

1.

$$\begin{bmatrix} A & I \\ 0 & A^{-1} \end{bmatrix} \begin{bmatrix} \hat{x} \\ r \end{bmatrix} = \begin{bmatrix} b \\ 0 \end{bmatrix}$$

$\left\{ \begin{array}{l} A \hat{x} + r = b \\ A^T r = 0 \end{array} \right.$

$$N(A^T) = R(A)^\perp$$

$$r \in R(A)^\perp \quad A \hat{x} = b$$

$$\therefore (A \hat{x}) \perp r$$

Then

$$b \perp r \quad \text{satisfy } A \hat{x} + r = b$$

System  $A \hat{x} = b$  has [Least square solution]

$$\|x\|_A = \|A\|$$

$$\|x\|$$

A

to always get the same answer. In fact,  $w_{12} = 4000$

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L.

$$\|x\|_A = \|Ax\|_2$$

$$(1) Ax = a_1x_1 + a_2x_2 + \dots + a_nx_n$$

$$\|x\|_A = \|Ax\|_2 \geq 0 \quad \text{clearly} \quad \text{--- } \textcircled{1}$$

$$\|\alpha x\|_A = \|\alpha Ax\|_2 = \alpha \|Ax\|_2 = \alpha \|x\|_A \quad \text{--- } \textcircled{2}$$

$$\begin{aligned} \|x+y\|_A &= \|A(x+y)\|_2 = \|Ax+Ay\|_2 \leq \|Ax\|_2 + \|Ay\|_2 \\ &= \|x\|_A + \|y\|_A \end{aligned}$$

$$\|x\|_A = 0 \quad \text{if and only if } x=0, \quad \text{for } A \text{ is nonsingular} \quad \text{--- } \textcircled{3}$$

Say,  $u = u_1 x_1 + u_2 x_2 + \dots + u_k x_k \in S_1$

$v = v_1 x_{k+1} + v_2 x_{k+2} + \dots + v_n x_n \in S_2$

$$\forall u, v (u \cdot v = 0)$$

$$S_1 \perp S_2$$

4.

$$\begin{cases} x_1 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} & x_3 = \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} \\ x_2 = \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix} \end{cases}$$

$$y_1 = x_1 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$$

$$y_2 = x_2 - \frac{y_1^T x_2}{y_1^T y_1} y_1$$

$$= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} - \frac{1}{6} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{6} \\ \frac{1}{3} \\ \frac{1}{6} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{6} \\ \frac{1}{3} \\ \frac{1}{6} \end{bmatrix}$$

$$u_1 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$$

$$y_3 = x_3 - \frac{y_1^T x_3}{y_1^T y_1} y_1 - \frac{y_2^T x_3}{y_2^T y_2} y_2$$

$$= \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} - \frac{6}{6} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} - \frac{0}{1} \begin{bmatrix} \frac{1}{6} \\ \frac{1}{3} \\ \frac{1}{6} \end{bmatrix}$$

$$= \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$$

$$u_3 = \frac{1}{\sqrt{11}} \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$$

$$u_2 = \frac{1}{\sqrt{66}} \begin{bmatrix} -1 \\ 1 \\ 7 \end{bmatrix}$$

5.

$$\det(A - \lambda I) = 0$$

last term of  $p(\lambda) = 3^2 (-1)^2 (1)$   
 $= 36 = \det(A)$

$$\det(A^{-1}) = \frac{1}{36}$$

6.

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & \ddots & \vdots \\ & \ddots & a_{nn} \end{bmatrix} \quad \text{where } \sum_{i=1}^n a_{im} = 1 \quad \forall m$$

$$A^T = \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{nn} \end{bmatrix} \quad \text{where } \sum_{m=1}^n a_{im} = 1 \quad \forall i$$

$$A^T e = \begin{bmatrix} \sum a_{11} \\ \sum a_{12} \\ \vdots \\ \sum a_{in} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix} = e$$

$$A^T e = e$$

e is an eigenvector of  $A^T$

7.

$$f(x, y) = \frac{y}{x^2} - \frac{x}{y^2} + xy$$

$$\frac{\partial f(x, y)}{\partial x} = -2yx^{-3} - y^{-2} + y$$

$$\frac{\partial f(x, y)}{\partial y} = x^{-2} + 2xy^{-3} + x$$

$$f_{xx} = 6yx^{-4} \quad f_{xx}(1, -1) = -6$$

$$f_{xy} = (-2x^{-3}) + 2y^{-3}, \quad f_{xy}(1, -1) = 1$$

$$f_{yy} = -6xy^{-4} \quad f_{yy}(1, -1) = -6$$

$$D = (-6)(-6) - 1^2 = 35$$

$$f_{xx}(1, -1) = -6 < 0$$

$(1, -1)$  is a local minimum

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8.

$$a_{11} = (L_{11})^2$$

$$a_{21} = L_{21} L_{11}$$

$$a_{31} = L_{31} L_{11} \quad \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & -2 \\ 0 & -2 & 4 \end{bmatrix}$$

$$L_{11} = 1$$

$$L_{21} = -1$$

$$L_{31} = 0$$

$$= \begin{bmatrix} L_{11} & 0 & 0 \\ L_{21} & L_{22} & 0 \\ L_{31} & L_{32} & L_{33} \end{bmatrix} \begin{bmatrix} L_{11} & L_{21} & L_{31} \\ 0 & L_{22} & L_{32} \\ 0 & 0 & L_{33} \end{bmatrix}$$

$$(L_{22})^2 + (L_{21})^2 = 1 =$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

$$L_{22} = T_2$$

$$L_{31} L_{41} + L_{22} L_{32} = -2$$

$$L_{32} = -L$$

$$(L_{11})^2 + (L_{11})^2 + (L_{11})^2 = 4$$

$$L_{11} = T_2$$

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9.

$$G_i(A) = \lambda_i(A \bar{A}^\top)$$

$$= \lambda_i(A \bar{A})$$

$$G_i(A) = \lambda_i(A)$$

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