

Lab 2 Report - EEG Classification

- Student Info

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- Introduction (20%)

此次實驗是基於PyTorch實作兩個neural network - EEGNet及DeepConvNet，而的dataset為BCI Competition III – IIIb，目的是腦波圖的分類。

在dataset方面，dataset shape為(B, 1, 2, 750)，其中B代表的是batch size，是我們可以調整的參數之一，而(2, 750)則是因為 `read_bci_data` 已經將兩個channel的data合為一個channel，每個channel原本就具有750筆資料，代表的是一段時間內的腦波變化，而label的0, 1則代表左手還是右手。

在實作方面TA提供 `read_bci_data` 用於load training及testing data，並提供EEGNet及DeepConvNet兩模型的參數，因此我們需要根據模型參數建立模型，再根據lab 0所教的PyTorch基本操作，實作training及testing，最後根據accuracy紀錄模型參數，以便在demo時可重現accuracy的結果。

- Experiments Setups (30%)

1. The detail of your model

- EEGNet

根據spec上的定義，建立 `EEGNet`，在 `init` function內會建立每一個layer，而forward會將output做為下一層的input。

1. `first_conv`

```

63 # nn.Sequential is sequential model container. The forward() method of Sequential accepts any input and
64 # forwards it to the first module it contains. It then "chains" outputs to inputs sequentially for each
65 # subsequent module, finally returning the output of the last module.
66 self.first_conv = nn.Sequential(
67     nn.Conv2d(
68         in_channels=1,
69         out_channels=16,
70         kernel_size=(1, 51),
71         stride=(1, 1),
72         padding=(0, 25),
73         bias=False,
74     ),
75     nn.BatchNorm2d(
76         # C from an expected input of size (N, C, H, W).
77         num_features=16,
78         # A value added to the denominator for numerical stability.
79         eps=1e-05,
80         # The value used for the running_mean and running_var computation.
81         momentum=0.1,
82         # A boolean value that when set to True, this module has learnable affine parameters.
83         affine=True,
84         # A boolean value that when set to True, this module tracks the running mean and variance,
85         # and when set to False, this module does not track such statistics.
86         track_running_stats=True,
87     )
88 )

```

2. `depth_wise_conv`

```

80 self.depth_wise_conv = nn.Sequential(
81     nn.Conv2d(
82         in_channels=16,
83         out_channels=32,
84         kernel_size=(2, 1),
85         stride=(1, 1),
86         # Number of blocked connections from input channels to output channels.
87         # Reference: https://blog.csdn.net/monsterhoho/article/details/80173400
88         groups=16,
89         bias=False,
90     ),
91     nn.BatchNorm2d(
92         num_features=32,
93         eps=1e-05,
94         momentum=0.1,
95         affine=True,
96         track_running_stats=True,
97     ),
98     activation_function(),
99     nn.AvgPool2d(
100         kernel_size=(1, 4),
101         stride=(1, 4),
102         padding=0,
103     ),
104     # During training, randomly zeroes some of the elements of the input tensor with probability p using
105     # samples from a Bernoulli distribution.
106     # The objective is avoiding overfitting to some channel data.
107     nn.Dropout(
108         # probability of an element to be zeroed.
109         p=0.25,
110     )
111 )

```

3. `separable_conv`

```

113         self.separable_conv = nn.Sequential(
114             nn.Conv2d(
115                 in_channels=32,
116                 out_channels=32,
117                 kernel_size=(1, 15),
118                 stride=(1, 1),
119                 padding=(0, 7),
120                 bias=False,
121             ),
122             nn.BatchNorm2d(
123                 num_features=32,
124                 eps=1e-05,
125                 momentum=0.1,
126                 affine=True,
127                 track_running_stats=True,
128             ),
129             activation_function(),
130             nn.AvgPool2d(
131                 kernel_size=(1, 8),
132                 stride=(1, 8),
133                 padding=0
134             ),
135             nn.Dropout(p=0.25)
136         )

```

4. `classify`

```

138         self.classify = nn.Sequential(
139             # Flattens a contiguous range of dims into a tensor.
140             nn.Flatten(),
141             # Applies a linear transformation to the incoming data.
142             nn.Linear(
143                 in_features=736,
144                 out_features=2,
145                 bias=True,
146             )
147         )

```

5. `forward`

```

149     def forward(self, inputs: TensorDataset):
150         inputs = self.first_conv(inputs)
151         inputs = self.depth_wise_conv(inputs)
152         inputs = self.separable_conv(inputs)
153         return self.classify(inputs)

```

• DeepConvNet

和 `EEGNet` 相似，根據spec上的定義，建立 `DeepConvNet`，在 `init` function內會建立每一個layer，而forward會將output做為下一層的input。

1. `conv0`

```

163         self.conv0 = nn.Sequential(
164             nn.Conv2d(
165                 in_channels=1,
166                 out_channels=self.deepconv[0],
167                 kernel_size=(1, 5),
168                 stride=(1, 1),
169                 padding=(0, 0),
170                 bias=True
171             ),
172             nn.Conv2d(
173                 in_channels=self.deepconv[0],
174                 out_channels=self.deepconv[0],
175                 kernel_size=(2, 1),
176                 stride=(1, 1),
177                 padding=(0, 0),
178                 bias=True
179             ),
180             nn.BatchNorm2d(
181                 num_features=self.deepconv[0]
182             ),
183             activation_function(),
184             nn.MaxPool2d(
185                 kernel_size=(1, 2)
186             ),
187             nn.Dropout(
188                 p=dropout
189             )
190         )

```

2. conv1 - conv3

由於layer操作相似，因此可以基於for loop來建立 conv1 - conv3 。

```

192         for index in range(1, len(self.deepconv)):
193             setattr(self, 'conv' + str(index), nn.Sequential(
194                 nn.Conv2d(
195                     in_channels=self.deepconv[index - 1],
196                     out_channels=self.deepconv[index],
197                     kernel_size=(1, 5),
198                     stride=(1, 1),
199                     padding=(0, 0),
200                     bias=True
201                 ),
202                 nn.BatchNorm2d(
203                     num_features=self.deepconv[index]
204                 ),
205                 activation_function(),
206                 nn.MaxPool2d(
207                     kernel_size=(1, 2)
208                 ),
209                 nn.Dropout(
210                     p=dropout
211                 )
212             ))

```

3. classify

```

214         flatten_size = self.deepconv[-1] * reduce(lambda x, _: round((x - 4) / 2), self.deepconv, 750)
215         self.classify = nn.Sequential(
216             nn.Linear(
217                 in_features=flatten_size,
218                 out_features=2,
219                 bias=True,
220             ),
221         )

```

4. forward

```

223 def forward(self, inputs: TensorDataset):
224     for index in range(len(self.deepconv)):
225         inputs = getattr(self, 'conv' + str(index))(inputs)
226
227         # Flatten
228         inputs = inputs.view(-1, self.classify[0].in_features)
229         inputs = self.classify(inputs)
230     return inputs

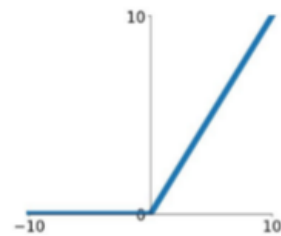
```

2. Explain the activation function

- ReLU

1. 介紹

ReLU
 $\max(0, x)$



為最常見的activation function。

2. 優點

- back-propagation過程運算簡單
- training過程不需要很多的computation。
- 相對Sigmoid不會saturate。
- 收斂數度快。

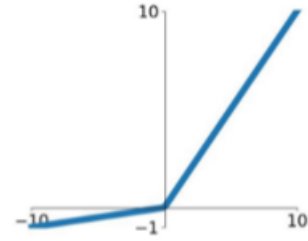
3. 缺點

- 當hidden layer output為0時，gradient為0，產生dead ReLU。

- Leaky ReLU

1. 介紹

Leaky ReLU

$$\max(0.1x, x)$$


2. 優點

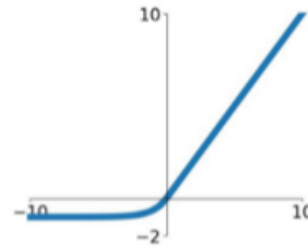
- 具有ReLU的所有特性。
- 改善ReLU的dead ReLU問題。

• ELU

1. 介紹

ELU

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



2. 優點

- 不具ReLU的dead ReLU問題。
- 比Leaky ReLU更接近0平均輸出。

3. 缺點

- 需更多的computation，原因是exponential function。

• Experiments Results (30%)

1. The highest testing accuracy

• EEG

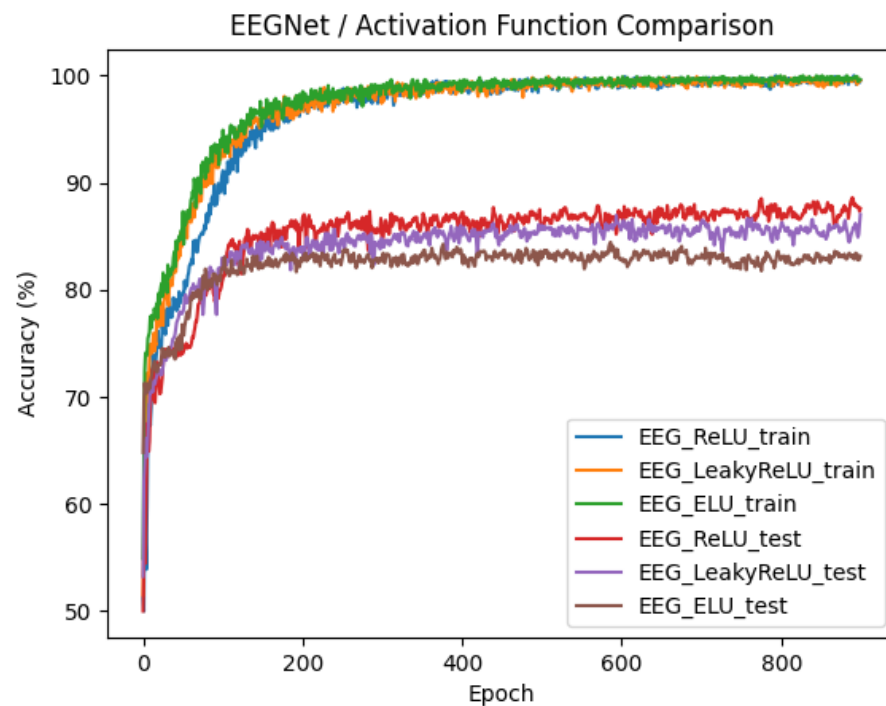
1. Parameters

- batch_size=1080
- learning_rate=0.005
- epoch=900
- optimizer: Adam
- loss_function: `torch.nn.CrossEntropyLoss()`

2. Accuracy

```
EEG_ReLU_train: 100.00 %  
EEG_LeakyReLU_train: 99.91 %  
EEG_ELU_train: 100.00 %  
EEG_ReLU_test: 88.61 %  
EEG_LeakyReLU_test: 87.04 %  
EEG_ELU_test: 84.44 %  
  
Process finished with exit code 0
```

3. Comparison figures



4. Discussion

在嘗試使用不同的 `batch_size` 後，發現當 `batch_size` 變大時，accuracy會變大，因此直接把 `batch_size` 調到最大的1080，得到87.78%的 accuracy。原因我認為是當 `batch_size` 變大時，所算的weight gradient是基於所有dataset，因此結果不會偏向每次batch的dataset。

- DeepConvNet

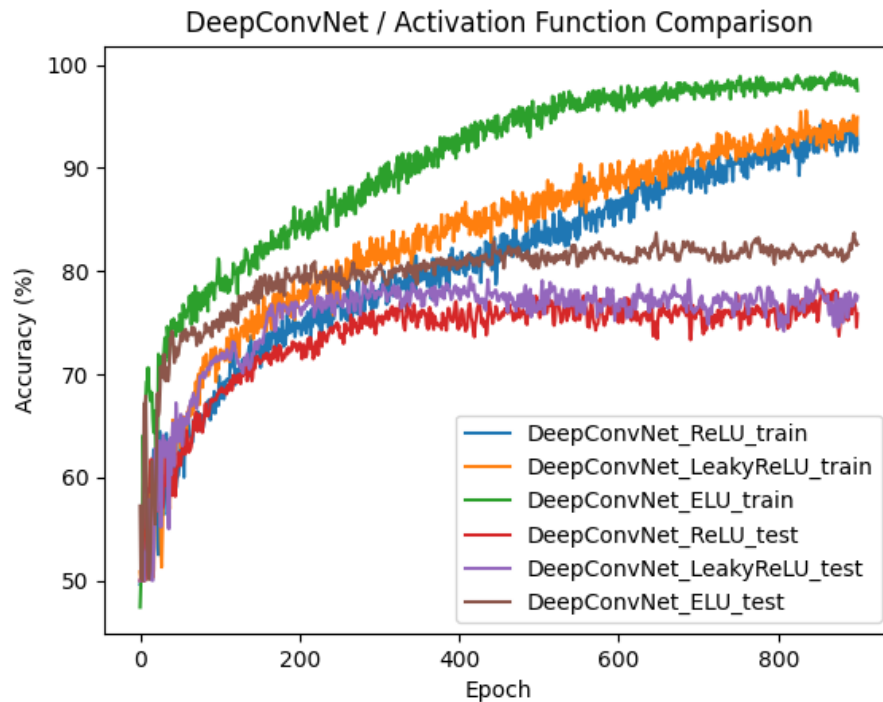
1. Parameters

- `batch_size=1080`
- `learning_rate=0.005`
- `epoch=900`
- `optimizer: Adam`
- `loss_function: torch.nn.CrossEntropyLoss()`

2. Accuracy

```
DeepConvNet_ReLU_train: 94.54 %  
DeepConvNet_LeakyReLU_train: 95.56 %  
DeepConvNet_ELU_train: 99.26 %  
DeepConvNet_ReLU_test: 78.24 %  
DeepConvNet_LeakyReLU_test: 79.44 %  
DeepConvNet_ELU_test: 83.70 %  
  
Process finished with exit code 0
```

3. Comparison figures



4. Discussion

嘗試利用與 EEGNet 相同的parameters，但結果並沒有 EEGNet 來的好。但從comparison figure的趨勢可看出，可能在給更多的epoch表現會更佳。

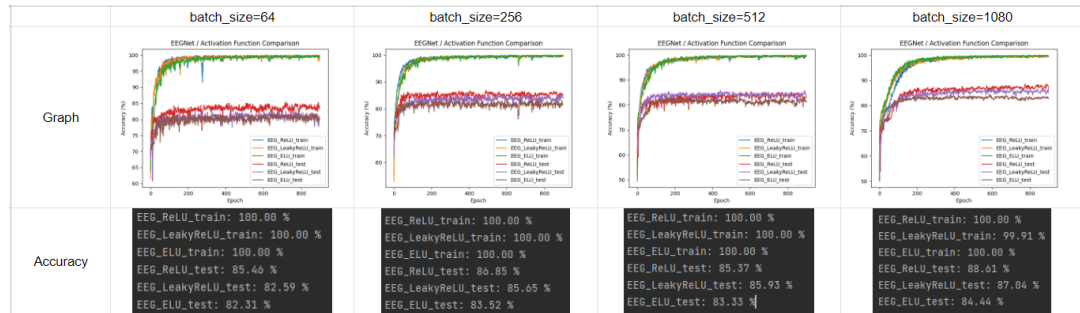
- Discussion (20%)

1. Try different batch size in EEGNet

- Parameters

1. learning_rate=0.005
2. epoch=900
3. optimizer: Adam
4. loss_function: `torch.nn.CrossEntropyLoss()`

- Results



- Discussion

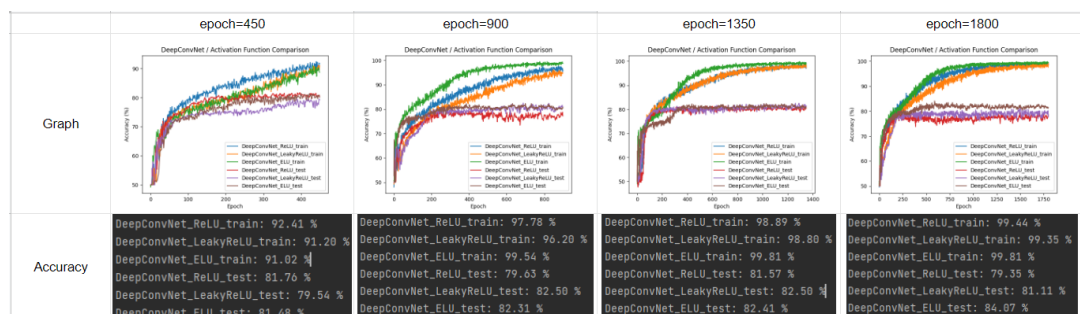
當 `batch_size` 上升時，會產生更好的accuracy，且收斂時間點差異不大，但實際上在 `batch_size` 256及512之間，差距並不大。

2. Try more epoch in DeepConvNet

- Parameters

1. `batch_size=1080`
2. `learning_rate=0.005`
3. optimizer: Adam
4. `loss_function: torch.nn.CrossEntropyLoss()`

- Results



- Discussion

當 `epoch` 上升時，對training data會產生更好的accuracy，但對testing data就不一定，可能變高也可能變低。

- Reference

1. https://www.youtube.com/watch?v=GMSjDTU8Zlc&ab_channel=CloudCasts-AlanSmith
2. <https://medium.com/@shrutijadon/survey-on-activation-functions-for-deep-learning-9689331ba092>