

Assignment 3, TTK4190

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1 Autopilot design

1.1 Heading autopilot

Her skriver vi om Heading autopilot

1.2 Speed autopilot

Her skriver vi om speed autopilot

2 Path following and Path tracking

2.1 Path Generation

Her skriver vi om Path generation

2.2 Path following

Her skriver vi om Path following

2.3 Path Tracking

Her skriver vi om Path tracking