

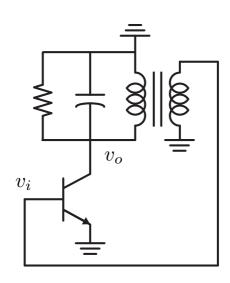
#### Lecture 22: Oscillator Steady-State Analysis

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### **Summary of Last Lecture**



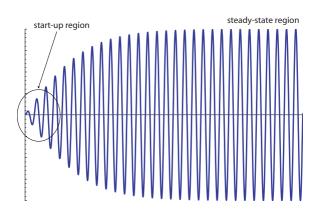
Last lecture we analyzed the small-signal behavior of the above circuit. We found that the closed-loop gain is given by

$$H(s) = \frac{g_m R s \frac{L}{R}}{1 + s \frac{L}{R} (1 - A_\ell) + s^2 L C}$$

### Review: Role of Loop Gain

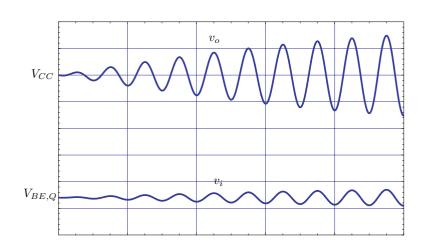
- The behavior of the circuit is determined largely by  $A_\ell$ , the loop gain at DC and resonance. When  $A_\ell=1$ , the poles of the system are on the  $j\omega$  axis, corresponding to constant amplitude oscillation.
- When  $A_{\ell} < 1$ , the circuit oscillates but decays to a quiescent steady-state.
- When  $A_{\ell} > 1$ , the circuit begins oscillating with an amplitude which grows exponentially. Eventually, we find that the steady state amplitude is fixed.

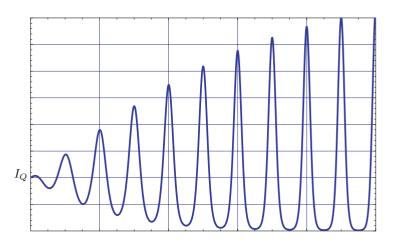
## **Steady-State Analysis**



- To find the steady-state behavior of the circuit, we will make several simplifying assumptions. The most important assumption is the high tank Q assumption (say Q > 10), which implies the output waveform  $v_o$  is sinusoidal.
- Since the feedback network is linear, the input waveform  $v_i = v_o/n$  is also sinusoidal.
- We may therefore apply the large-signal periodic steady-state analysis of the BJT to the oscillator.

# **Steady-State Waveforms**





- The collector current is not sinusoidal, due to the large signal drive.
- The output voltage, though, is sinusoidal and given by

$$v_o \approx I_{\omega_1} Z_T(\omega_1) = G_m Z_T v_i$$

# **Steady State Equations**

But the input waveform is a scaled version of the output

$$v_o = G_m Z_T \frac{v_o}{n} = \frac{G_m Z_T}{n} v_o$$

The above equation implies that

$$\frac{G_m Z_T}{n} \equiv 1$$

• Or that the loop gain in steady-state is unity and the phase of the loop gain is zero degrees (an exact multiple of  $2\pi$ )

$$\left| \frac{G_m Z_T}{n} \right| \equiv 1$$

$$\angle \frac{G_m Z_T}{n} \equiv 0^{\circ}$$

# Large Signal $G_m$

Recall that the small-signal loop gain is given by

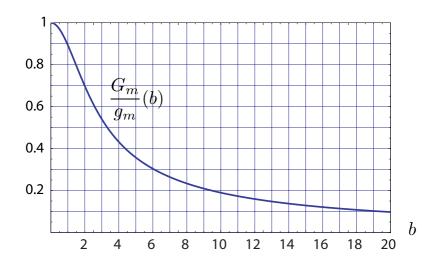
$$|A_{\ell}| = \left| \frac{g_m Z_T}{n} \right|$$

Which implies a relation between the small-signal start-up transconductance and the steady-state large-signal transconductance

$$\left| \frac{g_m}{G_m} \right| = A_\ell$$

• Notice that  $g_m$  and  $A_\ell$  are design parameters under our control, set by the choice of bias current and tank Q. The steady state  $G_m$  is therefore also fixed by initial start-up conditions.

# Large Signal $G_m$ (II)



- To find the oscillation amplitude we need to find the input voltage drive to produce  $G_m$ .
- For a BJT, we found that under the constraint that the bias current is fixed

$$I_{\omega_1} = \frac{2I_1(b)}{I_0(b)}I_Q = G_m v_i = G_m b \frac{kT}{q}$$

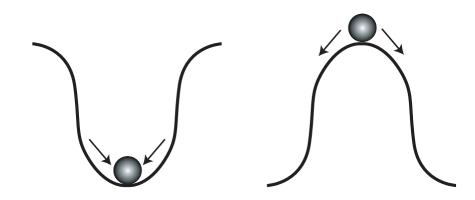
# Large Signal $G_m$ (III)

ullet Thus the large-signal  $G_m$  is given by

$$G_m = \frac{2I_1(b)}{bI_0(b)} \frac{qI_Q}{kT} = \frac{2I_1(b)}{bI_0(b)} g_m$$

$$\frac{G_m}{g_m} = \frac{2I_1(b)}{bI_0(b)}$$

### **Stability (Intuition)**



- Phere's an intuitive argument for how the oscillator reaches a stable oscillation amplitude. Assume that initially  $A_l > 1$  and oscillations grow. As the amplitude of oscillation increases, though, the  $G_m$  of the transistor drops, and so effectively the loop gain drops.
- As the loop gain drops, the poles move closer to the  $j\omega$  axis. This process continues until the poles hit the  $j\omega$  axis, after which the oscillation ensues at a constant amplitude and  $A_{\ell} = 1$ .

#### **Intuition (cont)**

- To see how this is a stable point, consider what happens if somehow the loop gain changes. If the loop gain changes to  $A_\ell + |\epsilon|$ , then we already see that the system will roll back. If the loop gain drops below unity,  $A_\ell |\epsilon|$ , then the poles move into the LHP and amplitude of oscillation will begin to decay.
- As the oscillation amplitude decays, the  $G_m$  increases and this causes the loop gain to grow. Thus the system also rolls back to the point where  $A_{\ell}=1$ .

# **BJT Oscillator Design**

- Say we desire an oscillation amplitude of  $v_0 = 100 \mathrm{mV}$  at a certain oscillation frequency  $\omega_0$ .
- We begin by selecting a loop gain  $A_{\ell} > 1$  with sufficient margin. Say  $A_{\ell} = 3$ .
- We also tune the LC tank to  $\omega_0$ , being careful to include the loaded effects of the transistor  $(r_o, C_o, C_{in}, R_{in})$
- We can estimate the required first harmonic current from

$$I_{\omega_0} = \frac{v_o}{R_T'}$$

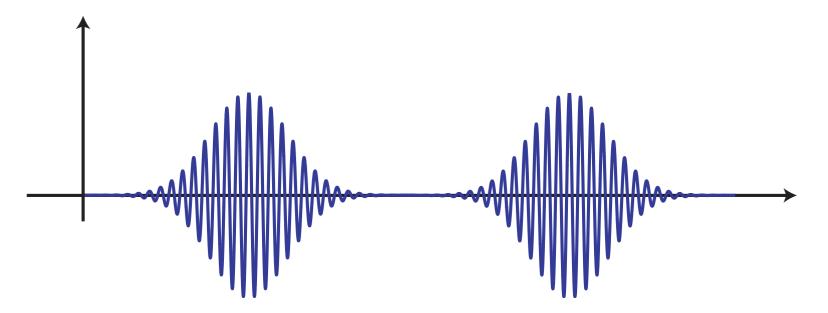
## **Design** (cont)

- This is an estimate because the exact value of  $R_T$  is not known until we specify the operating point of the transistor. But a good first order estimate is to neglect the loading and use  $R_T^\prime$
- We can now solve for the bias point from

$$I_{\omega_1} = \frac{2I_1(b)}{I_0(b)}I_Q$$

- b is known since it's the oscillation amplitude normalized to kT/q and divided by n. The above equation can be solved graphically or numerically.
- Once  $I_Q$  is known, we can now calculate  $R_T''$  and iterate until the bias current converges to the final value.

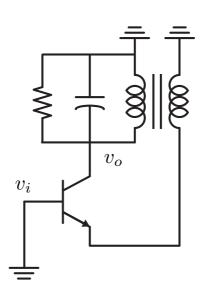
# Squegging



- Squegging is a parasitic oscillation in the bias circuitry of the amplifier.
- It can be avoided by properly sizing the emitter bypass capacitance

$$C_E \le nC_T$$

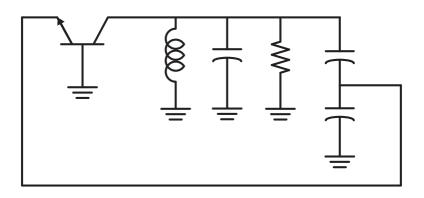
#### **Common Base Oscillator**



- Another BJT oscillator uses the common-base transistor. Since there is no phase inversion in the amplifier, the transformer feedback is in phase.
- Since we don't need phase inversion, we can use a simpler feedback consisting of a capacitor divider.

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# **Colpitts Oscillator**

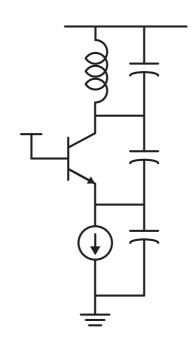


• The cap divider works at higher frequencies. Under the cap divider approximation  $f \approx \frac{C_1}{C_1 + C_2'} = \frac{1}{n}$ 

$$n = 1 + \frac{C_2'}{C_1}$$

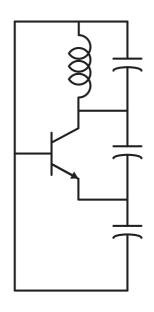
•  $C_2'$  includes the loading from the transistor and current source.

# **Colpitts Bias**



Since the bias current is held constant by a current source  $I_Q$  or a large resistor, the analysis is identical to the BJT oscillator with transformer feedback. Note the output voltage is divided and applied across  $v_{BE}$  just as before.

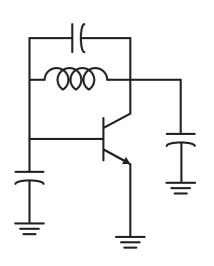
# **Colpitts Family**

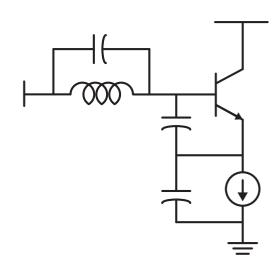


- If we remove the explicit ground connection on the oscillator, we have the template for a generic oscillator.
- It can be shown that the Colpitts family of oscillator never squegg.

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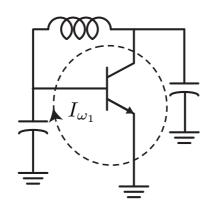
#### **CE and CC Oscillators**





- If we ground the emitter, we have a new oscillator topology, called the Pierce Oscillator. Note that the amplifier is in CE mode, but we don't need a transformer!
- Likewise, if we ground the collector, we have an emitter follower oscillator.
- A fraction of the tank resonant current flows through  $C_{1,2}$ . In fact, we can use  $C_{1,2}$  as the tank capacitance.

#### **Pierce Oscillator**



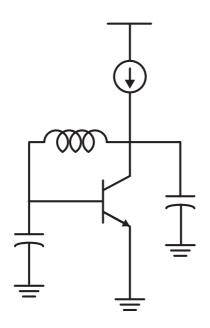
• If we assume that the current through  $C_{1,2}$  is larger than the collector current (high Q), then we see that the same current flows through both capacitors. The voltage at the input and output is therefore

$$v_o = I_{\omega_1} \frac{1}{j\omega C_1} \qquad \qquad v_i = -I_{\omega_1} \frac{1}{j\omega C_2}$$

or

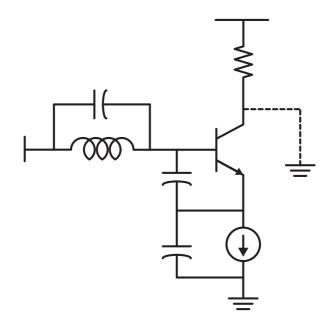
$$\frac{v_o}{v_i} = n = \frac{C_1}{C_2}$$

#### **Pierce Bias**



- A current source or large resistor can bias the Pierce oscillator.
- Since the bias current is fixed, the same large signal oscillator analysis applies.

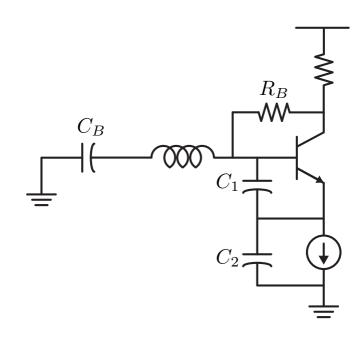
#### **Common-Collector Oscillator**



Note that the collector can be connected to a resistor without changing the oscillator characteristics. In fact, the transistor provides a buffered output for "free".

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## **Clapp Oscillator**



- The common-collector oscillator shown above uses a large capacitor  $C_T$  to block the DC signal at the base.  $R_B$  is used to bias the transistor.
- If the shunt capacitor  $C_T$  is eliminated, then the capacitor  $C_B$  can be used to resonate with L and the series combination of  $C_1$  and  $C_2$ . This is a series resonant circuit.