

Verified Synthesis of Components for Cyber Assurance

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I. CONTIGUITY TYPES

The formal specification of a component, and the synthesis of that specification, relies on *contiguity types* to define the input and output data [1]. A contiguity type is a self-describing specification for messages, and its formalism has basis in formal languages. Similar to how a regular expression implies a set of words that form its associated language, so does a contiguity type specification imply a set of messages for its language where a message is a finite sequence of contiguous bytes (e.g., a string).

What makes contiguity type specification more expressive than regular expressions is that it is self-describing meaning that the contents of the message itself may determine the rest of the message. An example is the following contiguity type specification for the message format of an AutomationResponse generated by a flight planner for a UAV.

```
{TaskID : i64
 Length : u8
 Waypoints : Waypoint[Length]
}
```

The Waypoints array size depends on the value of Length so the actual number of bytes in the message depends on the contents of the message itself.

The type specifications may also carry meta-information about the contents of the message.

```
{Latitude : float
 lt-rng : Assert (-90 <= Latitude <= 90)
 Longitude : float
 lng-rng : Assert (-180 <= Longitude <= 180)
 Altitude : float
 a-rng : Assert (10000 <= Altitude <= 15000)
}
```

Here the specification encodes the allowed ranges for each field of the waypoint. These assumptions restrict the resulting language to include only conforming messages and can be checked while constructing a message from a sequence of bytes. The notation $\mathcal{L}_\theta(\tau)$ denotes the language defined by the specification τ using the environment θ for expression evaluation.

Every contiguity type specification has a corresponding CakeML *matcher* that when given a message string returns

$$\begin{aligned}
 c &= \text{input } [(f : \tau) \dots] \\
 &\quad \text{output } [(f : \tau) \dots] \\
 &\quad \text{eq } [(f : \tau := \text{exp}) \dots] \\
 &\quad \text{guarantee } [(b\text{exp}) \dots] \\
 \\
 lval &= f \mid lval[\text{exp}] \mid lval.f \\
 \\
 f &= \text{varName} \\
 \\
 \text{exp} &= \text{Loc } lval \mid \text{nLit nat} \mid \text{constname} \\
 &\quad \mid \text{exp} + \text{exp} \mid \text{exp} * \text{exp} \\
 &\quad \mid (\text{exp} \rightarrow \text{exp}) \\
 &\quad \mid (\text{pre exp}) \\
 &\quad \mid (\text{ite } b\text{exp } \text{exp } \text{exp}) \\
 &\quad \mid b\text{exp} \\
 \\
 b\text{exp} &= \text{bLoc } lval \mid \text{bLit bool} \mid \neg b\text{exp} \mid b\text{exp} \wedge b\text{exp} \\
 &\quad \mid \text{exp} = \text{exp} \mid \text{exp} < \text{exp}
 \end{aligned}$$

Fig. 1. Syntax for high-assurance component specifications.

true or false if that message belongs to the language of the specification. If the message does belong to the language, an *environment* is provided to access each part of the message. An environment, $\theta : lval \mapsto \text{string}$ binds *L-values* to strings, where an L-value is an expression that can appear on the left hand side of an assignment (e.g., AutomationRequest.Waypoints[0].Latitude).

The main result of contiguity types is the proof of the relationship between the language of the specification and the synthesized matcher from the specification that is summarized below.

$$\text{match } s_1 s_2 = \text{SOME}(\theta, s_2) \Rightarrow \theta(\tau) \cdot s_2 = s_1 s_2 \wedge s_1 \in \mathcal{L}_\theta(\tau)$$

If there is a match on the substring s_1 , then reconstituting the string from the resulting environment and concatenating it with s_2 yields the original string, and the matched string s_1 is in the language of the type specification.

II. SEMANTICS

The specification language for a high-assurance component is in Fig. 1. A specification defines the inputs, outputs, local

values, and guarantees for each output. A type τ is a contiguity type, and $(f : \tau) \dots$ means zero or more repetition (e.g., Kleene star). An *lval* must eventually resolve to something that can be assigned. The expression language divides out Boolean expressions to simplify the semantics but is otherwise typical. The Loc and bLoc refer to the value of an *lval*, while nLit and bLit indicate a literal. The language includes the initialization (\rightarrow), pre, and if-then-else (ite) operators.

Change the following paragraph and preceding paragraphs to define the specification as the core language with a well defined normal form where expressions are flat, lvals are unique etc. It takes care of all the normal semantic checks related to types, dependency order, etc. Anything in the core language has normal form and is perfect.

The semantics are only defined for *well-formed* specifications. A specification is well-formed if and only if

- 1) Every *lval* is unique;
- 2) the eq list is in dependency order and the expressions are acyclic;
- 3) the associated *lval* with each Loc and bLoc expression is a valid reference in the environment;
- 4) the associated literal with each nLit and bLit has the correct type;
- 5) pre expressions do not refer past the beginning of the associated streams;
- 6) the expression list from guarantee exactly corresponds in size and order to the list from output; and
- 7) every expression in the list from guarantee defines its corresponding output value under all input combinations.

These checks are part of the synthesis but omitted to simplify the presentation.

An environment, $\theta : lval \mapsto \text{string}$ binds L-values to strings.

The well-formed assumption enables the use of a single global environment for the semantics. The semantics are synchronous data-flow on a single clock defined over a sequences of environments where θ^i is the i^{th} environment in the stream. Expression evaluation is defined in the context of this environment stream as shown in Fig. 2. Here, $\text{eval } i \ e$ carries with it the index of the environment to be used for the expression. $\Delta : \text{string} \rightarrow \mathbb{N}$ binds constant names to numbers. Functions $\text{toN} : \text{string} \rightarrow \mathbb{N}$ and $\text{toB} : \text{string} \rightarrow \text{bool}$ interpret byte sequences to numbers and booleans, respectively.

Each environment in the stream is initially partial meaning that it only contains mappings for the inputs. *Stepping* the specification updates the current environment and checks the invariance of the guarantees. In other words, at the i^{th} step, θ^i is updated with the result of the sequential evaluation of the eq-statements in the specification and then the guarantees are checked for invariance.

The notation $(lval \mapsto \text{slice}) \bullet \theta$ denotes the addition of binding $lval \mapsto \text{slice}$ to θ . Create an eval function for eq-statement. Map it to the list of statements. Create a similar function for the guarantees with its map that fails if invariance does not hold. Define the language of the specification using the contiguity notation. Need to munge all the types into a single τ , but the gist is the language is any finite stream

possible that conform to the input specification are the result of the eq-statements, and are invariant. The set is prefix closed (trace theory).

III. SYNTHESIS

Synthesis maps from model and specifications to code. The synthesis algorithm traverses the system architecture looking for occurrences of filter and monitor specifications; for each such occurrence it generates a CakeML program. In the following, we examine both filter and monitor synthesis. The latter is typically much more involved, and we will therefore devote more attention to it.

A. Filter Generation

A filter is intended to be simple, although it may make deep semantic checks. A filter has one input port and one output; messages on the input that the filter policy admits pass unchanged to the output port; all others are dropped (not passed on). We have investigated two kinds of filter. In the first, a relatively shallow scan of the input suffices to enforce the policy. For example, we have used the expressive power of Contiguity Types [1] to enforce *lightweight* bounds constraints on GPS coordinates in UxAS messages. On the other hand, a filter may need to parse the input buffer into a data structure specified in AGREE and apply a user-defined *wellformedness* property, also specified in AGREE, to the data. Arbitrarily complex wellformedness checks can be made in this way. Fig. 3 shows a combination where the checking specified by `WELL_FORMED_AUTOMATION_RESPONSE` depends on an underlying check specified by the contiguity type checking bounds on waypoints.

The verdict of a filter is made and performed within one thread invocation. Thus, in its given time slice, the following steps must be completed:

- 1) The filter checks to see if there is any input available. If there is none then it yields control; otherwise;
- 2) The input is read (and parsed if need be);
- 3) The wellformedness predicate is evaluated on the input;
- 4) If the predicate returns true then the input buffer is copied to the output, otherwise no action is taken; and
- 5) The filter yields control.

Remark 1 (Partiality). Partiality is an important consideration: steps 2 and 3 above can fail; the data might not be parseable or the wellformedness computation could be badly written and fail at runtime. In such cases, the filter should recover and yield control without passing the input onwards. In these cases, the filter is behaving as it should, but we must also guard against situations in which a *correctly specified* filter fails at runtime. This kind of defect arises when the filter *ought* to accept a message, but lack of resources results in the filter failing to do so. For example, the parse of a message might need more space than has been allocated; another example could be if the time slice provided by the scheduler is too short for the wellformedness computation to finish. Thus resource bounds need to be included in the correctness argument.

$$\begin{aligned}
\text{eval } i \ e = \text{case } e \quad & \left\{ \begin{array}{ll} \text{Loc } lval & \Rightarrow \text{toN}(\theta^i(lval)) \\ \text{nLit } n & \Rightarrow n \\ \text{constname} & \Rightarrow \Delta(\text{constname}) \\ e_1 + e_2 & \Rightarrow \text{eval } i \ e_1 + \text{eval } i \ e_2 \\ e_1 * e_2 & \Rightarrow \text{eval } i \ e_1 * \text{eval } i \ e_2 \\ e_1 \rightarrow e_2 & \Rightarrow \text{if } i = 0 \text{ then eval } i \ e_1 \text{ else eval } i \ e_2 \\ (\text{pre } e) & \Rightarrow \text{eval } i - 1 \ e \end{array} \right. \\
\\
\text{evalB } i \ b = \text{case } b \quad & \left\{ \begin{array}{ll} \text{bLoc } lval & \Rightarrow \text{toB}(\theta^i(lval)) \\ \text{bLit } b & \Rightarrow b \\ \neg b & \Rightarrow \neg(\text{evalB } i \ b) \\ b_1 \vee b_2 & \Rightarrow \text{evalB } i \ b_1 \vee \text{evalB } i \ b_2 \\ b_1 \wedge b_2 & \Rightarrow \text{evalB } i \ b_1 \wedge \text{evalB } i \ b_2 \\ e_1 = e_2 & \Rightarrow \text{eval } e_1 = \text{eval } i \ e_2 \\ e_1 < e_2 & \Rightarrow \text{eval } e_1 < \text{eval } i \ e_2 \end{array} \right.
\end{aligned}$$

Fig. 2. Expression evaluation in the context of a stream on environments.

```

Waypoint =
{Latitude : f64
 Longitude : f64
 Altitude : f32
 Check : Assert
 (~90.0 <= Latitude and Latitude <= 90.0 andp
 ~180.0 <= Longitude and Longitude <= 180.0 and
 1000.0 <= Altitude and Altitude <= 15000.0)}

AutomationResponse =
{TaskID : i64
 Length : u8
 Waypoints : Waypoint [3]}

fun WELL_FORMED_AUTOMATION_RESPONSE(aresp) =
(forall wpt in aresp.Waypoints, WELL_FORMED_WAYPOINT(wpt))
and ... ;

```

Fig. 3. Filter specification.

```

fun filter_step () =
let val () = Utils.clear_buf buffer
    val () = API.callFFI "get_input" "" buffer
in
if WELL_FORMED_AUTOMATION_RESPONSE buffer
then
API.callFFI "put_output" buffer Utils.emptybuf
else print"Filter rejects message.\n"
end

```

Fig. 4. Synthesized CakeML for the filter.

The contiguity type specification and wellformedness predicate for the filter are shown in Fig. 3 and the synthesized CakeML code is in Fig. 4. The code is called at dispatch by the scheduler. The `API.callFFI` is the link to the communication fabric to capture input and provide output. The body of the function restates the filter contract to make the appropriate assignments in a way that matches the truth value of the predicate in the filter guarantee. The auto-generated AGREE specification raises an alert output when the relation is violated.

B. Monitor Generation

Monitors are intended to track and analyze the externally visible behavior of system components through time. Therefore, they require more extensive computational ability than

filters. In particular, our basic notion of a monitor is that it embodies a predicate over its input and output streams, and is able to access the value of a stream at any earlier point in time, if necessary. Monitors commonly use state to keep track of earlier values, unlike filters which, for us, are typically stateless components. (However, there is nothing in our approach that forbids stateful filters: they can be realized by monitors.) A monitor specification is mapped by code generation to a state transformation function of the following abstract type:

$$\text{stepFn} : \text{input} \times \text{stateVars} \rightarrow \text{stateVars} \times \text{output}$$

The system scheduler *activates* components in some order. It is an obligation on the system that the scheduler follows some sensible partial order of component activation and allows each component sufficient time for its computation. Activating a monitor component takes the form of the following pseudo-code, in which the monitor evaluates the `stepFn` on its current inputs and the current values of the state variables, returning the new state and the output values.

```

(i1, ...) = readInputs();
(v1, ...) = readState();
(v1', ..., (o1', ...) = stepFn((i1, ...), (v1, ...));
writeState(v1', ...);
writeOutputs(o1'...);

```

1) *Initialization*: A monitor may need to accumulate a certain minimum number of observations before being able to make a meaningful assessment of behavior. Until that threshold is attained, the monitor is essentially in its *initialization* phase. In order for correct code to be generated, monitor specifications need to spell out the values of output ports when in their initialization phases. For example, suppose a monitor does some kind of differential assessment of inputs at adjacent time slices, alerting when (say) the measured location of a UAV at times t and $t+1$ is such that the distance between the two locations is unusually large. Such a monitor needs two

```

stepFn (Request,Response)
  (req,rsp,current,previous,policy,alert) =
let val stateVars' =
  if !initStep then
    let val req = event(Request)
    val rsp = event(Response)
    val current = (req = rsp)
    val previous = req and not(rsp)
    val policy = current or previous
    val alert = not policy
    val () = (intStep := False)
  in (req,rsp,current,previous,policy,alert)
  end
else
  let val req = event(Request)
  val rsp = event(Response)
  val current = (req = rsp)
  val previous = pre(req and not rsp) and (not req and rsp)
  val policy = current or previous
  val alert = (is_latched and pre(alert)) or not(policy)
  in (req,rsp,current,previous,policy,alert)
  end
val (_,rsp',_,_,_,alert') = stateVars'
val Alert = if alert' then Some () else None
val Output =
  if alert' then None else
  if rsp' then Some Response
  else None
in
  (stateVars', (Alert,Output))
end

```

Fig. 5. Synthesized CakeML for the monitor.

measurements before making its first judgement, but at the time of its first output, only one measurement will have been made. The specification must then explicitly state the correct value for the first output.

2) *Step function*: The stepFn works as follows:

- 1) Each input is parsed into data of the type specified by the port type;
- 2) New values for the state variables are computed, in dependency order. The discussion above on initialization now comes into play. Suppose the variable declarations have the following form:

$$\begin{aligned}
 v_1 &= i_1 \longrightarrow e_1 \\
 &\dots \\
 v_n &= i_n \longrightarrow e_n
 \end{aligned}$$

In the generated code, for the first invocation of stepFn only, the initializations are executed in order:

$$\begin{aligned}
 v_1 &= i_1; \\
 &\dots \\
 v_n &= i_n;
 \end{aligned}$$

In all subsequent steps, the *non-initialization* assignments are performed:

$$\begin{aligned}
 v_1 &= e_1; \\
 &\dots \\
 v_n &= e_n;
 \end{aligned}$$

- 3) Values of the outputs are computed;
- 4) Outputs are written and the new state is written;
- 5) The monitor yields control.

The stepFn for the monitor of the example described in Section ?? is displayed in Fig. 5.

C. Component Behavior

Intuitively, for monitor specification s , stepFn is the concrete embodiment of SynthEval s , as defined in Section ?? . Its correctness amounts to showing that, given a sequence of inputs, and an initial state meeting the initialization constraints, iterating stepFn produces a π s.t. $\pi \in \mathcal{L}(s)$; and taking the union over all input sequences and initial states produces $\mathcal{L}(s)$ itself.

REFERENCES

- [1] K. L. Slind, “Specifying message formats with Contiguity Types,” in *Proceedings of the Twelfth International Conference on Interactive Theorem*

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