

$$4.2 c) D_{4\rightarrow 1} = \lim_{t \to 1} \frac{\ln(2^{4}+1) - 4 \ln 3}{(1-4) \ln 3} = \left\{ \frac{L + \text{lospitals}}{\text{rule}} \right\} = \frac{2 \ln 2 - 3 \ln 3}{2^{4}+1} = \frac{2 \ln 2 - 3 \ln 3}{-3 \ln 3} = \frac{2 \ln 2 - 3 \ln 3}{-3 \ln 3} = \frac{2 \ln 2 - 3 \ln 3}{-3 \ln 3} = \frac{1 \ln 2 - 3 \ln 3}{-3 \ln 3} = \frac{1 \ln 2 - 3 \ln 3}{-3 \ln 3} = \frac{1 \ln 2 - 3 \ln 3}{-3 \ln 3} = \frac{1 \ln 2 - 3 \ln 3}{-3 \ln 3} = \frac{1 \ln 2 - 3 \ln 3}{(1-2) \ln 3} = \frac{1 \ln 2 - 3 \ln 3}{(1-4) \ln 3} = \frac{1 \ln 2 - 3 \ln 3}{$$

2022-12-16 15:50 4.2b.py

```
import numpy as np
import matplotlib.pyplot as plt
import sys

qmin = -20
qmax = 20
q = np.linspace(qmin,qmax,50)
Dq = (np.log(2**q+1)-q*np.log(3))/((1-q)*np.log(3))

plt.figure()
plt.plot(q,Dq)
plt.title('$4.2b$')
plt.xlabel('$q$')
plt.ylabel('$p_q$')
plt.xlim(qmin,qmax)
plt.savefig('Dynamical Systems/DS HW4/4.2/4.2b2.png')
plt.show()
```