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## Lecture 9: Least Squares Estimation using Matrices STAT 632, Spring 2020

## Mathematical Preliminaries

Let

$$heta = egin{pmatrix} heta_1 \\ heta_2 \\ \vdots \\ heta_n \end{pmatrix}$$

be an  $n \times 1$  vector, and  $f(\theta)$  a scalar function of  $\theta$ . The derivative of  $f(\theta)$  with respect to the vector  $\theta$  is defined as

 $R(\beta) = Y'Y - Y'X\beta - (X\beta)'Y + (X\beta)'(X\beta)$ 

= V'V - 2V'XB + B'X'XB

 $\hat{g} = (X'X)^{-1}X'Y$ 

$$\frac{\partial f(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = \begin{pmatrix} \frac{\partial f(\boldsymbol{\theta})}{\partial \theta_1} \\ \frac{\partial f(\boldsymbol{\theta})}{\partial \theta_2} \\ \vdots \\ \frac{\partial f(\boldsymbol{\theta})}{\partial \theta_n} \end{pmatrix}$$

Recall from calculus two important rules of differentiation for a scalar a and variable x:

1. 
$$\frac{d}{dx}ax = a$$

$$2. \ \frac{d}{dx}ax^2 = 2ax$$

There are similar rules when taking a derivative with respect to a vector:

1. Let 
$$c' = (c_1 \ c_2 \ \cdots \ c_n)$$
 and  $f(\theta) = c'\theta$ , then it follows that

Nexts to had the least squares estimates, we minimize 
$$E(\beta)$$
 by taking the derive  $(\theta) \frac{1}{2} \frac{1}{2$ 

2. Let A be an  $n \times n$  symmetric matrix and  $f(\theta) = \theta' A \theta$ , then it follows that

$$rac{\partial f(oldsymbol{ heta})}{\partial oldsymbol{ heta}} = 2oldsymbol{A}oldsymbol{ heta}$$

Your turn: Prove the first rule for vector differentiation.

$$\frac{\partial f(\theta)}{\partial \theta} = \left(\frac{\partial f(\theta)}{\partial f(\theta)}\right) / \frac{\partial \theta}{\partial \theta} = \left(\frac{c_1}{c_2}\right)^2 = \left(\frac{c_1}{$$

Recall the matrix notation for multiple linear regression (MLR):

$$Y = X\beta + e$$

Your turn: What are the dimensions of each term?

$$Y=2n\times 1$$
  $\beta=(p+1)\times 1$   $X=2n\times (p+1)$   $C=2n\times 1$ 

For MLR, the residuals sum of squares, as a function of the vector  $\boldsymbol{\beta}$ , can be written in matrix notation as

be an 
$$n \times 1$$
 vector, and  $f(\theta)$  a scalar function of  $f$ . The derivative of  $f(\theta)$  with respect to the vector  $\theta$  is defined as 
$$\left(\beta(X-Y) \left( \beta(X) - \gamma \right) \left( \beta(X) - \gamma \right) \right) = R(\beta) = R(\beta) + R(\beta) + R(\beta) = R(\beta) + R(\beta) + R(\beta) + R(\beta) = R(\beta) + R(\beta) + R(\beta) + R(\beta) = R(\beta) + R$$

Expanding this equation out gives:

$$R(\beta) = Y'Y - Y'X\beta - (X\beta)'Y + (X\beta)'(X\beta)$$

$$= Y'Y - Y'X\beta - \beta'X'Y + \beta'X'X\beta$$

$$= Y'Y - 2Y'X\beta + \beta'X'X\beta$$

$$= Y'Y - 2Y'X\beta + \beta'X'X\beta$$

$$= Y'Y - 2Y'X\beta + \beta'X'X\beta$$

Your turn: Argue that  $Y'X\beta = \beta'X'Y$ , so the terms can be combined.

$$Y' \times \beta$$
 $Y' \times \beta = (Y' \times \beta) = (\times \beta)'Y = \beta' \times Y'$ 
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Next, to find the least squares estimates, we minimize  $R(\beta)$  by taking the derivative, with respect to the vector  $\beta$ , and setting the derivative equal to zero. Since X'X is a symmetric matrix, we can use the two rules for vector differentiation to accomplish this.

$$\frac{\partial R(\beta)}{\partial \beta} = 0 - 2X'Y + 2X'X\beta$$

$$\frac{\partial R(\beta)}{\partial \beta} = 0 - 2X'Y + 2X'X\beta$$

$$\frac{(p+1)\times n \times 1}{(p+1)\times 1} \qquad \frac{(p+1)\times n \times$$

Setting the derivative equal to zero gives the normal equations for MLR:

$$X'X\beta = X'Y$$

Assuming that X'X is invertible, the vector of least squares estimates is given by

$$\hat{\beta} = (X'X)^{-1}X'Y$$

$$\frac{\partial}{\partial \beta} = (X'X)^{-1}X'Y$$

$$\frac{\partial}{$$