2 (5.9)	ETH / UCY Avg.	SDD TrajNet (1.5)
S-GAN	0.919 / 1.742	0.480 / 0.950	0.744 / 1.573	0.438 / 1.001	0.362 / 0.794	0.589 / 1.12	13.76 / 24.84
Trajectron++	0.726 / 1.299	0.237 / 0.418	0.609 / 1.316	0.359 / 0.712	0.294 / 0.625	0.445 / 0.874	11.36 / 18.21
PECNet	0.618 / 1.097	0.291 / 0.587	0.666 / 1.417	0.408 / 0.896	0.372 / 0.840	0.471 / 0.967	10.82 / 19.48
Y-Net	0.495 / 0.781	0.205 / 0.386	0.695 / 1.559	0.487 / 1.045	0.492 / 1.101	0.475 / 0.974	9.67 / 16.01
MemoNet	0.499 / 0.859	0.222 / 0.416	0.686 / 1.466	0.349 / 0.723	0.385 / 0.864	0.428 / 0.866	9.59 / 16.43
View Vertically	0.561 / 0.776	0.196 / 0.332	0.654 / 1.307	0.328 / 0.654	0.298 / 0.602	0.408 / 0.734	10.75 / 17.45
Joint View Vertically (Ours)	0.652 / 0.839	0.186 / 0.309	0.523 / 1.091	0.331 / 0.634	0.267 / 0.547	0.392 / 0.684	10.92 / 17.70
AgentFormer	0.482 / 0.794	0.237 / 0.456	0.622 / 1.310	0.285 / 0.564	0.296 / 0.624	0.384 / 0.749	9.67 / 16.92
Joint AgentFormer (Ours)	0.485 / 0.798	0.186 / 0.320	0.590 / 1.219	0.271 / 0.513	0.252 / 0.509	0.357 / 0.672	9.56 / 16.59



Fewer Predicted Collisions

Dataset (mean # peds) →	CR _{mean} /CR _{JADE} ↓ (m), K = 20 samples						
	ETH (1.4)	HOTEL (2.7)	UNIV (25.7)	ZARA1 (3.3)	ZARA2 (5.9)	ETH / UCY Avg.	SDD TrajNet (1.5)
S-GAN	0.015 / 0.045	0.031 / 0.090	0.165 / 0.251	0.060 / 0.185	0.083 / 0.195	0.071 / 0.153	0.00 / 0.00
Trajectron++	0.025 / 0.137	0.044 / 0.271	0.281 / 0.489	0.088 / 0.466	0.126 / 0.456	0.113 / 0.364	0.00 / 0.00
PECNet	0.014 / 0.115	0.043 / 0.269	0.218 / 0.409	0.059 / 0.396	0.128 / 0.455	0.092 / 0.329	0.00 / 0.03
Y-Net	0.016 / 0.141	0.039 / 0.250	0.265 / 0.482	0.100 / 0.513	0.134 / 0.480	0.111 / 0.373	0.00 / 0.00
MemoNet	0.014 / 0.160	0.040 / 0.301	0.206 / 0.415	0.065 / 0.445	0.136 / 0.483	0.092 / 0.361	0.00 / 0.00
View Vertically	0.014 / 0.090	0.029 / 0.203	0.212 / 0.428	0.045 / 0.233	0.082 / 0.316	0.077 / 0.254	0.00 / 0.00
Joint View Vertically (Ours)	0.011 / 0.076	0.026 / 0.168	0.276 / 0.484	0.045 / 0.262	0.081 / 0.349	0.088 / 0.268	0.00 / 0.00
AgentFormer	0.016 / 0.068	0.022 / 0.084	0.204 / 0.362	0.021 / 0.088	0.054 / 0.139	0.063 / 0.148	0.00 / 0.00
Joint AgentFormer (Ours)	0.013 / 0.064	0.019 / 0.094	0.163 / 0.333	0.021 / 0.100	0.055 / 0.203	0.054 / 0.159	0.00 / 0.00
Ground Truth	0.000	0.001	0.021	0.000	0.002	0.005	0.00

