

Determine the minimum utility consumption for the two hot and two cold streams given below:

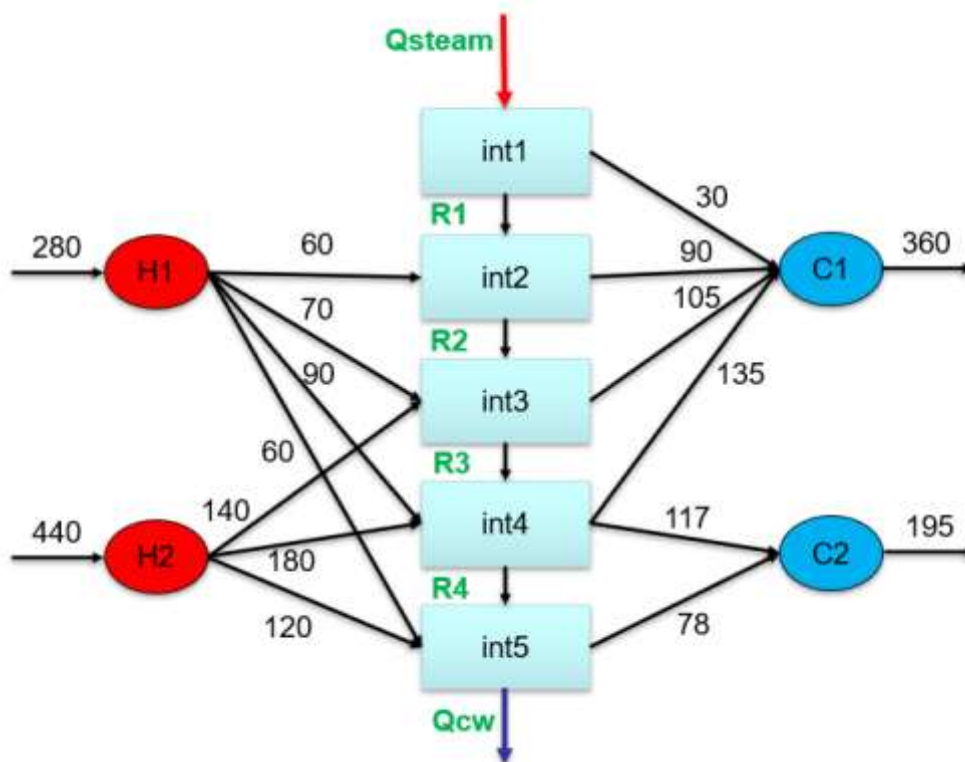
	Fcp (MW/C)	Tin (°C)	Tout (°C)
H1	1	400	120
H2	2	340	120
C1	1,5	160	400
C2	1,3	100	250

Steam: 500 °C

Cooling water: 20-30 °C

Minimum recovery approach temperature: 20 C

En este caso, resolveremos el ejemplo utilizando el "Transshipment model", en el cual se plantean los balances alrededor de cada intervalo de temperaturas



```
In [ ]: from pyomo.environ import *
        model = ConcreteModel()
```

Variables

```
In [ ]: Qsteam = model.Qsteam = Var(within = NonNegativeReals)
        Qcw = model.Qcw = Var(within = NonNegativeReals)
        R1 = model.R1 = Var(within = NonNegativeReals)
        R2 = model.R2 = Var(within = NonNegativeReals)
        R3 = model.R3 = Var(within = NonNegativeReals)
        R4 = model.R4 = Var(within = NonNegativeReals)
```

Objective function

```
In [ ]: model.util = Objective(expr = Qsteam + Qcw)
```

Constraints

```
In [ ]: model.int1 = Constraint(expr = Qsteam - 30 - R1 == 0)
model.int2 = Constraint(expr = 60 + R1 - R2 - 90 == 0)
model.int3 = Constraint(expr = R2 + 70 + 140 - R3 - 105 == 0)
model.int4 = Constraint(expr = R3 + 90 + 180 - R4 - 117 - 135 == 0)
model.int5 = Constraint(expr = R4 + 60 + 120 - 78 - Qcw == 0)
```

Solution

```
In [ ]: results = SolverFactory('glpk').solve(model)
model.pprint()
results.write()
```

6 Var Declarations

```
Qcw : Size=1, Index=None
      Key : Lower : Value : Upper : Fixed : Stale : Domain
      None :      0 : 225.0 : None : False : False : NonNegativeReals
Qsteam : Size=1, Index=None
      Key : Lower : Value : Upper : Fixed : Stale : Domain
      None :      0 : 60.0 : None : False : False : NonNegativeReals
R1 : Size=1, Index=None
      Key : Lower : Value : Upper : Fixed : Stale : Domain
      None :      0 : 30.0 : None : False : False : NonNegativeReals
R2 : Size=1, Index=None
      Key : Lower : Value : Upper : Fixed : Stale : Domain
      None :      0 : 0.0 : None : False : False : NonNegativeReals
R3 : Size=1, Index=None
      Key : Lower : Value : Upper : Fixed : Stale : Domain
      None :      0 : 105.0 : None : False : False : NonNegativeReals
R4 : Size=1, Index=None
      Key : Lower : Value : Upper : Fixed : Stale : Domain
      None :      0 : 123.0 : None : False : False : NonNegativeReals
```

1 Objective Declarations

```
util : Size=1, Index=None, Active=True
      Key : Active : Sense : Expression
      None : True : minimize : Qsteam + Qcw
```

5 Constraint Declarations

```
int1 : Size=1, Index=None, Active=True
      Key : Lower : Body : Upper : Active
      None : 0.0 : Qsteam - 30 - R1 : 0.0 : True
int2 : Size=1, Index=None, Active=True
      Key : Lower : Body : Upper : Active
      None : 0.0 : 60 + R1 - R2 - 90 : 0.0 : True
int3 : Size=1, Index=None, Active=True
      Key : Lower : Body : Upper : Active
      None : 0.0 : R2 + 70 + 140 - R3 - 105 : 0.0 : True
int4 : Size=1, Index=None, Active=True
      Key : Lower : Body : Upper : Active
      None : 0.0 : R3 + 90 + 180 - R4 - 117 - 135 : 0.0 : True
int5 : Size=1, Index=None, Active=True
      Key : Lower : Body : Upper : Active
      None : 0.0 : R4 + 60 + 120 - 78 - Qcw : 0.0 : True
```

```

12 Declarations: Qsteam Qcw R1 R2 R3 R4 util int1 int2 int3 int4 int5
# =====
# = Solver Results =
# =====
# -----
# Problem Information
# -----
Problem:
- Name: unknown
  Lower bound: 285.0
  Upper bound: 285.0
  Number of objectives: 1
  Number of constraints: 6
  Number of variables: 7
  Number of nonzeros: 11
  Sense: minimize
# -----
# Solver Information
# -----
Solver:
- Status: ok
  Termination condition: optimal
  Statistics:
    Branch and bound:
      Number of bounded subproblems: 0
      Number of created subproblems: 0
    Error rc: 0
    Time: 0.10663795471191406
# -----
# Solution Information
# -----
Solution:
- number of solutions: 0
  number of solutions displayed: 0

```

In []:

```

Qc = value(Qcw)
Qh = value(Qsteam)
print('Cold utility = {0:2.2f}, Hot utility = {1:2.2f}'.format(Qc, Qh))

```

Cold utility = 225.00, Hot utility = 60.00