University of Illinois

Spring 2020

CS 446/ECE 449 Machine Learning Homework 6: Structured Prediction

Due on Thursday March 12 2020, noon Central Time

1. [28 points] Structured Prediction

We are interested in jointly predicting/modeling two discrete random variables $y = (y_1, y_2) \in \mathcal{Y}$ with $y_i \in \mathcal{Y}_i = \{0, 1\}$ for $i \in \{1, 2\}$ and $\mathcal{Y} = \prod_{i \in \{1, 2\}} \mathcal{Y}_i$. We define the joint probability distribution to be $p(y) = p(y_1, y_2) = \frac{1}{Z} \exp F(y)$.

(a) (3 points) What is the value of Z (in terms of F(y)) and what is Z called? How many configurations do we need to sum over? Provide the expression using \mathcal{Y}_i .

Solution:

(partition function/normalization constant) $Z = \sum_{y \in \mathcal{Y}} \exp F(y)$

Number of summands: $\prod_{i \in \{1,2\}} |\mathcal{Y}_i|$

(b) (6 points) Next we want to solve (for any hyperparameter ϵ)

$$\max_{\hat{p} \in \Delta_{\mathcal{Y}}} \sum_{y \in \mathcal{Y}} \hat{p}(y) F(y) - \sum_{y \in \mathcal{Y}} \epsilon \hat{p}(y) \log \hat{p}(y), \tag{1}$$

where $\Delta_{\mathcal{Y}}$ denotes the probability simplex, *i.e.*, \hat{p} is a valid probability distribution over its domain \mathcal{Y} . Using general notation, write down the Lagrangian and compute its derivative w.r.t. $\hat{p}(y) \ \forall y \in \mathcal{Y}$. Subsequently, find the optimal \hat{p}^* . What is the resulting optimal cost function value for the program given in Eq. (1)? How does this result relate to part (a)?

Solution:

Lagrangian:

$$L(1) = \sum_{y \in \mathcal{Y}} \hat{p}(y)F(y) - \sum_{y \in \mathcal{Y}} \epsilon \hat{p}(y) \log \hat{p}(y) + \lambda \left(1 - \sum_{y \in \mathcal{Y}} \hat{p}(y)\right)$$

Derivative:

$$\frac{\partial L}{\partial \hat{p}(y)} = F(y) - \epsilon - \epsilon \log \hat{p}(y) - \lambda$$

Optimal solution:

$$\hat{p}^*(y) = \frac{\exp F(y)/\epsilon}{\sum_{\hat{y} \in \mathcal{Y}} \exp F(\hat{y})/\epsilon}$$

Optimal cost function value:

$$\epsilon \log \sum_{\hat{y} \in \mathcal{Y}} \exp F(\hat{y}) / \epsilon$$

For $\epsilon = 1$ optimal value equals $\log Z$

(c) (3 points) For the program in Eq. (1) assume now $\epsilon = 0$, *i.e.*, we are searching for that configuration $y^* = \arg \max_{\hat{y} \in \mathcal{Y}} F(\hat{y})$ which maximizes F(y). Assume $F(y) = f_1(y_1) + f_2(y_1) + f_3(y_2) = f_3(y_1) + f_3(y_2) = f_3$

 $f_2(y_2) + f_{1,2}(y_1, y_2)$. How many different values can the functions f_1 , f_2 and $f_{1,2}$ result in?

Solution:

 $f_1 : |\mathcal{Y}_1|$ $f_2 : |\mathcal{Y}_2|$ $f_{1,2} : |\mathcal{Y}_1||\mathcal{Y}_2|$

(d) (9 points) As discussed in class, finding the global maximizer can be equivalently written as the following integer linear program:

$$\max_{b} \sum_{r, y_r} b_r(y_r) f_r(y_r) \qquad \text{s.t.} \qquad \begin{cases} b_r(y_r) \in \{0, 1\} & \forall r, y_r \\ \sum_{y_r} b_r(y_r) = 1 & \forall r \\ \sum_{y_p \setminus y_r} b_p(y_p) = b_r(y_r) & \forall r, p \in P(r), y_r \end{cases}$$
 (2)

Using the decomposition $F(y) = f_1(y_1) + f_2(y_2) + f_{1,2}(y_1, y_2)$, i.e., for $r \in \{\{1\}, \{2\}, \{1, 2\}\}\}$, explicitly state the integer linear program and all its constraints for the special case that $\mathcal{Y}_i = \{0, 1\}$ for $i \in \{1, 2\}$. (**Hint:** The parent sets are as follows: $P(\{1\}) = \{1, 2\}$ and $P(\{2\}) = \{1, 2\}$. Use notation such as $f_1(y_1 = 0)$ and $f_2(y_1 = 0)$.)

Solution:
$$\max_{b} \quad b_{1}(y_{1}=0)f_{1}(y_{1}=0) + b_{1}(y_{1}=1)f_{1}(y_{1}=1) + b_{2}(y_{2}=0)f_{2}(y_{2}=0) + b_{2}(y_{2}=1)f_{2}(y_{2}=1) + b_{1,2}(y_{1}=0,y_{2}=0)f_{1,2}(y_{1}=1,y_{2}=0) + b_{1,2}(y_{1}=1,y_{2}=0) + b_{1,2}(y_{1}=1,y_{2}=1) + b_{1,2}(y_{1}=0,y_{2}=1)f_{1,2}(y_{1}=1,y_{2}=1) + b_{1,2}(y_{1}=1,y_{2}=1) + b_{1,2}(y_{1}=1,y_{2}=1) + b_{1,2}(y_{1}=1,y_{2}=1) + b_{1,2}(y_{1}=0,y_{2}=1) \in \{0,1\}, b_{1,2}(y_{1}=1,y_{2}=0) \in \{0,1\}, b_{1,2}(y_{1}=1,y_{2}=1) \in \{0,1\}, b_{1,2}(y_{1}=1,y_{2}=1\} \in \{0,1\}, b_{1,2}(y_{1}=1,y_{2}=1,y_{2}=1) \in \{0,1\}, b_{1,2}(y_{1}=1,y_{2}=1,y_{2}=1\} \in \{0,1\}, b_{1,2}(y_{1}=1,y$$

(e) (3 points) Let b be the vector

$$b = [b_1(y_1 = 0), b_1(y_1 = 1), b_2(y_2 = 0), b_2(y_2 = 1), b_{1,2}(y_1 = 0, y_2 = 0), b_{1,2}(y_1 = 1, y_2 = 0), b_{1,2}(y_1 = 0, y_2 = 1), b_{1,2}(y_1 = 1, y_2 = 1)]^{\top}.$$

Specify all but the integrality constraints of part (d) using matrix vector notation, *i.e.*, provide A and c for Ab = c.

Name:

Solution:

$$A = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & -1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 & 1 \end{bmatrix} \quad \text{and} \quad c = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

(f) (4 points) Complete A6_Structure.py where we approximately solve the integer linear program using the linear programming relaxation. Implement the constraints. Why do we provide -f as input to the solver? What is the obtained result b for the relaxation of the program given in Eq. (2) and its cost function value? Is this the configuration y^* which has the largest score?

Solution:

Solver solves a minimization problem rather than a maximization.

Cost function value: 5

This is the largest possible score for the given f