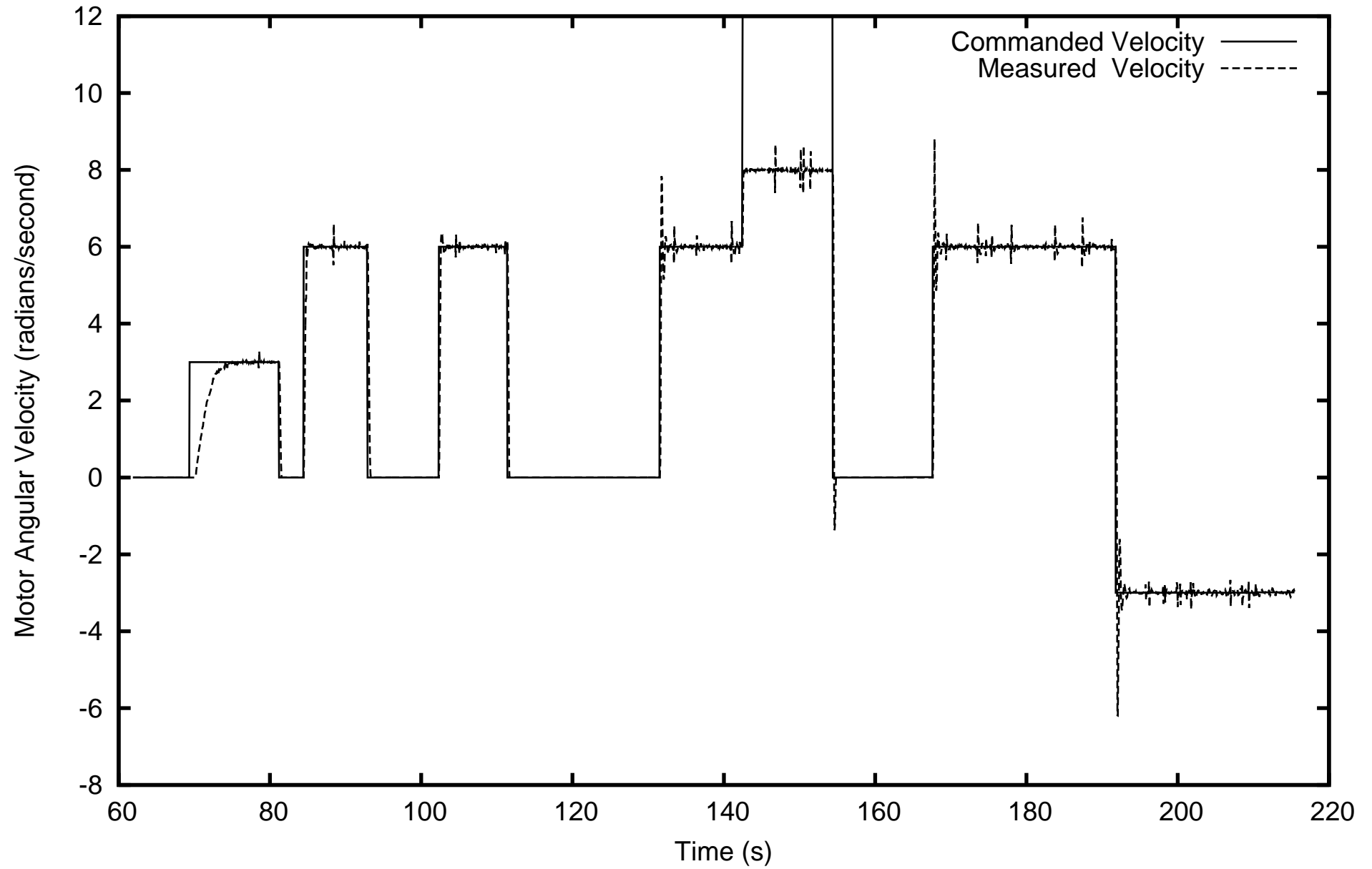


Proportional Controller Behavior for Low-Gain and High-Gain Regimes



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