

## Calculus HW3

Date: Mar 13

Made by Eric

**1.****1.(a)***Proof.*  $PV = mRT$ 

$$P = mrTV^{-1}$$

$$V = \frac{mR}{P}T$$

$$T = \frac{V}{mR}P$$

$$\frac{\partial P}{\partial V} \frac{\partial V}{\partial T} \frac{\partial T}{\partial P} = (-mrTV^{-2})\left(\frac{mR}{P}\right)\left(\frac{V}{mR}\right) = \frac{-mrT}{PV} = -1$$

■

**1.(b)***Proof.*  $P = \frac{mR}{V}T$ 

$$V = \frac{mR}{P}T$$

$$T \frac{\partial P}{\partial T} \frac{\partial V}{\partial T} = T\left(\frac{mR}{V}\right)\left(\frac{mR}{P}\right) = mR \frac{mRT}{PV} = mR$$

■

**2.****2.(a)**

$$f(x, t) = \tan^{-1}(x\sqrt{t})$$

*Proof.*  $f_x = \frac{1}{1+tx^2}\sqrt{t}$ 

$$f_t = \frac{1}{1+tx^2} \frac{x}{2\sqrt{t}}$$

■

**2.(b)**

$$f(x, y) = \int_y^x \cos(t^2) dt$$

*Proof.*  $f_x = \cos(x^2)$ 

$$f = - \int_x^y \cos(t^2) dt$$

$$f_y = -\cos(y^2)$$

■

2

2.(c)

$$f(\mathbf{x}) = \sqrt{x_1^2 + \cdots + x_n^2}$$

*Proof.* Let  $1 \leq i \leq n$

$$f_i = \frac{x_i}{f(\mathbf{x})}$$

■

2.(d)

$$u(x, y) = f\left(\frac{x}{y}\right)$$

*Proof.*  $u_x = f'\left(\frac{x}{y}\right) \frac{1}{y}$

$$u_y = f'\left(\frac{x}{y}\right) \frac{-x}{y^2}$$

■

3.

*Proof.* Notice  $\forall i : 1 \leq i \leq n, \frac{\partial u}{\partial x_i} = a_i u$

Then  $\forall i : 1 \leq i \leq n, \frac{\partial^2 u}{\partial x_i^2} = a_i^2 u$

$$\sum_{i=1}^n \frac{\partial^2 u}{\partial x_i^2} = \sum_{i=1}^n a_i^2 u = \left(\sum_{i=1}^n a_i^2\right) u = u$$

■

4.

*Proof.* We now prove  $f_x$  exist on  $\mathbb{R}^2$

We view  $f_x$  as the ordinal derivative of  $g(x) = f(x, y)$  where  $y$  is fixed

Notice the product of two differentiable function is a differentiable function, and the composition of two differentiable function is a differentiable function

Let  $h(x) = x^2 + y^2$  and  $r(x) = \sin\left(\frac{1}{x}\right)$

Notice  $r$  and  $h$  are both differentiable over  $\mathbb{R} \setminus \{0\}$

Notice  $g = h(r \circ h)$ , so we know  $g$  is differentiable over  $\mathbb{R} \setminus \{0\}$

Now we check if  $g$  is differentiable at 0, more precisely, if  $\lim_{h \rightarrow 0} \frac{g(h) - g(0)}{h}$  exists when  $y$  is fixed at 0

$$\lim_{h \rightarrow 0} \frac{g(h) - g(0)}{h} = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} h \sin\left(\frac{1}{h^2}\right) = 0 \text{ (done)}$$

We now prove  $f_y$  exist on  $\mathbb{R}^2$

We view  $f_y$  as the ordinal derivative of  $g(y) = f(x, y)$  where  $x$  is fixed

Notice the product of two differentiable function is a differentiable function, and the composition of two differentiable function is a differentiable function

Let  $h(y) = x^2 + y^2$  and  $r(y) = \sin(\frac{1}{y})$

Notice  $r$  and  $h$  are both differentiable over  $\mathbb{R} \setminus \{0\}$

Notice  $g = h(r \circ h)$ , so we know  $g$  is differentiable over  $\mathbb{R} \setminus \{0\}$

Now we check  $g$  is differentiable at 0, more precisely, if  $\lim_{h \rightarrow 0} \frac{g(h) - g(0)}{h}$  exists when  $x$  is fixed at 0

$$\lim_{h \rightarrow 0} \frac{g(h) - g(0)}{h} = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} h \sin(\frac{1}{h^2}) = 0 \text{ (done)}$$

Notice  $f_x = 2x \sin(\frac{1}{x^2 + y^2}) + \frac{-2x}{x^2 + y^2} \cos(\frac{1}{x^2 + y^2})$  when  $(x, y) \neq (0, 0)$

Setting  $y = 0$ , we see  $\lim_{x \rightarrow 0^-} f_x = \infty$  by direct computation, so  $f_x$  is discontinuous at  $(0, 0)$

Notice  $f_y = 2y \sin(\frac{1}{x^2 + y^2}) + \frac{-2y}{x^2 + y^2} \cos(\frac{1}{x^2 + y^2})$  when  $(x, y) \neq (0, 0)$

Setting  $x = 0$ , we see  $\lim_{y \rightarrow 0^-} f_y = \infty$  by direct computation, so  $f_y$  is discontinuous at  $(0, 0)$

Notice  $f_x(0, y) = 0$  and  $f_x(0, 0) = 0$ , so  $f_{xy}(0, 0) = 0$

Notice  $f_y(x, 0) = 0$  and  $f_y(0, 0) = 0$ , so  $f_{yx}(0, 0) = 0$

■

## 5.

### 5.(a)

*Proof.*

$$\frac{\partial \frac{1}{r(\mathbf{x})}}{\partial x_i} = \frac{d \frac{1}{r(\mathbf{x})}}{dr(\mathbf{x})} \frac{\partial r(\mathbf{x})}{\partial x_i} = -r^{-2}(\mathbf{x}) \frac{\partial r(\mathbf{x})}{\partial x_i} = -r^{-2}(\mathbf{x}) \frac{2x_i}{2\sqrt{x_1^2 + \dots + x_n^2}} = \frac{-x_i}{r^3(\mathbf{x})}$$

■

### 5.(b)

*Proof.*

$$\frac{\partial r^m(\mathbf{x})}{\partial x_i} = \frac{dr^m(\mathbf{x})}{dr(\mathbf{x})} \frac{\partial r(\mathbf{x})}{\partial x_i} = mr^{m-1}(\mathbf{x}) \frac{\partial r(\mathbf{x})}{\partial x_i} = mr^{m-1}(\mathbf{x}) \frac{2x_i}{2\sqrt{x_1^2 + \dots + x_n^2}} = mr^{m-2}(\mathbf{x}) x_i$$

■

**6.**

*Proof.* Write  $z = f(x_1, \dots, x_n) = g(h(x_1, \dots, x_n))$

Write  $y = h(x_1, \dots, x_n)$ , so  $z = g(y)$

Then

$$\frac{\partial f}{\partial x_i} = \frac{\partial z}{\partial x_i} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial x_i} = g'(y) \frac{\partial y}{\partial x_i} = g'(y) h_i(x_1, \dots, x_n) = g'(h(x_1, \dots, x_n)) h_i(x_1, \dots, x_n) \quad (1)$$

$g$  is differentiable at  $\mathbf{a}$  and  $h_i(\mathbf{a})$  exists shows that  $\frac{\partial f}{\partial x_i}(\mathbf{a})$

Substituting  $(x_1, \dots, x_n) = \mathbf{a}$ , we have

$$\frac{\partial f}{\partial x_i}(\mathbf{a}) = g'(h(\mathbf{a})) h_i(\mathbf{a})$$

■

**7.**

*Proof.* Notice  $\frac{df(x,a)}{da} = f_y$

So  $f(x, a) = \int_0^a f_y(x, y) dy + C$

Then obviously  $\forall x \in [1, 1], \forall a \in (1, 1), f(x, a)$  is bounded by  $\pm 2aM + C$

■

**8.****8.(a)**

*Proof.*

$$\frac{du}{dt} = \frac{\partial u}{\partial x} \frac{dx}{dt} + \frac{\partial u}{\partial y} \frac{dy}{dt}$$

$$\frac{\partial u}{\partial x} = 1 + 2\sqrt{\frac{y}{x}}$$

$$\frac{\partial u}{\partial y} = 1 + 2\sqrt{\frac{x}{y}}$$

$$\frac{dx}{dt} = 3t^2$$

$$\frac{dy}{dt} = -t^{-2}$$

$$\frac{du}{dt} = (1 + 2\sqrt{\frac{y}{x}})3t^2 + (1 + 2\sqrt{\frac{x}{y}})(-t^{-2})$$

■

**8.(b)***Proof.*

$$\frac{du}{dt} = \frac{\partial u}{\partial x} \frac{dx}{dt} + \frac{\partial u}{\partial y} \frac{dy}{dt} + \frac{\partial u}{\partial z} \frac{dz}{dt}$$

$$\frac{\partial u}{\partial x} = y + z$$

$$\frac{\partial u}{\partial y} = x + z$$

$$\frac{\partial u}{\partial z} = x + y$$

$$\frac{dx}{dt} = 2t$$

$$\frac{dy}{dt} = -2t + 1$$

$$\frac{dz}{dt} = -2(1 - t)$$

$$\frac{du}{dt} = (y + z)2t + (x + z)(-2t + 1) - 2(x + y)(1 - t)$$

■

**8.(c)***Proof.*  $\frac{\partial u}{\partial x} = z^2 y \sec(xy) \tan(xy)$ 

$$\frac{\partial u}{\partial y} = z^2 x \sec(xy) \tan(xy)$$

$$\frac{\partial u}{\partial z} = 2x \sec(xy)$$

$$\frac{\partial x}{\partial s} = 2t$$

$$\frac{\partial x}{\partial t} = 2s$$

$$\frac{\partial y}{\partial s} = 1$$

$$\frac{\partial y}{\partial t} = -2t$$

$$\frac{\partial z}{\partial s} = 2ts$$

$$\frac{\partial z}{\partial t} = s^2$$

**(i)**

$$\frac{\partial u}{\partial s} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial s} + \frac{\partial u}{\partial z} \frac{\partial z}{\partial s}$$

$$\frac{\partial u}{\partial s} = z^2 y \sec(xy) \tan(xy) 2t + z^2 x \sec(xy) \tan(xy) + 2x \sec(xy) 2ts$$

$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial t} + \frac{\partial u}{\partial z} \frac{\partial z}{\partial t}$$

$$\frac{\partial u}{\partial t} = z^2 y \sec(xy) \tan(xy) 2s + z^2 x \sec(xy) \tan(xy) + 2x \sec(xy) s^2$$

$$\frac{\partial}{\partial s} \frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial s \partial x} \frac{\partial x}{\partial t} + \frac{\partial u}{\partial x} \frac{\partial^2 x}{\partial s \partial t} + \frac{\partial^2 u}{\partial s \partial y} \frac{\partial y}{\partial t} + \frac{\partial u}{\partial y} \frac{\partial^2 y}{\partial s \partial t} + \frac{\partial^2 z}{\partial s \partial y} \frac{\partial z}{\partial t} + \frac{\partial u}{\partial z} \frac{\partial^2 z}{\partial s \partial t}$$

$$\frac{\partial^2 u}{\partial s \partial x} = \frac{\partial^2 u}{\partial x^2} \frac{\partial x}{\partial s}$$

$$\frac{\partial^2 u}{\partial s \partial y} = \frac{\partial^2 u}{\partial y^2} \frac{\partial y}{\partial s}$$

$$\frac{\partial^2 u}{\partial s \partial z} = \frac{\partial^2 u}{\partial z^2} \frac{\partial z}{\partial s}$$

$$\frac{\partial^2 u}{\partial x^2} = z^2 y^2 (\tan^2(xy) \sec(xy) + \sec^2(xy))$$

$$\frac{\partial^2 u}{\partial y^2} = z^2 x^2 (\tan^2(xy) \sec(xy) + \sec^2(xy))$$

$$\frac{\partial^2 u}{\partial z^2} = 0$$

$$\frac{\partial^2 x}{\partial s \partial t} = 2$$

$$\frac{\partial^2 y}{\partial s \partial t} = 0$$

$$\frac{\partial^2 z}{\partial s \partial t} = 2s$$

■

### 8.(d)

*Proof.*

$$\frac{\partial u}{\partial r} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial w} \frac{\partial w}{\partial r} + \frac{\partial u}{\partial x} \frac{\partial x}{\partial t} \frac{\partial t}{\partial r} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial w} \frac{\partial w}{\partial r} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial t} \frac{\partial t}{\partial r} + \frac{\partial u}{\partial z} \frac{\partial z}{\partial w} \frac{\partial w}{\partial r} + \frac{\partial u}{\partial z} \frac{\partial z}{\partial t} \frac{\partial t}{\partial r}$$

■

### 9.

*Proof.*

$$\frac{\partial u}{\partial r} = \frac{\partial u}{\partial x} \cos(\theta) + \frac{\partial u}{\partial y} \sin(\theta) \quad (2)$$

$$\frac{\partial^2 u}{\partial r^2} = \frac{\partial^2 u}{\partial x^2} \cos^2 \theta + \frac{\partial^2 u}{\partial y^2} \sin^2 \theta + 2 \frac{\partial^2 u}{\partial x \partial y} \sin \theta \cos \theta \quad (3)$$

$$\frac{\partial^2 u}{\partial \theta^2} = \frac{\partial^2 u}{\partial \theta \partial x} r(-\sin \theta) + \frac{\partial u}{\partial x} r(-\cos \theta) + \frac{\partial^2 u}{\partial \theta \partial y} r \cos \theta + \frac{\partial u}{\partial y} r(-\sin \theta) \quad (4)$$

$$\frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} = \frac{-1}{r} \left( \frac{\partial^2 u}{\partial \theta \partial x} \sin \theta - \frac{\partial^2 u}{\partial \theta \partial y} \cos \theta \right)$$

$$\frac{\partial^2 u}{\partial \theta \partial x} = -r \frac{\partial^2 u}{\partial x^2} \sin \theta + r \frac{\partial^2 u}{\partial y \partial x} \cos \theta$$

$$\frac{\partial^2 u}{\partial \theta \partial y} = r \frac{\partial^2 u}{\partial y^2} \cos \theta - r \frac{\partial^2 u}{\partial x \partial y} \sin \theta$$

$$\frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} = \sin^2(\theta) \frac{\partial^2 u}{\partial x^2} + \cos^2(\theta) \frac{\partial^2 u}{\partial y^2} - 2 \sin \theta \cos \theta \frac{\partial^2 u}{\partial y \partial x} \quad (5)$$

$$\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} = \frac{\partial^2 u}{\partial x^2} (\sin^2 \theta + \cos^2 \theta) + \frac{\partial^2 u}{\partial y^2} (\sin^2 \theta + \cos^2 \theta) = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \quad (6)$$

■

## 10.

### 10.(a)

*Proof.*

$$z = x + y + 16 - 8(\sqrt{x} + \sqrt{y}) + 2\sqrt{xy}$$

$$\frac{\partial z}{\partial x} = 1 + \frac{\sqrt{y} - 4}{\sqrt{x}}$$

$$\frac{\partial z}{\partial y} = 1 + \frac{\sqrt{x} - 4}{\sqrt{y}}$$

$$\frac{\partial z}{\partial x}(1, 4) = -1$$

$$\frac{\partial z}{\partial y}(1, 4) = \frac{-1}{2}$$

The tangent plane at  $(1, 4, 1)$  is

$$z - 1 = -(x - 1) + \frac{1}{-2}(y - 4)$$

■

**10.(b)***Proof.*

$$\frac{\partial z}{\partial x} = \cos(x \cos y) \cos y$$

$$\frac{\partial z}{\partial y} = -\cos(x \cos y) x \sin y$$

$$\frac{\partial z}{\partial x}(1, \tfrac{1}{2}\pi) = 0$$

$$\frac{\partial z}{\partial y}(1, \tfrac{1}{2}\pi) = -1$$

The tangent plane at  $(1, \tfrac{1}{2}\pi, 0)$  is

$$z = -(y - \tfrac{1}{2}\pi)$$

■

**11.**

*Proof.*  $\frac{\partial f}{\partial x} = 2x + 2yz$

$$\frac{\partial f}{\partial y} = 2xz - z^2$$

$$\frac{\partial f}{\partial z} = -2yz + 2xy$$

$$\frac{\partial f}{\partial x}(1, 1, 2) = 6$$

$$\frac{\partial f}{\partial y}(1, 1, 2) = 0$$

$$\frac{\partial f}{\partial z}(1, 1, 2) = -2$$

The direction vector  $\mathbf{u}$  is  $\frac{1}{\sqrt{14}}(2, 1, -3)$

The direction derivative is  $\frac{1}{\sqrt{14}}(12 + 6)$

■

**12.***Proof.*

$$f_x = -2xe^y$$

$$f_y = e^y(y^2 + 2y - x^2)$$

$$f_x = 0 = f_y \implies x = 0 \text{ and } (y = 0 \text{ or } -2)$$

So the critical points are  $(0, 0)$  or  $(0, -2)$



$$f_{xx} = -2e^y$$

$$f_{yy} = e^y(y^2 + 4y + 2 - x^2)$$

$$f_{xy} = -2xe^y$$

$$D = -2e^{2y}[(y+2)^2 + x^2 - 6]$$

$$\forall (a, b) \in \mathbb{R}^2, f_{xx}(a, b) < 0$$

$$D(0, 0) = 4 > 0$$

$$D(0, 2) < 0$$

So  $(0, 2)$  is a saddle points and  $(0, 0)$  is a local maximum

