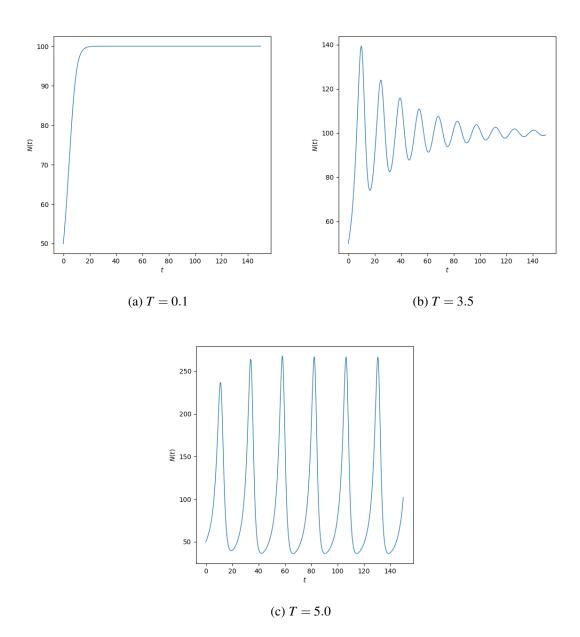
## Problem 1

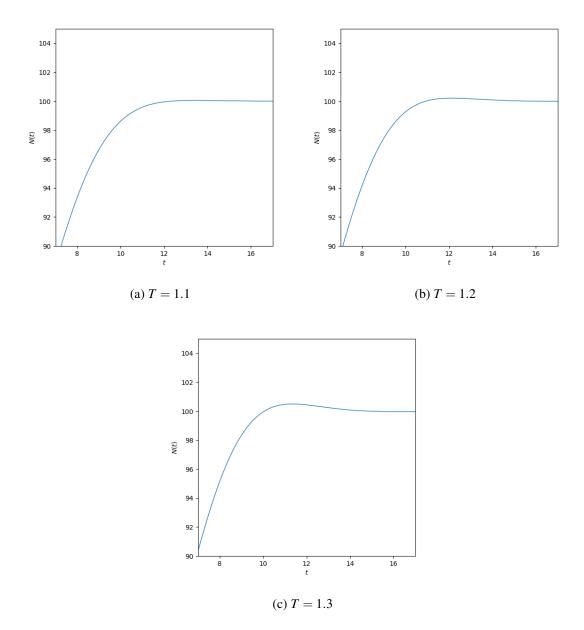
Collaborators: Erik Norlin & Hannes Nilsson

a)



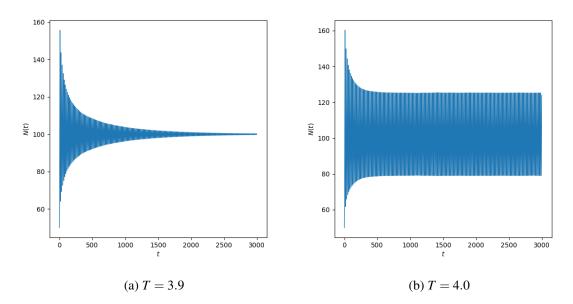
Figur 1: Examples of no oscillations (a), damped oscillations (b) and stable oscillations (c).

b)



Figur 2: No oscillations can be seen in (a) when T = 1.1. A small overshoot can be vaguely seen in (b) when T = 1.2. Overshooting is clearly visible in (c) when T = 1.3. According to the theory for damped oscillations, if there's an overshoot, there's also an undershoot with a smaller amplitude which indicates oscillation.

c)



Figur 3: The dynamics show damped oscillations for a long time when T = 3.9 (a) which indicates that there's only a spiral in the system, while the dynamics show stable oscillations when T = 4.0 (b) i.e. the dynamics instead converge to a limit cycle. We can say that the dynamics undergoes a Hopf bifurcation between 3.9 and 4.0 for the value of T.

d)

$$\dot{N}(t) = rN(t) \left(1 - \frac{N(t-T)}{K}\right) \left(\frac{N(t)}{A} - 1\right).$$

Linearizing around fixed point  $N^* = K \implies N(t) \approx K + \eta(t)$  &  $\dot{N}(t) \approx \dot{\eta}(t)$ :

$$\begin{split} \dot{\eta}(t) &= r \big(K + \eta(t)\big) \left(1 - \frac{K + \eta(t - T)}{K}\right) \left(\frac{K + \eta(t)}{A} - 1\right) \\ &= \left(rK + r\eta(t)\right) \left(1 - \frac{K}{K} + \frac{\eta(t - T)}{K}\right) \left(\frac{K}{A} + \frac{\eta(t)}{A} - 1\right) \\ &= \frac{\eta(t - T)}{K} \big(rK + r\eta(t)\big) \left(\frac{K - A}{A} + \frac{\eta(t)}{A}\right). \end{split}$$

Since  $\eta << 1$ , we consider only the linear term, and plug in the values A=20, K=100, r=0.1:

$$\dot{\eta}(t) \approx rK \frac{K - A}{A} \frac{\eta(t - T)}{K} = \frac{2}{5} \eta(t - T).$$

Now we make the ansatz  $\eta(t) = Be^{\lambda t}$ :

$$\lambda B e^{\lambda t} = \frac{2}{5} \eta(t - T) = \frac{2B}{5} e^{\lambda(t - T)}.$$

Dividing by  $Be^{\lambda t}$  on both sides gives:

$$\lambda = \frac{2}{5}e^{-\lambda T}.$$

Assume  $\lambda$  is complex and rewrite as:

$$\begin{split} \lambda' + i\lambda'' &= \frac{2}{5}e^{(-\lambda' - i\lambda'')T} \\ &= \frac{2}{5}e^{-\lambda'T}e^{-i\lambda''T} \\ &= \frac{2}{5}e^{-\lambda'T} \left(\cos(-\lambda''T) + i\sin(-\lambda''T)\right) \\ &= \frac{2}{5}e^{-\lambda'T} \left(\cos(\lambda''T) - i\sin(\lambda''T)\right) \end{split}$$

From here, we can deduce the real and imaginary parts of  $\lambda$  as:

$$\lambda' = \frac{2}{5}e^{-\lambda'T}\cos(\lambda''T).$$

$$\lambda'' = \frac{2}{5}e^{-\lambda'T}\sin(\lambda''T).$$

At a Hopf bifurcation, we have  $Re(\lambda) = 0$ . This gives us:

$$\lambda''T_H = \frac{\pi}{2} \implies \lambda'' = \frac{2}{5}e^0\sin(\pi/2) = \frac{2}{5}.$$

We can now find  $T_H$  as:

$$T_H = \frac{\pi}{2\lambda''} = \frac{5\pi}{4} \approx 3.93.$$

This analysis is in agreement with our experimental results, where we found the Hopf bifurcation to take place between T = 3.9 and T = 4.0.

## **Appendix**

## **Code for simulations (Python)**

```
import numpy as np
import matplotlib.pyplot as plt
from ddeint import ddeint
import sys
```

```
# Numerical solver
T = 5
T_end = T*5
dt = 0.1
t = np.linspace(0,T_end,int(T_end/dt)+1)
T_i = np.linspace(0,T,int(T/dt)+1)
N0 = lambda t: 50
```

```
def model(Y, t, d):
   N = Y(t)
    Nd = Y(t-d)
    r = 0.1
   K = 100
   A = 20
    dNdt_solver = r*N*(1-Nd/K)*(N/A-1)
    return dNdt_solver
# Hopf bif. between T = 3.9 and 4.0
N_{solver} = ddeint(model, N0, t, fargs = (d,))
# for d in T_i:
      # 1.1b) damped oscillations starts at around d = 4.4
    \# N_solver = ddeint(model, N0, t, fargs=(d,))
    # ax.plot(t, N_solver, linewidth=1, label='delay = %.01f'%d)
    # break
# Plotting solver
fig, ax = plt.subplots(figsize = (6,6))
ax.plot(t, N_solver, linewidth=1, label='delay = \%.01f'\%d)
ax.set_xlabel('$t$')
ax.set_ylabel('$N(t)$')
ax.set_xlim([7,17])
ax.set_ylim([90,105])
ax.set_box_aspect(1)
# plt.legend(loc="upper left")
title = '/1.1b Start of damped oscillations, T={}'.format(d)
location = r'C:\Users\erikn\OneDrive - Chalmers\Computational Biology\CB HW 1'
plt.savefig(location+title+'.png')
plt.show()
```