Autonomous Robots:
Assignment 1

Erik Norlin

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1c

To run the microservice you have to run the docker image in two different terminals. This is to set up a receiver that can send back the message that is intended in this task. The docker image is run with the following command:

```
docker run --rm -ti --net=host registry.git.chalmers.se/norliner/opendlv-logic-norliner:1.3
```

It should now look something like fig. 1.

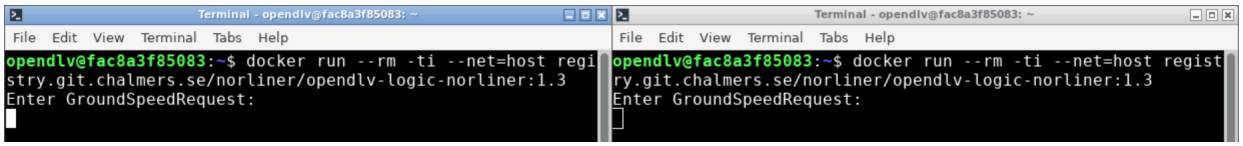

Figure 1

Type any **number** you wish in any terminal. Inputting ”2” in the first terminal looks like fig. 2

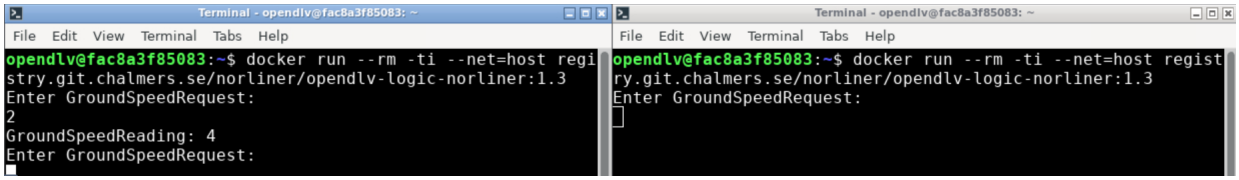

Figure 2

The first terminal sends a message of type `GroundSpeedRequest`. The second terminal acts as a server and receives this message and multiples it with a float 2.0, converts the new number to a message of type `GroundSpeedReading`, and sends it. The first terminal acts now as a server and receives the message of type `GroundSpeedReading`, and prints the message. This is why two terminals are needed even though the second terminal remains unaffected at sight.

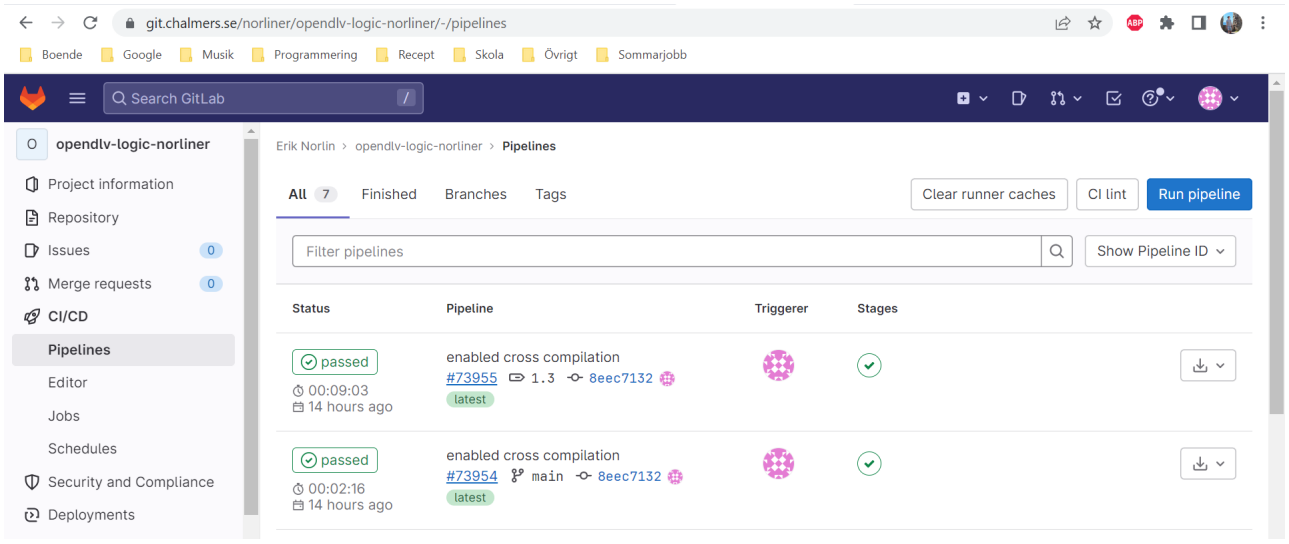

Figure 3: Status and pipeline of the docker image on git.chalmers.se.

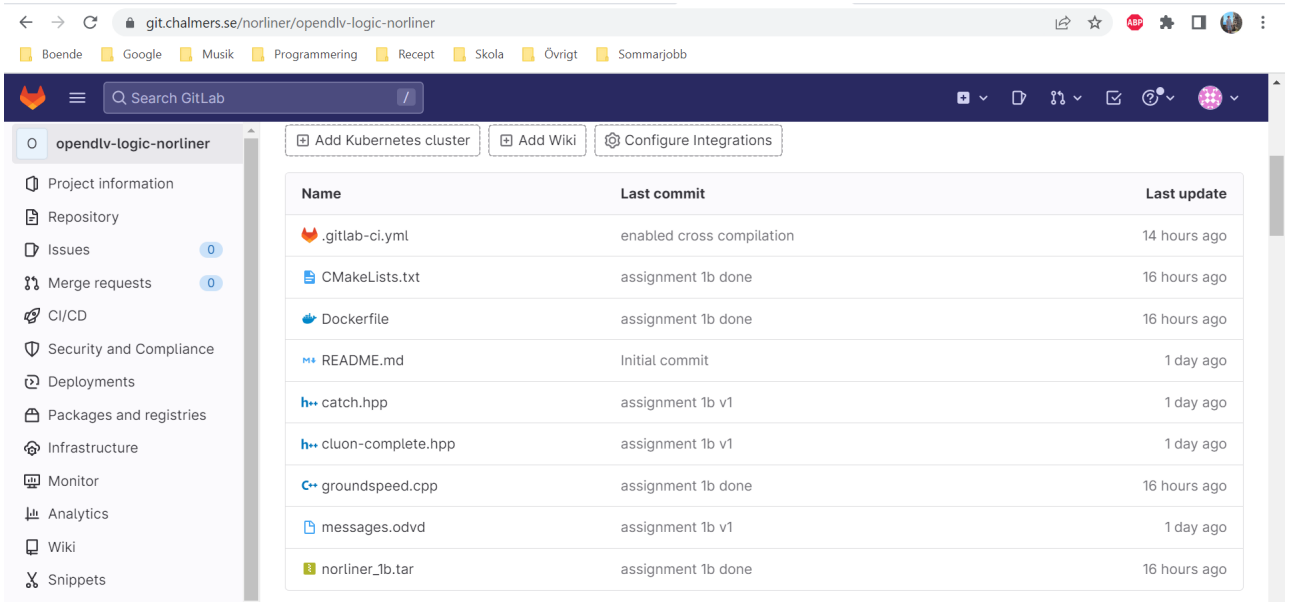

Figure 4: Repository on git.chalmers.se. The first file ".gitlab-ci.yml" in the repository is automating CI+CD. The third file is the Dockerfile.