

Comments on tasks:

Task 1

I implemented it, but it wasn't right, it keeps going in a circle, instead of an eight. It'd my fault here for the implementation, didn't face error. Also, when the robot reached the wall because of the wall scene, it would just circle around the wall then.

Task 2

Yes, I implemented it, but I couldn't get past the problem of the error, which didn't make the other code run after it. The error was "ControllerNode object has no attribute rightPromixity". The sensor readings from the robot was not able to be taken because of this error, so it was difficult to test whether the code after runs. At the start, it would run, but after it doesn't.

Task 3

Yes, I implemented it, but I couldn't get past the problem of the error, which didn't make the other code run after it. The error was "ControllerNode object has no attribute rightPromixity". The sensor readings from the robot was not able to be taken because of this error, so it was difficult to test whether the code after runs. At the start, it would run, but after it doesn't.