

- 1) <https://github.com/eriklovekin>
- 2) The residuals for both (a) and (b) are approximately 0.
- 3) The error in the function definition is from publishing without inputs. As can be seen from the bode plots, the MATLAB and custom responses are similar, but the custom response is exact at the critical omega where as MATLAB is accurate at omega=0.

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HW1 Problem 2

```
b = RR_poly([2,-2,5,-5],1);
a = RR_poly([-1 1 -3 3 -6 6],1);
f = RR_poly([-1 -1 -3 -3 -6 -6],1);
```

(a)

```
[x,y] = RR_diophantine(a,b,f);
test = trim(a*x+b*y);
residual = norm(f-test)% test that answer is correct (should = 0)

residual =
    1.1369e-13
```

(b)

```
f_roots = RR_roots(f);
k = 6;
f2 = RR_poly([f_roots -20*ones(1,k)],1);% Add k poles to make y/x proper
[x2,y2] = RR_diophantine(a,b,f2);
test2 = trim(a*x2+b*y2);
residual2 = norm(f2-test2)% test result is correct (should = 0)

residual2 =
    1.9457e-04
```

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ESL_C2D_matched

```
function [Gz] = ESL_C2D_matched(Ds,h,omegac,proper)
% function [Gz] = ESL_C2D_matched(Ds,h)
% Convert Ds(s) to Dz(z) using matched method with timestep h.
% Match gain at default omega = 0 or at critical gain omegac.

if nargin < 4 % Assume proper
    proper = true;
elseif nargin < 3 % Assume desired omegac = 0
    omegac = 0;
    proper = true;
end

Gz = RR_tf(exp(Ds.z*h),exp(Ds.p*h),1);% Initialize Gz
Gz.h = h;

nz_inf = length(Gz.p)-length(Gz.z);% # Zeros at infinity = # poles - #
zeros

Gz.z = [Gz.z -1*ones(1,nz_inf-1)];% Add poles at z=-1

if proper
    Gz.z = [Gz.z Inf(1)];% Final pole at inf
else
    Gz.z = [Gz.z -1];% Final pole at -1
end

Ks = abs(RR_evaluate(Ds,omegac*1i));% Continuous gain at omegac
Kz = abs(RR_evaluate(Gz,exp(omegac*1i*h)));% Discrete gain at omegac

Gz = Gz*Ks/Kz;% Scale discrete gain
end

Not enough input arguments.
Error in ESL_C2D_matched (line 14)
    Gz = RR_tf(exp(Ds.z*h),exp(Ds.p*h),1);% Initialize Gz
```

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ESL_C2D_matched test

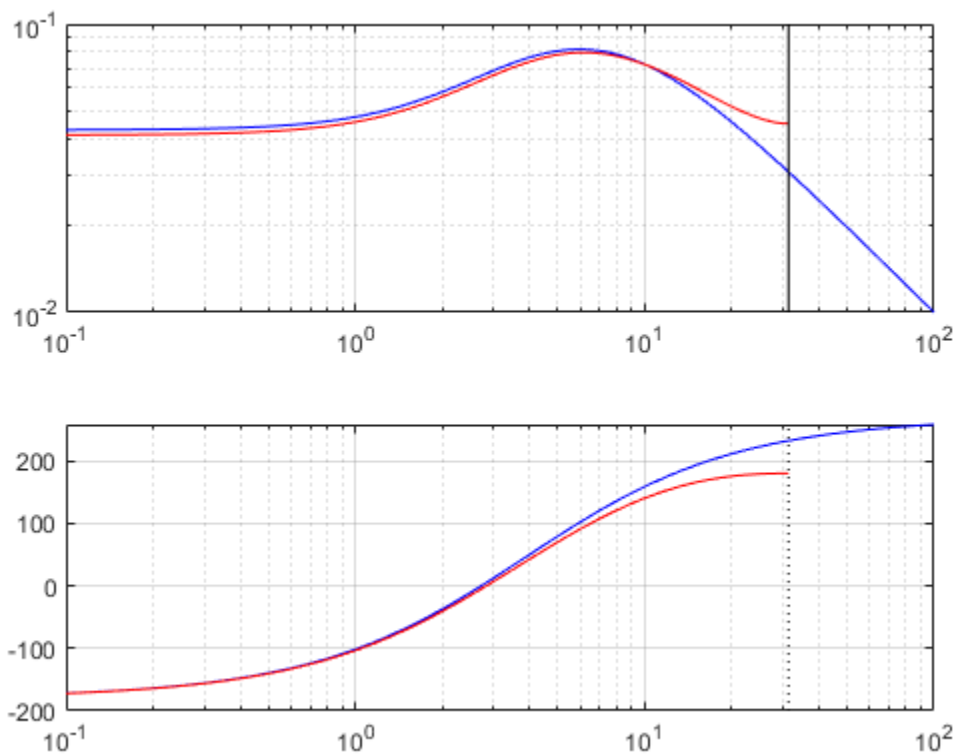
```
close all
num = [1 5 6];
den = [1 -16 83 -140];
h = 0.1;% Time step size
omegac = 10;% critical frequency

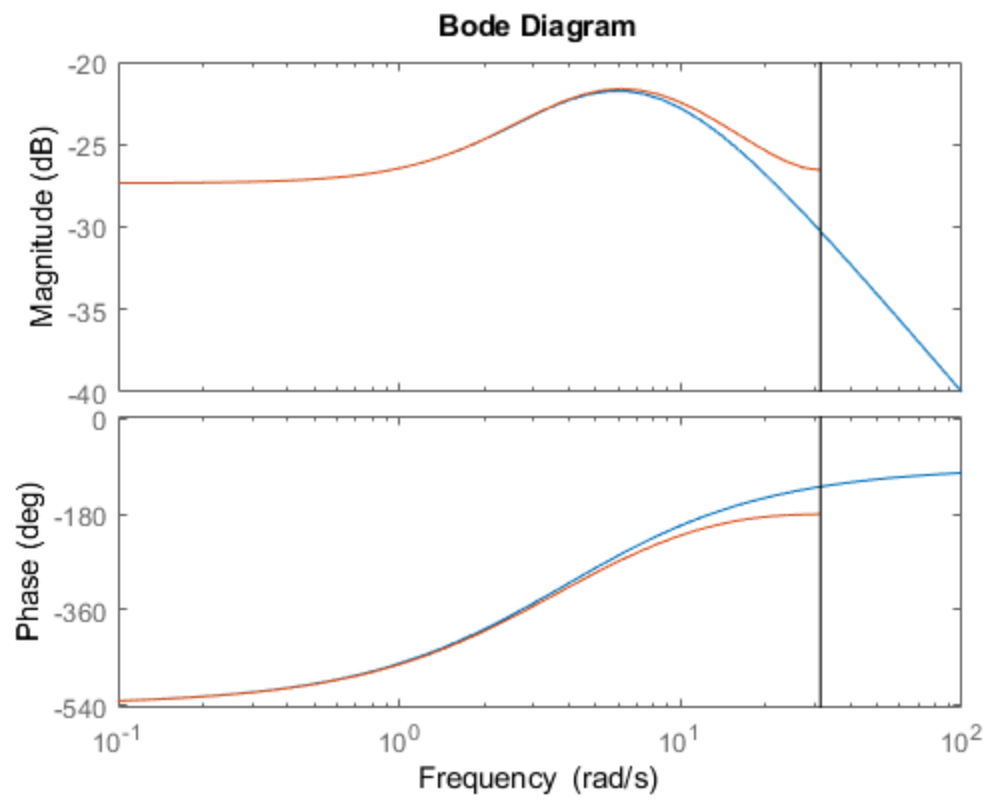
Ds = RR_tf(num,den);% Define continuous functions
Ms = tf(num,den);

Dz = ESL_C2D_matched(Ds,h,omegac); %discretize
Mz = c2d(Ms,h,'matched'); %discretize with MATLAB method

figure(1)
hold on
RR_bode(Ds)
RR_bode(Dz)
hold off

figure(2)
hold on
bode(Ms)
bode(Mz)
hold off
```





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