100MSps oscilloscope with RP2040

En este artículo mostraré el diseño de un osciloscopio basado en el microcontrolador RP2040 de Raspberry. Este osciloscopio utiliza un ADC08100 que es un conversor de 8bits capaz de funcionar a una freq máxima de 100MHz. La caracteristica principal de este diseño es poder utilizar el propio microcontrolador para controlar el ADC, gracias a la potencia de un periferico especial del microcontrolador llamado PIO.

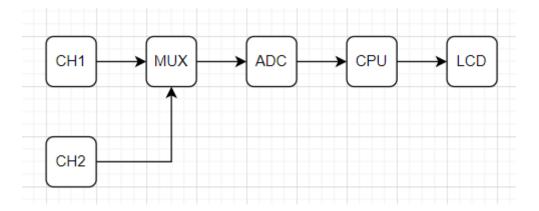
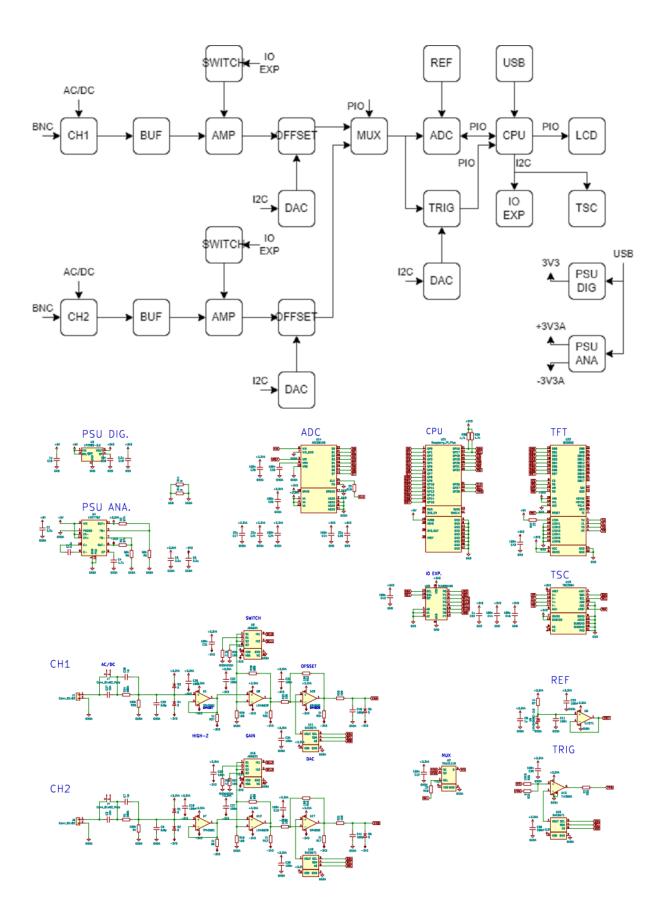
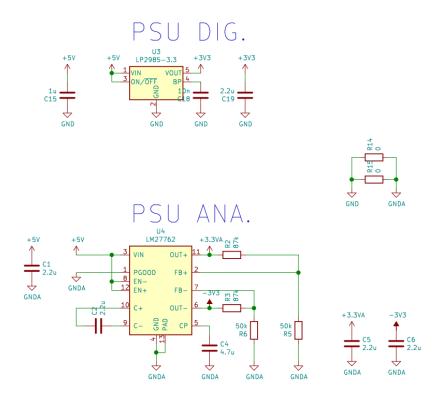
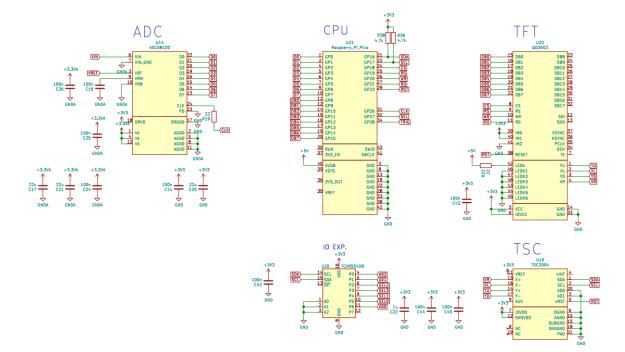
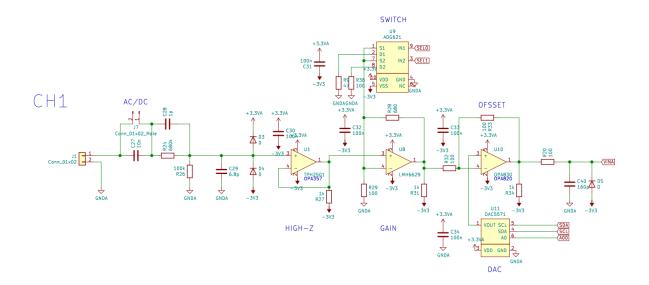


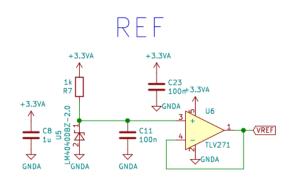
Diagrama general

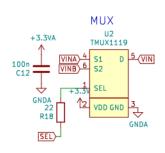


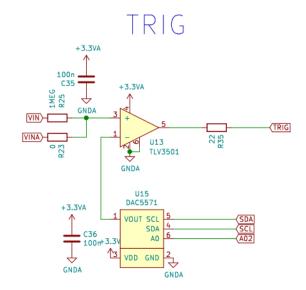


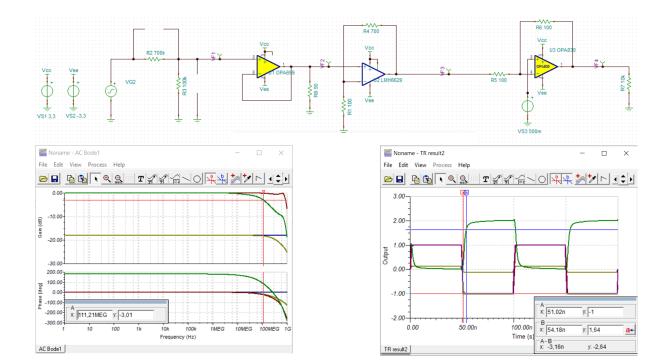


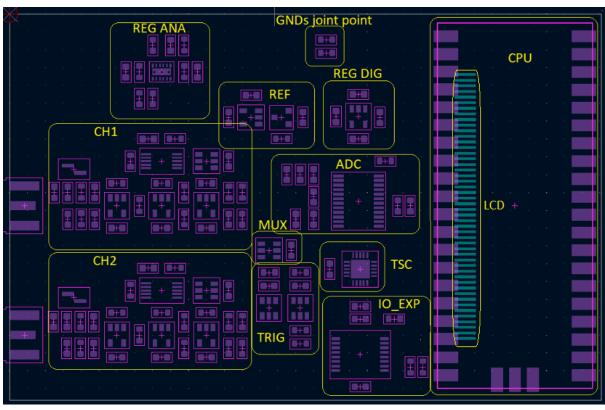


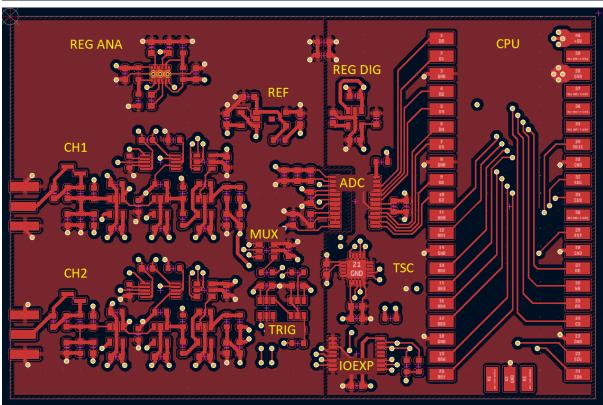


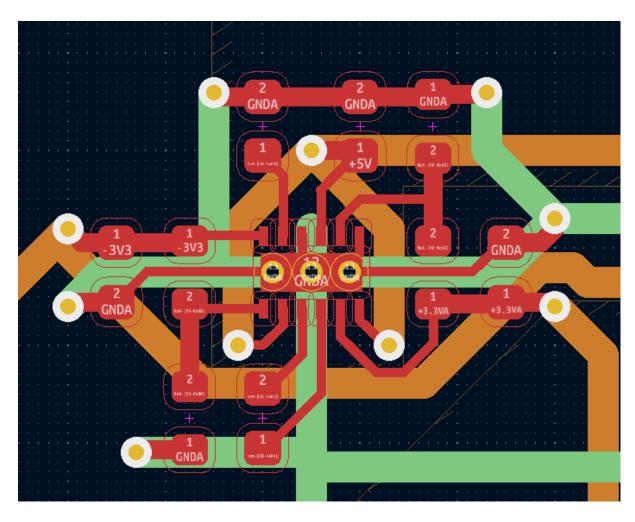


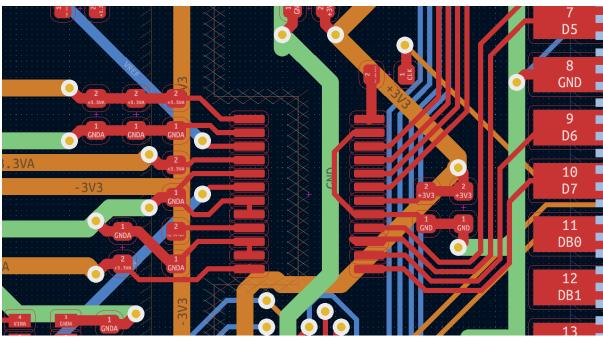


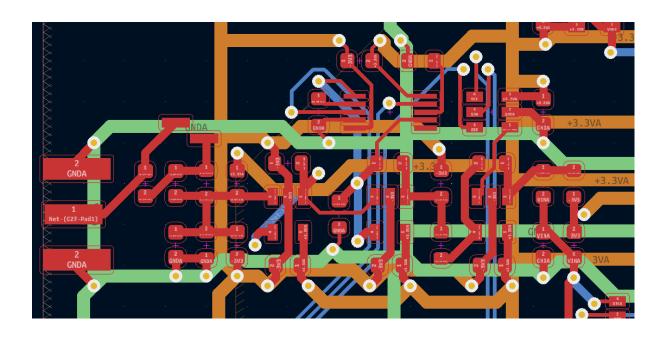


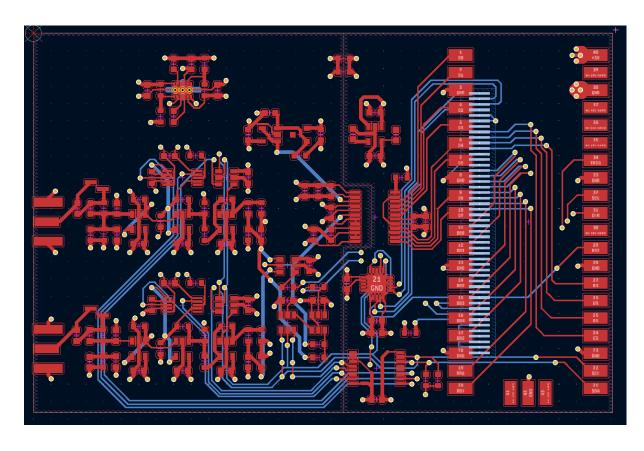


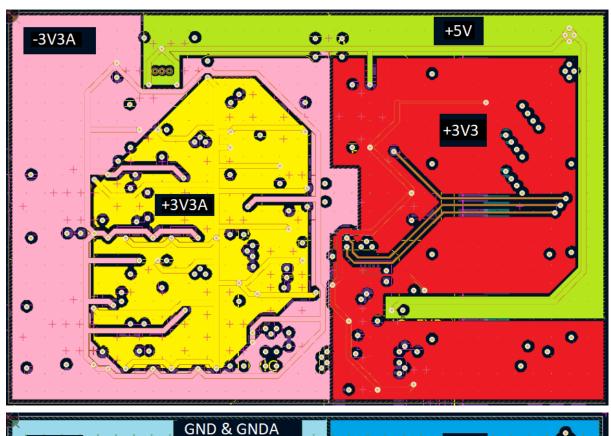


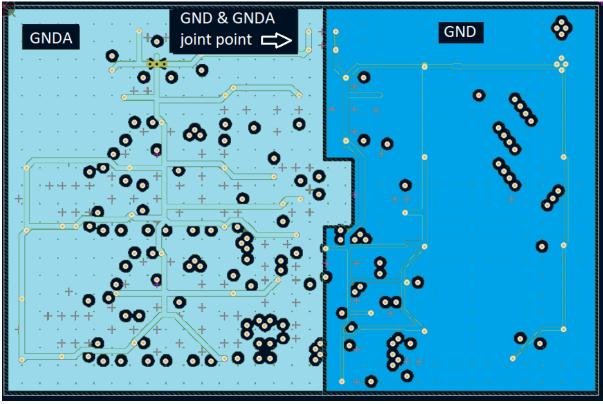


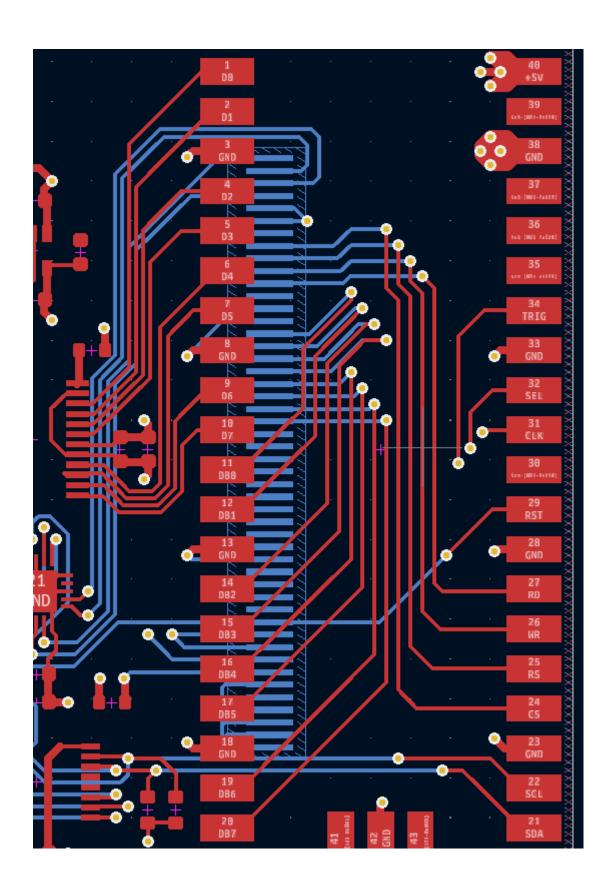


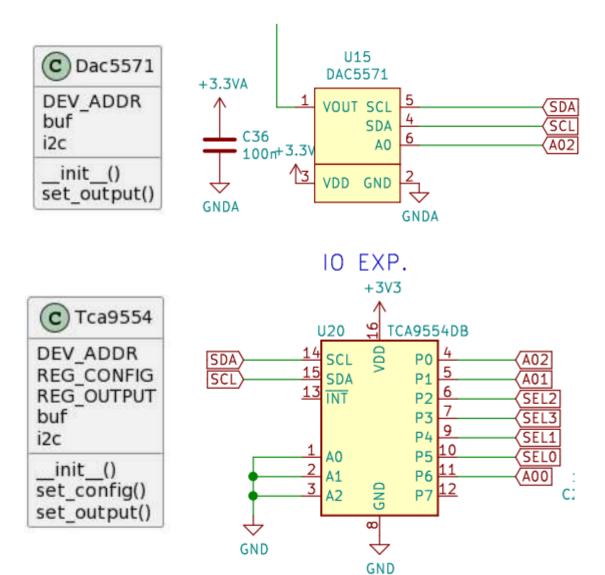


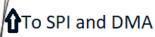


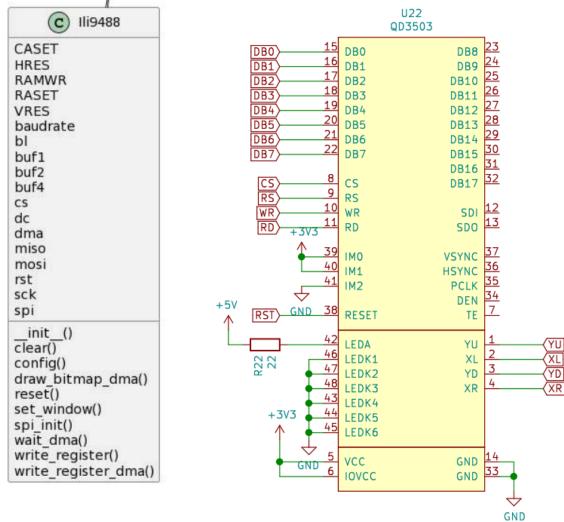




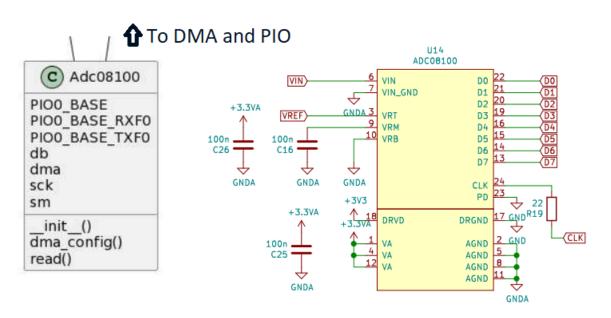








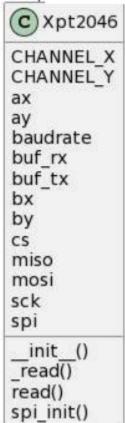
```
class Ili9488:
· · · · · HRES · = · 480
· · · · VRES · = · 320
\cdot \cdot \cdot \cdot \cdot \text{CASET} \cdot = \cdot 0 \times 2 \text{A}
\cdot \cdot \cdot \cdot RASET \cdot = \cdot 0x2B
\cdot \cdot \cdot \cdot RAMWR \cdot = \cdot 0 \times 2C \cdot
 def init (self, baudrate, cs, sck, mosi, miso, dc, rst, bl):
····def·reset(·self·):
····def·spi init(·self·):
····def·write register(·self,·reg,·buf·):
····def·write register dma(·self, reg, buf, is blocking=True·):····
····def·wait dma(·self·):
· · · · def · config ( · self · ):
····def·set window(·self,·x,·y,·w,·h·):
····def·draw_bitmap_dma(.self, x, y, w, h, buf, is_blocking=True):
·····self.set window(·x,·y,·w,·h·)
.....self.write register dma(.Ili9488.RAMWR, buf, is blocking.)
····def·clear(·self,·color·):
```

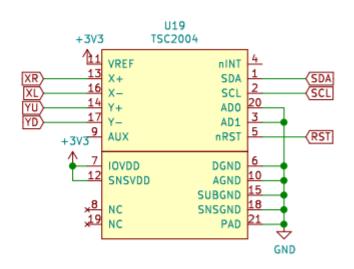


```
@rp2.asm pio(
sideset init = (rp2.PIO.OUT HIGH, rp2.PIO.OUT HIGH),
····in shiftdir = rp2.PIO.SHIFT LEFT,
def · build sm adc08100():
\cdot \cdot \cdot \cdot \cdot in (\cdot pins, \cdot 8 \cdot) \cdot .side(\cdot 0b0 \cdot)
\cdotspush(\cdotblock\cdot)\cdotsside(\cdot0b1\cdot)
@rp2.asm pio(
def · build sm adc08100 trigger():
class Adc08100:
····PIO0 BASE·····=·0x50200000
····PIO0 BASE TXF0·=·PIO0 BASE·+·0x10
····PIO0 BASE RXF0·=·PIO0 BASE·+·0x20
....def init (.self, sps, sck, db, use trigger=False):
····def·dma config(·self, buf, count, ring size pow2=0·):
····def·read(·self, buf, dma config=True·):
·····if( dma config ):
.....self.dma config(.buf,.len(buf).)
....self.dma.enable()
·····self.sm.active(·True·)
.....while(.self.dma.is busy().):
....pass
·····self.sm.active(·False·)
.....self.dma.disable()
```

```
@rp2.asm pio()
def · build_sm_trigger_rising():
····label(·"prog_trigger"·)
····pull(·block·)
····mov(·y,·osr·)
····pull(·block·)
····mov(·x,·osr·)
\cdotsirq(\cdot 4\cdot)
····label(·"loop y dec"·)
· · · · nop ()
····jmp(·y_dec, ·"loop_y_dec"·)
\cdots wait (\cdot0, \cdotpin, \cdot0\cdot)
\cdots wait (·1, ·pin, ·0·)
····label(·"loop x dec"·)
· · · · nop ()
····jmp(·x dec, · "loop x dec" ·)
····push(·block·)
· · · · nop () [4]
····irq(·block,·1·)
····jmp(·"prog trigger"·)
@rp2.asm pio()
def build sm trigger falling():
class Trigger:
....def init (.self,.sps,.trig,.rising.):
····def·read(·self, ·pre, ·post, ·addr stop·):
....self.dma.config(
. . . . . . . . ) . .
....self.sm.put(.pre.)
····self.sm.put(.post.)
.....self.dma.enable()
....self.sm.active(.True.)
....while(.self.dma.is_busy().):
....pass
.....self.sm.active(.False.)
.....self.dma.disable()
```

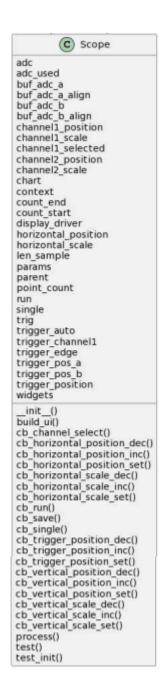
↑ To I2C



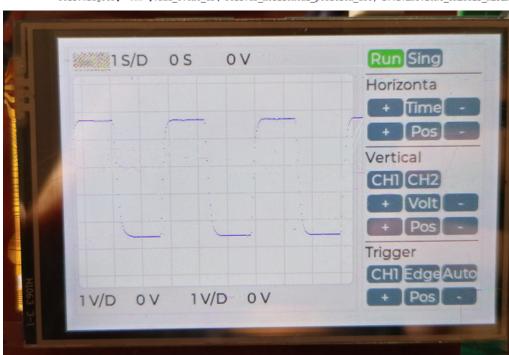


```
class Xpt2046:
\cdots CHANNEL X = 0x90
\cdot \cdot \cdot \cdot \cdot \text{CHANNEL } Y \cdot = \cdot 0 \times D0
\cdot \cdot \cdot \cdot \cdot def \cdot init \quad (\cdot self, \cdot baudrate, \cdot cs, \cdot sck, \cdot mosi, \cdot miso, \cdot ax=1, \cdot bx=0, \cdot ay=1, \cdot by=0 \cdot):
···def·spi init(·self·):
····def· read(·self·):
\cdots def · read ( · self · ):
....xacc⋅=⋅0
....yacc⋅=⋅0
\cdots \cdots for \cdot i \cdot in \cdot range (\cdot 4 \cdot):
·························x,·y·=·self. read()
\cdots \cdots if(x \cdot and \cdot y \cdot):
....xacc.+=.x
.....yacc.+=.y
····else:
....return · 0 , · 0
\cdots x \cdot = \cdot xacc/4
· · · · · · · · y · = · yacc/4
\cdots x = self.ax*x + self.bx
·····y·=·self.ay*y·+·self.by
\cdots \cdots return \cdot int(\cdot x \cdot), \cdot int(\cdot y \cdot)
```

```
class DMA:
    ·DMA BASE · · = · 0x50000000
    \cdot DMA EN \cdot \cdot \cdot \cdot = \cdot 0 \times 01 \cdot << \cdot 0
....HIGH_PRIO = .0x01 .<< 1
....INCR_READ = .0x01 .<< 4
....INCR_WRITE= .0x01 .<< 5
... DREQ_PIOO_RXO = 0x04 << 15
... DREQ_PIOO_RX1 = 0x05 << 15
... DREQ_SPI1_TX = 0x12 << 15
···· DREQ_PERMANENT= · 0x3F · << · 15
···· IRQ_QUIET ·= · 0x01 · << · 21
···· BUSY ···· = · 0x01 · << · 24
CHAIN_TO_POS = 0x0B
 ····RING_SIZE_POS=·0x06
····def·
             init ( self, channel number ):
  ···def·config('self,'src_addr,'dst_addr,'count,'src_inc,'dst_inc,'trig_dreq,'ring_sel=False,'ring_size_pow2=0.):
 .....machine.mem32[.self.CHx_CTRL_TRIG.]...=.0
machine.mem32[self.CHx_READ_ADDR:] = src_addr
machine.mem32[self.CHx_WRITE_ADDR:] = dst_addr
machine.mem32[self.CHx_TRANS_COUNT:] = count
·····trig_val·=·0
 .....if(.src_inc.):
             · trig_val |= DMA.INCR_READ
.....if(.dst inc.):
....trig_val |= DMA.INCR_WRITE
.....trig_val.|=.self.channel_number.<<.DMA.CHAIN_TO_POS
....trig_val.|=.ring_sel.<<.DMA.RING_SEL_POS
trig_val | = ring_size_pow2 << DMA.RING_SIZE_POS trig_val | = trig_dreq
......machine.mem32[.self.CHx_CTRL_TRIG.]...=.trig_val
    def enable(self):
   ··def·disable(·self·):
    .def · is busy( · self ·):
```



```
def build_ui( self, parent):
 ·width -= - 160
 ·point_count ·= · 480-width
 ...self.context.append(.parent.)
 ...set_context( self.context)
...set_widgets( self.widgets)
····with·Cont():
   with Cont(0,0,0,480-width,320-15):
....with Column():
     .....lblw=.74
.....with.Row():
.....self.chart = lv.chart( self.context[-1] )
self.chart.set_div_line_count(.8,.10.)
.....add_line(.0,.2,.120+2*4,.1.)
.....add_label(."Horizontal",.w=100.)
.....with Row():
        .....with.Row():
```



```
import · lvgl · as · lv
class Display Driver:
····def· init (·self, width, height, lcd, tsc, fb rows=64·):
····def·init gui(·self·):
.....lv.init()
.....self.fbl = bytearray( self.width*self.fb_rows)
.....self.fb2 = bytearray( self.width*self.fb_rows)
print(\"len(\fb1\cdot)\", \len(\fb1\cdot)\delta)
print(\"len(\fb2\cdot)\", \len(\foself.fb1\cdot)\delta)
.....print(."disp draw buf t()".)
.....self.disp_draw_buf.=.lv.disp_draw_buf_t()
.....self.disp_draw_buf.init(.self.fb1,.self.fb2,.len(.self.fb1.)//lv.color_t.SIZE.)
·····print(·"disp_drv_t()"·)
.....self.disp drv = lv.disp drv t()
.....self.disp_drv.init()
.....self.disp_drv.draw_buf = self.disp_draw_buf
.....self.disp_drv.flush_cb = self.disp_drv_flush_cb
.....self.disp_drv.hor_res = self.width
....self.disp_drv.ver_res = self.height
.....self.disp_drv.register()
.....print(\"indev_drv_t()"\)
....self.indev_drv = lv.indev_drv_t()
.....self.indev_drv.init()
.....self.indev_drv.type = lv.INDEV_TYPE.POINTER
.....self.indev_drv.read_cb = self.indev_drv_read_cb
.....self.indev_drv.register()
....def disp_drv_flush_cb(.self, disp_drv, area, color):
....#print(."disp_drv_flush_cb", area.x1, area.x2, area.y1, area.y2.)
.....if( self.dma running == True ):
....self.lcd.wait_dma()
.....self.dma_running = False
.....if(.self.is_fbl.):
.....fb = memoryview( self.fb1 )
····else:
           · · fb · = · memoryview ( · self.fb2 · )
····self.is_fbl·=·not·self.is_fbl
....x.=.area.x1
····y·=·area.y1
.....w.=.area.x2.-.area.x1.+.1
.....h = area.y2 - area.y1 + 1
.....self.lcd.draw_bitmap_dma(.x,.y,.w,.h,.fb[0:w*h*lv.color_t.SIZE],.is_blocking=False.)
....self.dma running = True
.....disp_drv.flush_ready()
 ···def·indev drv read cb(·self, ·indev drv, ·data·):
```

```
import lvgl as lv
context -= []
widgets = {}
def · set context(·ctx·):
def · get context():
def · set widgets(·wgts·):
def · get widgets():
style = lv.style t()
style.init()
style.set pad all(\cdot 2 \cdot)
style.set_pad_gap(.2.)
style.set_radius(.2.)
style.set border width (.0.)
style.set bg color( lv.palette lighten( lv.PALETTE.GREY, 3))
class Cont:
 \frac{\text{def} \cdot \text{init}}{\text{self}, \text{vx=5}, \text{vy=5}, \text{w=480-10}, \text{h=320-10}} : \\ \cdots \cdots \text{self.obj} \cdot \text{=-lv.obj} (\cdot \text{context[-1]} \cdot) 
....self.obj.add_style(.style,.0.)
.....#self.obj.set flex flow(.lv.FLEX FLOW.COLUMN.)
·····self.obj.set pos(·x,·y·)
.....self.obj.set_size(.w,.h.)
\cdots #if(\cdot\context\cdot) \cdot=\cdot3\cdot):
·····self.obj.set_style_border_width(·0,·0·)
\cdots def \cdot __enter__(\cdot self \cdot):
.....context.append(.self.obj.)
....return self.obj
····def· exit (·self,·a,·b,·c·):
.....context.pop()
class Column:
class Row:
def add button( name, w=40, h=20, radius=5, checkable=False):
def · add spinbox ( · name , · w=100 , · h=40 · ) :
def \cdot add \ label(\cdot name, \cdot w=40, \cdot h=20 \cdot):
def \cdot add line(\cdot x=0, \cdot y=0, \cdot w=40, \cdot h=1, \cdot width=1\cdot):
```

```
def · capture ( · sps, · buf, · rising, · pre, · post · ):
\cdots db \cdot =  machine. Pin (\cdot 0 \cdot) \cdot # \cdot  out
\cdot \cdot \cdot \cdot \operatorname{sck} \cdot = \cdot \operatorname{machine.Pin} (\cdot 21 \cdot) \cdot \# \cdot \operatorname{side} \cdot 0
\cdots mux = machine.Pin(\cdot20\cdot) \cdot# side \cdot0
trig = machine.Pin(.7, machine.Pin.IN, machine.Pin.PULL_DOWN.) # trigger
#trig = machine.Pin(19, machine.Pin.IN, machine.Pin.PULL DOWN) # trigger
buf addr aligned = (uctypes.addressof(buf)+0xFF)&0xFFFFFF00
buf offset aligned = buf addr aligned - uctypes.addressof(buf)
····t0·=·time.ticks us()
····adc·=·Adc08100(·sps,·mux,·db,·use trigger=True·)
····t1·=·time.ticks us()
····t0·=·time.ticks us()
....adc.dma.config(
.....Adc08100.PIO0 BASE RXF0,
.....buf addr aligned,
·····OxFFFFFFF,
....src_inc=False,
.....dst inc=True,
.....trig dreq=DMA.DREQ PIO0 RX0,
·····ring sel=True,
·····ring size pow2=8
. . . . )
····t1·=·time.ticks us()
····t0·=·time.ticks us()
....adc.dma.enable()
····adc.sm.active( True )
····t1·=·time.ticks us()
····t0·=·time.ticks_us()····
trigger = Trigger( sps, trig, rising)
····t1·=·time.ticks_us()
\cdot \cdot \cdot \cdot \cdot DMA1 TRIG \cdot = \cdot 0x500000000 \cdot + \cdot 1 \cdot * \cdot 0x40 \cdot + \cdot 0x0C
····t0·=·time.ticks_us()····
····trans count0 = machine.mem32[ adc.dma.CHx TRANS COUNT ]
····trigger.read(.pre,.post,.DMA1_TRIG.)
....trans count1 = machine.mem32[ adc.dma.CHx TRANS COUNT ]
····t1·=·time.ticks us()
····t0·=·time.ticks us()····
····adc.dma.disable()
····adc.sm.active( False )
····t1·=·time.ticks us()
····trans count diff.=.trans count0.-.trans count1.#.-.1
····trans count diff.= trans count diff&0xFF
···· return buf offset aligned, trans count diff
```