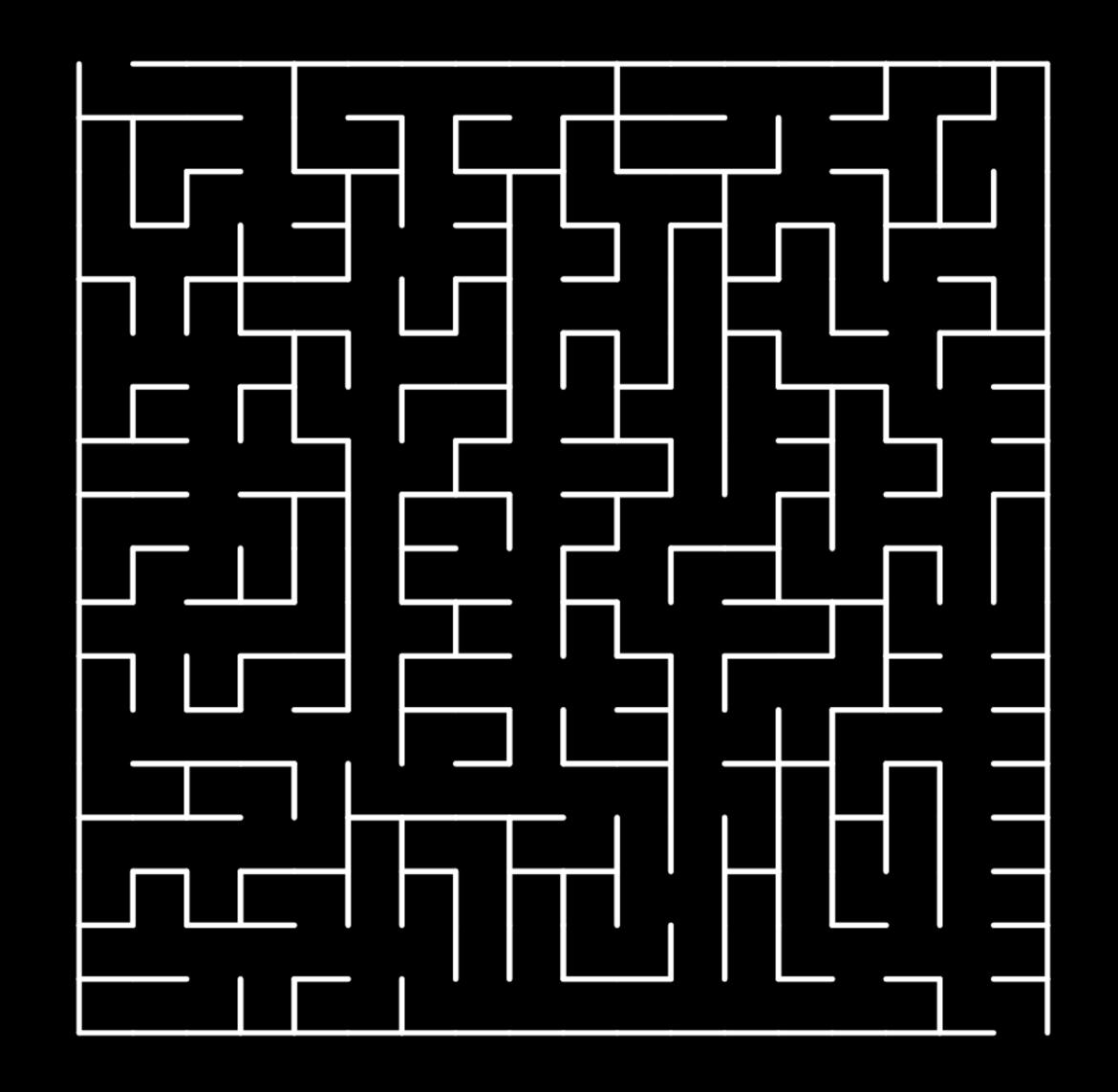
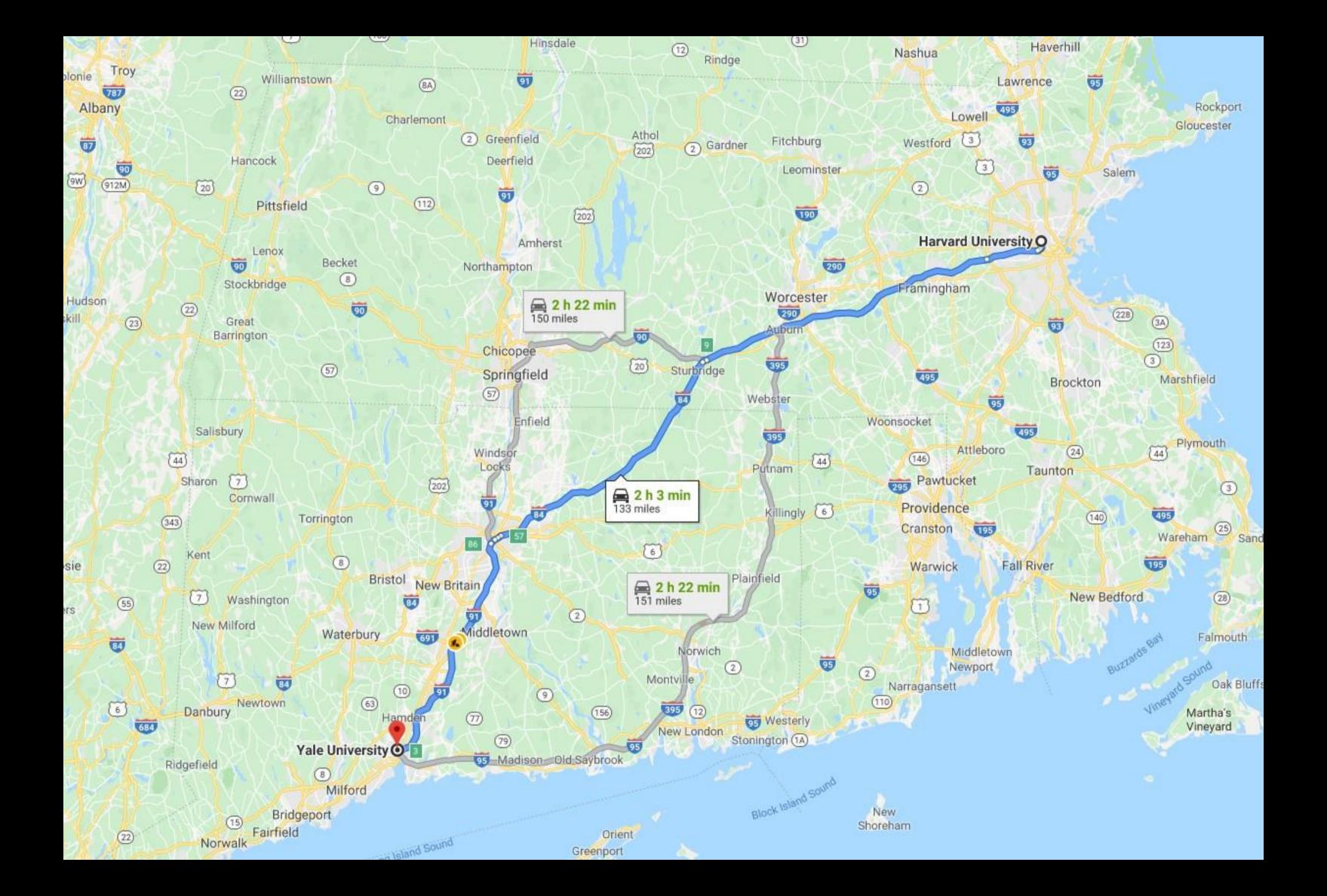
Search

1	2	3	4
5	6	7	8
9	10	11	12
13	14	15	





Search Problems

agent

entity that perceives its environment and acts upon that environment

state

a configuration of the agent and its environment

2	4	5	7
8	3	1	11
14	6		10
9	13	1 5	12

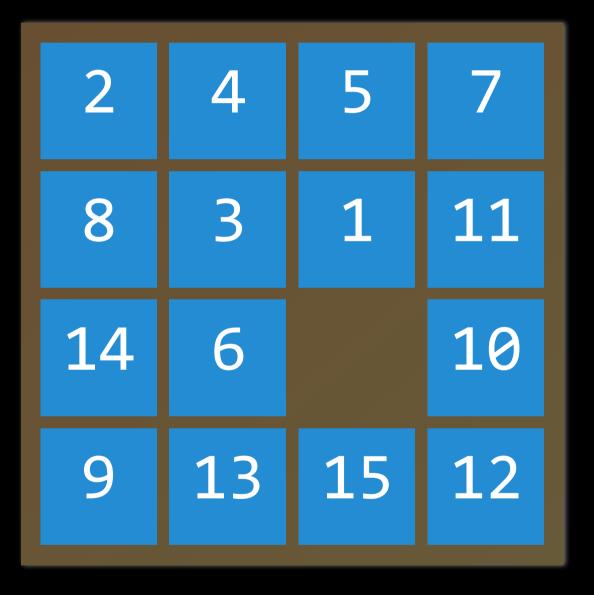
12	9	4	2
8	7	3	14
	1	6	11
5	13	10	1 5

15	4	10	3
13	1	11	12
9	5	14	7
6	8		2

initial state

the state in which the agent begins

initial state



actions

choices that can be made in a state

actions

ACTIONS(s) returns the set of actions that can be executed in state s

actions

transition model

a description of what state results from performing any applicable action in any state

transition model

RESULT(s, a) returns the state resulting from performing action a in state s

	2	4	5	7		2	4	5	7
RESULT(8	3	1	11		8	3	1	11
	14	6	10	12	,	14	6	10	12
	9	13	1 5			9	13		1 5
	2	4	5	7		2	4	5	7
Decimací	2 8	3		7 11		2 8	3	5 1	7 11
RESULT(1		,				7

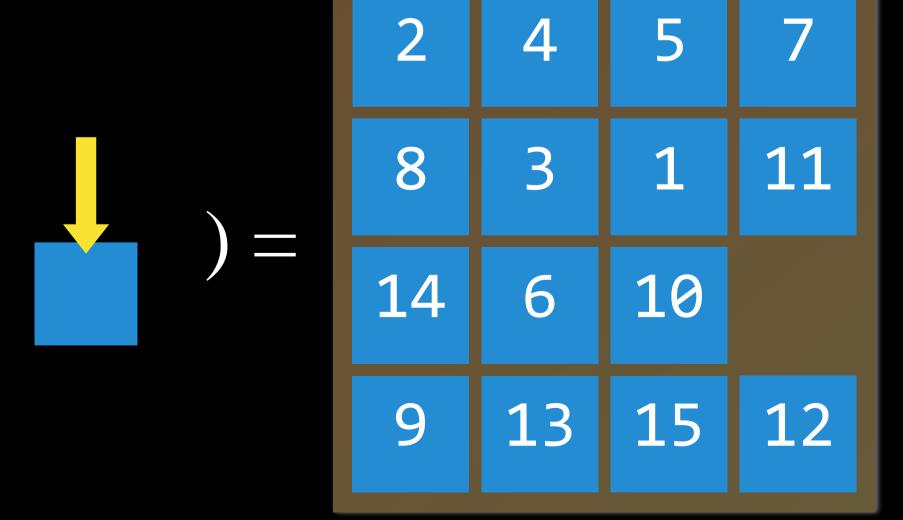
transition model

 RESULT(
 2
 4
 5
 7

 14
 3
 1
 11

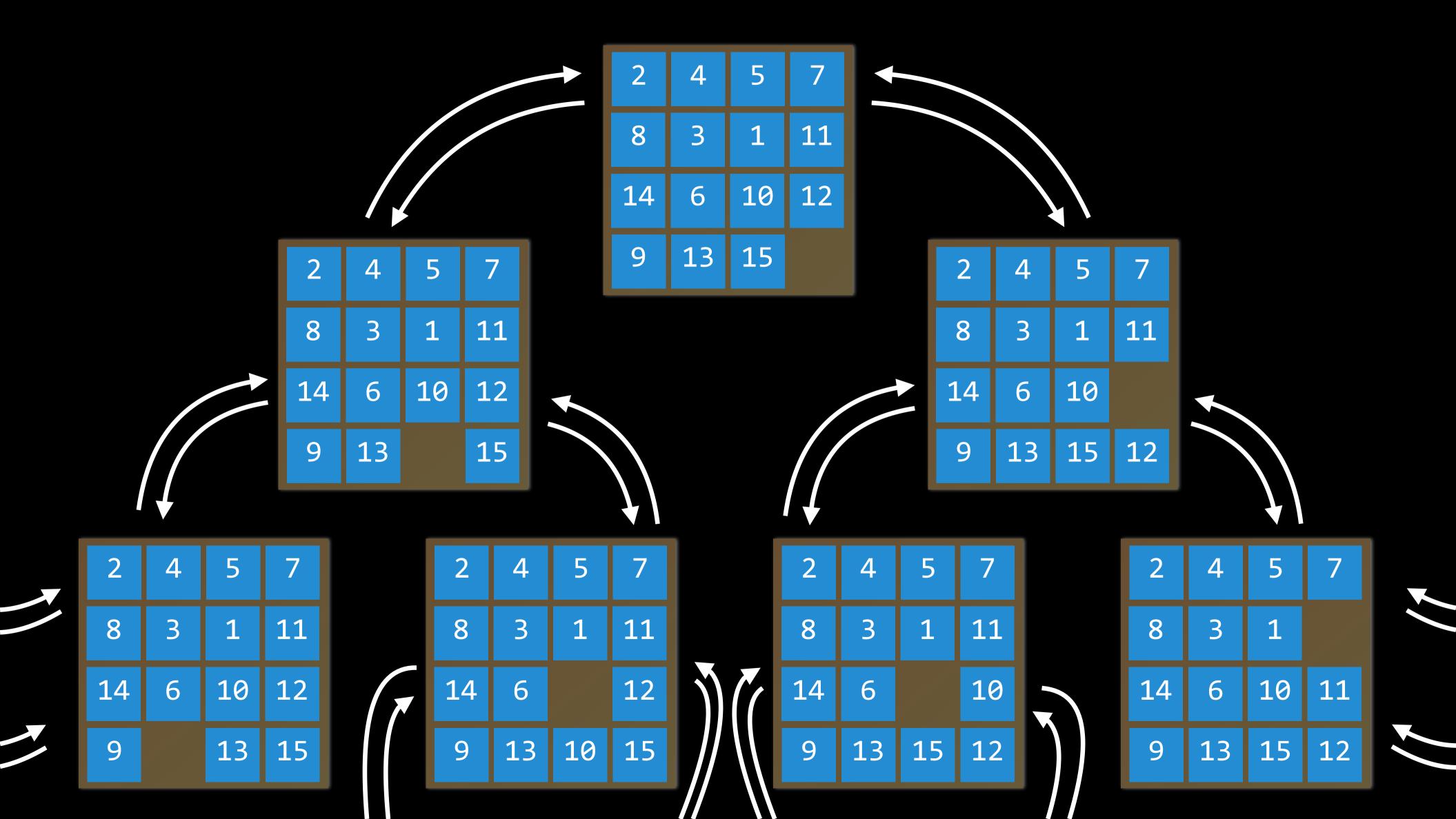
 14
 6
 10
 12

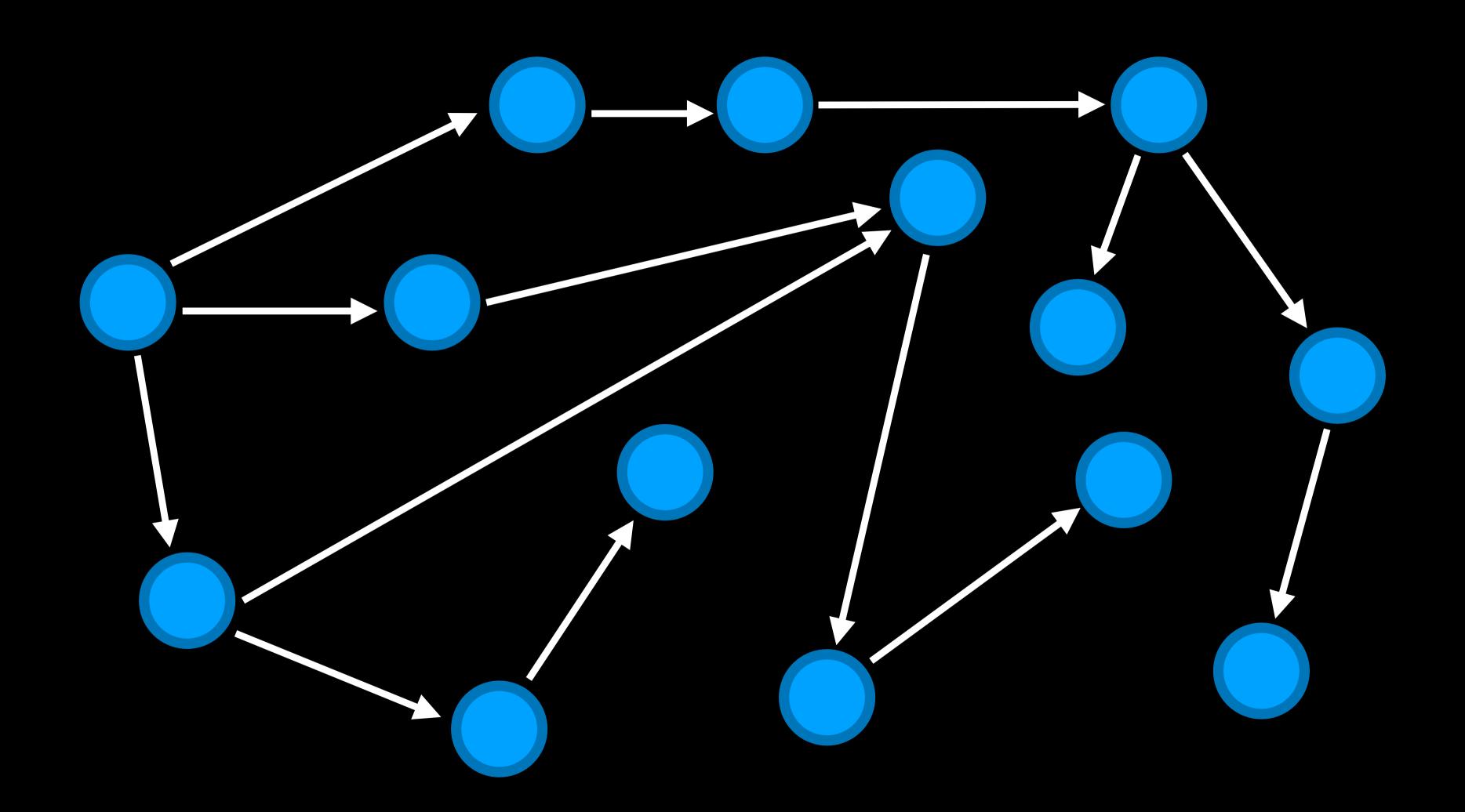
 9
 13
 15



state space

the set of all states reachable from the initial state by any sequence of actions



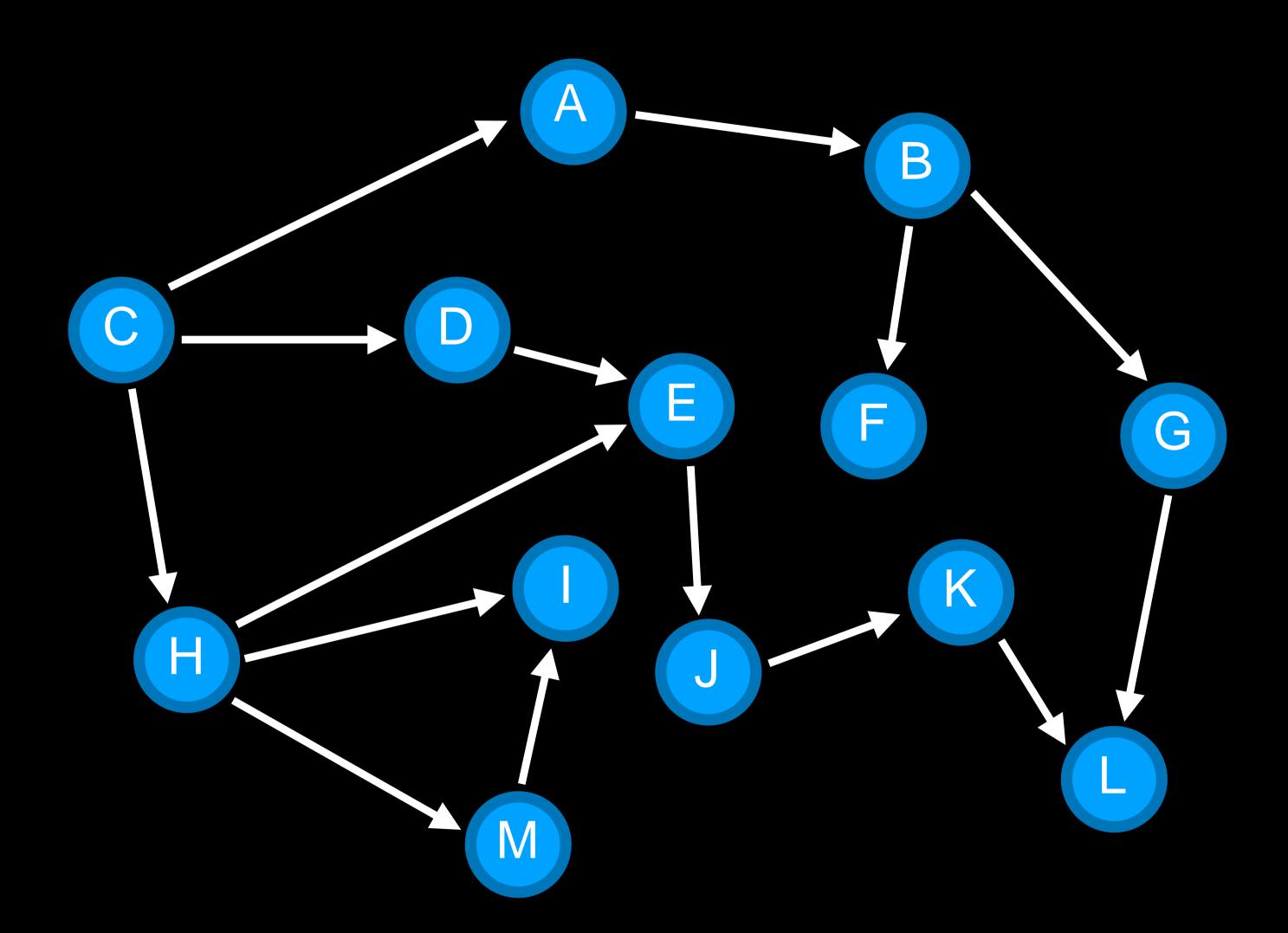


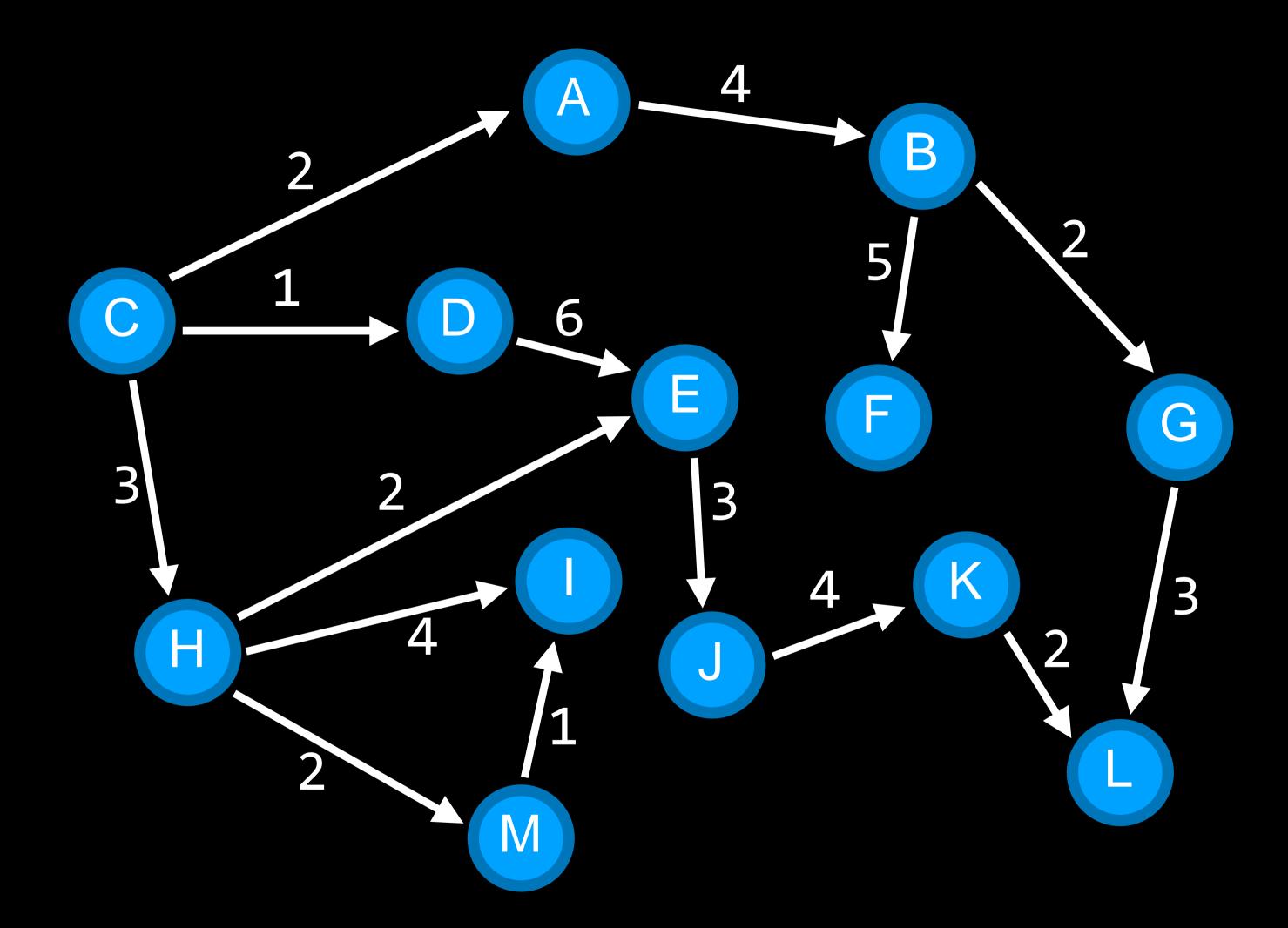
goal test

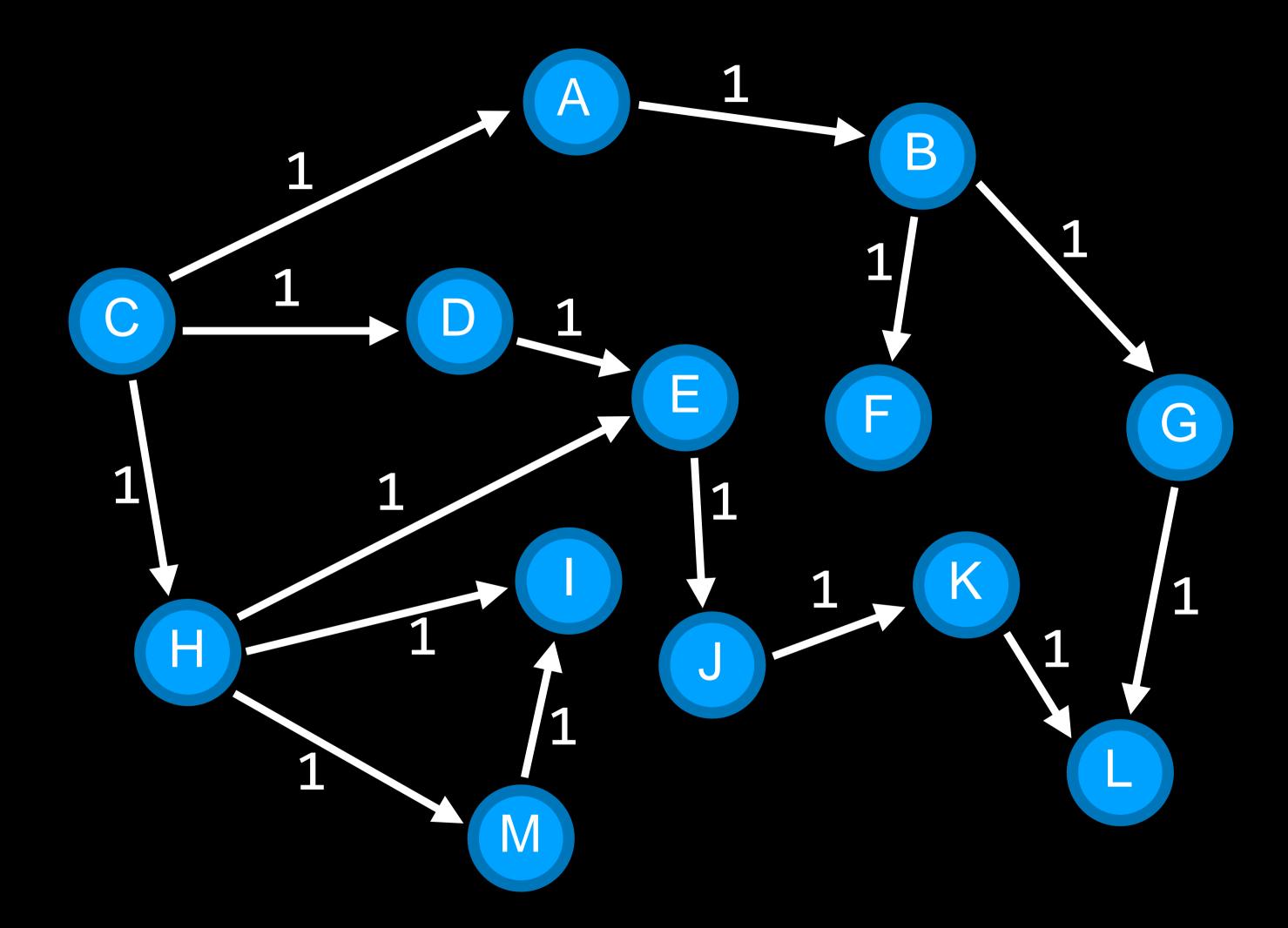
way to determine whether a given state is a goal state

path cost

numerical cost associated with a given path







Search Problems

- initial state
- actions
- transition model
- goal test
- path cost function

solution

a sequence of actions that leads from the initial state to a goal state

optimal solution

a solution that has the lowest path cost among all solutions

node

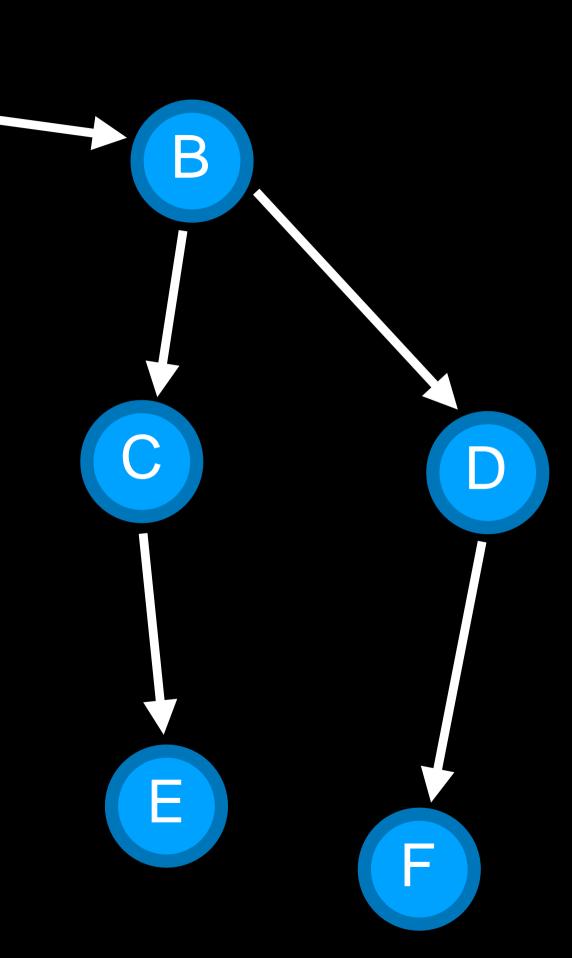
a data structure that keeps track of

- a state
- a parent (node that generated this node)
- an action (action applied to parent to get node)
- a path cost (from initial state to node)

Approach

- Start with a frontier that contains the initial state.
- Repeat:
 - If the frontier is empty, then no solution.
 - Remove a node from the frontier.
 - If node contains goal state, return the solution.
 - Expand node, add resulting nodes to the frontier.

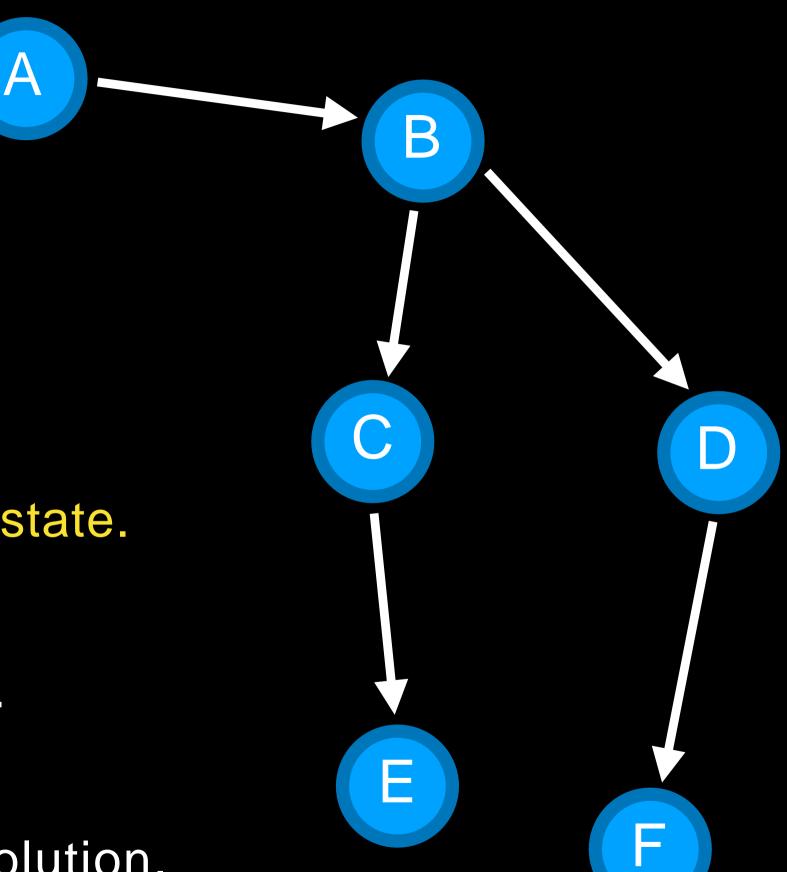
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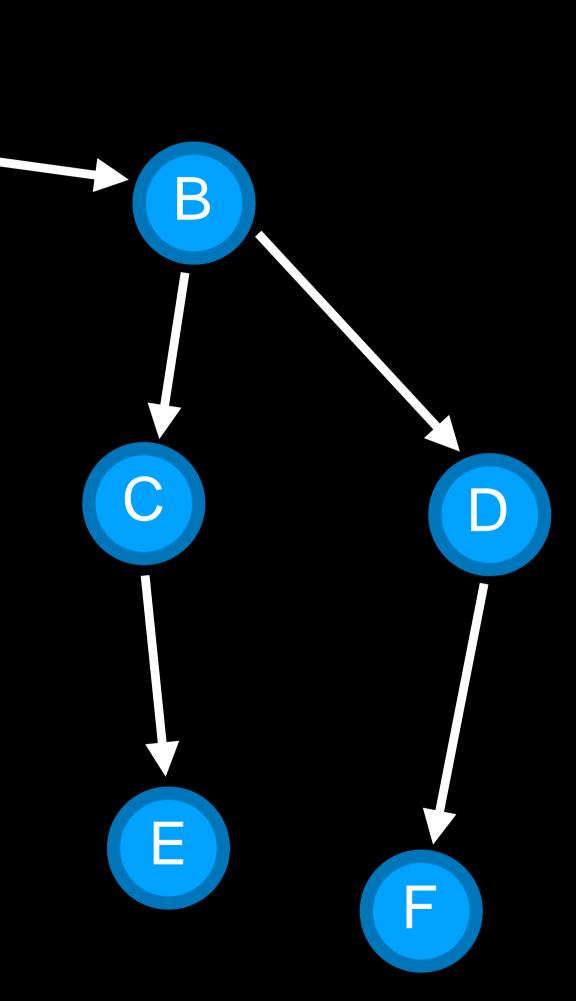




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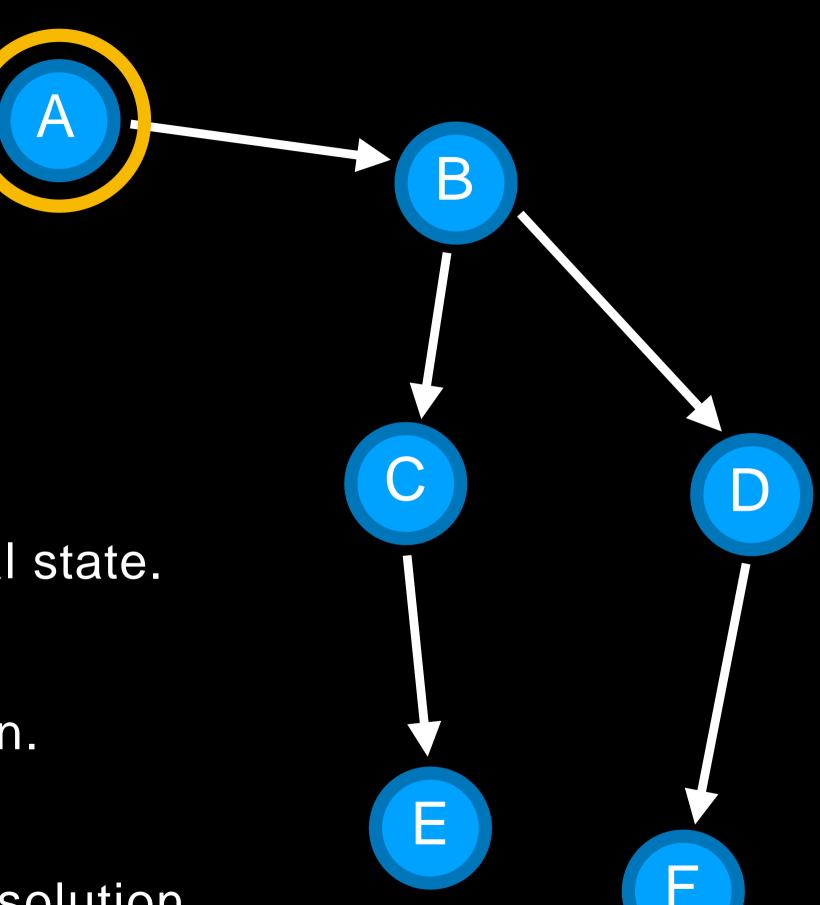
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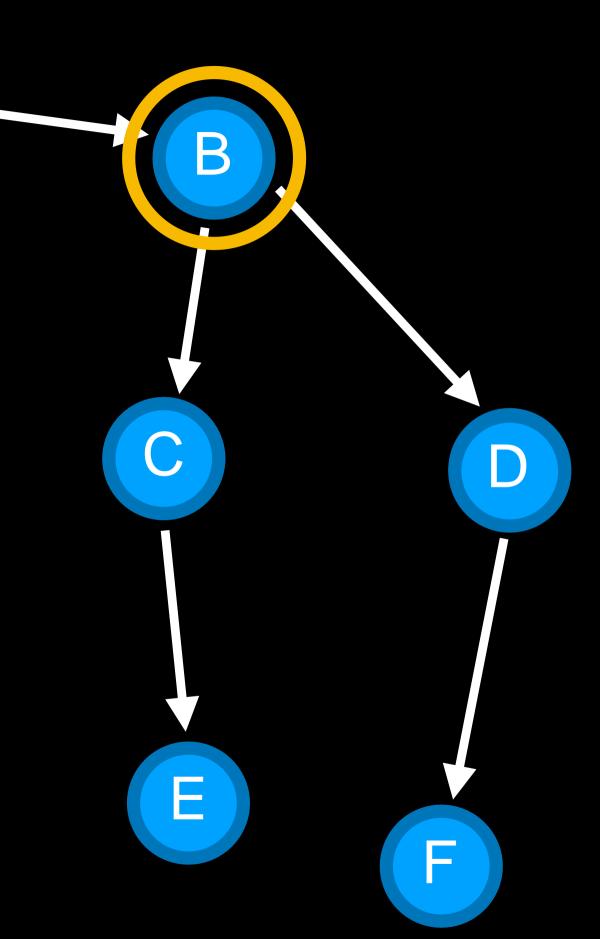




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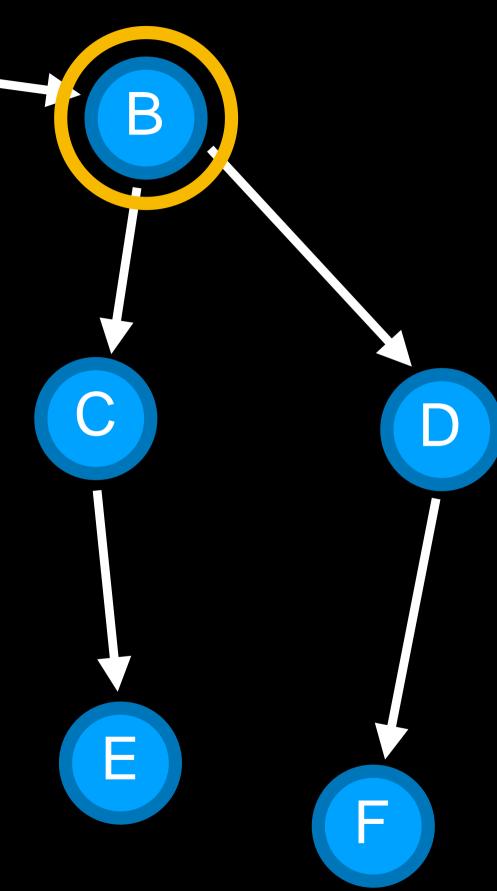
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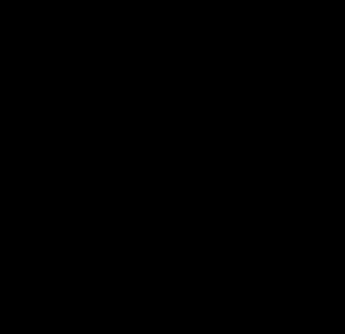


Frontier C D

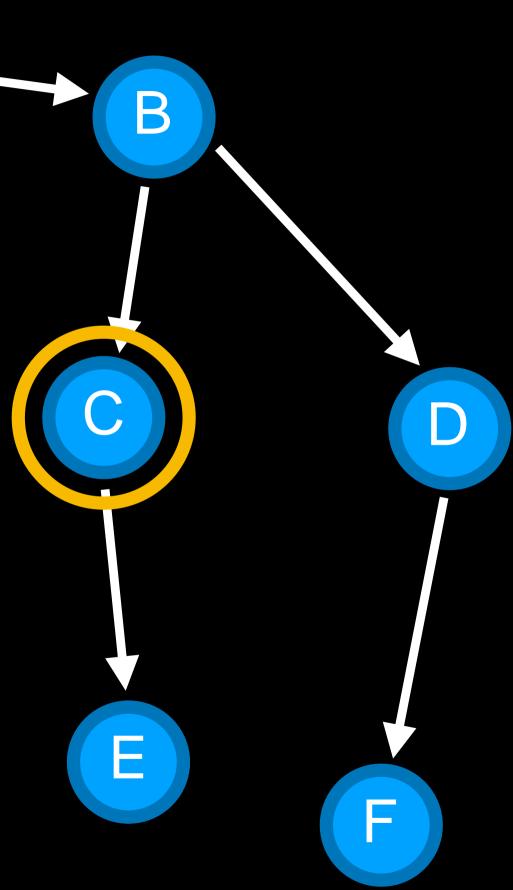


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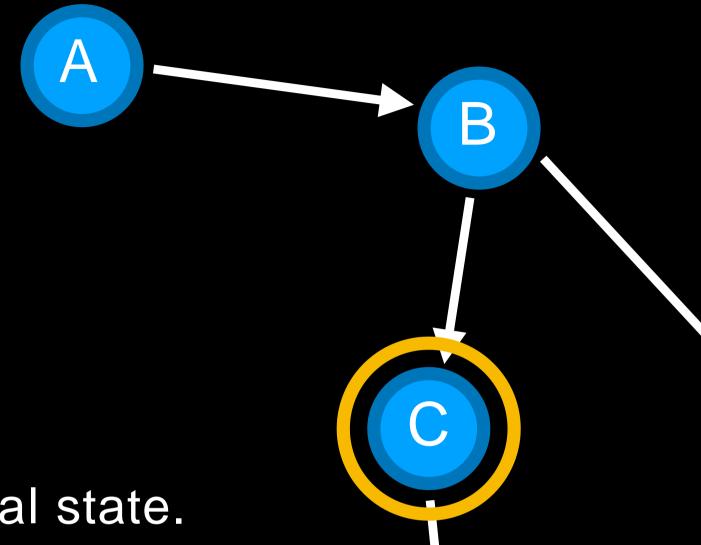




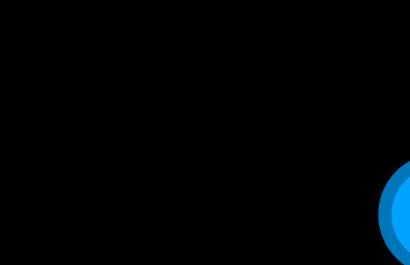
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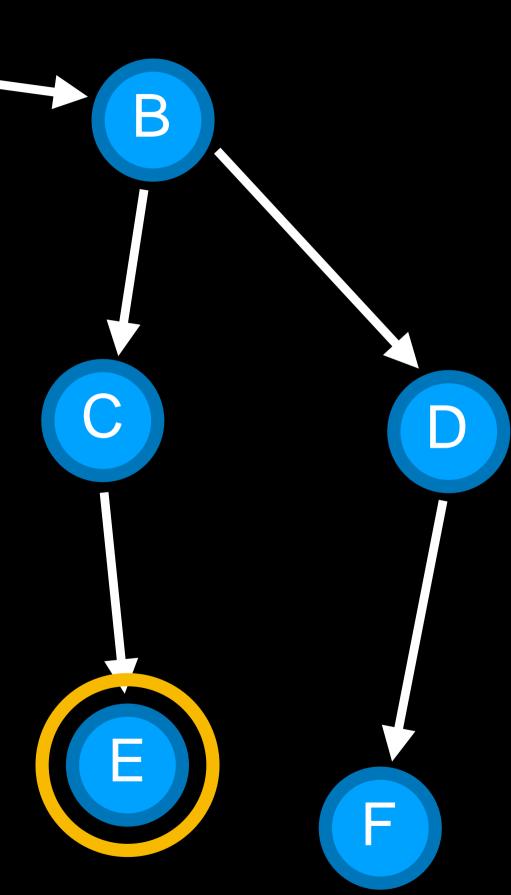
Frontier (E) (D)

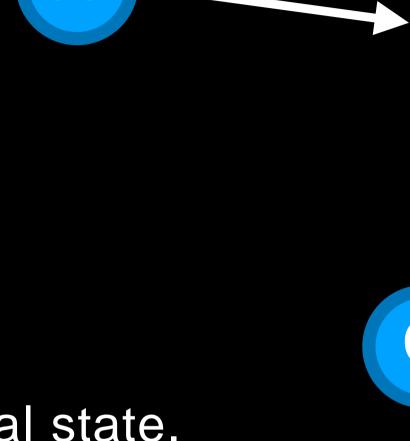


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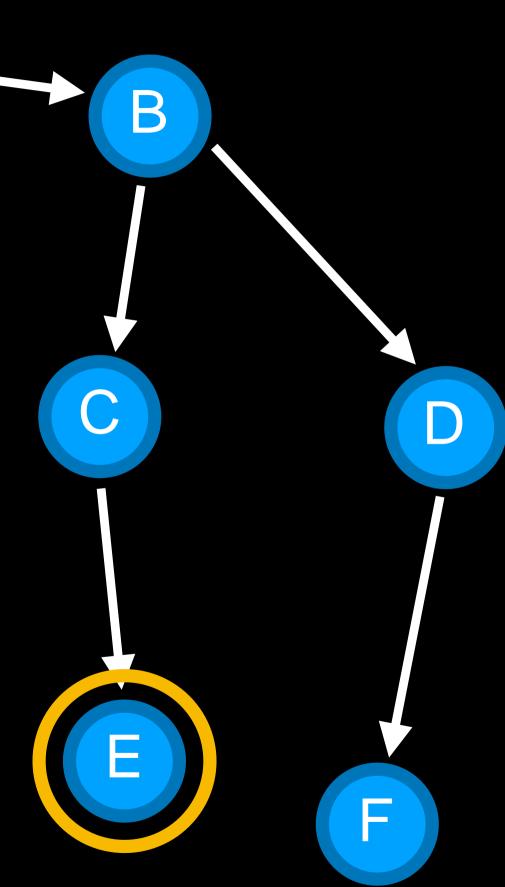


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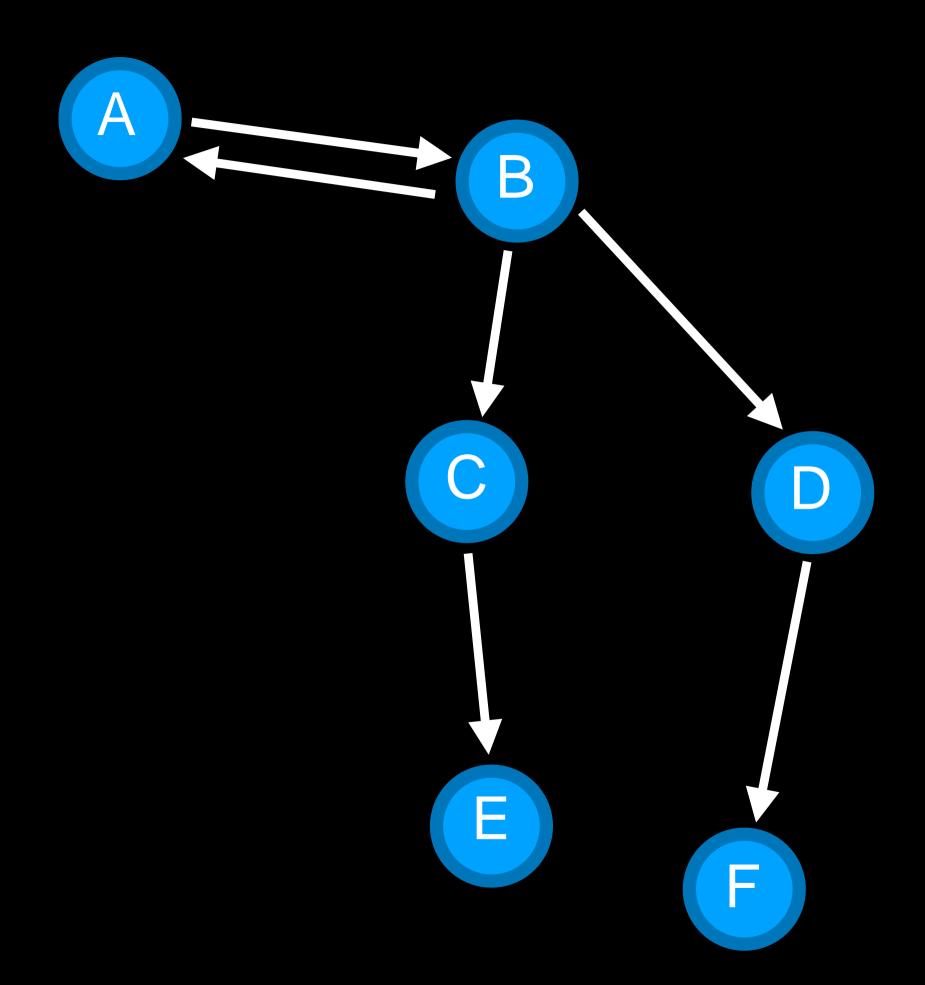




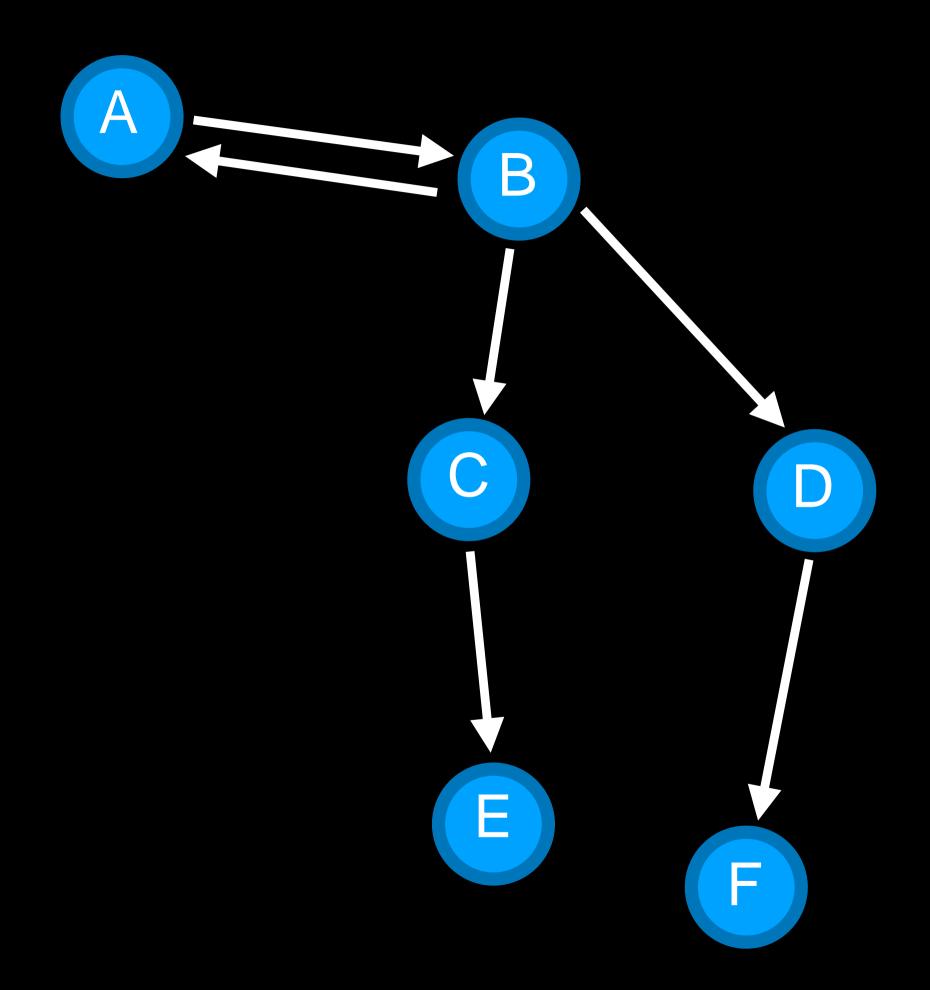
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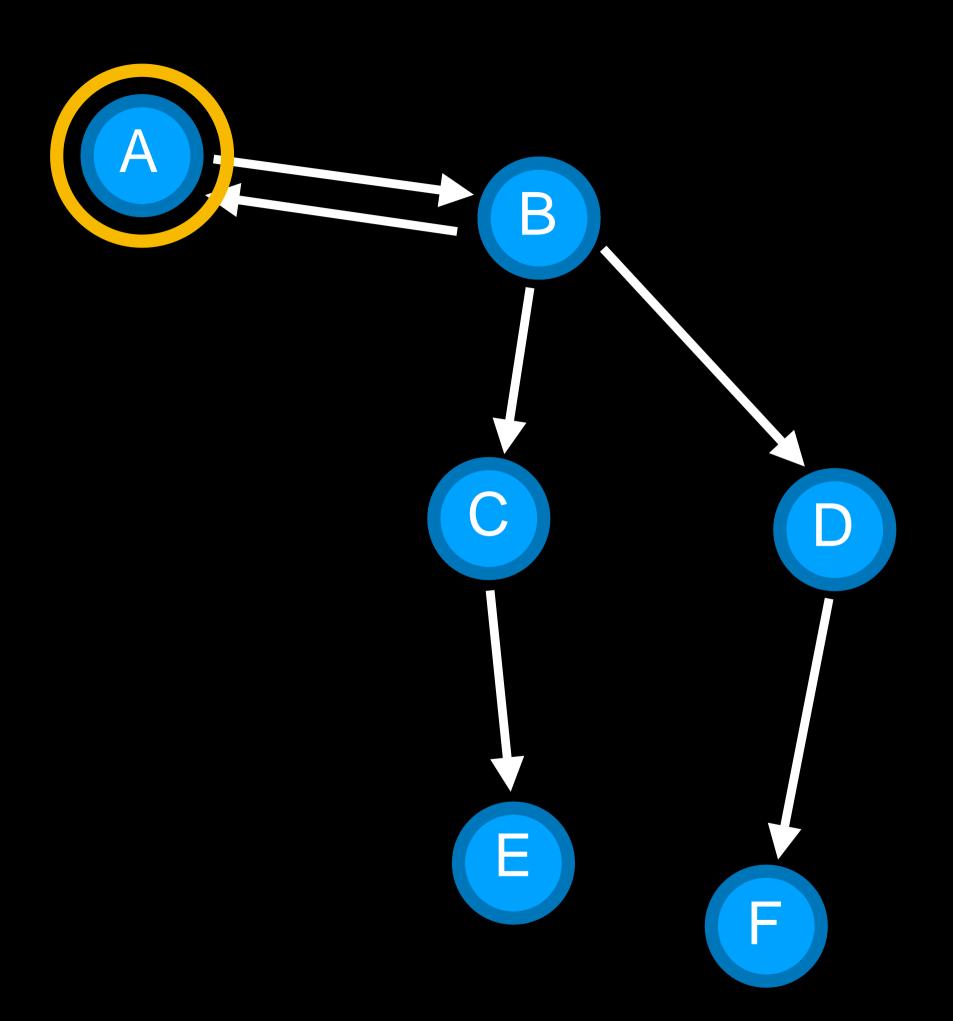


What could go wrong?

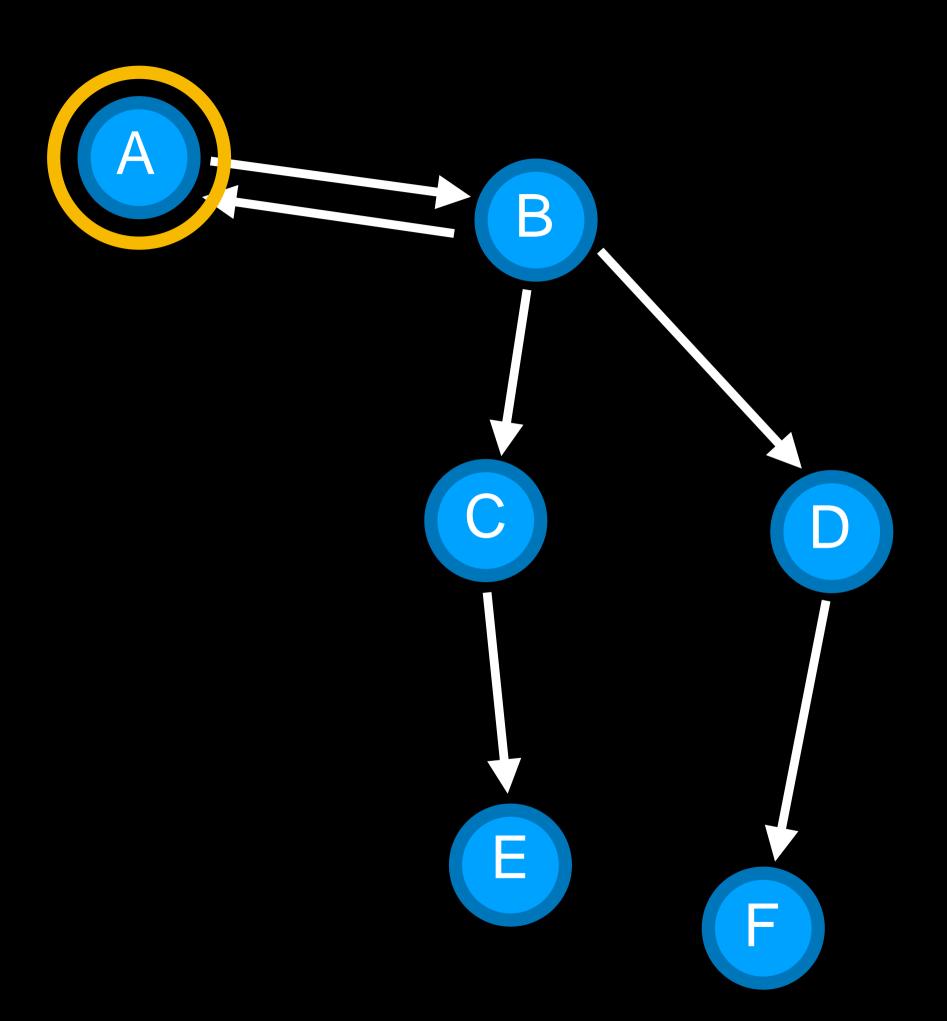


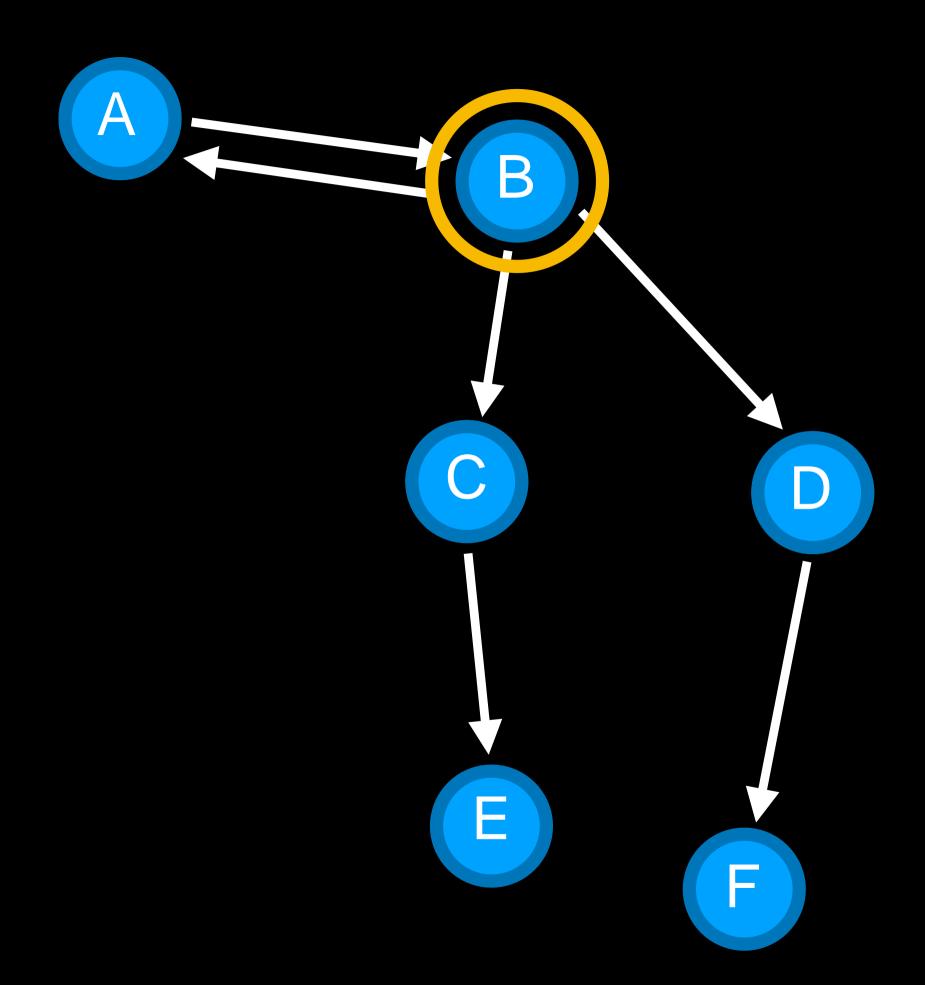


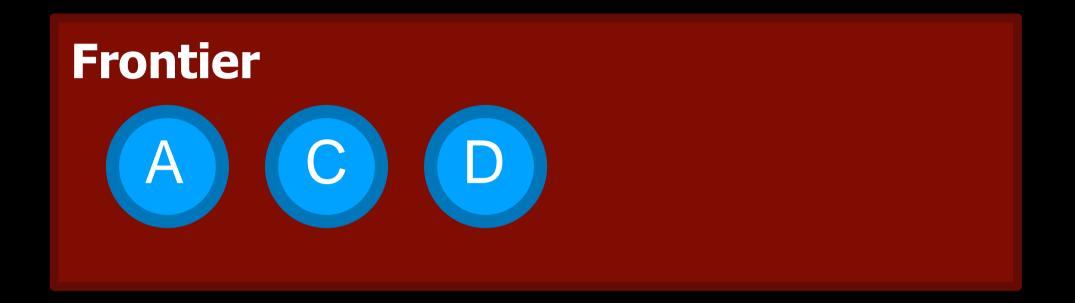


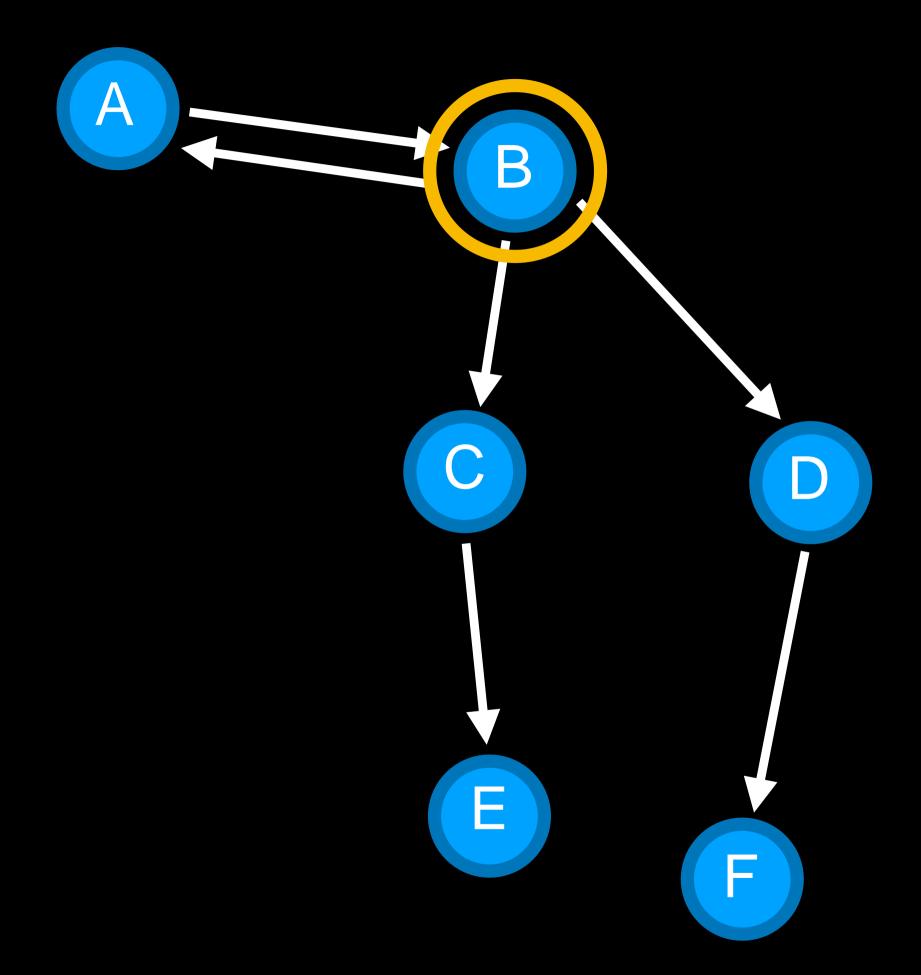


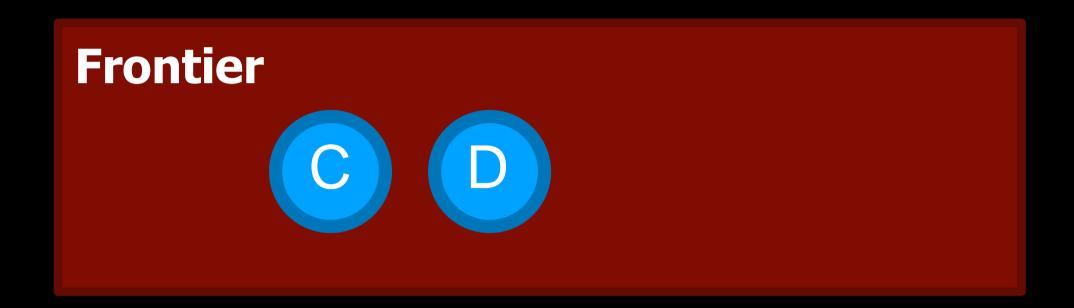


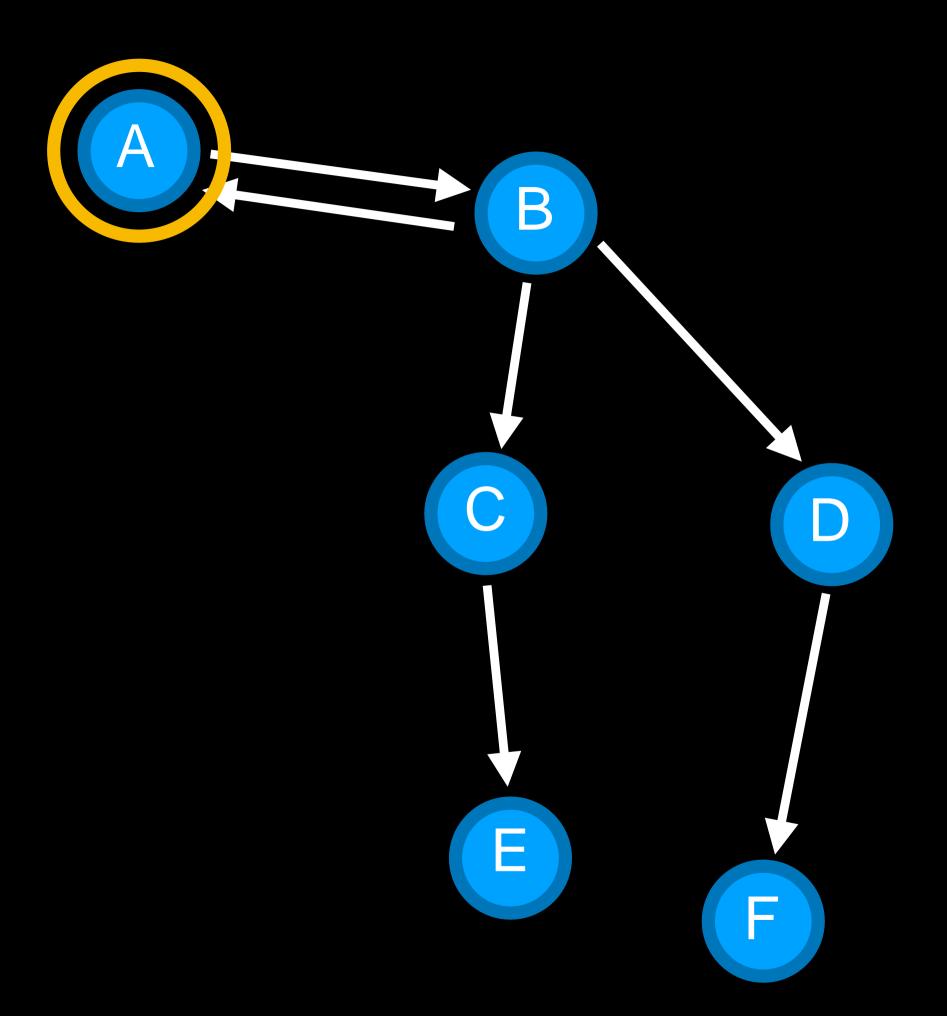












Revised Approach

- Start with a frontier that contains the initial state.
- Start with an empty explored set.
- Repeat:
 - If the frontier is empty, then no solution.
 - Remove a node from the frontier.
 - If node contains goal state, return the solution.
 - Add the node to the explored set.
 - **Expand** node, add resulting nodes to the frontier if they aren't already in the frontier or the explored set.

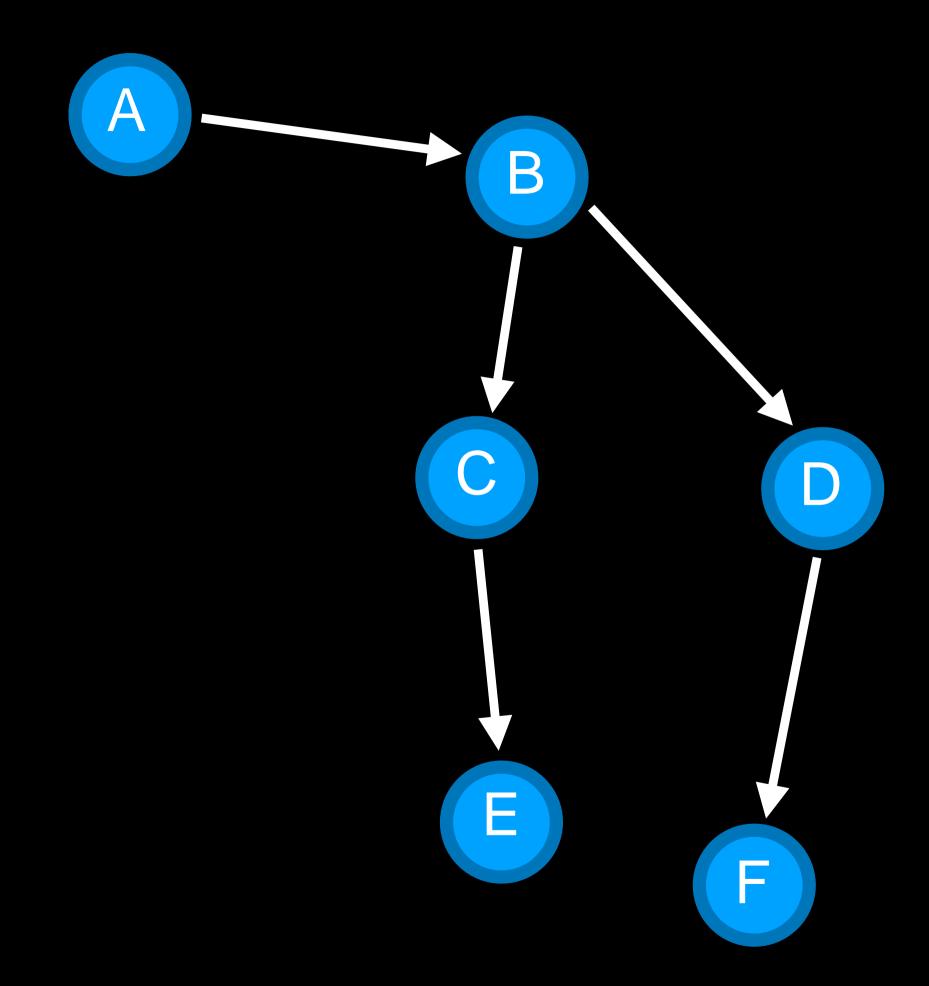
Revised Approach

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 - Add the node to the explored set.
 - Expand node, add resulting nodes to the frontier if they aren't already in the frontier or the explored set.

stack

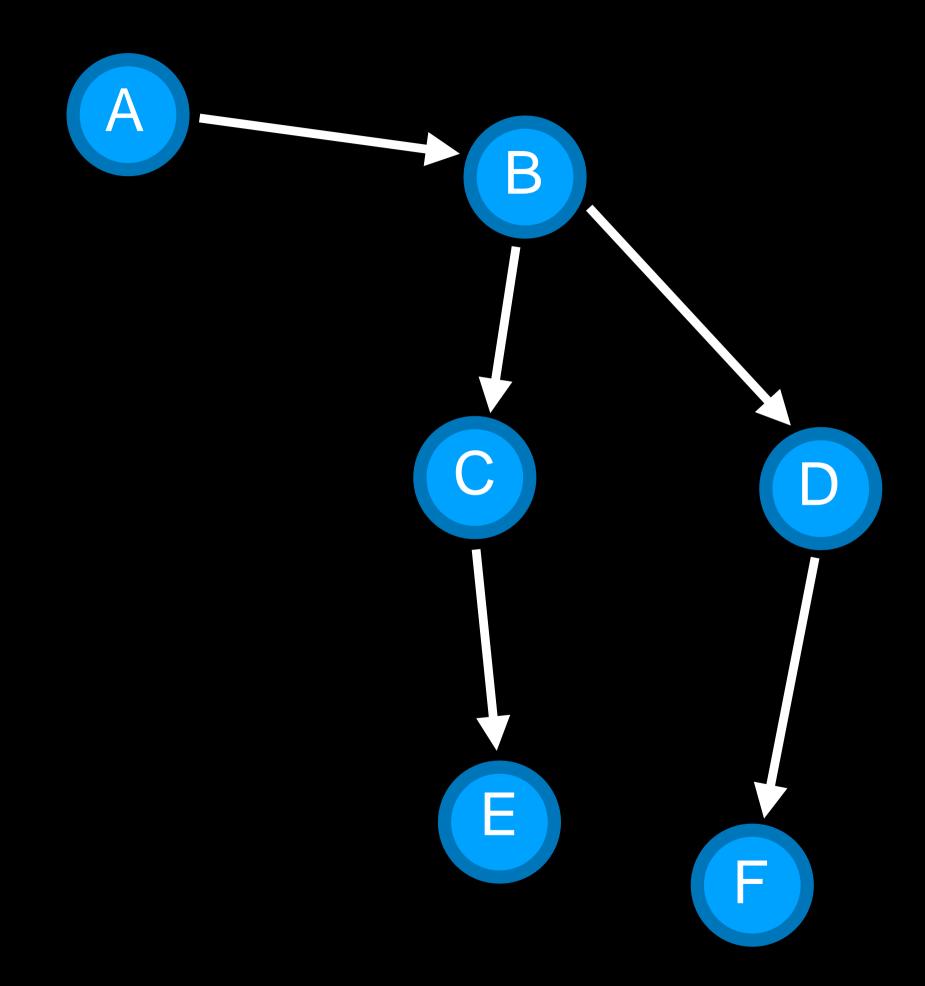
last-in first-out data type

Frontier



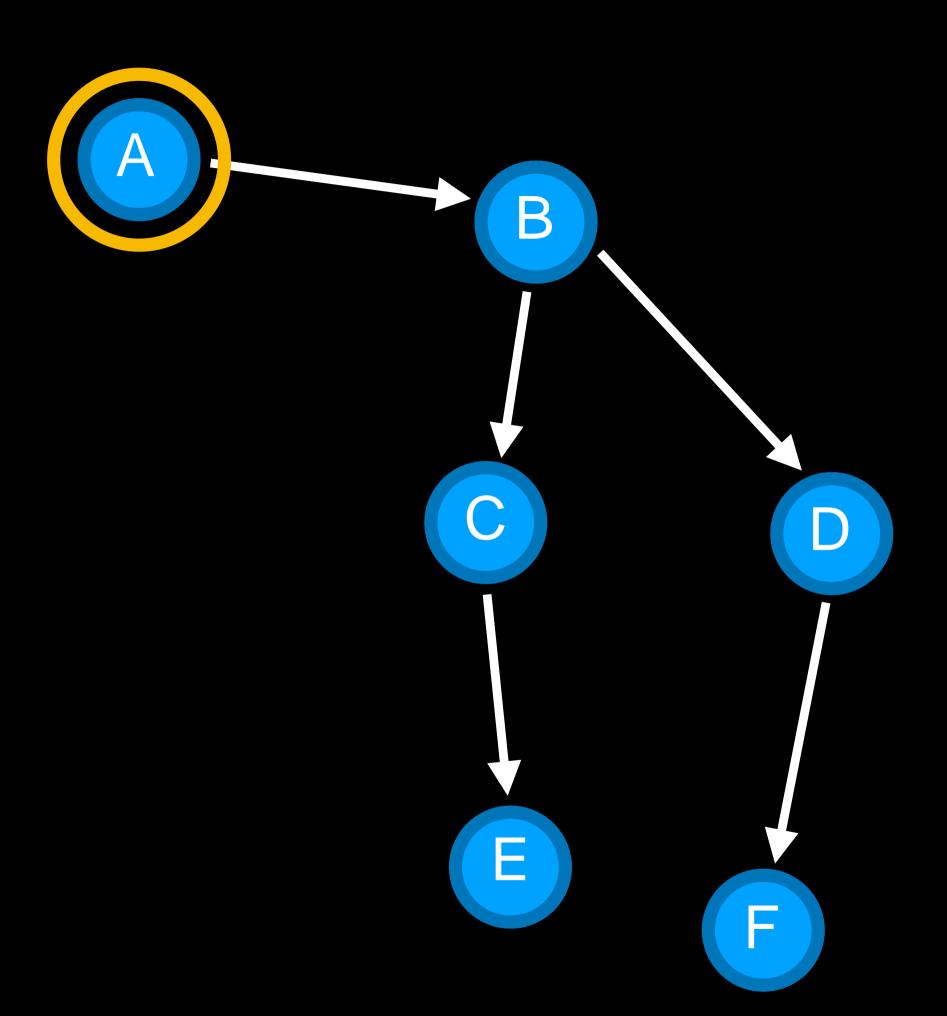
Frontier





Frontier

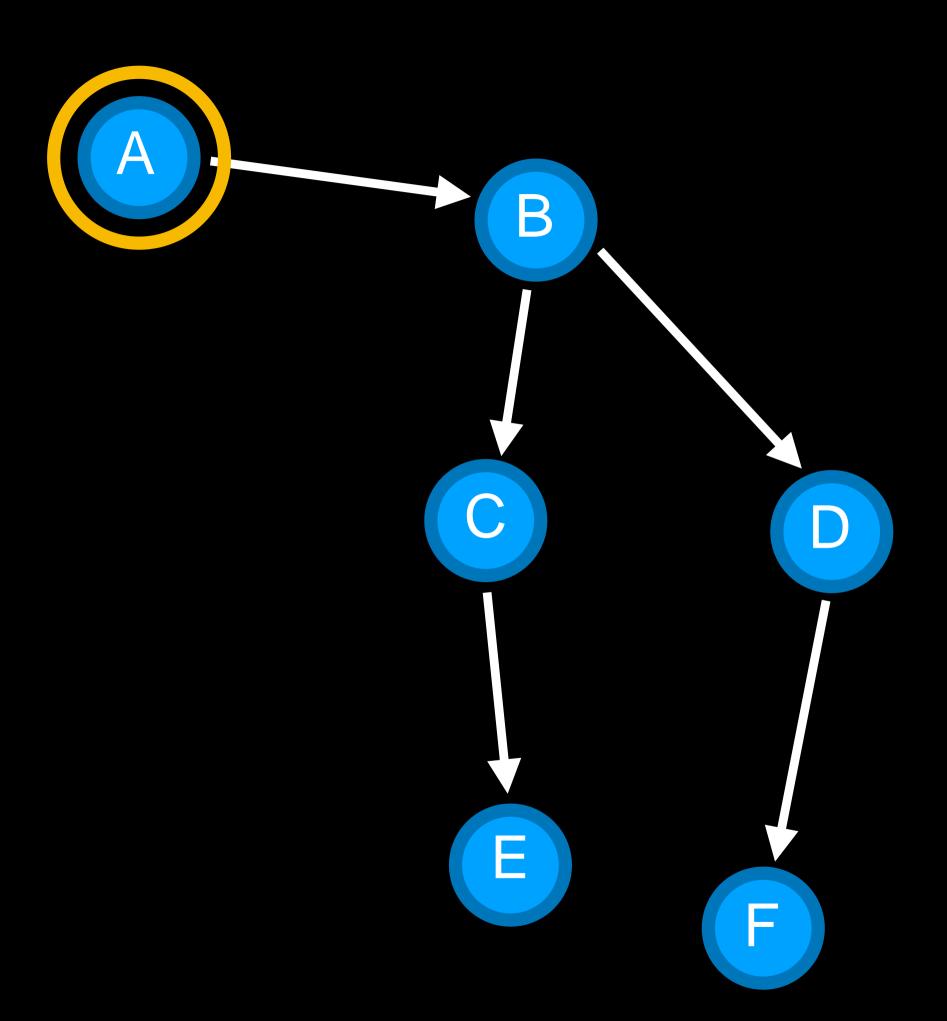




Frontier



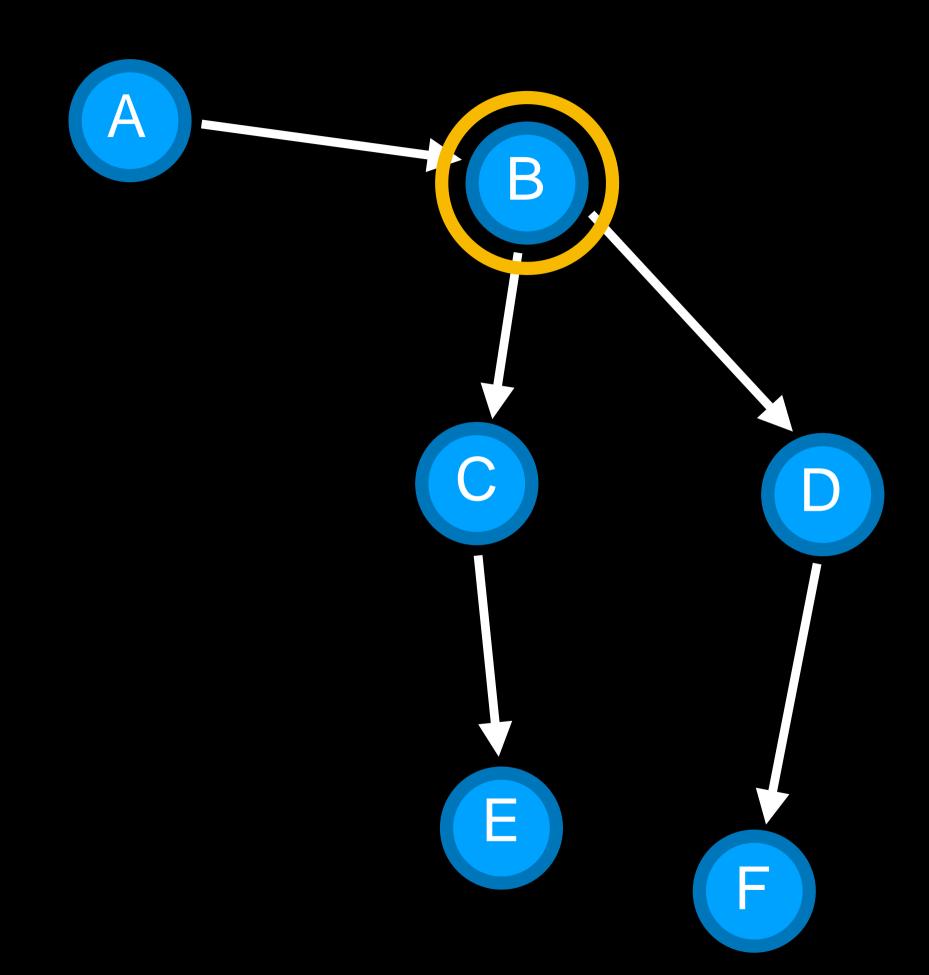




Frontier

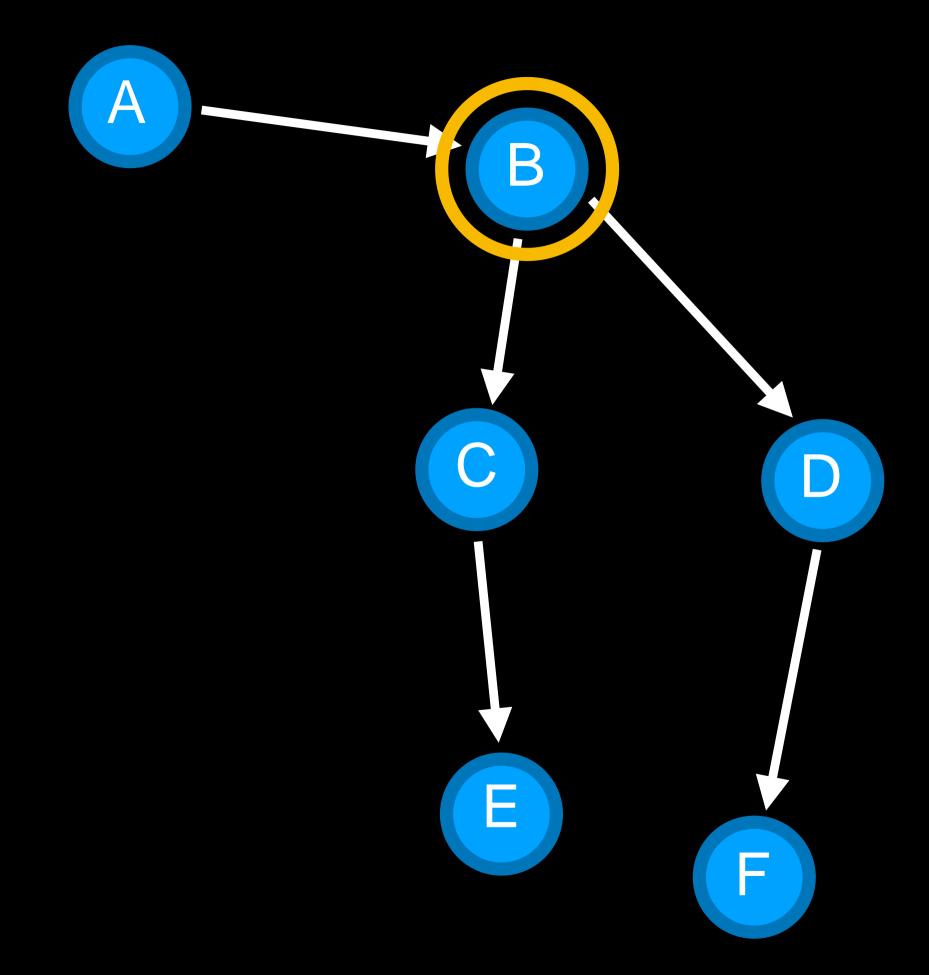






Frontier C D





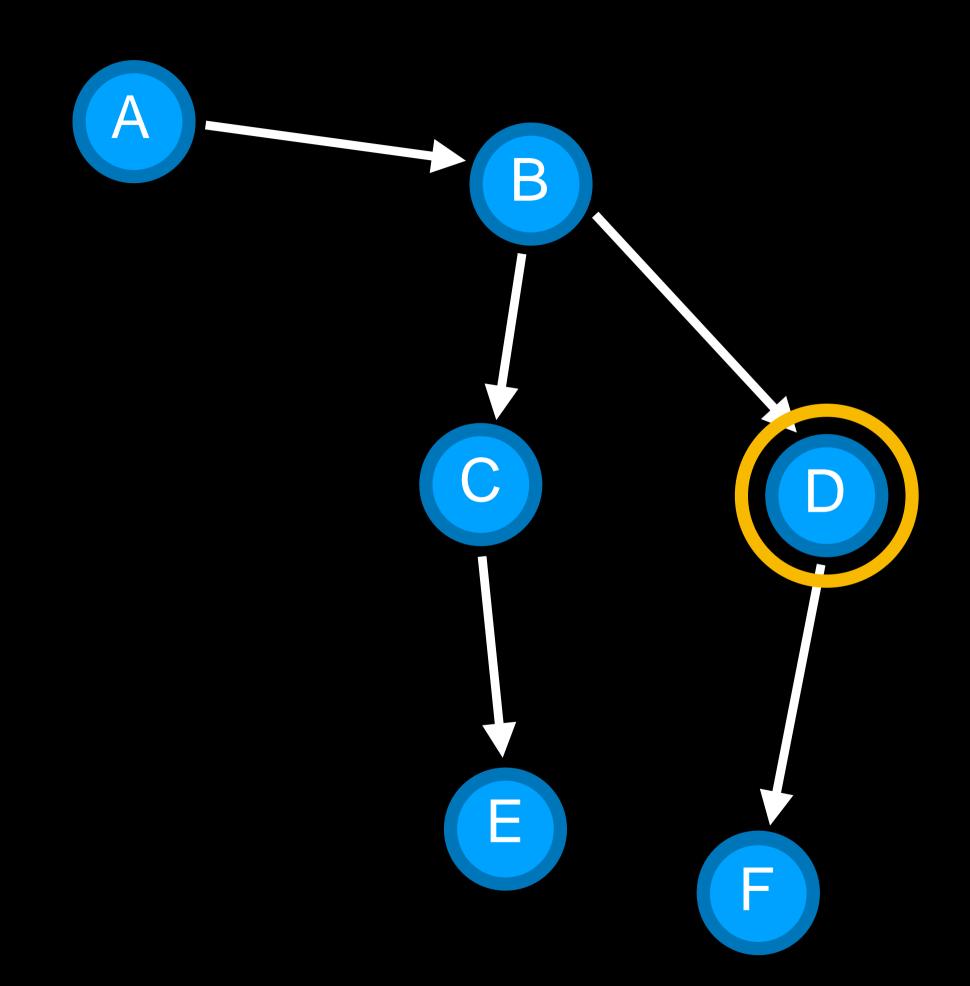
Frontier



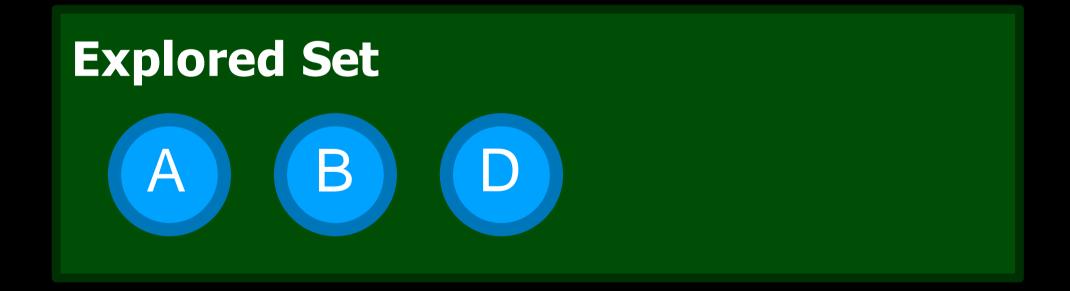


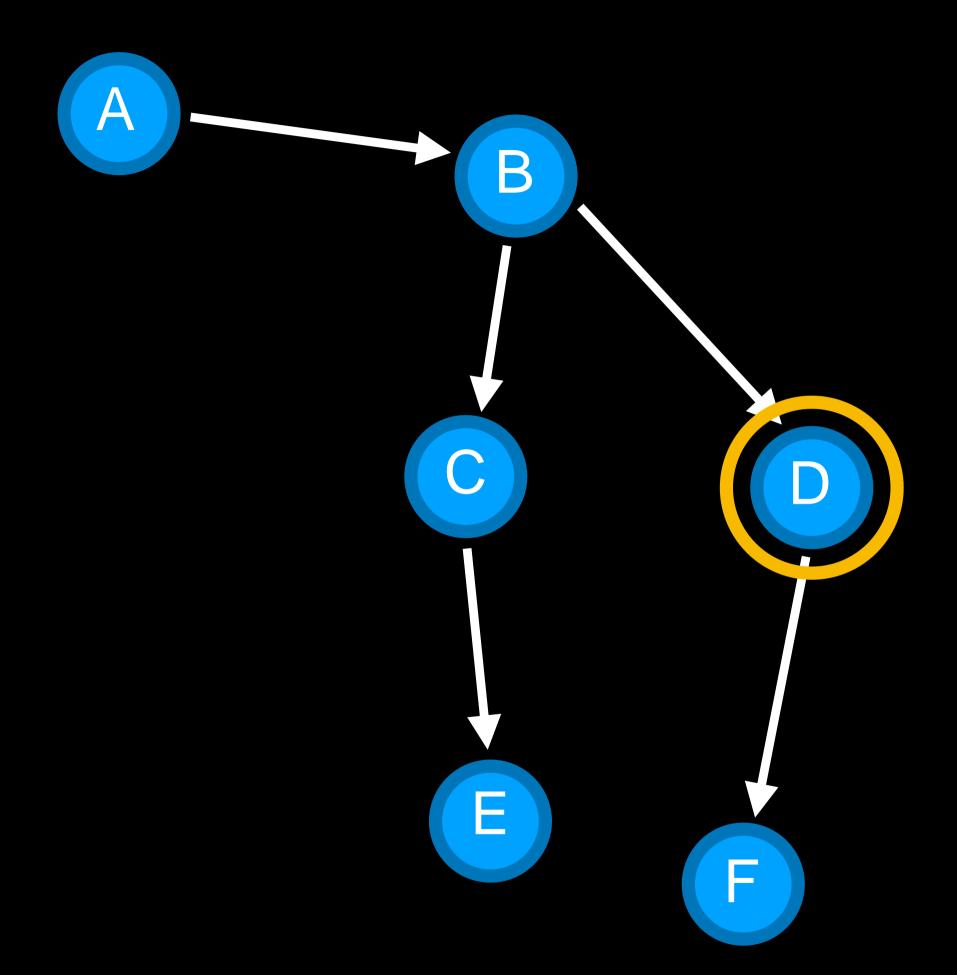






Frontier (C) (F)





Frontier

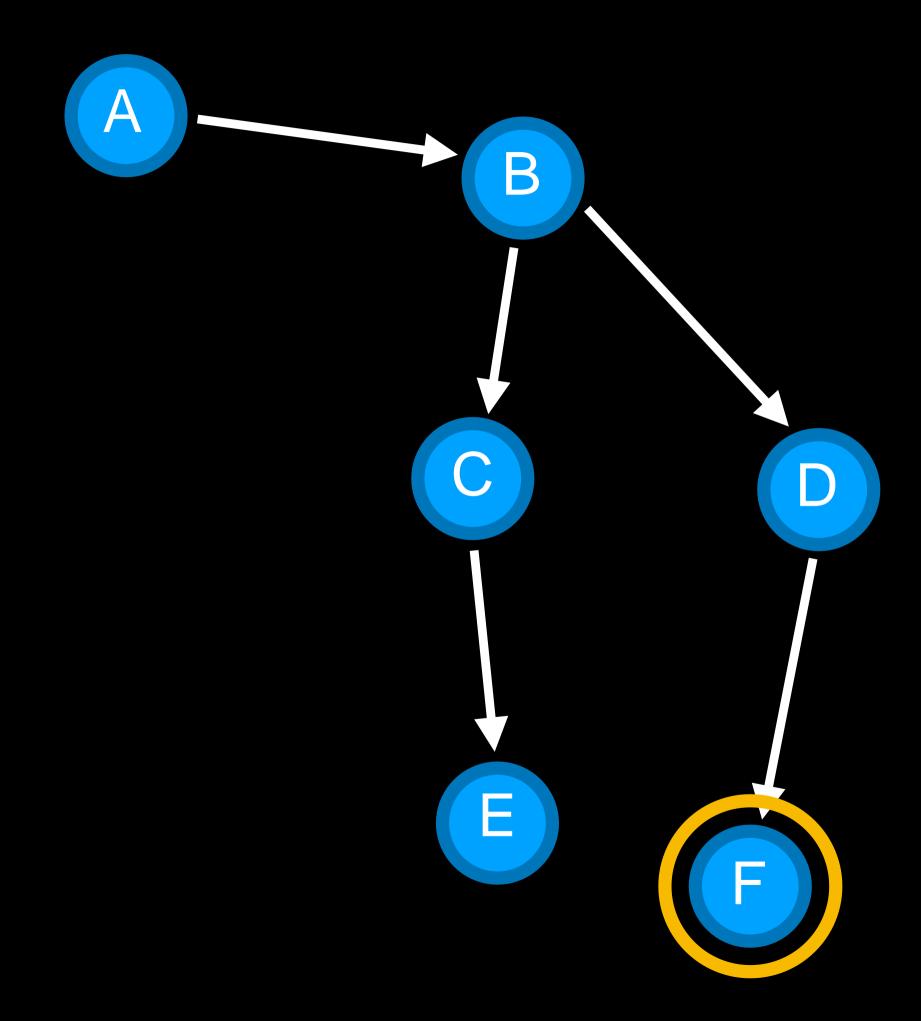


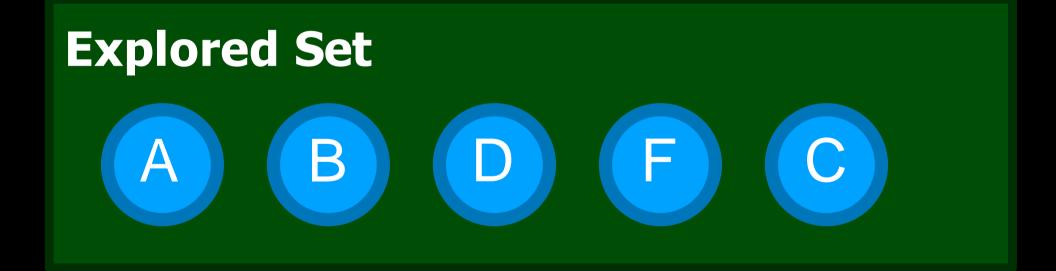


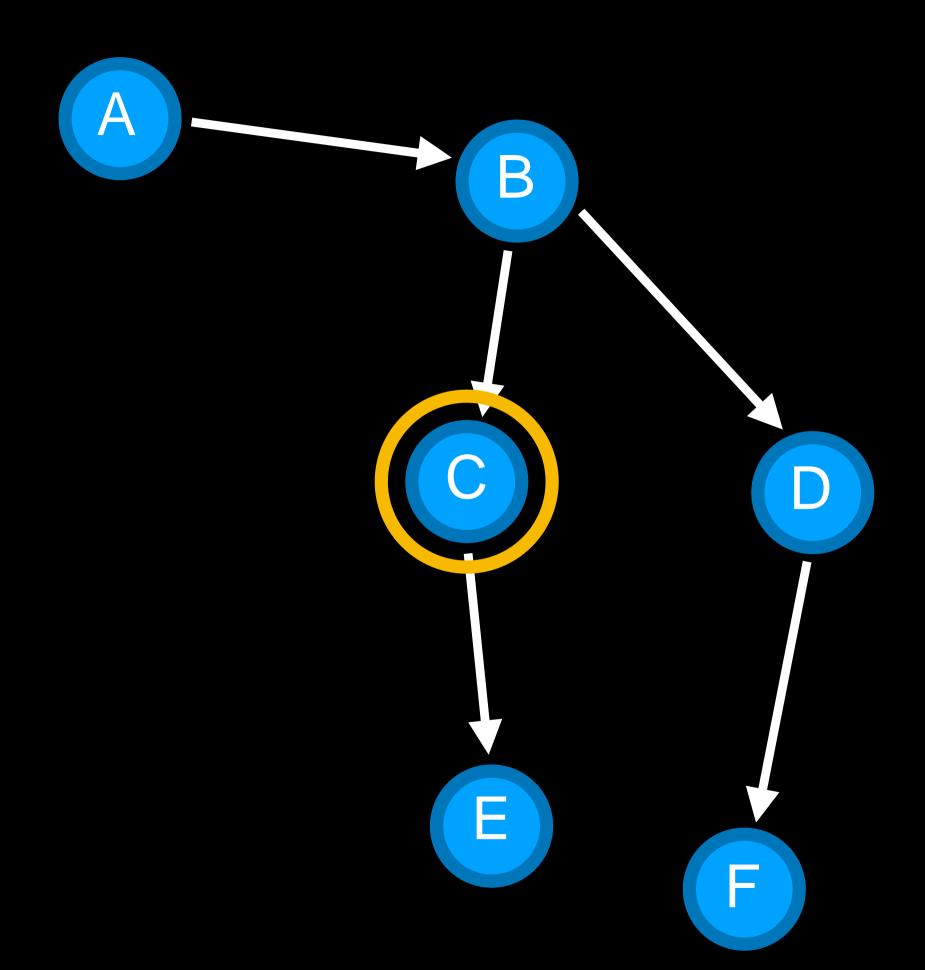












Frontier



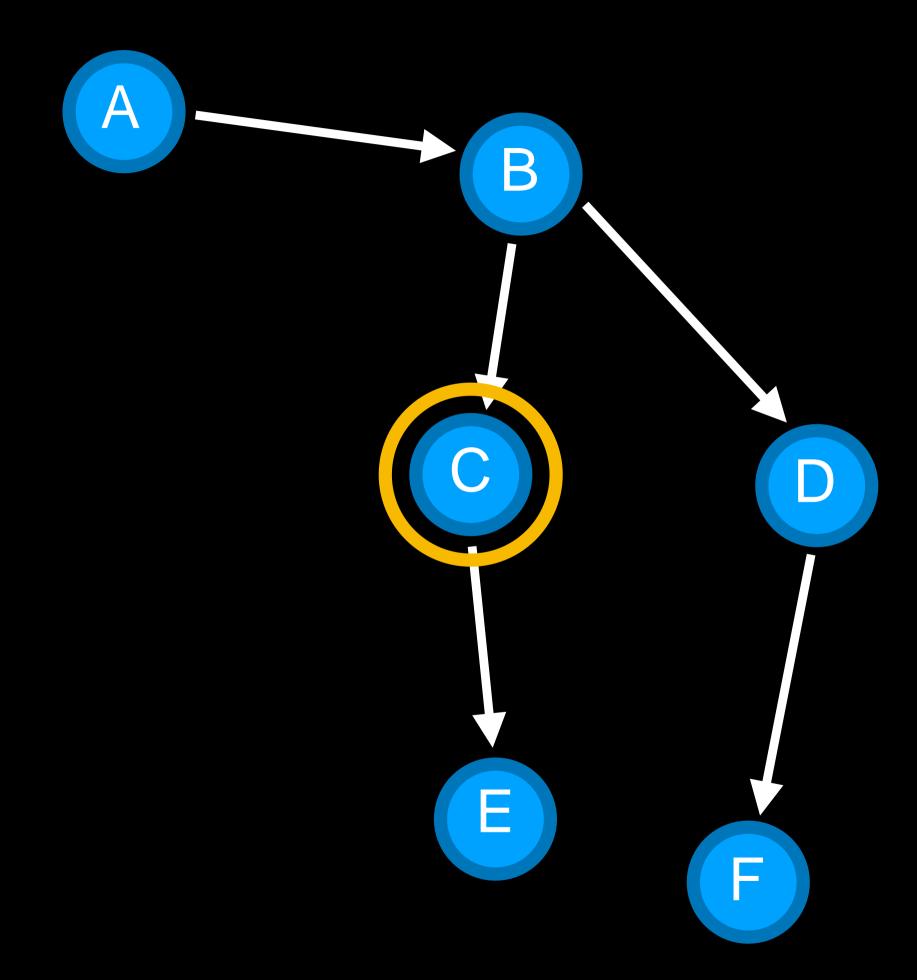




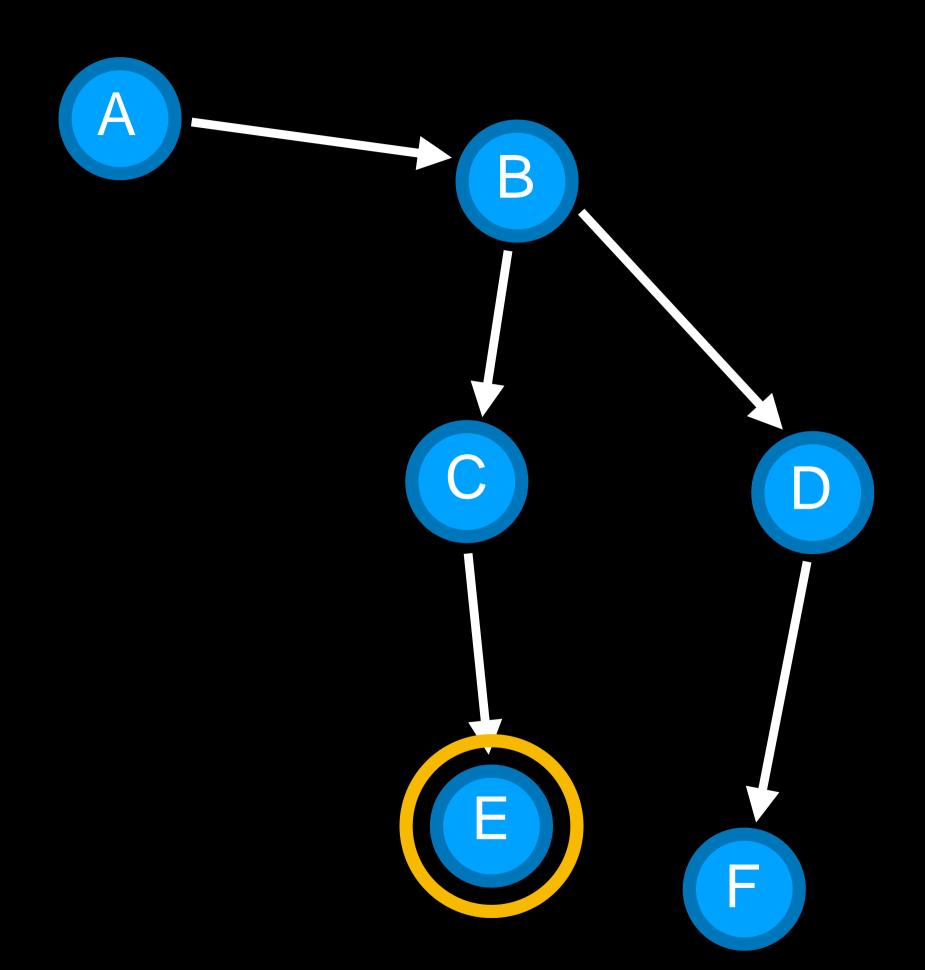












Depth-First Search

depth-first search

search algorithm that always expands the deepest node in the frontier

Breadth-First Search

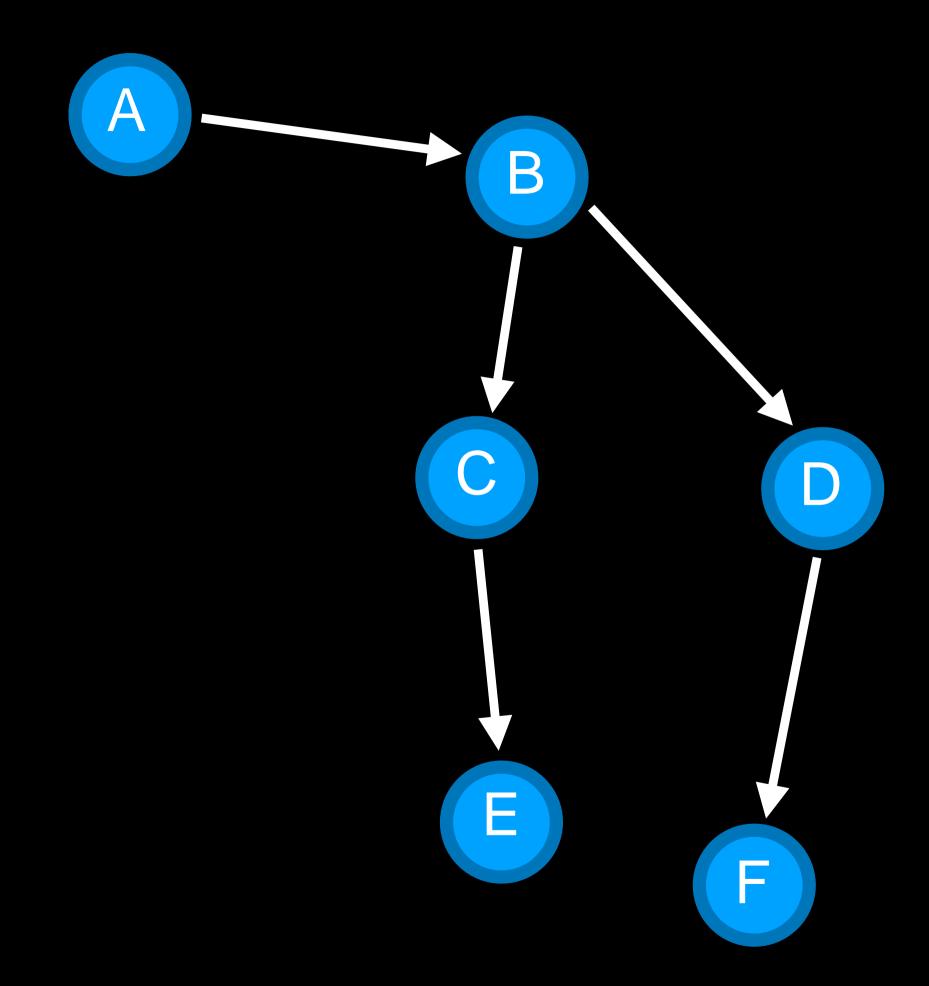
breadth-first search

search algorithm that always expands the shallowest node in the frontier

queue

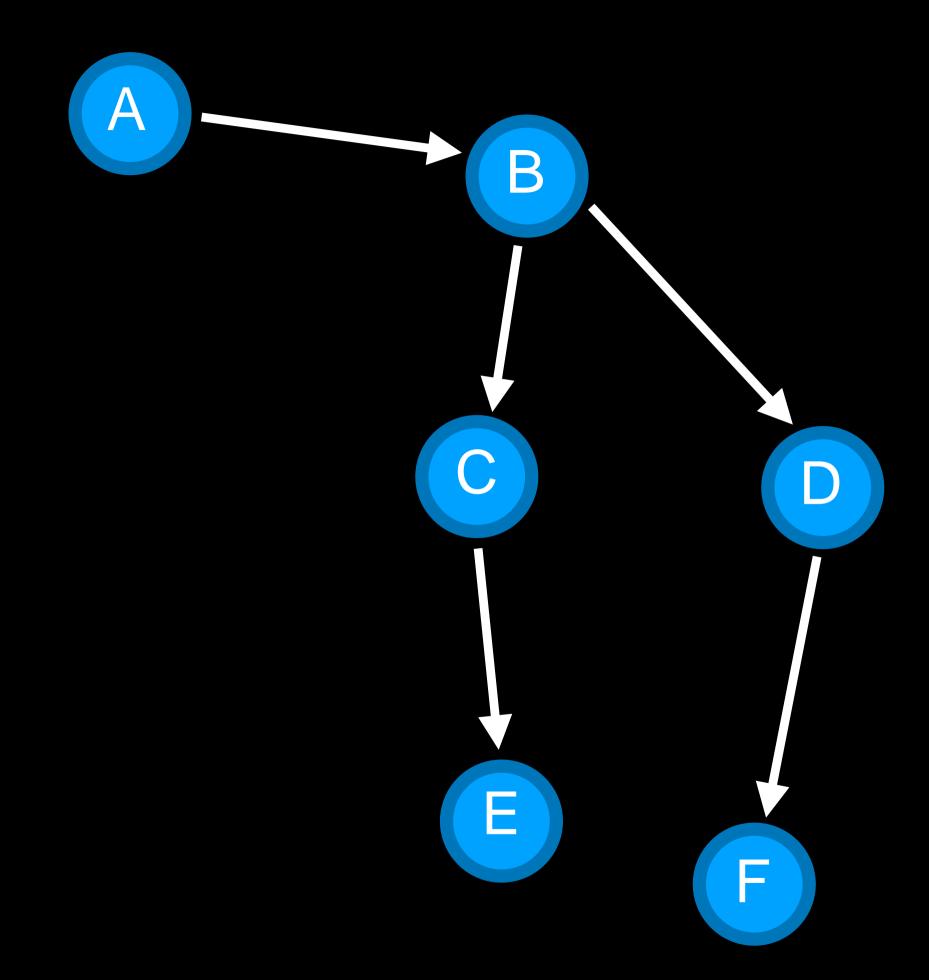
first-in first-out data type

Frontier



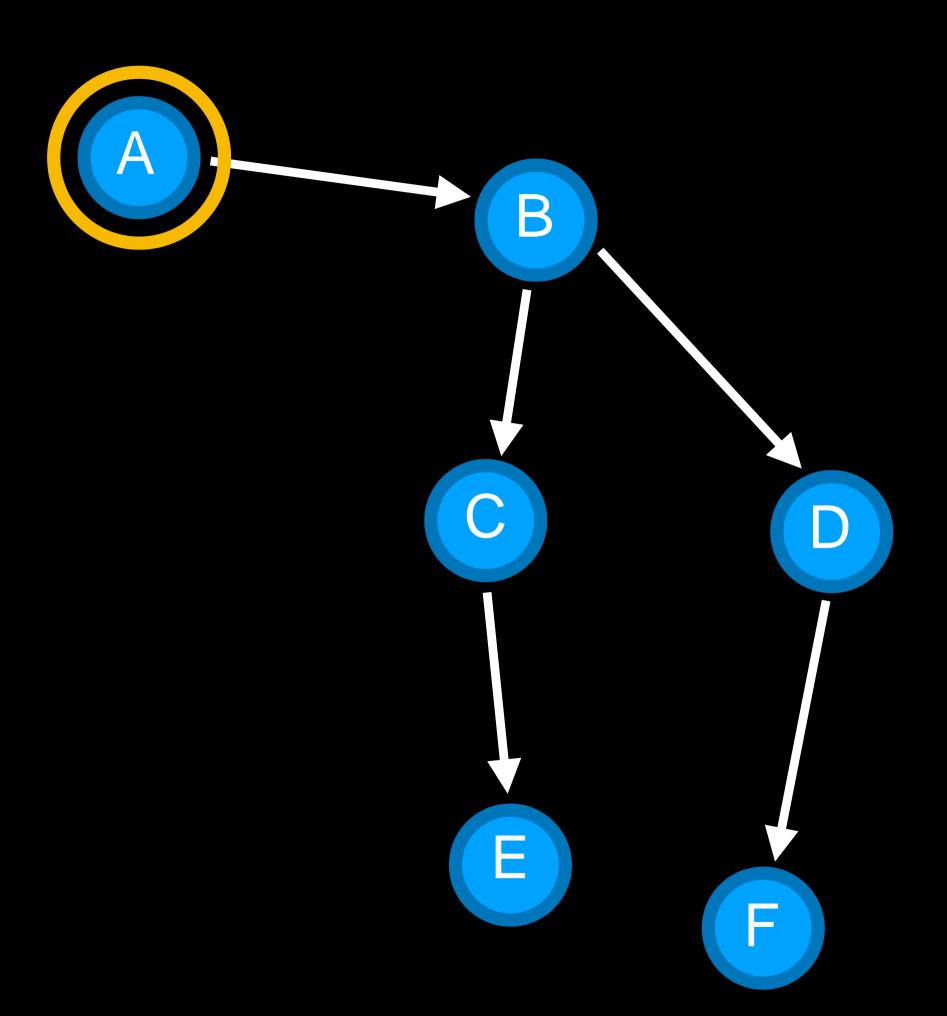
Frontier





Frontier

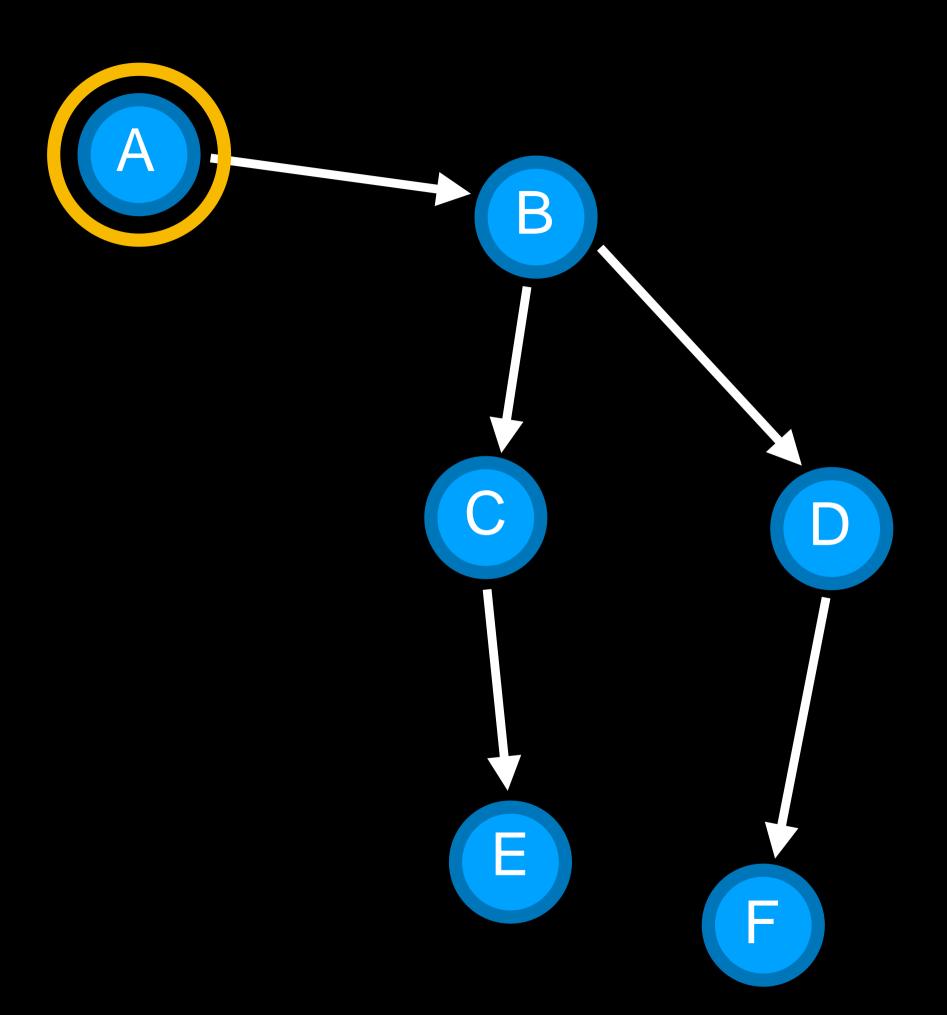




Frontier





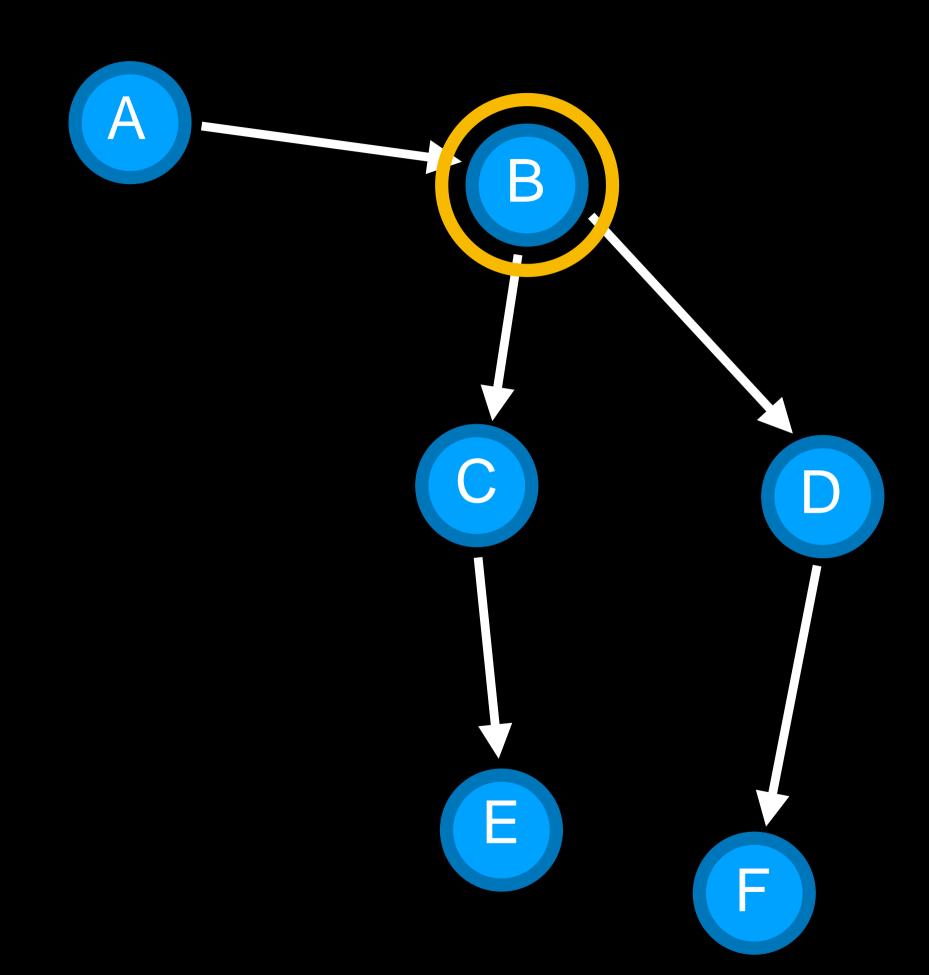


Frontier

Explored Set



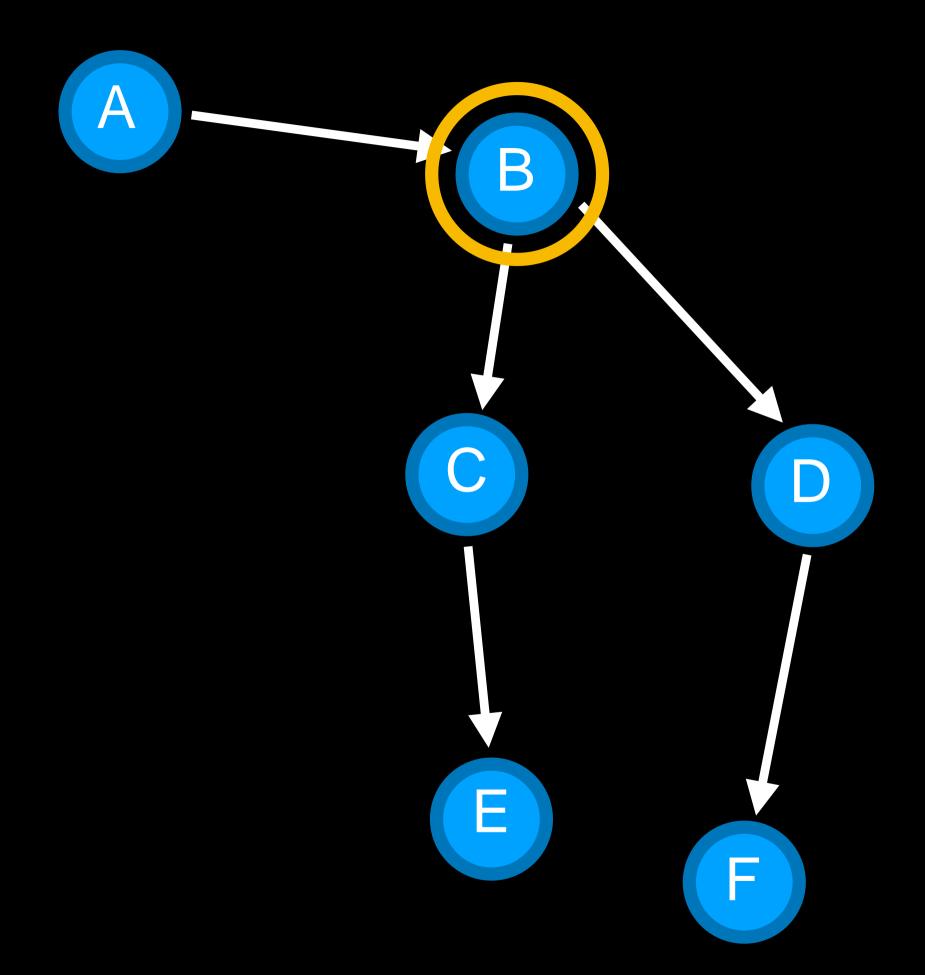




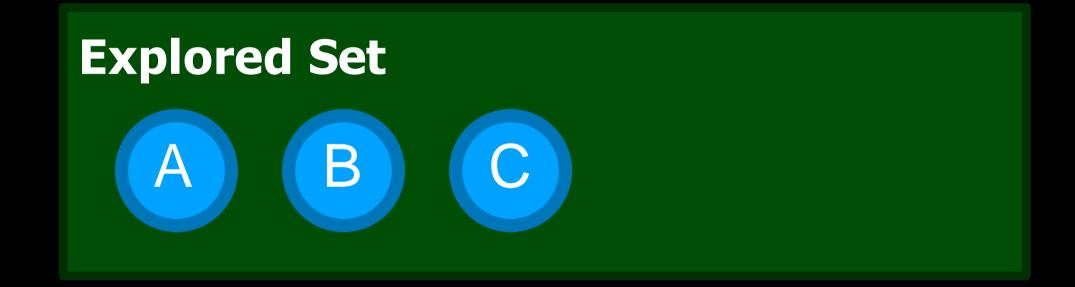
Frontier C D

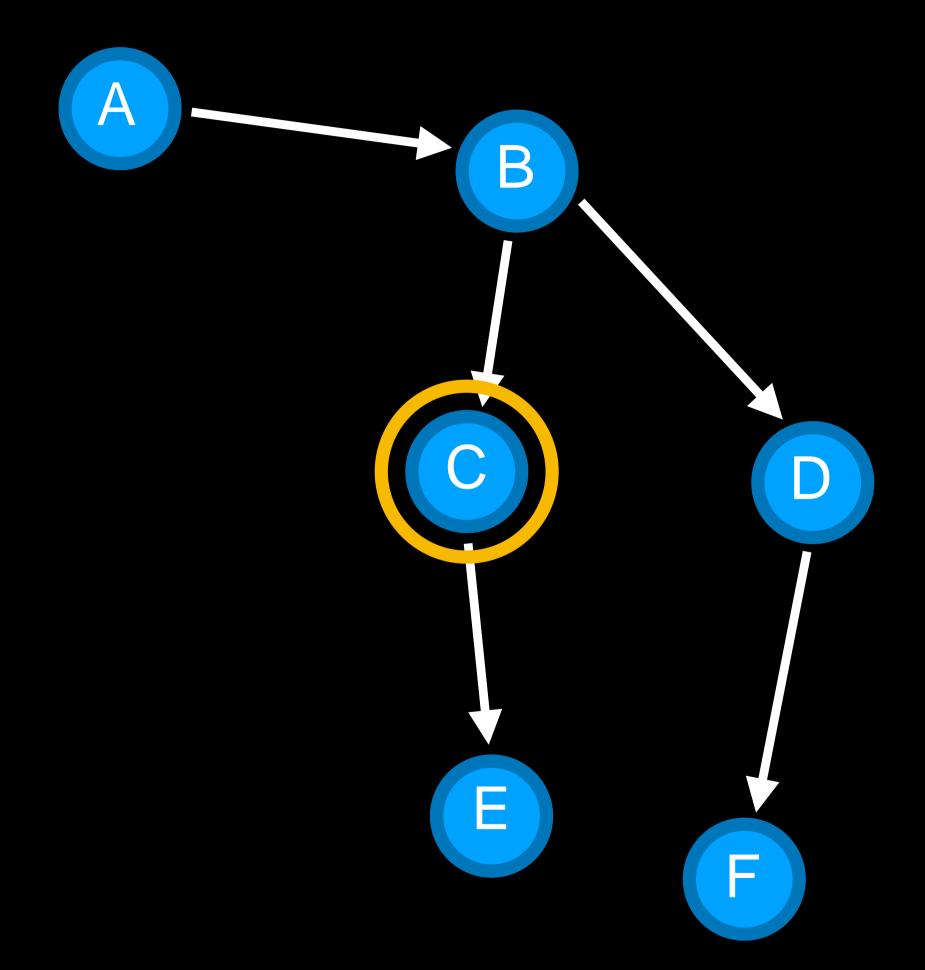
Explored Set



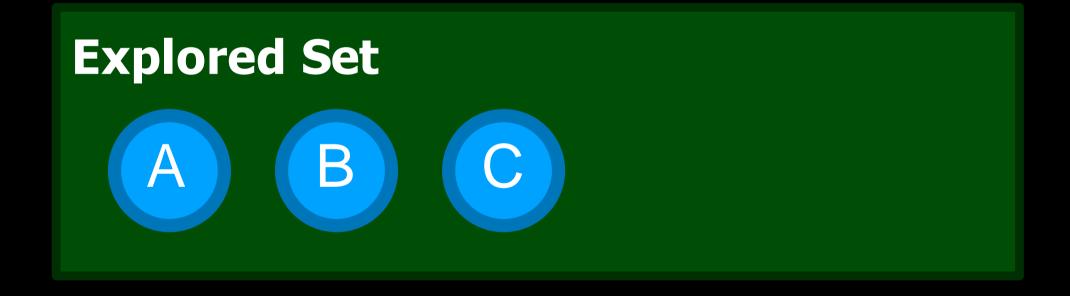


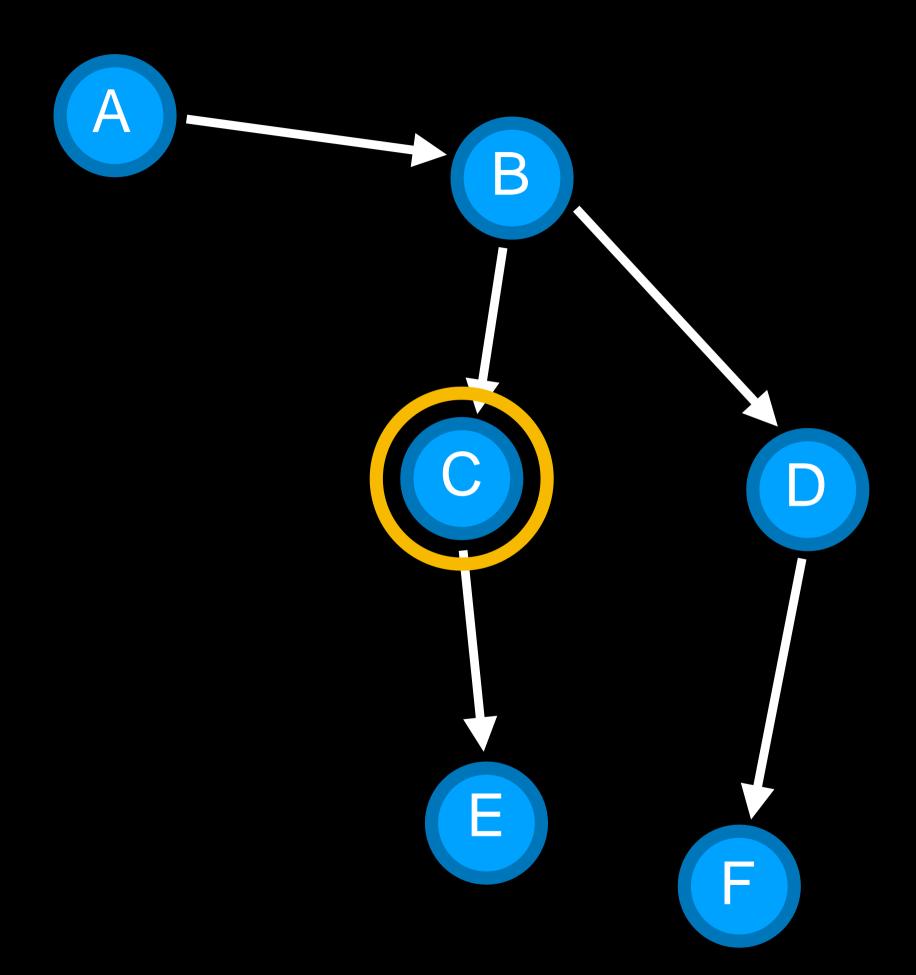
Frontier

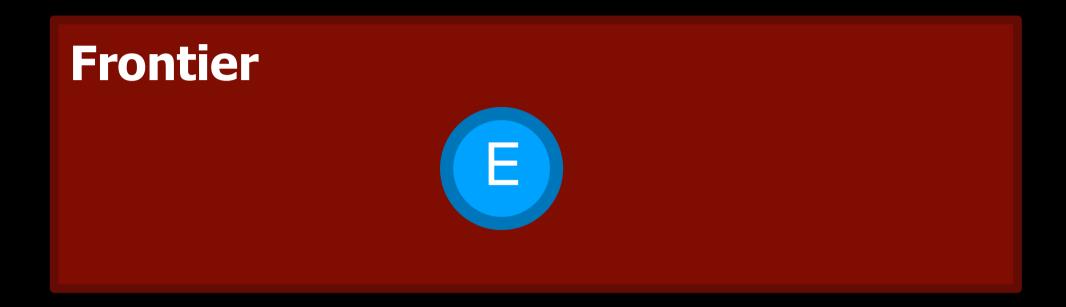


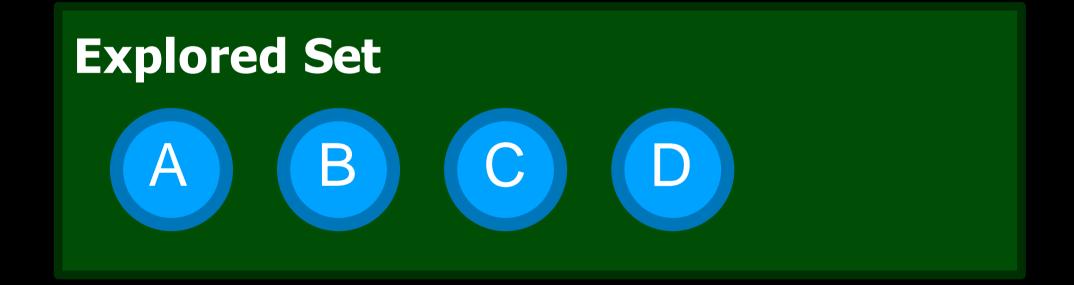


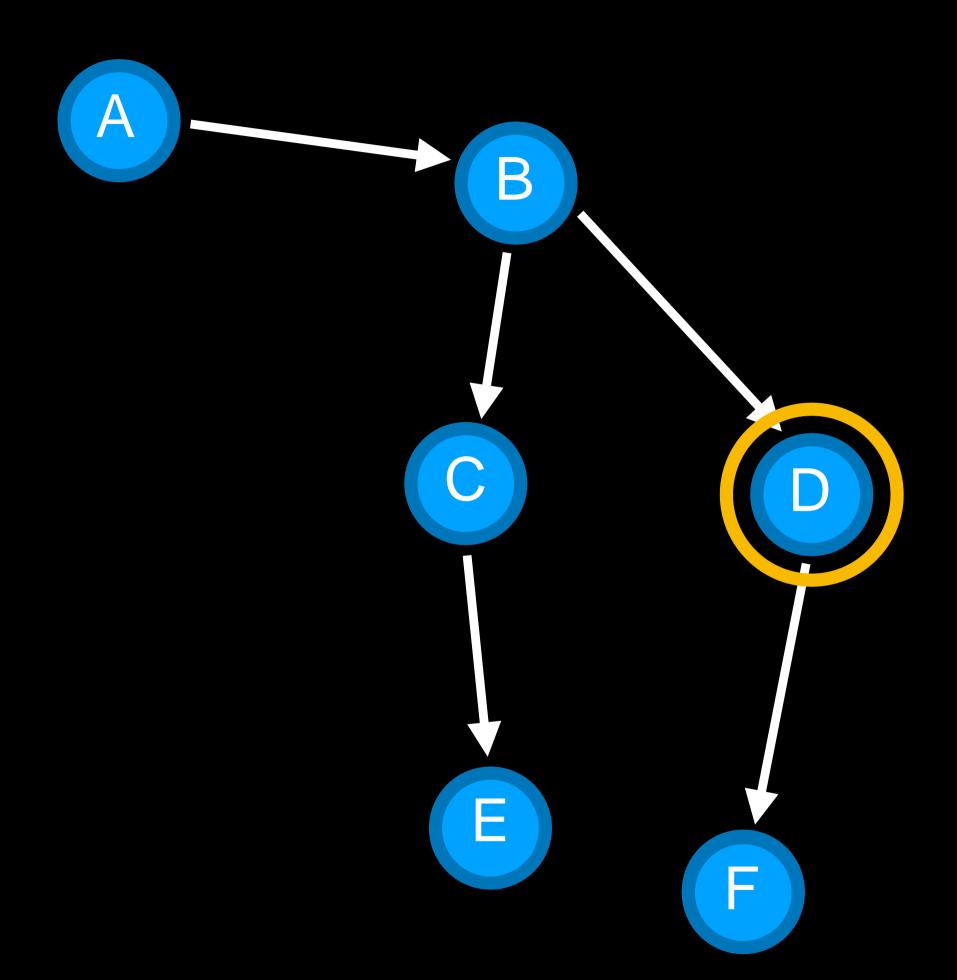
Frontier D E



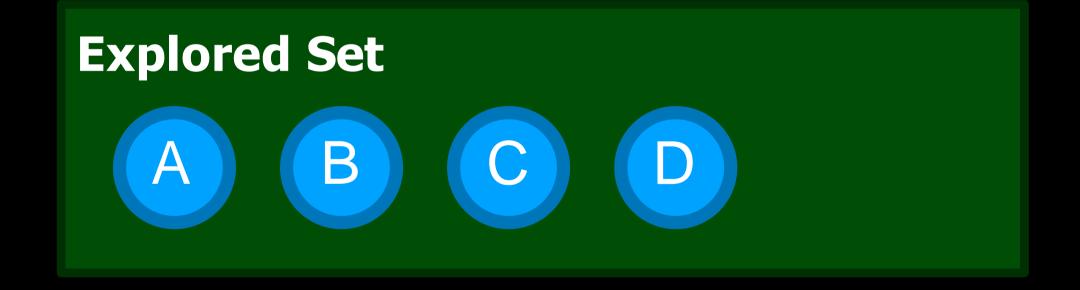


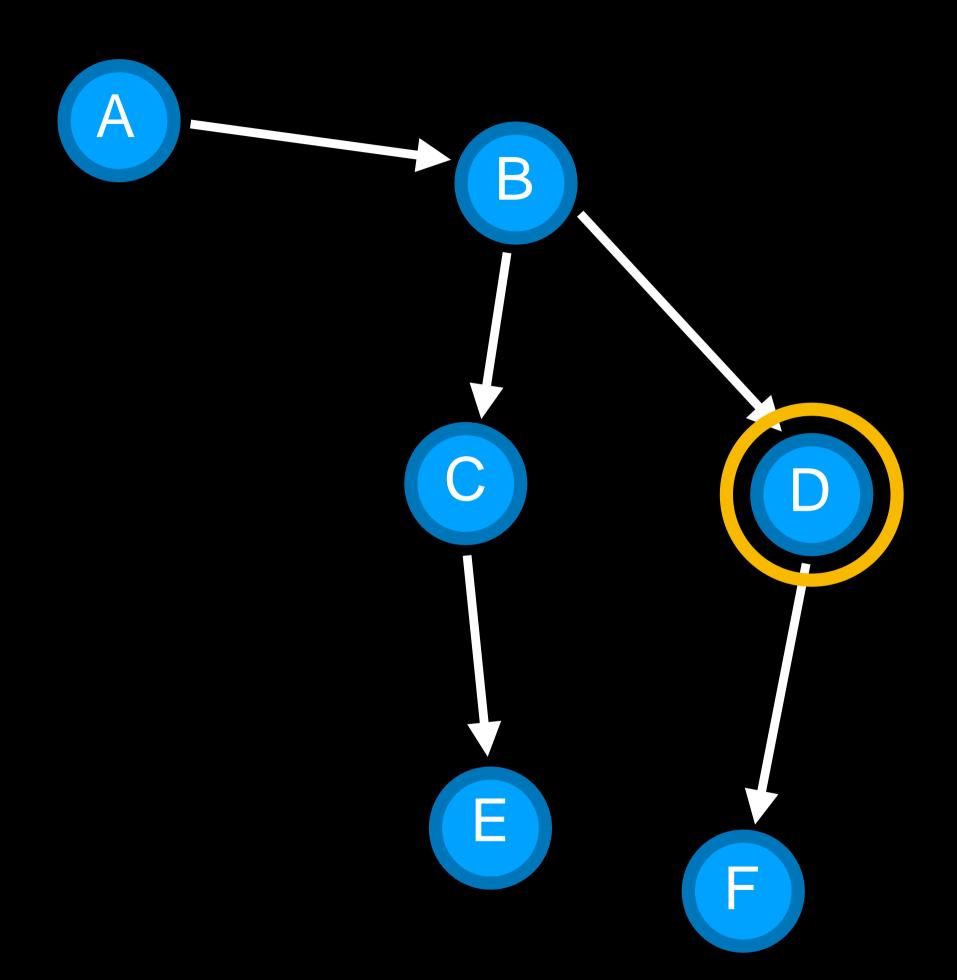


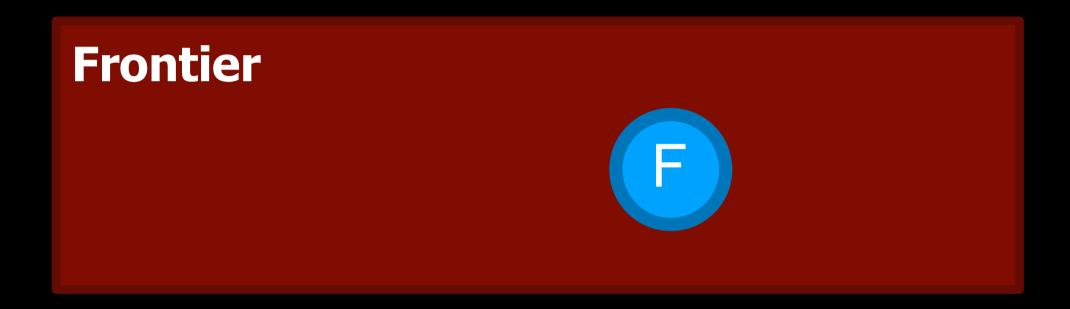


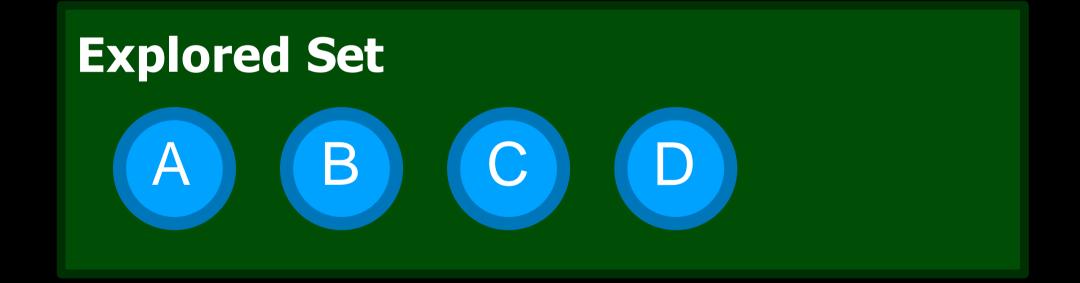


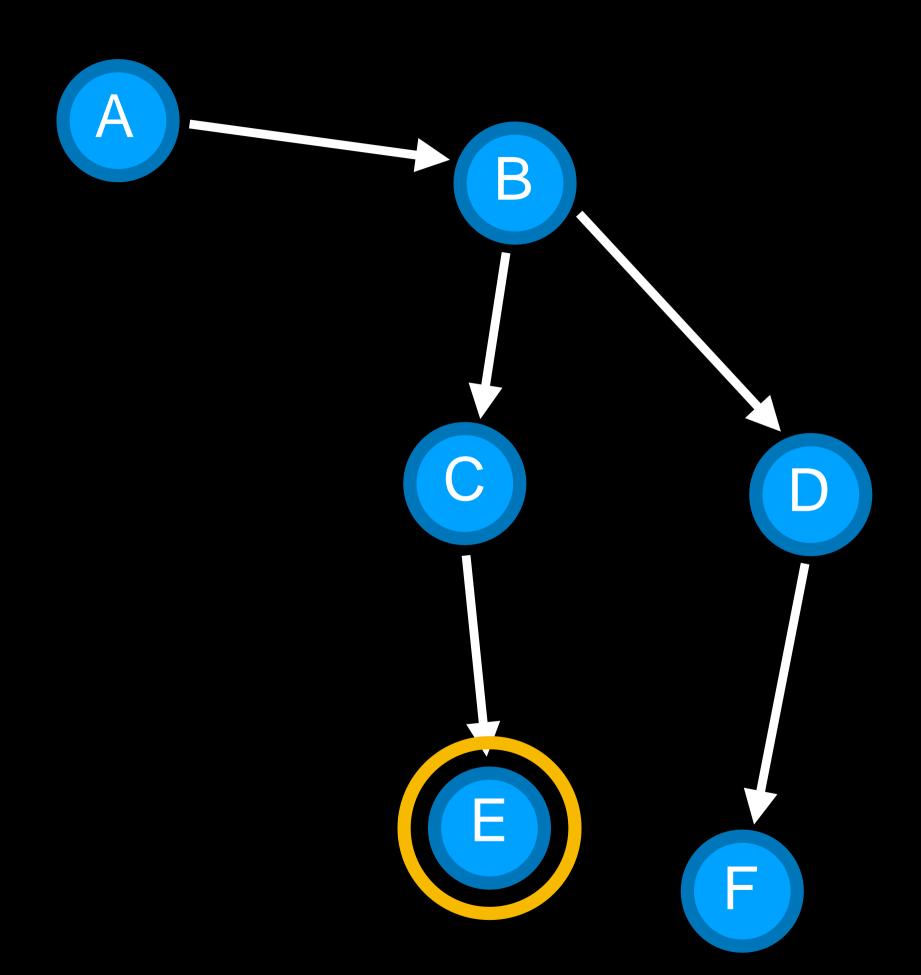
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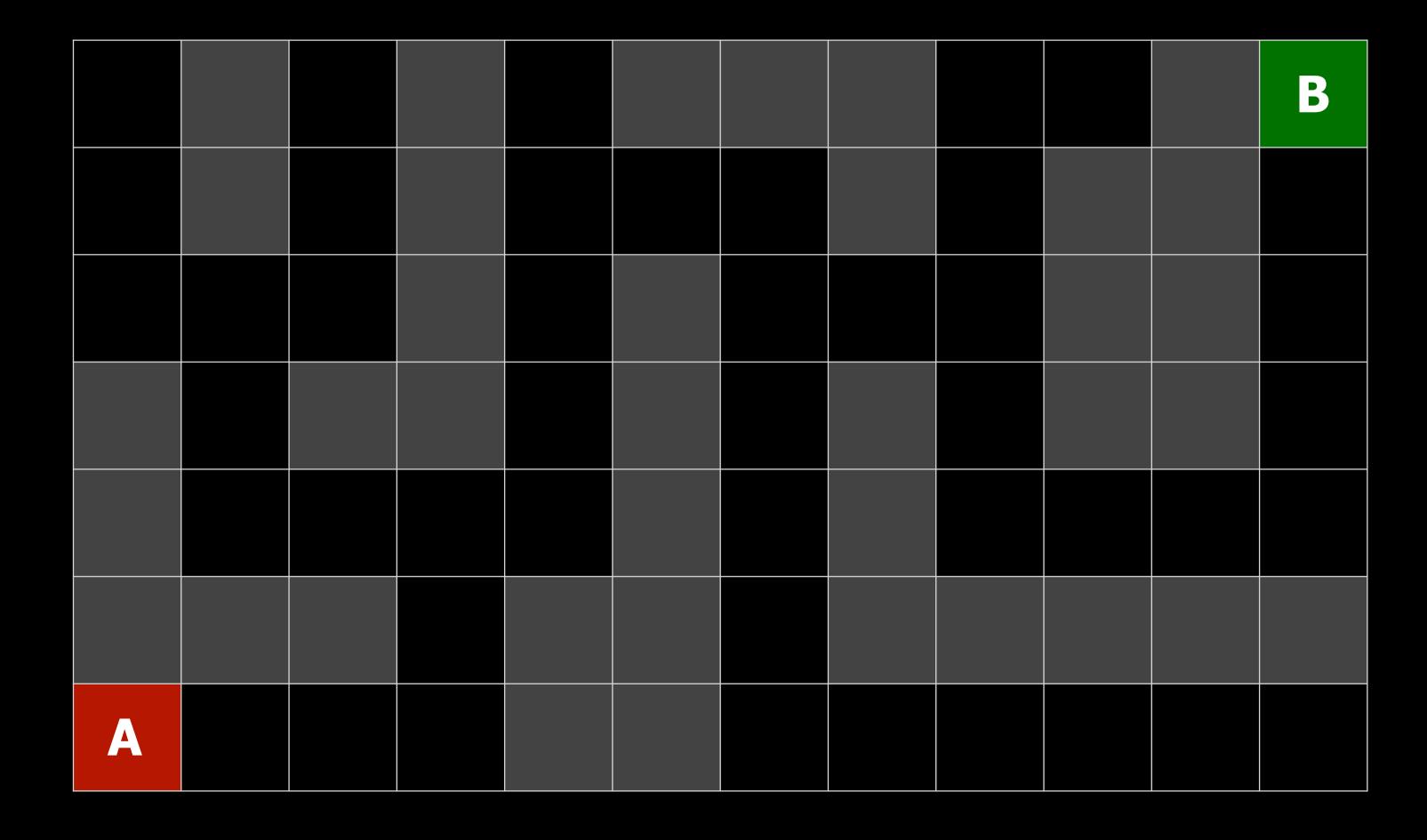


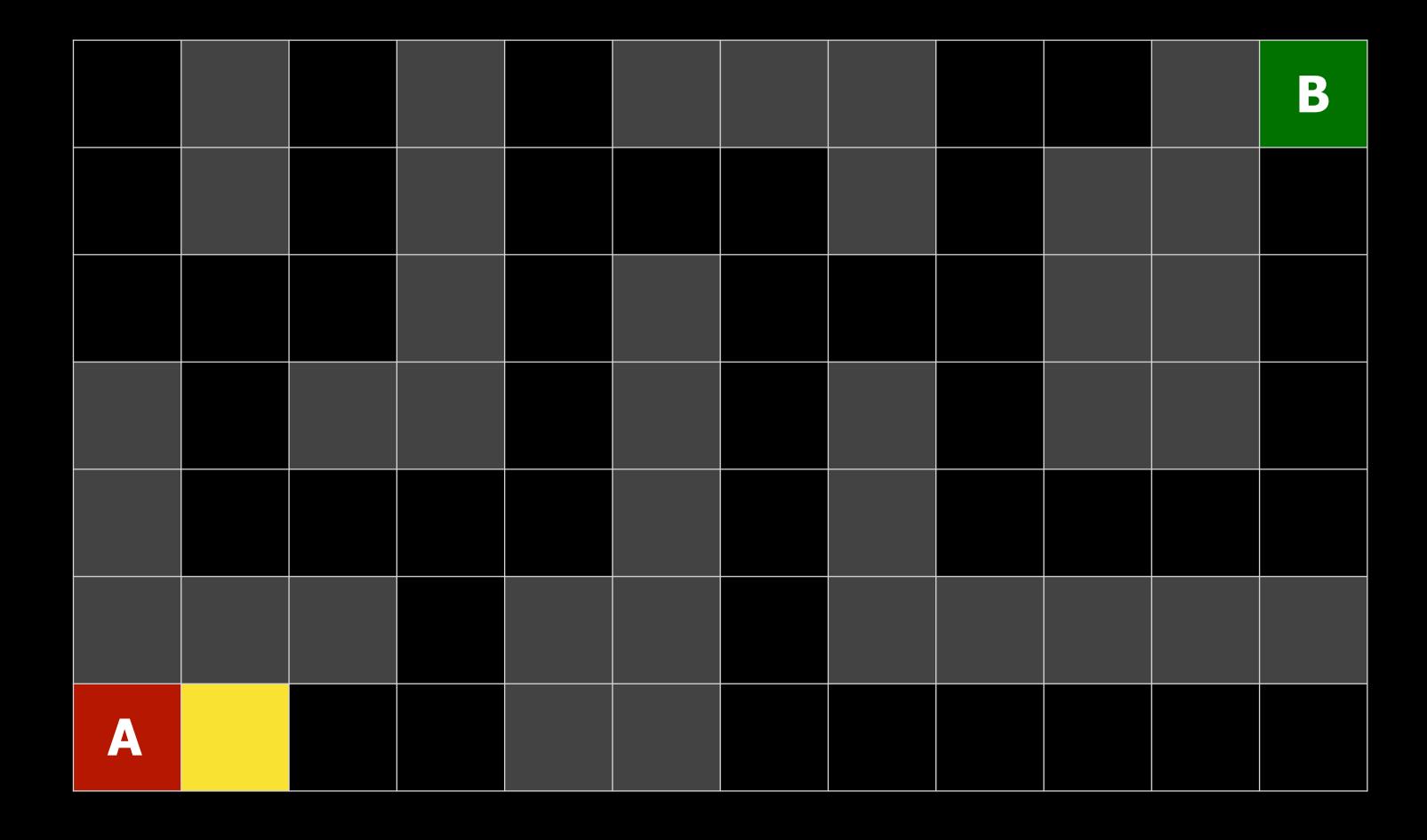


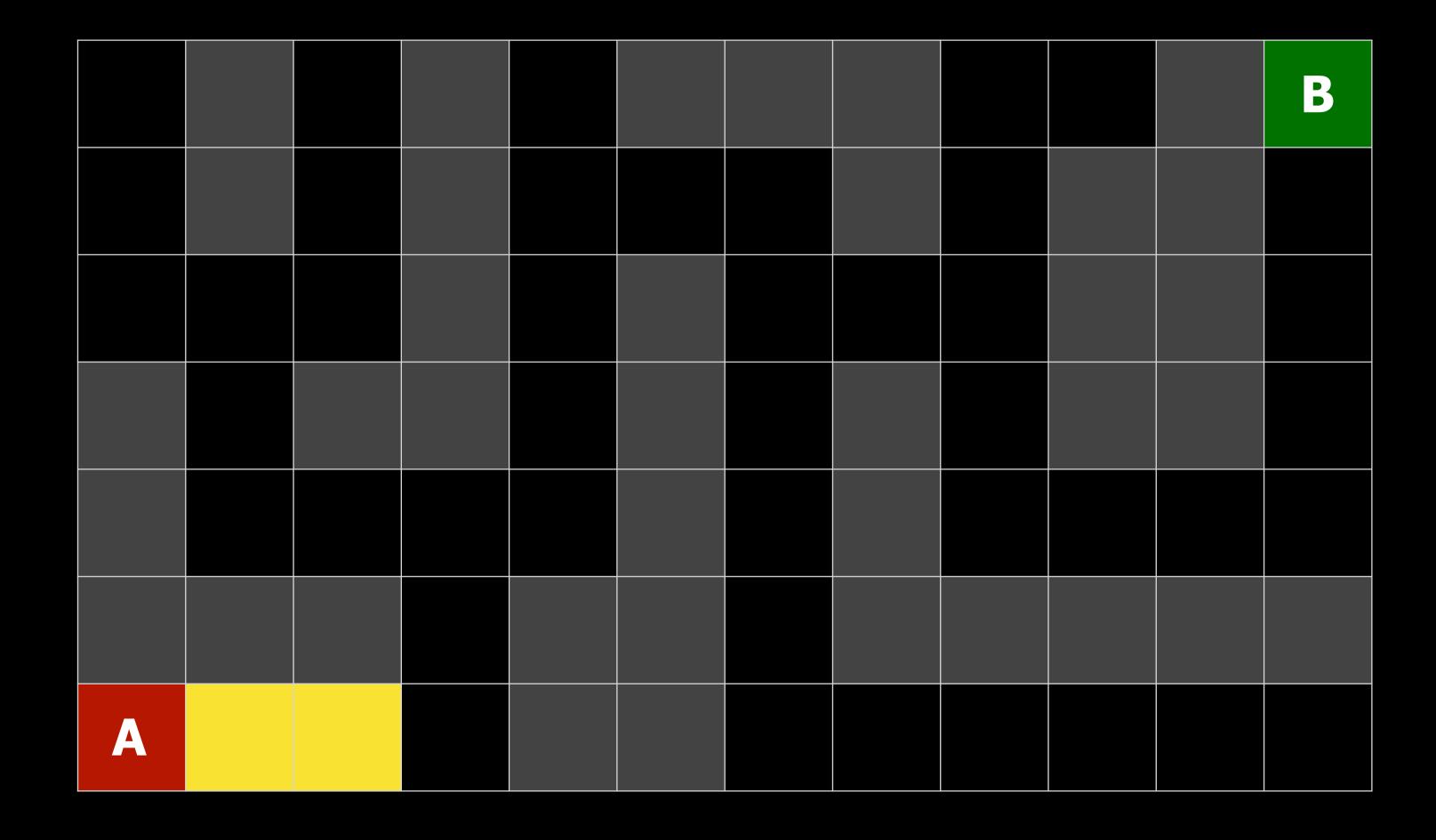


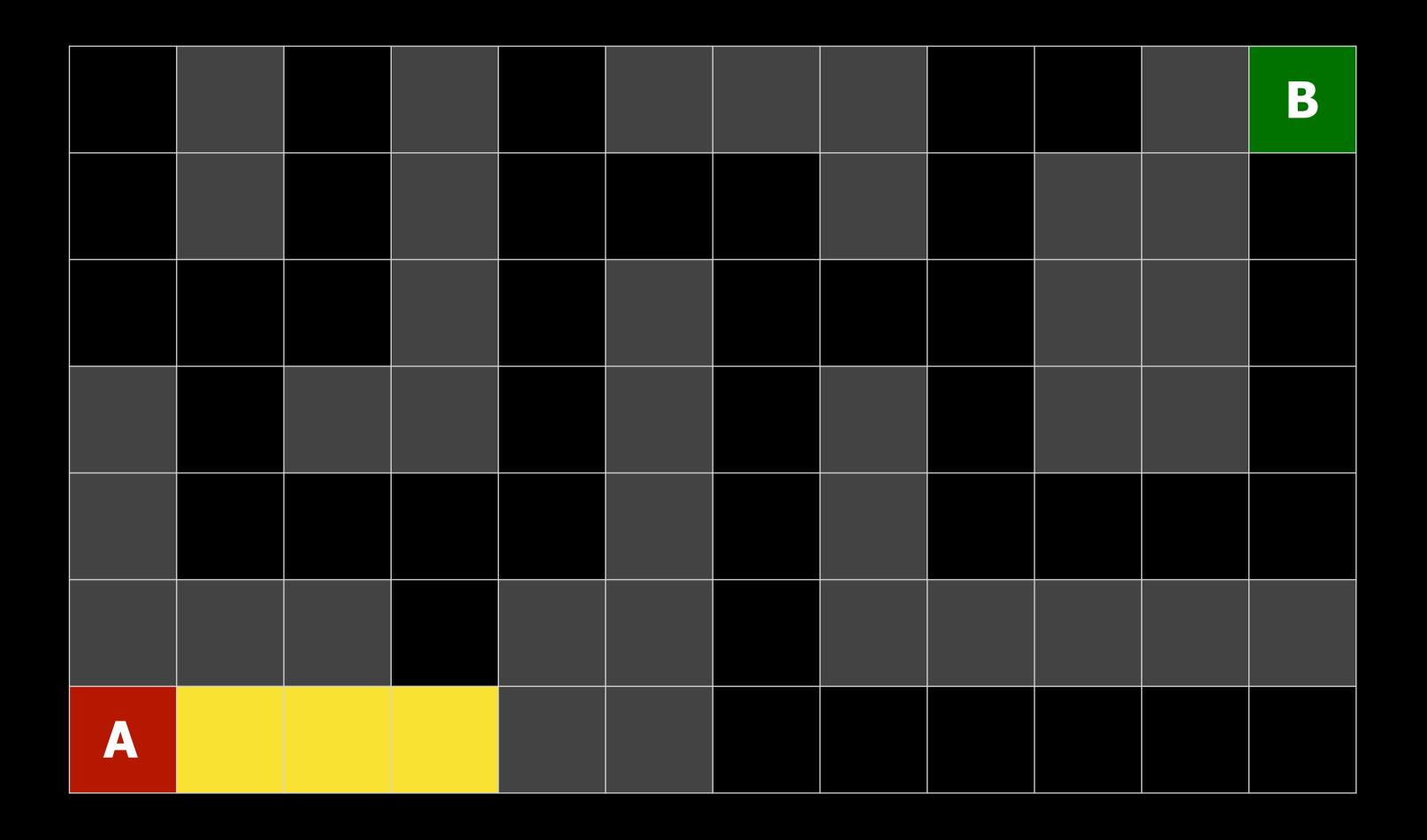


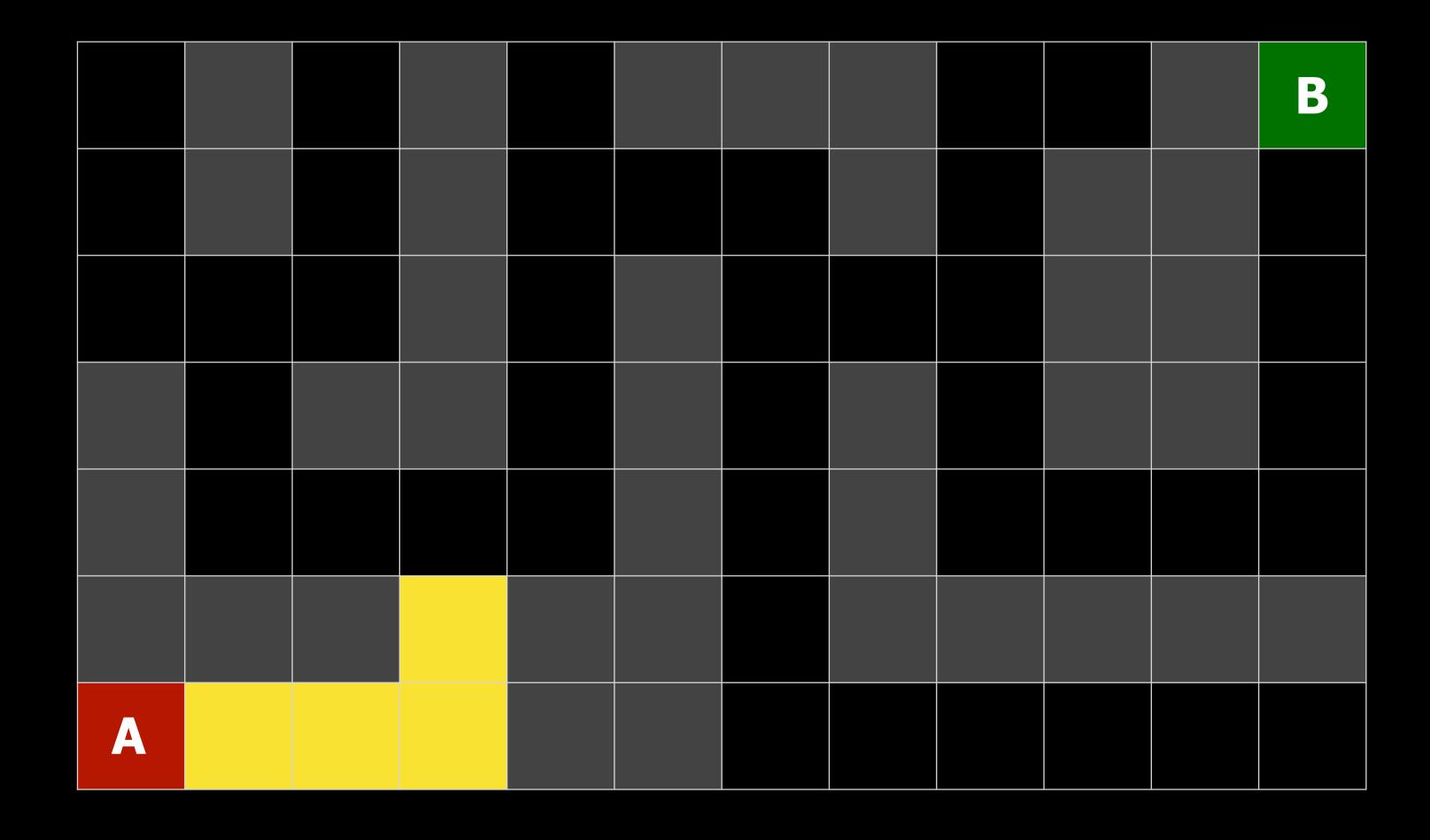


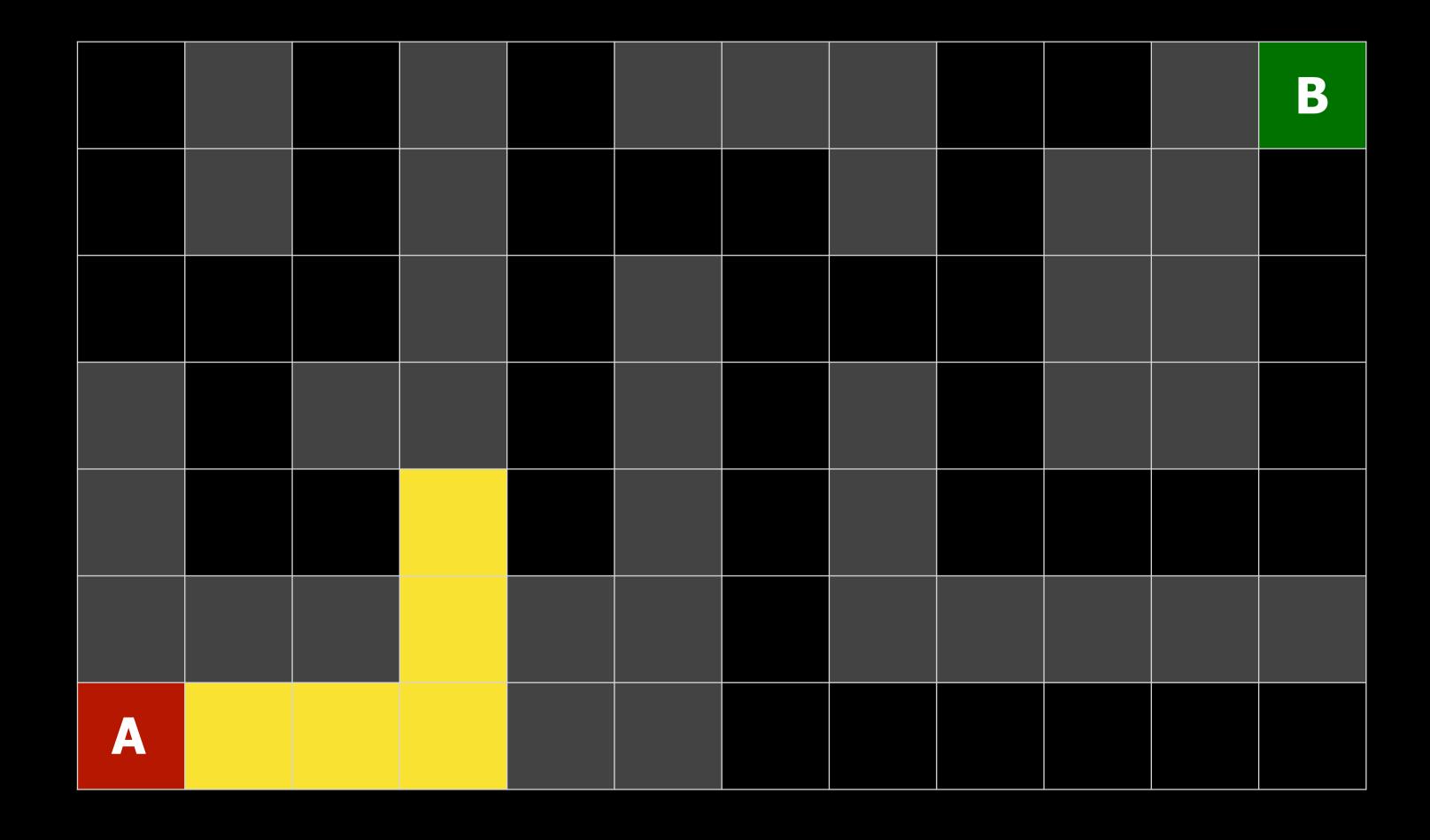


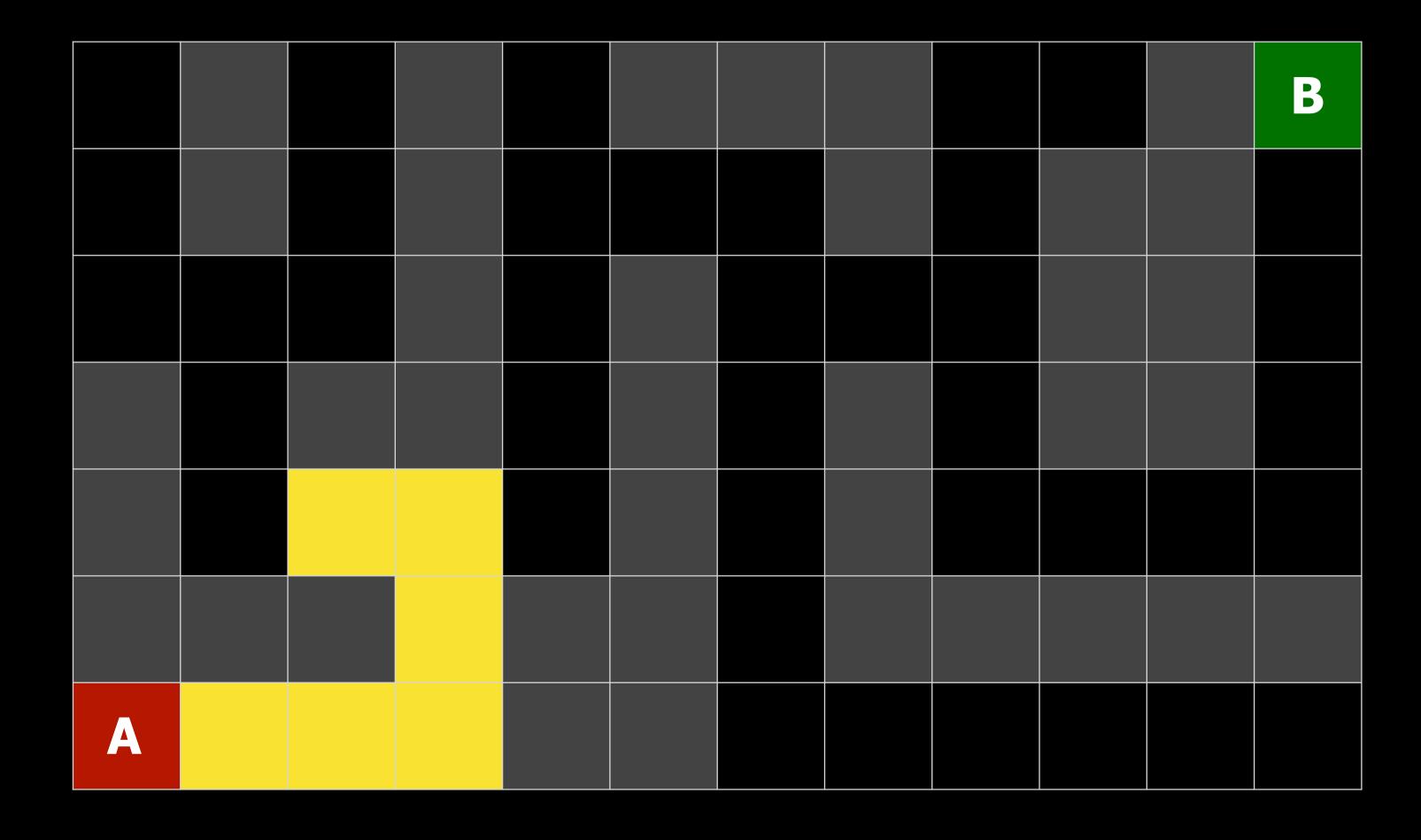


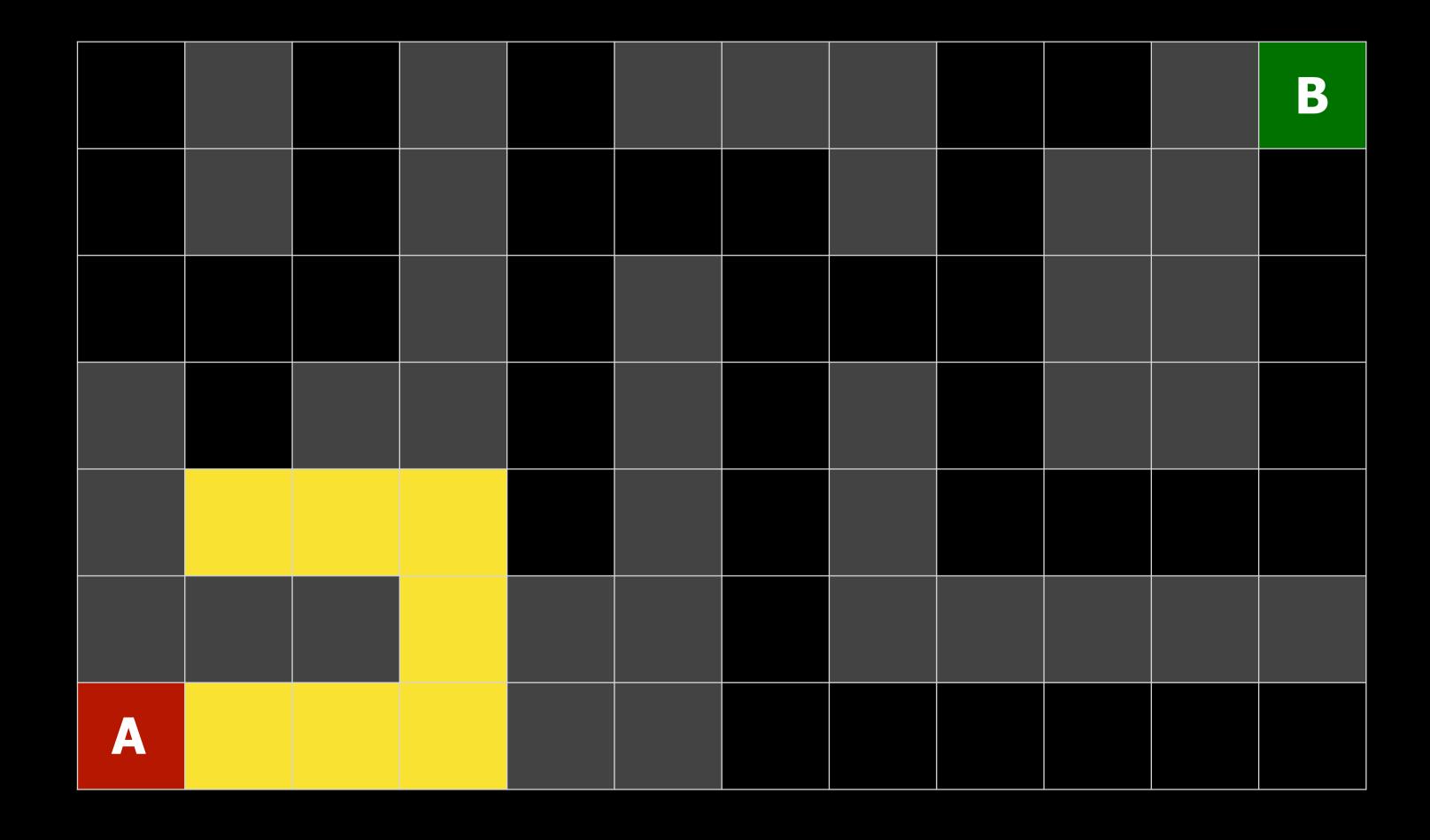


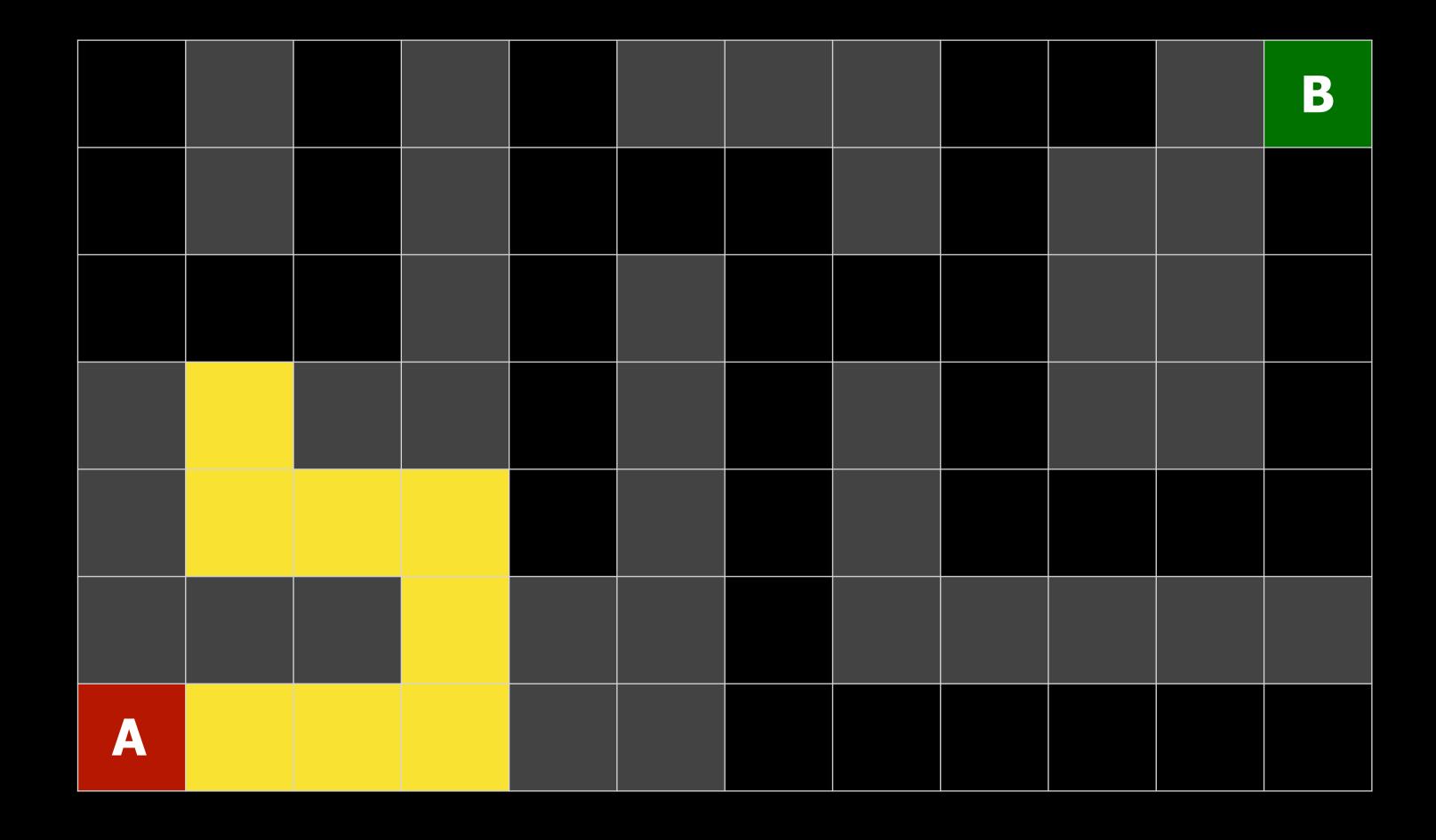


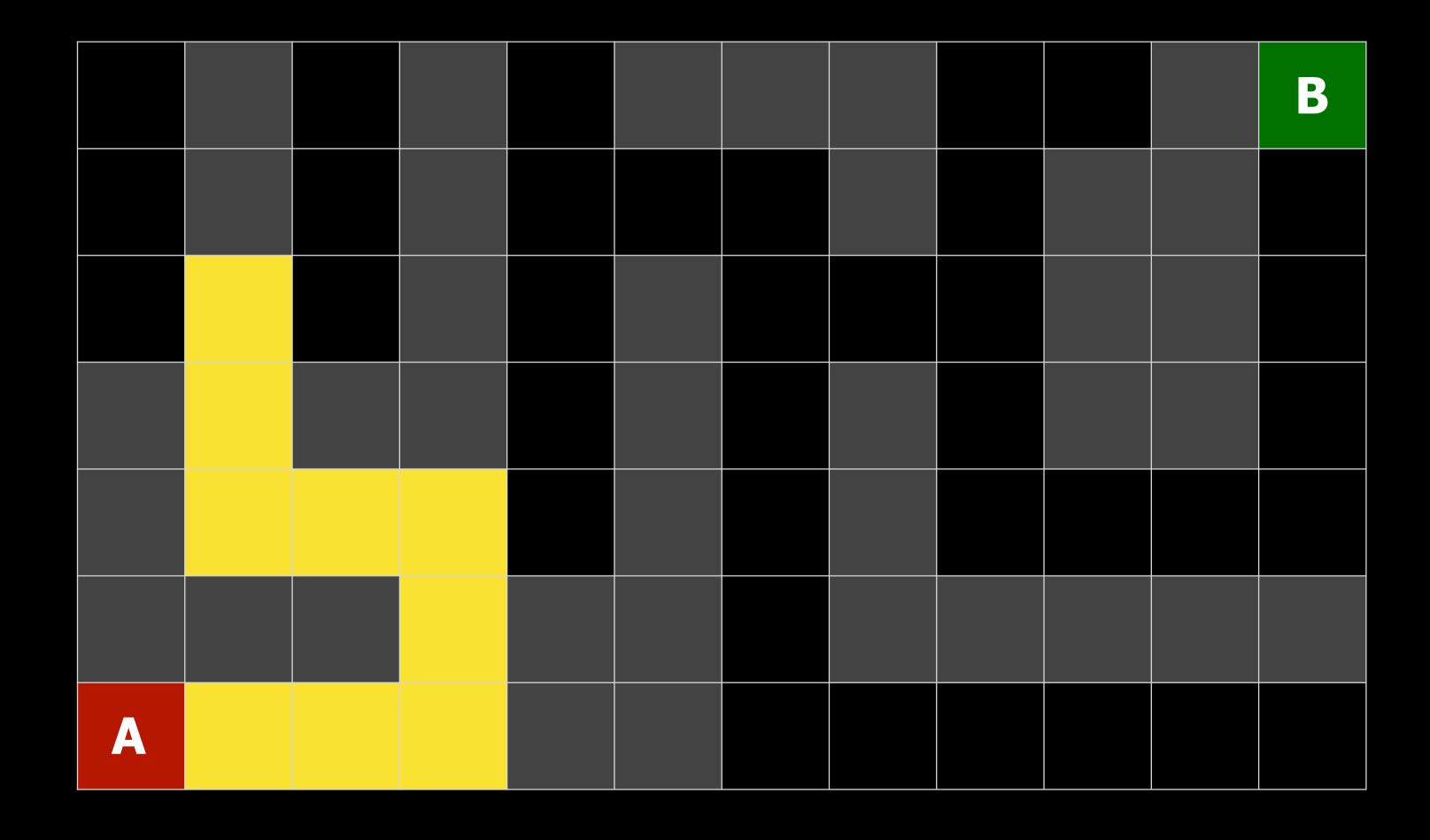


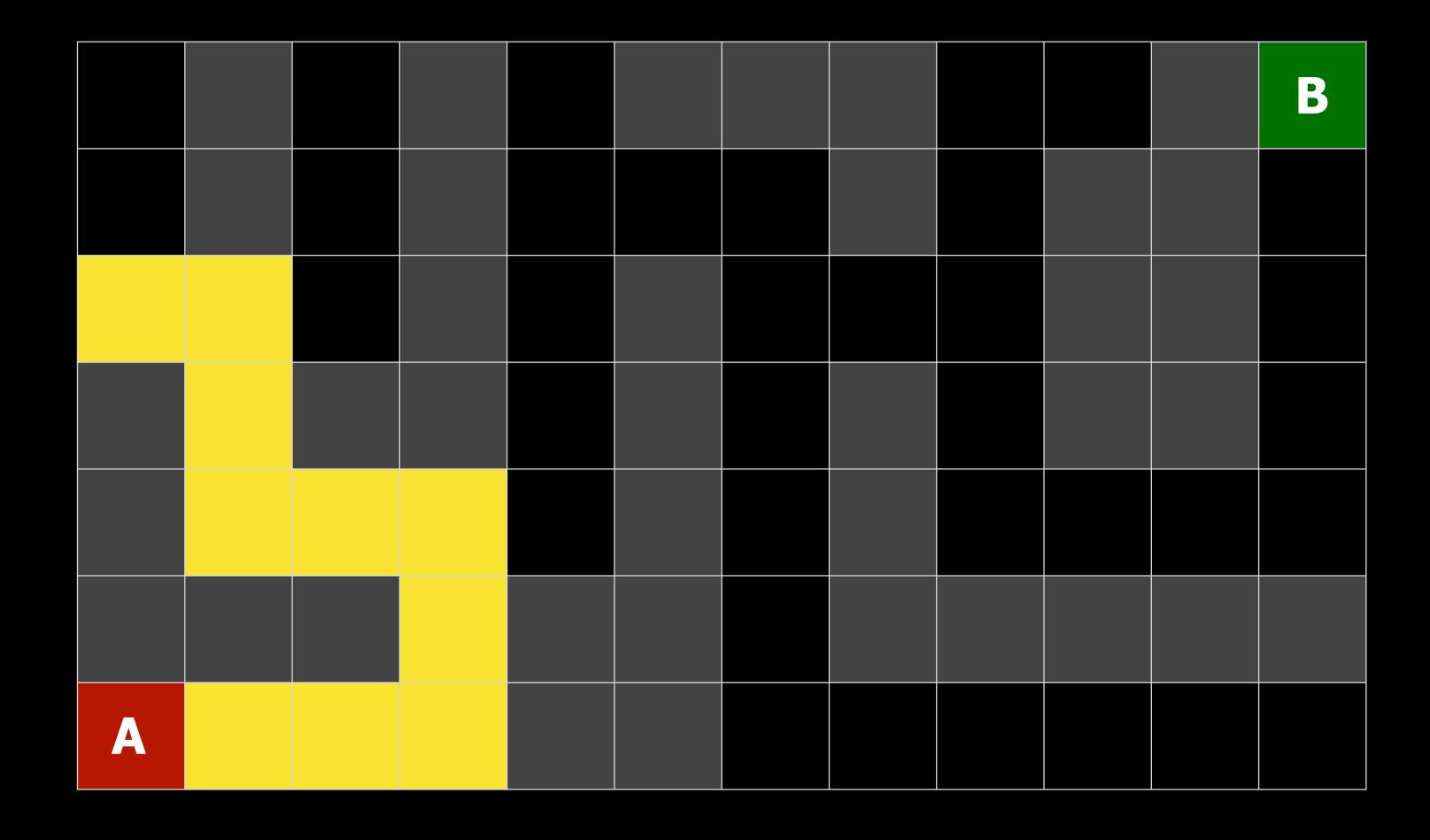


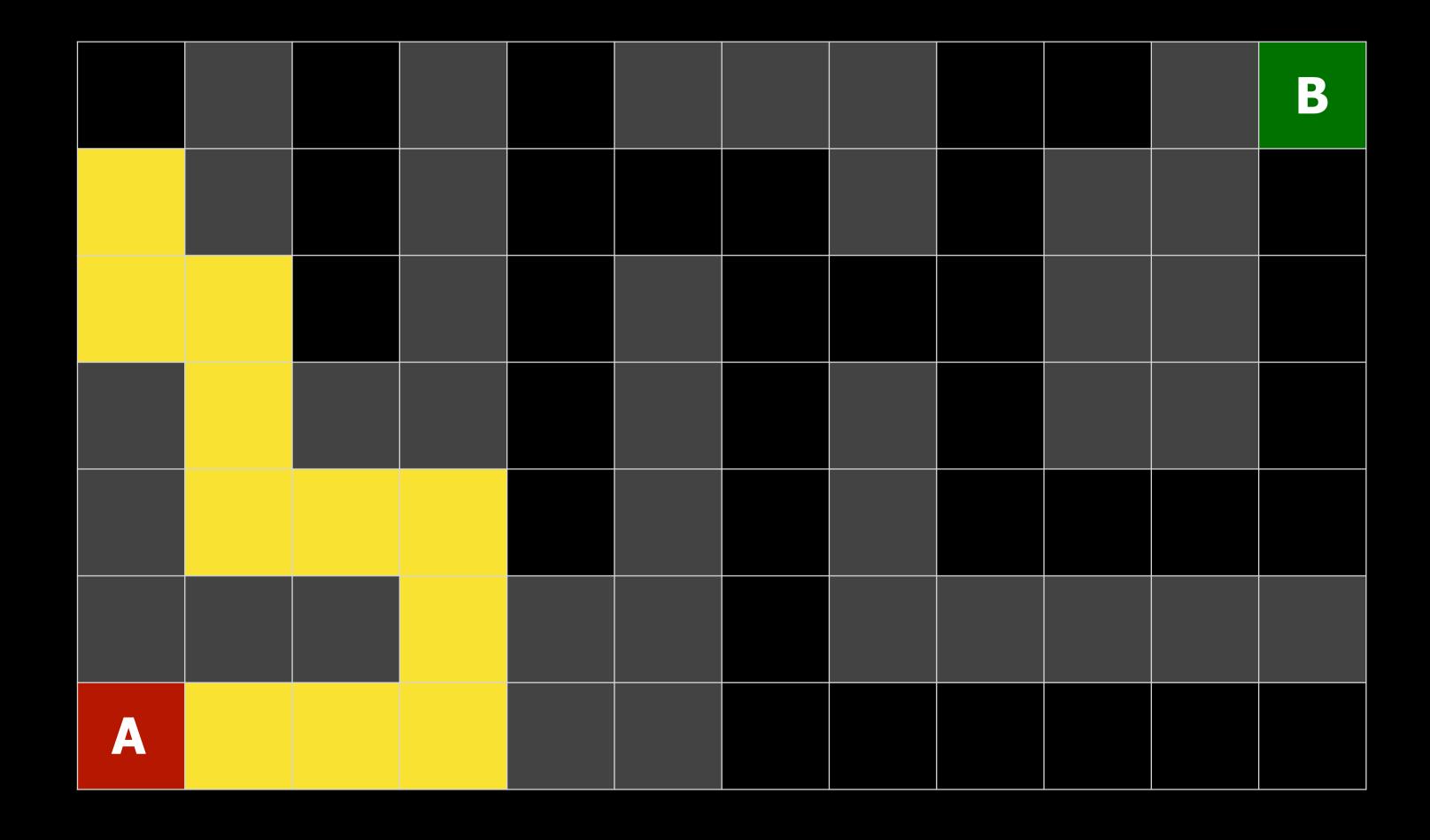


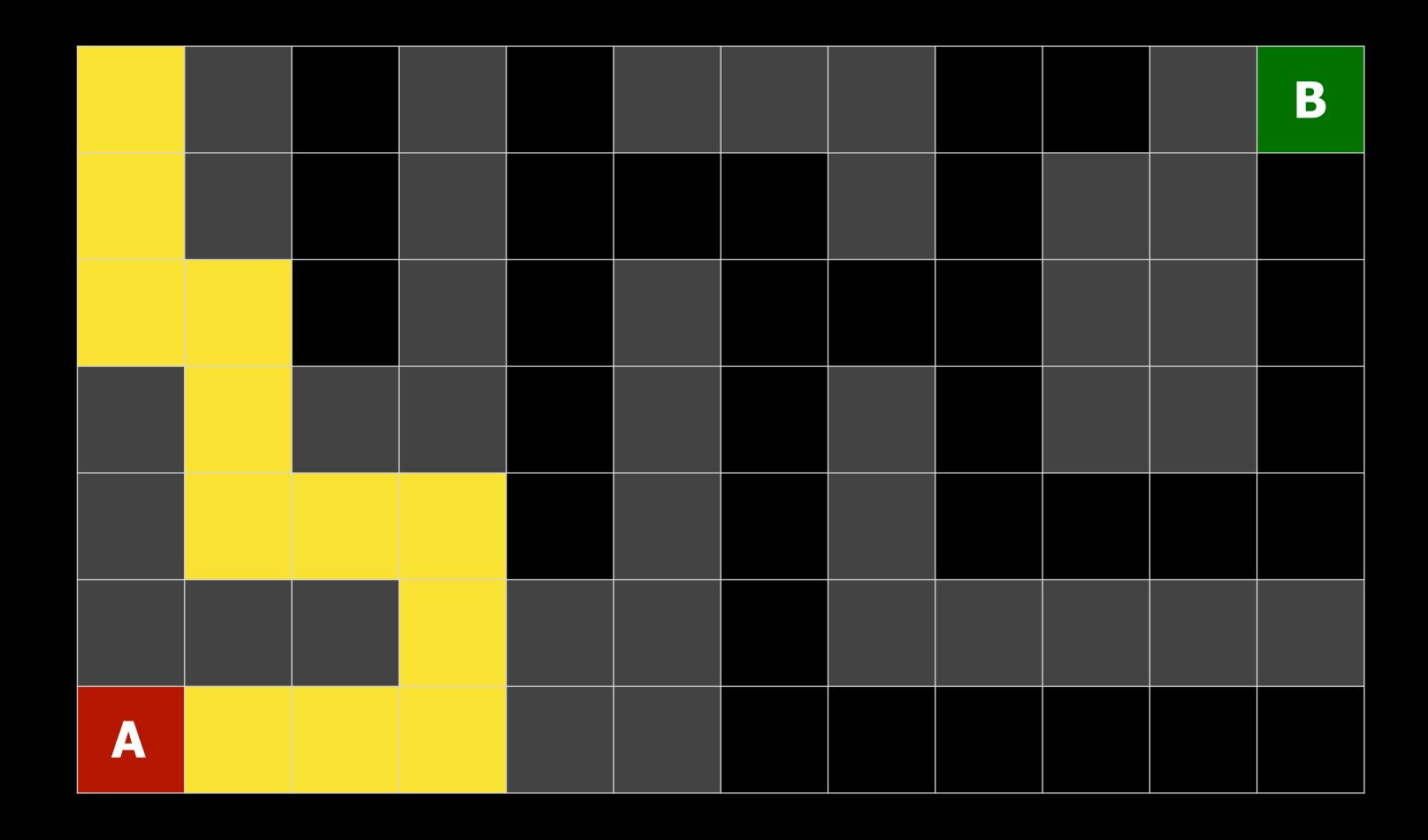


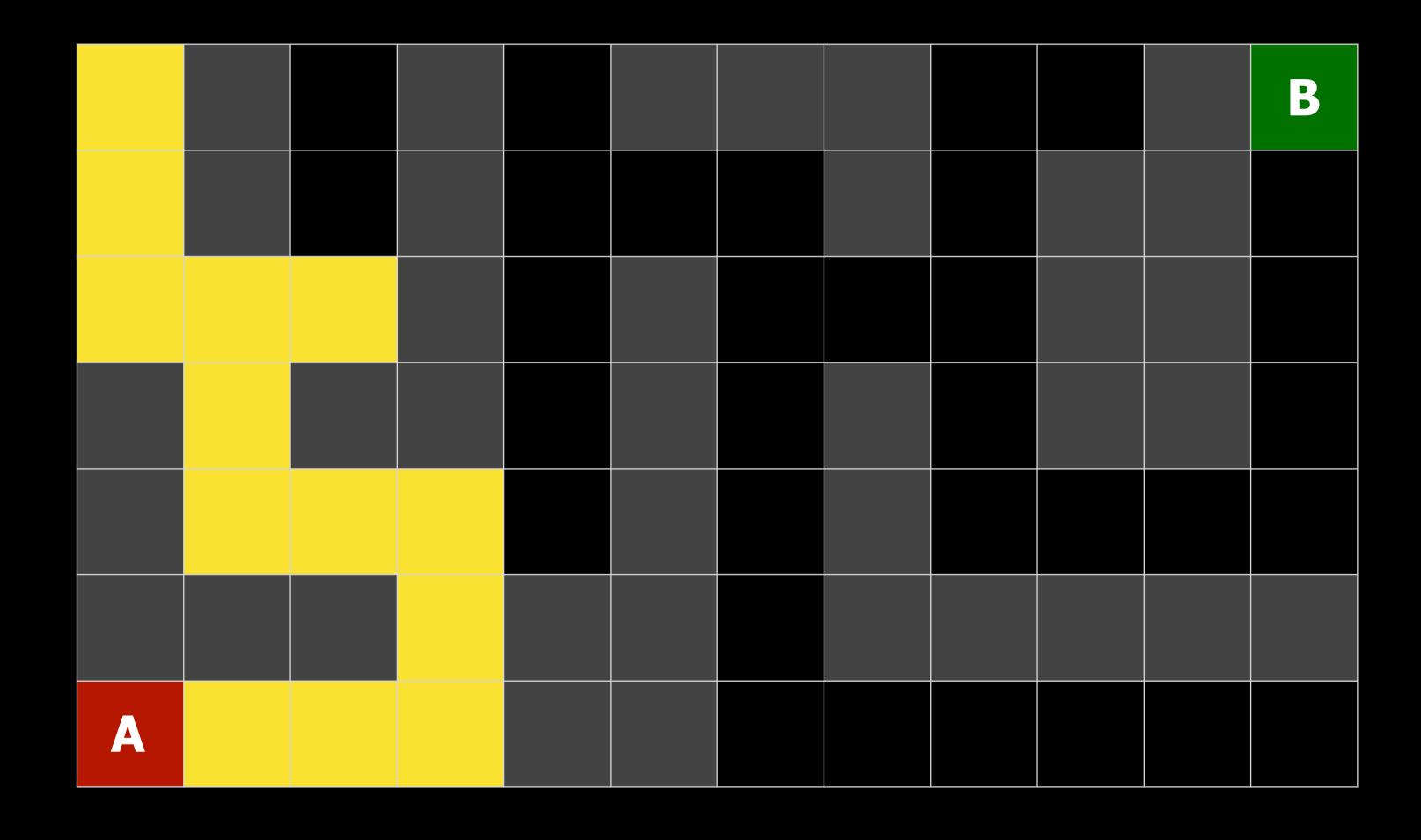


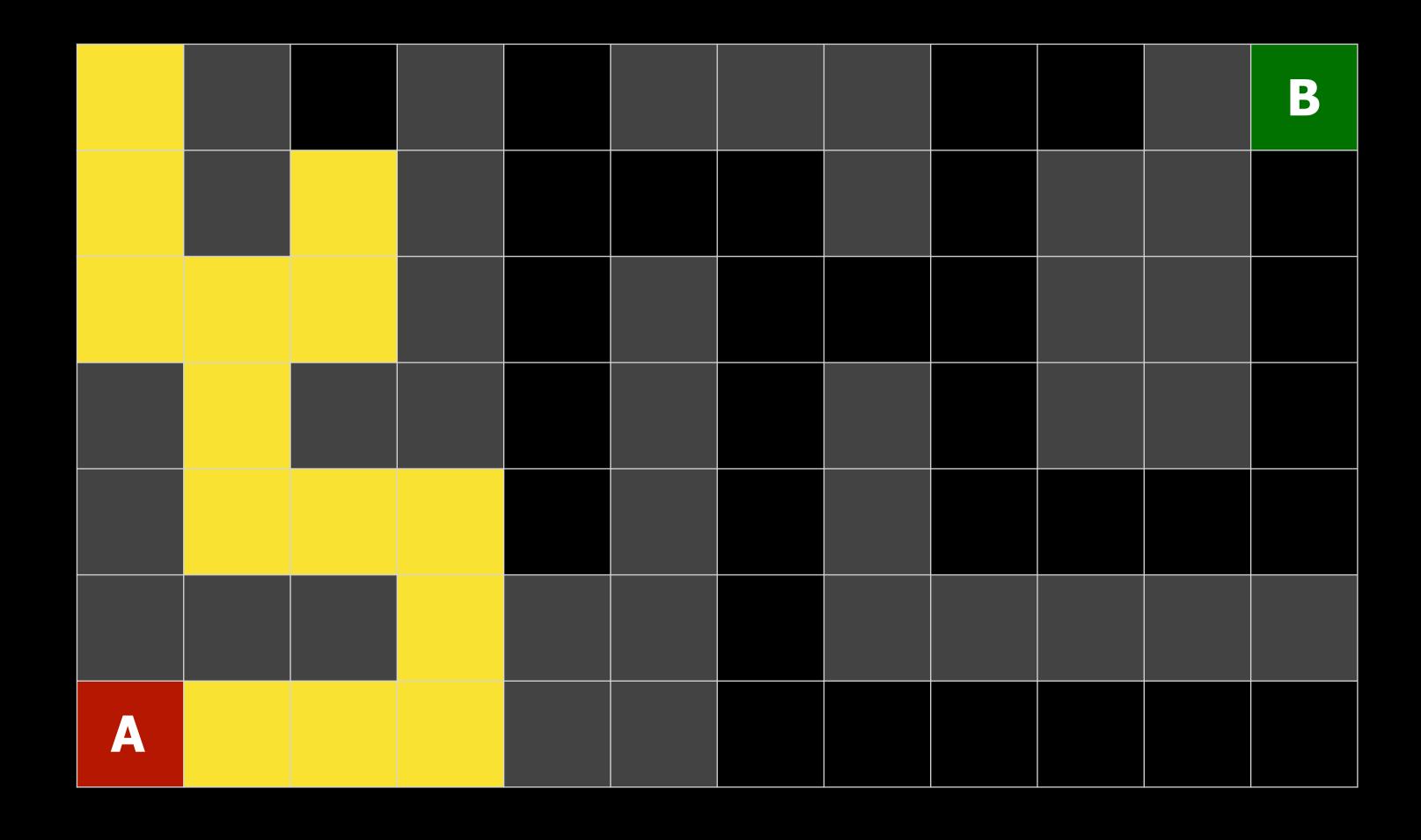


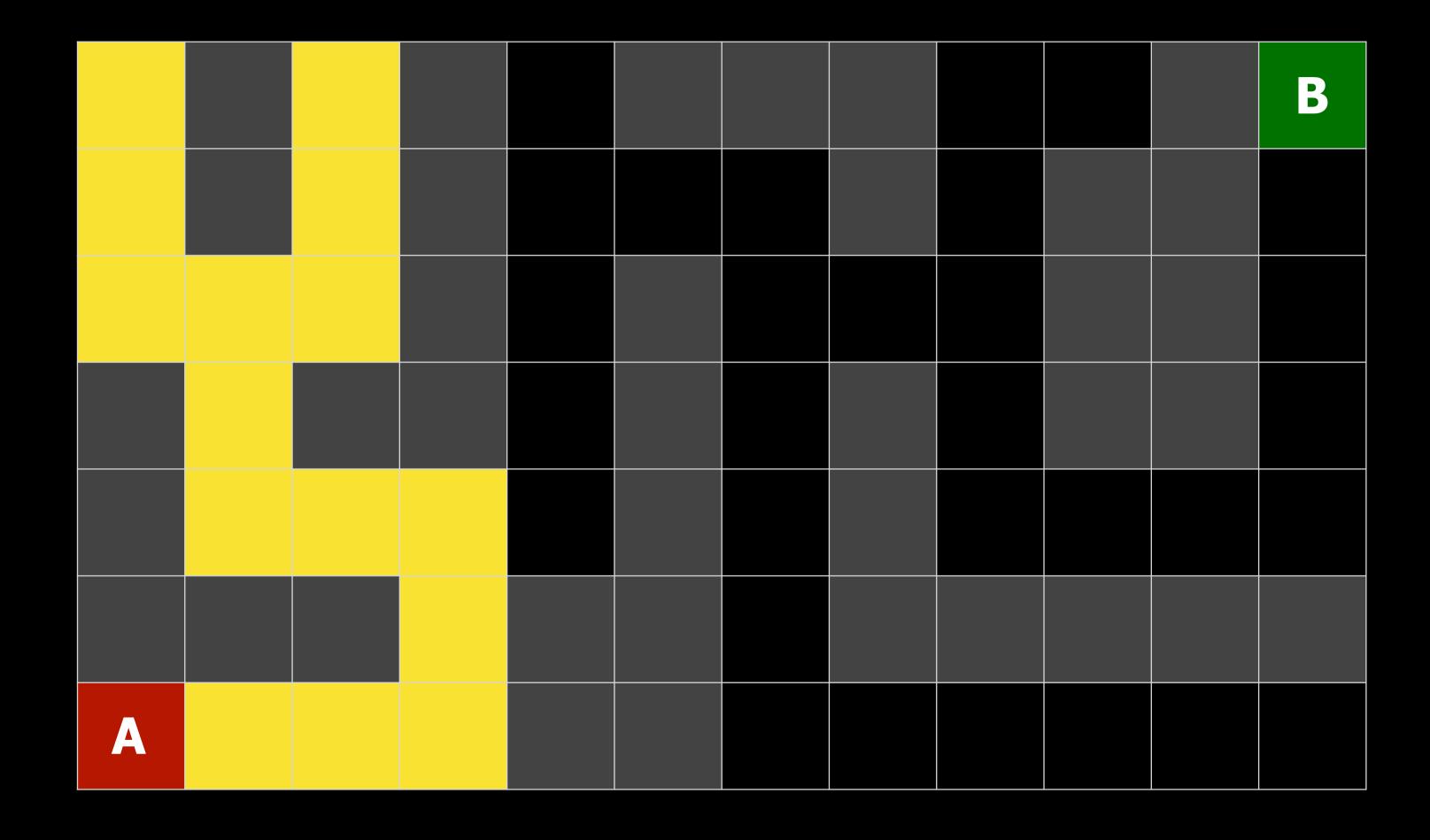


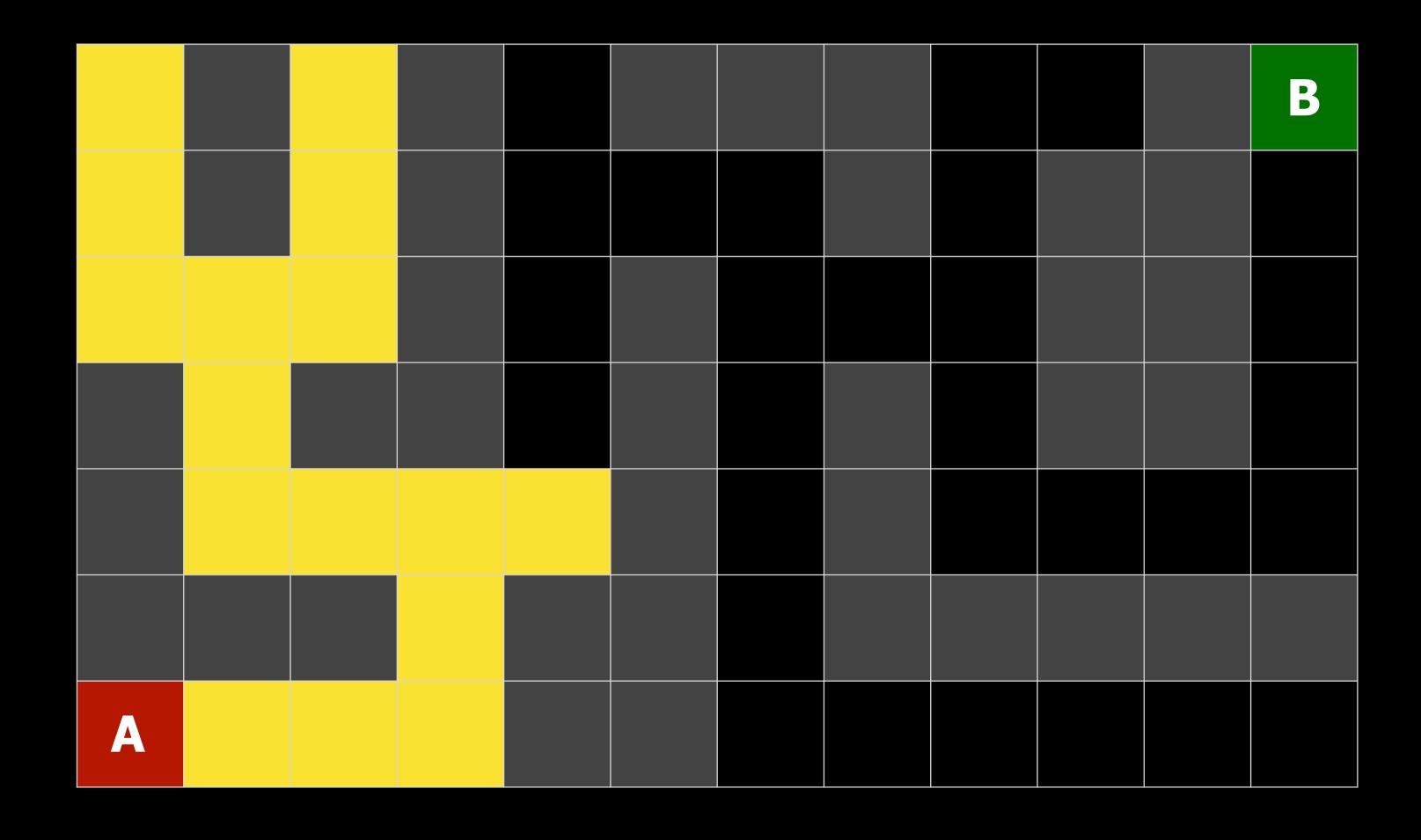


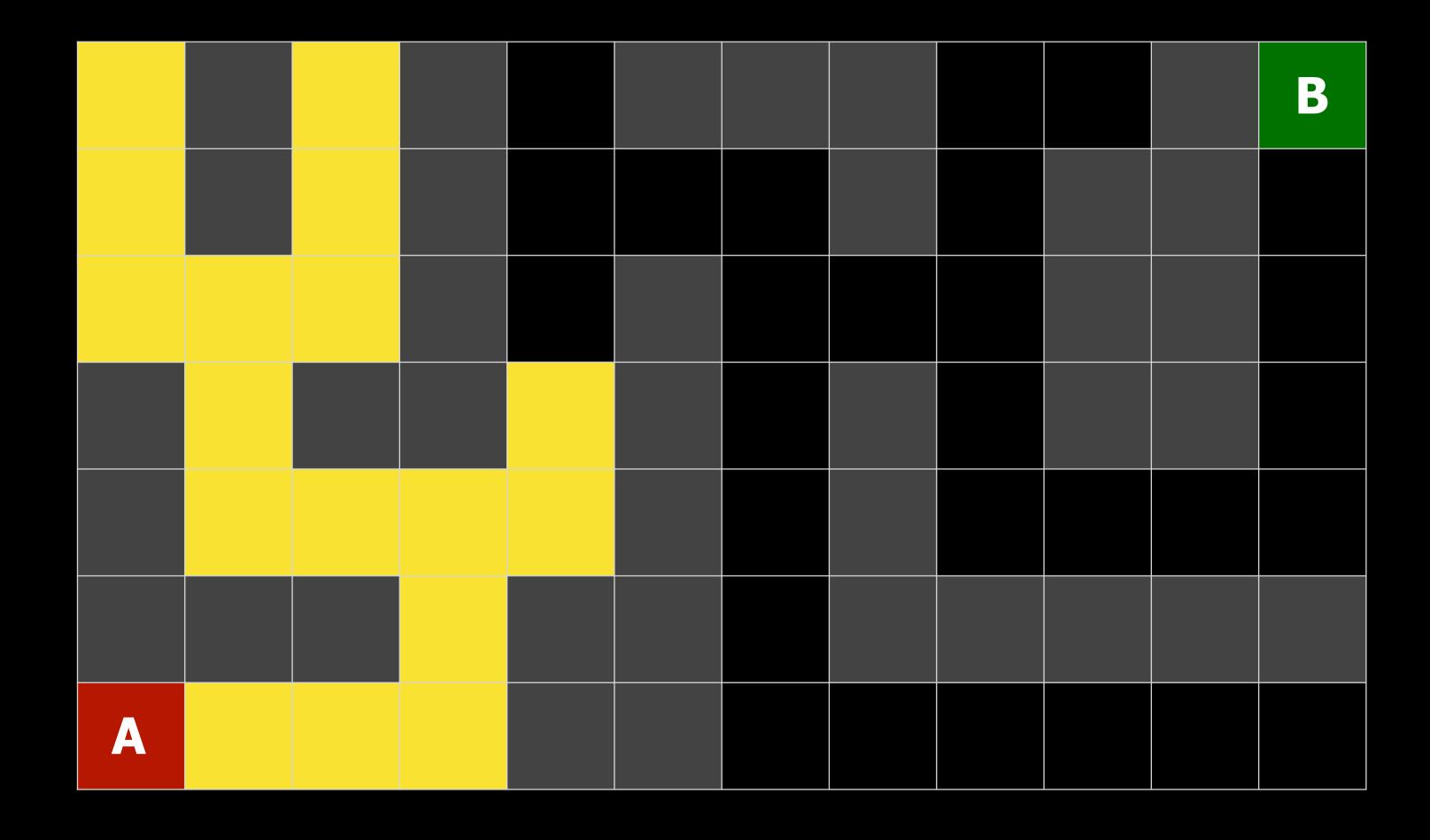


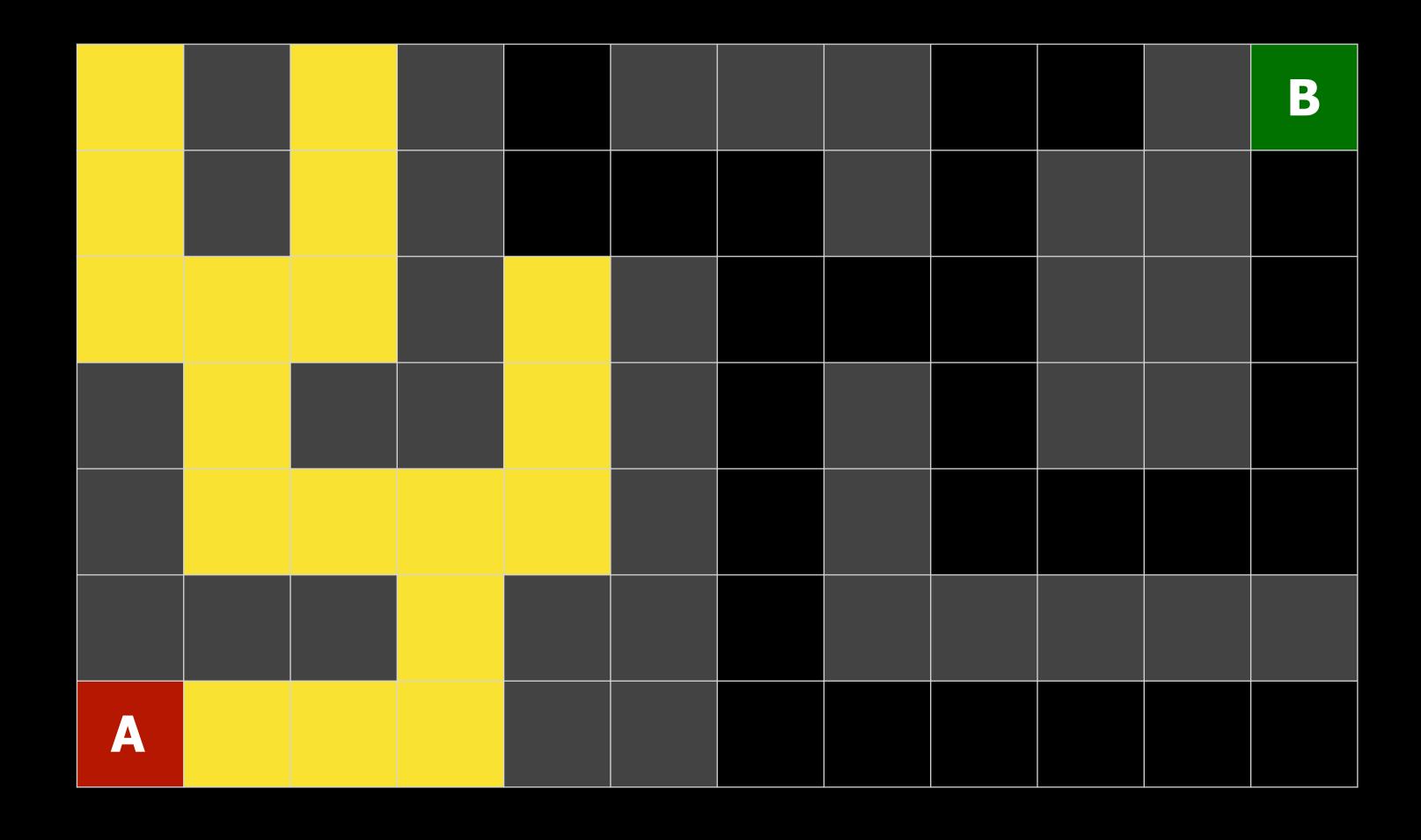


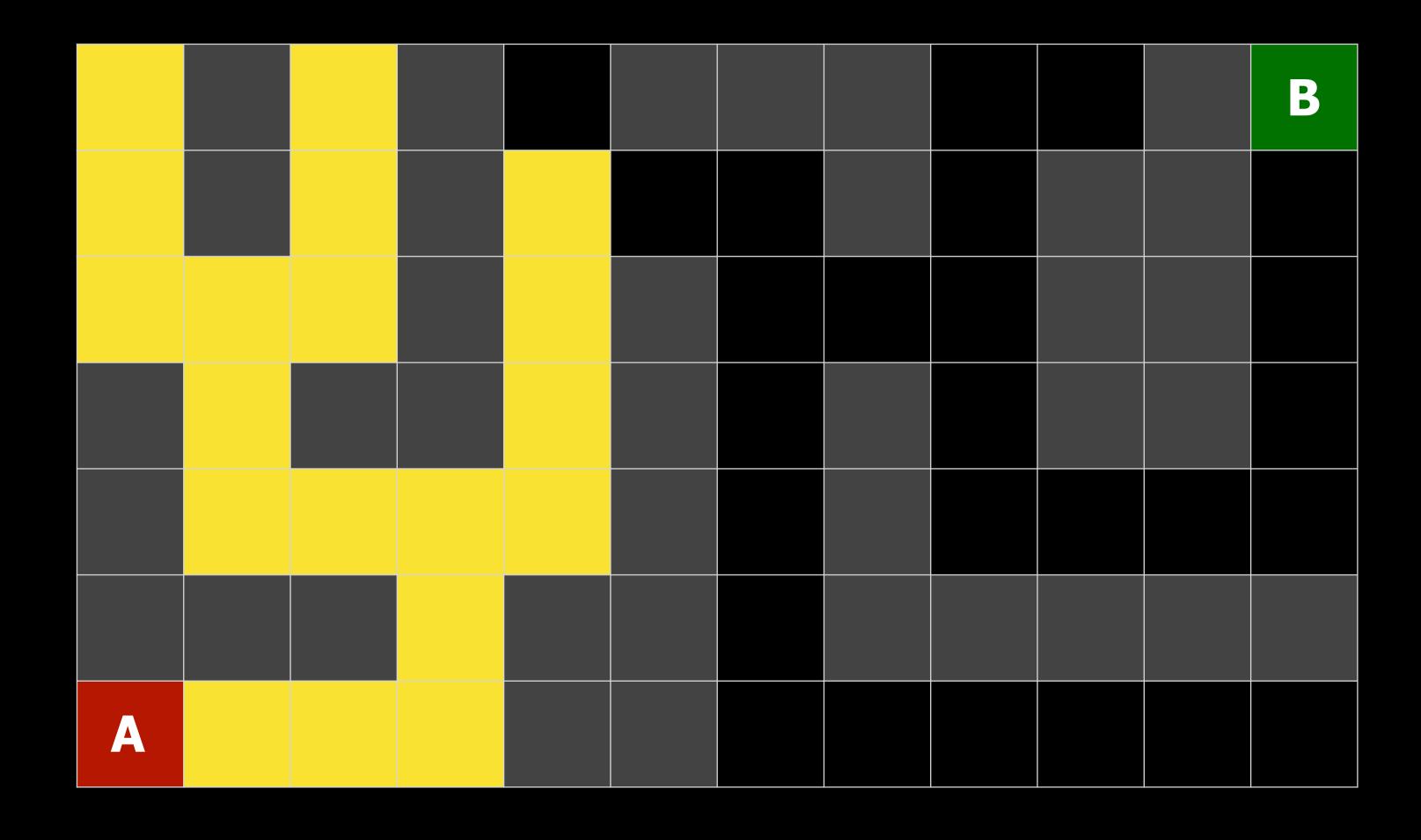


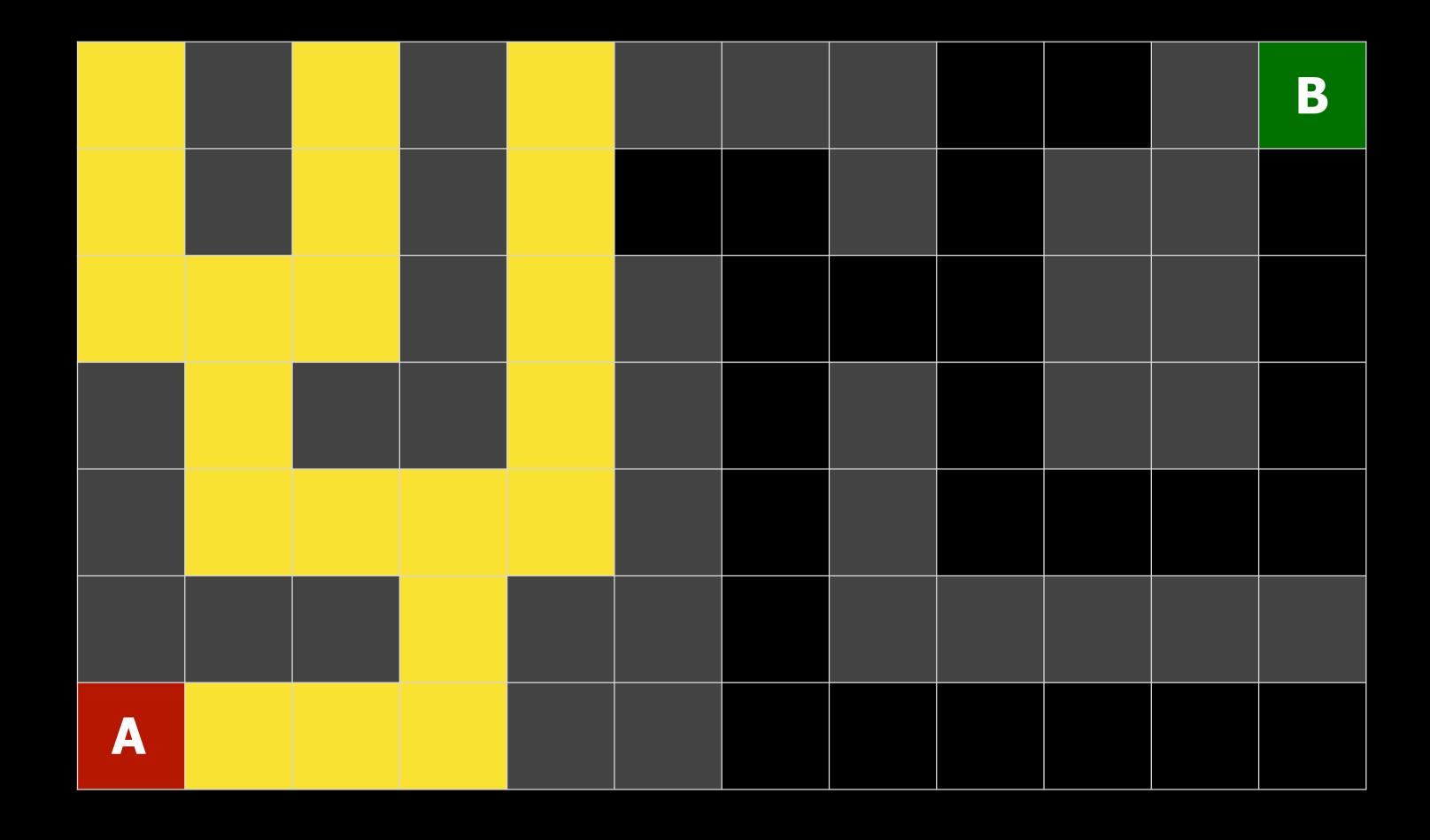


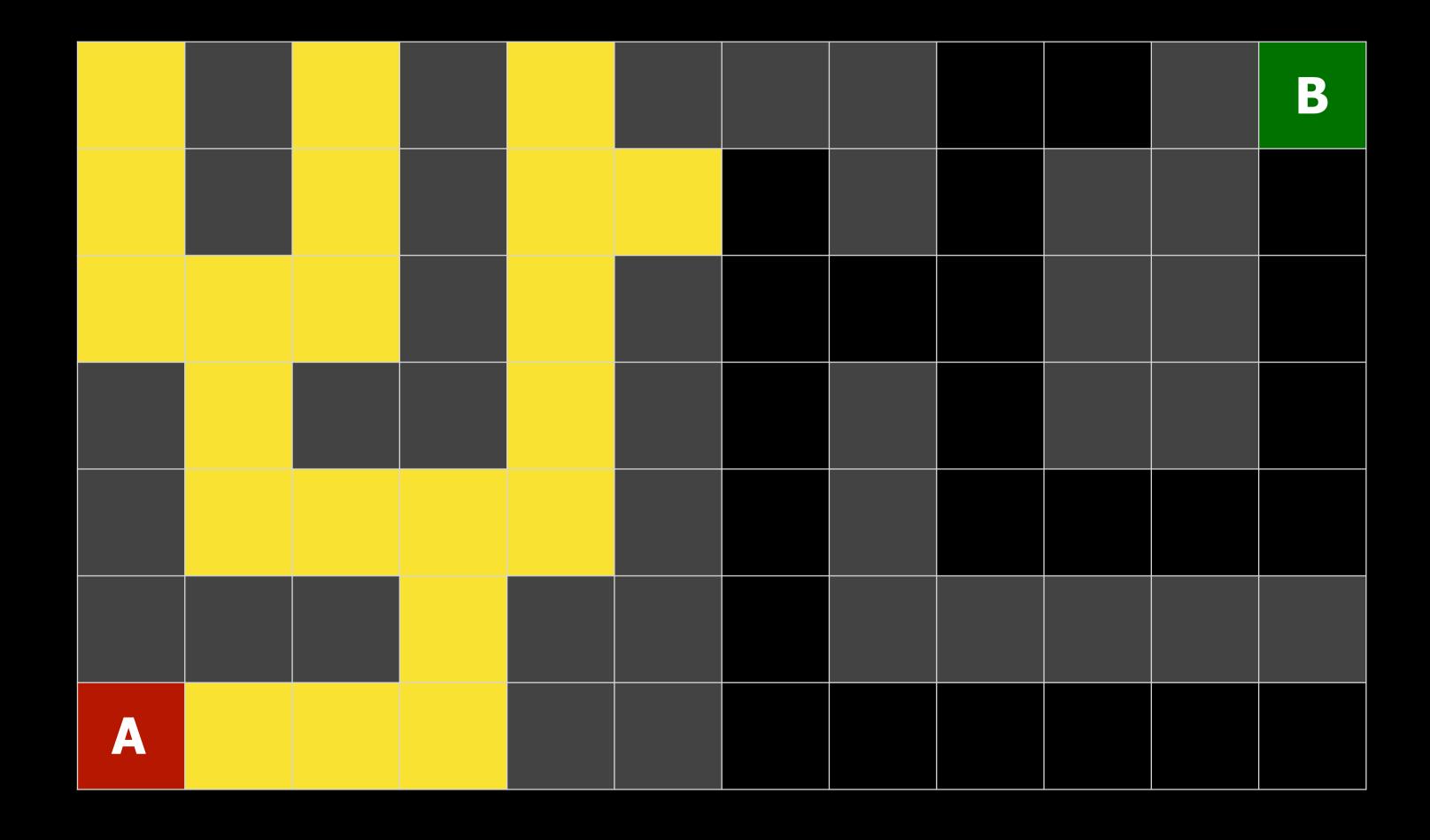


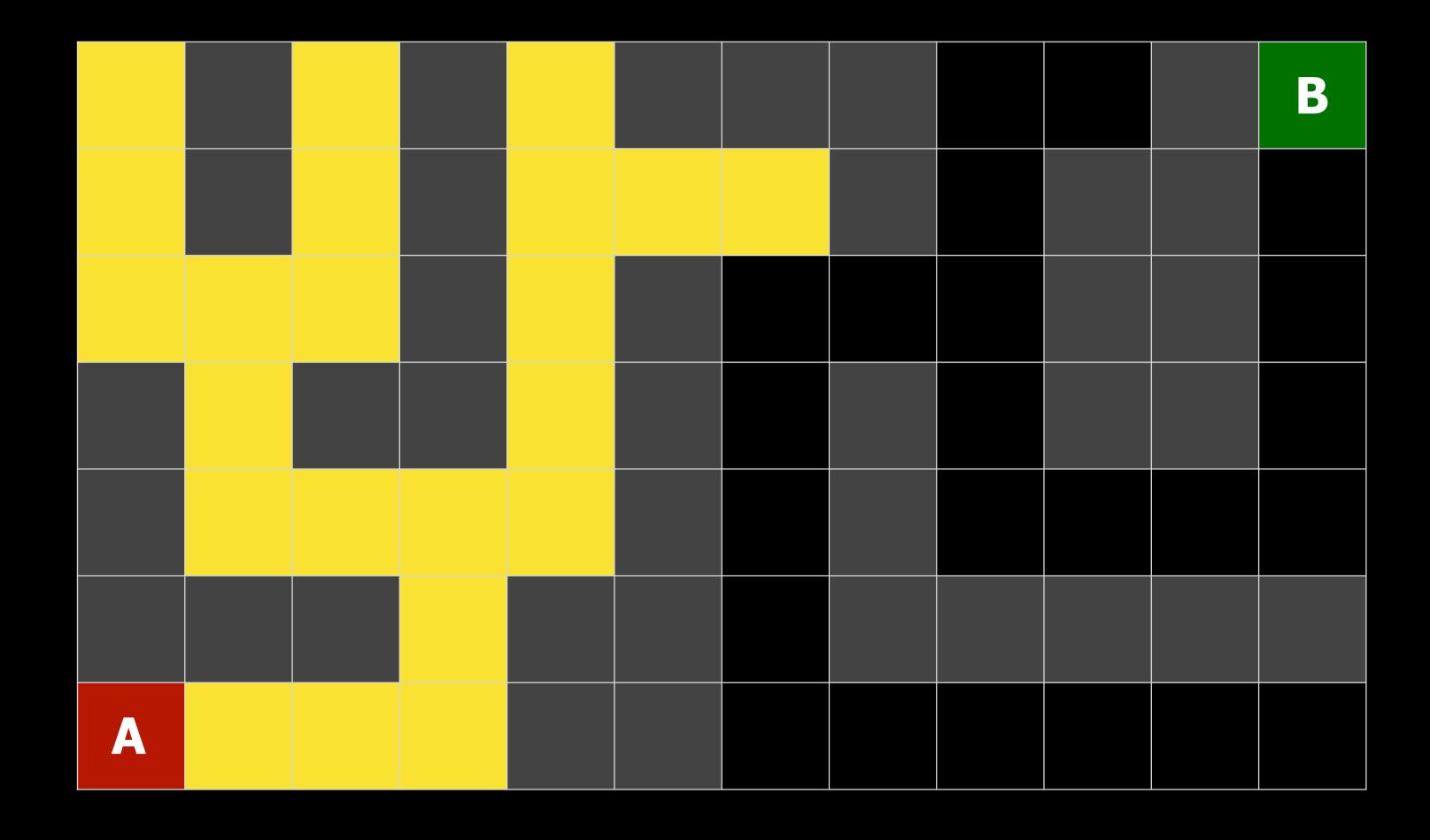


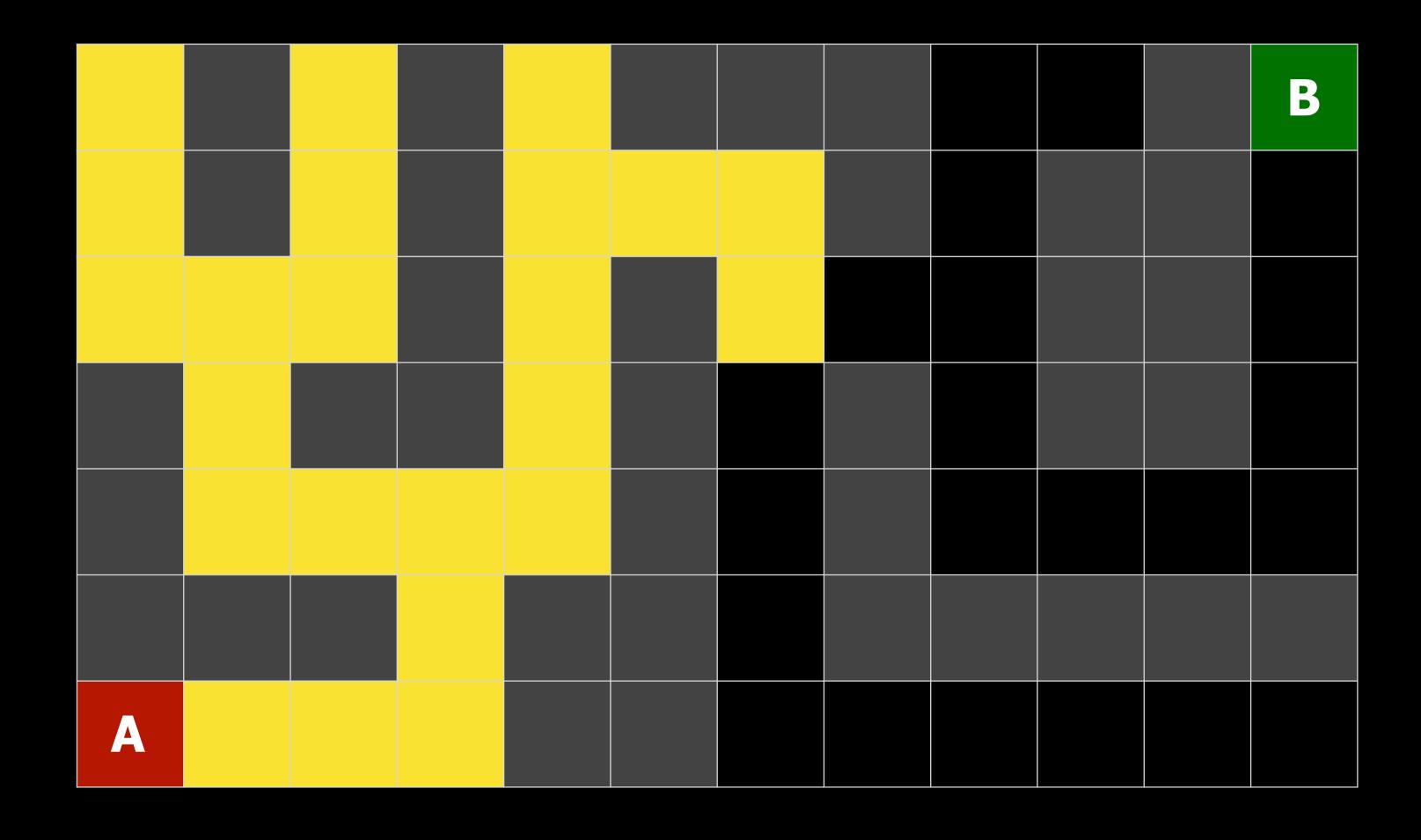


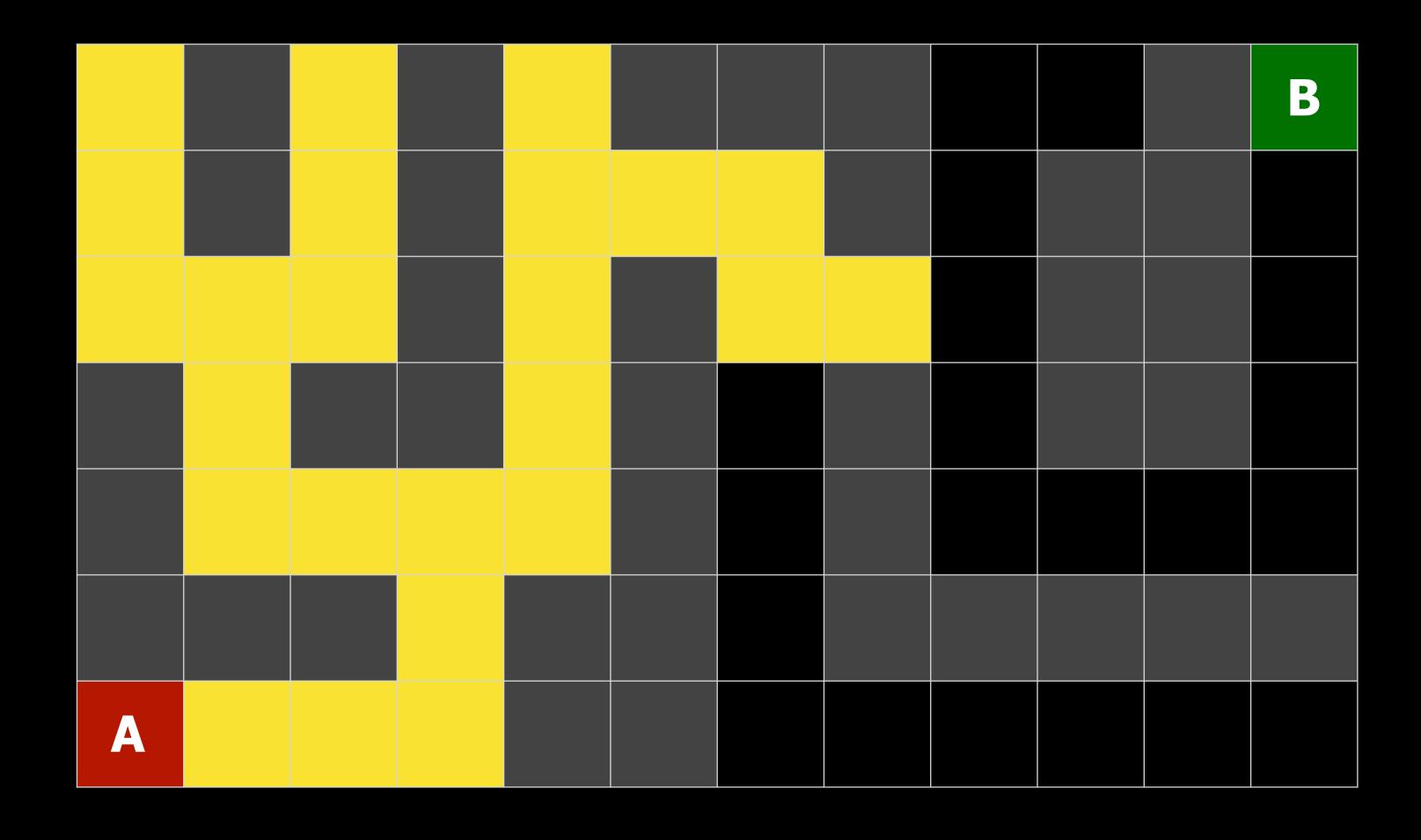


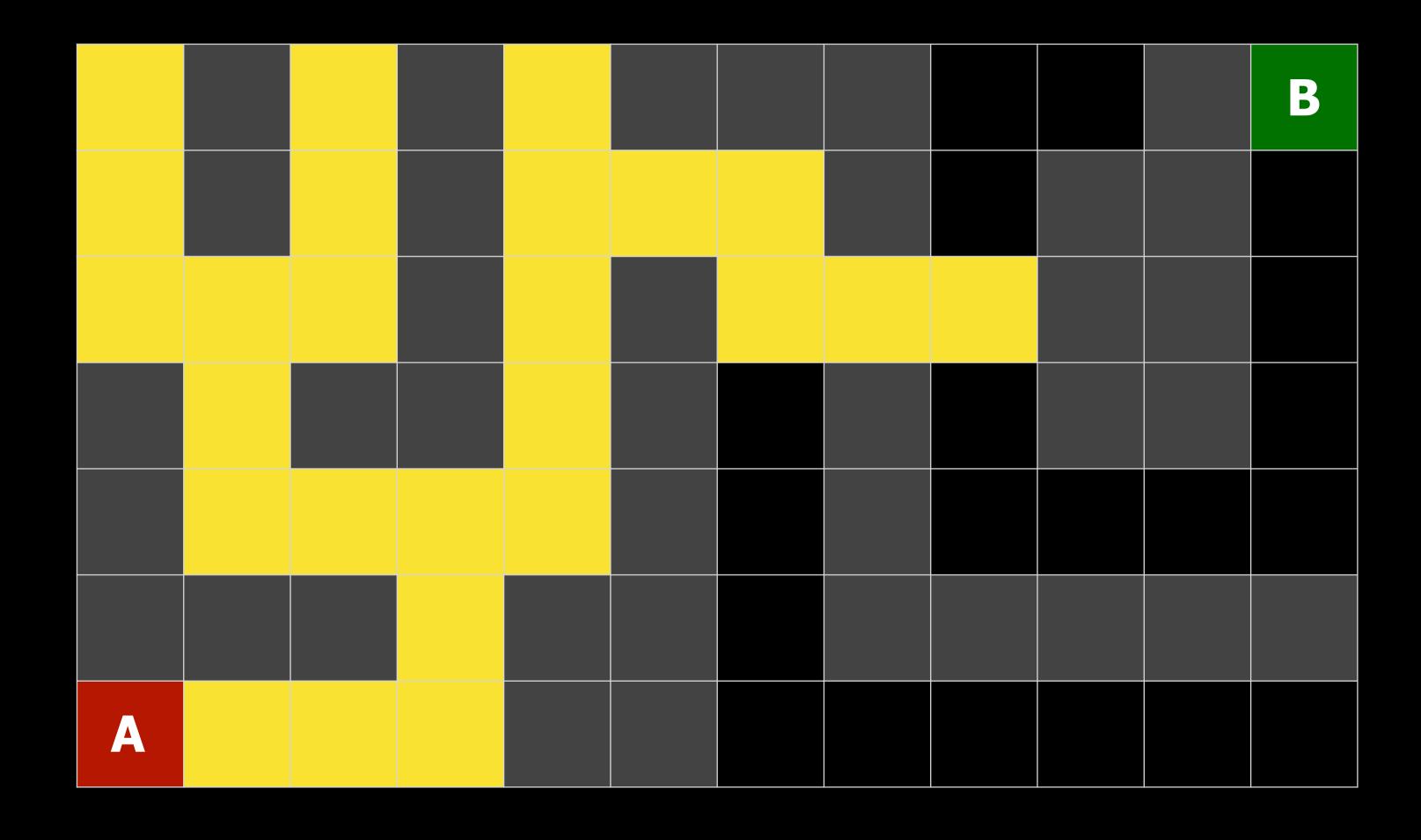


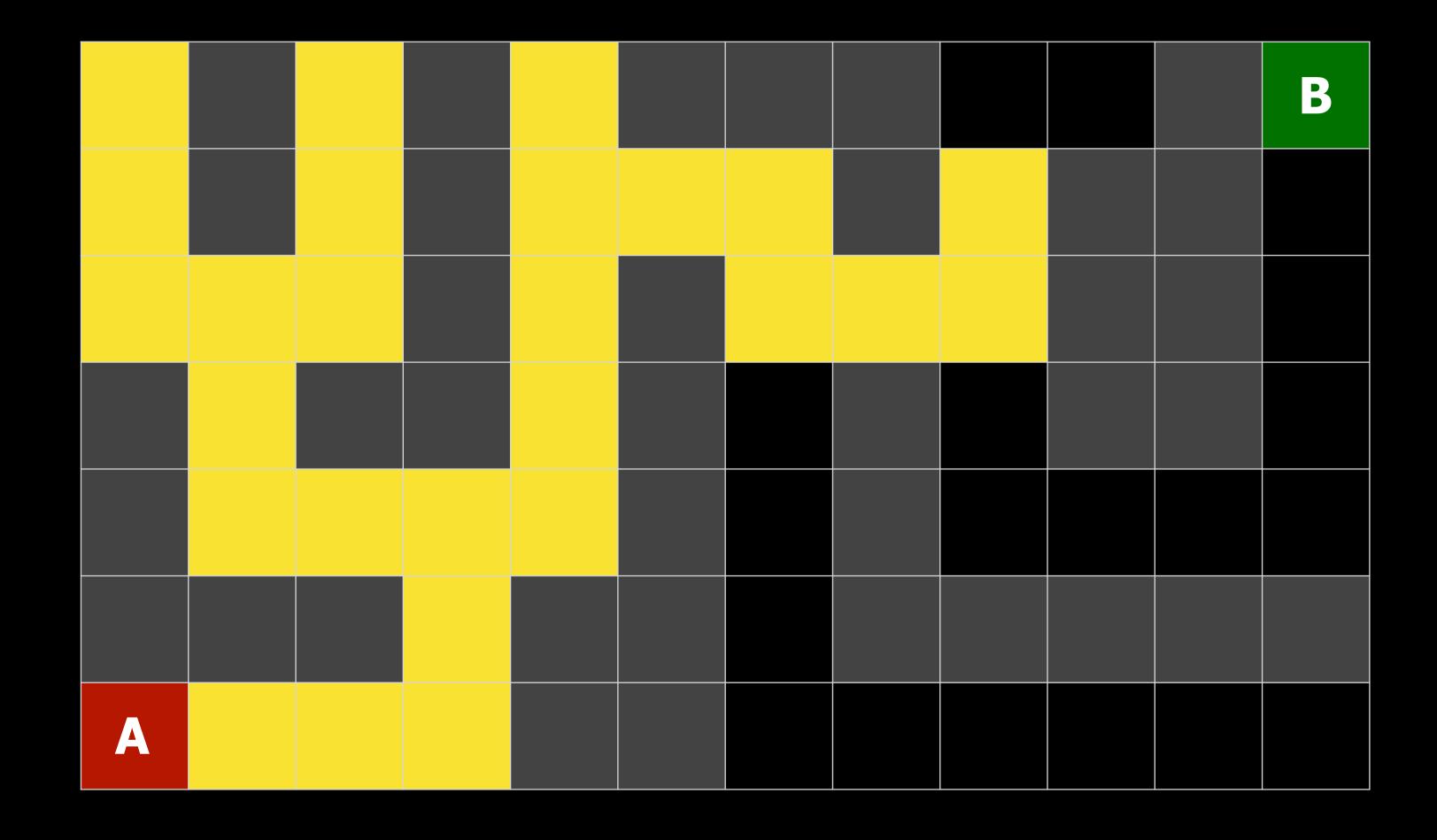


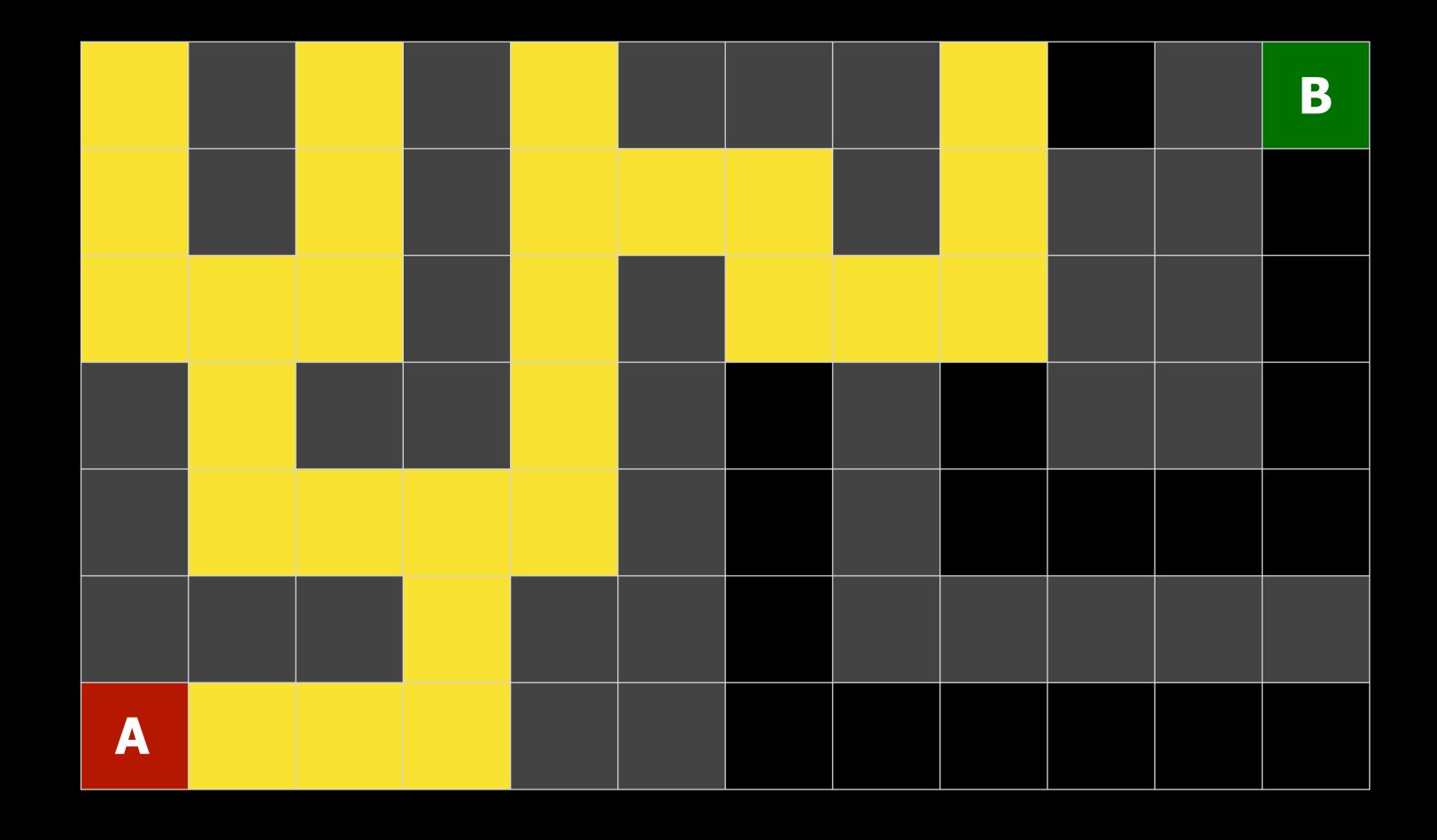


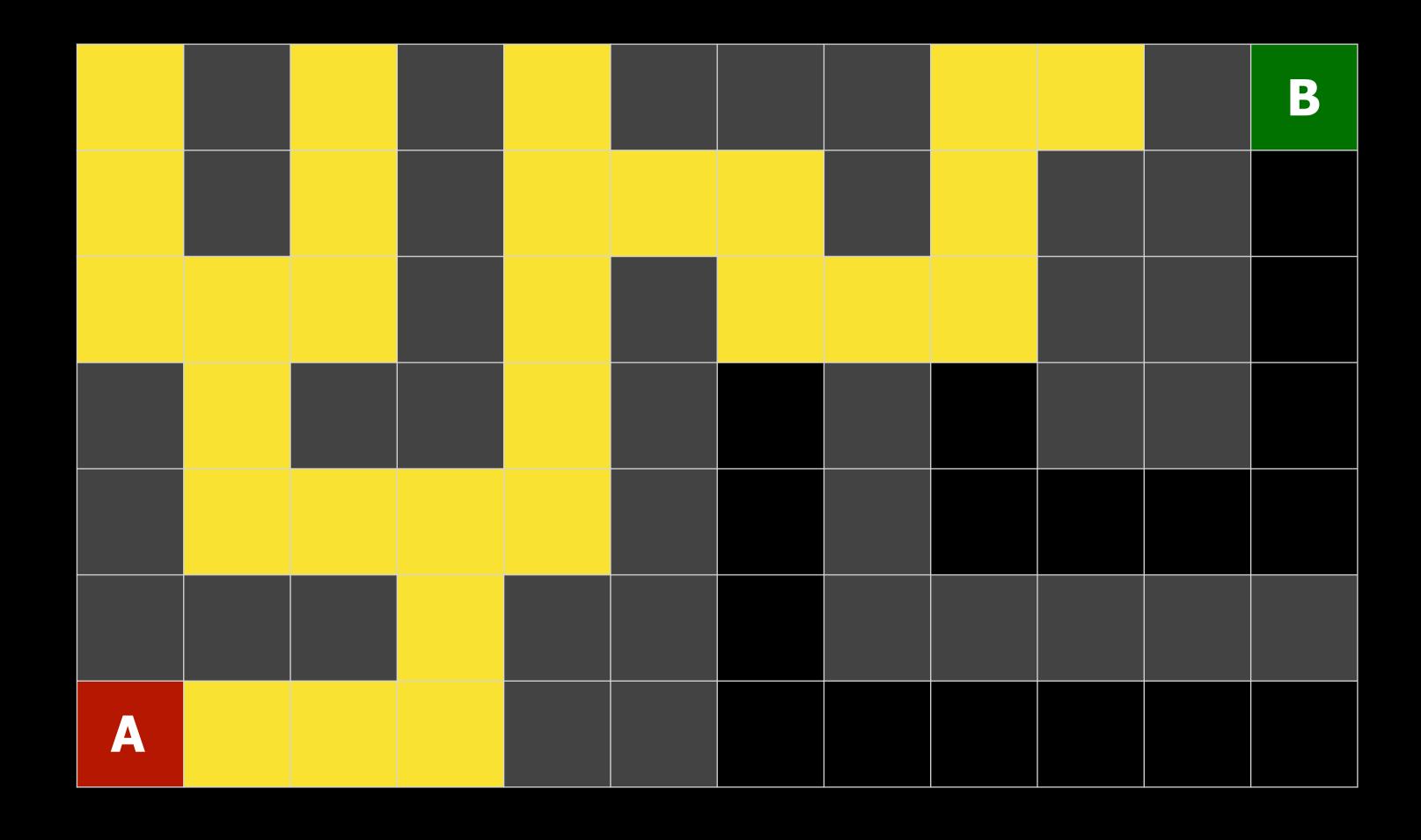


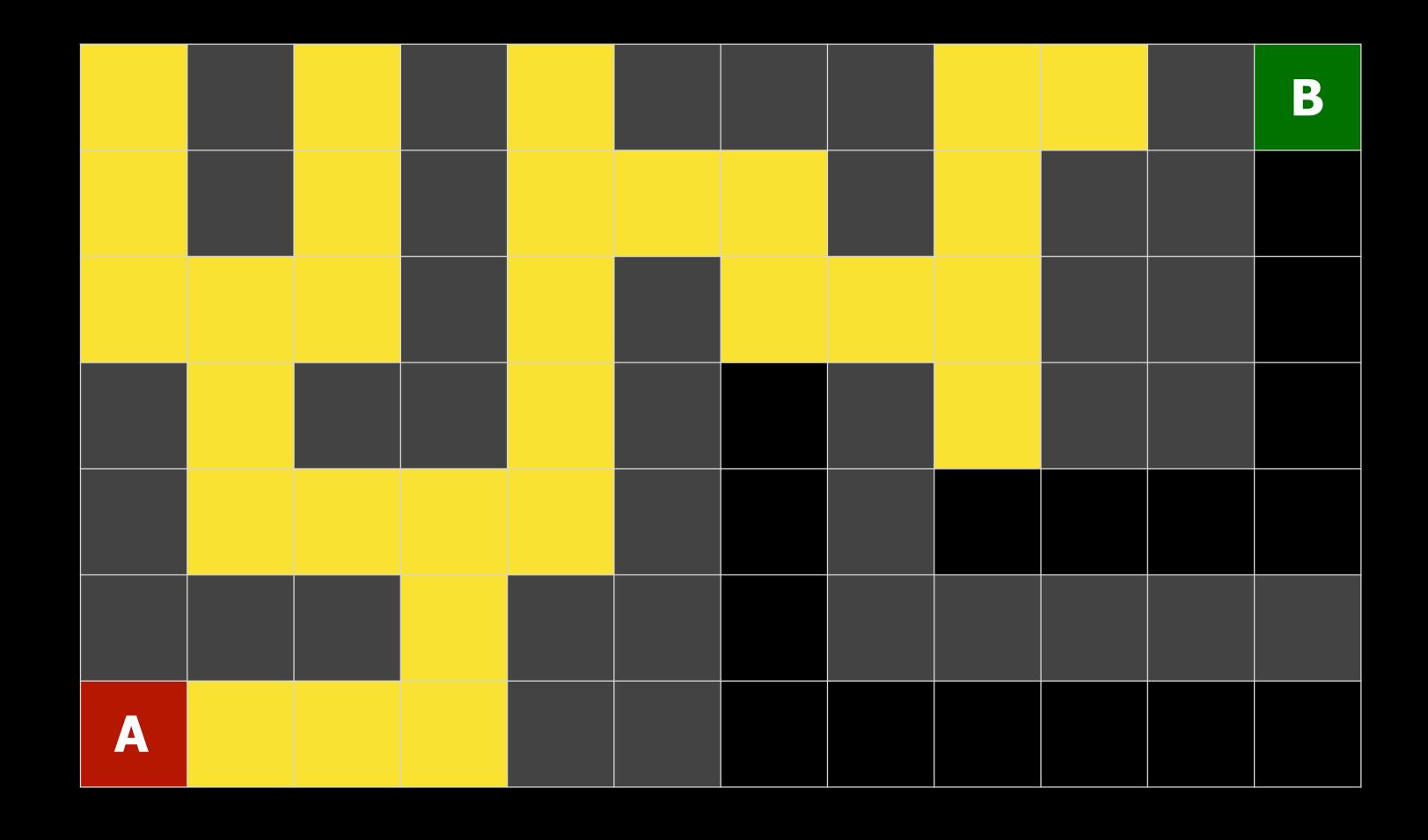


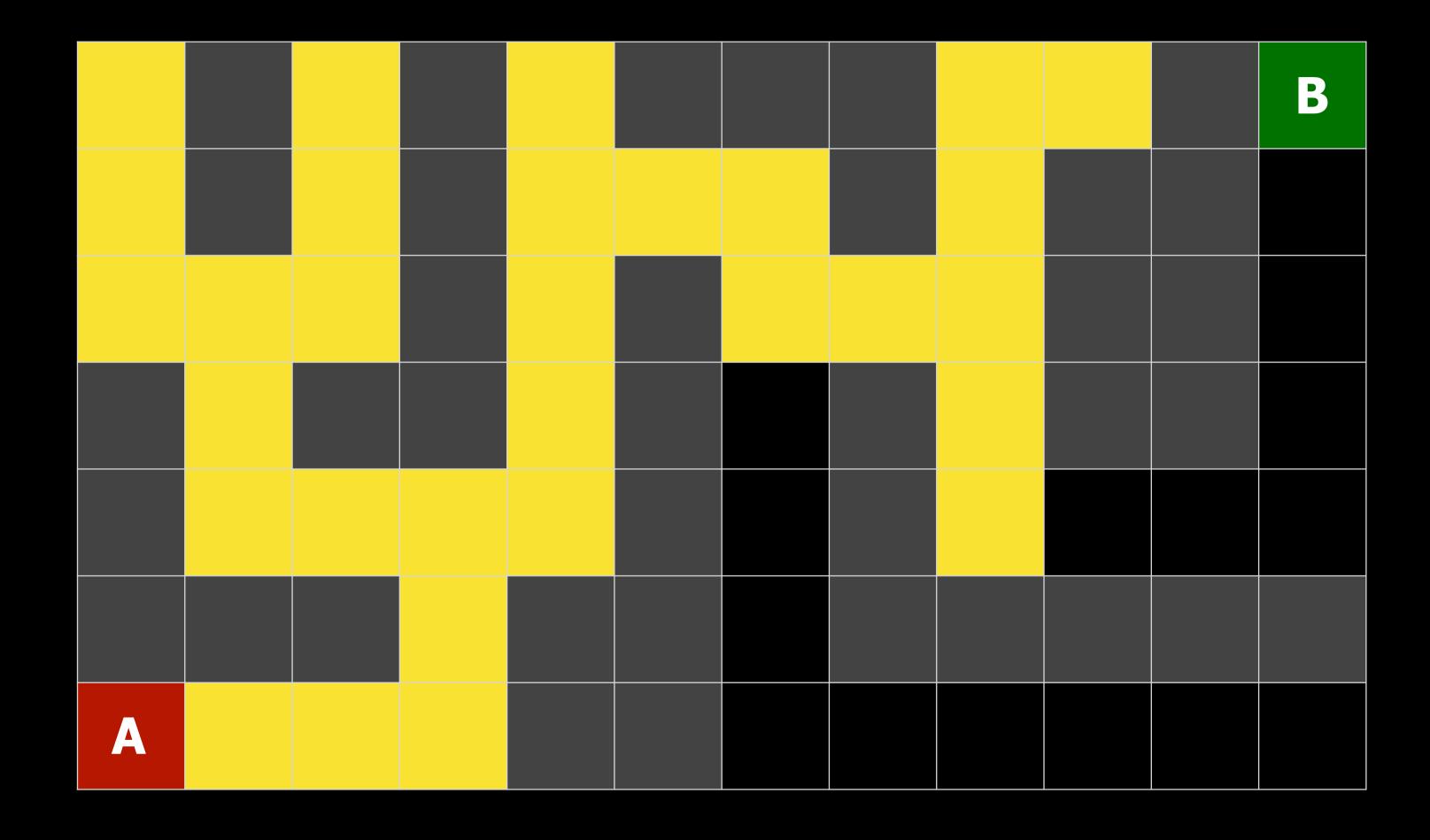


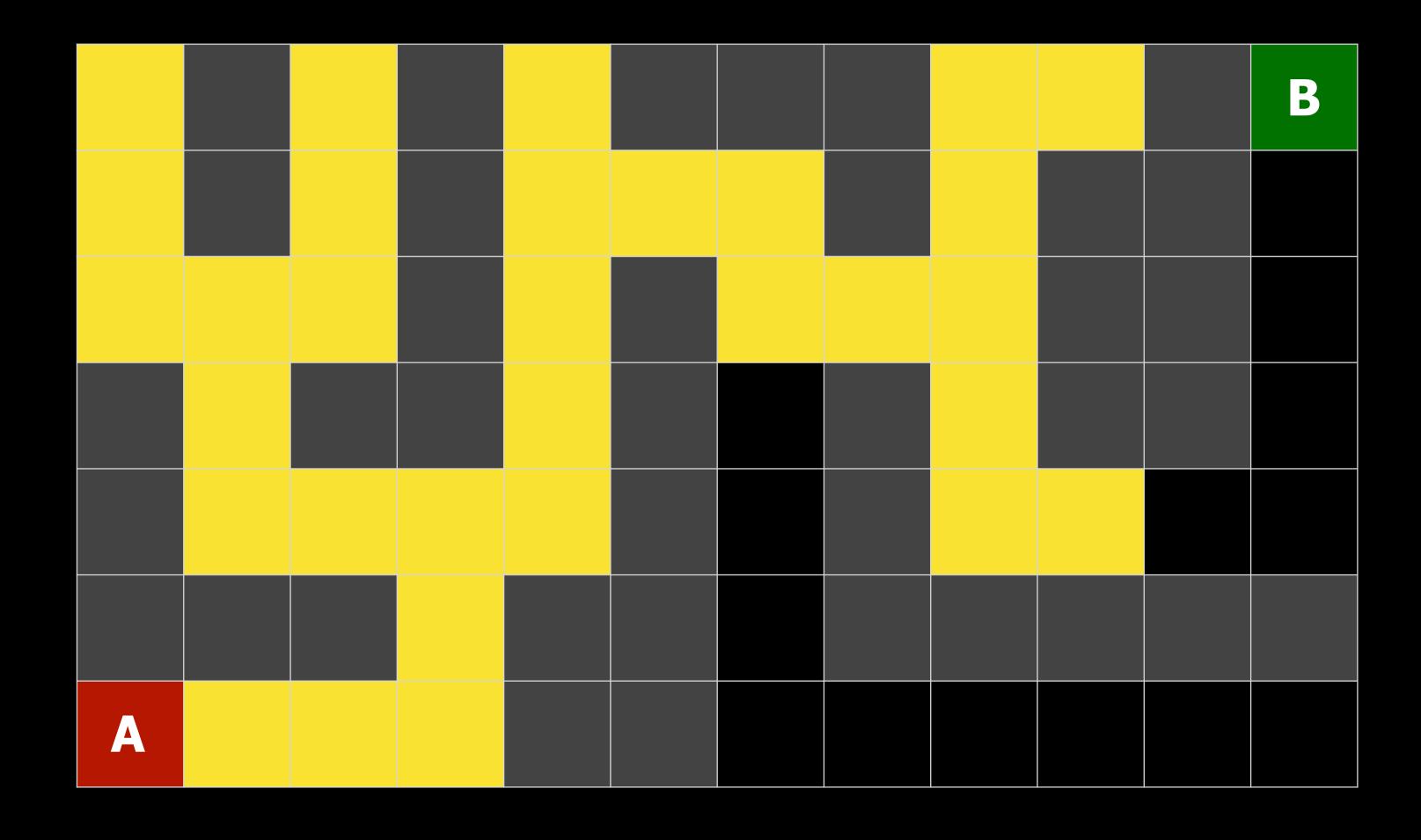


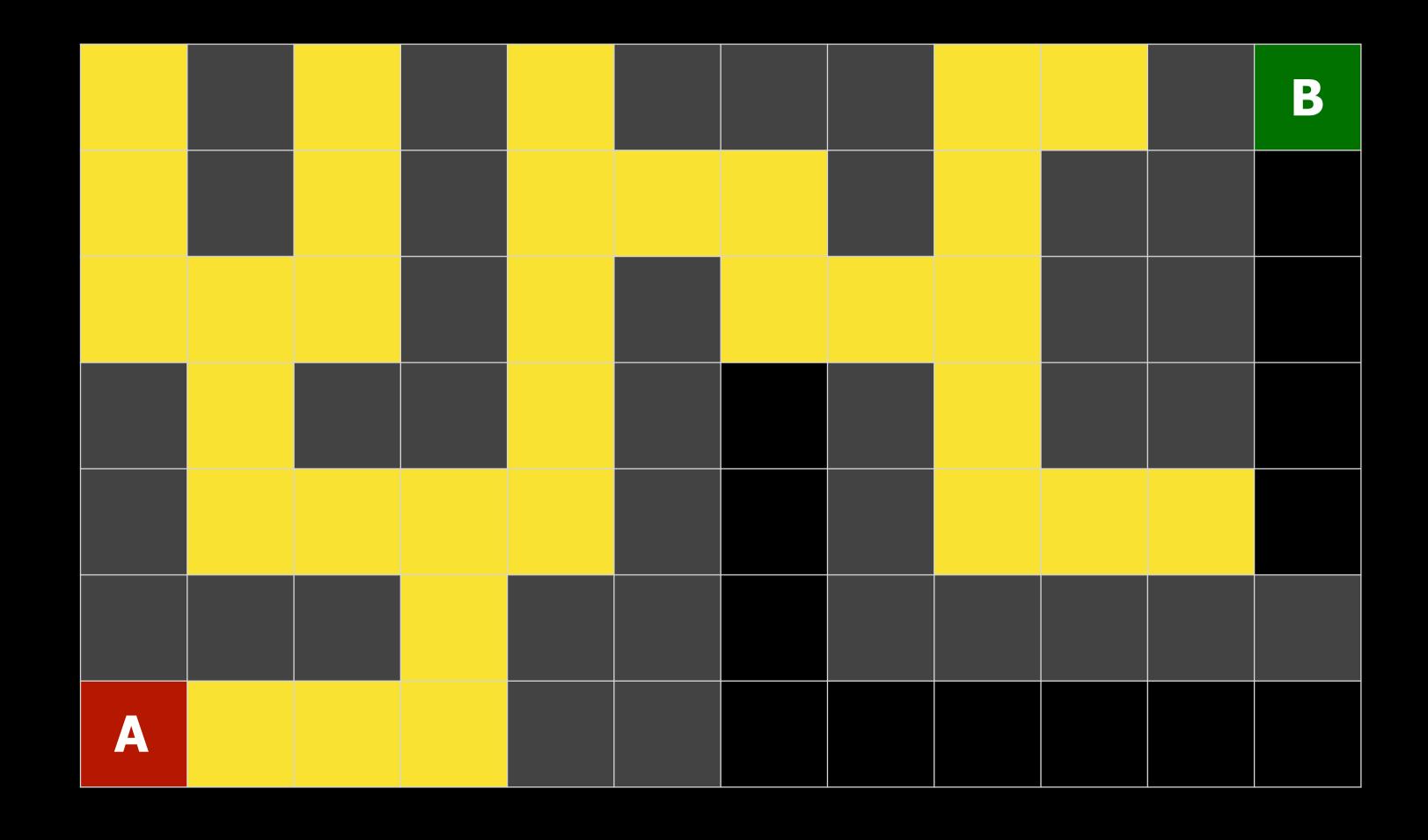


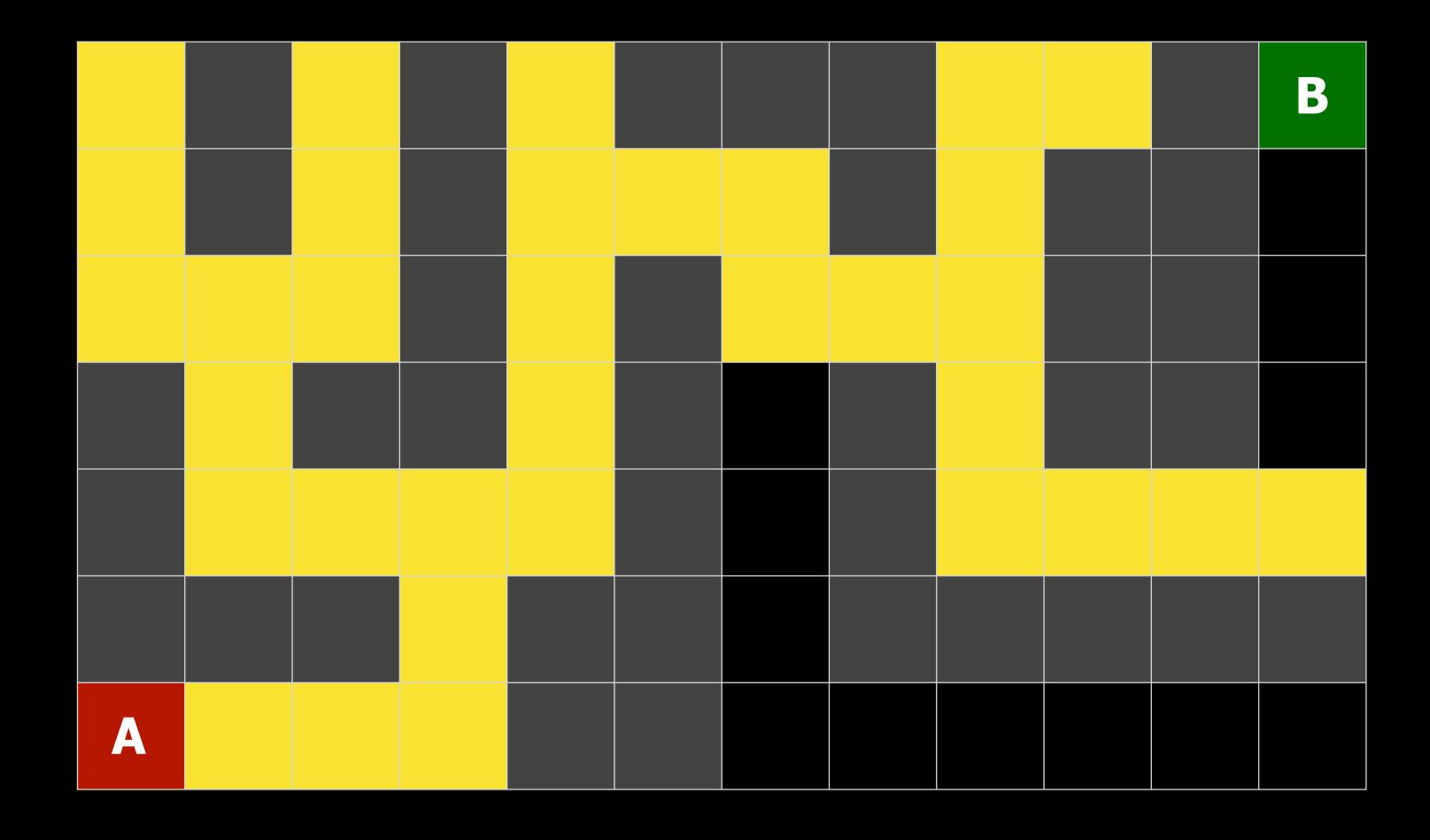


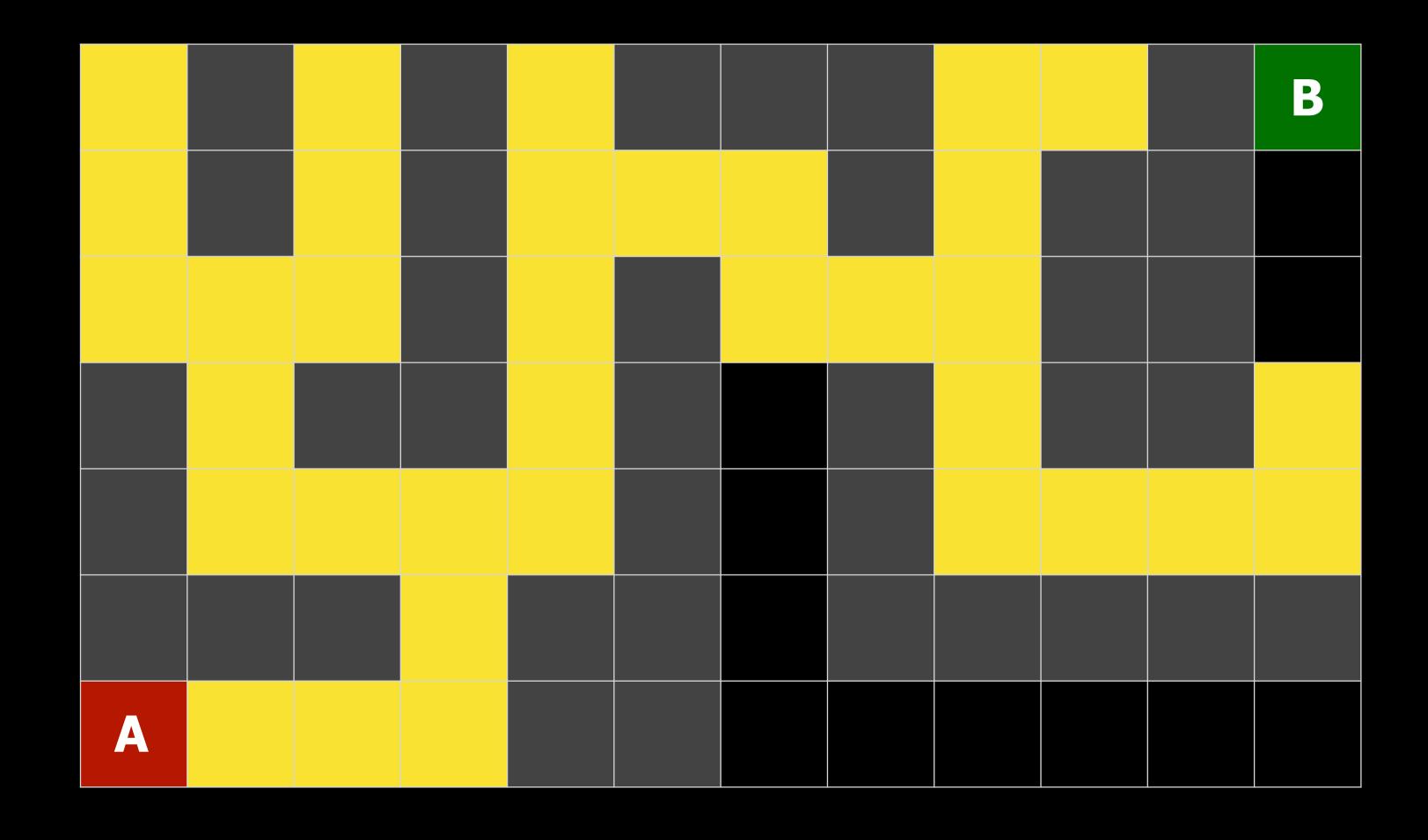


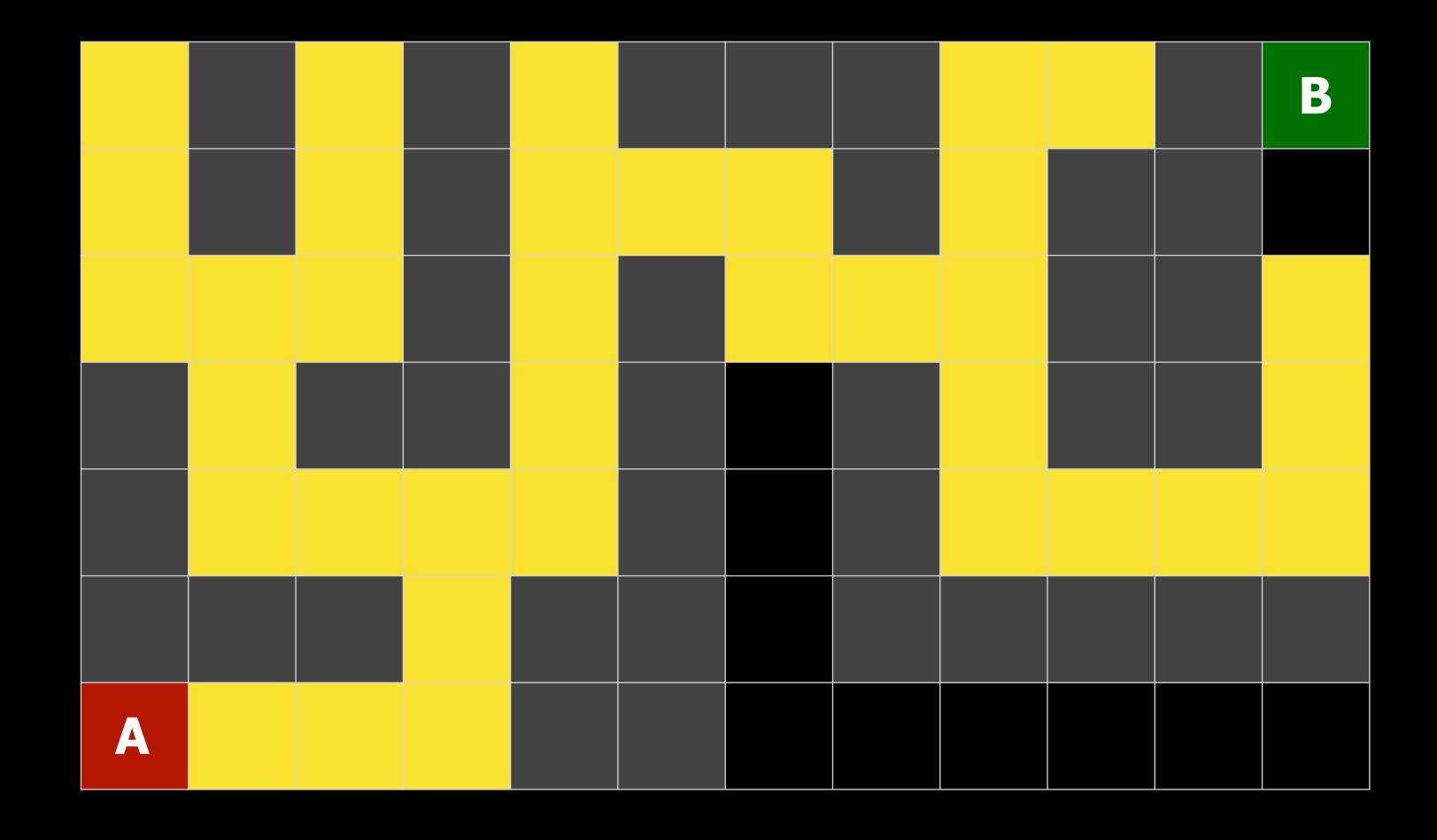


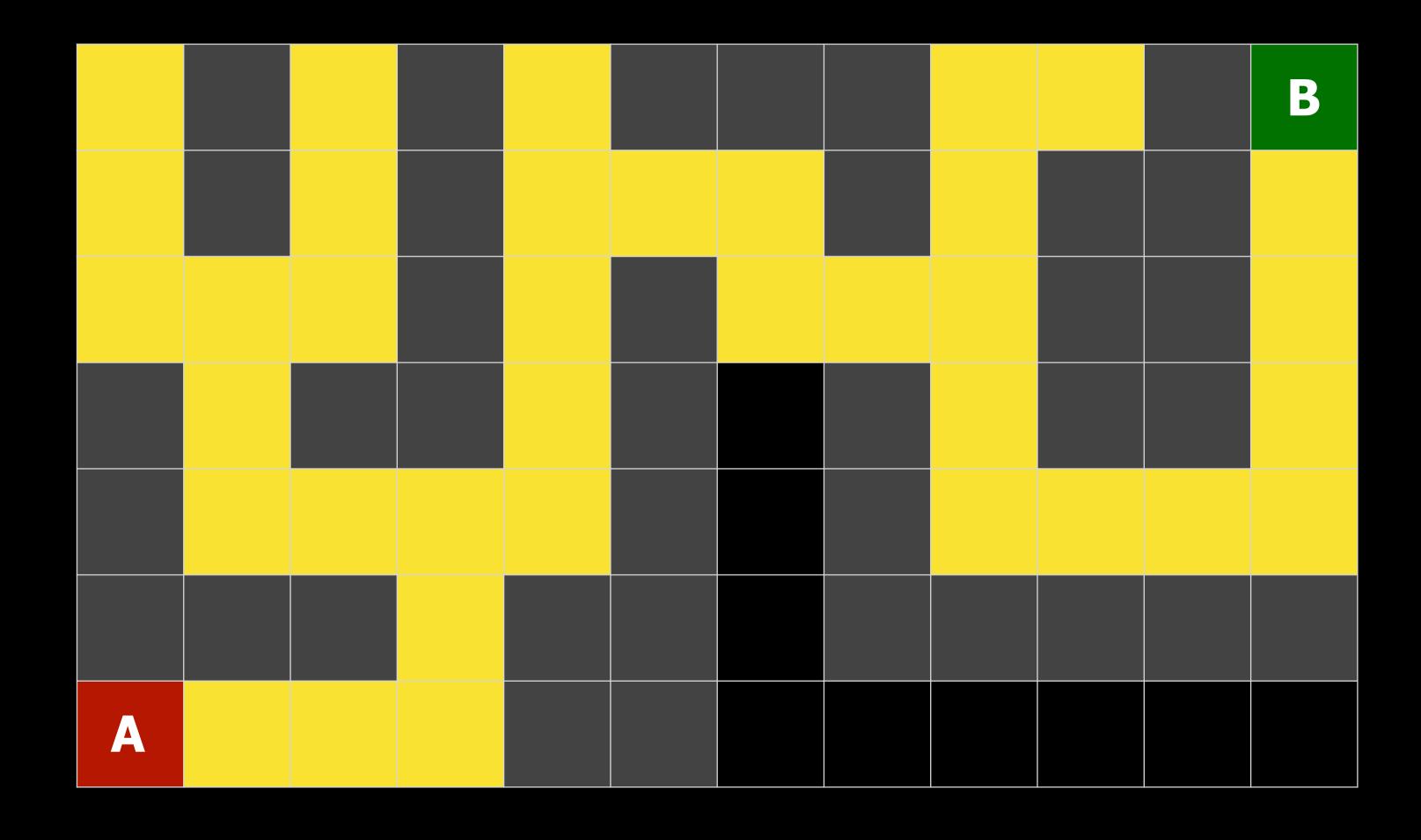


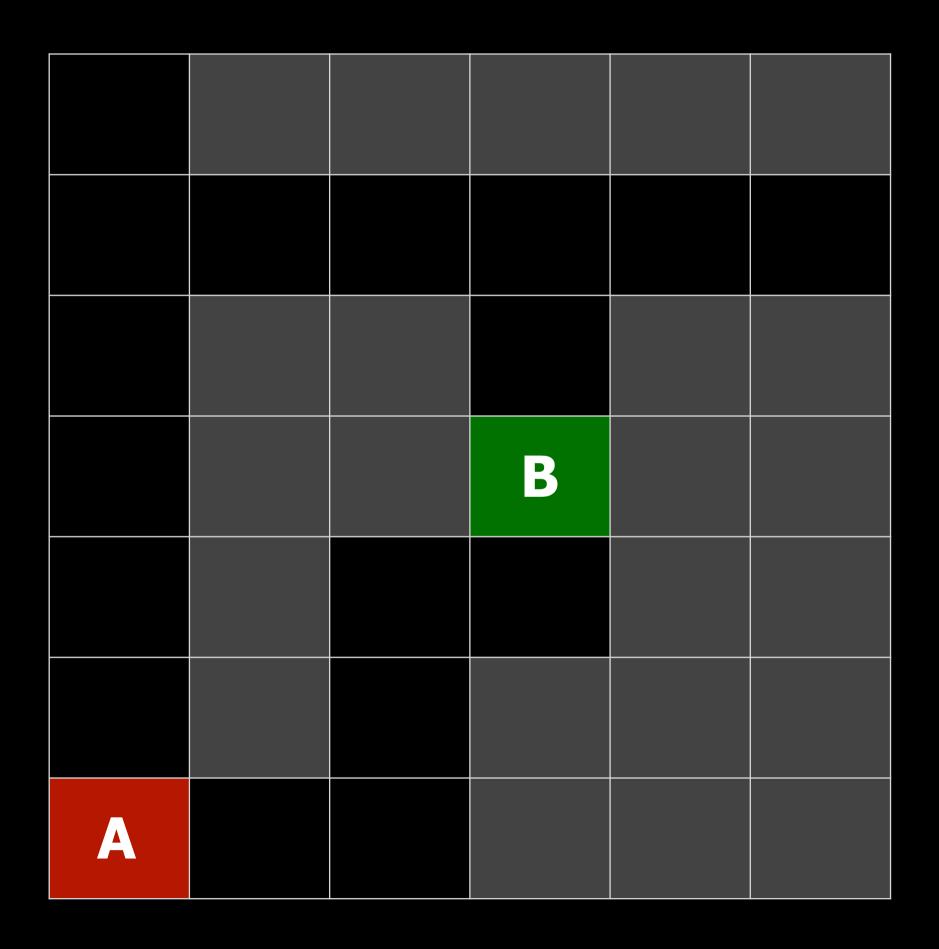


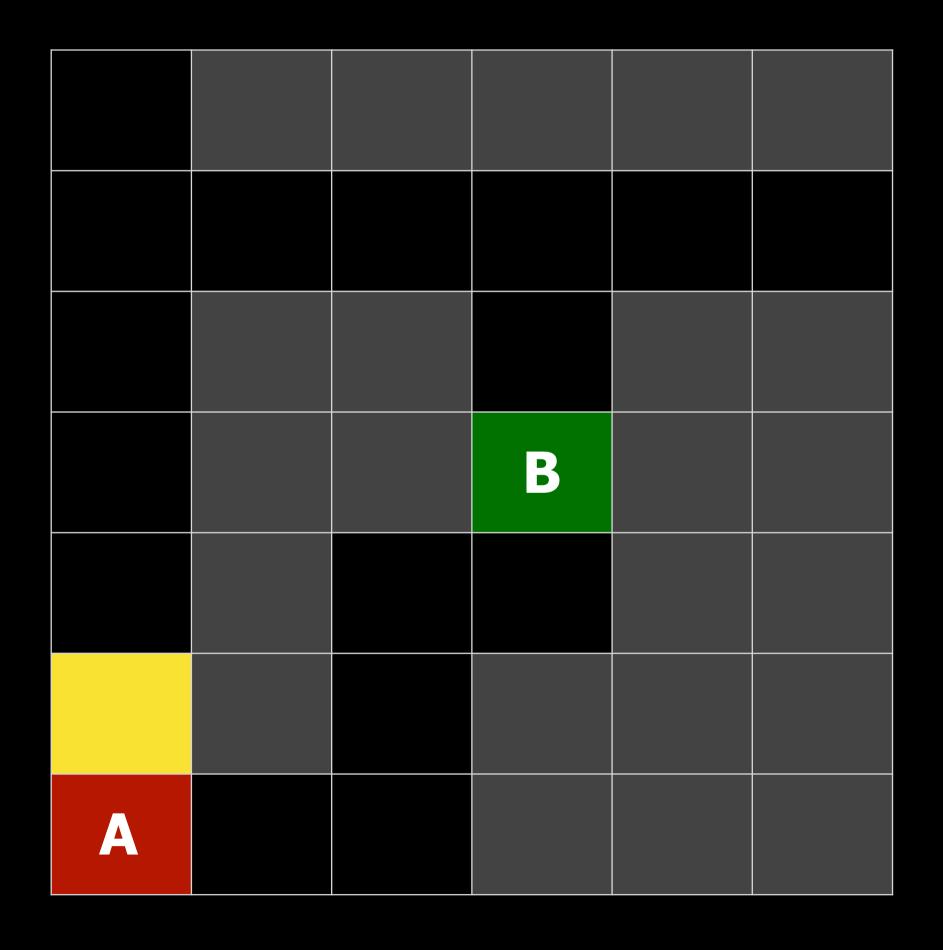


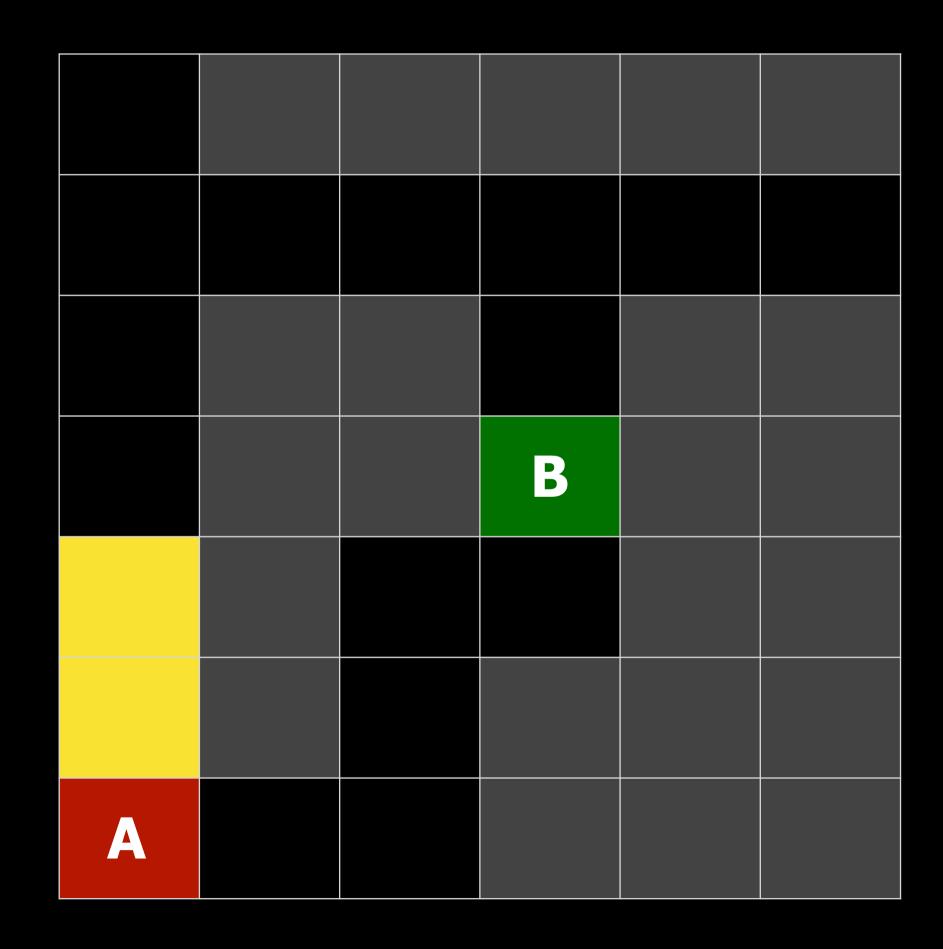


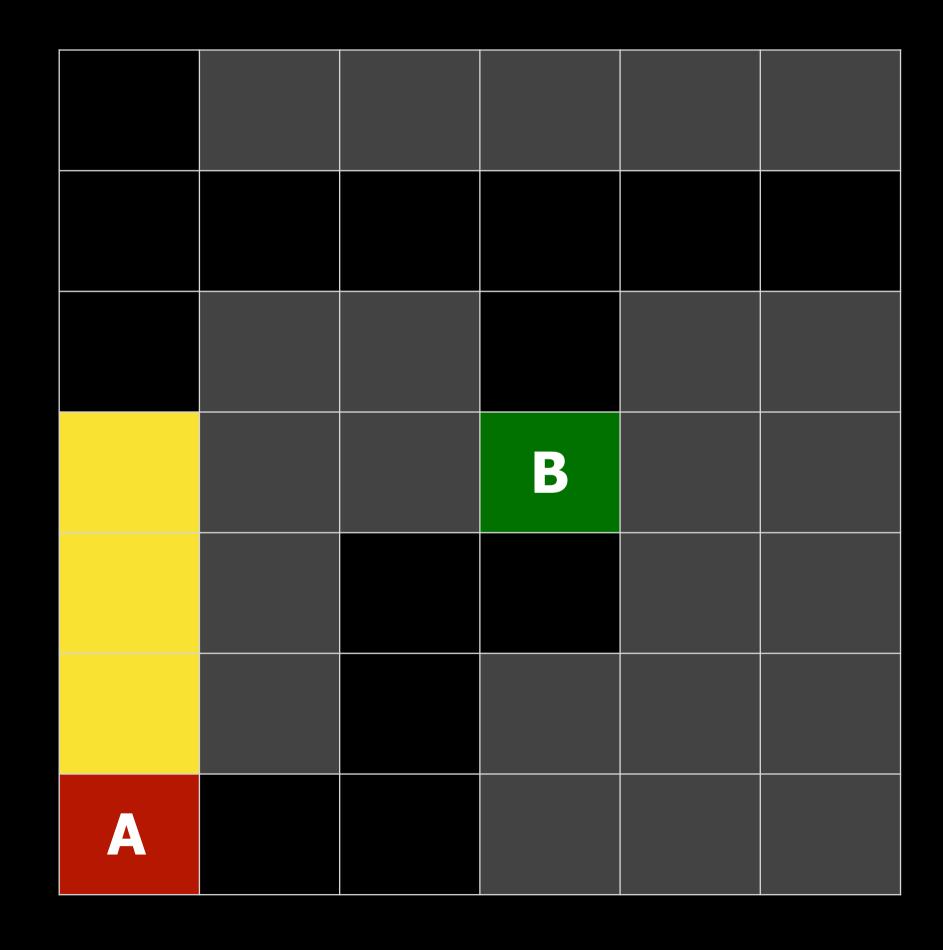


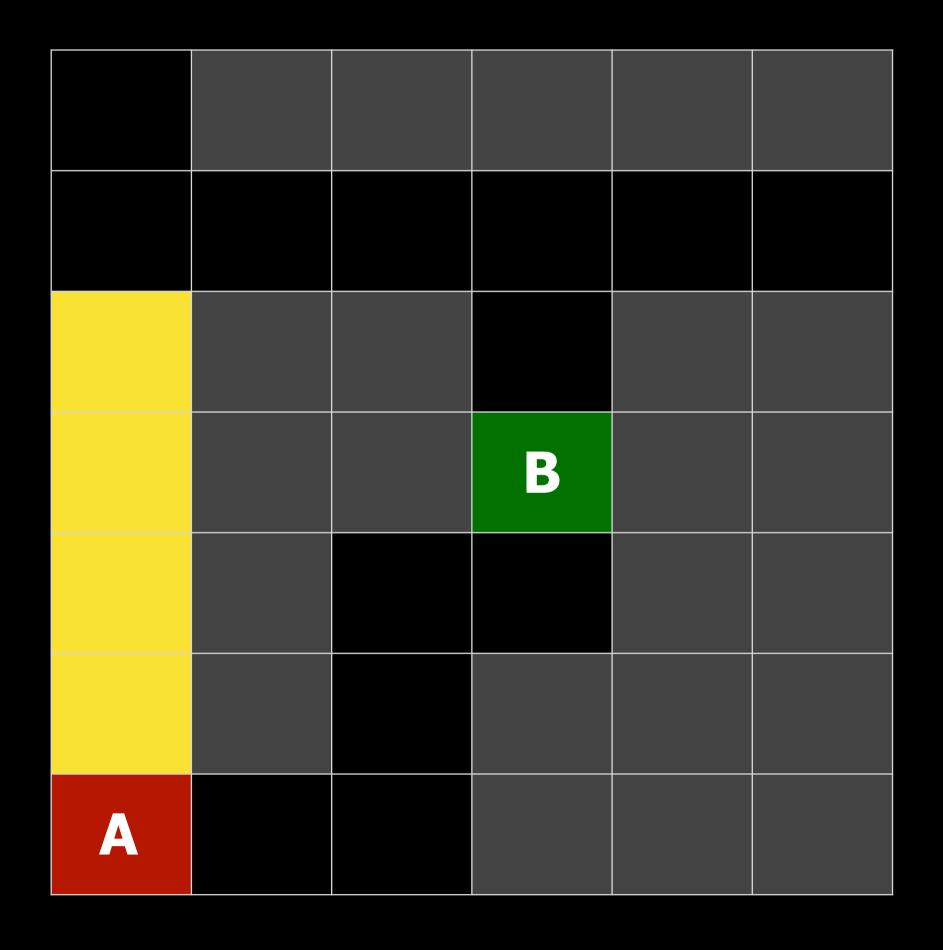


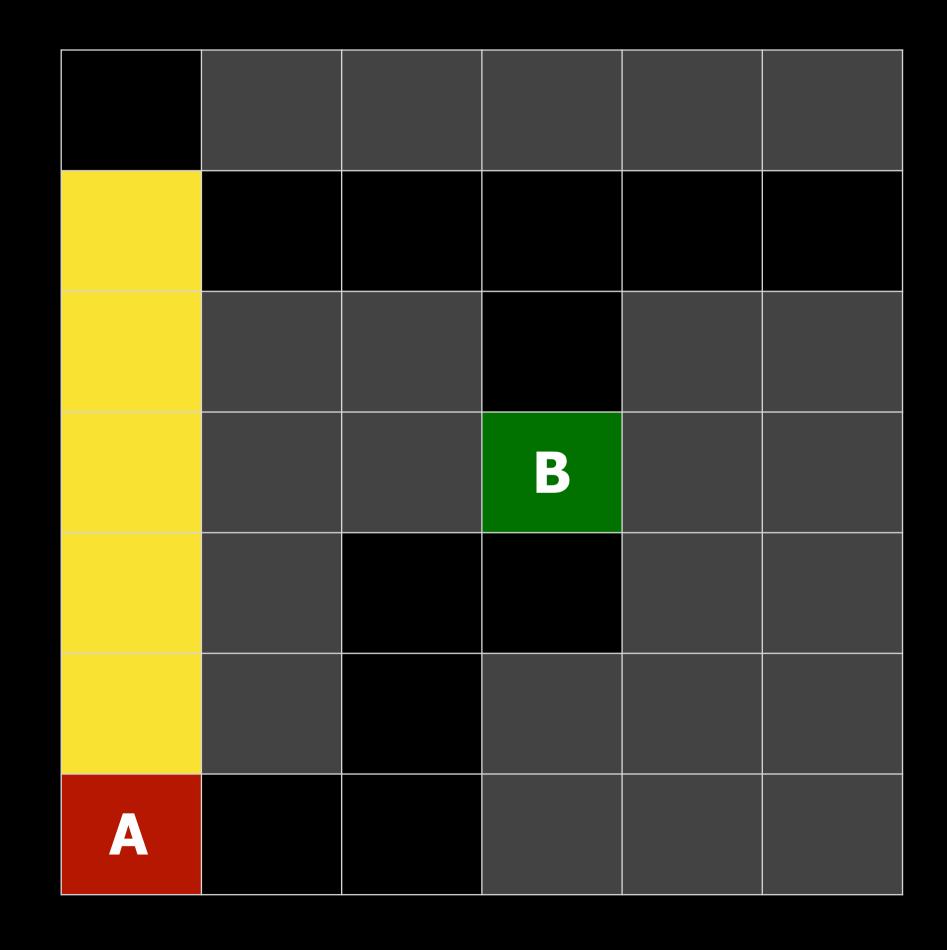


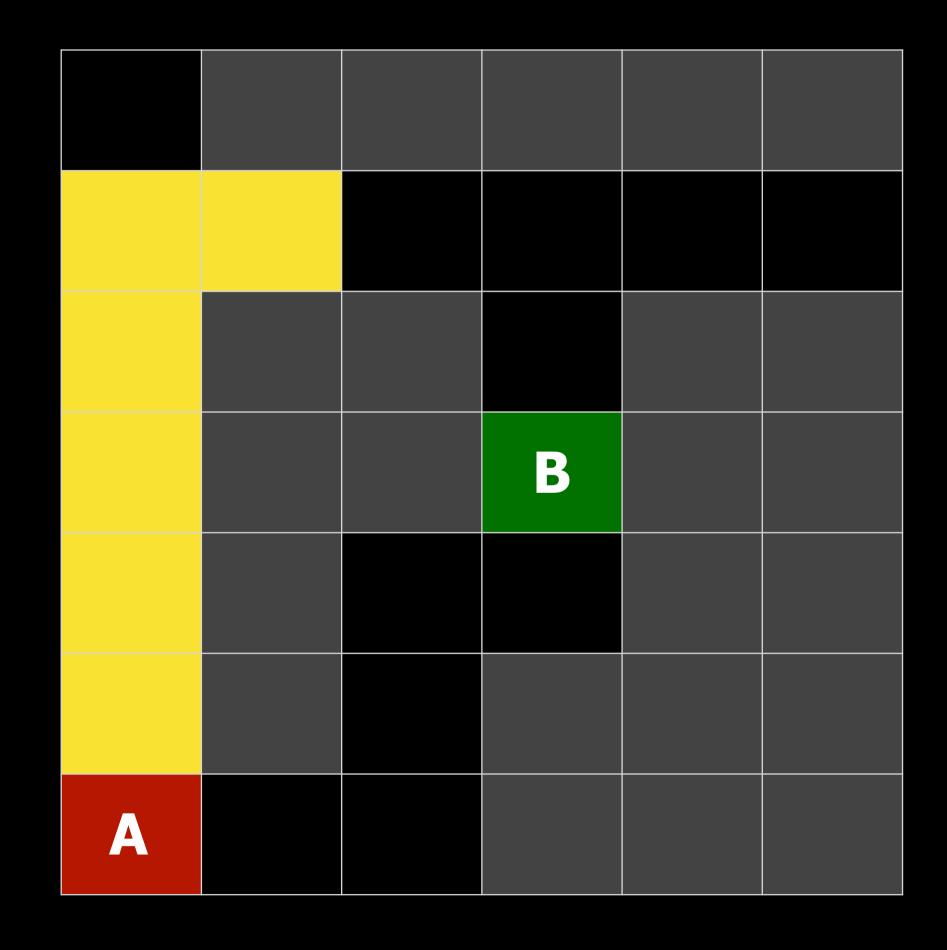


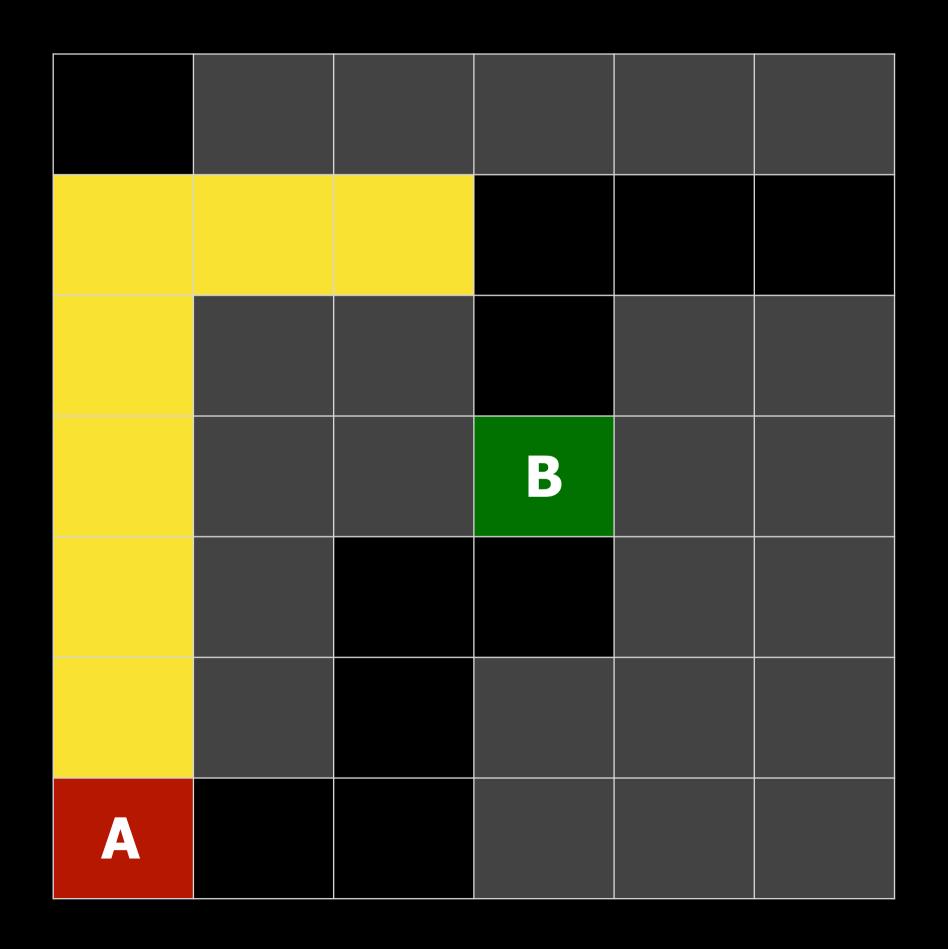


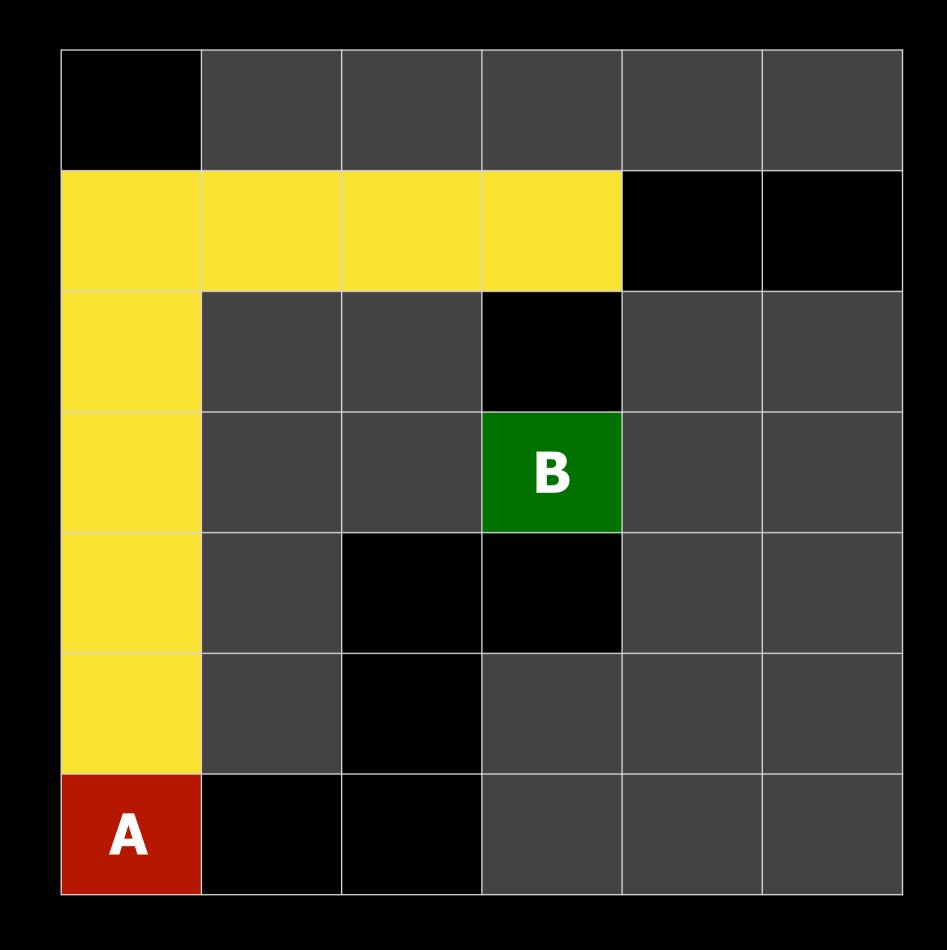


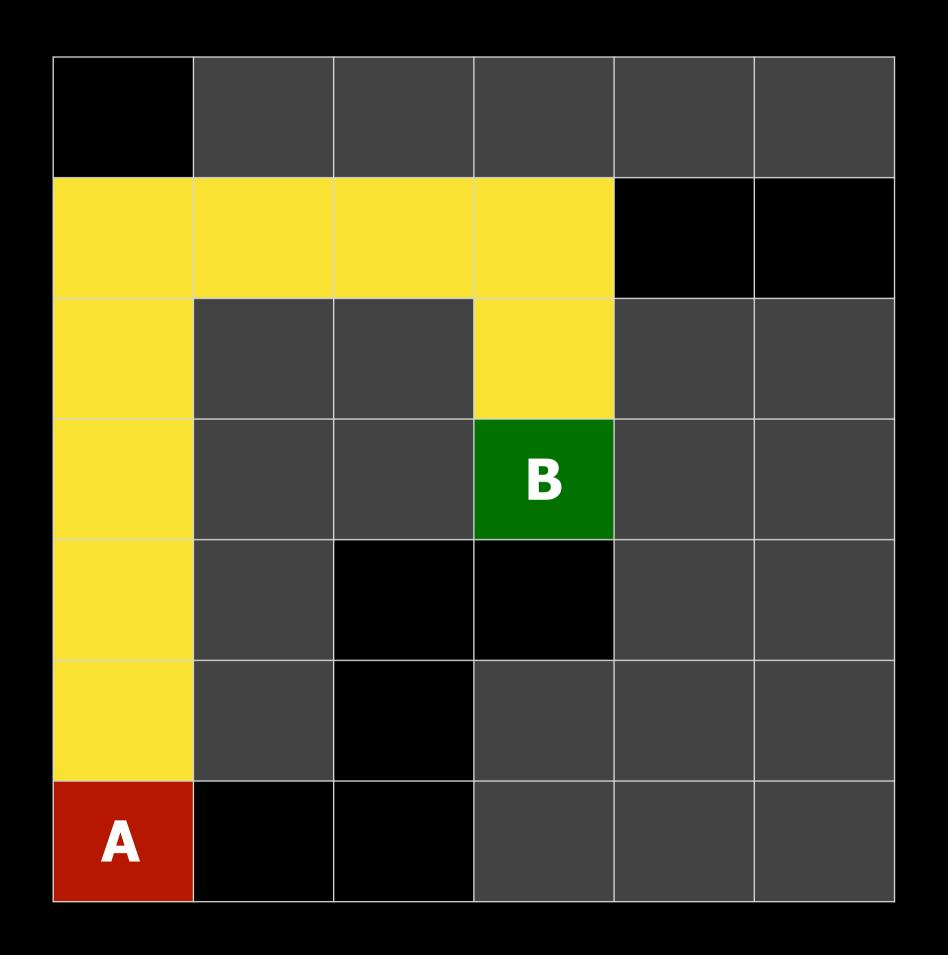


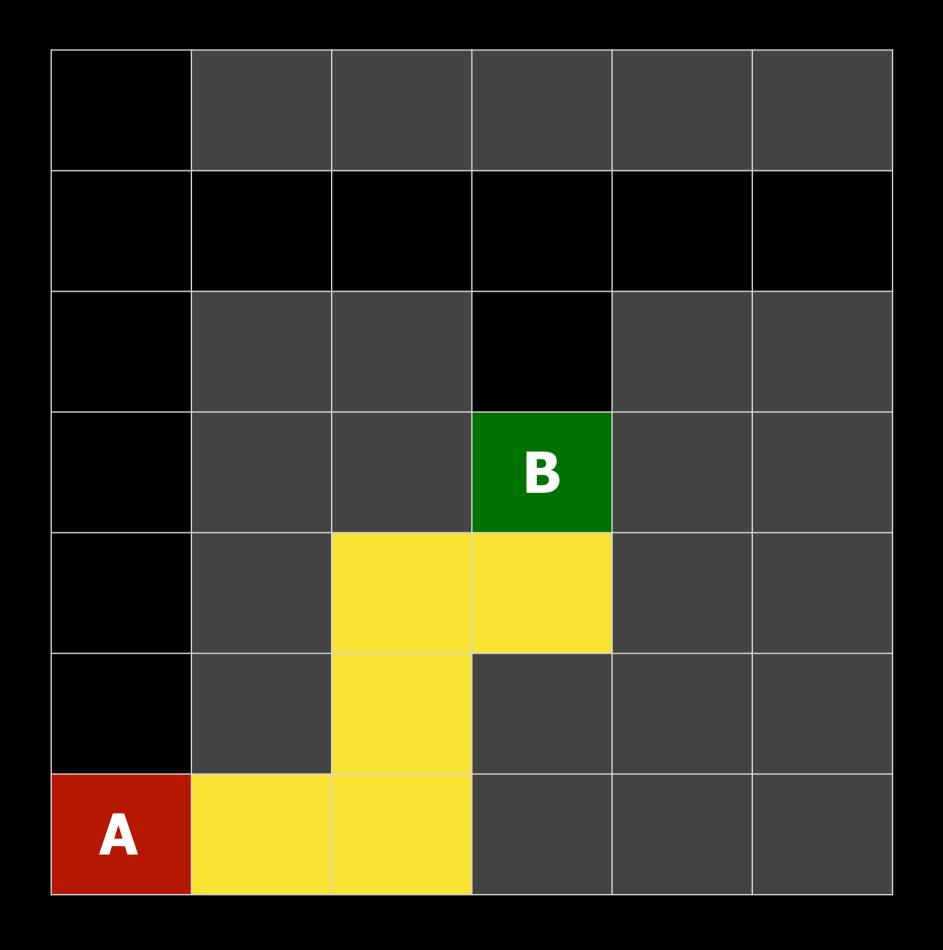


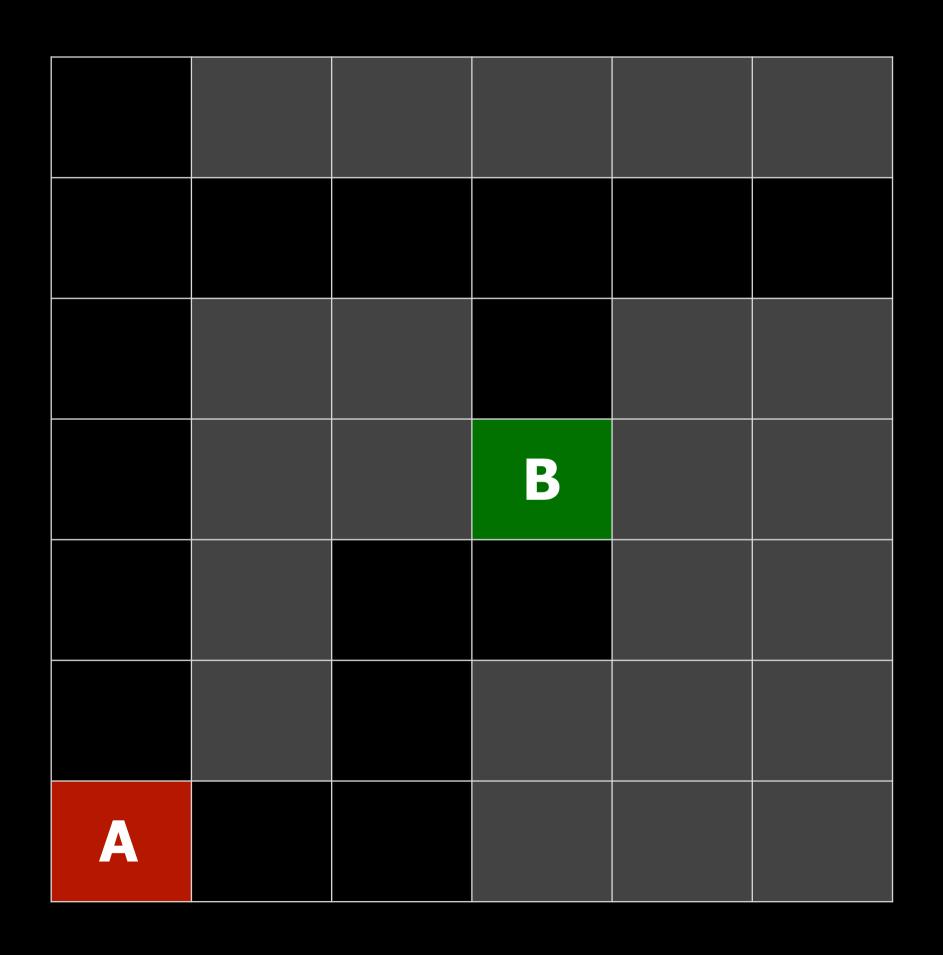


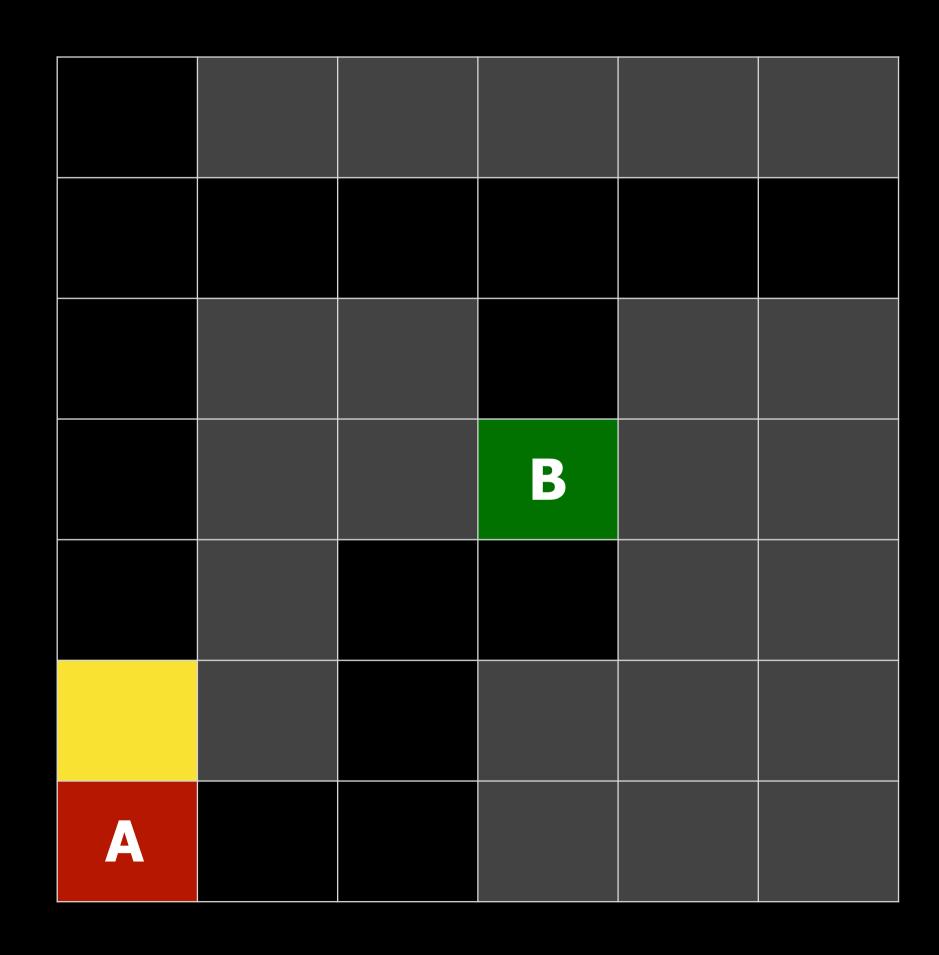


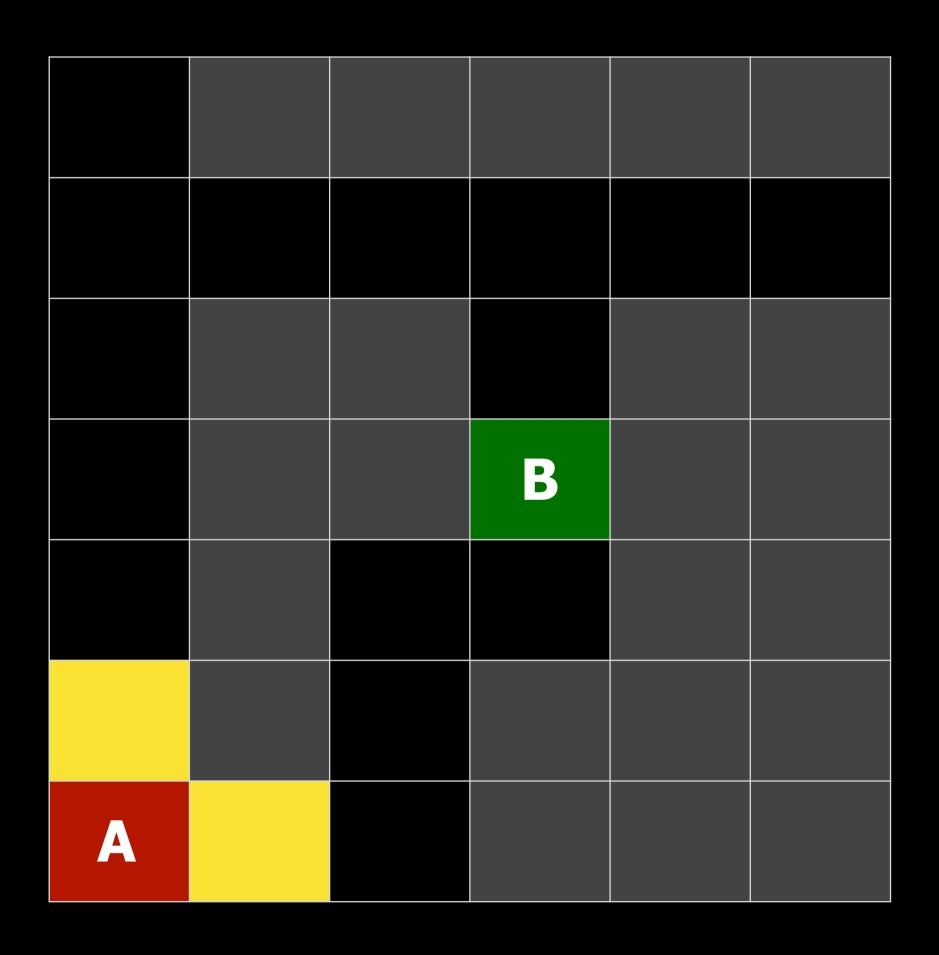


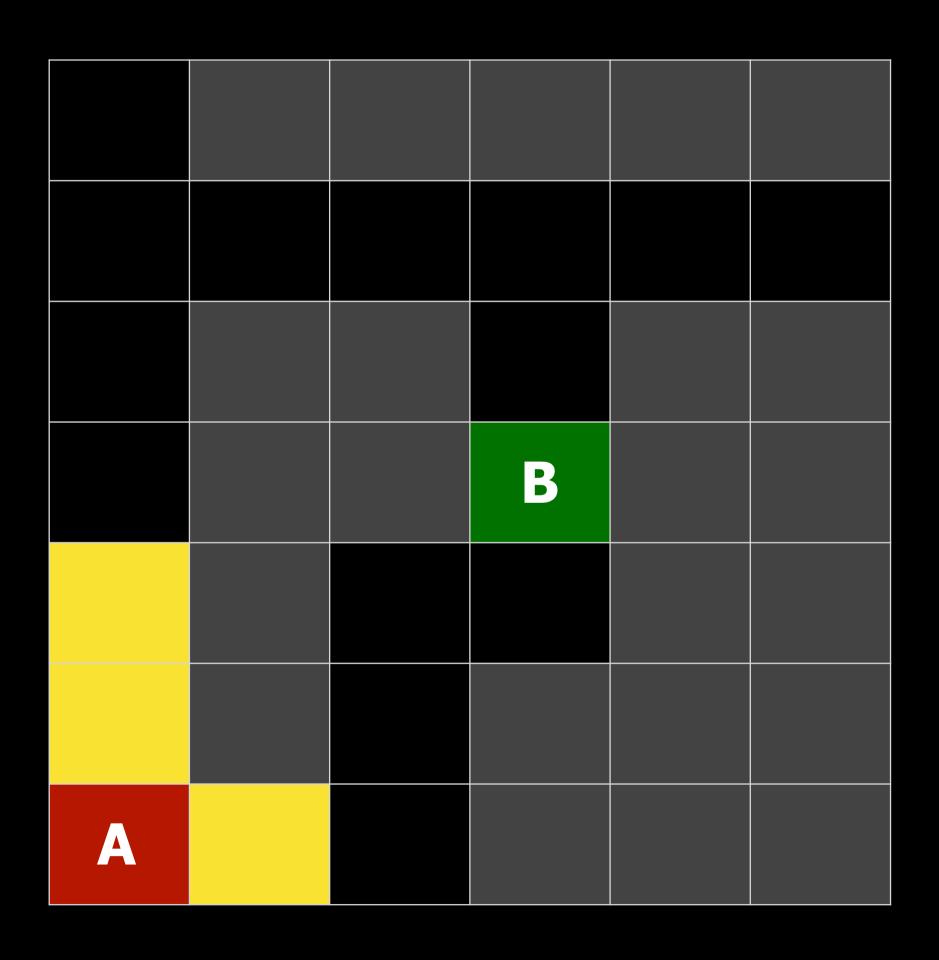


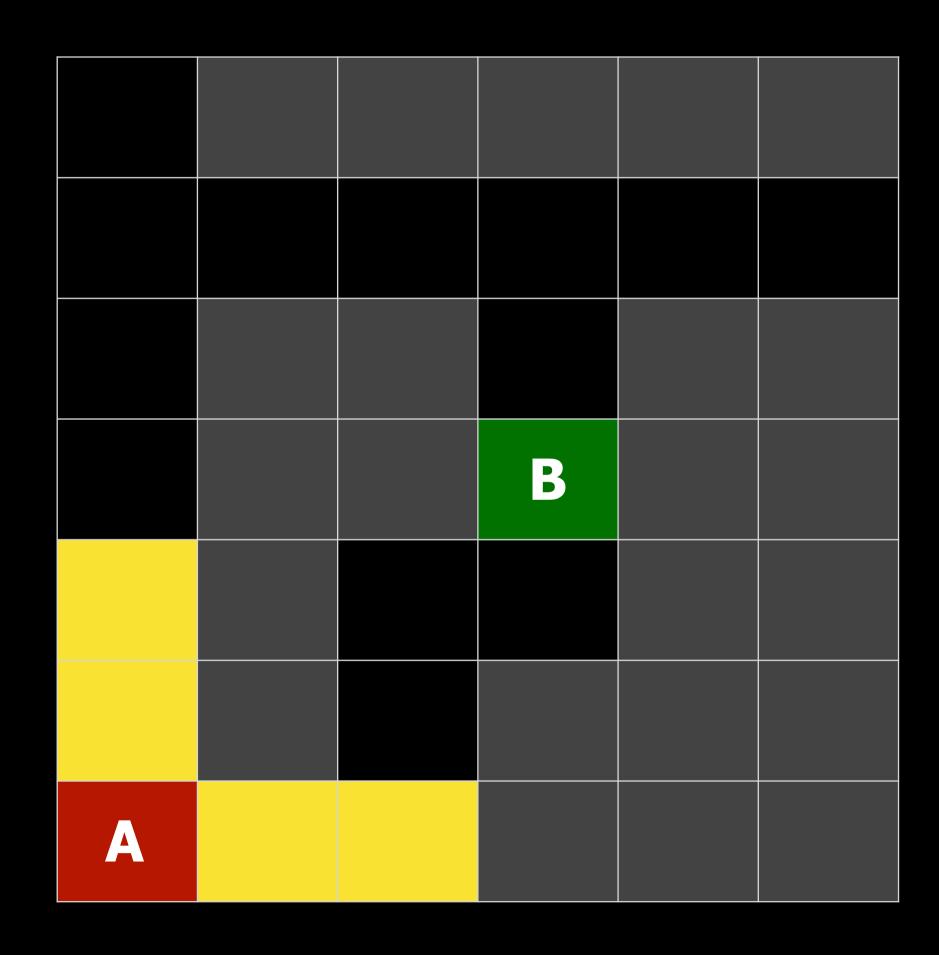


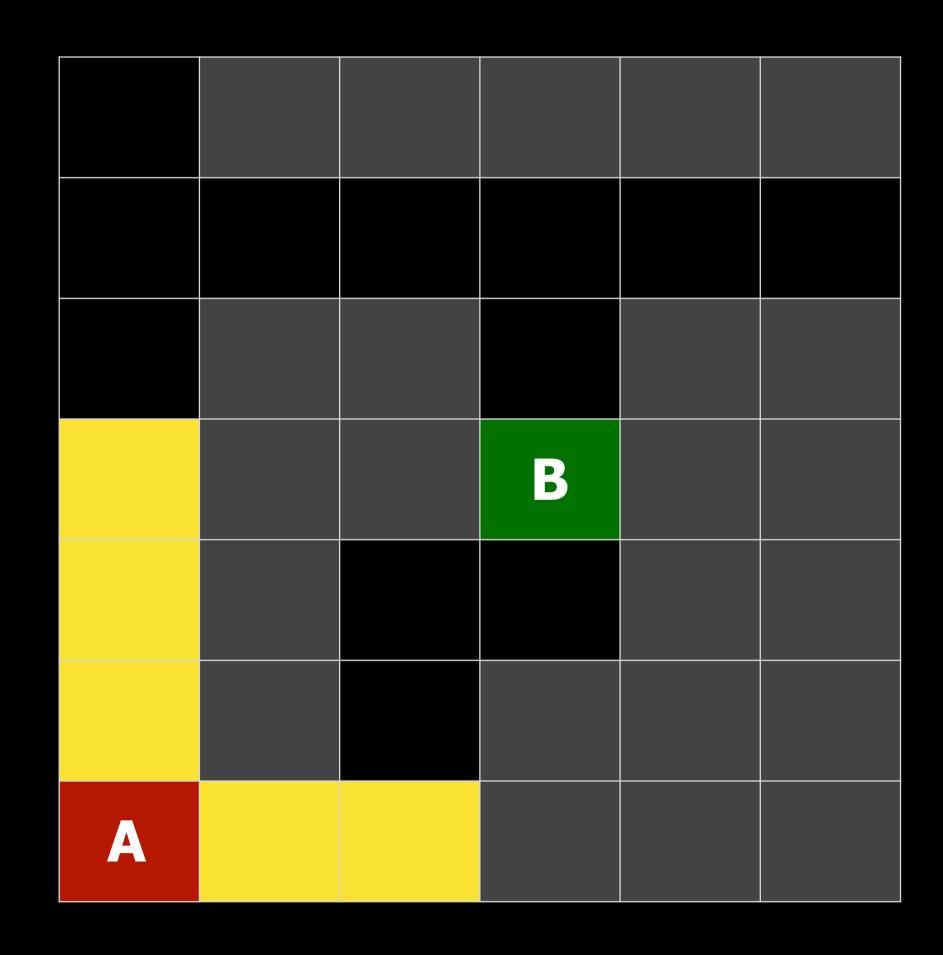


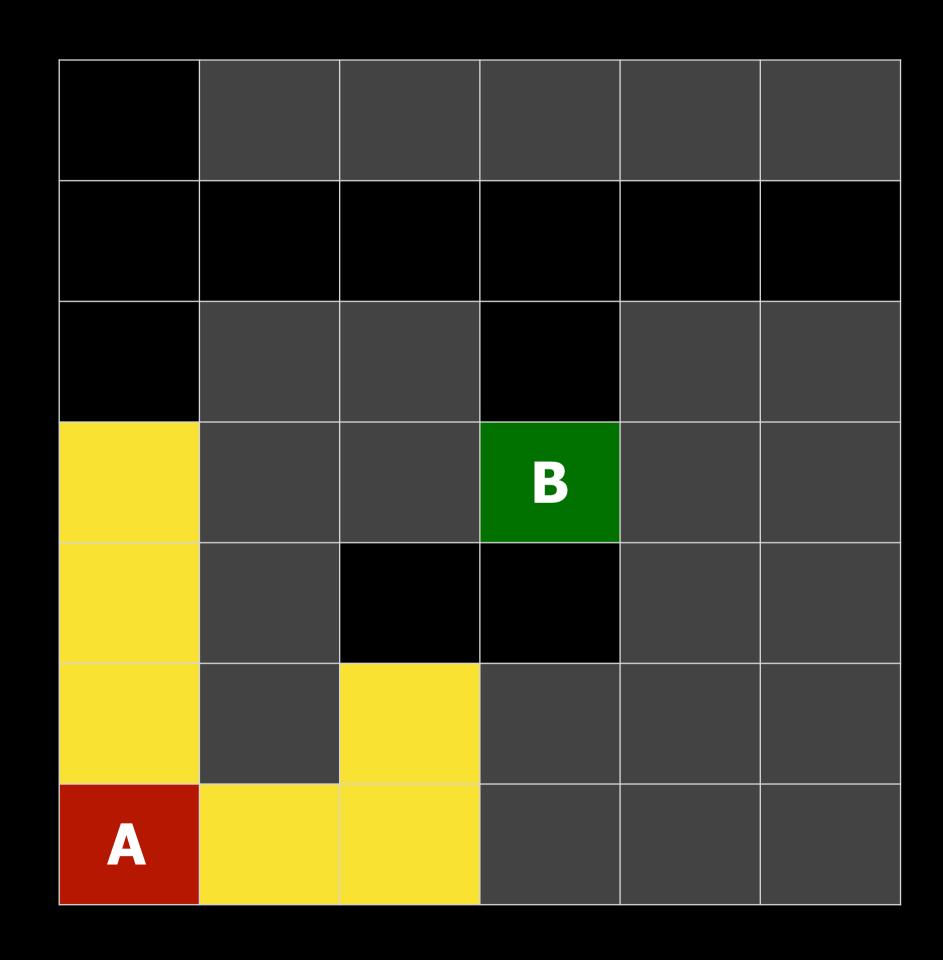


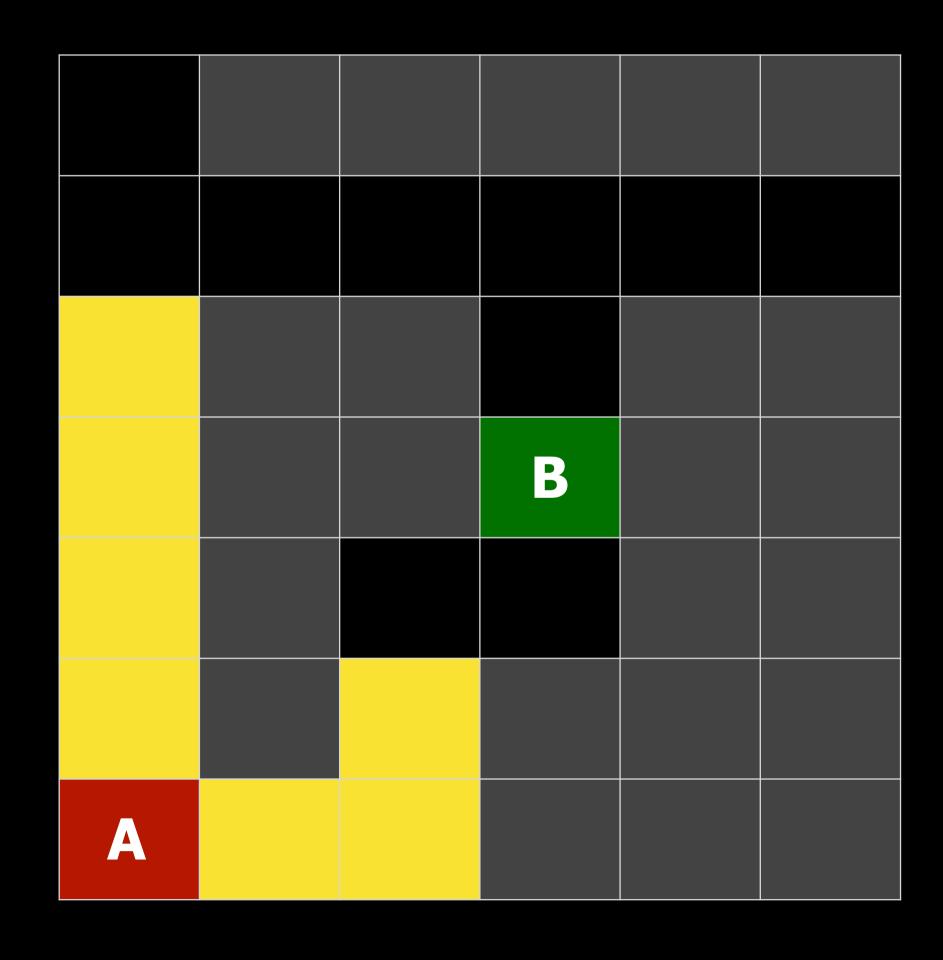


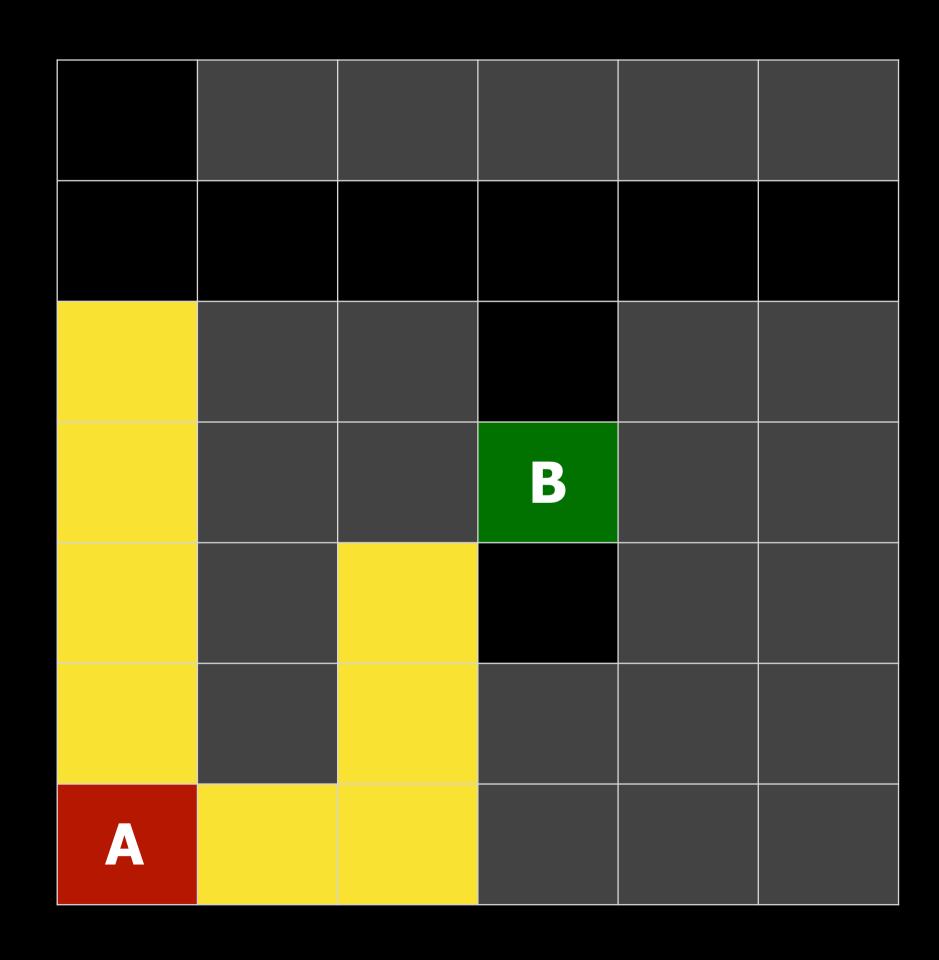


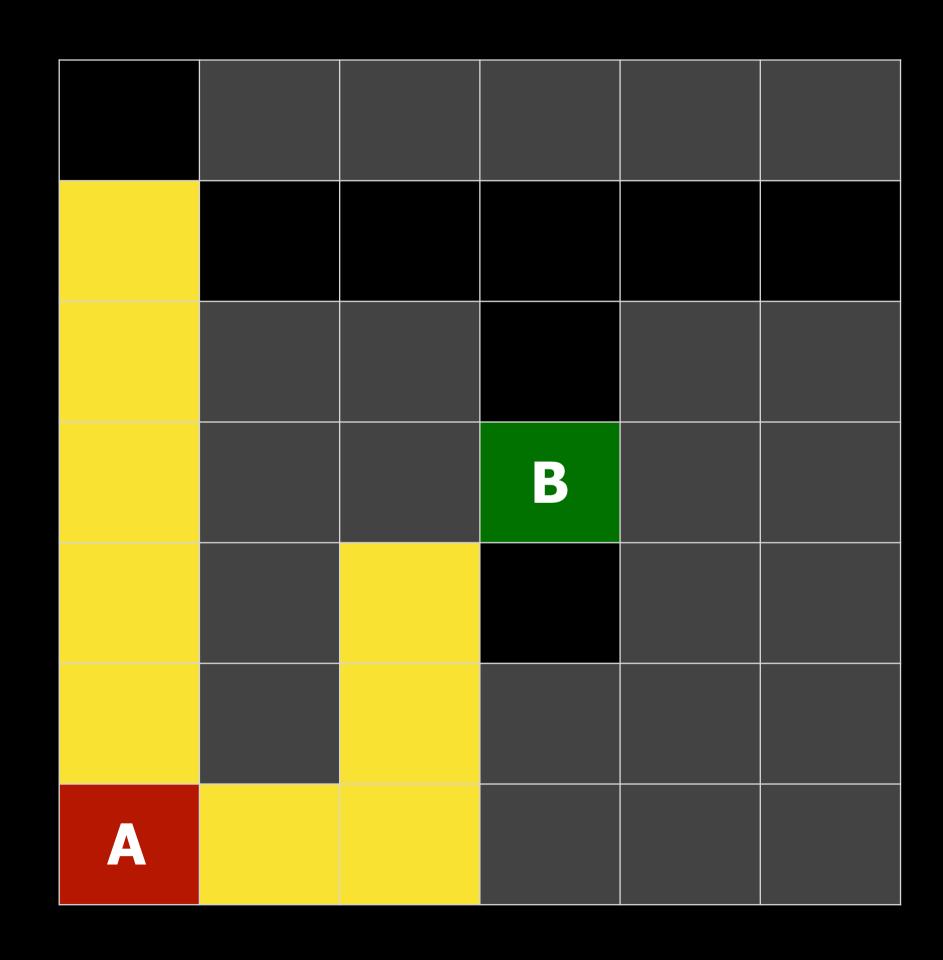


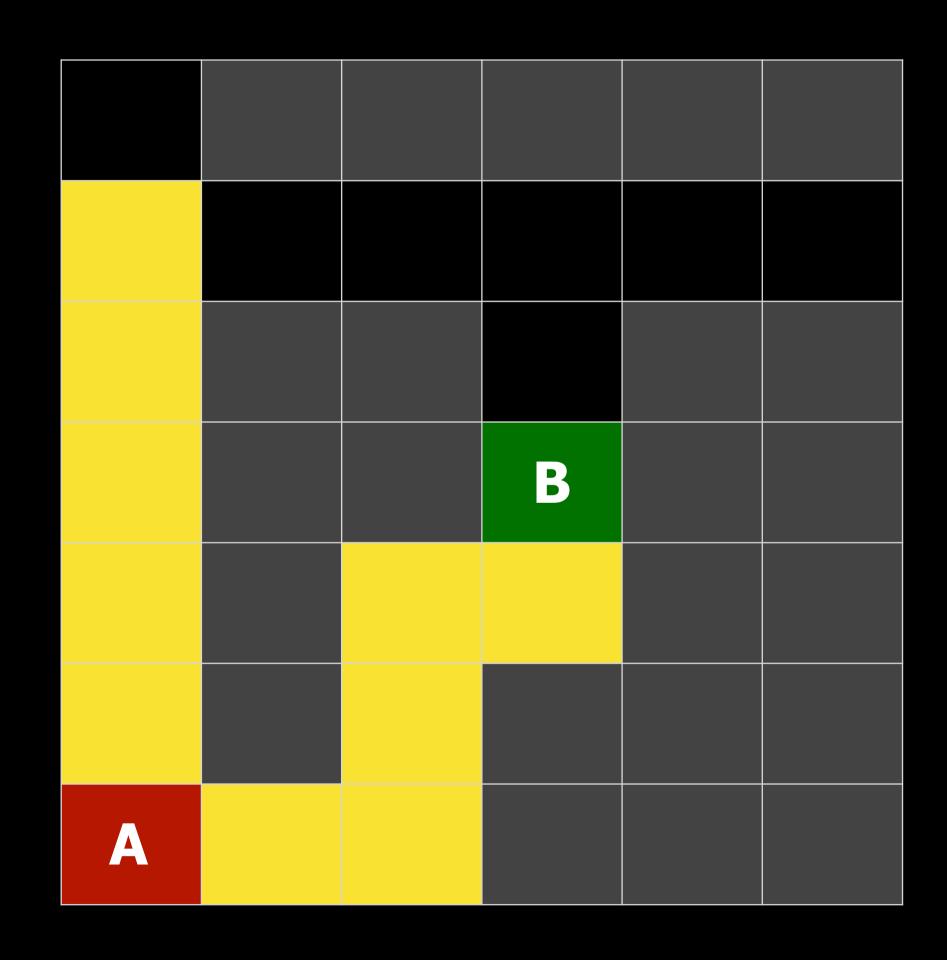


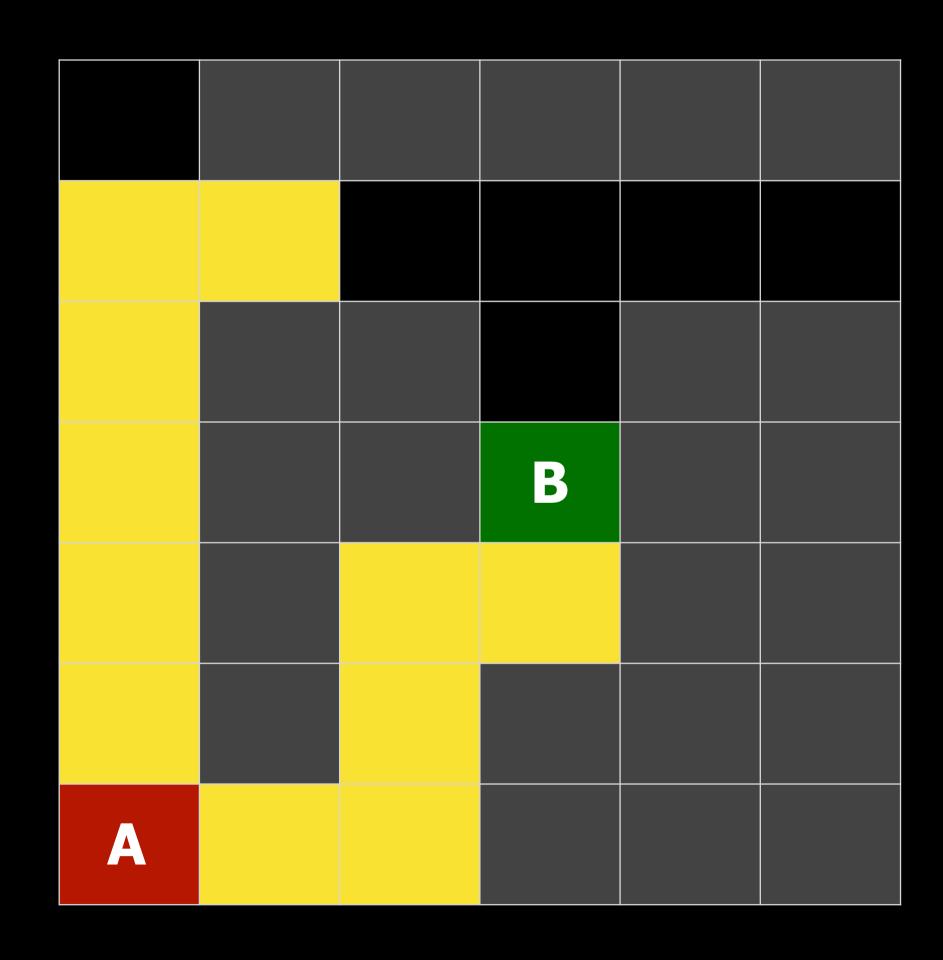


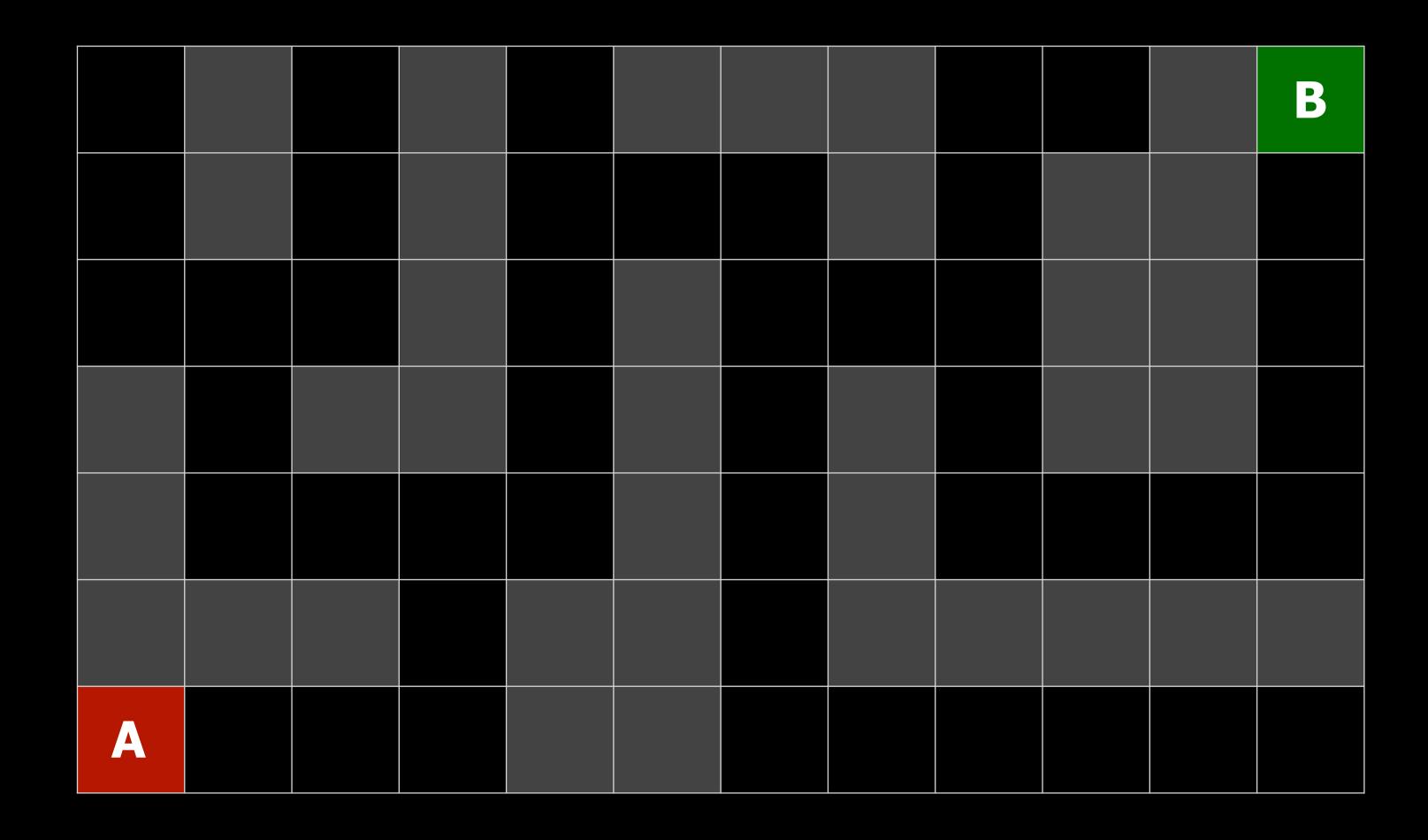


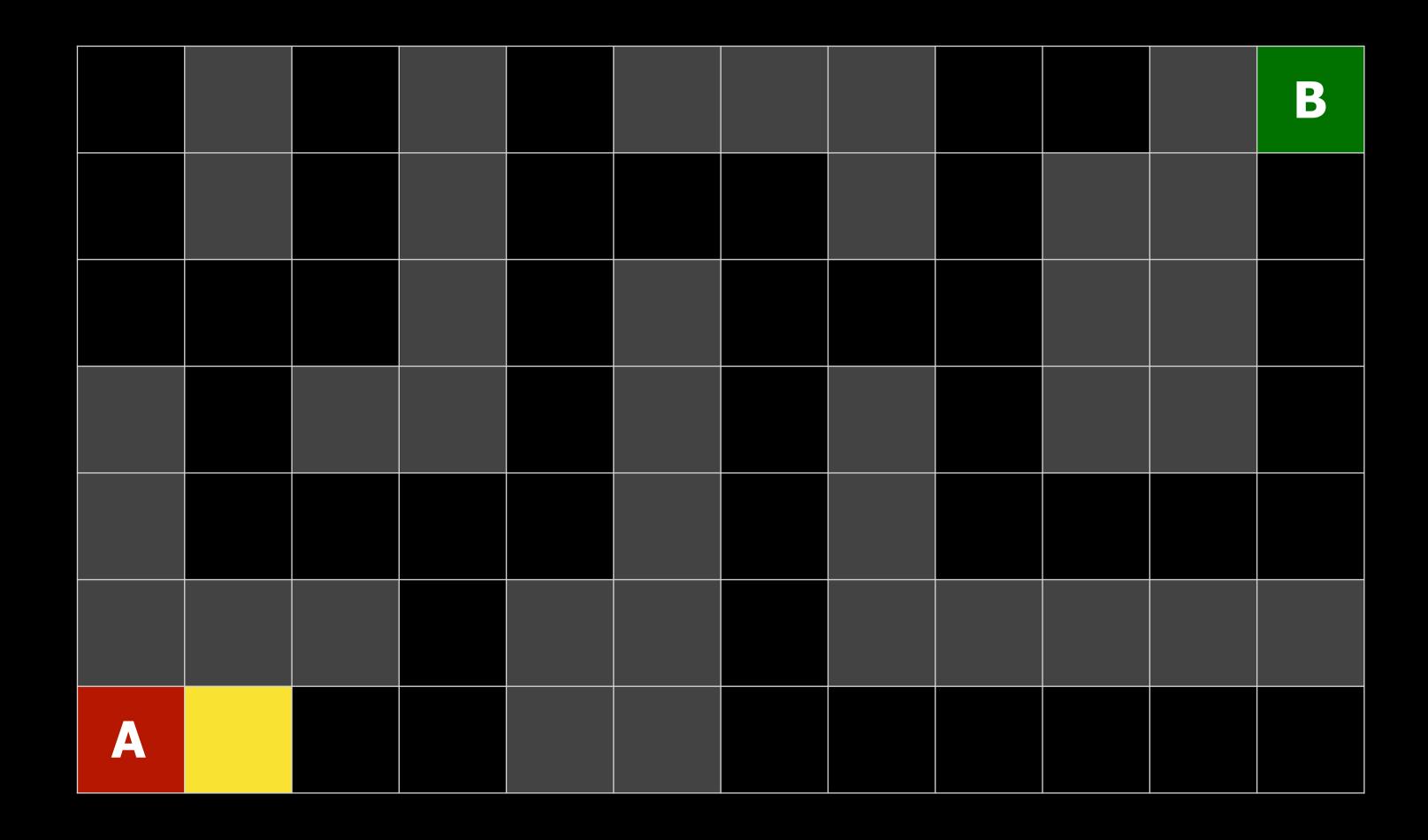


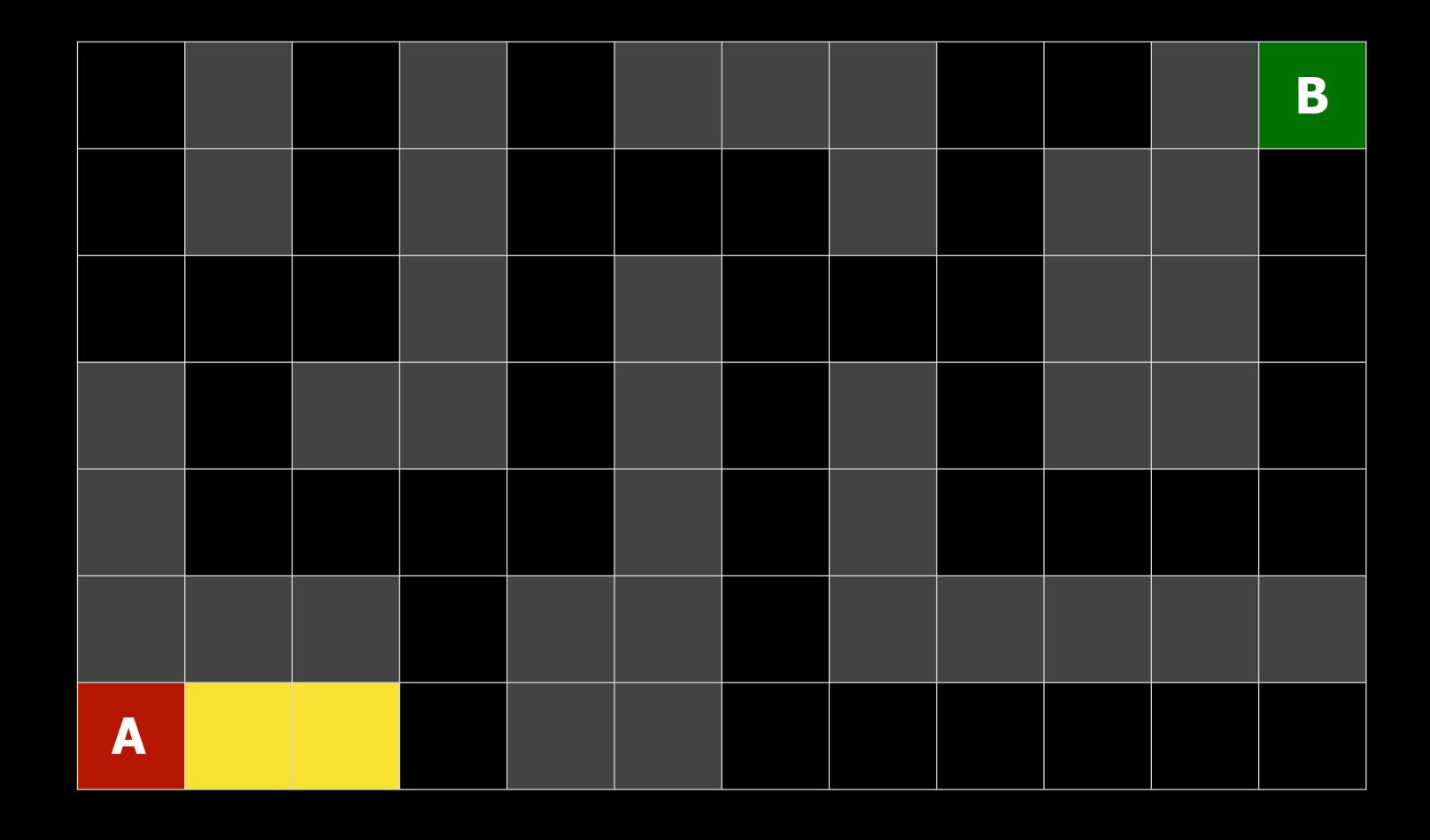


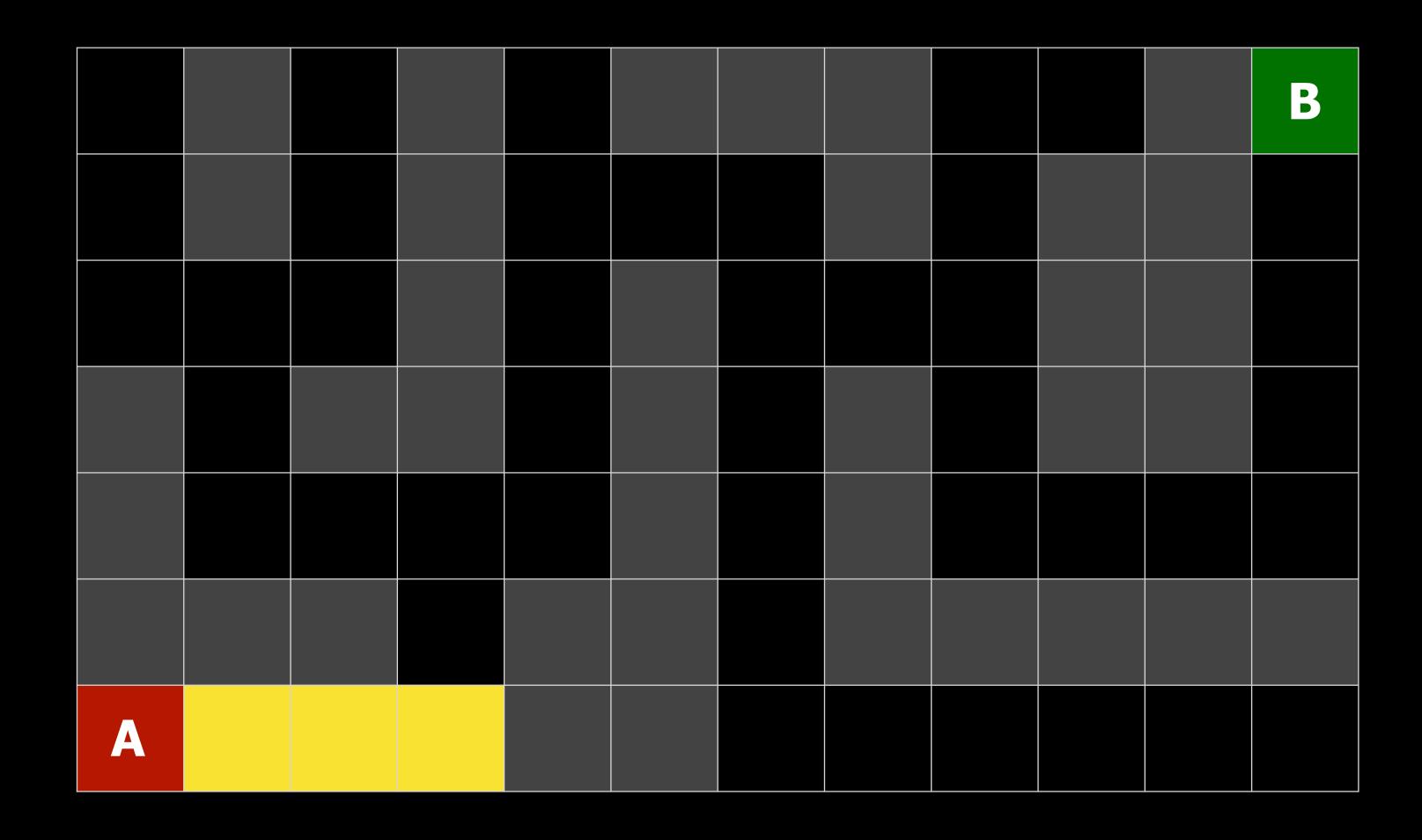


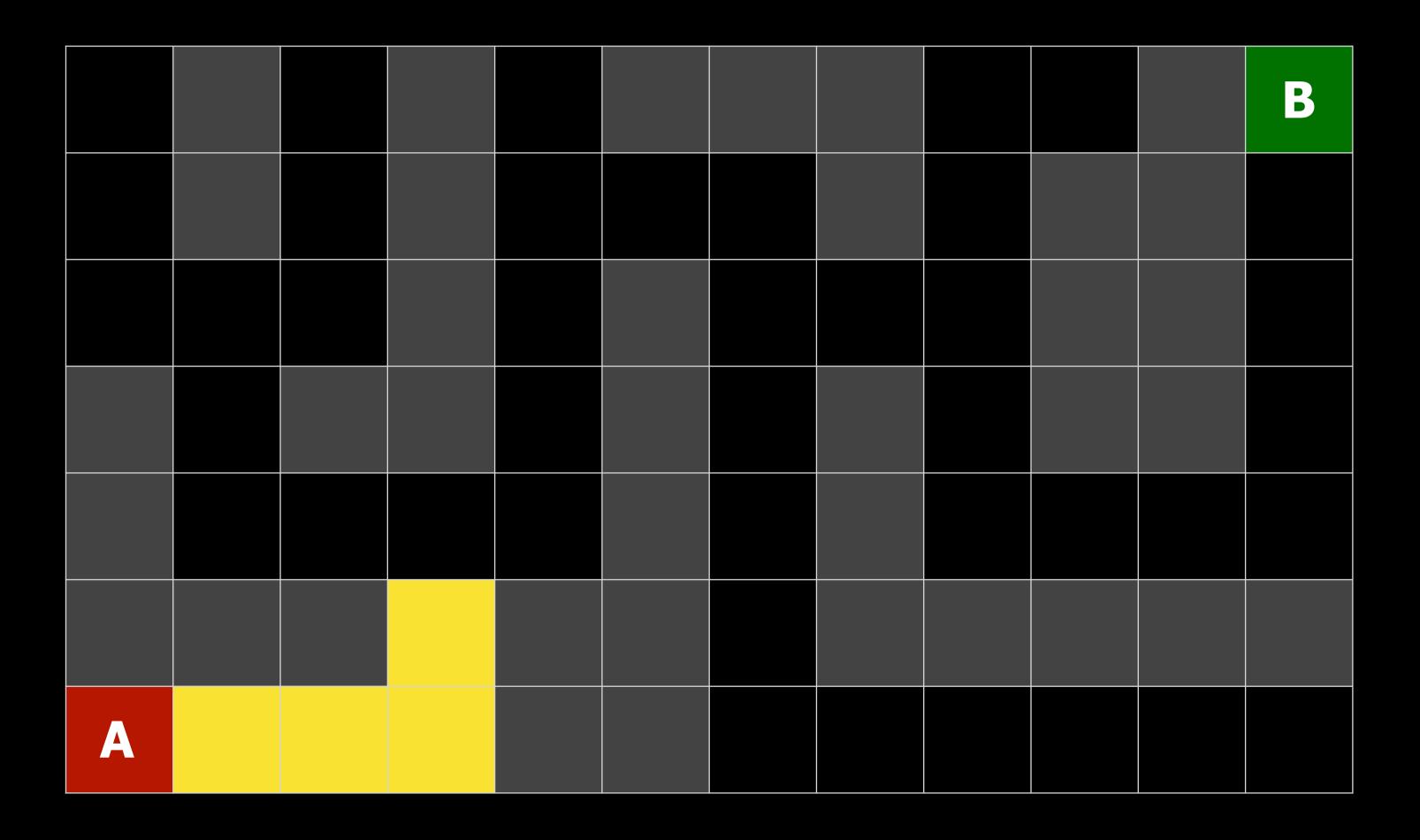


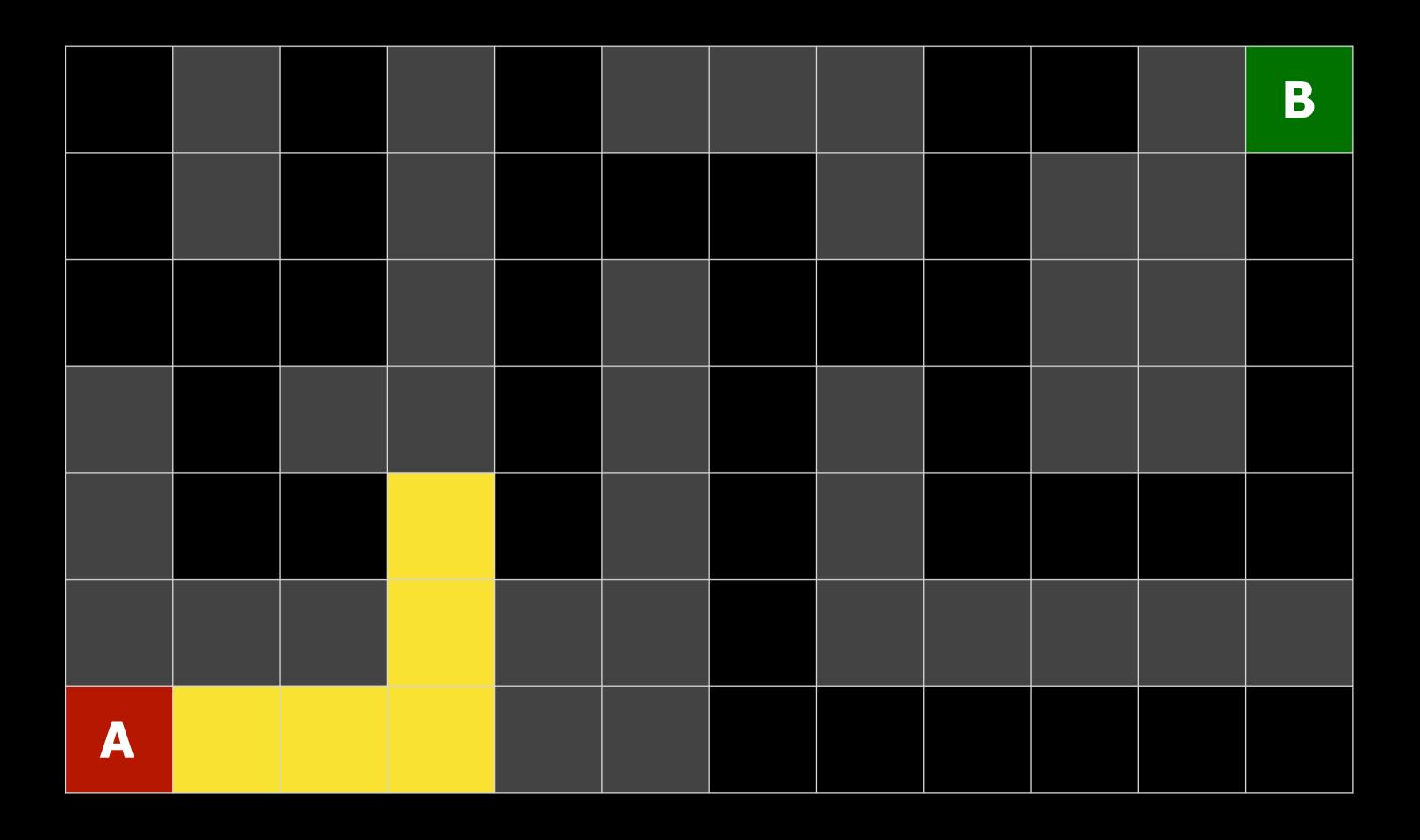


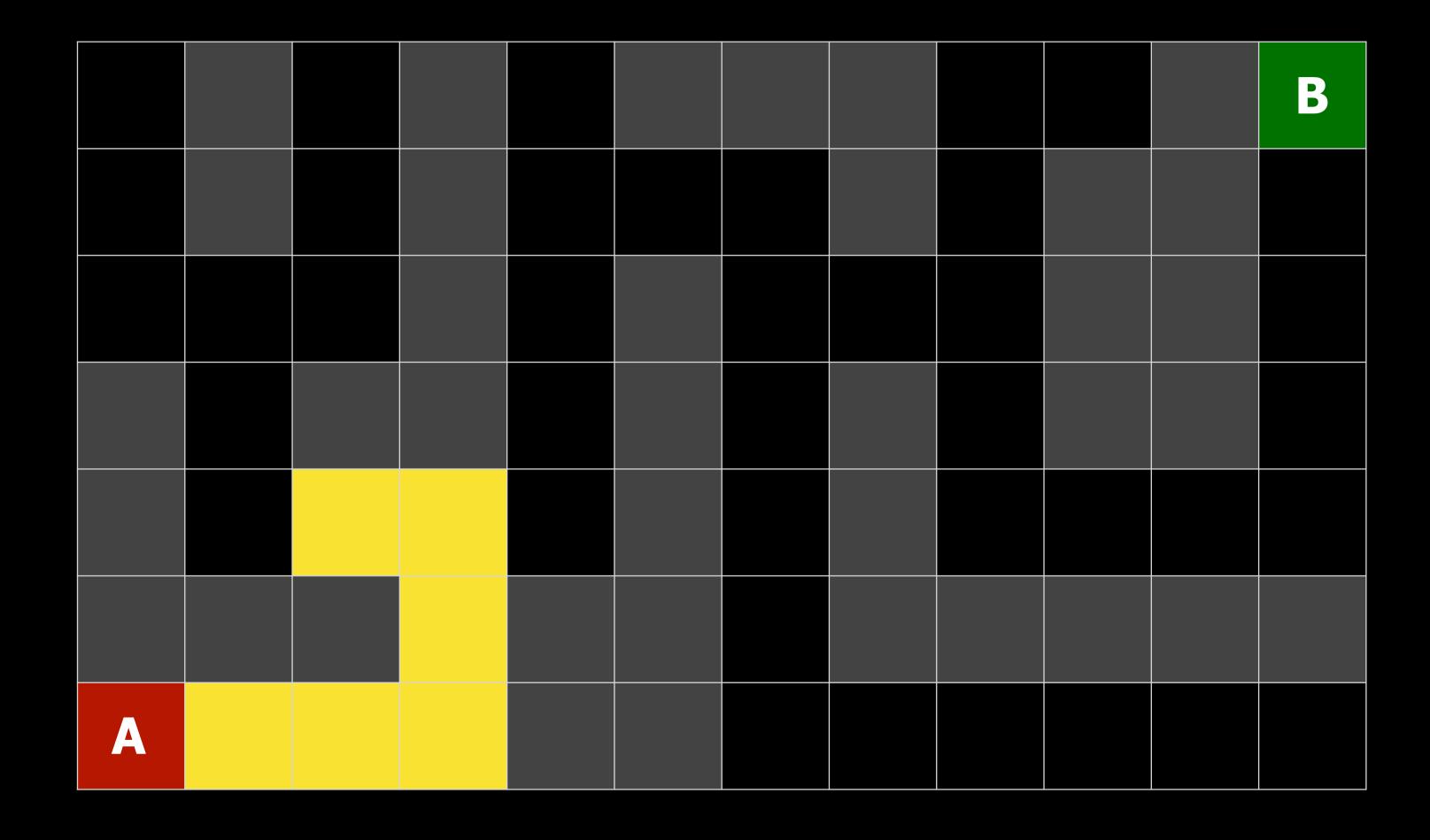


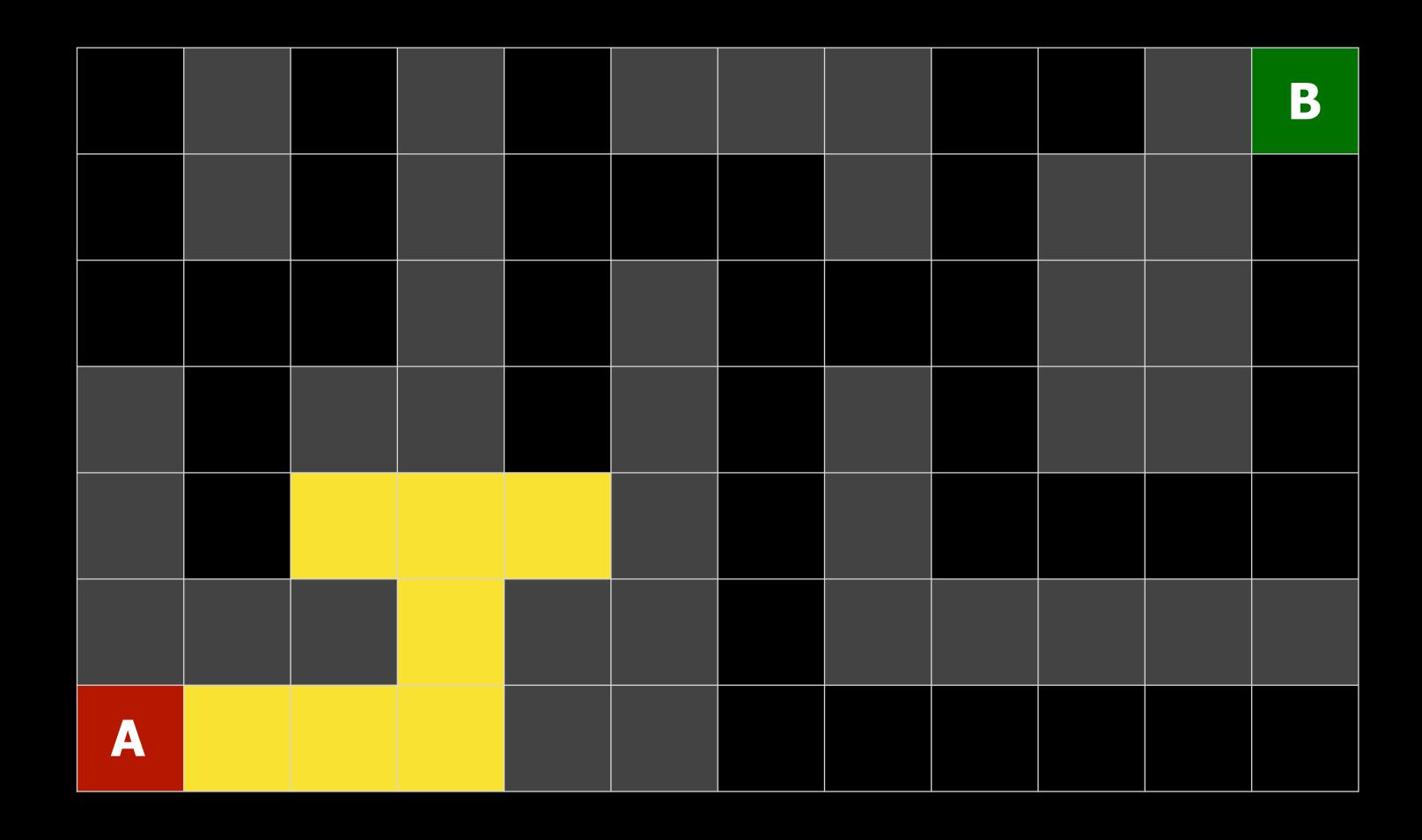


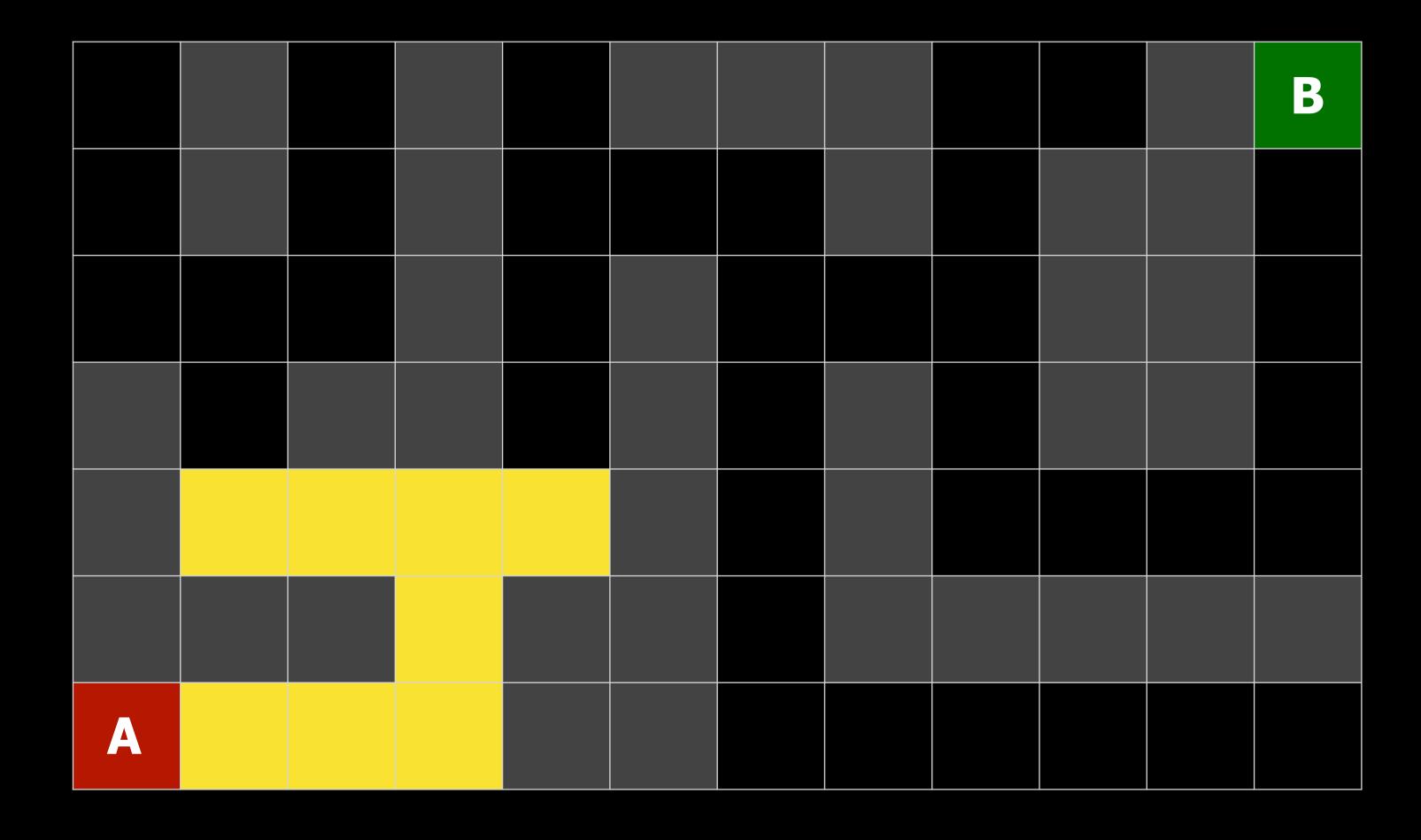


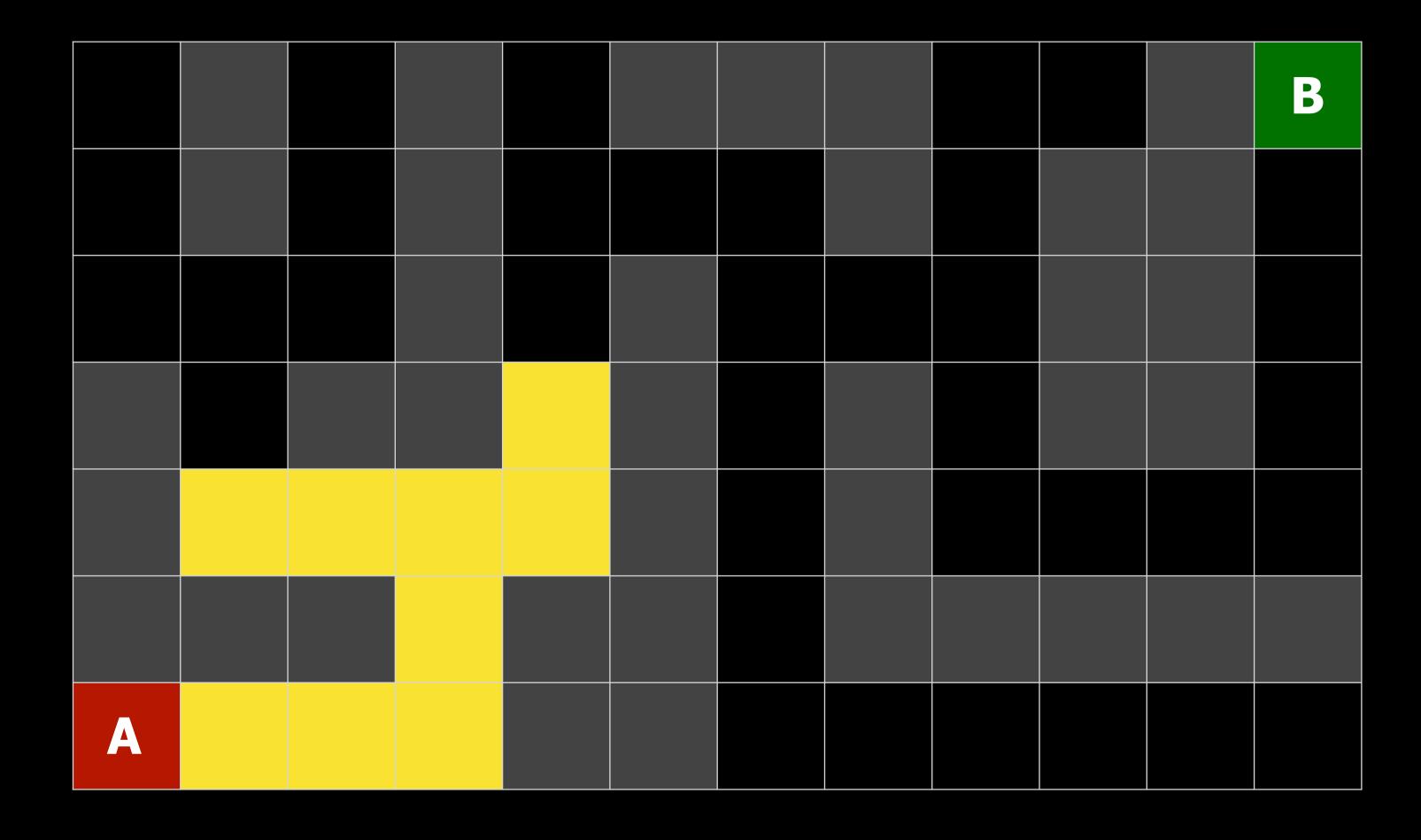


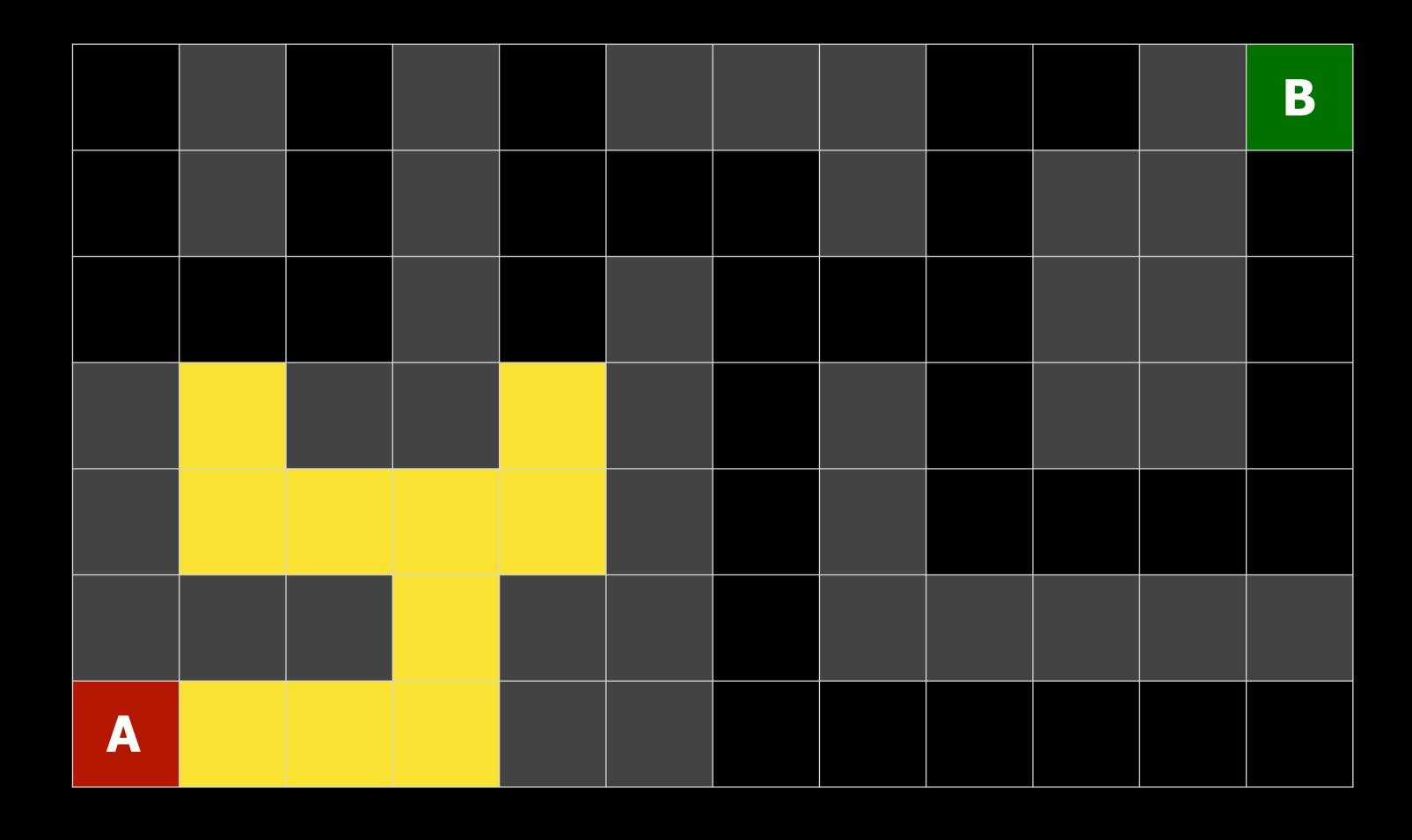


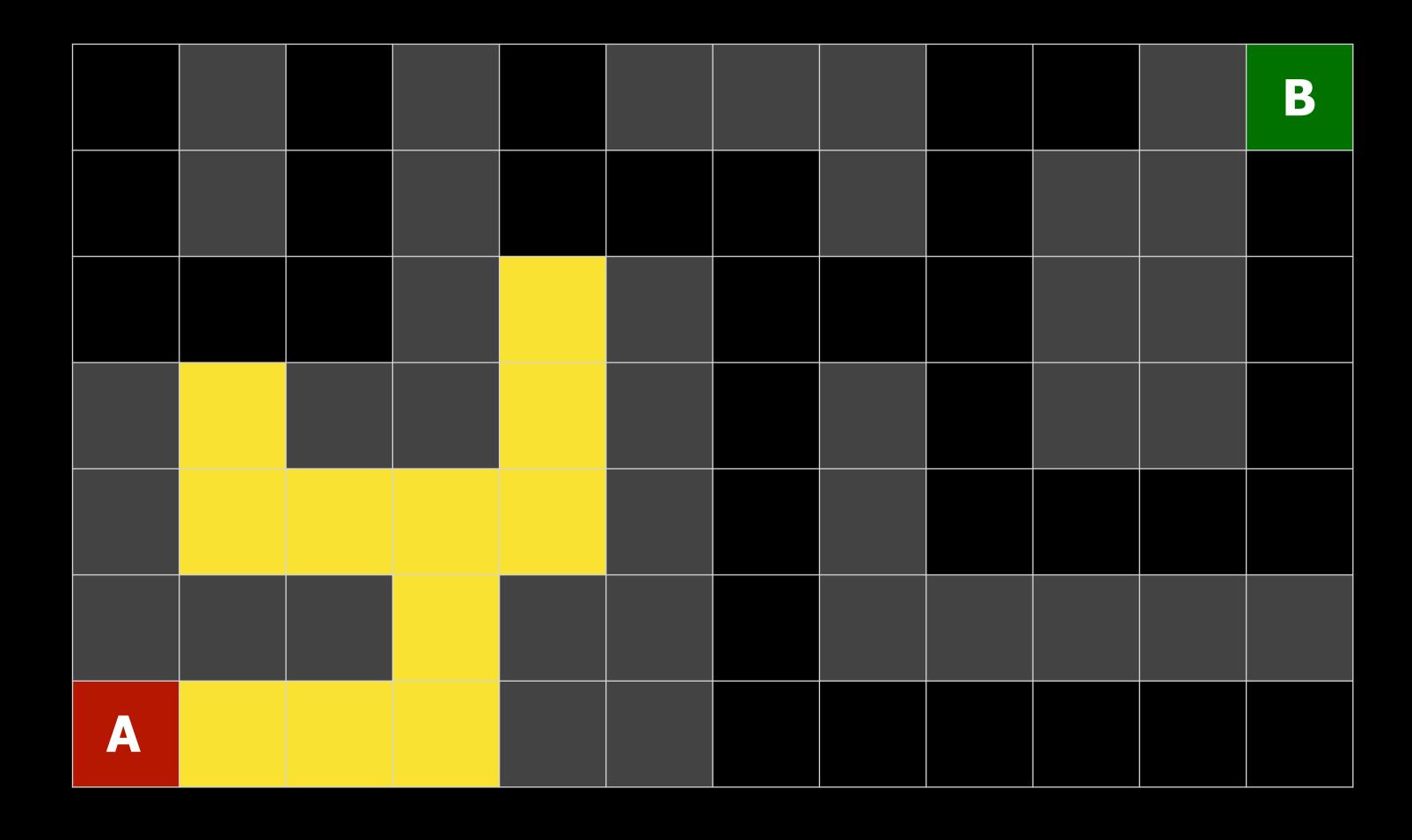


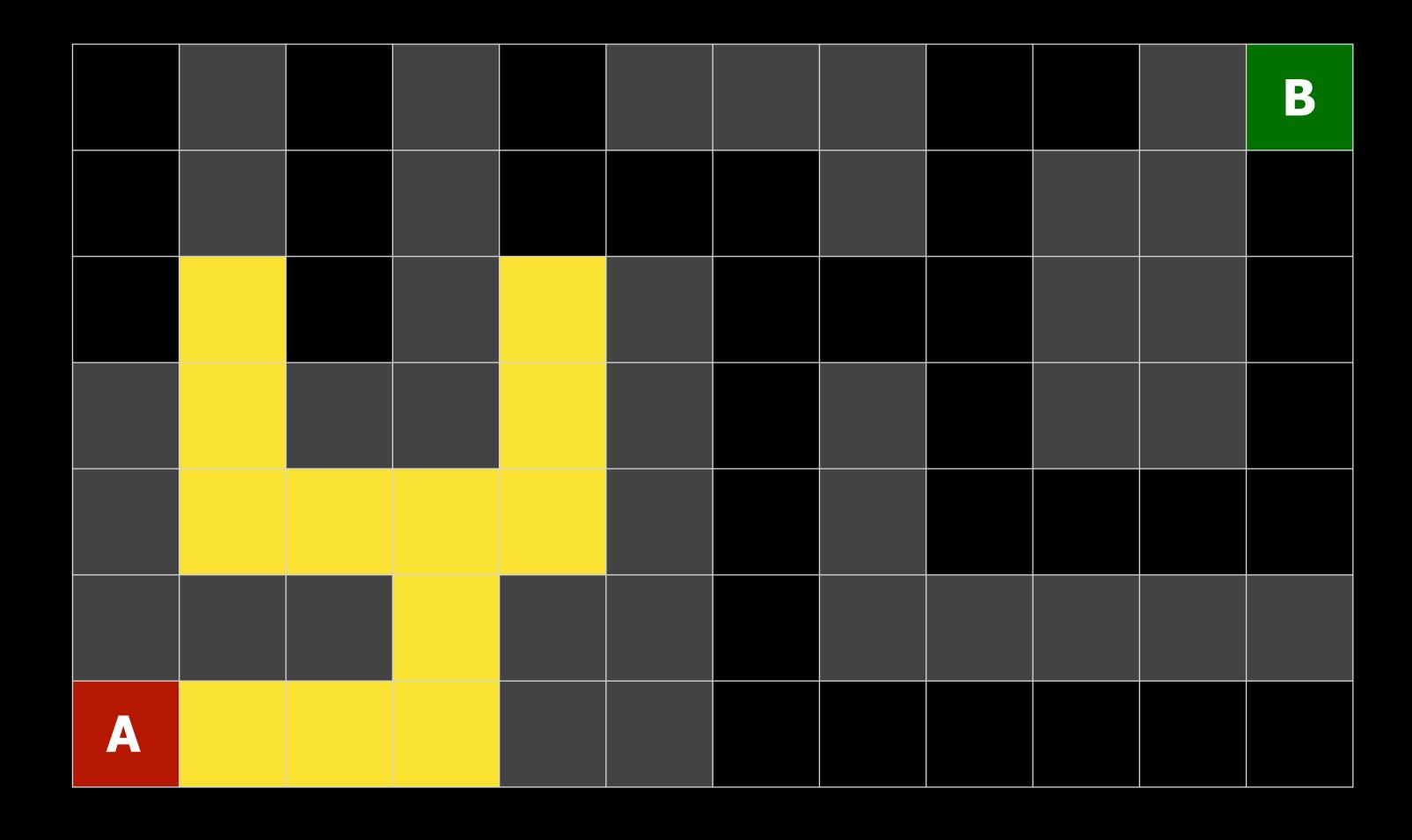


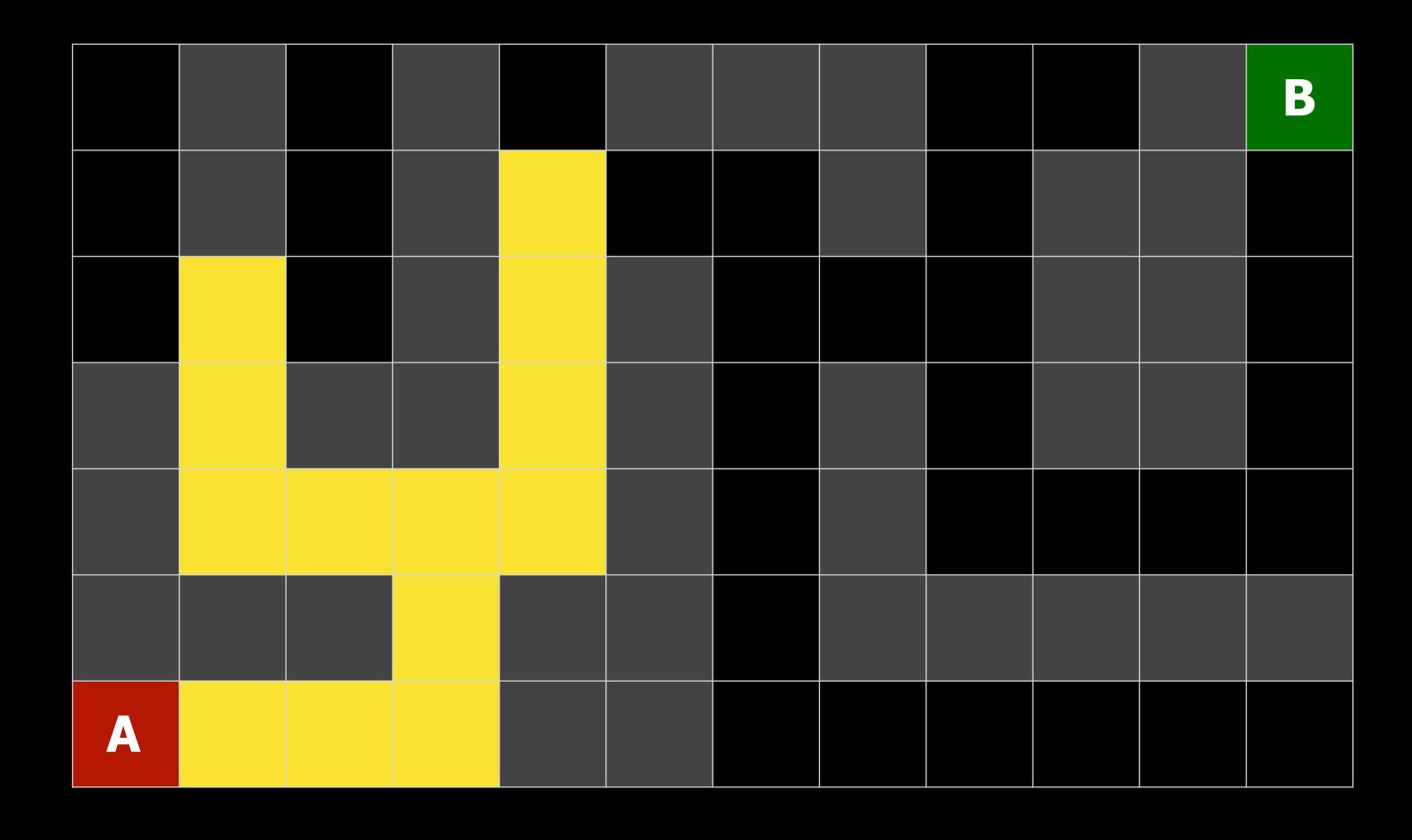


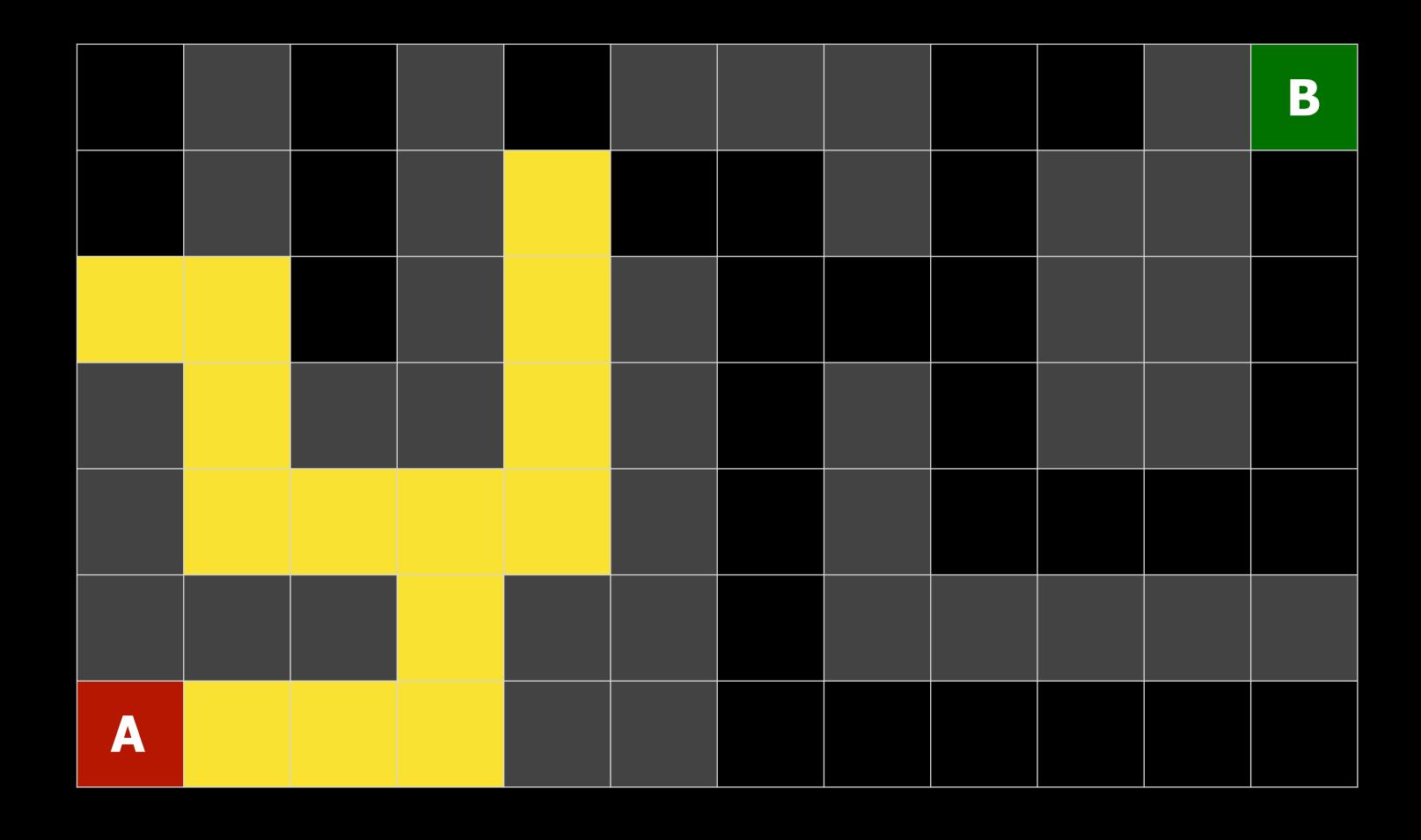


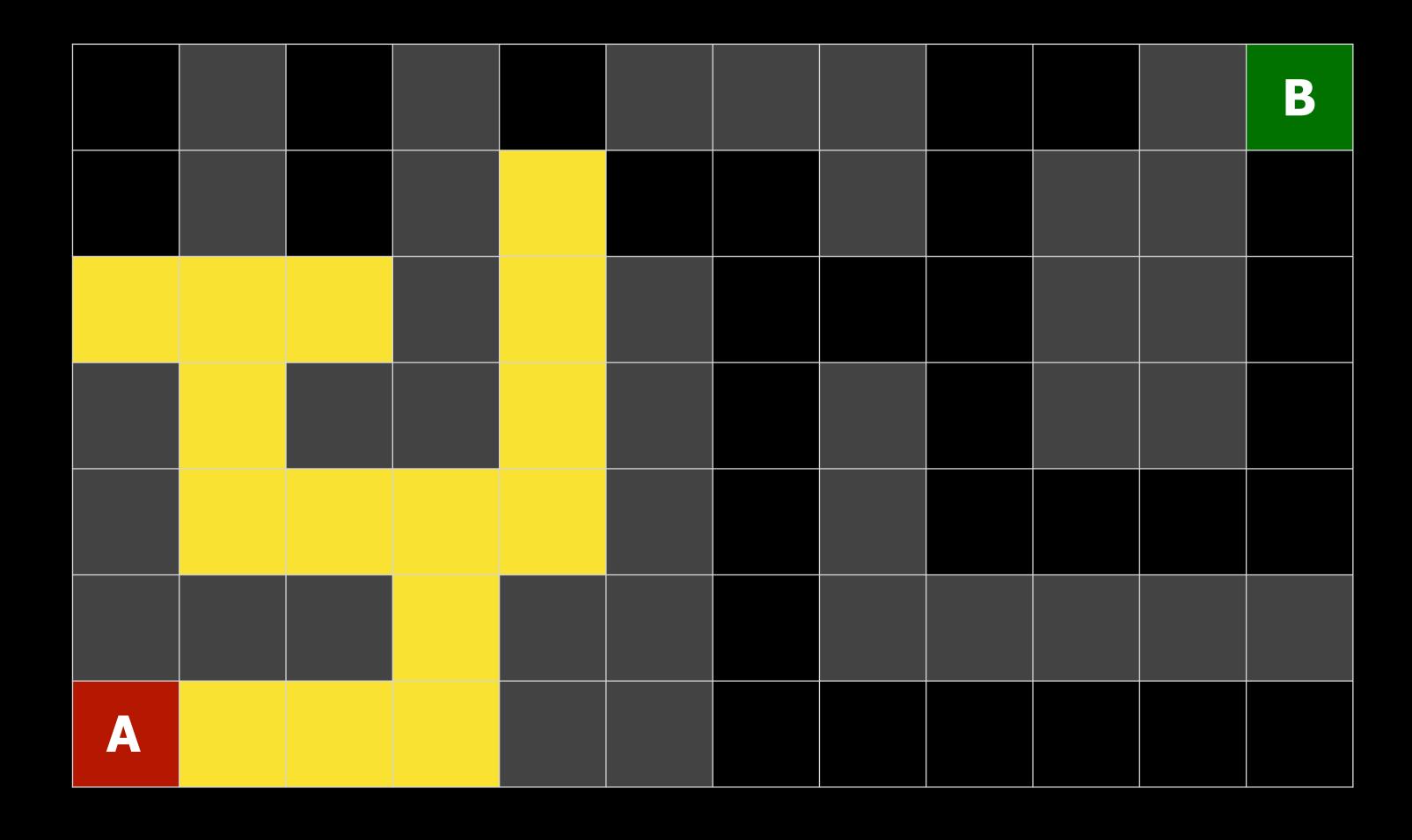


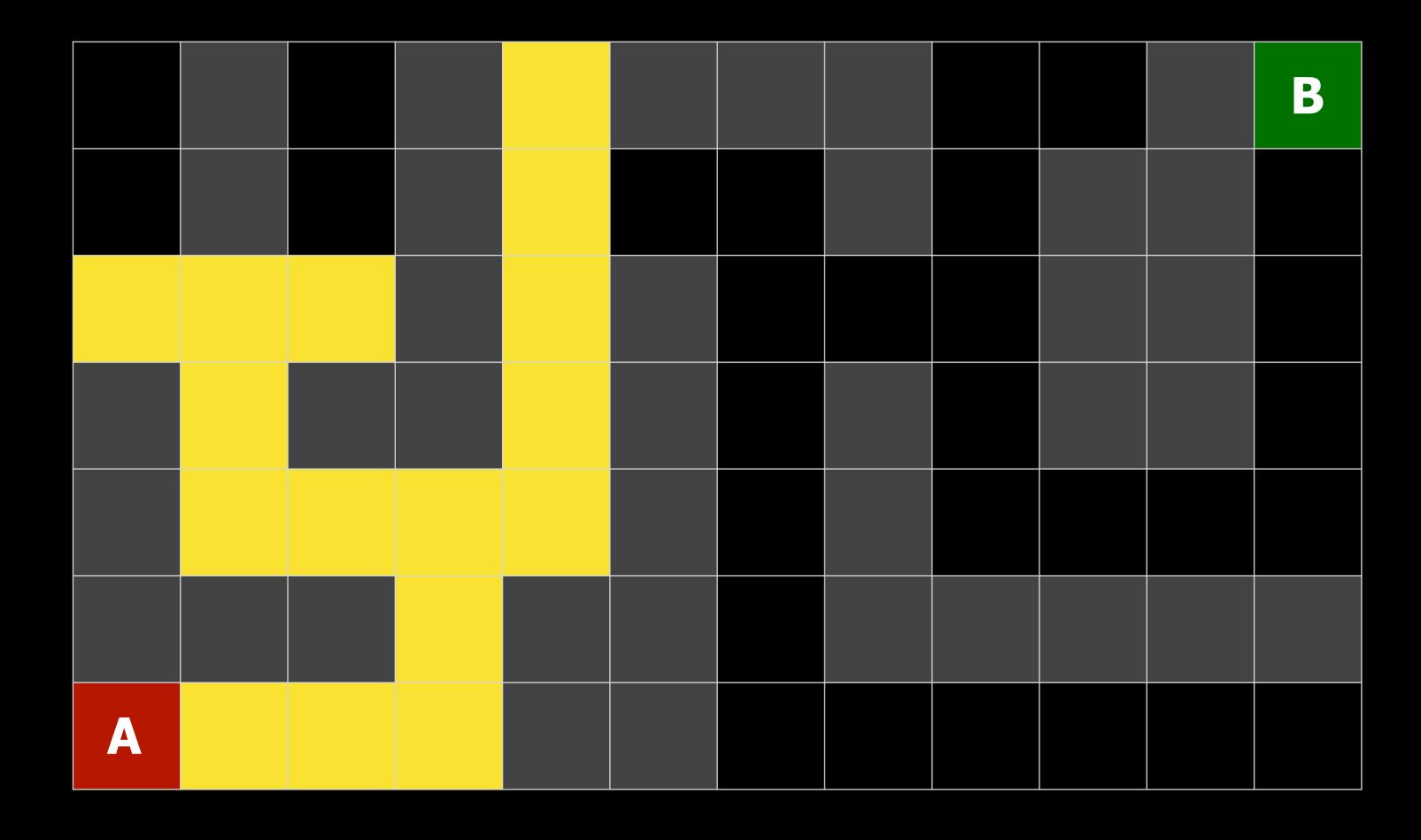


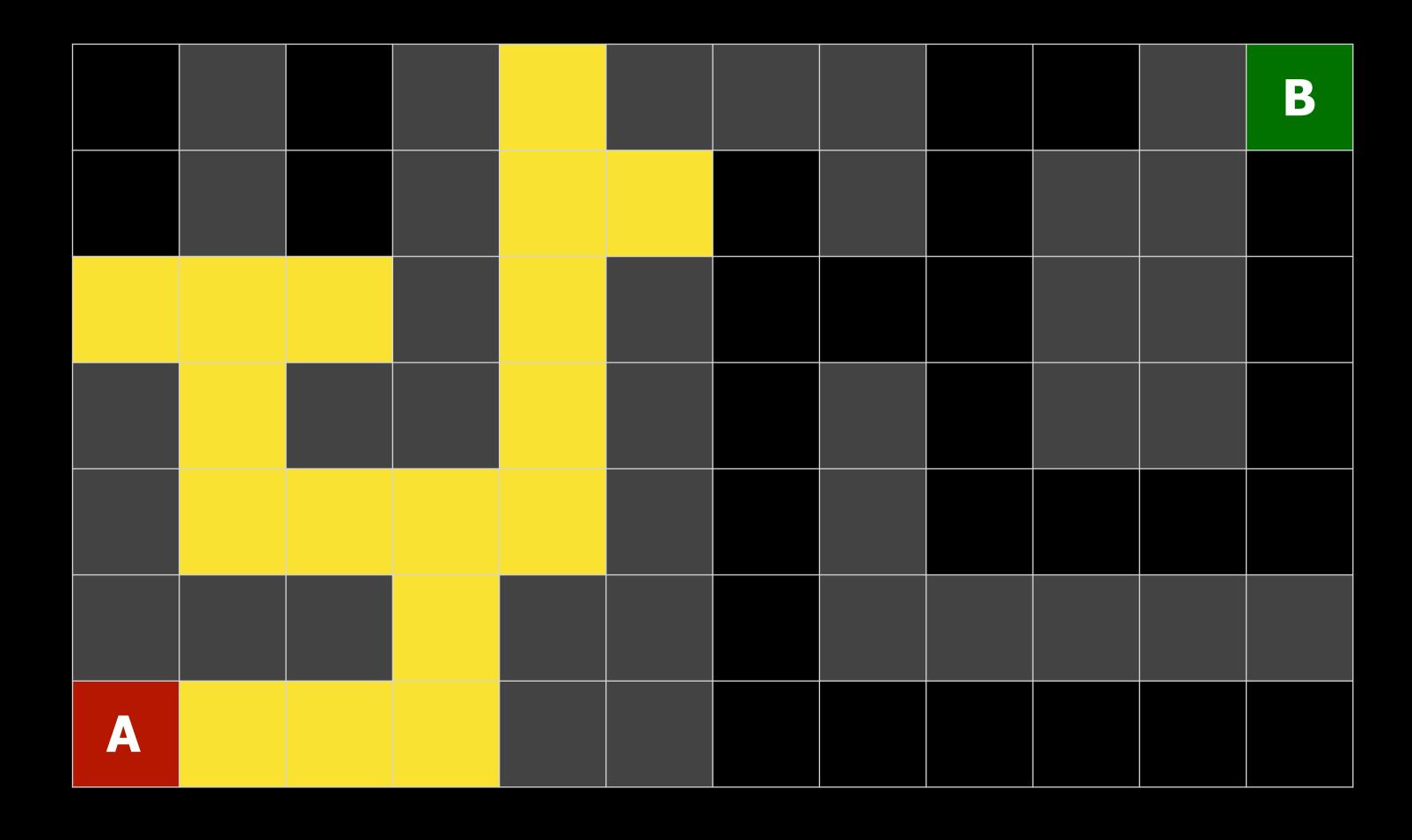


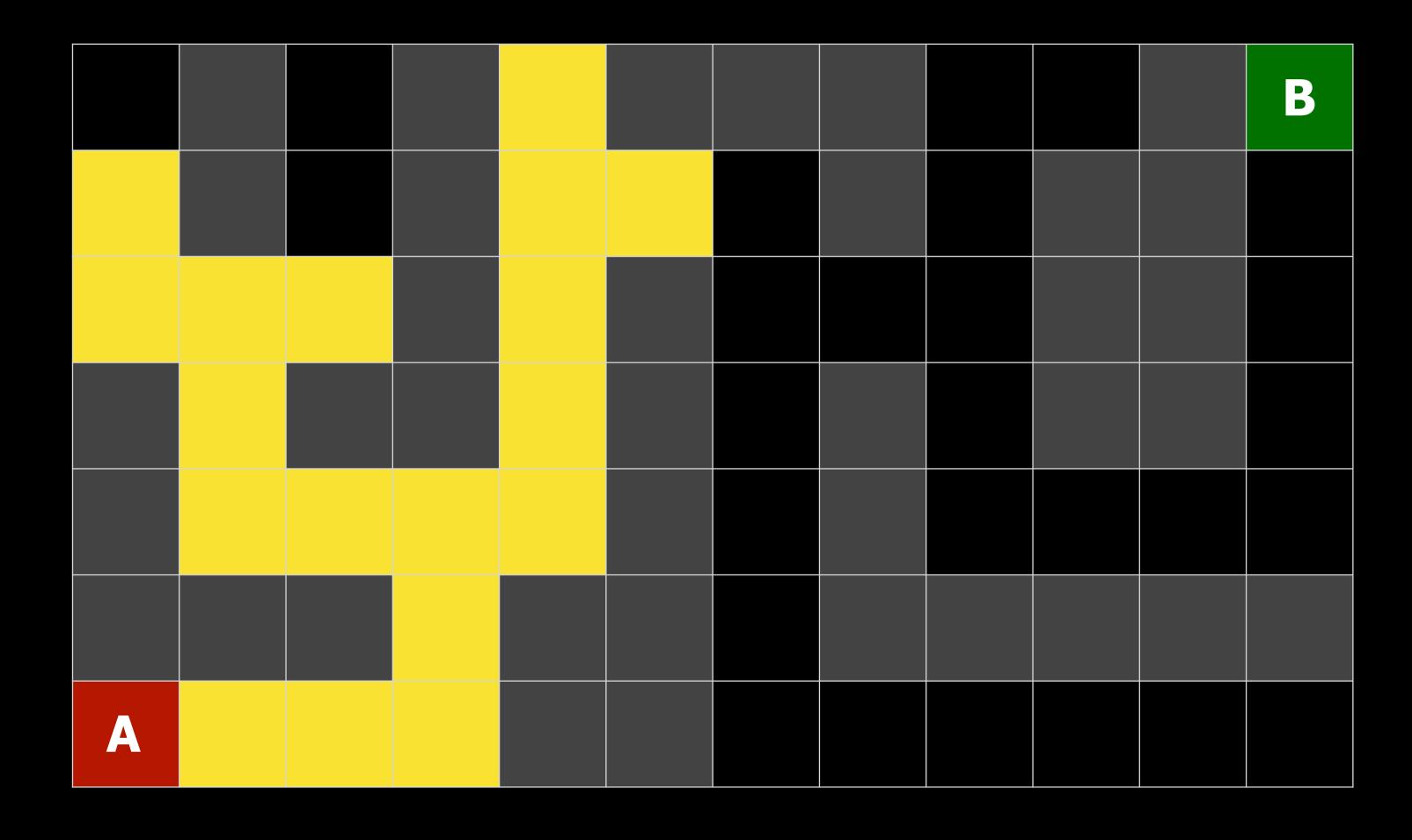


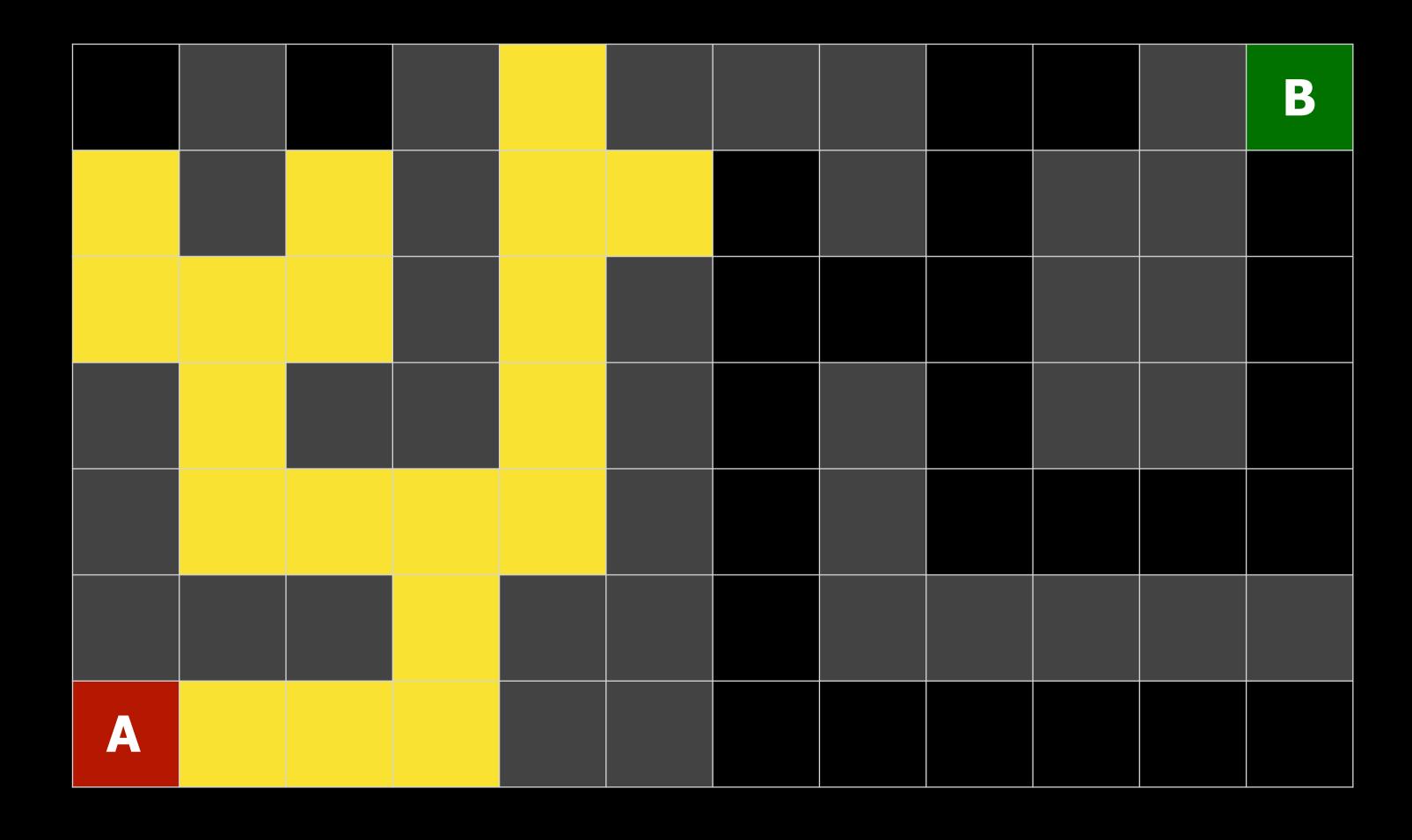


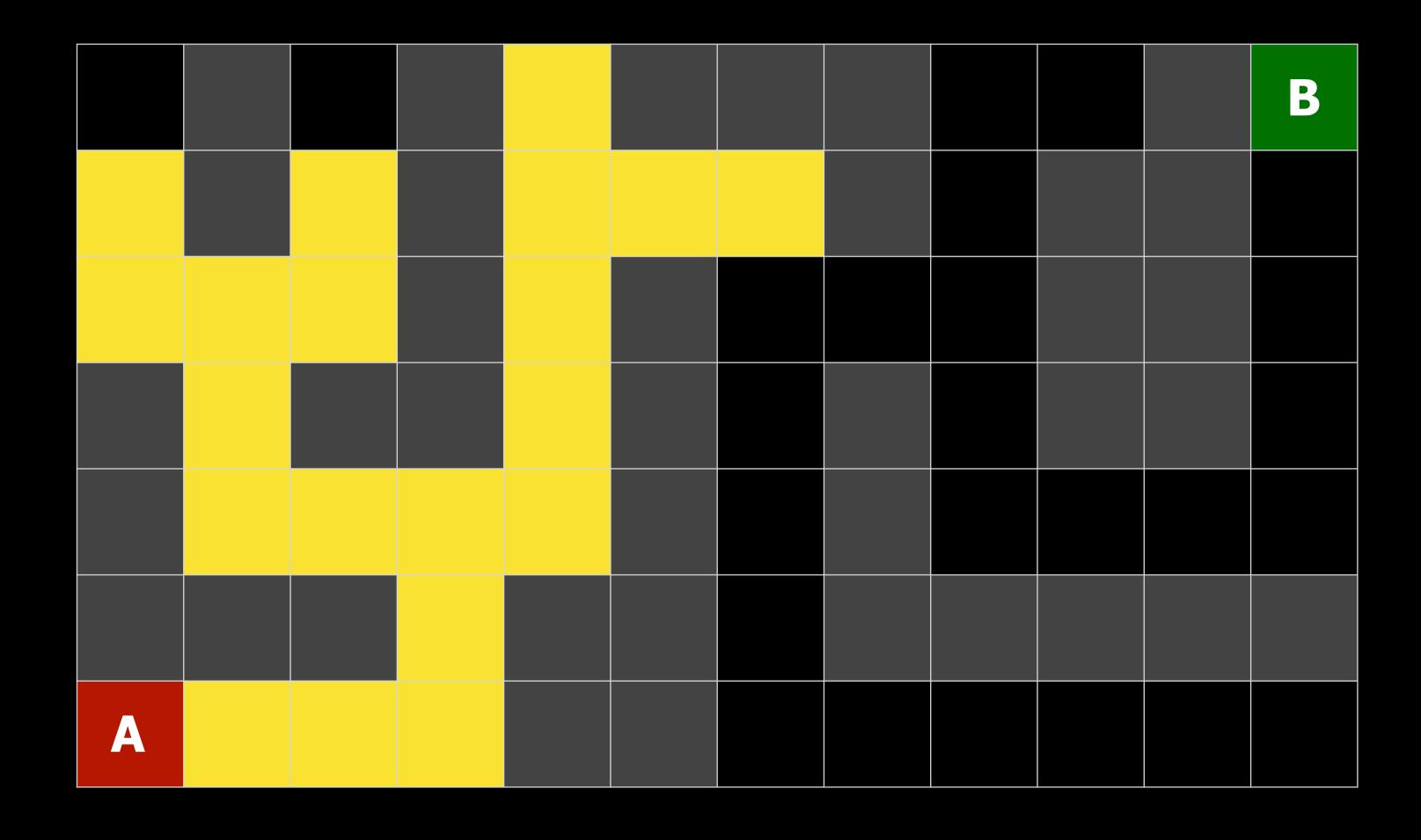


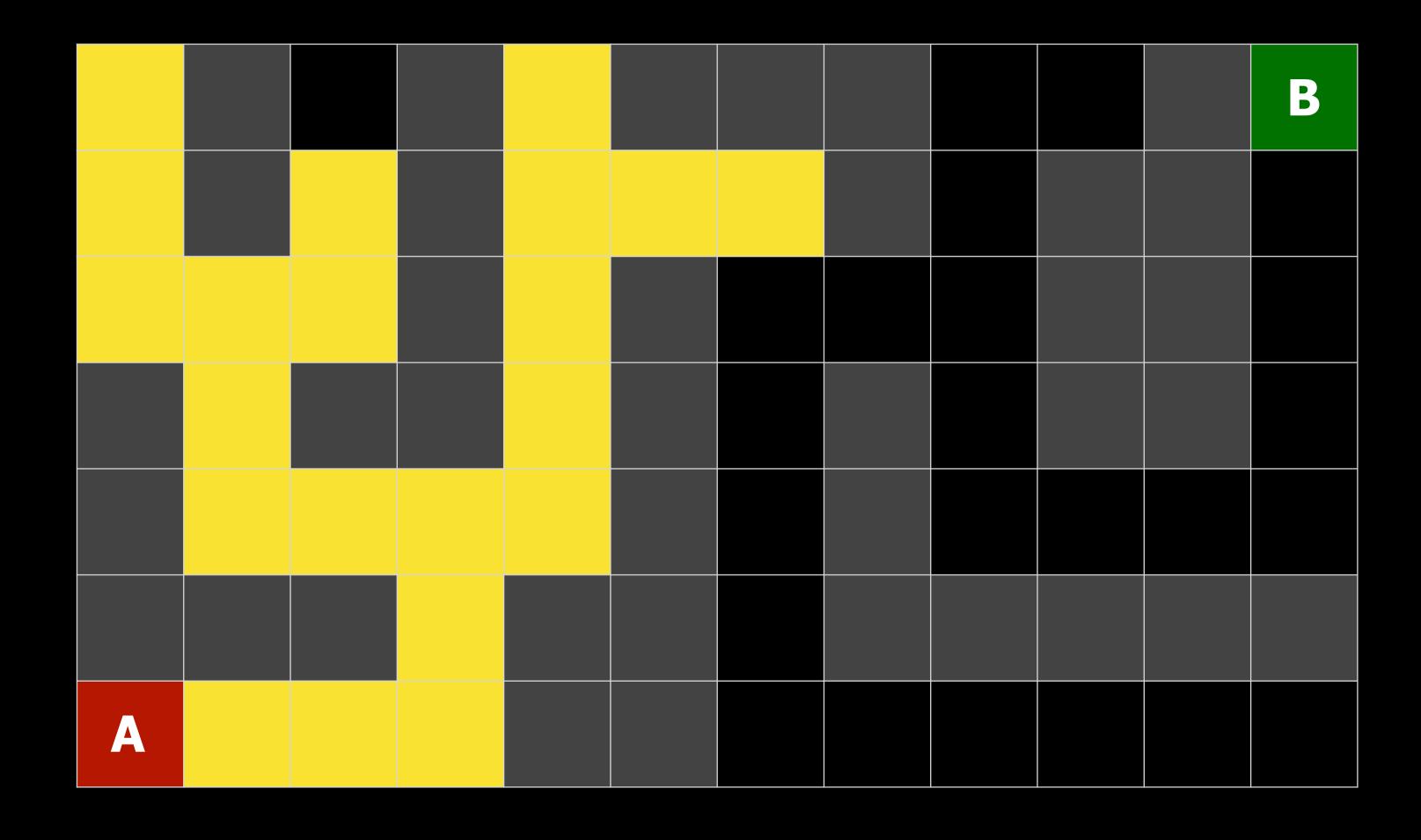


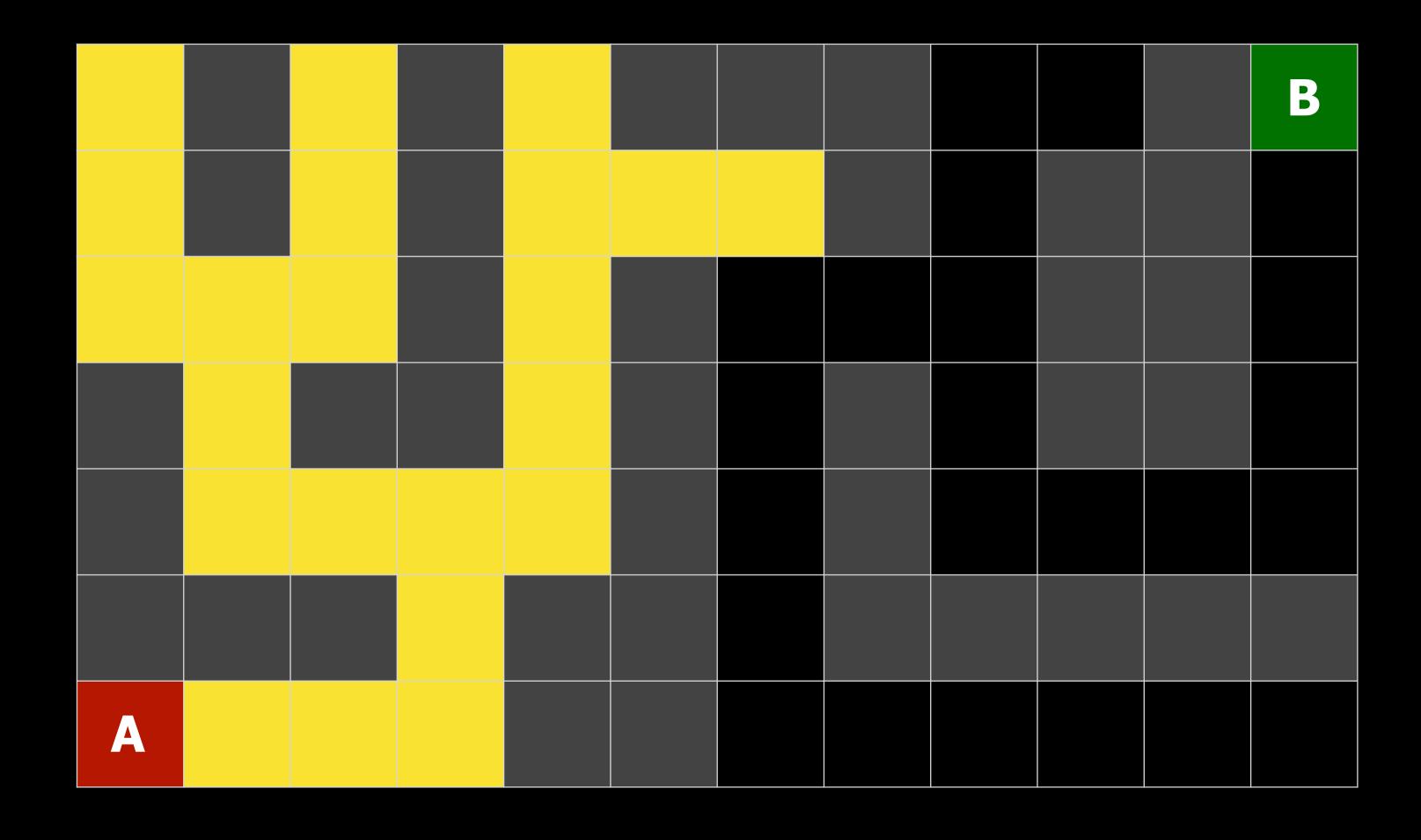


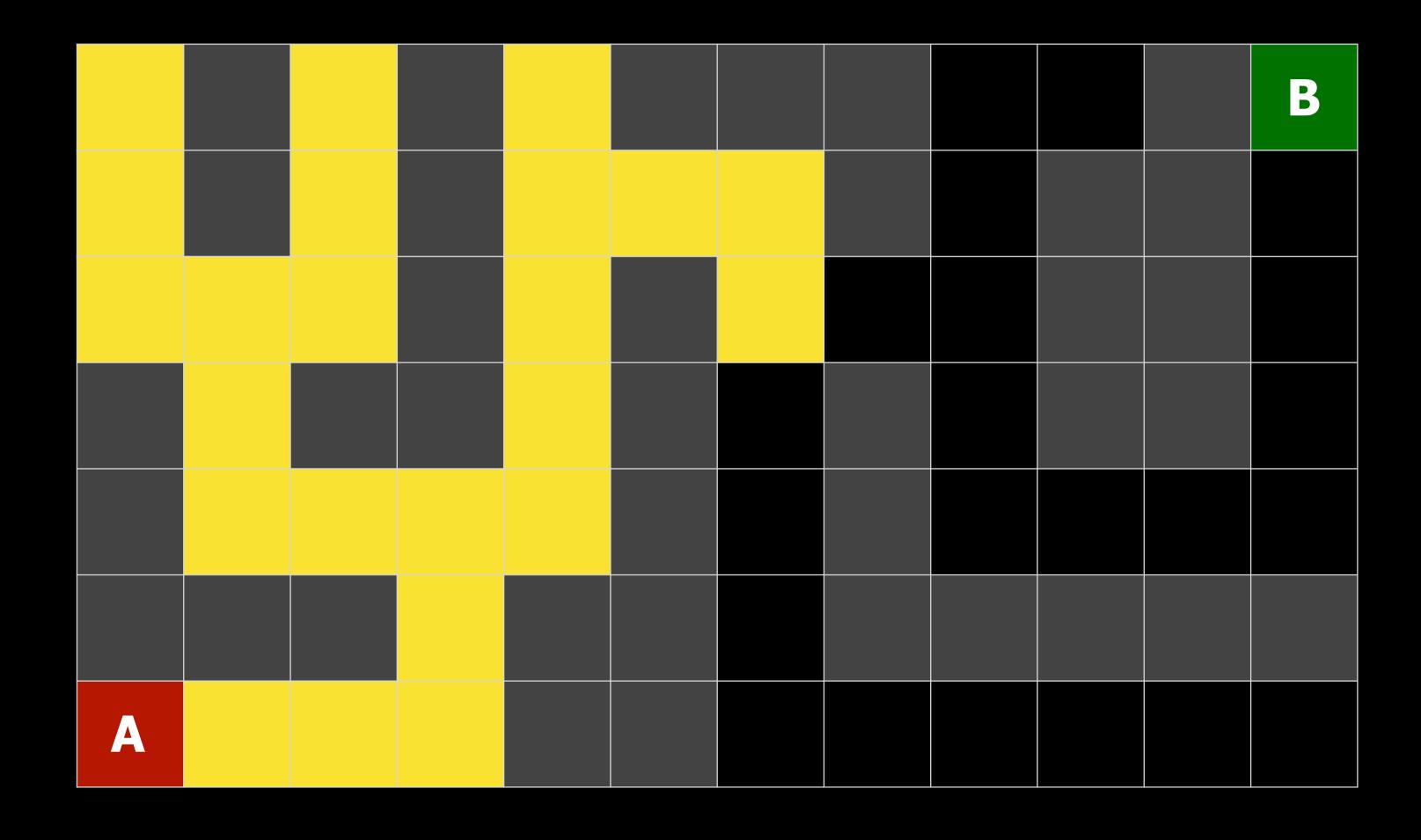


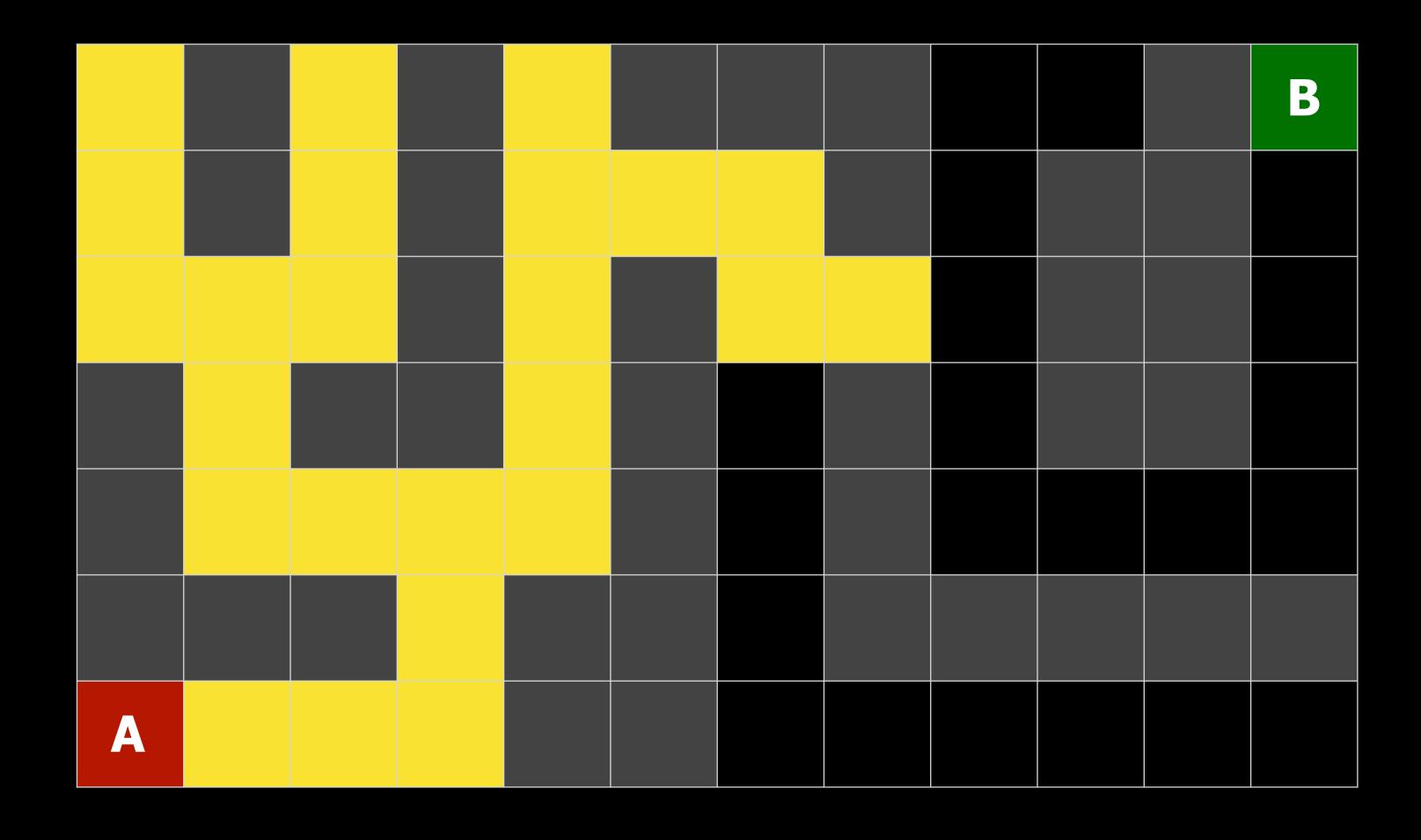


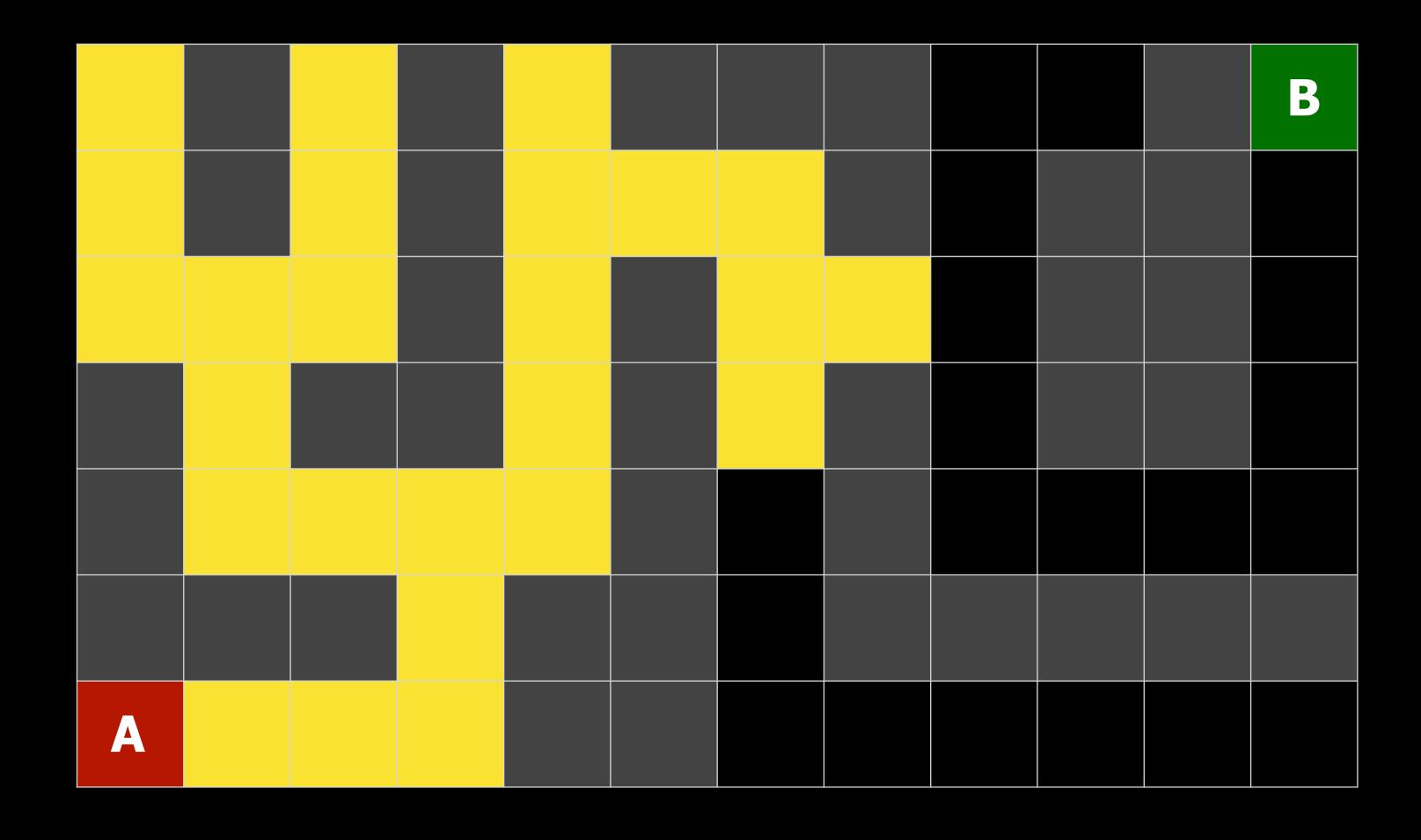


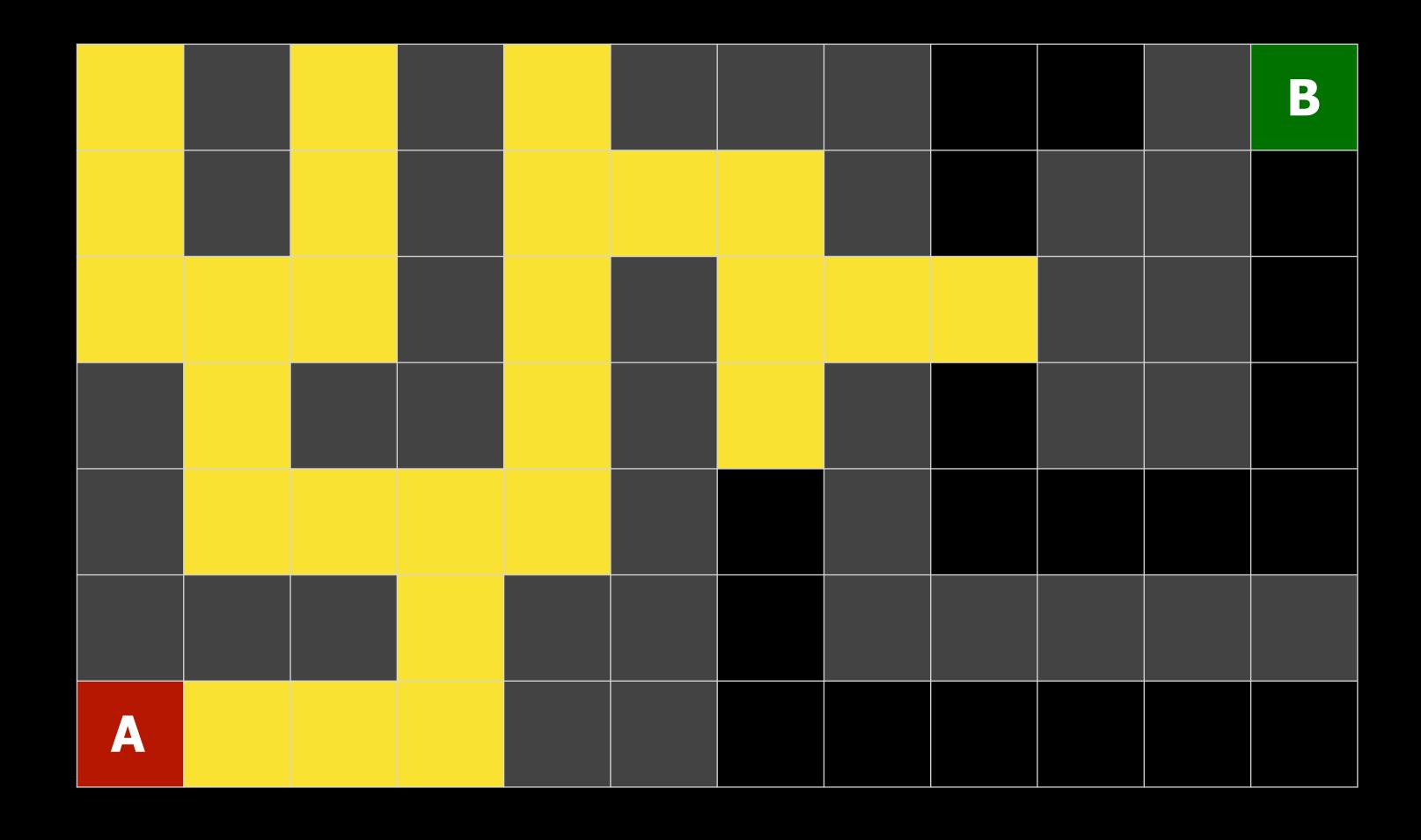


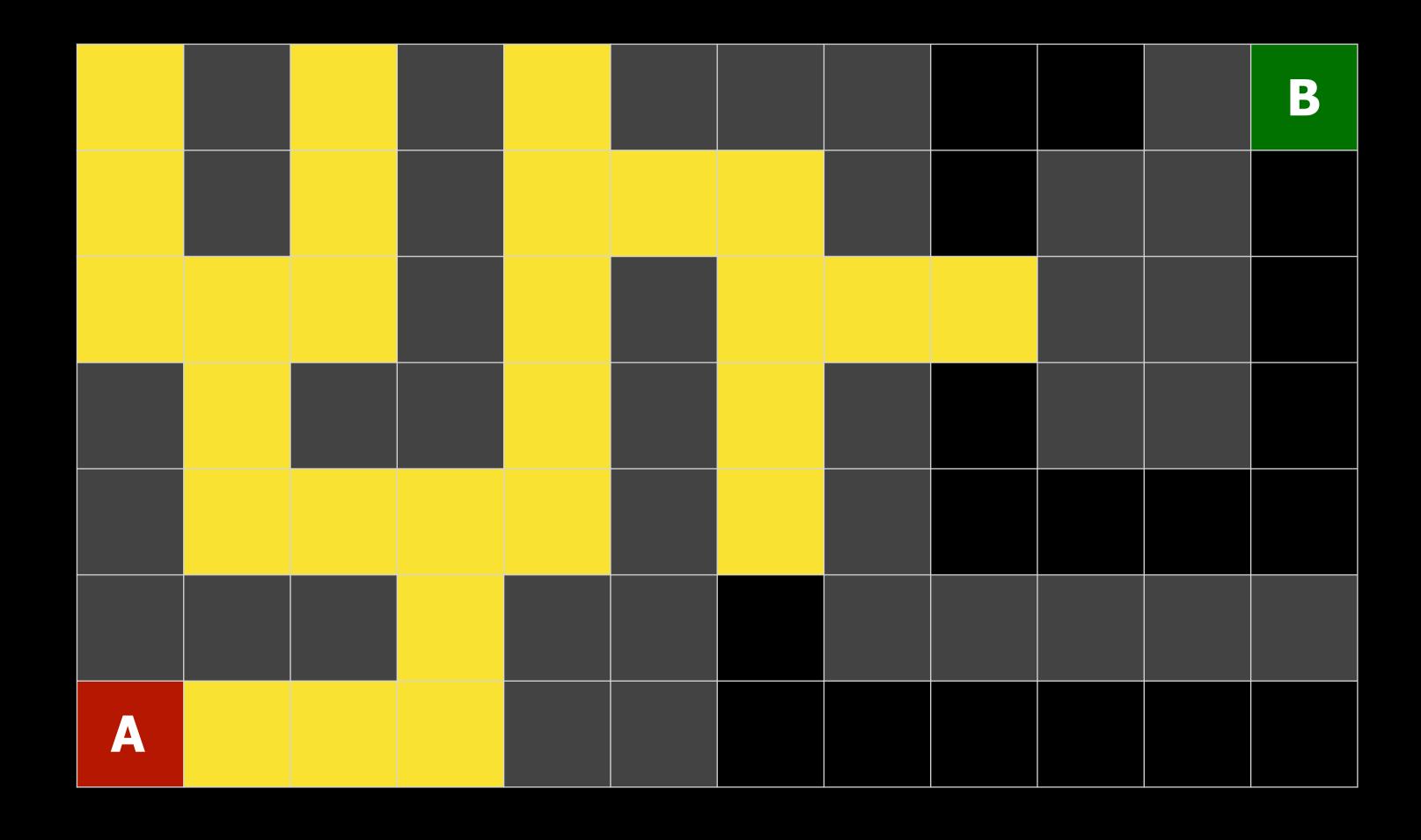


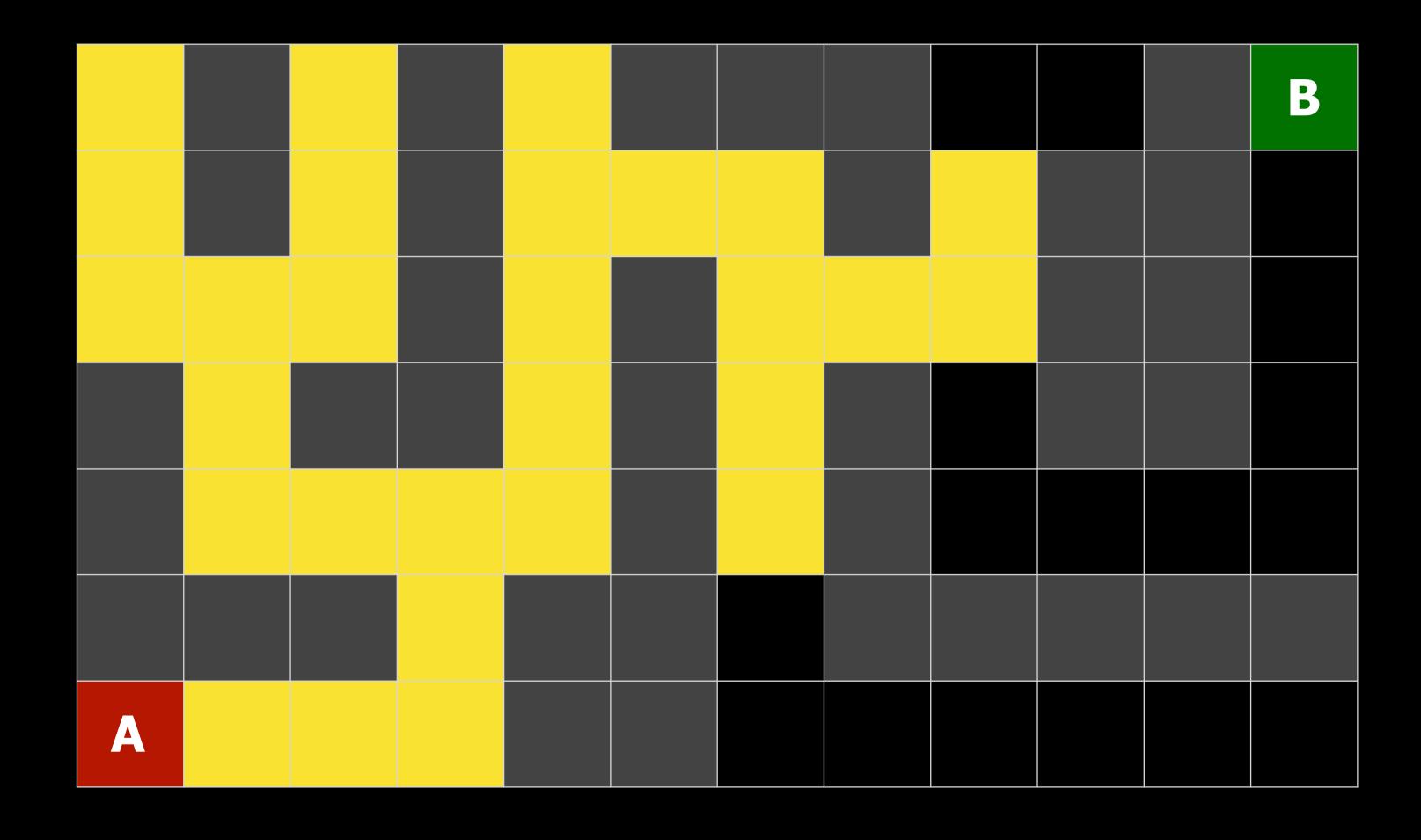


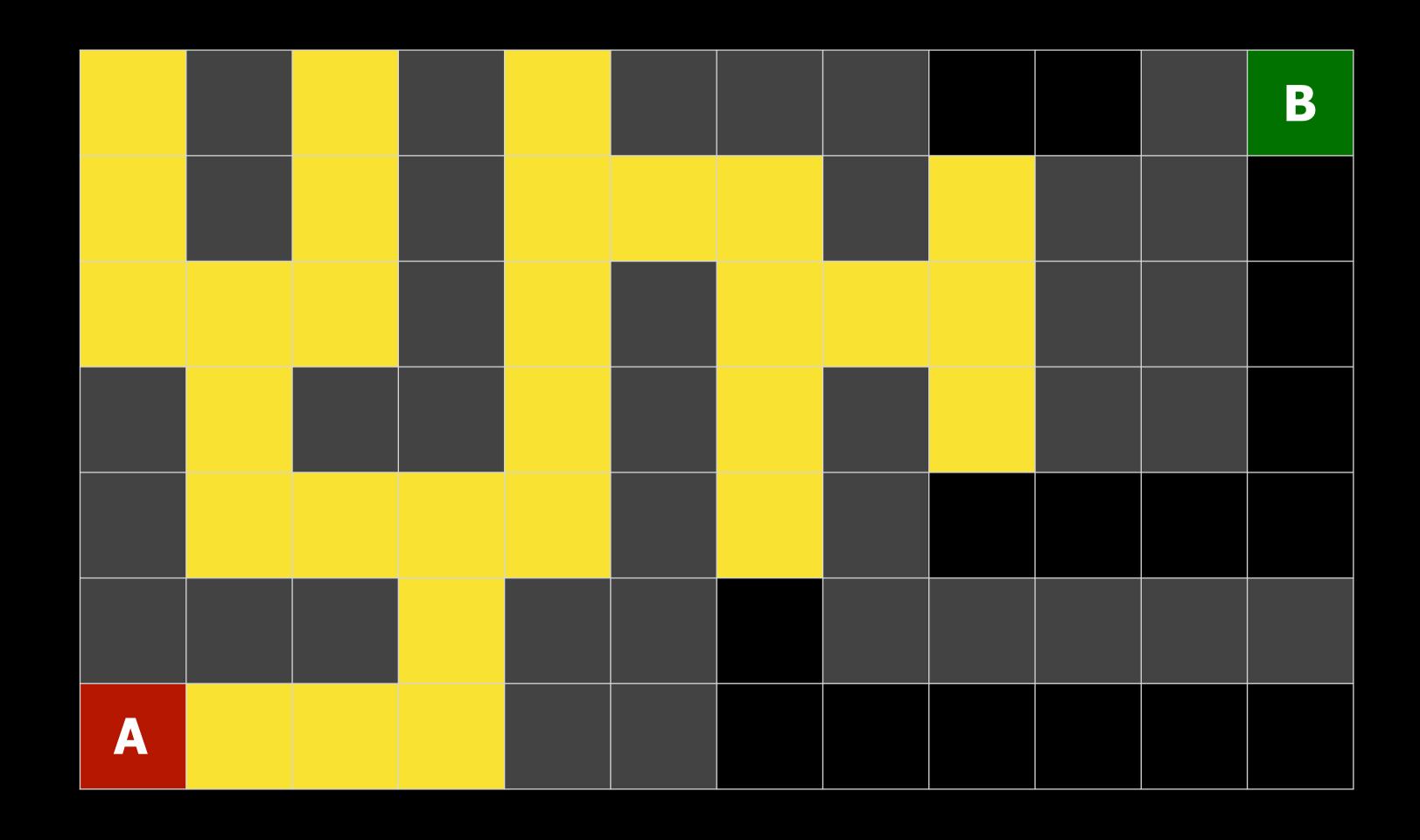


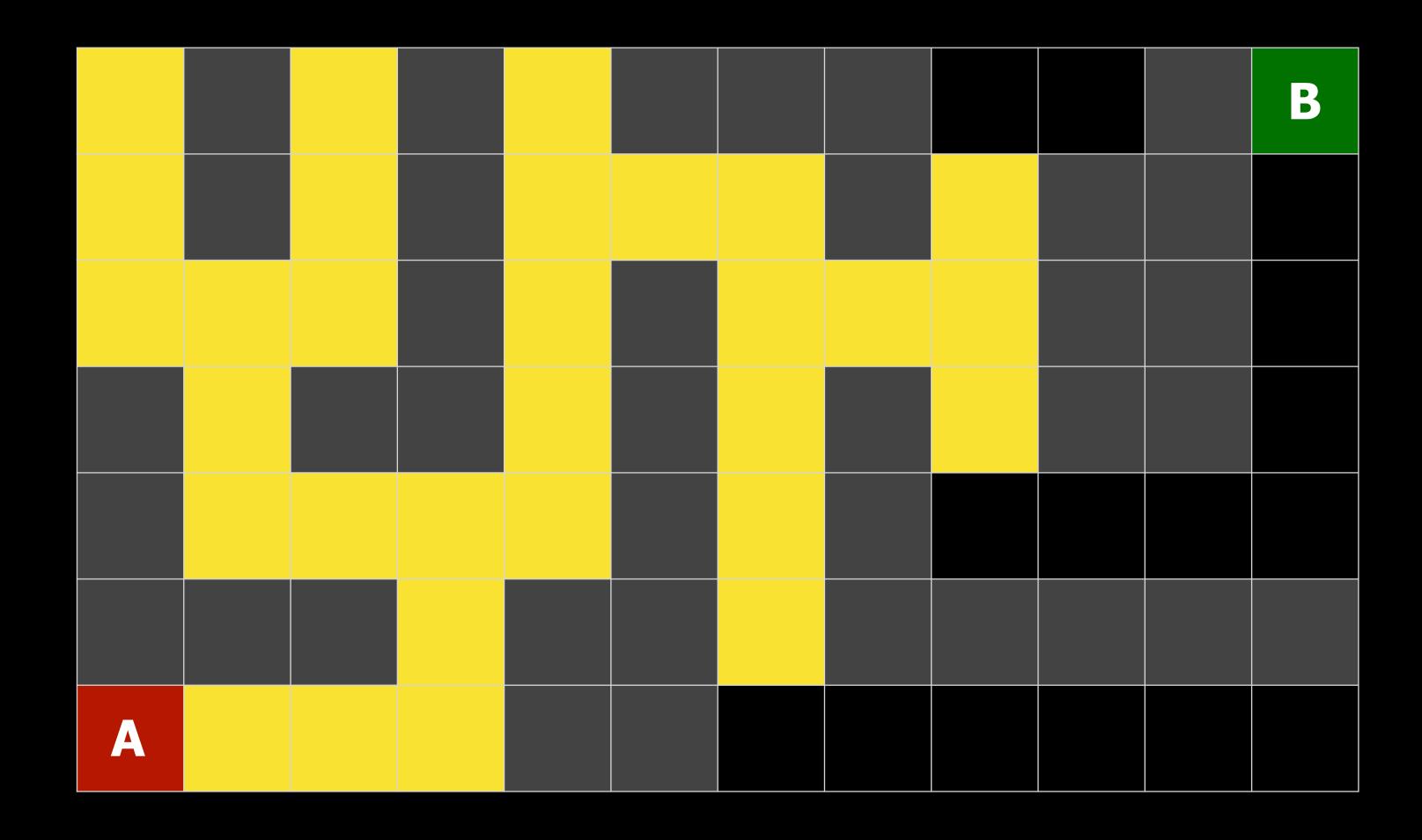


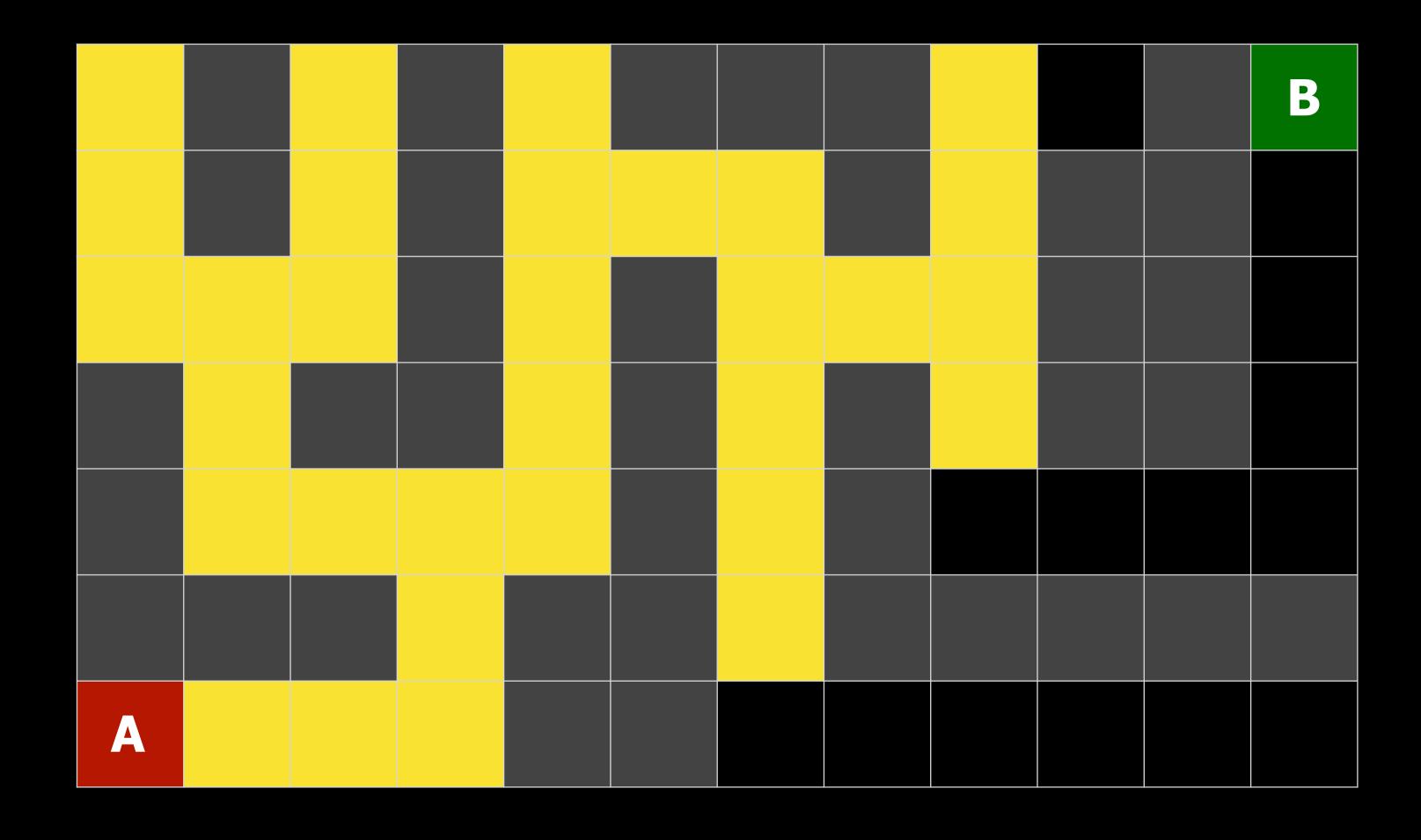


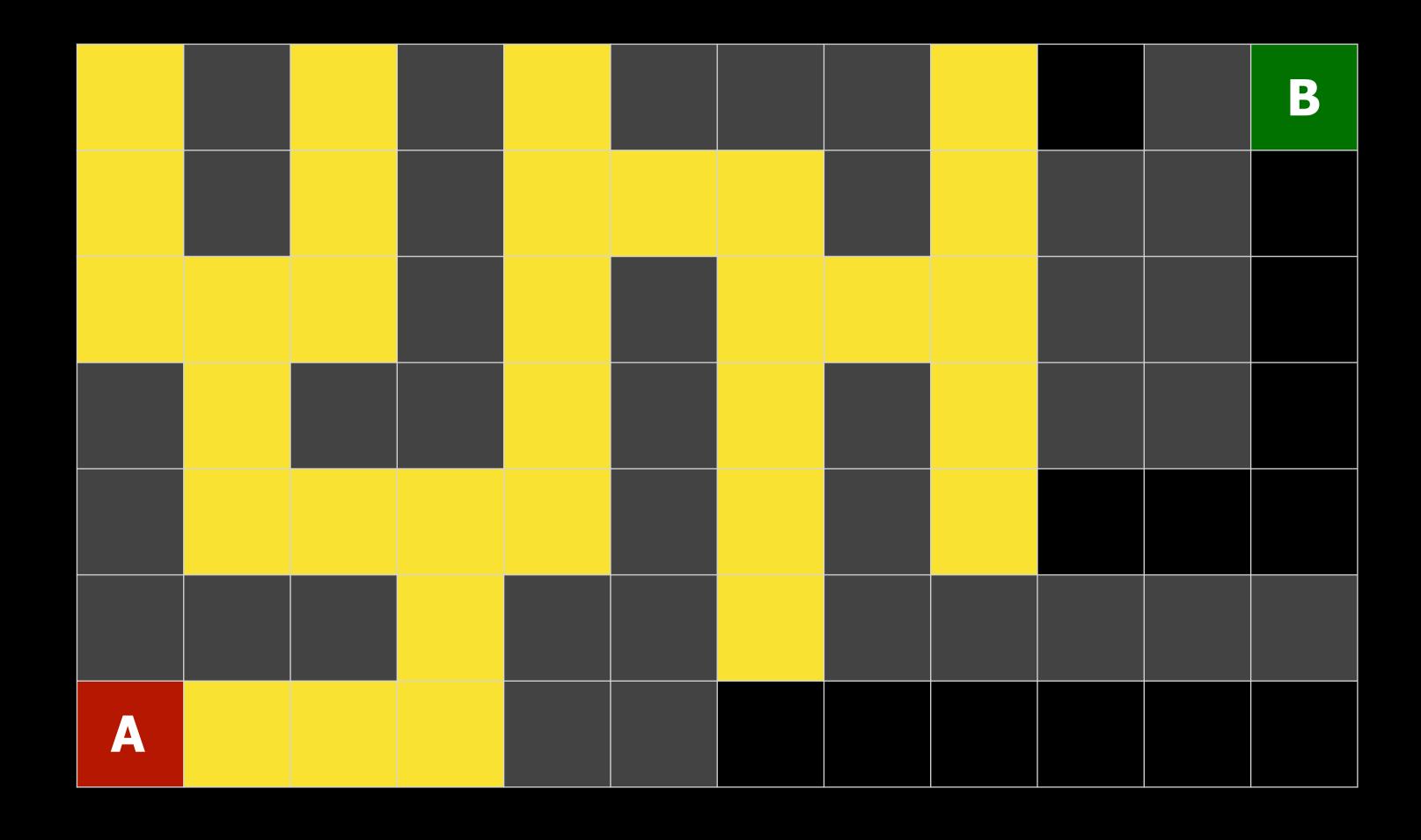


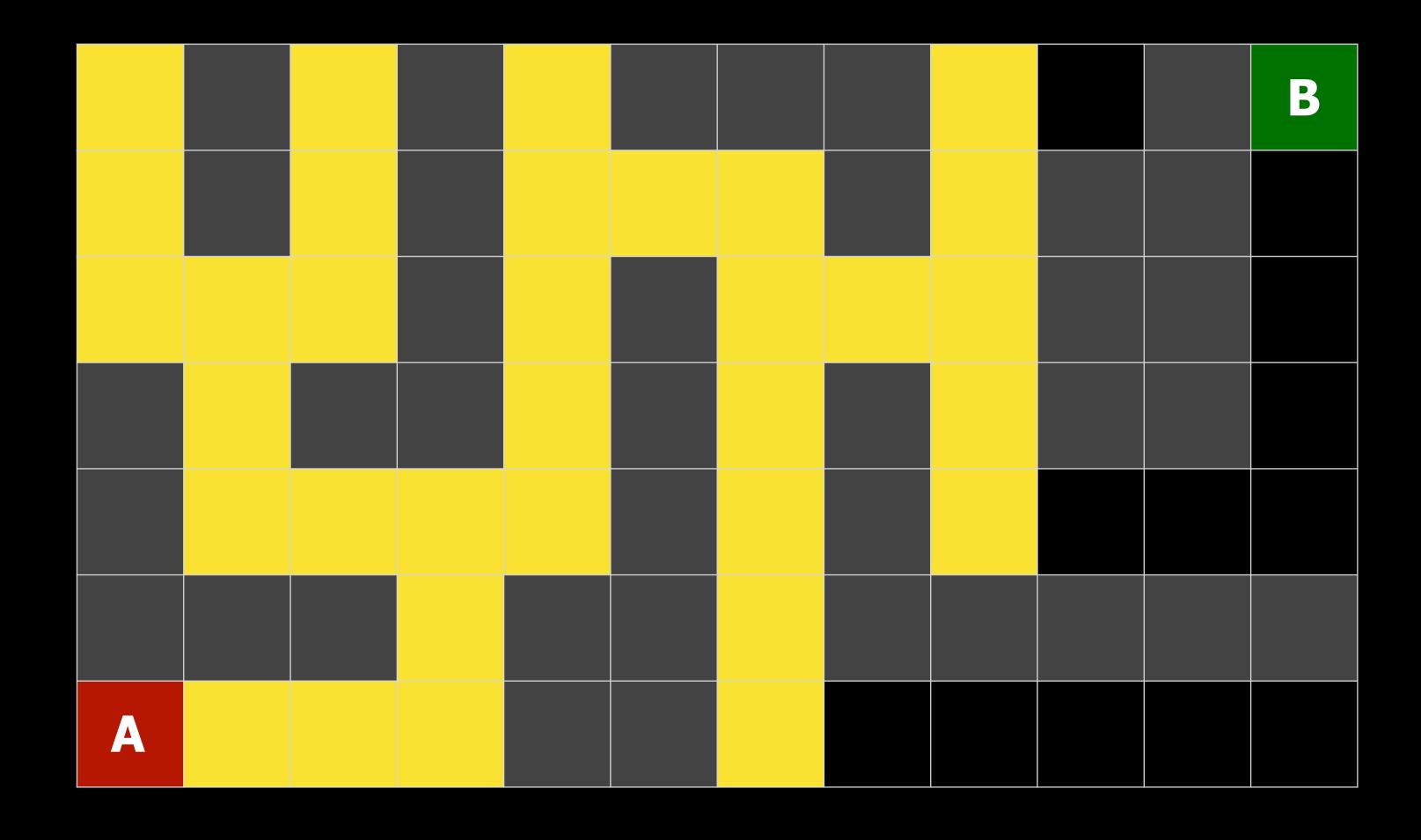


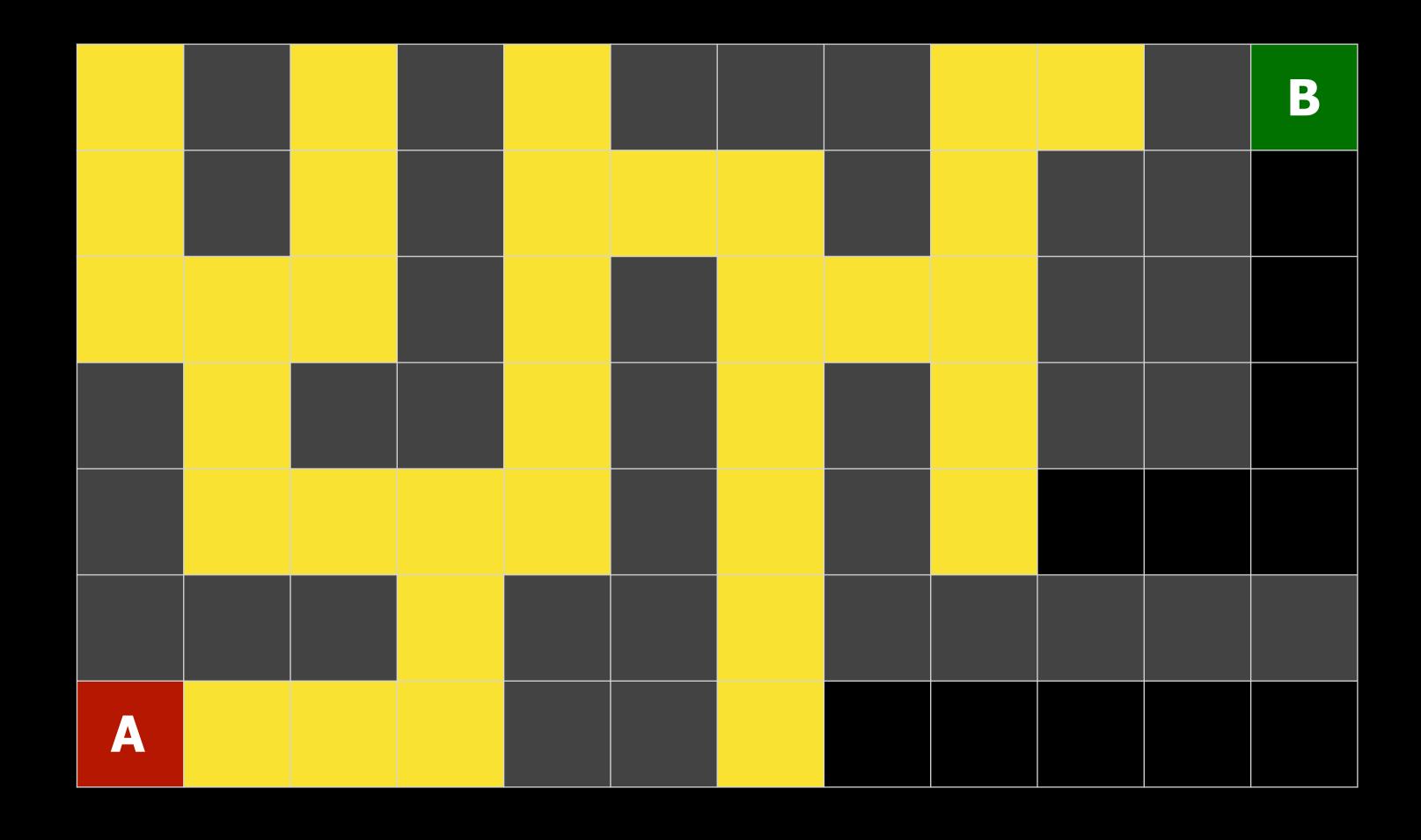


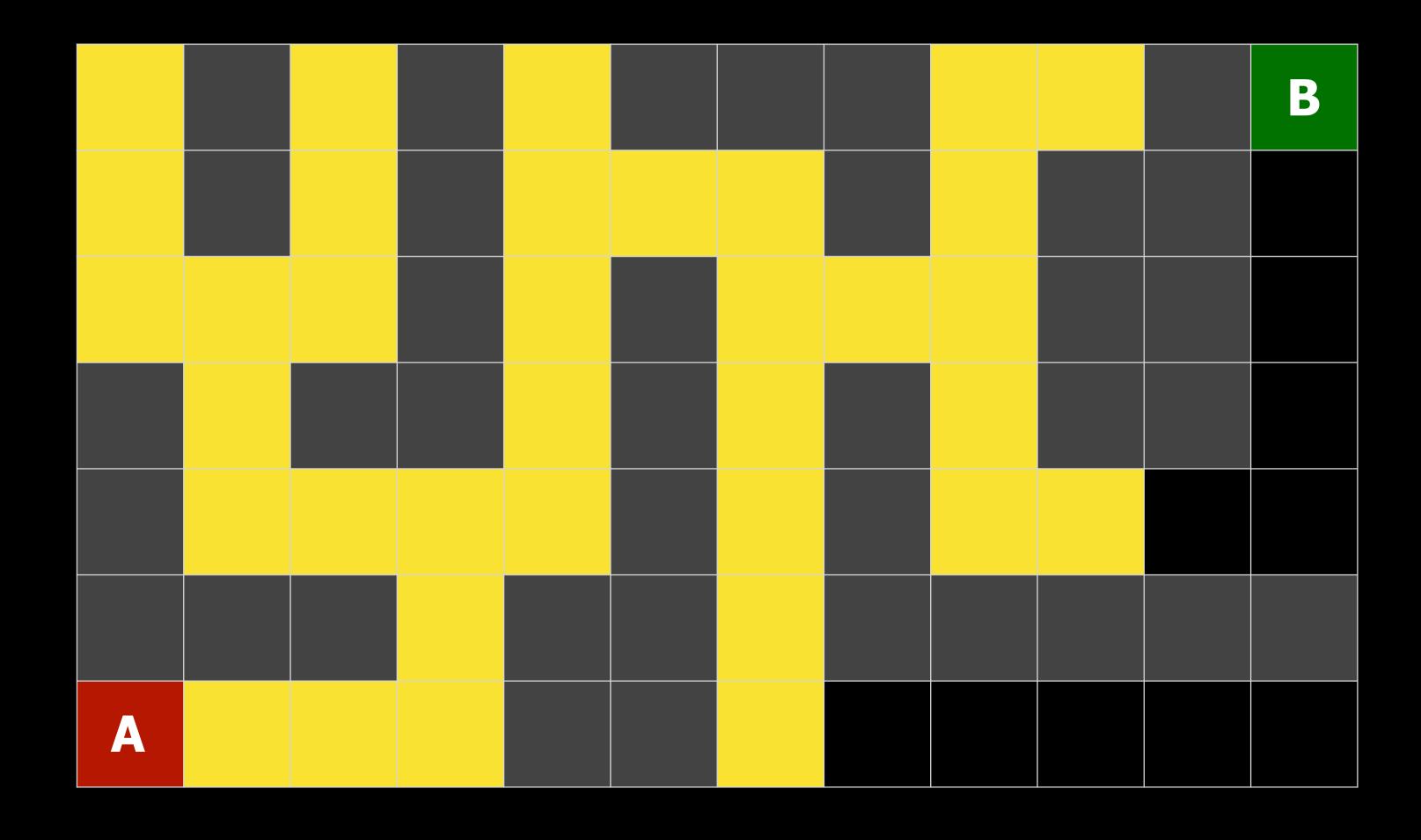


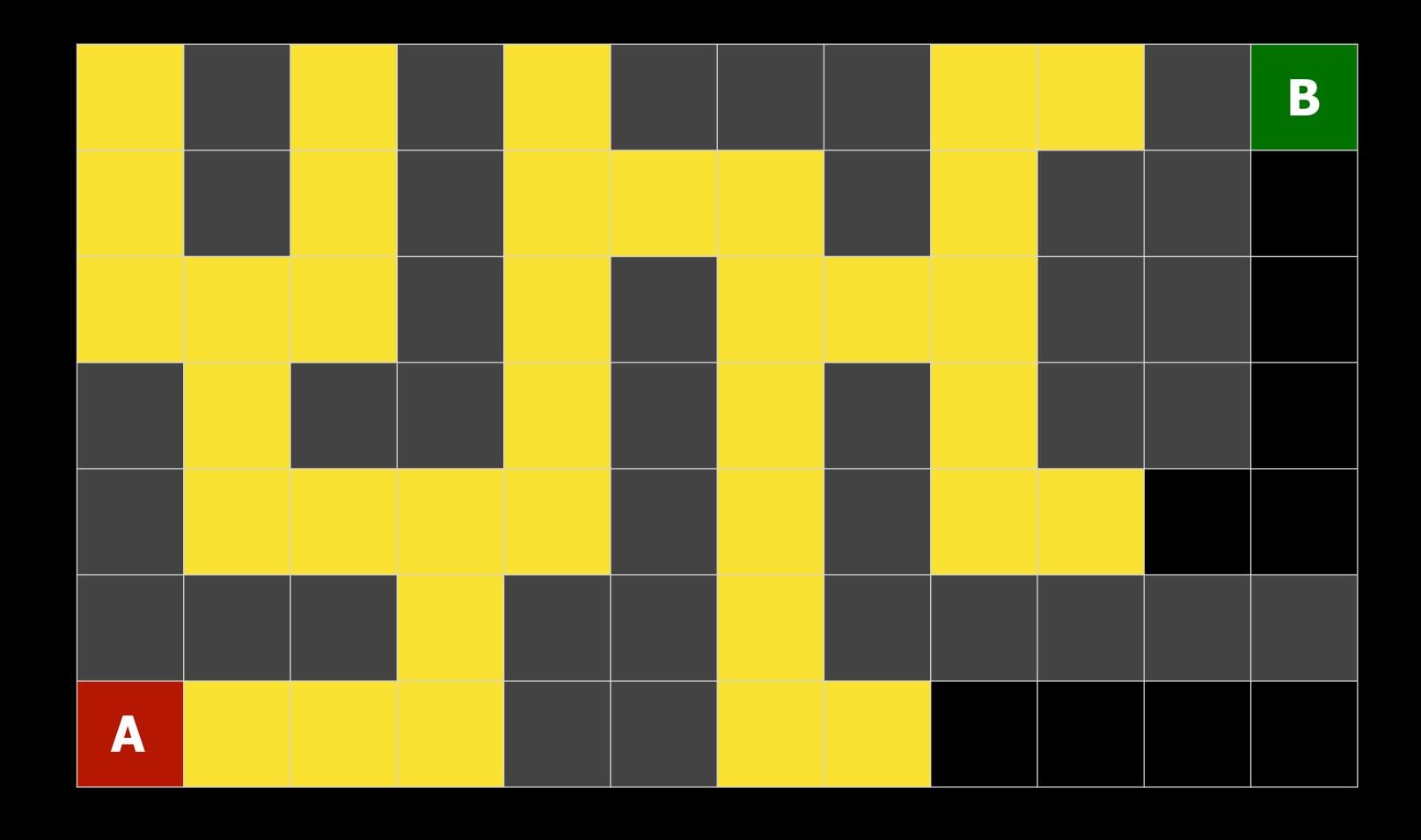


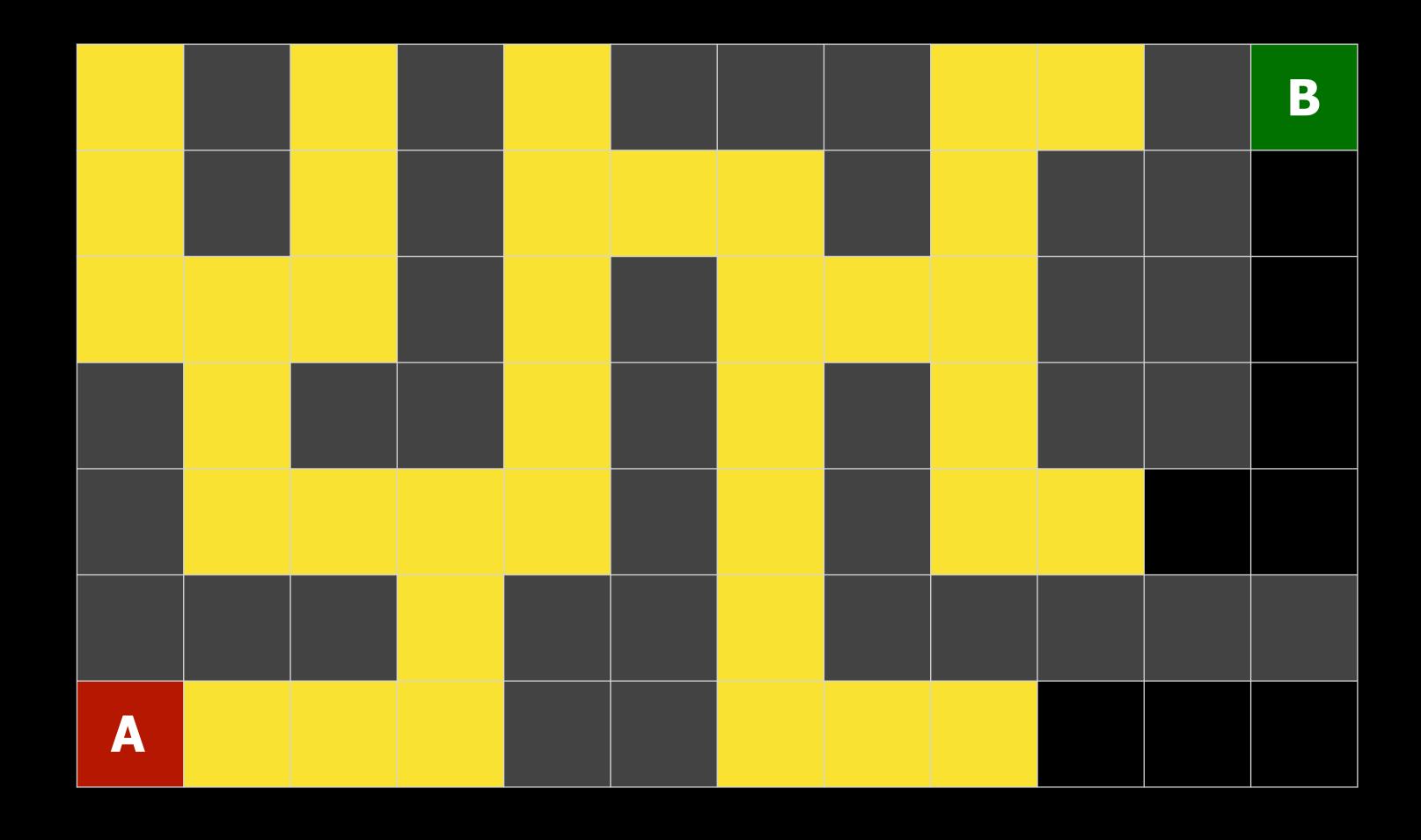


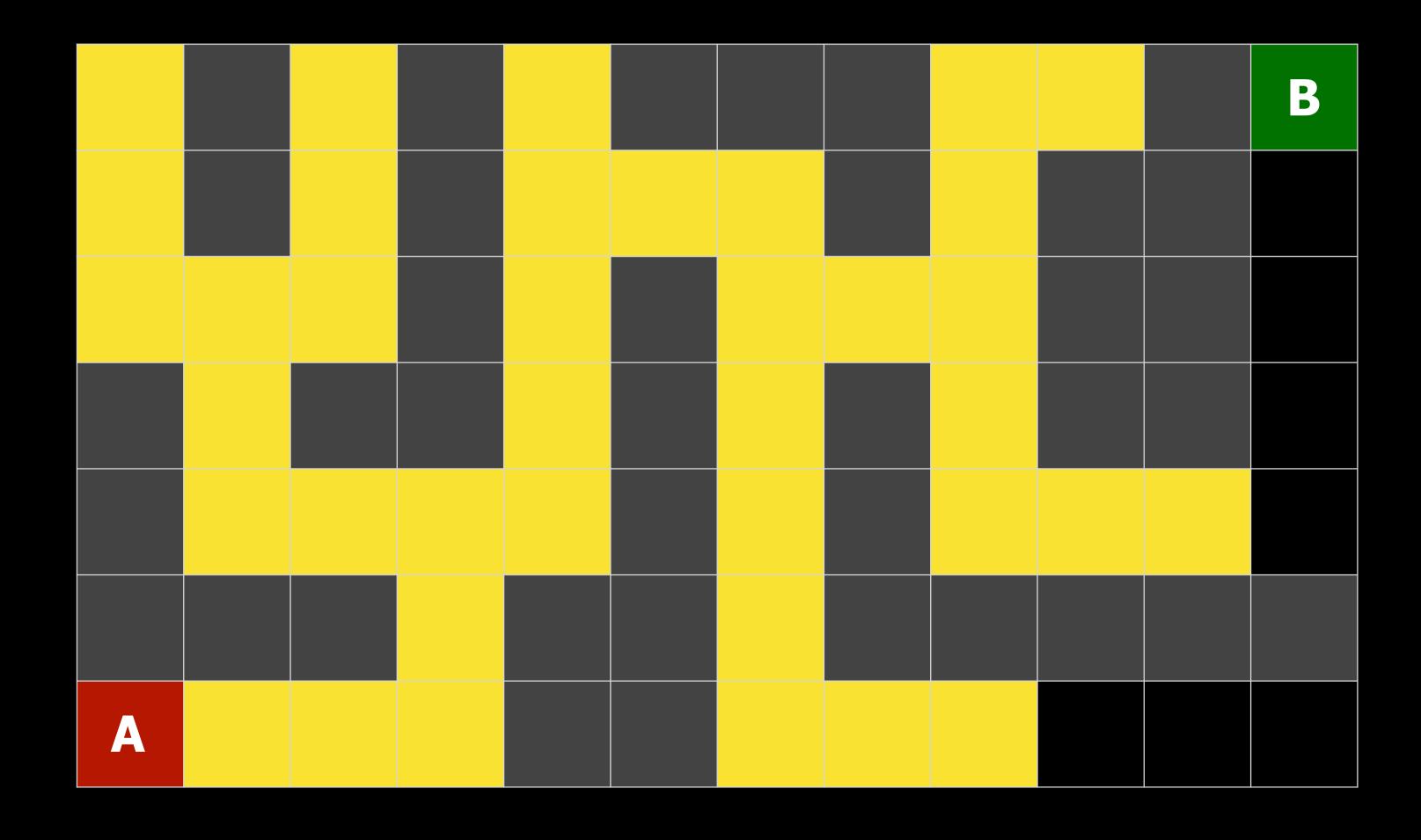


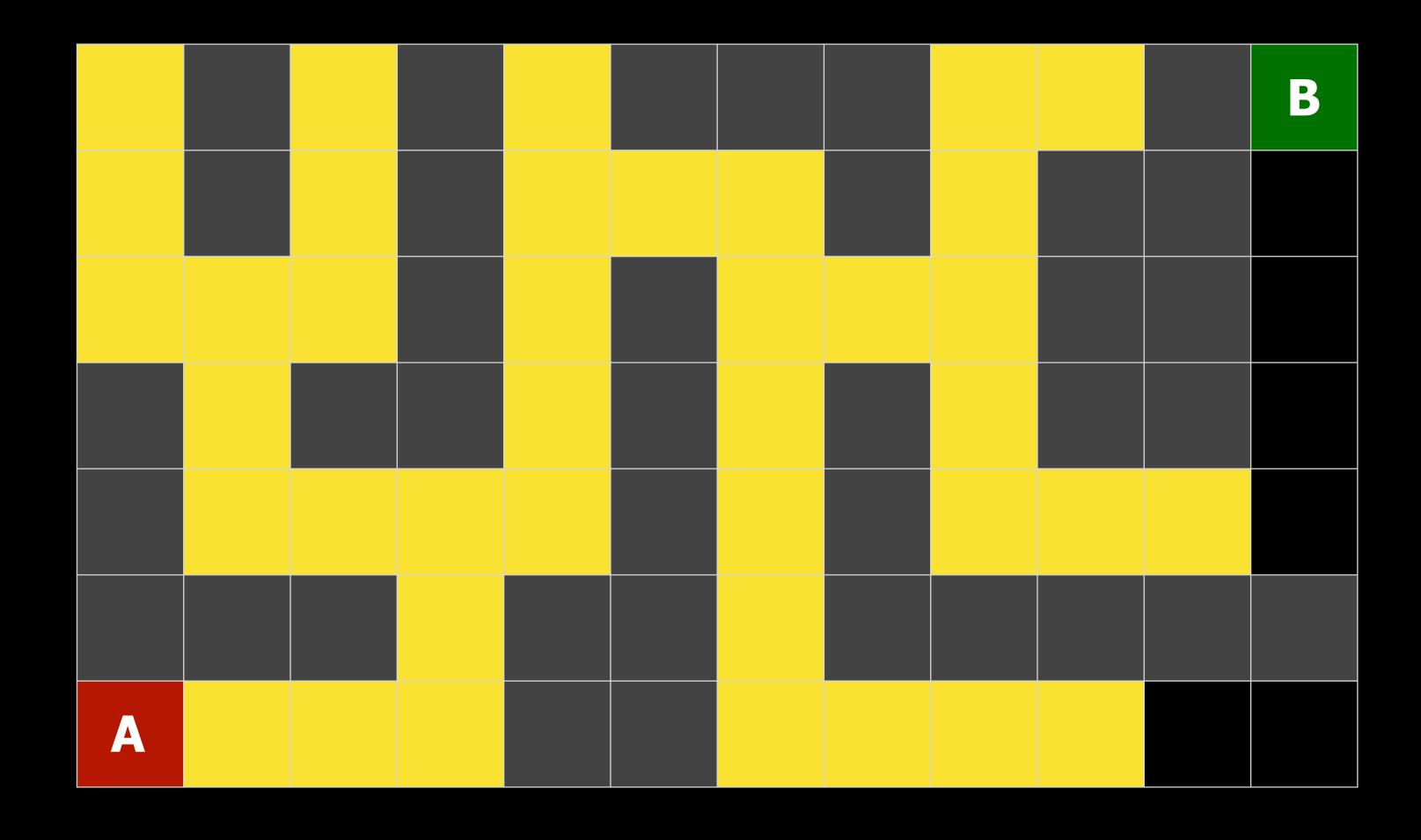


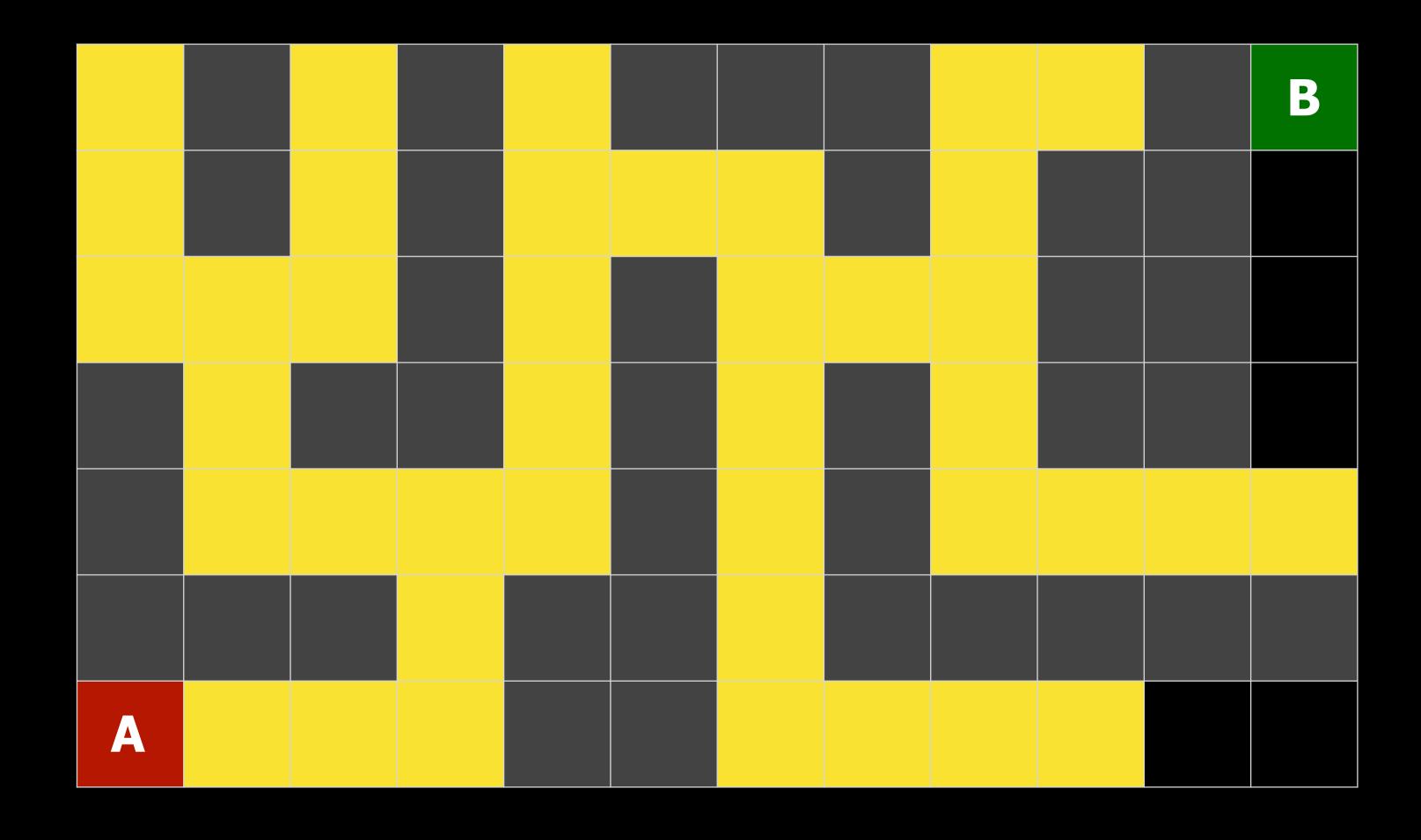


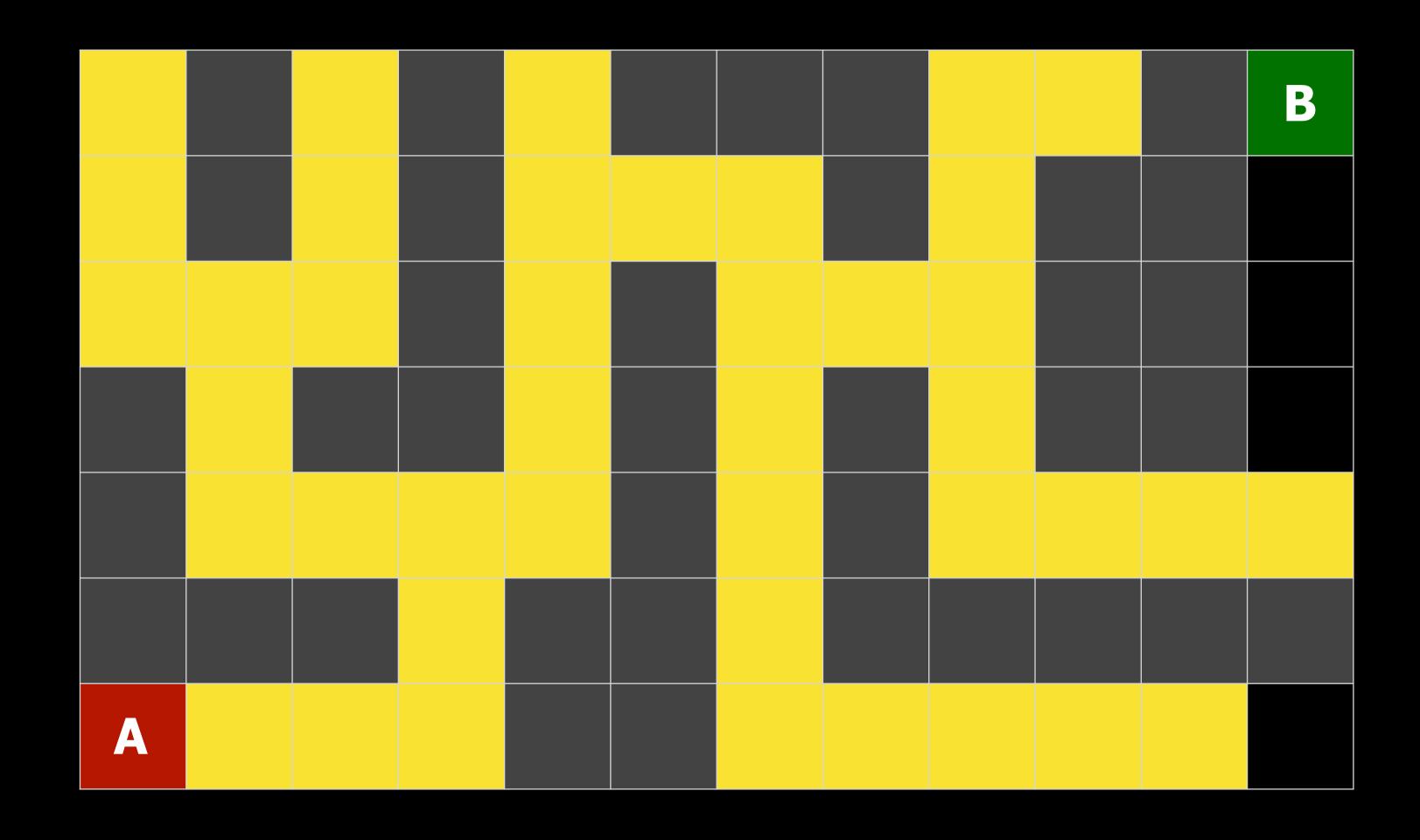


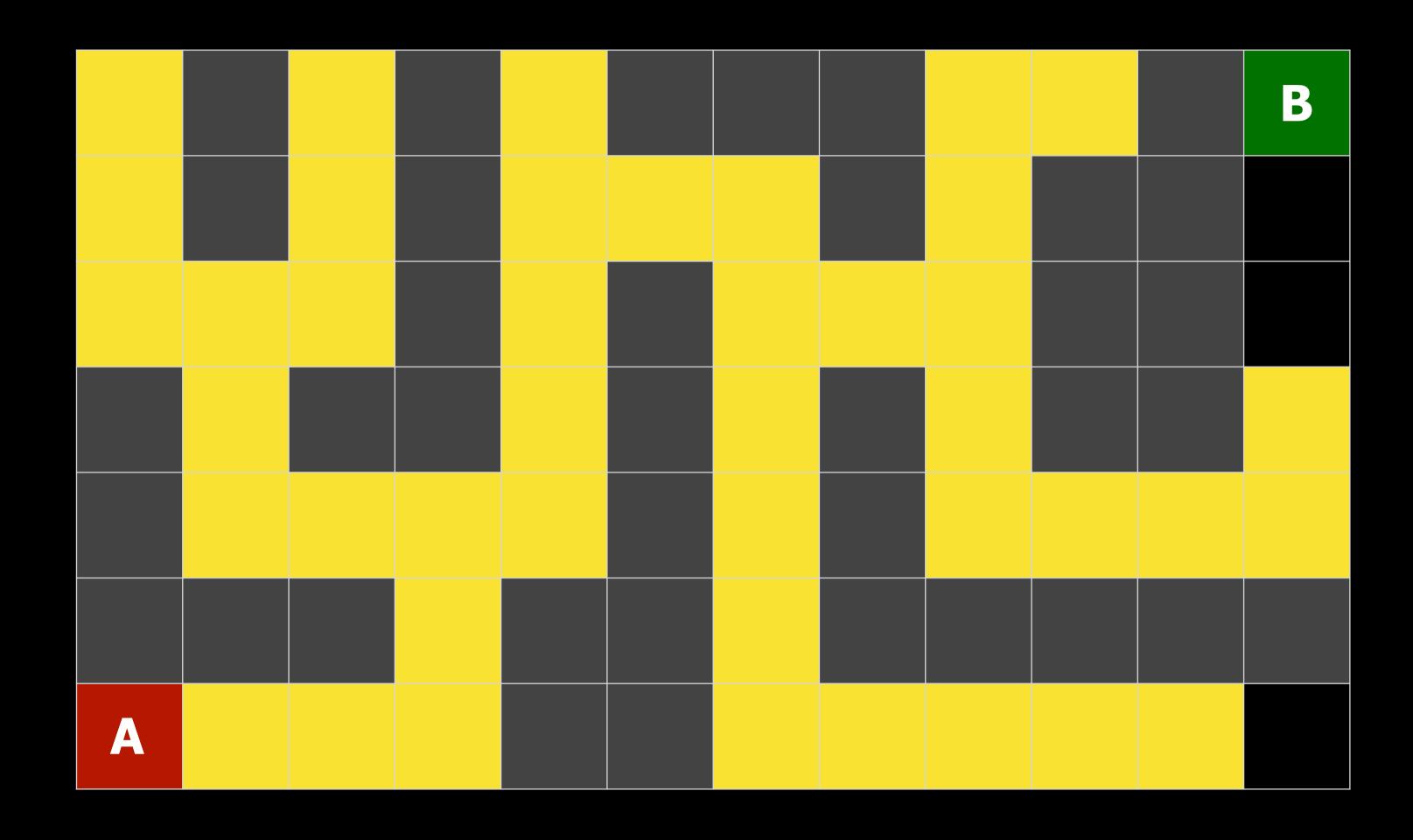


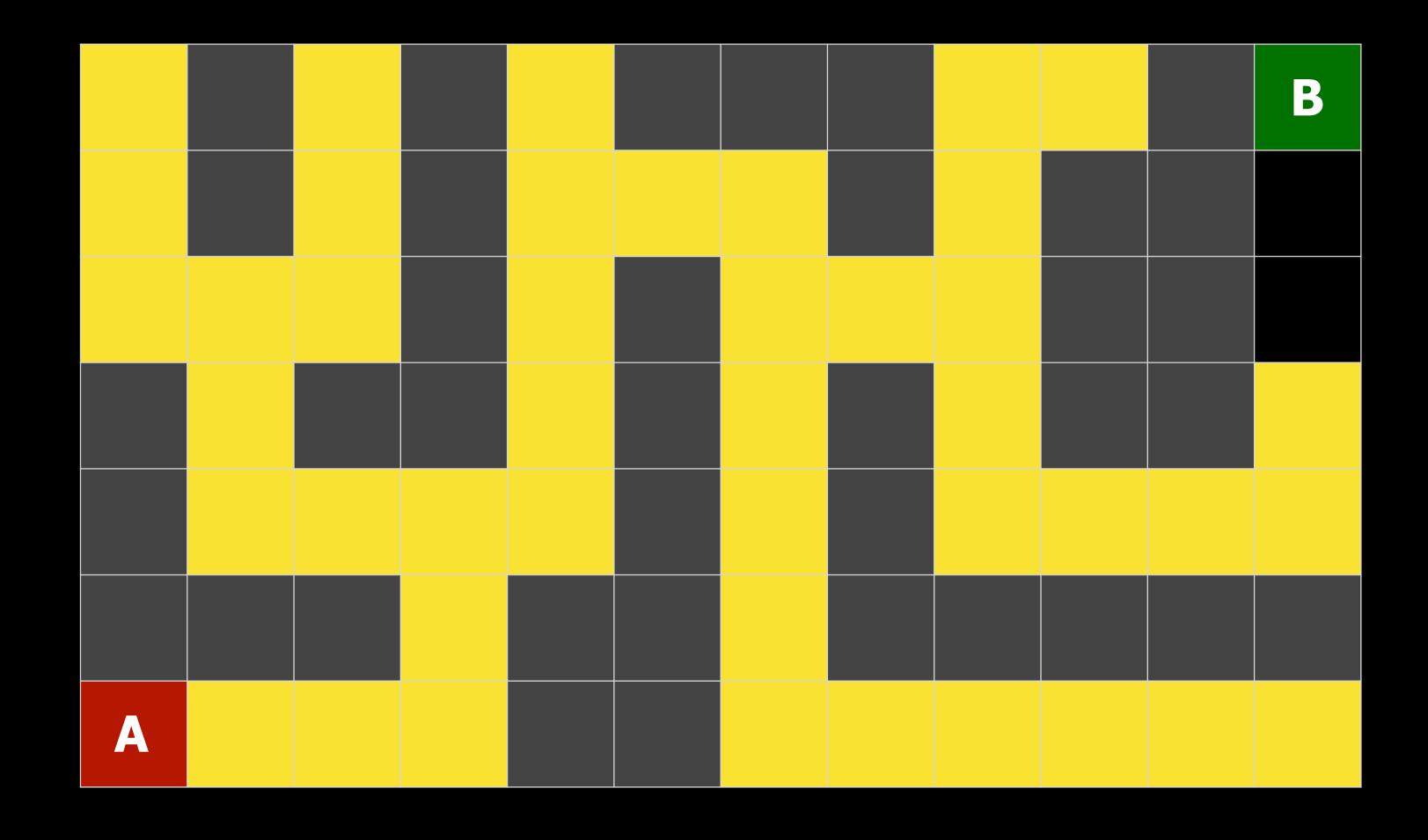


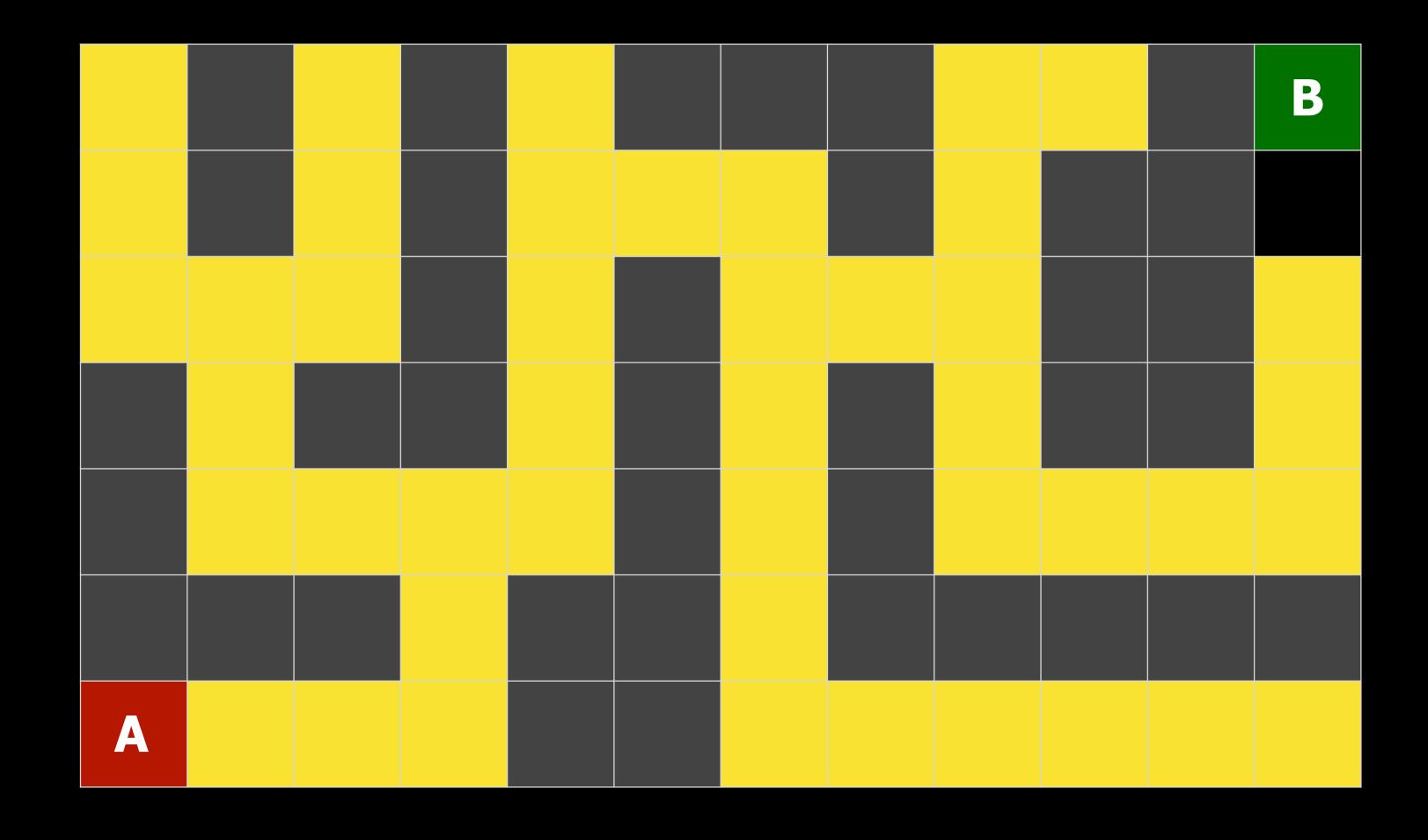


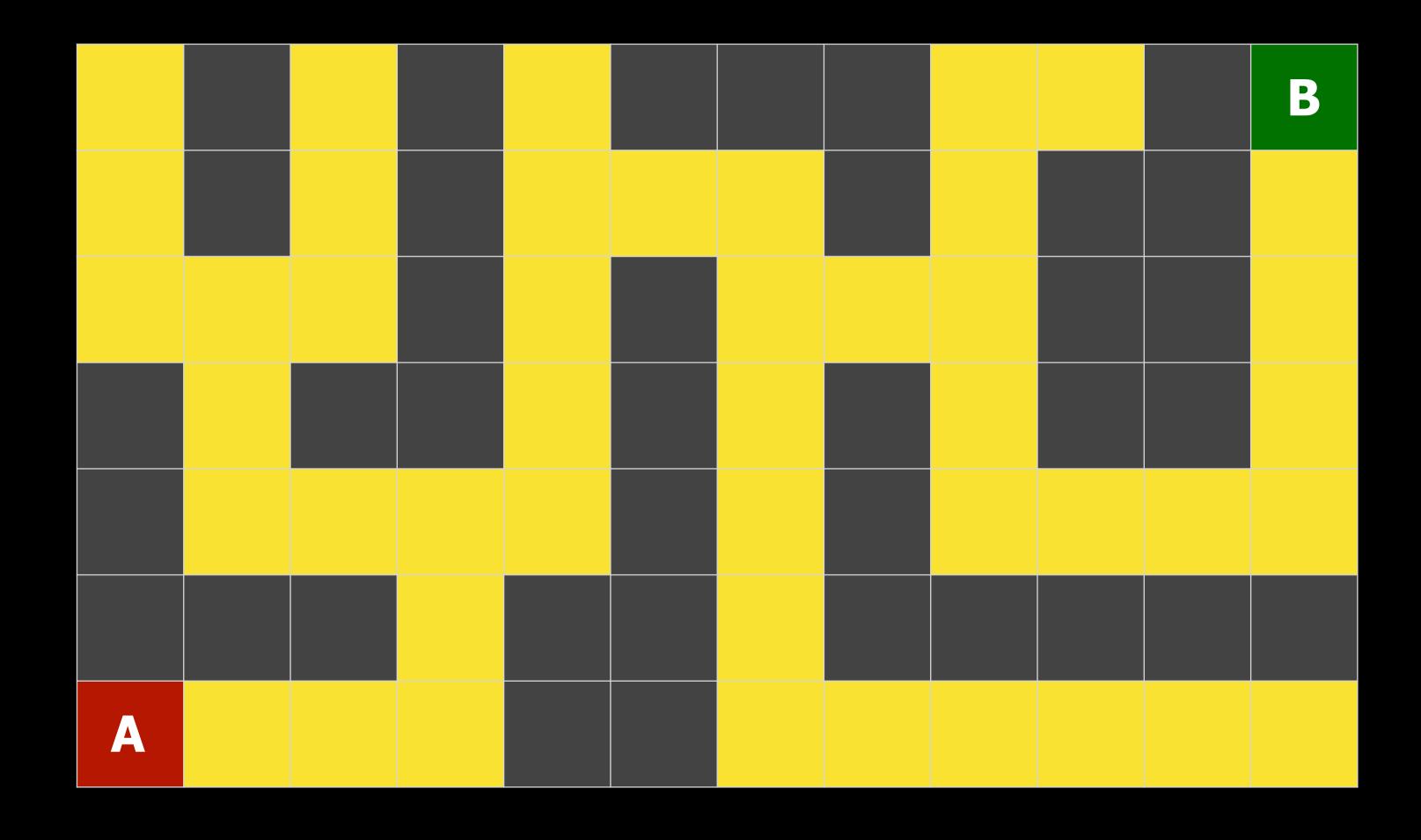


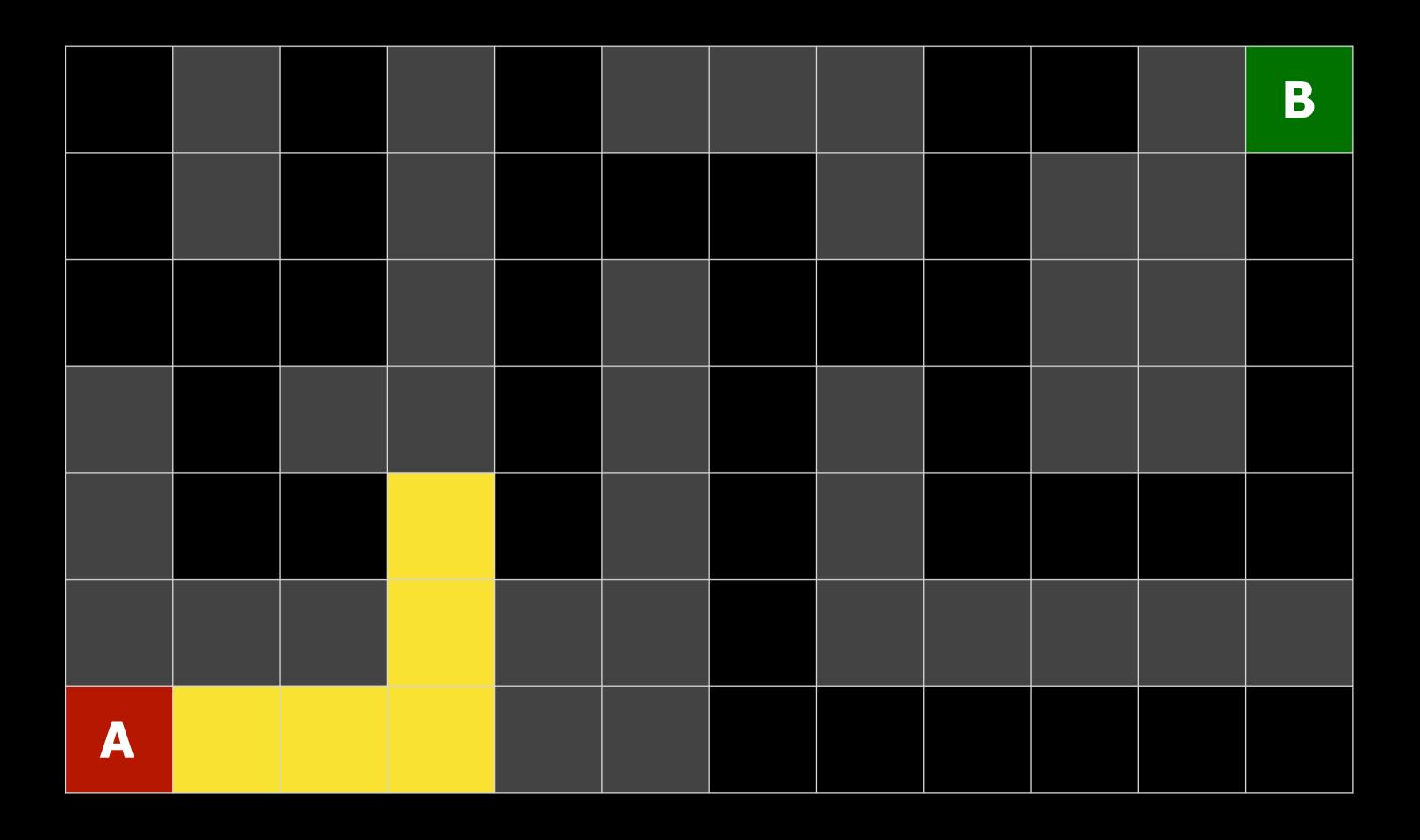












uninformed search

search strategy that uses no problemspecific knowledge

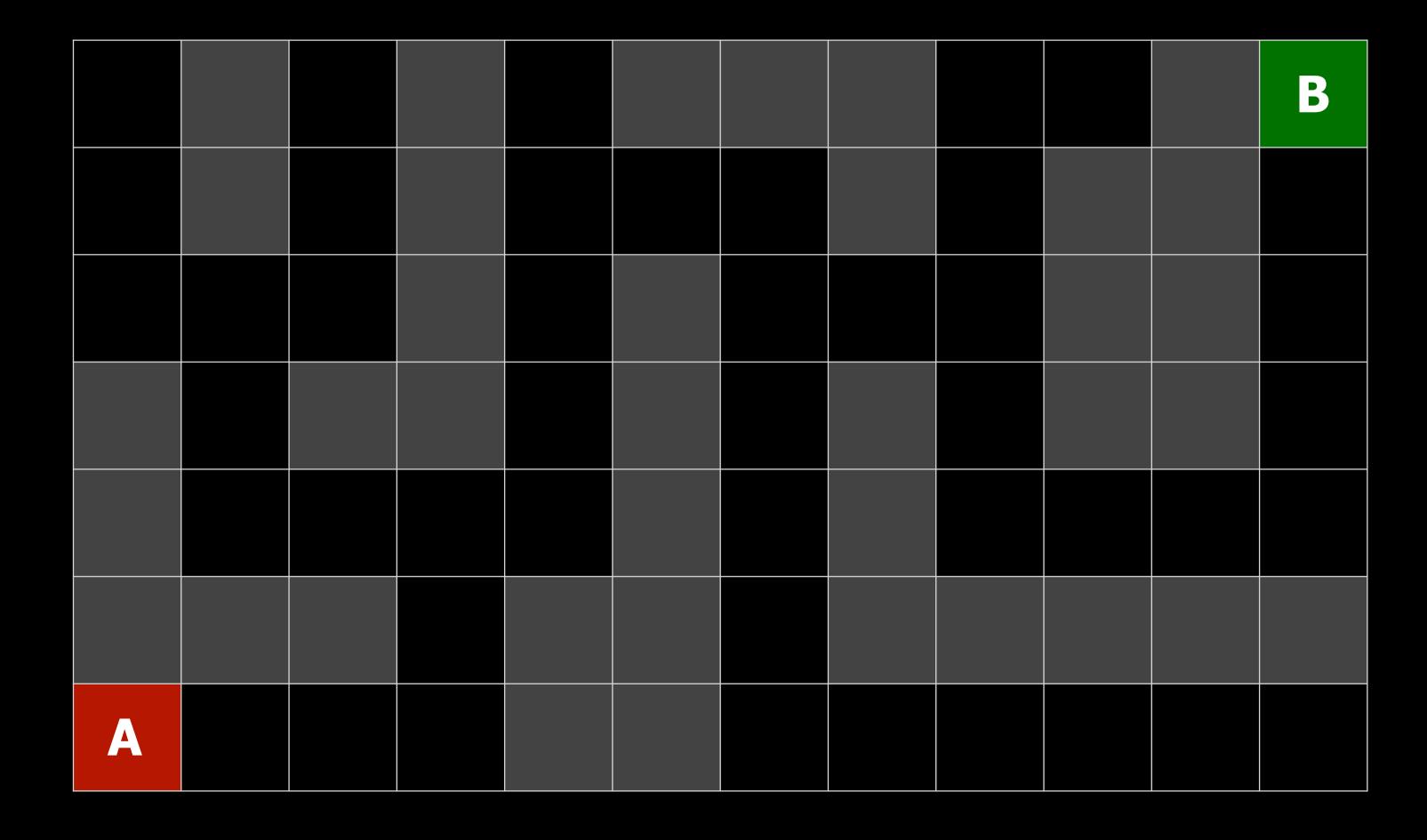
informed search

search strategy that uses problem-specific knowledge to find solutions more efficiently

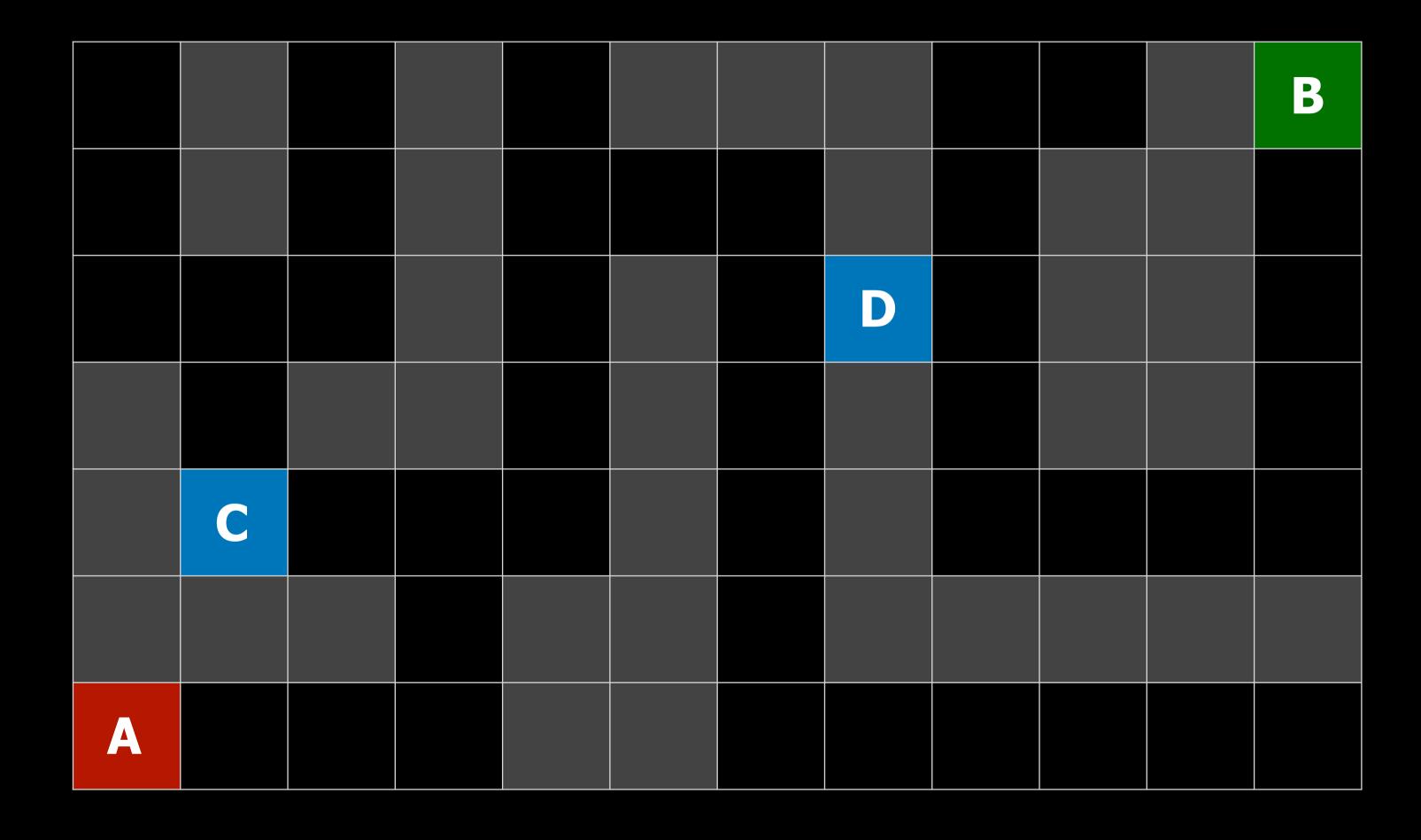
greedy best-first search

search algorithm that expands the node that is closest to the goal, as estimated by a heuristic function h(n)

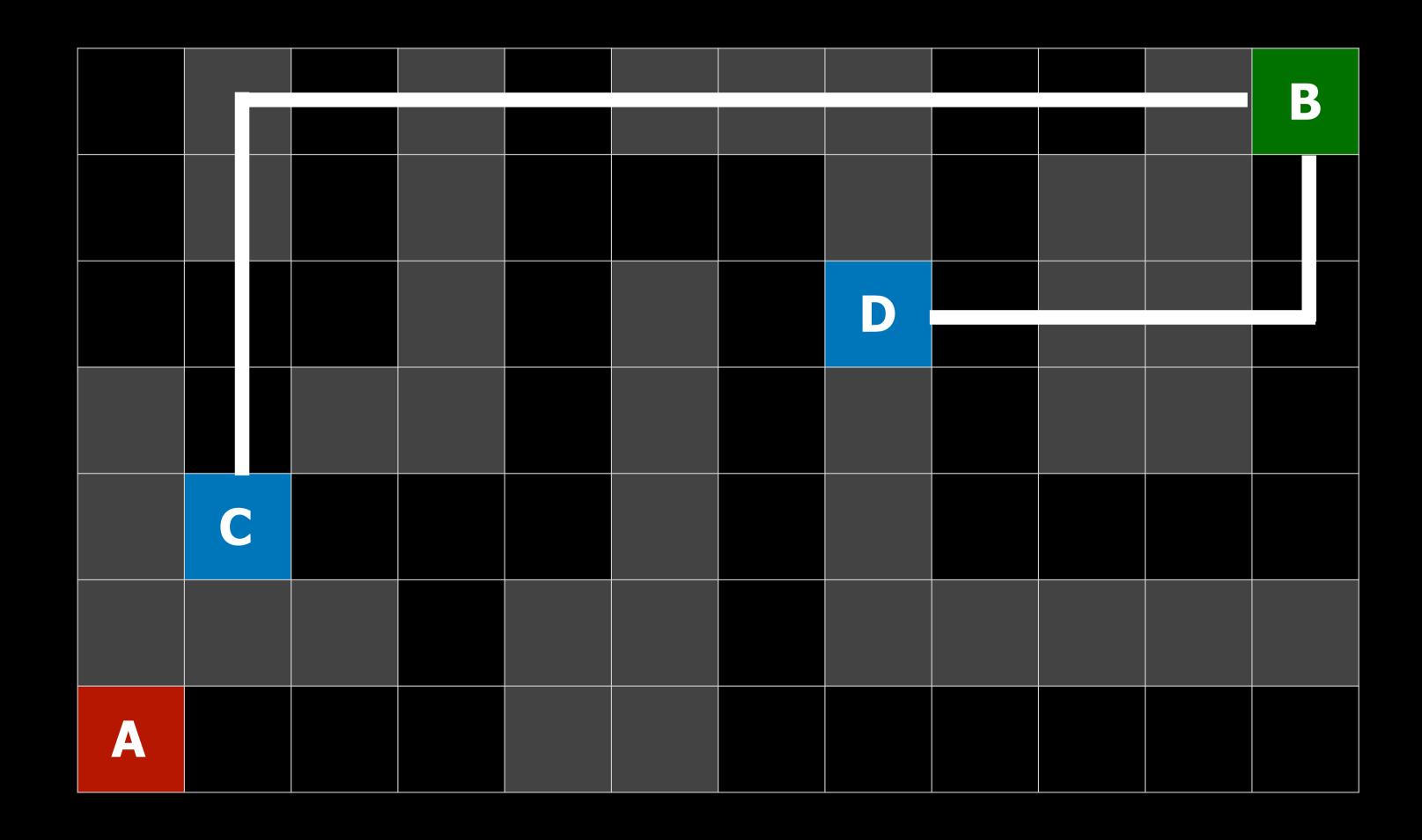
Heuristic function?



Heuristic function?



Heuristic function? Manhattan distance.



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13	12	11		9		7	6	5			2
	13			10		8		6			3
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			13			10					
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11		9		7				3	2		В
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A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

11		9		7				3	2		В
12		10		8	7	6		4			1
13	12	11		9		7	6	5			2
	13			10		8		6			3
	14	13	12	11		9		7	6	5	4
			13			10					
A	16	1 5	14			11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	1 5	14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

A* search

search algorithm that expands node with lowest value of g(n) + h(n)

g(n) = cost to reach node

h(n) = estimated cost to goal

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	16	15	14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	15	14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	2+15	14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		10	9	8	7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	9	8	7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	8	7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	11+6	5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	14	13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	14	6+13	5+12		10	9	8	7	6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	10	9	8	7	6	5	4	3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	11+10	9	8	7	6	5	4	3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	11+10	12+9	8	7	6	5	4	3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	11+10	12+9	13+8	7	6	5	4	3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	11+10	12+9	13+8	14+7	6	5	4	3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	11+10	12+9	13+8	14+7	15+6	5	4	3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	11+10	12+9	13+8	14+7	15+6	16+5	4	3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	19+2	1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

A* Search

	11+10	12+9	13+8	14+7	15+6	16+5	17+4	18+3	19+2	20+1	В
	10+11										1
	9+12		7+10	8+9	9+8	10+7	11+6	12+5	13+4		2
	8+13		6+11						14+5		3
	7+14	6+13	5+12		10	9	8	7	15+6		4
			4+13		11						5
A	1+16	2+15	3+14		12	11	10	9	8	7	6

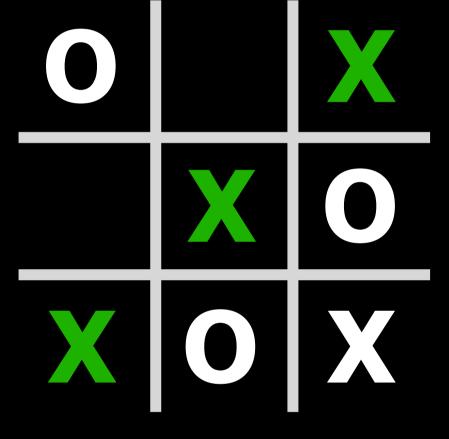
A* search

optimal if

- h(n) is admissible (never overestimates the true cost), and
- h(n) is consistent (for every node n and successor n' with step cost c, $h(n) \le h(n') + c$)

Adversarial Search

X	X
0	
X	X



-1

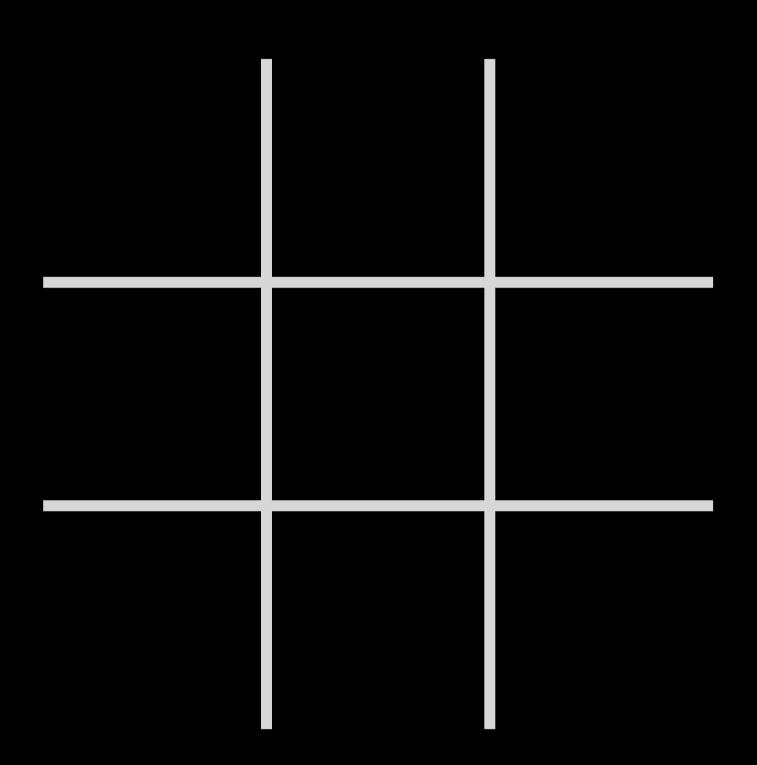
0

- MAX (X) aims to maximize score.
- MIN (O) aims to minimize score.

Game

- S_0 : initial state
- PLAYER(s): returns which player to move in state s
- ACTIONS(s): returns legal moves in state s
- Result(s, a): returns state after action a taken in state s
- TERMINAL(s): checks if state s is a terminal state
- UTILITY(s): final numerical value for terminal state s

Initial State



PLAYER(s)

PLAYER(
$$\frac{1}{\mathbf{x}}$$
) = \mathbf{X}
PLAYER($\frac{\mathbf{x}}{\mathbf{x}}$) = \mathbf{O}

ACTIONS(s)

RESULT(s, a)

TERMINAL(s)

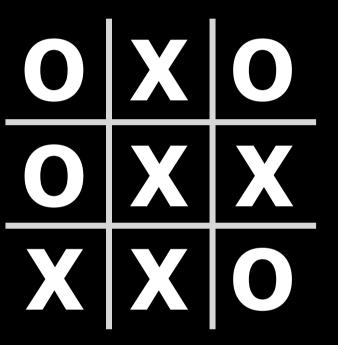
TERMINAL(
$$\begin{array}{c|c} o & x \\ \hline o & x \\ \hline x & o & x \\ \end{array}$$
) = false TERMINAL($\begin{array}{c|c} o & x \\ \hline o & x \\ \hline x & o & x \\ \end{array}$) = true

UTILITY(s)

$$\begin{array}{c|cccc} o & x \\ \hline 0 & x \\ \hline x & o & x \\ \hline \end{array}) = 1$$

$$\begin{array}{c|cccc} o & x \\ \hline x & o & x \\ \hline \end{array}$$

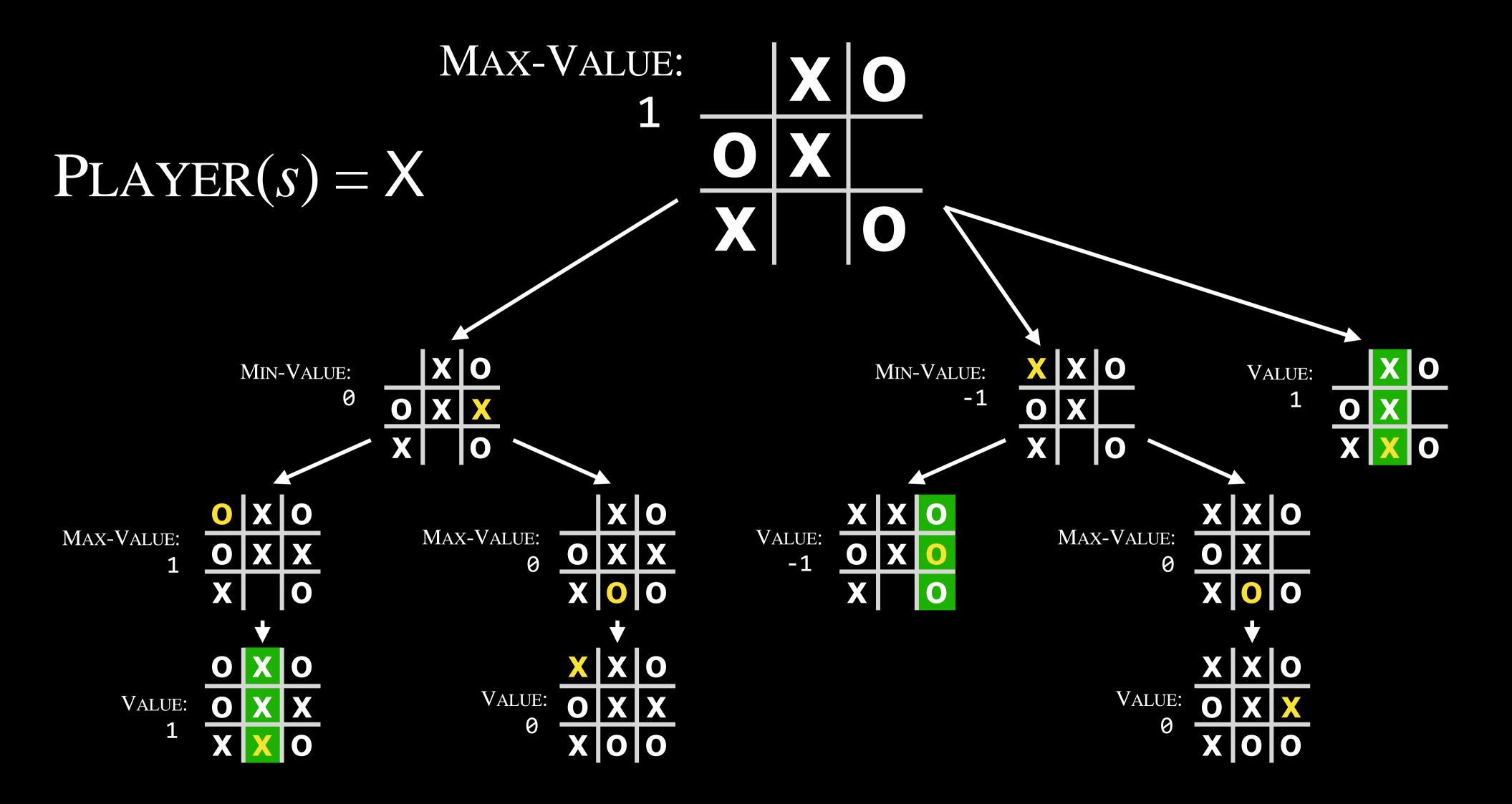
$$\begin{array}{c|ccccc} O & x & x \\ \hline \hline x & o & x \\ \hline \hline o & x & o \\ \hline \hline o & x & o \\ \hline \end{array}) = -1$$

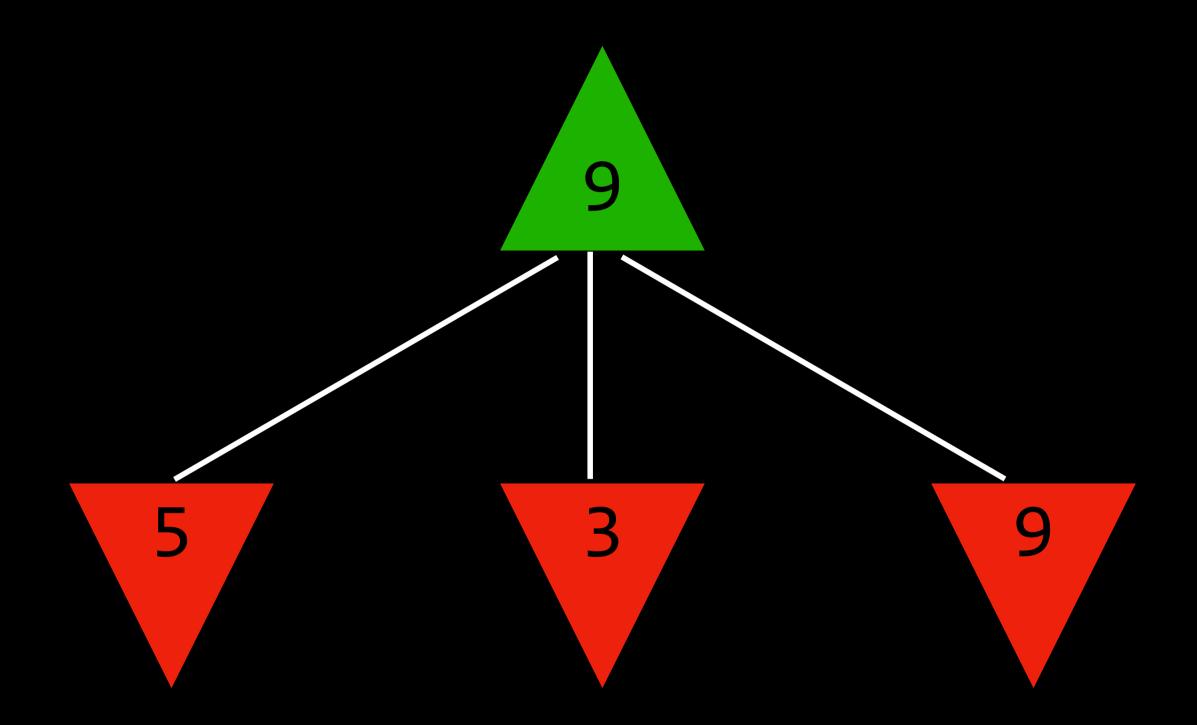


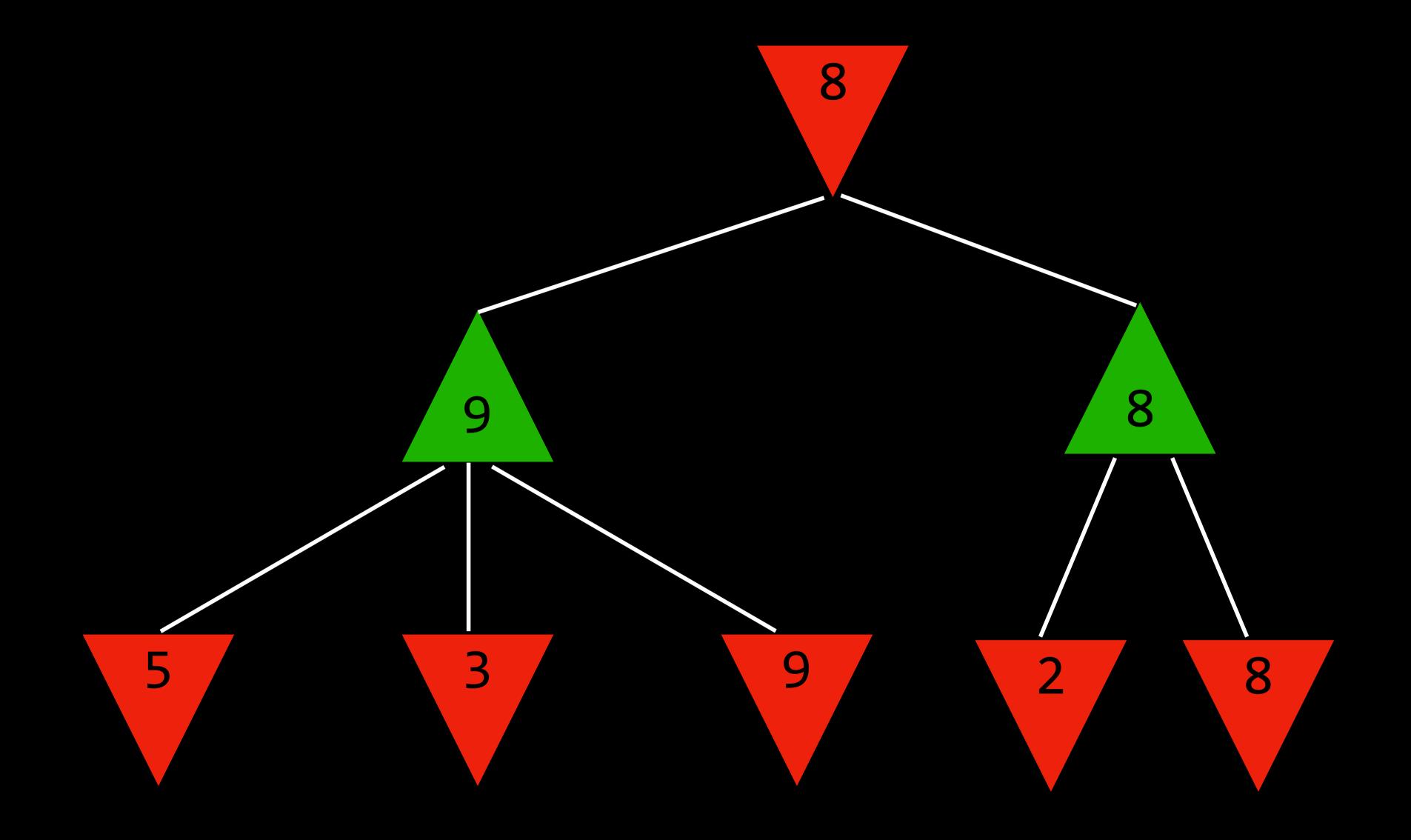
Value: 1

MIN-VALUE: PLAYER(s) = O0 MAX-VALUE: MAX-VALUE: 0 VALUE: VALUE: 0

MIN-VALUE: PLAYER(s) = O0 MAX-VALUE: MAX-VALUE: 0 VALUE: VALUE: 0





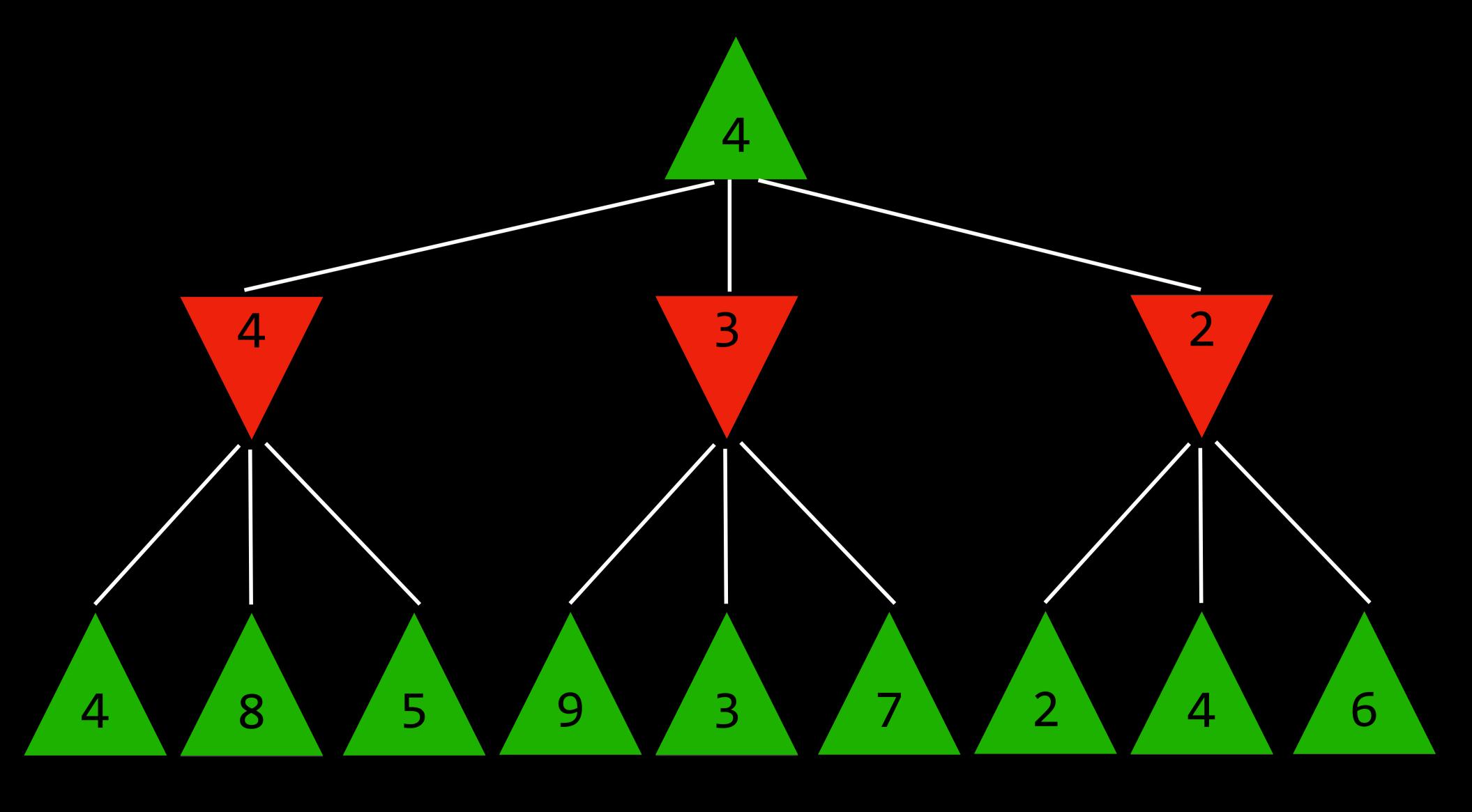


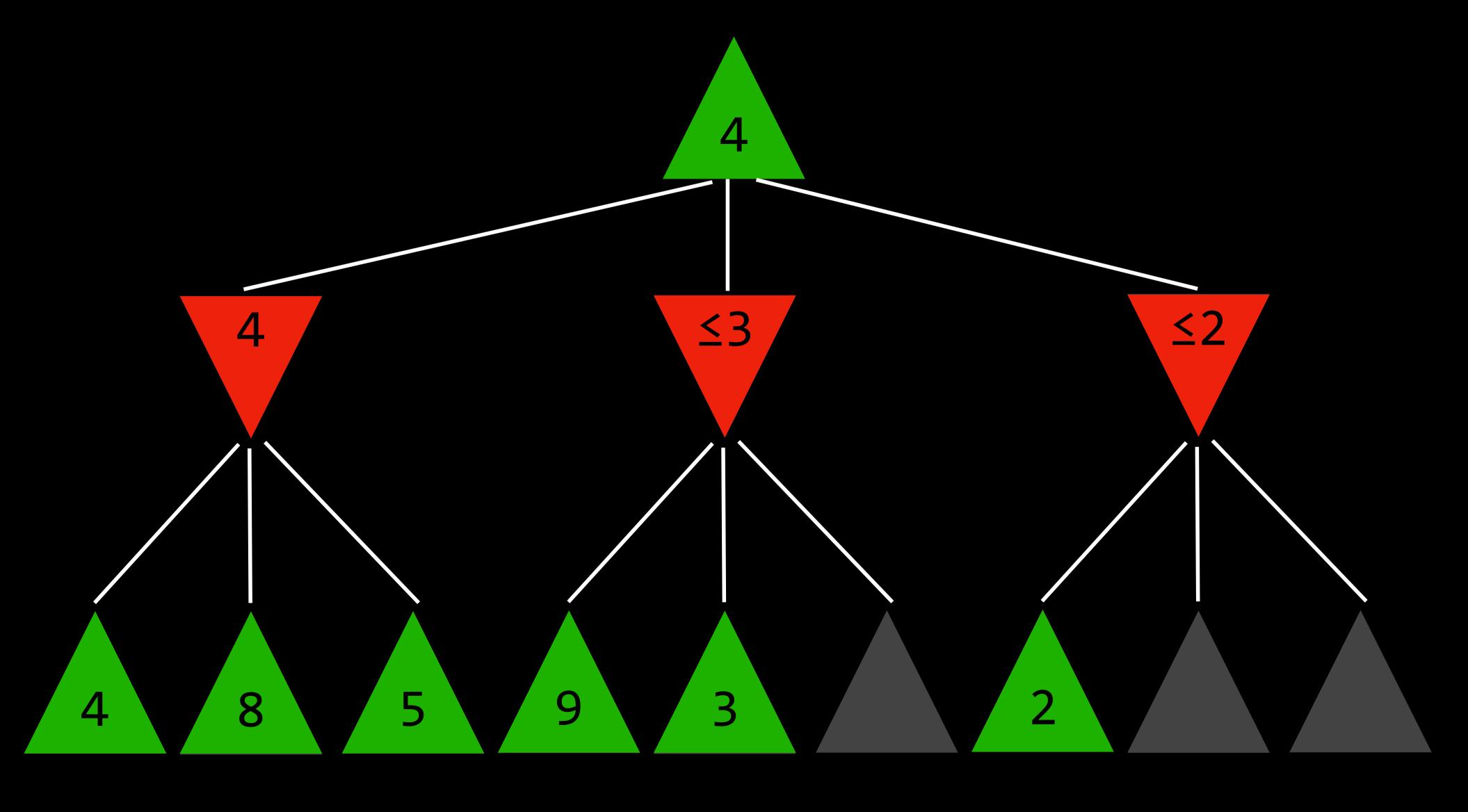
- Given a state s:
 - MAX picks action *a* in ACTIONS(*s*) that produces highest value of MIN-VALUE(RESULT(*s*, *a*))
 - MIN picks action *a* in ACTIONS(*s*) that produces smallest value of MAX-VALUE(RESULT(*s*, *a*))

```
function MAX-VALUE(state):
  if TERMINAL(state):
    return UTILITY(state)
  \nu = -\infty
  for action in ACTIONS(state):
     v = Max(v, Min-Value(Result(state, action)))
  return v
```

```
function MIN-VALUE(state):
  if TERMINAL(state):
    return UTILITY(state)
  \nu = \infty
  for action in ACTIONS(state):
     v = Min(v, Max-Value(Result(state, action)))
  return v
```

Optimizations





Alpha-Beta Pruning

255,168

total possible Tic-Tac-Toe games

288,000,000,000,000

total possible chess games after four moves each

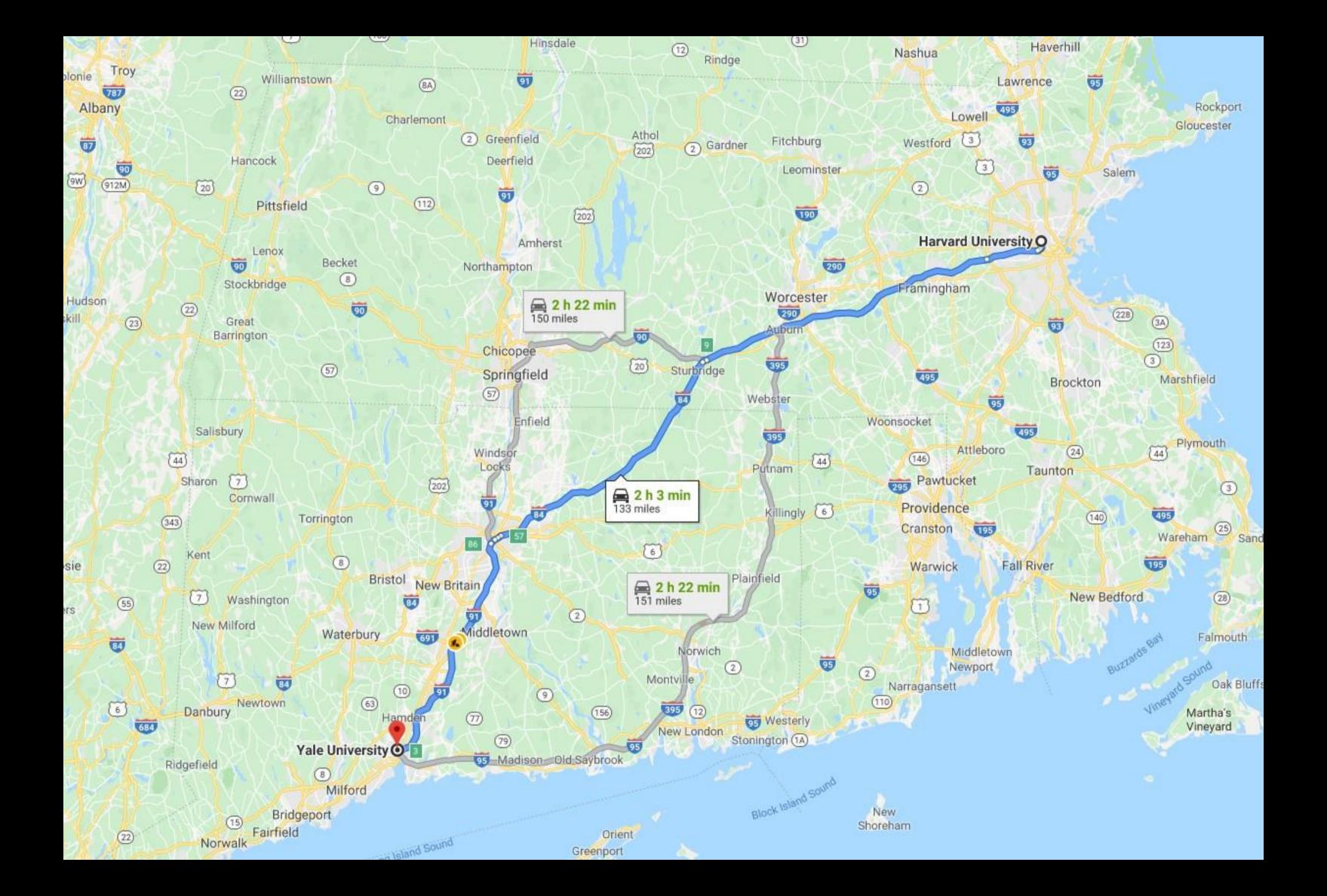
10229000

total possible chess games (lower bound)

Depth-Limited Minimax

evaluation function

function that estimates the expected utility of the game from a given state



COMPLETE MAP OF OPTIMALTIC-TAC-TOE MOVES

YOUR MOVE IS GIVEN BY THE POSITION OF THE LARGEST RED SYMBOL ON THE GRID. WHEN YOUR OPPONENT PICKS A MOVE, ZOOM IN ON THE REGION OF THE GRID WHERE THEY WENT. REPEAT.

MAP FOR X:

