

# Unbiased estimates for linear regression via volume sampling

Michał Dereziński and Manfred Warmuth

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# Outline

Introduction

Overview of Results

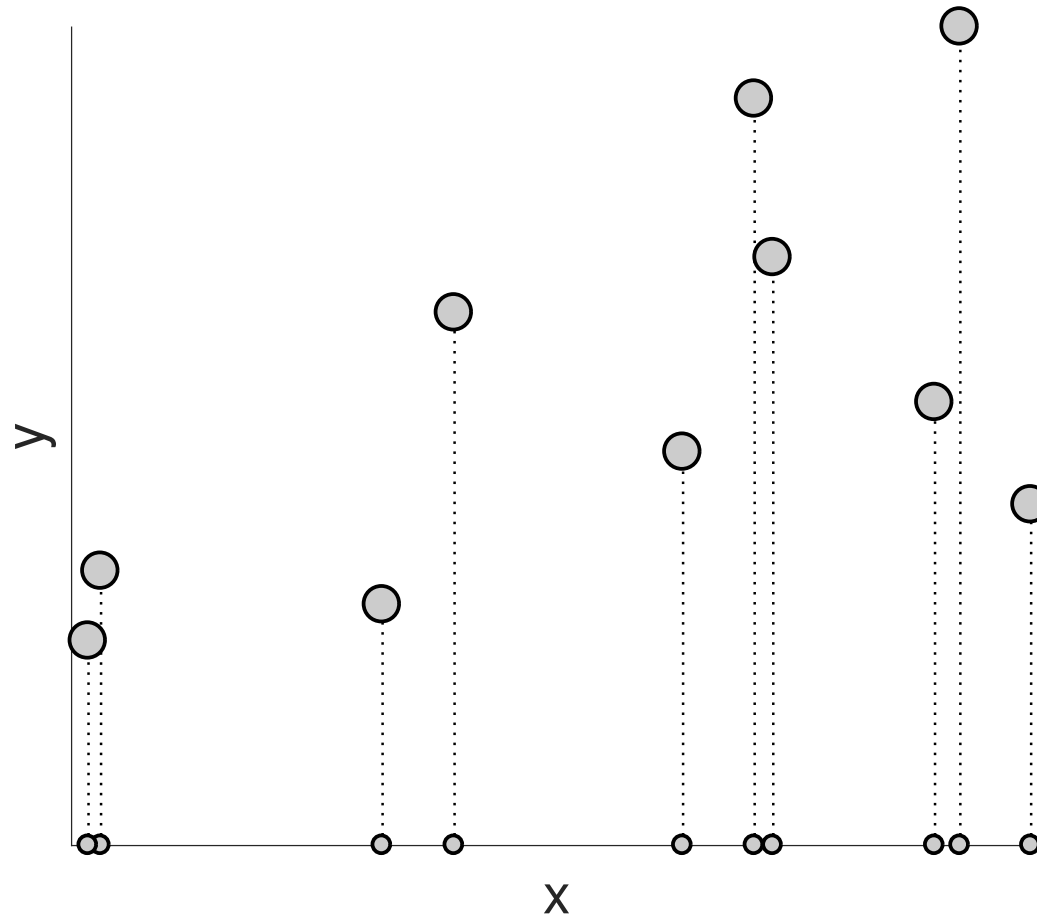
Main Proof Method

Further Research Directions

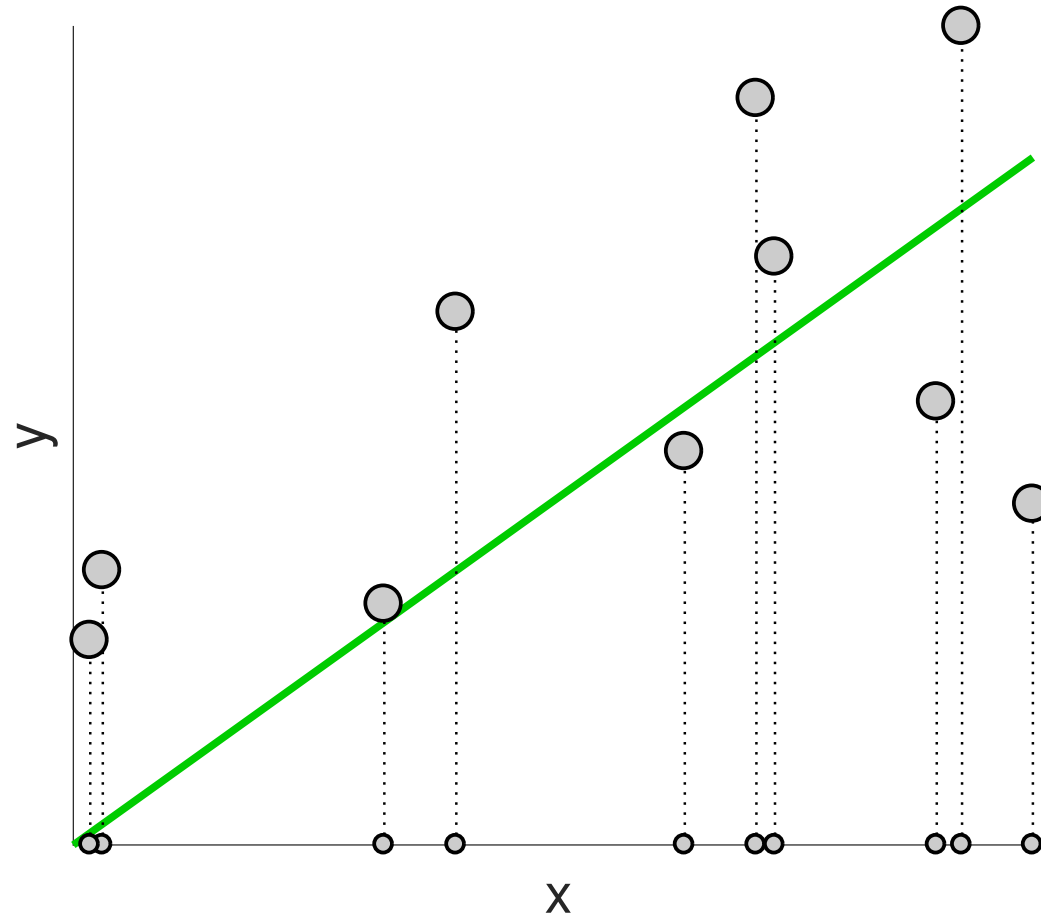
Proof of Loss Expectation Formula

Appendix

# Linear regression

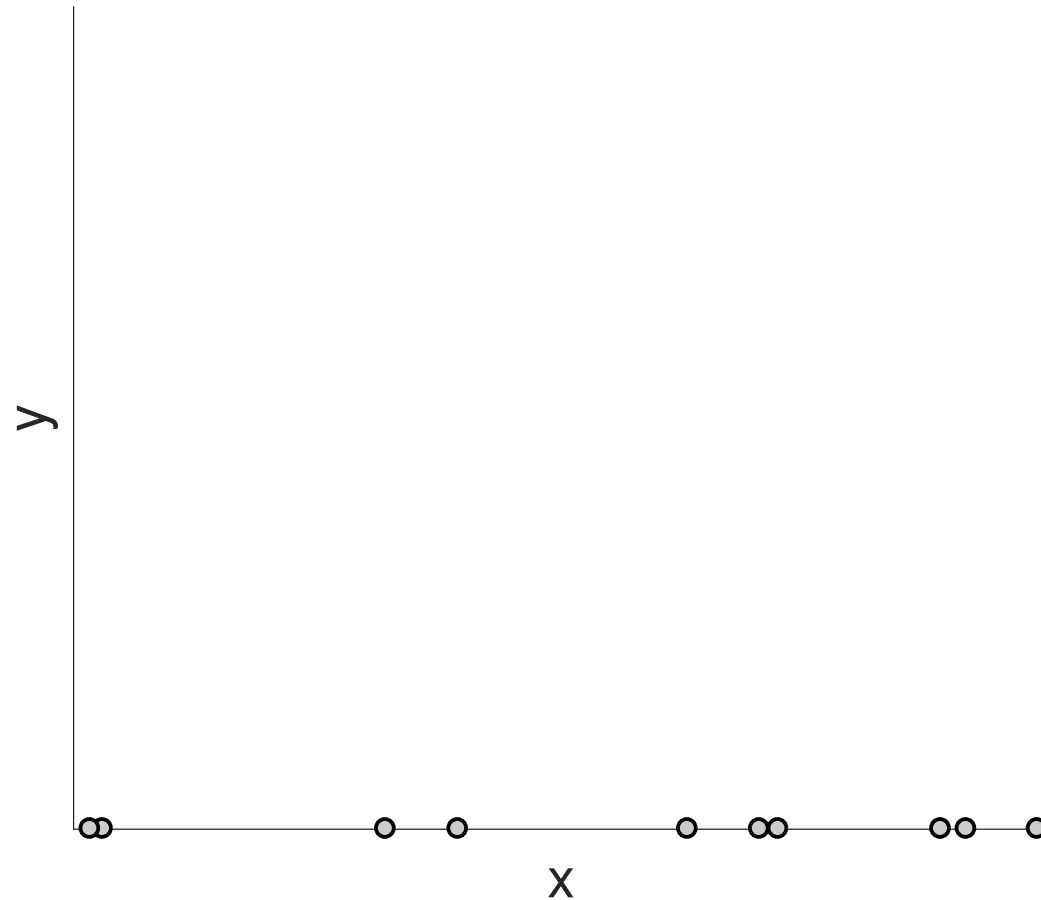


# Optimal solution



$$w^* = \operatorname{argmin}_w \sum_i (x_i w - y_i)^2$$

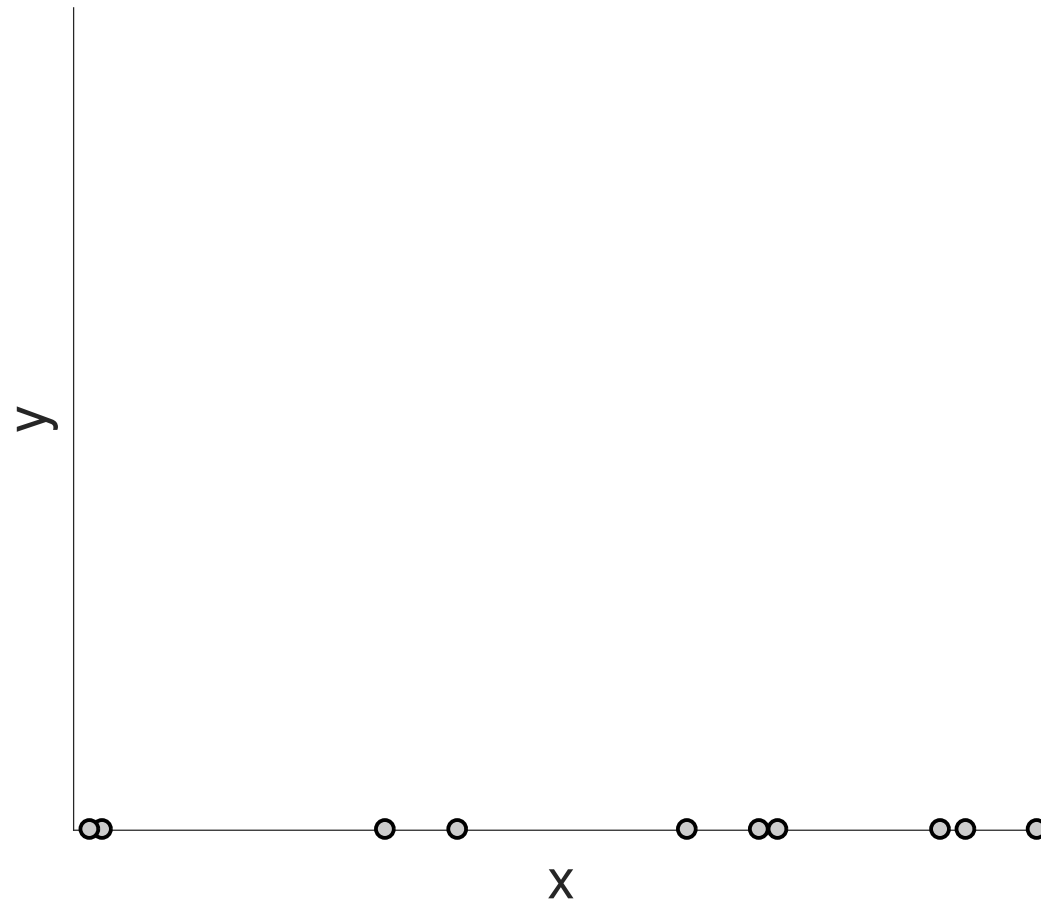
# How many labels needed to get close to optimum?



- All  $x_i$  given
- But labels  $y_i$  unknown

Guess how many needed?

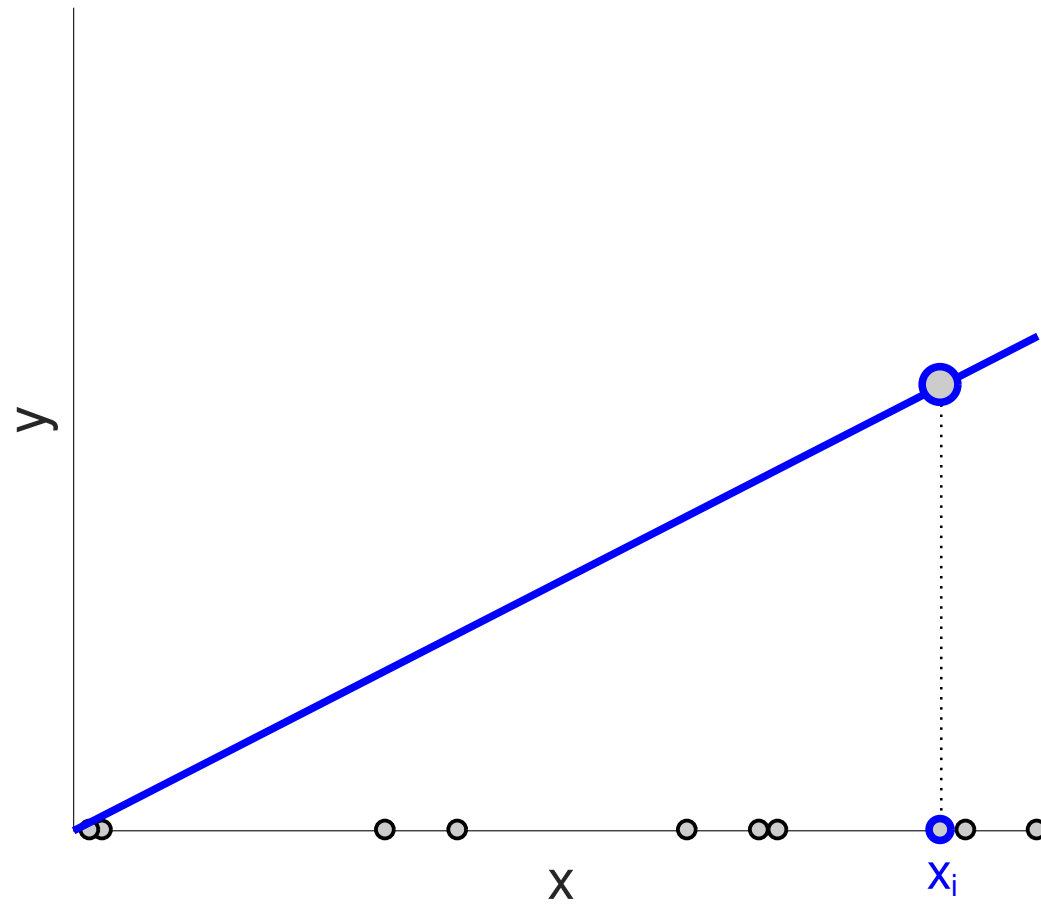
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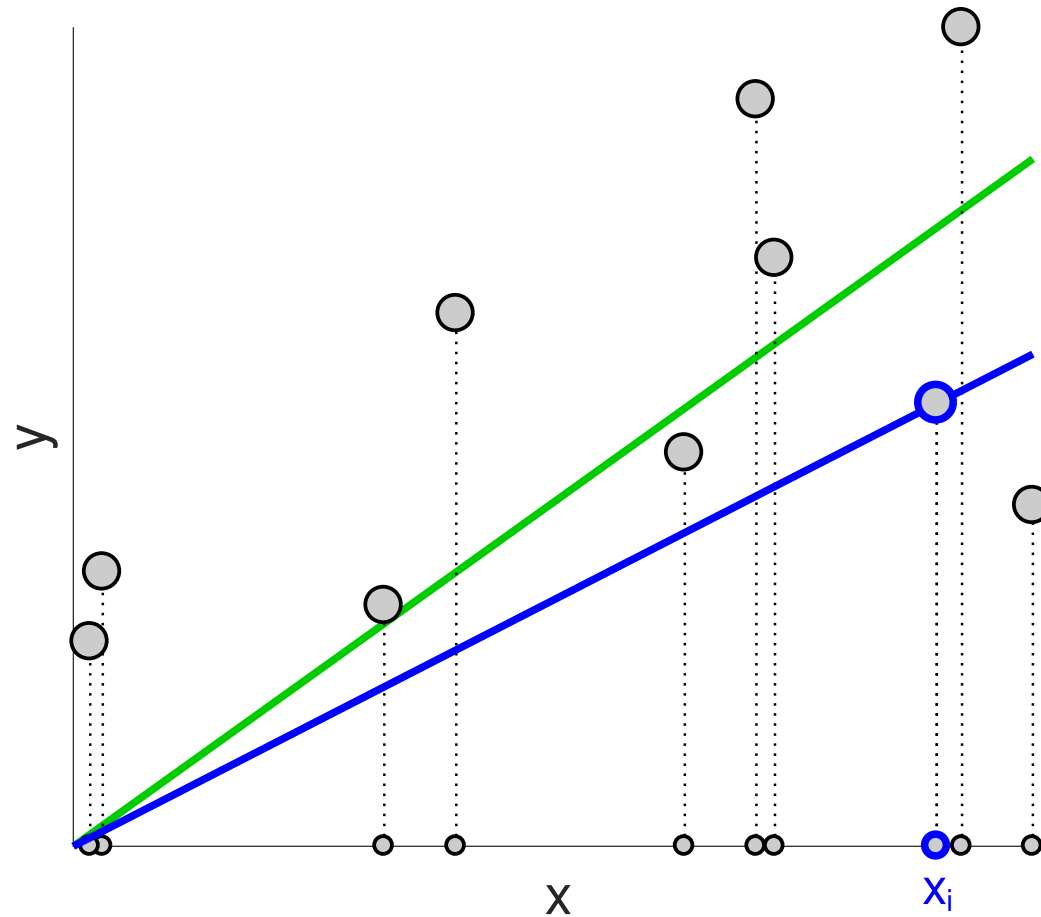
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**Guess how many needed?**

Answer: 1 label



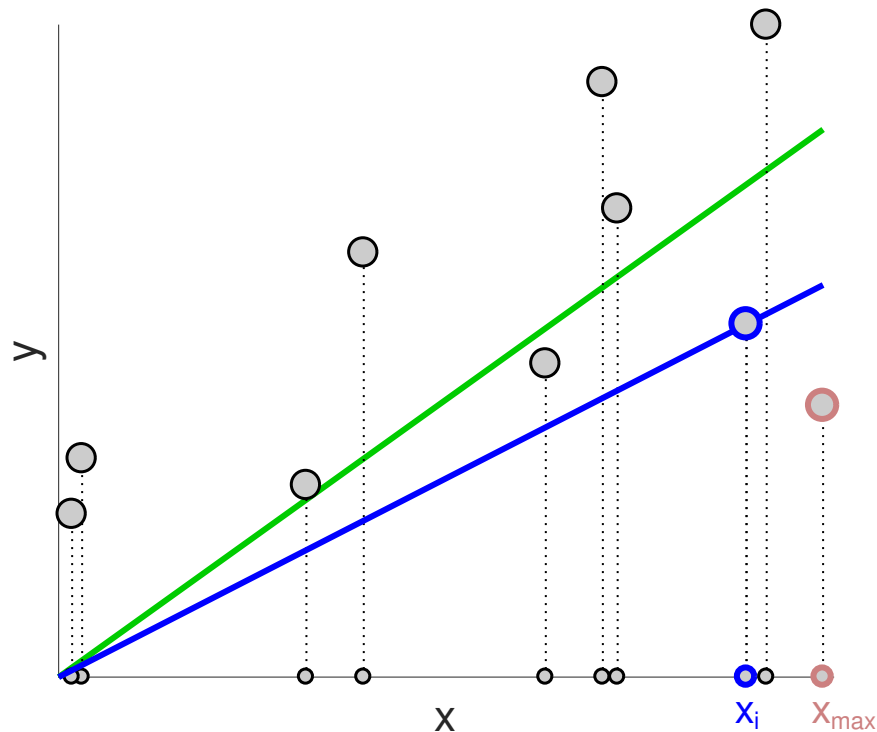
# How good is 1 label?



Loss of estimate =  $2 \times$  Loss of optimum



# Which one?



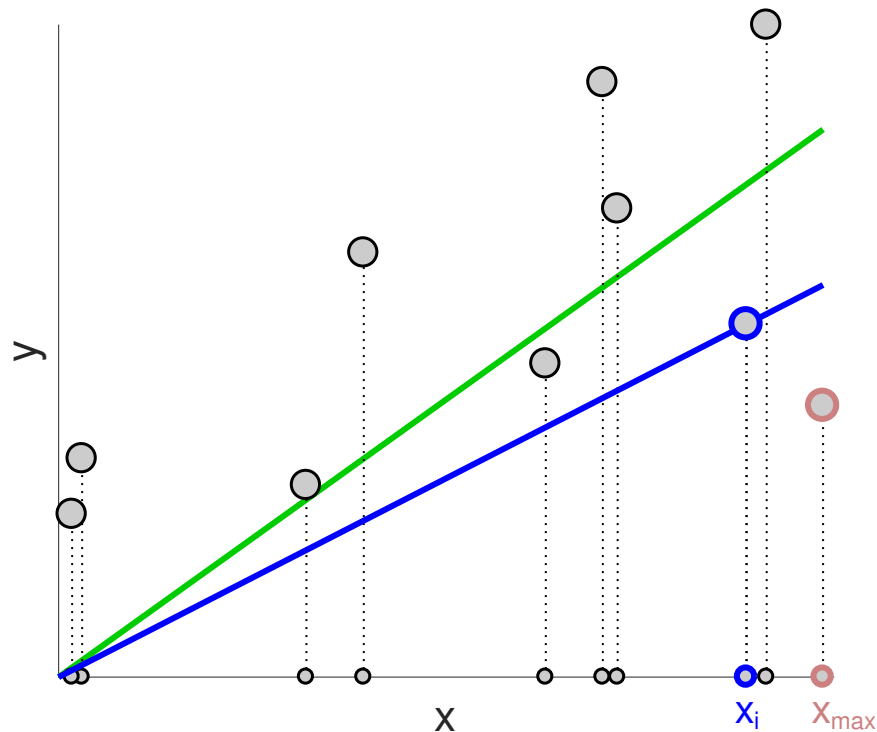
- $x_{\max}$  (furthest from 0) is bad
- any deterministic choice is bad

Good: 1 label  $y_i$  drawn  $\sim x_i^2$

$$\mathbb{E}_i \sum_j \left( \underbrace{\frac{y_i}{x_i}}_{w_i^*} x_j - y_j \right)^2 = 2 \sum_j (w^* x_j - y_j)^2$$

$$\mathbb{E}_i w_i^* = \sum_i \frac{\overbrace{x_i^2}^{P(i)}}{\|\mathbf{x}\|^2} \underbrace{\frac{y_i}{x_i}}_{w_i^*} = w^*$$

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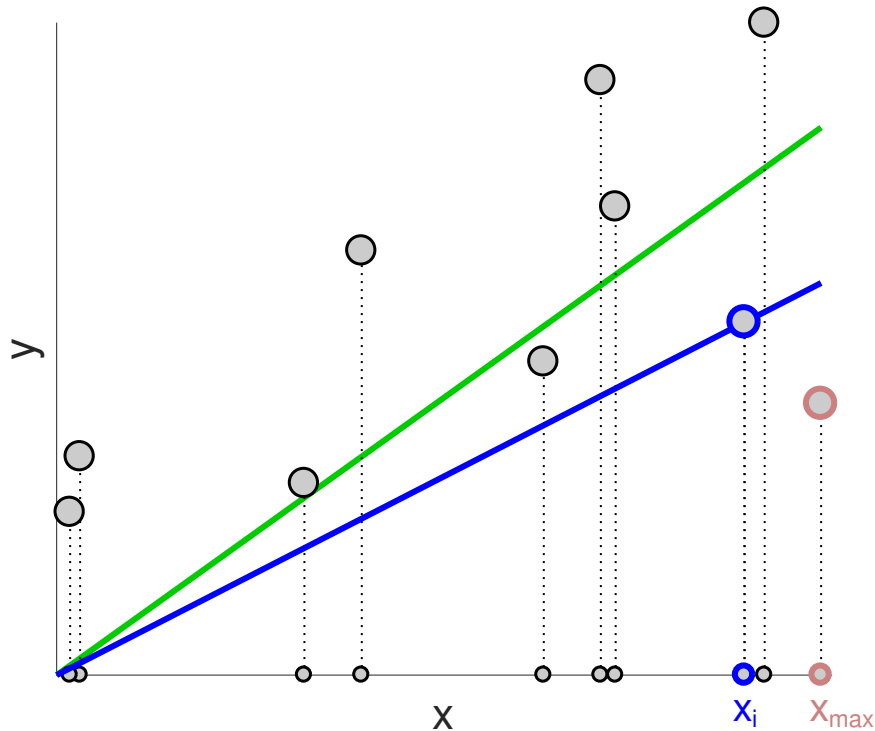
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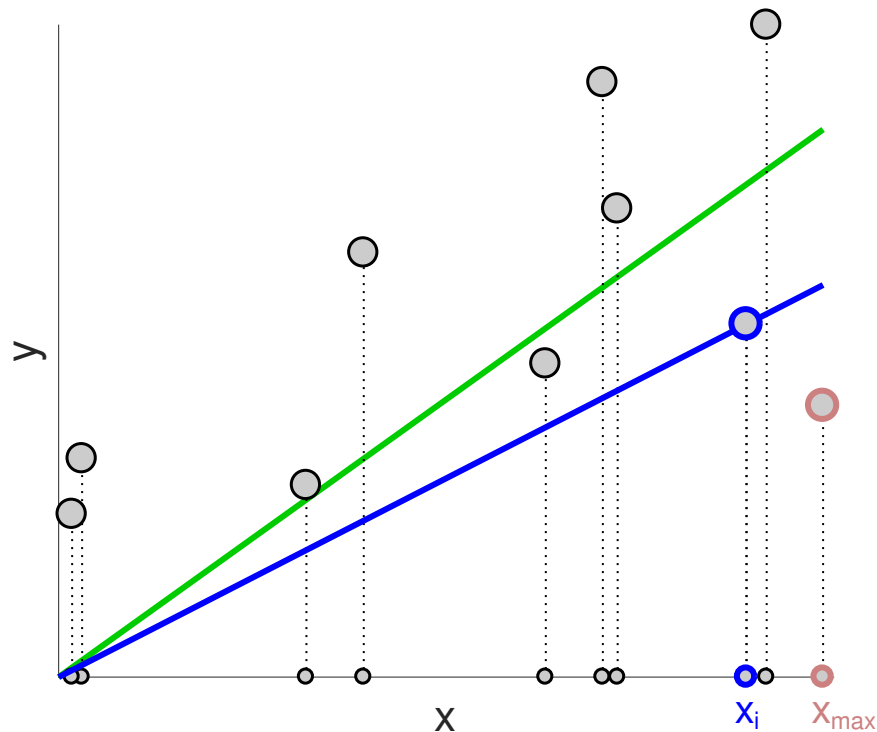
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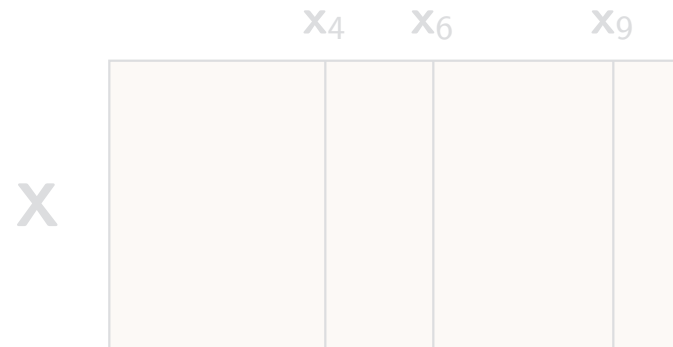
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# General: subsampling for linear regression

**Given:**  $n$  points  $\mathbf{x}_i \in \mathbb{R}^d$  with hidden labels  $y_i \in \mathbb{R}$

Select  $S = \{4, 6, 9\}$



Receive  $y_4, y_6, y_9$



**Goal:** Minimize loss  $L(\mathbf{w}) = \sum_i (\mathbf{x}_i^\top \mathbf{w} - y_i)^2$  over all  $n$  points

**Strategy:** Solve subproblem  $(\mathbf{X}_S, \mathbf{y}_S)$ , obtaining:

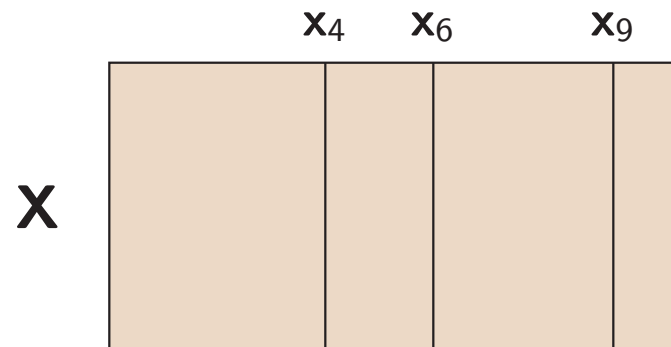
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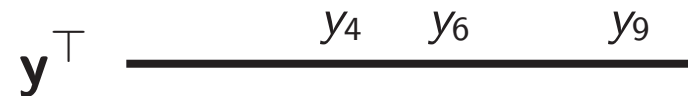
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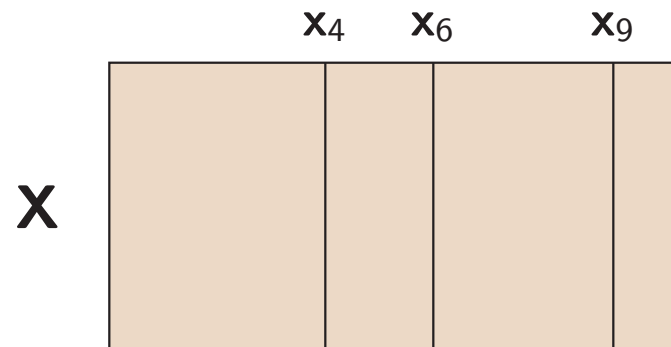
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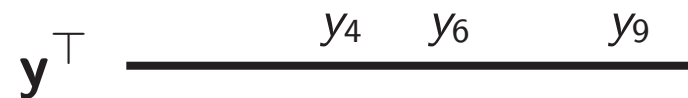
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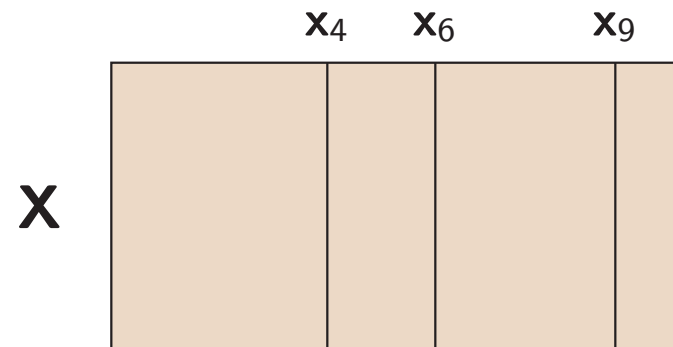
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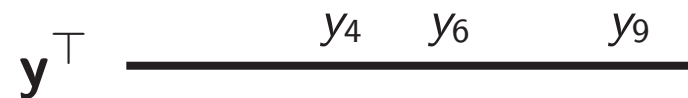
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# Are dimension many labels sufficient?

## Claim

There is no good deterministic algorithm for selecting  $d$  labels.

1-dimensional example:

$$\begin{array}{l} \mathbf{X} = \begin{pmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \cdots & \mathbf{x}_n \end{pmatrix} \\ \mathbf{y}^\top = \begin{pmatrix} 0 & 1 & \cdots & 1 \end{pmatrix} \end{array} \quad \begin{array}{l} \text{Deterministic pick } S = \{1\}, \text{ receive } y_1 = 0 \\ \text{Deterministic predictor } \mathbf{w}^*(\{1\}) = 0 \\ \text{Optimal predictor } \mathbf{w}^* = \frac{n-1}{n} = 1 - \frac{1}{n} \end{array}$$

$$\underbrace{L(\mathbf{w}^*(\{1\}))}_{n-1} = n \underbrace{L(\mathbf{w}^*)}_{\frac{n-1}{n}}$$

With uniform choice of  $S : |S| = 1$ ,  $\mathbb{E}[L(\mathbf{w}^*(S))] = 2L(\mathbf{w}^*)$

## Our Result

A randomized algorithm can achieve  $\mathbb{E}[L(\mathbf{w}^*(S))] = (d + 1) L(\mathbf{w}^*)$

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## 1-dimensional example:

$$\begin{array}{ll} \mathbf{X} = \begin{array}{cccc} \mathbf{x}_1 & \mathbf{x}_2 & & \mathbf{x}_n \\ \textcolor{brown}{1} & 1 & \cdots & 1 \end{array} & \begin{array}{l} \text{Deterministic pick } S = \{\textcolor{brown}{1}\}, \text{ receive } y_1 = 0 \\ \text{Deterministic predictor } \mathbf{w}^*(\{\textcolor{brown}{1}\}) = 0 \end{array} \\ \mathbf{y}^\top = (0 & 1 & \cdots & 1) & \text{Optimal predictor } \mathbf{w}^* = \frac{n-1}{n} = 1 - \frac{1}{n} \end{array}$$

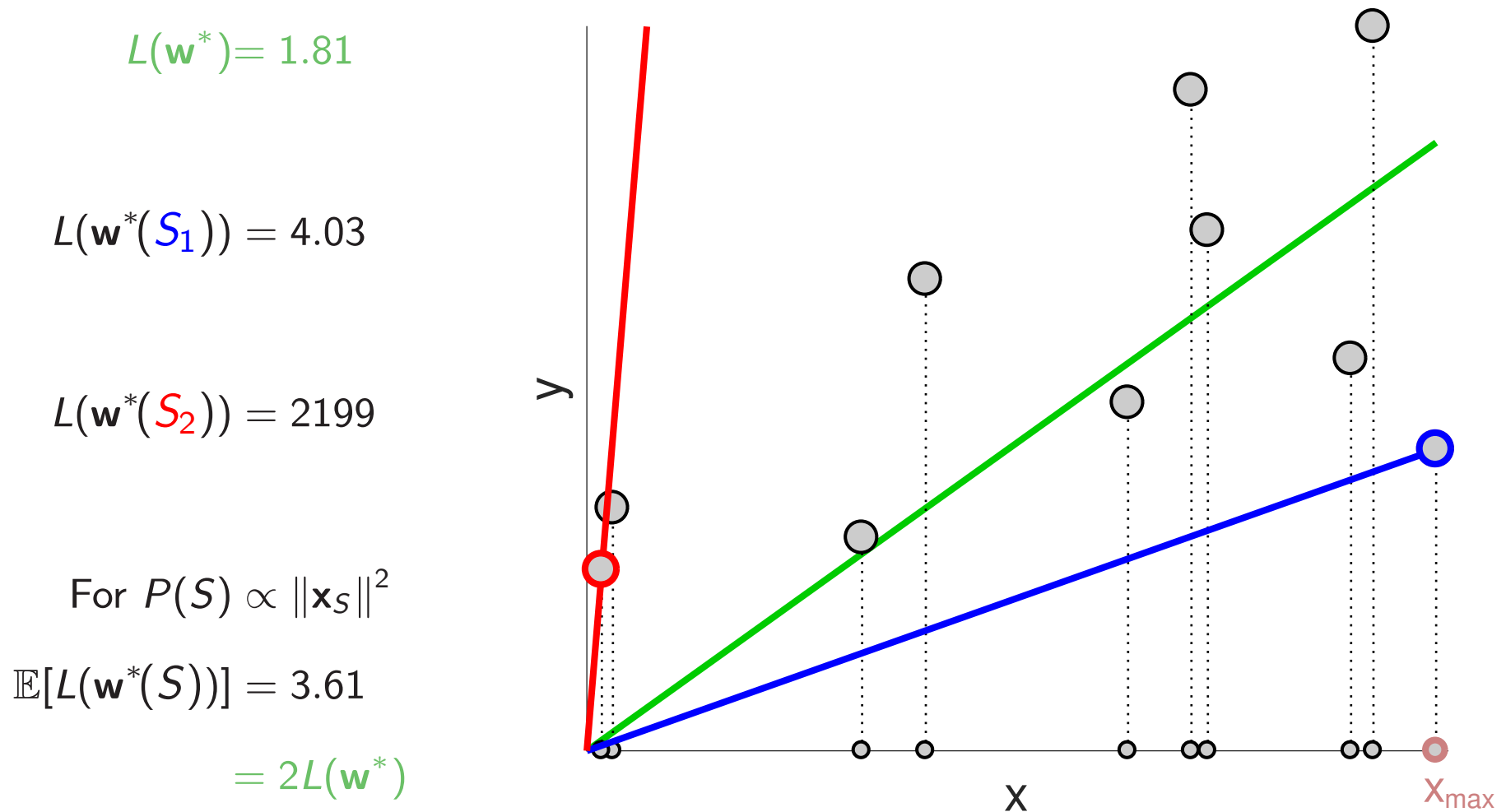
$$\underbrace{L(\mathbf{w}^*(\{\textcolor{brown}{1}\}))}_{n-1}^0 = \textcolor{red}{n} \underbrace{L(\mathbf{w}^*)}_{\frac{n-1}{n}}^{\frac{n-1}{n}}$$

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## Our Result

A randomized algorithm can achieve  $\mathbb{E}[L(\mathbf{w}^*(S))] = (\textcolor{red}{d} + 1) L(\mathbf{w}^*)$

# Towards Volume Sampling



Instances with larger norm  $\|\mathbf{x}\|^2$  are more informative

**What generalizes  $\|\mathbf{x}\|^2$ ?**

# Volume Sampling<sup>1</sup>

Generalize norms to sets of examples

Distribution over all  $d$ -element subsets  $S$ :

$$P(S) = \det(\mathbf{X}_S \mathbf{X}_S^\top) / Z$$

Also well defined for any  $|S| \geq d$ .

**Note:** Normalization factor  $Z$  can be derived using Cauchy-Binet formula:

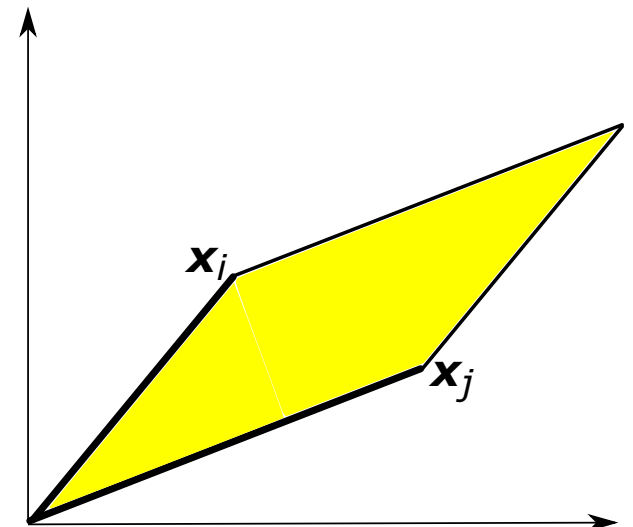
$$Z = \sum_{S: |S|=d} \det(\mathbf{X}_S \mathbf{X}_S^\top) = \det(\mathbf{X} \mathbf{X}^\top)$$

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<sup>1</sup>Deshpande, Rademacher, Vempala, Wang. 2006

$$\mathbf{X}_S = \begin{pmatrix} | & | \\ \mathbf{x}_i & \mathbf{x}_j \\ | & | \end{pmatrix}$$

$\det(\mathbf{X}_S \mathbf{X}_S^\top) =$   
**squared** volume of  
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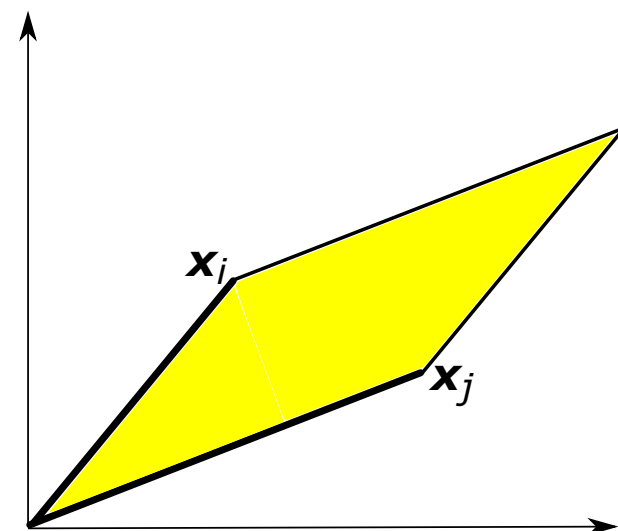
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# How many examples needed?

We will show that using volume sampling,  
 **$d$  labels suffice** to achieve a multiplicative approximation

**Thm:** For any full rank matrix  $\mathbf{X}$ ,  **$d - 1$  labels do not suffice**

**Proof idea:** Adversary has freedom to set the label of one additional point while  $L(\mathbf{w}^*) = 0$  and algorithm has positive loss



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# Main results

For a volume-sampled  $d$ -element set  $S$ ,

$$\mathbb{E} [L(\mathbf{w}^*(S))] = (d + 1) L(\underbrace{\mathbf{w}^*}_{\mathbb{E}[\mathbf{w}^*(S)]}),$$

if  $\mathbf{X}$  is in general position

- ▶ Sampling distribution does not depend on the labels
- ▶ No range restrictions!    **No dependence on  $n$**

Recall model:

- Adversary picks  $\mathbf{X}$
- Learner picks subset of label indices
- Adversary picks all labels

# Main Results in a Picture

