

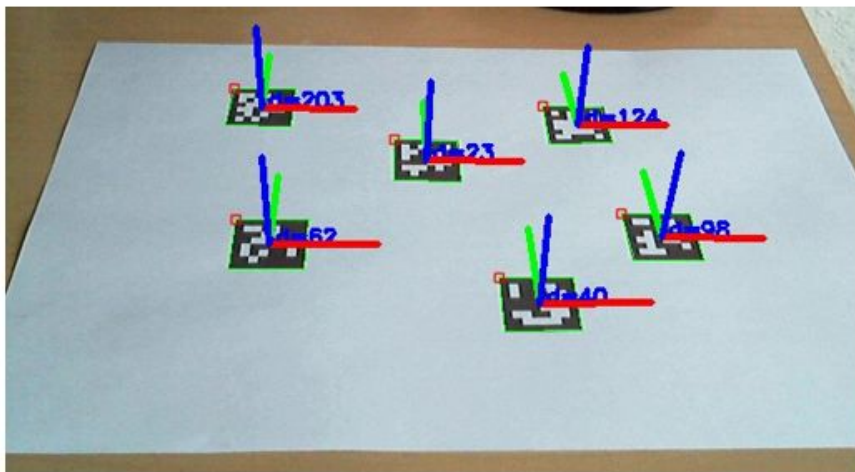
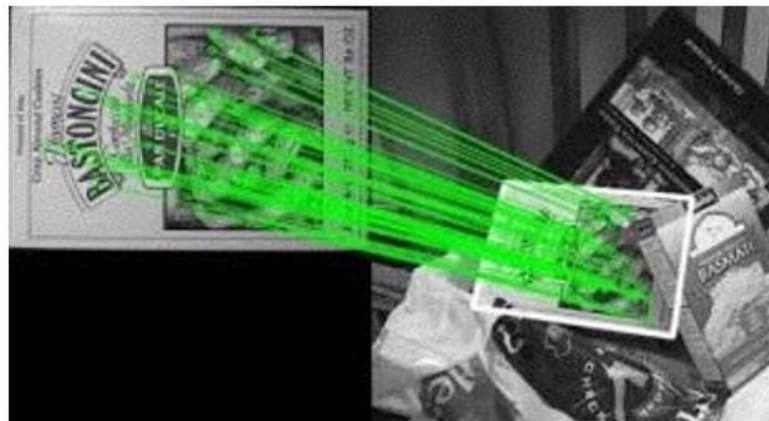
3/4 Lab

1. OpenCV introduction
2. Python 3 & opencv installation
3. Lab01



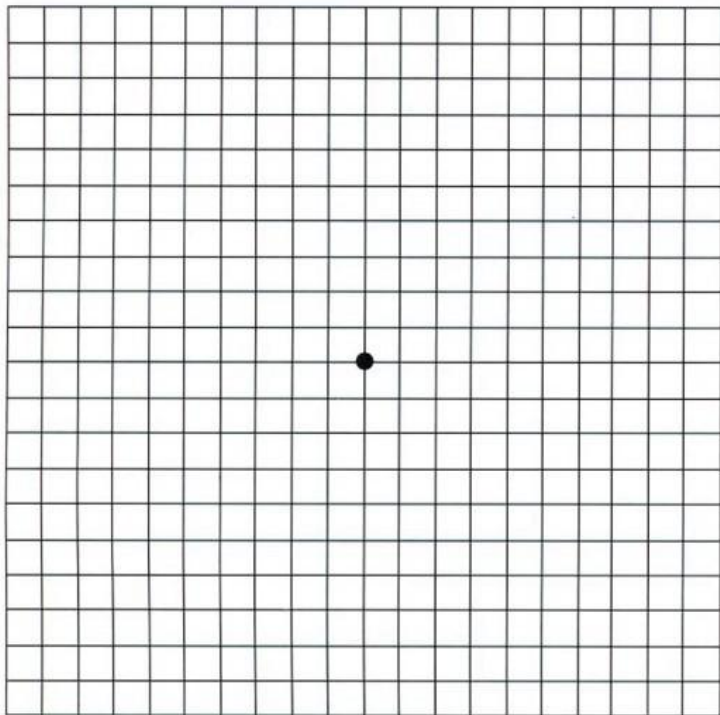
- core. The Core Functionality
- imgproc. Image Processing
- imgcodecs. Image file reading and writing
- videoio. Media I/O
- highgui. High-level GUI and Media I/O
- video. Video Analysis
- calib3d. Camera Calibration and 3D Reconstruction
- features2d. 2D Features Framework
- objdetect. Object Detection
- ml. Machine Learning
- flann. Clustering and Search in Multi-Dimensional Spaces
- photo. Computational Photography
- stitching. Images stitching
- cuda. CUDA-accelerated Computer Vision
- cudaarithm. CUDA-accelerated Operations on Matrices
- cudabgsegm. CUDA-accelerated Background Segmentation
- cudacodec. CUDA-accelerated Video Encoding/Decoding
- cudafeatures2d. CUDA-accelerated Feature Detection and Description
- cudafilters. CUDA-accelerated Image Filtering
- cudaimgproc. CUDA-accelerated Image Processing
- cudaoptflow. CUDA-accelerated Optical Flow
- cudastereo. CUDA-accelerated Stereo Correspondence
- cudawarping. CUDA-accelerated Image Warping
- shape. Shape Distance and Matching
- superres. Super Resolution
- videostab. Video Stabilization
- viz. 3D Visualizer
- bioinspired. Biologically inspired vision models and derivated tools
- cvv. GUI for Interactive Visual Debugging of Computer Vision Programs
- datasets. Framework for working with different datasets
- face. Face Recognition
- Binary descriptors for lines extracted from an image
- optflow. Optical Flow Algorithms
- reg. Image Registration
- rgbd. RGB-Depth Processing
- Saliency API
- surface_matching. Surface Matching

feature detection



pattern
recognition

Mat



rows: 長

cols: 寬

type: 像素型態

channels: 通道數

normal:

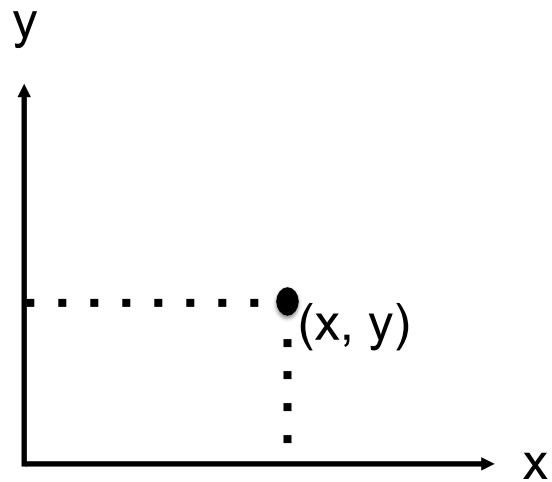
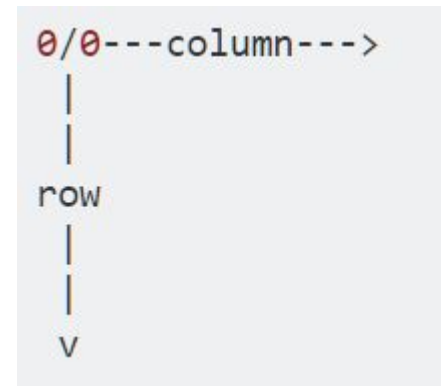
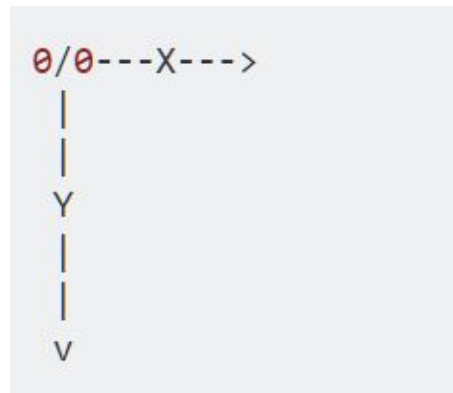


image:



Mat value access

	Column 0	Column 1	Column ...	Column m
Row 0	0,0	0,1	...	0, m
Row 1	1,0	1,1	...	1, m
Row,0	...,1, m
Row n	n,0	n,1	n,...	n, m

3-channel : B, G, R

	Column 0			Column 1			Column ...			Column m		
Row 0	0,0	0,0	0,0	0,1	0,1	0,1	0, m	0, m	0, m
Row 1	1,0	1,0	1,0	1,1	1,1	1,1	1, m	1, m	1, m
Row,0	...,0	...,0	...,1	...,1	...,1, m	..., m	..., m
Row n	n,0	n,0	n,0	n,1	n,1	n,1	n,...	n,...	n,...	n, m	n, m	n, m

```
1  import numpy as np
2  import cv2
3
4  #read
5  image = cv2.imread("image.jpg")
6  #show
7  cv2.imshow("My Image", image)
8
9  #按下按鍵關閉顯示視窗
10 cv2.waitKey(0)
11 cv2.destroyAllWindows()
12
13 #save
14 cv2.imwrite("output.jpg", image)
```


標頭引入

```
import numpy as np  
import cv2
```

讀寫圖片

讀取:

```
img = cv2.imread('image.jpg')
```

儲存:

```
cv2.imwrite('output.jpg', img)
```

顯示圖片

秀出影像:

```
# 顯示圖片  
cv2.imshow('My Image', img)
```

等待按鍵輸入:

```
# 按下任意鍵則關閉所有視窗  
cv2.waitKey(0)  
cv2.destroyAllWindows()
```

開一個指定大小的黑圖 複製圖片

```
blank_image = np.zeros((height,width,3), np.uint8)
```

```
newImage = myImage.copy()
```

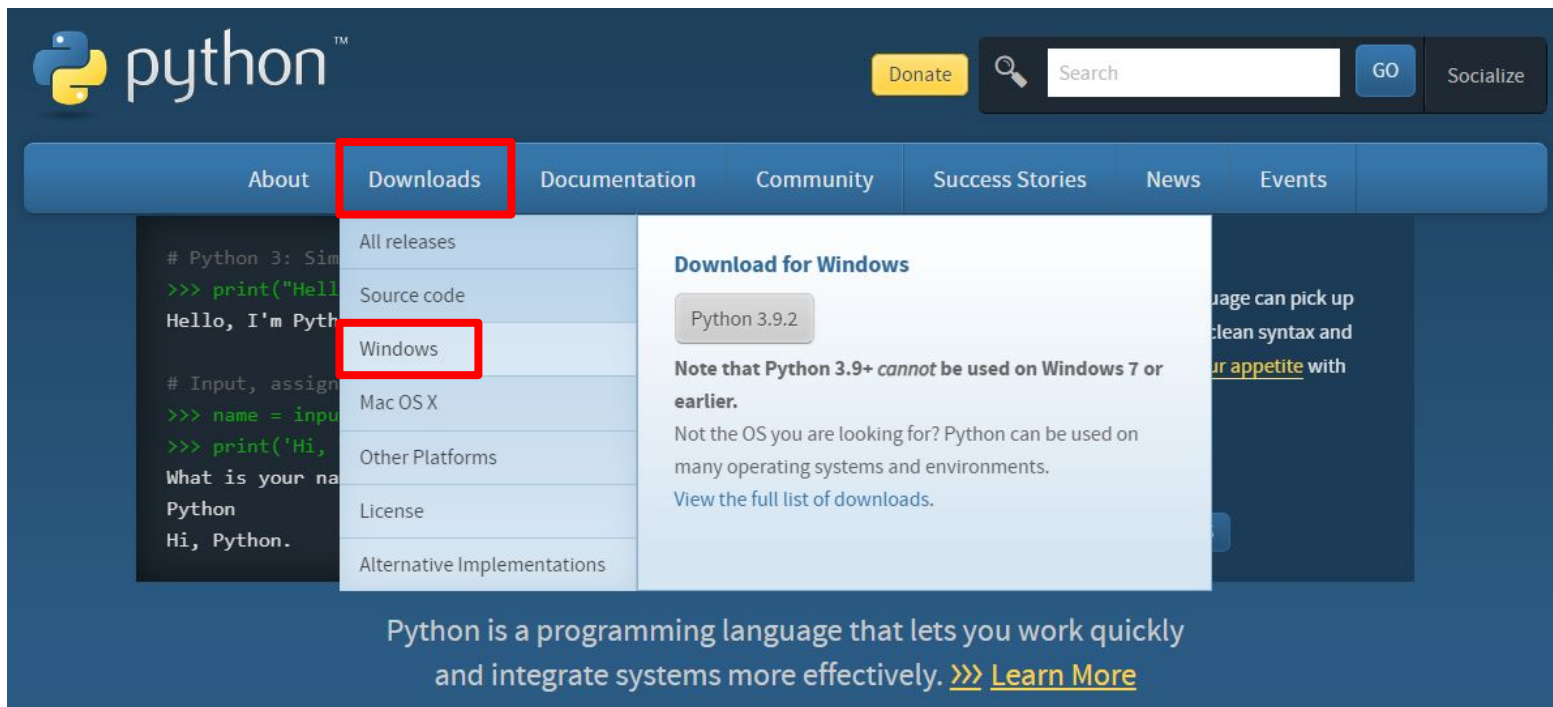
操作像素

`image[row, col, channel]`

Windows10
python 3 & opencv

1. 下載python

到[官網](#)點選Downloads



1. 下載python


選擇python 3

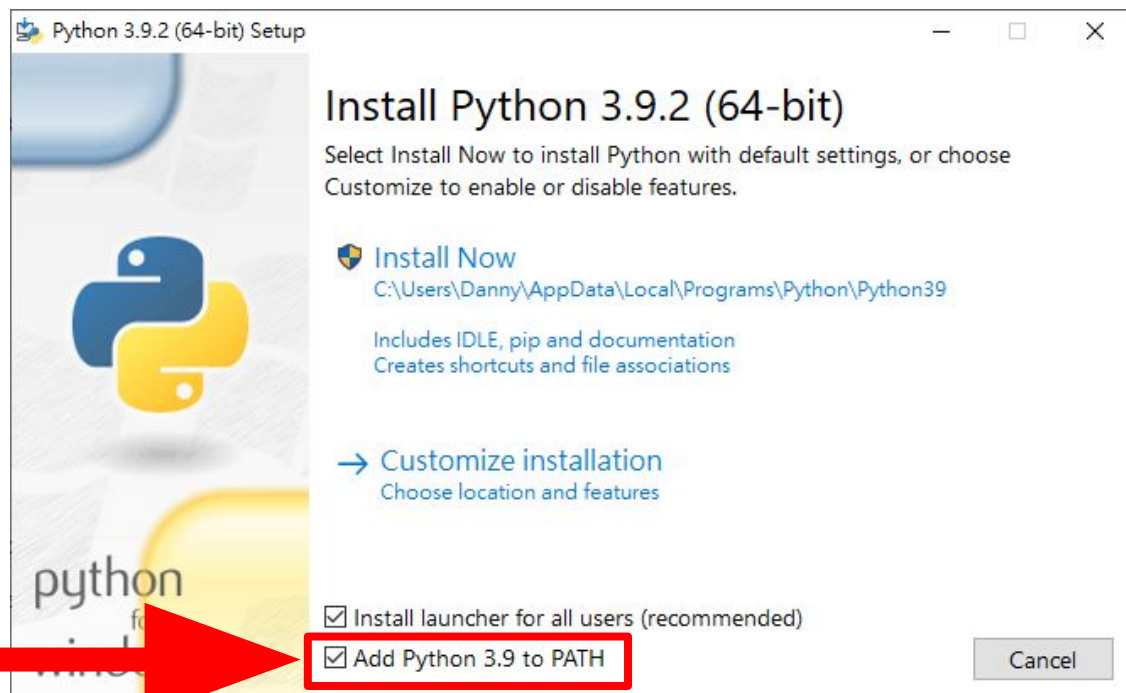
Python Releases for Windows

- 
- [Latest Python 3 Release - Python 3.9.2](#)
 - [Latest Python 2 Release - Python 2.7.18](#)

2. 安裝軟體

- 點選並安裝
- 加入環境變數

 python-3.9.2-amd64.exe



3. 安裝opencv

- pip install opencv-python
- Test :

```
1  import cv2
2
3  img = cv2.imread('kobe.jpg')
4
5  cv2.imshow('My Image', img)
6  cv2.waitKey(0)
7  cv2.destroyAllWindows()
8  |
```

4. 安裝numpy

- `pip install numpy`

```
Collecting numpy  
  Downloading numpy-1.22.2-cp38-cp38-win_amd64.whl (14.7 MB)  
    | ██████████ 14.7 MB 6.4 MB/s  
Installing collected packages: numpy  
Successfully installed numpy-1.22.2
```

Lab 01

1. 圖片灰階與顏色濾鏡
2. Interpolation (bilinear, nearest neighbor)

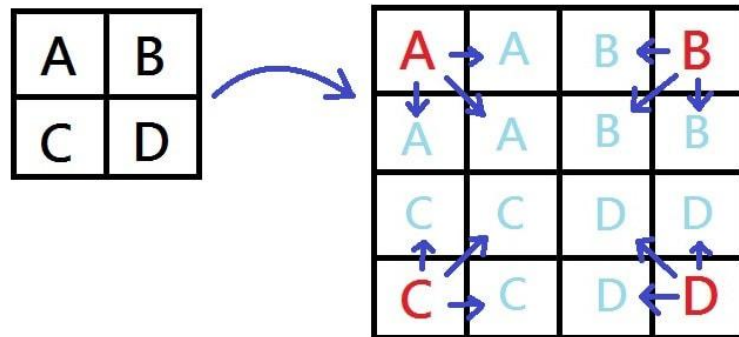
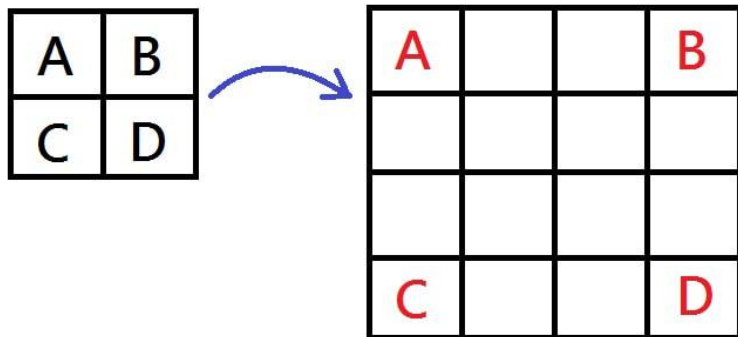
1. 灰階與藍色濾鏡(30%)

- 將原始圖片中的藍點予以保留，並把其餘的點改為灰階。
- Hint: $B > 100$ and $B * 0.6 > G$ and $B * 0.6 > R$



2. Interpolation - 最近相鄰內插法 (30%)

- 根據輸出影像的像素位置,找到輸入影像中最鄰近的點,即當作輸出影像的像素強度。
- 以下圖為例



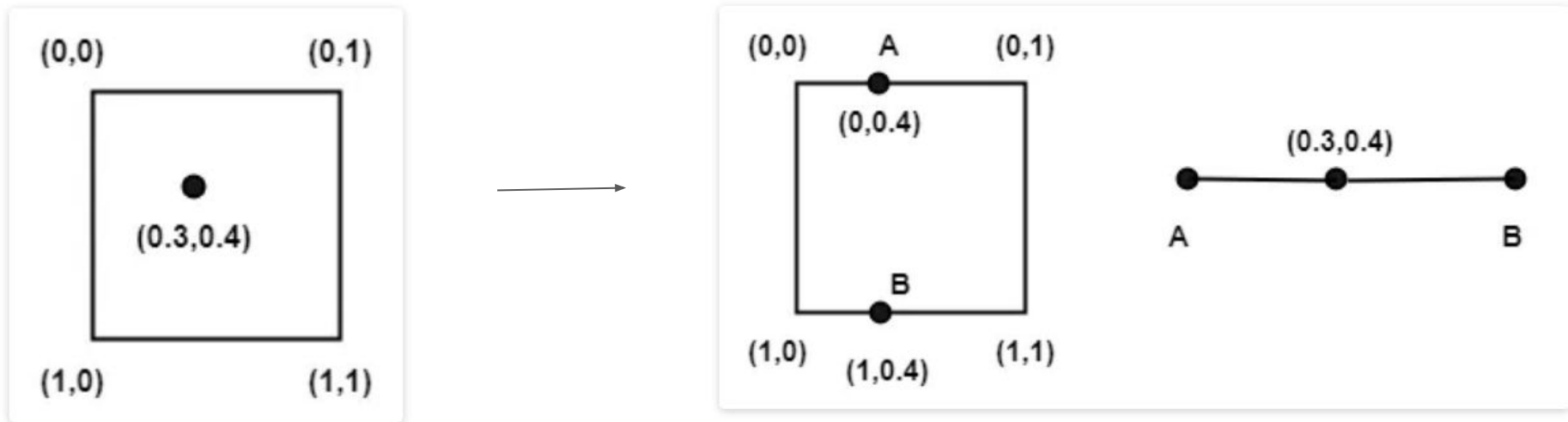
2. Interpolation - 最近相鄰內插法 (30%)

- 將照片放大3倍



3. Interpolation - 雙線性內插法 (40%)

- 根據輸出影像的像素位置, 找到輸入影像中最鄰近的四個點, 再利用雙線性內插法求出輸出影像的像素強度。



3. Interpolation - 雙線性內插法 (40%)

- 以參數方式輸入影像以及倍率
- 學會使用 OpenCV API (10%)
自行實作雙線性內插法 (40%)
- 下圖為輸入影像
右圖為
倍率=3之結果

