

Macroeconomics II, Lecture I: The Real Business Cycle Model: Basics

Erik Öberg

This course part

- Business cycle models
 - ▶ 6 lectures
 - ▶ Frameworks for studying aggregate fluctuations
- Frictional labor markets
 - ▶ 4 lectures
 - ▶ Digging deeper into the determinants of household income
- Incomplete asset markets
 - ▶ 3 lectures
 - ▶ Digging deeper into the determinants of consumption-savings dynamics, taking the income process as given
- 1 Dynare tutorial session; 6 problem sets
- Grading:
 - ▶ Problem sets 30%, Exam 70%
 - ▶ Part I: 25%, Part II: 75%
 - ▶ To pass, you need 50% of the points, with at least 30% from the exam

Learning outcomes

- ① You should know a few key empirical facts about business cycles, the labor market and the distribution/dynamics of earnings-consumption-wealth
- ② You should be able to construct, solve and analyze workhorse models within the business-cycle, macro-labor and incomplete-markets literatures
 - ▶ Within these models, you should know which assumptions are essential and which can be relaxed
 - ▶ You should acquire the technical skills needed to solve/analyze the presented models
- ③ You should know key predictions of the models presented and how the models can be used to interpret the data

Hidden agenda

- Two guiding principles:
 - ① You should acquire sufficient tools to continue studying on your own (especially for those that decide to specialize in macro)
 - ② You should acquire an overview about how research in this field looks like, and how it relates to other areas of economic research (labor, public finance etc.)
- Repeated emphasis on how to use models for *quantitative interpretation* of the data
- Repeated emphasis on how to use micro data for informing macroeconomic research

My teaching style

- In class, we go through most steps, but not all, when solving the models
 - ▶ I expect you to work (or know how to work) through the missing pieces at home
- The problem sets are the heart of the course
 - ▶ Primary benefit is that you learn economics
 - ▶ Secondary benefit is that you practice for the main exam
 - ▶ Third benefit is that you gain som points for the exam
- References: I use convention Name-Name-... (journal, year)
 - ▶ Example: Gabaix-Lasry-Lions-Moll (Ecmtre, 2016)
 - ▶ Abbreviation when reference is recurrently repeated
 - ▶ If not published, I do not write out journal
- I very much appreciate questions and you pointing out errors, inconsistencies or anything else that makes my slides/teaching unclear

Part I: Business cycles

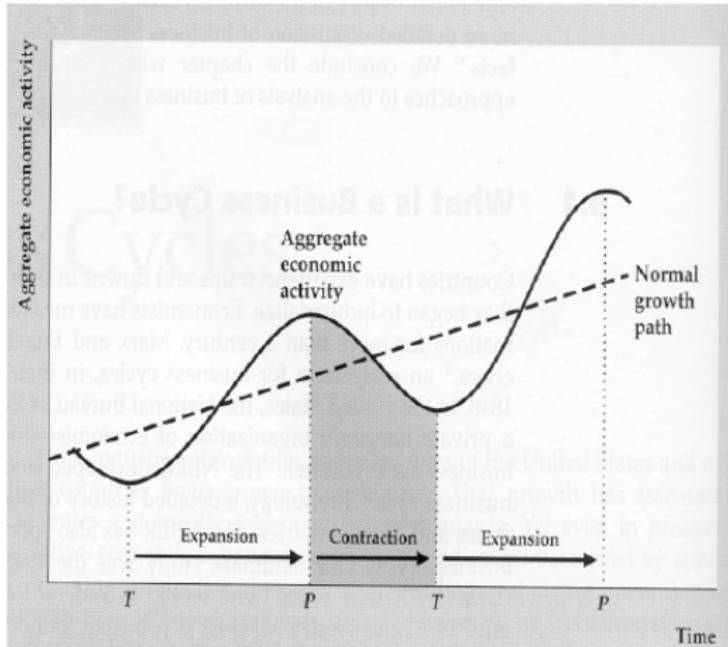
- Basic questions:
 - ① What are business cycles?
 - ② What causes business cycles?
 - ③ What consequences do they have?
 - ④ When, and if so, how, should government policy intervene?
- The facts and models that we introduce represent *an attempt* to start reasoning about these questions
- As you will see, there are many questions raised by these facts and models that we still do not have great answers to

Agenda

- ① Business cycle facts
- ② Math preliminaries
- ③ The Real Business Cycle model: Setup and solution
- ④ The Real Business Cycle model: Analysis

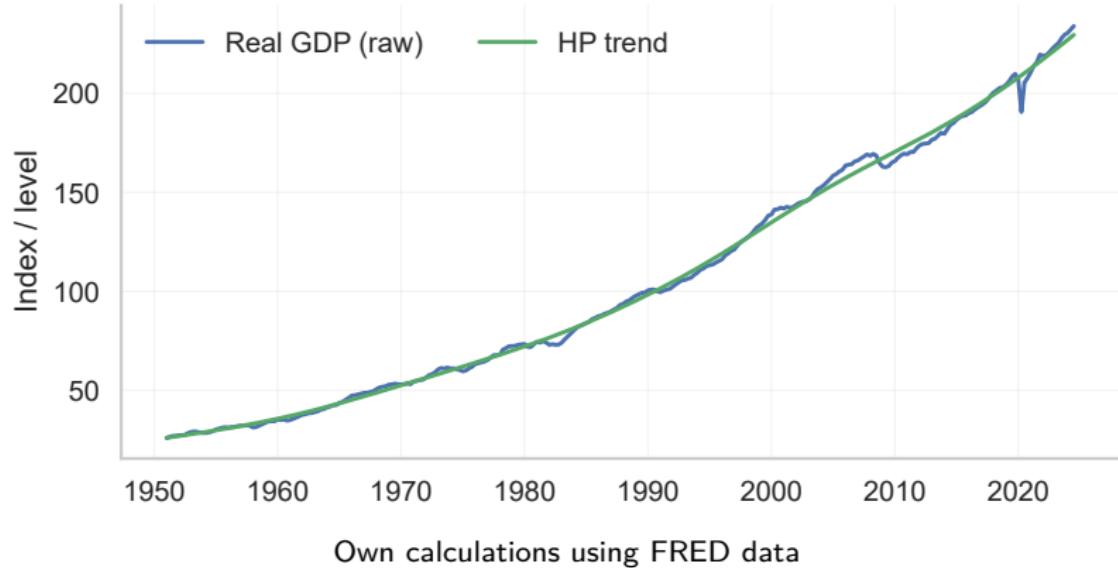
Business cycle facts

Two approaches to business cycle measurement



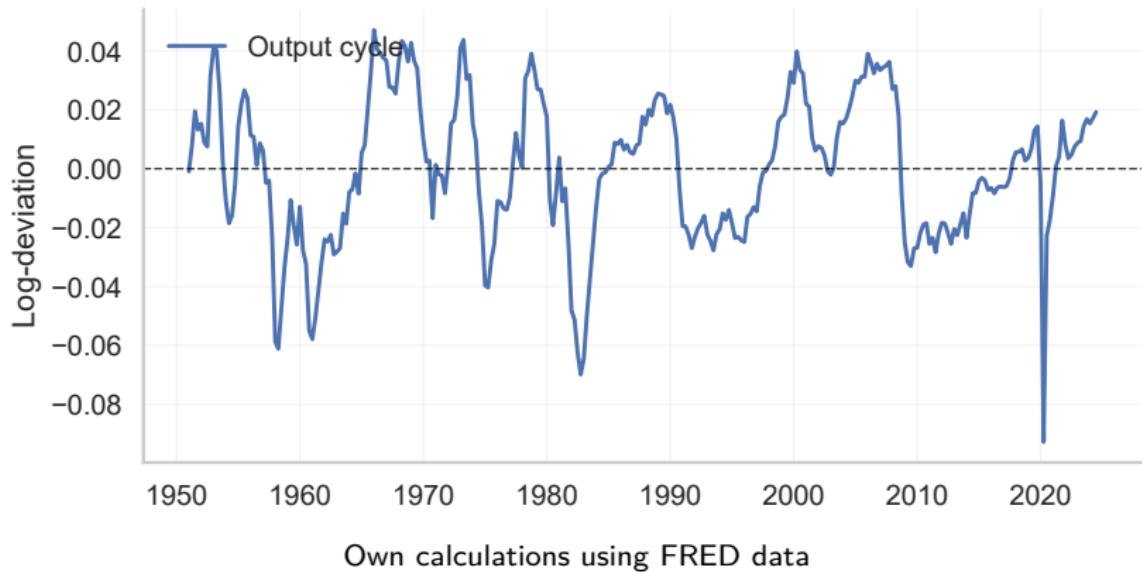
- NBER recession dating focus on periods of contraction
- In our course (and most academic literature): Periods where output is below trend

US post-war real GDP: trend and cycle



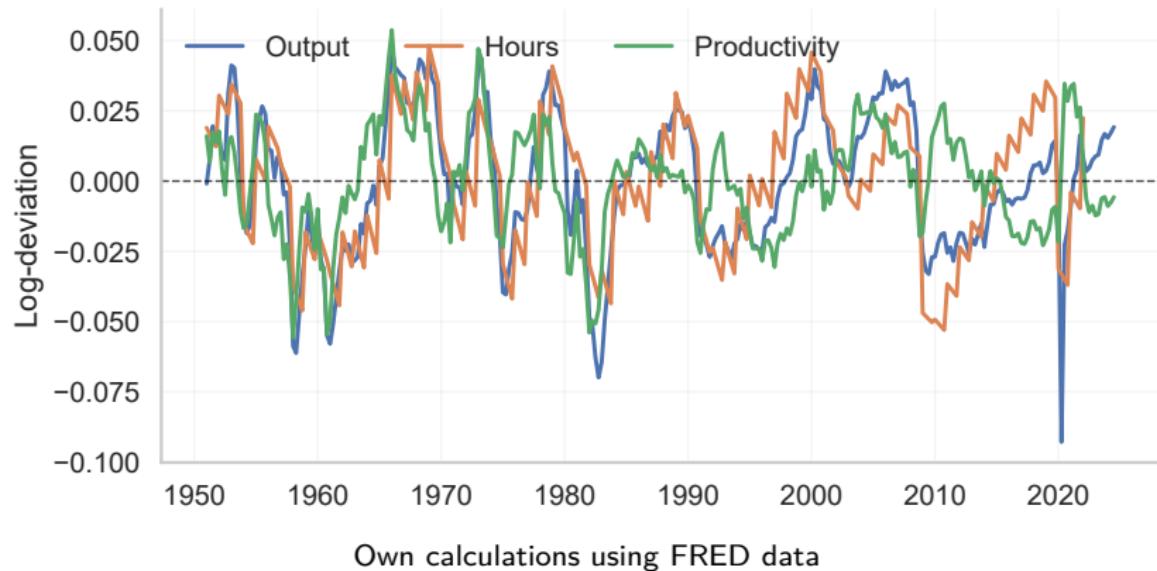
- Our focus: the deviations of blue from orange line

US Cyclical Real GDP



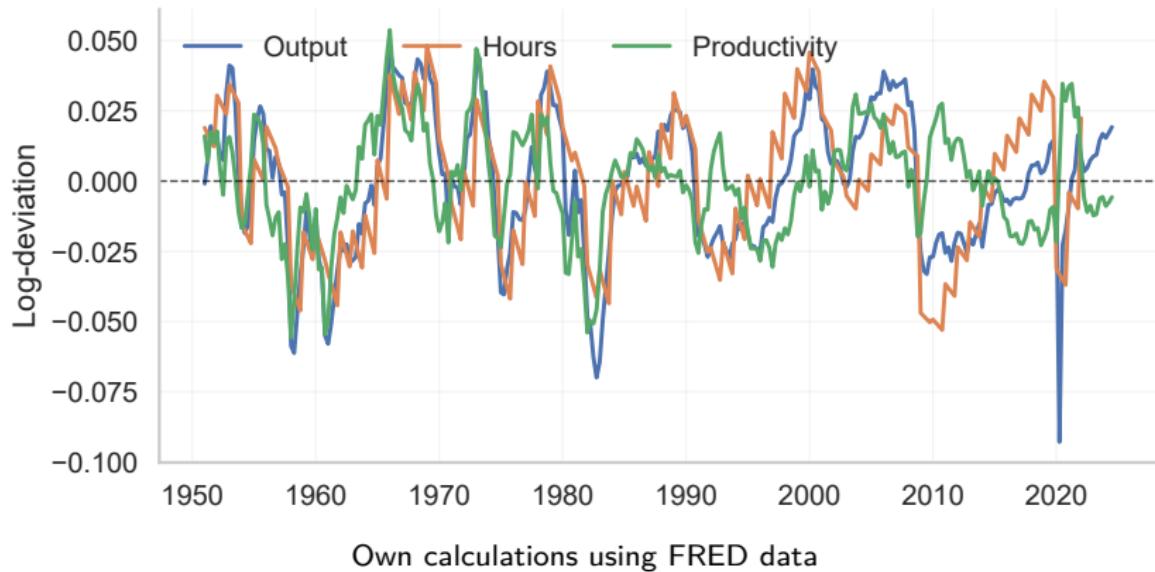
- Fact 1: considerable variations in GDP growth from year to year

US Cyclical Real GDP + Hours and productivity



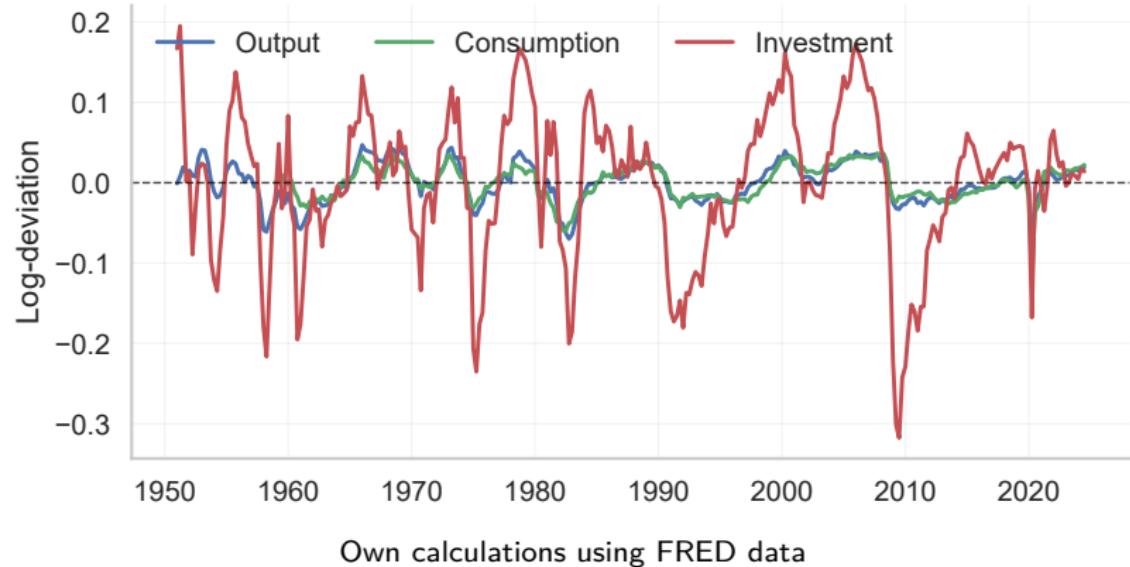
- Fact 2: Many key macroeconomic aggregates comove with GDP

US Cyclical Real GDP + Hours and productivity



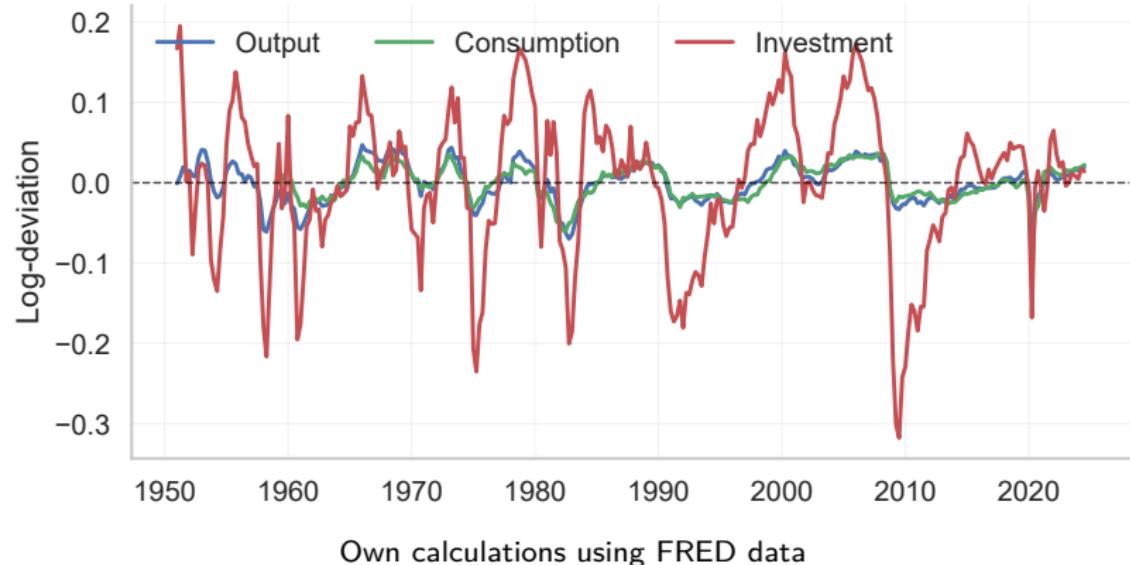
- Fact 3: Hours as volatile as GDP, Productivity less volatile than GDP

US Cyclical Real GDP + Consumption and Investment



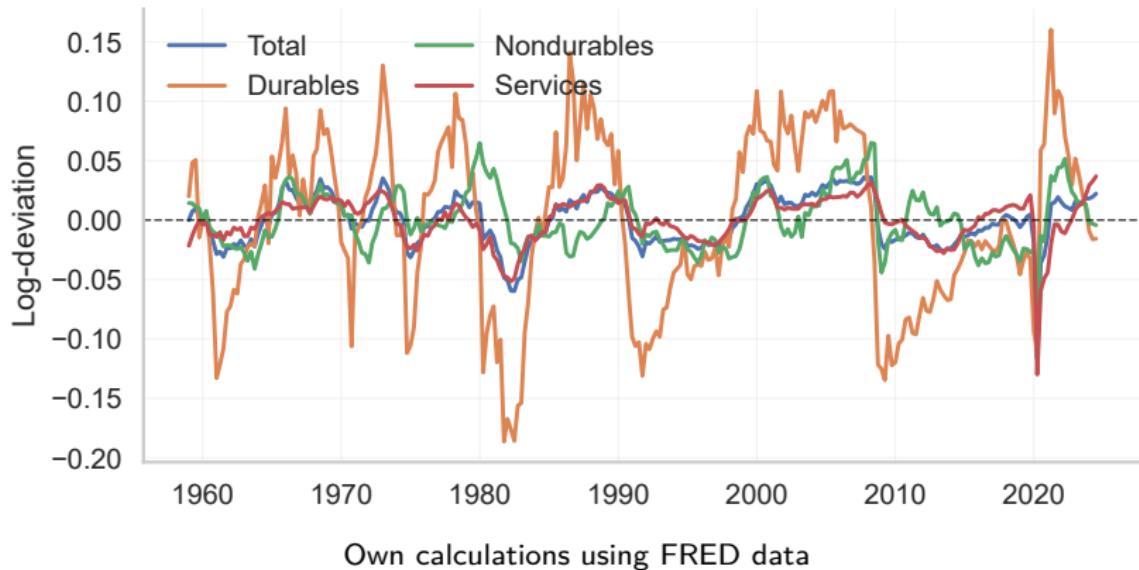
- Fact 2 again: Many key macroeconomic aggregates comove with GDP

US Cyclical Real GDP + Consumption and Investment



- Fact 4: Investment more volatile, consumption less volatile than GDP

US Cyclical Real consumption



- Moreover: Investment-like consumption goods more volatile than other consumption goods...

Summary of US business cycle moments

Series	SD	Rel. SD	Corr Y_t	Autocorr	Corr Y_{t-4}	Corr Y_{t+4}
Y_t (Output)	0.017	1.00	1.00	0.79	0.08	0.08
C_t (Consumption)	0.011	0.66	0.76	0.67	0.15	0.02
I_t (Investment)	0.044	2.67	0.76	0.86	-0.05	0.23
N_t (Hours)	0.021	1.27	0.87	0.82	0.28	-0.06
A_t (TFP)	0.013	0.76	0.78	0.76	-0.30	0.31
W_t (Wage)	0.012	0.69	-0.01	0.71	-0.11	0.17
R_t (Real rate)	0.004	0.26	0.00	0.47	0.27	-0.28
P_t (Price level)	0.010	0.58	-0.08	0.91	0.14	-0.44

Eric Sims, RBC notes (Spring 2024), Table 1. Quarterly HP-filtered data 1947Q1–2022Q3 ($\lambda = 1600$).

On top of the facts already discussed, we see that

- All series display a considerable degree of persistence
- Wages and interest rates are not very correlated with output (especially not contemporaneously correlated)

US Business cycle: key facts

- ① Standard deviation of US quarterly Real GDP ~ 2 percent
- ② Many macroeconomic variables comove with output
- ③ Productivity less volatile than output, Hours worked as volatile as output
- ④ Investment more volatile than output, consumption less volatile than output
- ⑤ All series display considerable degree of persistence
- ⑥ Wages and interest rates are not very correlated with output

Math preliminaries

Math preliminaries I: Natural Logarithms

- An appealing feature of the natural logarithm is that for small x , we have that

$$\log(1 + x) \approx x$$

- As a result, we can interpret log differences as percentage growth rates

$$\begin{aligned}\log(x_1) - \log(x_2) &= \log\left(\frac{x_1}{x_2}\right) \\ &= \log\left(1 + \frac{x_1 - x_2}{x_2}\right) \\ &\approx \frac{x_1 - x_2}{x_2}\end{aligned}$$

Math preliminaries II: Log-linearization

- An equilibrium characterization is set of n equations in n unknowns

$$F^1(\mathbf{X}) = 0, F^2(\mathbf{X}) = 0, \dots, F^n(\mathbf{X}) = 0$$

where $\mathbf{X} = \{X_1, X_2, \dots, X_n\}$ are endogenous variables

- For example, the Cobb-Douglas production function represent one such equation

$$Y_t = A_t K_t^\alpha N_t^{1-\alpha}$$

where the endogenous variables are Y_t, A_t, K_t, N_t .

- When analyzing the dynamic equilibrium response to shocks, we often consider a **log-linear approximation** of the equilibrium characterization $\{F^i(\mathbf{X})\}_{i=0}^n$ around its steady state

Math preliminaries II: Log-linearization

- Let's focus on the two-variable case
- Taylor's theorem: the value of a differentiable function F at the point X_1, X_2 , can be approximated knowing its value at the point X_1^*, X_2^* , like

$$F(X_1, X_2) \approx F(X_1^*, X_2^*) + \frac{\partial F(X_1^*, X_2^*)}{\partial X_1}(X_1 - X_1^*) + \frac{\partial F(X_1^*, X_2^*)}{\partial X_2}(X_2 - X_2^*)$$
$$\Leftrightarrow \Delta F(X_1, X_2) \approx F_1(X_1^*, X_2^*)\Delta X_1 + F_2(X_1^*, X_2^*)\Delta X_2$$

- If we take logs first, this becomes

$$\begin{aligned}\Delta \log F(X_1, X_2) &\approx \frac{\partial \log F(X_1^*, X_2^*)}{\partial X_1} \Delta X_1 + \frac{\partial \log F(X_1^*, X_2^*)}{\partial X_2} \Delta X_2 \\ &= \frac{F_1(X_1^*, X_2^*)}{F(X_1^*, X_2^*)} \Delta X_1 + \frac{F_2(X_1^*, X_2^*)}{F(X_1^*, X_2^*)} \Delta X_2 \\ &= \frac{F_1(X_1^*, X_2^*) X_1^*}{F(X_1^*, X_2^*)} \hat{x}_1 + \frac{F_2(X_1^*, X_2^*) X_2^*}{F(X_1^*, X_2^*)} \hat{x}_2\end{aligned}$$

where $\hat{x}_i = \frac{X_i - X_i^*}{X_i^*} \approx \Delta \log X_i$

Math preliminaries II: Log-linearization

- Result: the percentage growth of the function value can be approximated with an appropriate linear combination of the percentage growths in the function variables
- Log-linearizing** = applying this formula
- Lets consider a few examples from dynamic economic models
- For any variable X_t , denote
 - its steady state value with X
 - its log with x_t
 - its log steady state value x
 - its log difference to steady state with \hat{x}_t

Math preliminaries II: Log-linearization (do on whiteboard)

- Example 1: Capital law of motion

$$K_{t+1} = (1 - \delta)K_t + I_t$$

- Log-linearizing around the steady state gives

$$\hat{k}_{t+1} \approx (1 - \delta)\hat{k}_t + \delta\hat{i}_t$$

- Example 2: Resource constraint

$$Y_t = C_t + I_t$$

- Log-linearizing around the steady state gives

$$\hat{y}_t \approx \frac{C}{Y}\hat{c}_t + \frac{I}{Y}\hat{i}_t$$

Math preliminaries II: Log-linearization

- Multiplicative-exponential relationships are log-linear to start with, these need not to be approximated
- Example: Cobb-Douglas production function:

$$Y_t = A_t K_t^\alpha N_t^{1-\alpha}$$

- Taking logs

$$y_t = a_t + \alpha k_t + (1 - \alpha) n_t$$

- Subtracting steady state

$$\begin{aligned} y_t - y &= a_t - a + \alpha(k_t - k) + (1 - \alpha)(n_t - n) \\ \hat{y}_t &= \hat{a}_t + \alpha \hat{k}_t + (1 - \alpha) \hat{n}_t \end{aligned}$$

Math preliminaries III: Systems of linear difference equations

- After log-linearizing, the typical macro model can be written as a **forward-looking auto-regressive system** of **linear difference equations**:

$$\mathbf{A}_1 \mathbf{x}_t = \mathbf{A}_2 E_t \mathbf{x}_{t+1} + \mathbf{B}_1 \epsilon_t$$

where

- $\mathbf{x}_t = [x_{1t}, \dots, x_{nt}]'$ is a vector of endogenous variables
- $\epsilon_t = [\epsilon_{1t}, \dots, \epsilon_{kt}]'$ is a vector of exogenous shocks

Math preliminaries III: Systems of linear difference equations

- We are typically interested in finding a **bounded** solution to this system, in response to the shocks ϵ_t
- Question: Under what conditions does a **unique bounded solution** exist?
- Rewrite system as

$$\mathbf{x}_t = \mathbf{A}E_t\mathbf{x}_{t+1} + \mathbf{B}\epsilon_t$$

where $\mathbf{A} = \mathbf{A}_1^{-1}\mathbf{A}_2$ and $\mathbf{B} = \mathbf{A}_1^{-1}\mathbf{B}_1$

Math preliminaries III: Systems of linear difference equations

- To gain intuition, consider a 1-equation system with one forward-looking variable

$$x_t = aE_t x_{t+1} + \epsilon_t$$

with the shock sequence $\epsilon_t = \epsilon > 0$, $\epsilon_{t+s} = 0$ for all $s > 0$

- Any solution satisfies

$$\begin{aligned} x_t &= aE_t [aE_{t+1}x_{t+2}] + \epsilon_t \\ &= \dots \\ &= \lim_{T \rightarrow \infty} a^T E_t x_{t+T} + \epsilon_t \end{aligned}$$

- What is a solution? A: Any stochastic process for x_t that satisfies this equation.
- What is a **bounded solution**? A: any stochastic process for x_t such that $x_{t+s} \leq M$ for some $M < \infty$ and all $s \geq 0$
- Ergo, a bounded solution has $\lim_{T \rightarrow \infty} E_t x_{t+T} < \infty$

Math preliminaries III: Systems of linear difference equations

- Our equation:

$$x_t = \lim_{T \rightarrow \infty} a^T E_t x_{t+T} + \epsilon_t$$

- Q: How many solutions to this equation has $\lim_{T \rightarrow \infty} E_t x_{t+T} < \infty$?
- Suppose $a < 1$, then
 - ▶ Given $\lim_{T \rightarrow \infty} E_t x_{t+T} < \infty$, we have $\lim_{T \rightarrow \infty} a^T E_t x_{t+T} = 0$
 - ▶ Hence, $x_t = \epsilon_t$ is the unique bounded solution
- Suppose $a \geq 1$, then
 - ▶ any stochastic process for x_t with $\lim_{T \rightarrow \infty} E_t x_{t+T} = 0$ is a solution.
 - ▶ Example:
$$x_t = \epsilon_t + \nu_t, \quad \nu_t \sim F \text{ with } E_t \nu_t = 0$$
 - ▶ Infinitely many bounded solutions!

Math preliminaries III: Systems of linear difference equations

- Consider the general system of n equations:

$$\mathbf{x}_t = \mathbf{A}E_t\mathbf{x}_{t+1} + \mathbf{B}\epsilon_t \quad (1)$$

- The counterpart of the AR(1) scalar a in our 1-equation system are the eigenvalues of \mathbf{A}
- The eigenvalues are the solution to the deterministic equation

$$\det(\mathbf{A} - \mathbf{I}\lambda) = 0$$

- Theorem (Blanchard-Kahn, Ecmttra 1981): There exist a **unique bounded solution** to the system (1) if and only if \mathbf{A} has the **same number of eigenvalues inside the unit circle as the number of forward-looking variables**.
- Forward-looking variables = variables that are not pre-determined

The Real Business Cycle Model: Setup and solution

Overview

- Vanilla RBC model = Neoclassical growth model with stochastic TFP shocks
- No market frictions: dynamics caused by efficient response of production inputs to technology shocks
- Why use this as our starting point?
 - ① To establish a minimal efficient benchmark
 - ★ Modern business cycle models can be thought of as extensions to this framework
 - ★ Policy analysis often boils down to the question: "how we can make the world behave more like an RBC model?"
 - ② Use this model as an example for understanding commonly employed methods
 - ★ Log-linear approximation of model dynamics
 - ★ Calibration
- Origination: Kydland-Prescott (Ecmta, 1982); King-Plosser (AER, 1984)
 - ▶ Important prior developments: Rational expectations paradigm (Lucas, JET 1972); structural econometrics (Sargent, JPE 1976)
 - ▶ These models and methods completely transformed economic research (not only macro!)

Model structure

- A representative household chooses consumption C , labor supply N and investment I , taking W and R as given
 - ▶ \Rightarrow Supply curves of N and K , Demand curve for goods Y
- A representative firm chooses capital and labor input, taking W and R and a stochastic process for TFP A_t as given
 - ▶ \Rightarrow Demand curves of N and K , Supply curve for Y
- Markets are complete: every good can be traded at very point in time.
- Equilibrium concept: W and R has to be such that when agents optimize, we have that
 - ▶ Labor supply = Labor Demand
 - ▶ Capital supply = Capital Demand
 - ▶ Goods supply = Goods Demand
- Since markets are complete and there are no distortions, the decentralized equilibrium and the social planner solution yield the same allocation
- We proceed with using the decentralized setup

Household problem

- Program of the representative household

$$\begin{aligned} & \max_{\{C_t, N_t^s, I_t, K_{t+1}^s\}} E_0 \sum_{t=0}^{\infty} \beta^t [U(C_t) - V(N_t^s)] \\ \text{s.t. } & C_t + I_t \leq W_t N_t^s + R_t^r K_t^s, \\ & K_{t+1}^s \leq (1 - \delta) K_t^s + I_t, \\ & C_t, N_t^s, I_t \geq 0, \end{aligned}$$

with $U(C_t)$, $V(N_t^s)$ satisfying the usual regularity conditions

- Note:
 - ▶ Separable preferences for simplicity
 - ▶ The household owns the capital stock
 - ▶ R_t^r = rental rate earned on capital stock rented to firm in period t
 - ▶ $R_t^r \neq$ risk-free real interest rate R_t
 - ▶ Return on period t investment, $R_{t+1}^r + (1 - \delta)$, not known in period t
 - ▶ However, $E_t [R_{t+1}^r + (1 - \delta)]$ intimately related to R_t
 - ★ In a first-order approximation, they are, in fact, the same (more on this in Lecture III)

Firm problem

- The firm rents labor and capital from the household, can freely adjust in each period
⇒ Static problem
- Program of the representative firm

$$\begin{aligned} \max_{\{N_t^d, K_t^d\}} \quad & A_t F(K_t^d, N_t^d) - R_t^r K_t^d - W_t N_t^d \\ \text{s.t.} \quad & A_t = A_{t-1}^{\rho_a} \exp(\epsilon_t) \end{aligned}$$

with $F_t(\cdot)$ being homogeneous of degree 1

- Note:
 - ▶ Competitive markets ensures profits are zero
 - ▶ The process for A_t is AR(1) in logs - parsimonious, and captures the fluctuations in measured TFP well

Equilibrium

- A **competitive equilibrium** is a set of allocations $\{C_t, N_t^s, I_t, K_t^s, N_t^d, N_t^d\}$ and prices $\{W_t, R_t^r\}$ such that

- ▶ Given $\{W_t, R_t^r\}$, $\{C_t, N_t^s, I_t, K_t^s\}$ solve the household problem
- ▶ Given $\{W_t, R_t^r\}$, $\{N_t^d, K_t^d\}$ solve the firm problem
- ▶ Markets clear:

Goods Market: $C_t + I_t = A_t F(K_t^d, N_t^d)$ for all t

Labor Market: $N_t^s = N_t^d$ for all t

Capital Market: $K_t^s = K_t^d$ for all t

- Going forward, I will skip supply-demand notation and simply use N_t, K_t in both the household and firm problem

Equilibrium (imposing some market clearing)

- A **competitive equilibrium** is a set of allocations $\{C_t, N_t, I_t, K_t\}$ and prices $\{W_t, R_t^r\}$ such that
 - ▶ Given $\{W_t, R_t^r\}$, $\{C_t, N_t, I_t, K_t\}$ solve the household problem
 - ▶ Given $\{W_t, R_t^r\}$, $\{N_t, K_t\}$ solve the firm problem
 - ▶ Markets clear:
$$C_t + I_t = A_t F(K_t, N_t) \text{ for all } t$$
- Comment: In fact, now the last equation is redundant. Since we have imposed that the capital and labor market clear, the goods market will clear by [Walras law](#)

Equilibrium (imposing some market clearing and Walras' law)

- A **competitive equilibrium** is a set of allocations $\{C_t, N_t, I_t, K_t\}$ and prices $\{W_t, R_t^r\}$ such that
 - ▶ Given $\{W_t, R_t^r\}$, $\{C_t, N_t, I_t, K_t\}$ solve the household problem
 - ▶ Given $\{W_t, R_t^r\}$, $\{N_t, K_t\}$ solve the firm problem

Model solution

- What is a model solution?
 - ▶ A set of policy functions that specifies the equilibrium response of the endogenous variables as a function of **parameters** and the realization of the **exogenous shocks**
- Two ways to solve for the equilibrium:
 - ① Global solution: solve for global policy functions, using, e.g., value function iteration (or a neural net)
 - ② Log-linear approximation: Do a local approximation of the policy functions around some point of the equilibrium
- Here, we will explore option 2
- Why?
 - ▶ Because we know how to handle linear difference equations
 - ▶ Because log-differences have an appealing interpretation (percent growth)
 - ▶ Because, in practice, a large class of models that we use are, in fact, not very non-linear
- In practice, this means that we will **log-linearize** the model around the (non-stochastic) **steady state**

Log-linearization cook book

- ① Start with making an **equilibrium characterization**
 - ▶ List all equations that must hold true in equilibrium
 - ▶ Given our equilibrium definition, they must consist of
 - ★ Equations that must be satisfied in a solution to the household problem
 - ★ Equations that must be satisfied in a solution to the firm problem
 - ★ Market clearing conditions
- ② Solve for the **steady state**
 - ▶ Typically a simple algebraic exercise once you have the equilibrium characterization
- ③ Log-linearize the **equilibrium characterization** around the **steady state**

Step 1: Equilibrium characterization

- Lagrangian to the household problem:

$$\mathbf{L} = E_0 \left(\sum_{t=0}^{\infty} \beta^t [U(C_t) - V(N_t)] - \sum_{t=0}^{\infty} \lambda_t [C_t + K_{t+1} - W_t N_t - (R_t^r + (1-\delta))K_t] \right)$$

where I have substituted the capital accumulation equation into the budget constraint

- First order conditions

$$C_t : \quad \beta^t U'(C_t) - \lambda_t = 0$$

$$N_t : \quad -\beta^t V'(N_t) + \lambda_t W_t = 0$$

$$K_{t+1} : \quad -\lambda_t + E_t \lambda_{t+1} (R_{t+1}^r + (1-\delta)) = 0$$

- In an **interior solution**, these equations + the constraints must be satisfied, and also the **transversality condition**:

$$\lim_{T \rightarrow \infty} \beta^T K_T U'(C_T) \leq 0$$

- In practice, we search for a candidate solution to the household problem, then check that this candidate also satisfies transversality

Equilibrium characterization II

- Necessary conditions for household optimality:

$$\begin{aligned}U'(C_t)W_t &= V'(N_t) \\U'(C_t) &= \beta E_t(R_{t+1}^r + (1 - \delta))U'(C_{t+1}) \\C_t + I_t &= W_t N_t + R_t^r K_t \\K_{t+1} &= (1 - \delta)K_t + I_t\end{aligned}$$

- Necessary conditions for firm optimality:

$$\begin{aligned}R_t^r &= A_t F_k(K_t, N_t) \\W_t &= A_t F_n(K_t, N_t) \\A_t &= A_{t-1}^{\rho_a} \exp(\epsilon_t)\end{aligned}$$

- This completes the equilibrium characterization
- Again: resource constraint $C_t + I_t = A_t F(K_t, N_t)$ is implied by Walras' law
 - ▶ Going forward, however, I will add the resource constraint, and drop the household budget constraint instead

Equilibrium characterization III

- Summing up, the equilibrium is characterized by:

$$U'(C_t)W_t = V'(N_t)$$

$$U'(C_t) = \beta E_t [(R_{t+1}^r + (1 - \delta)) U'(C_{t+1})]$$

$$C_t + I_t = A_t F(K_t, N_t)$$

$$K_{t+1} = (1 - \delta)K_t + I_t$$

$$R_t^r = A_t F_k(K_t, N_t)$$

$$W_t = A_t F_n(K_t, N_t)$$

$$A_t = A_{t-1}^{\rho_a} \exp(\epsilon_t)$$

- Seven variables $\{C_t, N_t, I_t, K_t, W_t, R_t^r, A_t\}$ and seven equations

Equilibrium characterization III (it's nice with output as a separate variable)

- Summing up, the equilibrium is characterized by:

$$U'(C_t)W_t = V'(N_t)$$

$$U'(C_t) = \beta E_t [(R_{t+1}^r + (1 - \delta)) U'(C_{t+1})]$$

$$C_t + I_t = Y_t$$

$$Y_t = A_t F(K_t, N_t)$$

$$K_{t+1} = (1 - \delta)K_t + I_t$$

$$R_t^r = A_t F_k(K_t, N_t)$$

$$W_t = A_t F_n(K_t, N_t)$$

$$A_t = A_{t-1}^{\rho_a} \exp(\epsilon_t)$$

- **Eight** variables $\{C_t, N_t, I_t, K_t, Y_t, W_t, R_t^r\}$ and **eight** equations

Equilibrium characterization III (it's nice with output as a separate variable)

- Summing up, the equilibrium is characterized by:

$$\begin{aligned}U'(C_t)W_t &= V'(N_t) \\U'(C_t) &= \beta E_t [(R_{t+1}^r + (1 - \delta)) U'(C_{t+1})] \\C_t + I_t &= Y_t \\Y_t &= A_t F(K_t, N_t) \\K_{t+1} &= (1 - \delta)K_t + I_t \\R_t^r &= A_t F_k(K_t, N_t) \\W_t &= A_t F_n(K_t, N_t) \\A_t &= A_{t-1}^{\rho_a} \exp(\epsilon_t)\end{aligned}$$

- **Eight** variables $\{C_t, N_t, I_t, K_t, Y_t, W_t, R_t^r\}$ and **eight** equations
- Question: Which are the state variables and which are the shocks?

Functional forms

- To compute the steady state, we need to impose some functional forms
- Note: choice of functional forms of course restricts the quantitative properties of the model - it should be treated as part of the **calibration**
- Cobb-Douglas (AER, 1928) production function:

$$F(K_t, N_t) = K_t^\alpha N_t^{1-\alpha}$$

- MacCurdy (JPE, 1981) consumption-leisure preferences:

$$U(C_t) - V(N_t) = \log C_t - \theta \frac{N_t^{1+\varphi}}{1+\varphi}$$

- Note:
 - ▶ MacCurdy is a special case of balance-growth path preferences (King-Plosser-Rebelo, JME 1988; Boppart-Krusell JPE 2019)
 - ▶ Generate constant hours if wage and non-wage (capital) income grow at the same rate
 - ▶ With MacCurdy, $\frac{1}{\varphi}$ measures the **Frisch elasticity** (more on this next class)

Equilibrium characterization with assumed functional forms

$$\begin{aligned}\frac{1}{C_t} W_t &= \theta N_t^\varphi \\ \frac{1}{C_t} &= \beta E_t \left[(R_{t+1}^r + (1 - \delta)) \frac{1}{C_{t+1}} \right] \\ C_t + I_t &= Y_t \\ Y_t &= A_t K_t^\alpha N_t^{1-\alpha} \\ K_{t+1} &= (1 - \delta) K_t + I_t \\ R_t^r &= \alpha A_t \left(\frac{K_t}{N_t} \right)^{\alpha-1} \\ W_t &= (1 - \alpha) A_t \left(\frac{K_t}{N_t} \right)^\alpha \\ A_t &= A_{t-1}^{\rho_a} \exp(\epsilon_t)\end{aligned}$$

Step 2: solve for steady state

- Set $A_t = 1$ and impose $X_t = X_{t+1}$ for all variables X , then work through the algebra
- Take-home exercise: show that the steady state is given by:

$$\begin{aligned} R^r &= \frac{1}{\beta} - (1 - \delta) \\ W &= (1 - \alpha) \left(\frac{R^r}{\alpha} \right)^{-\frac{\alpha}{1-\alpha}} \\ N &= \left[\frac{1}{\theta} \frac{W}{\frac{R^r}{\alpha} - \delta} \left(\frac{R^r}{\alpha} \right)^{\frac{1}{1-\alpha}} \right]^{\frac{1}{1+\varphi}} \\ K &= \left(\frac{R^r}{\alpha} \right)^{-\frac{1}{1-\alpha}} N \\ Y &= \frac{R^r K}{\alpha} \\ I &= \delta K \\ C &= \left(\frac{R^r}{\alpha} - \delta \right) K \end{aligned}$$

- (Trick: after solving for R^r and W , write the intratemporal household optimality condition in terms of $\frac{K}{N}$)

Step 3: Log-linearize

- From levels to log deviations: (Do an example on whiteboard)

$$\frac{1}{C_t} W_t = \theta N_t^\varphi \Rightarrow \hat{w}_t = \hat{c}_t + \varphi \hat{n}_t$$

$$\frac{1}{C_t} = \beta E_t \left[(R_{t+1}^r + (1 - \delta)) \frac{1}{C_{t+1}} \right] \Rightarrow \hat{c}_t = -\beta R^r E_t \hat{r}_{t+1}^r + E_t \hat{c}_{t+1}$$

$$C_t + I_t = Y_t \Rightarrow \frac{C}{Y} \hat{c}_t + \frac{I}{Y} \hat{i}_t = \hat{y}_t$$

$$Y_t = A_t K_t^\alpha N_t^{1-\alpha} \Rightarrow \hat{y}_t = \hat{a}_t + \alpha \hat{k}_t + (1 - \alpha) \hat{n}_t$$

$$K_{t+1} = (1 - \delta) K_t + I_t \Rightarrow \hat{k}_{t+1} = (1 - \delta) \hat{k}_t + \delta \hat{i}_t$$

$$R_t^r = \alpha A_t \left(\frac{K_t}{N_t} \right)^{\alpha-1} \Rightarrow \hat{r}_t^r = \hat{a}_t - (1 - \alpha)(\hat{k}_t - \hat{n}_t)$$

$$W_t = (1 - \alpha) A_t \left(\frac{K_t}{N_t} \right)^\alpha \Rightarrow \hat{w}_t = \hat{a}_t + \alpha(\hat{k}_t - \hat{n}_t)$$

$$A_t = A_{t-1}^{\rho_a} \exp(\epsilon_t) \Rightarrow \hat{a}_t = \rho_a \hat{a}_{t-1} + \epsilon_t$$

- Note: we can interpret \hat{r}_{t+1}^r as:

- percent deviation in gross rental rate R_{t+1}^r from steady state
- percentage point deviation in net rental rate ($R_{t+1}^r - 1$) from steady state

Log-linear equilibrium system

- The log-linear system can be written as:

$$\mathbf{A}_1 \mathbf{x}_t = \mathbf{A}_2 E_t \mathbf{x}_{t+1} + \mathbf{B}_1 \epsilon_t$$

where $\mathbf{x}_t = [\hat{r}_t, \hat{w}_t, \hat{c}_t, \hat{n}_t, \hat{i}_t, \hat{y}_t, \hat{k}_t, \hat{a}_{t-1}]'$, and

$$\mathbf{A}_1 = \begin{bmatrix} 0 & 1 & -1 & -\varphi & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{C}{Y} & 0 & \frac{I}{Y} & -1 & 0 & 0 \\ 0 & 0 & 0 & -(1-\alpha) & 0 & 1 & -\alpha & 0 \\ 0 & 0 & 0 & 0 & -\delta & 0 & -(1-\delta) & 0 \\ 1 & 0 & 0 & -(1-\alpha) & 0 & (1-\alpha) & 0 & 0 \\ 0 & 1 & 0 & \alpha & 0 & -\alpha & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -\rho_a \end{bmatrix}$$

$$\mathbf{A}_2 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -\beta R^r & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -\alpha & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \end{bmatrix} \quad \mathbf{B}_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

- Which variables in \mathbf{x}_t are pre-determined?

Log-linear equilibrium system

- We rewrite this as:

$$\begin{aligned}\mathbf{A}_1 \mathbf{x}_t &= \mathbf{A}_2 E_t \mathbf{x}_{t+1} + \mathbf{B}_1 \epsilon_t \\ \Rightarrow \quad \mathbf{x}_t &= \mathbf{A} E_t \mathbf{x}_{t+1} + \mathbf{B} \epsilon_t\end{aligned}$$

where $\mathbf{A} = \mathbf{A}_1^{-1} \mathbf{A}_2$, and $\mathbf{B} = \mathbf{A}_1^{-1} \mathbf{B}_1$

- Goal: simulate this system
- Simulate = Solve the path of endogenous variables $\{\mathbf{x}_t\}$ given some sequence of shocks $\{\epsilon_t\}$
- Given that the system has one unique bounded solution, solving this system amounts to some clever usage of matrix algebra
 - ▶ Older approach: Blanchard-Kahn (Ecmttra, 1981)
 - ▶ Modern approach: QZ-method (Klein, JEDC 2000)
- Nowadays, there exist ready-made routines that do the job for us, e.g., [Dynare](#)

The Real Business Cycle Model: Analysis

Quantitative analysis

- We have discussed how to solve and simulate the system
- So let's proceed and analyze it
- To do so, we need to pick parameter values

- Main idea:
 - ① Estimate driving process for exogenous TFP shocks
 - ② Pick the other parameters to a) be consistent with external estimates and/or b) that the model steady state matches long-run data moments
- The idea that you could calibrate a theoretical model to quantitatively analyze data was the second major contribution of Kydland-Prescott (Ecmtra, 1982)
 - ▶ Traditional method: use theory to generate hypotheses, and reduced-form econometrics for quantification
 - ▶ Prior development: structural econometrics, where theory is used to derive an estimating equation
 - ▶ Calibration was very controversial when introduced
 - ▶ Now: bread and butter in all of economics

Calibration II

- The model has 6 parameters: $\varphi, \delta, \beta, \alpha, \rho_a, \sigma_\epsilon$
- Typical procedure:
 - ▶ Pick δ to match NIPA estimates of average yearly capital depreciation rate $\sim 10\%$
 - ▶ Pick β to match average gross yearly real return on capital $\sim 1 + 0.04 + \delta_{yearly}$
 - ★ Recall steady-state relationship $R^r = \frac{1}{\beta} - (1 - \delta)$
 - ▶ Pick φ to match outside estimates of the Frish elasticity ~ 1 (to be discussed more!)
 - ▶ Pick α to match long-run labor share $\sim 2/3$
 - ★ Recall steady-state relationship $\frac{R^r K}{Y} = \alpha$
- For TFP, one starting point is to assume that these shocks has to be consistent with the fluctuations of the **Solow residuals**
 - ▶ Suppose we have quarterly data on Y_t, K_t, N_t
 - ▶ Taking logs of the production function, we can estimate SR's as the residuals from the regression

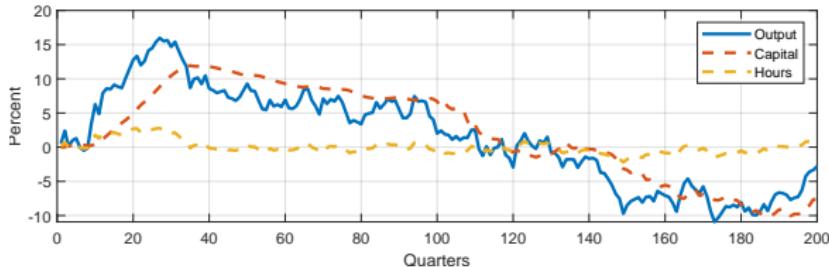
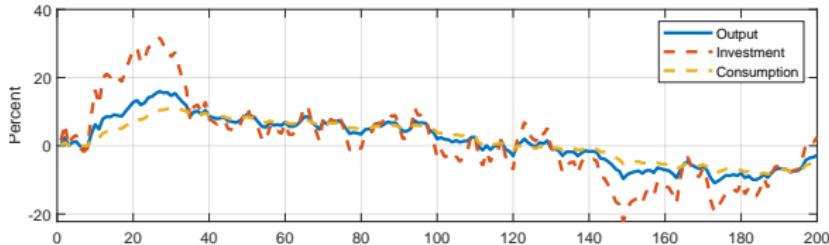
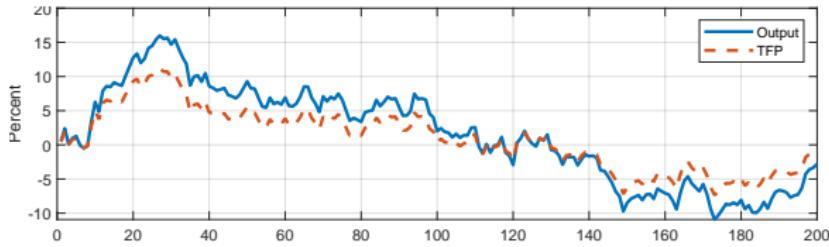
$$y_t - n_t = \alpha(k_t - n_t) + a_t$$

- ▶ Having estimated a_t , we can estimate ρ_a and σ_ϵ of

$$a_t = \rho_a a_{t-1} + \epsilon_t$$

Sims (Mitman) reports $\rho_a = 0.979$ (0.95) and $\sigma_\epsilon = 0.009$ (0.007)

Simulation results



Simulation results (HP-filtered)

	SD		Rel. SD		Corr Y_t		Autocorr	
	Data	Model	Data	Model	Data	Model	Data	Model
Y_t	0.017	0.015	1.00	1.00	1.00	1.00	0.79	0.72
C_t	0.011	0.006	0.66	0.40	0.76	0.95	0.67	0.78
I_t	0.044	0.041	2.67	2.73	0.76	0.99	0.86	0.72
N_t	0.021	0.005	1.27	0.33	0.87	0.98	0.82	0.72
W_t	0.012	0.010	0.69	0.66	-0.01	1.00	0.71	0.74
R_t	0.004	0.015	0.26	1.00	0.00	0.97	0.47	0.71
A_t	0.013	0.012	0.76	0.80	0.78	1.00	0.76	0.72

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- ▶
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A_t	0.013	0.012	0.76	0.80	0.78	1.00	0.76	0.72

- **Consistent with the data, the RBC model has**
 - ▶ positive comovement of all GDP components
 - ▶ big swings in investment and small swings in consumption
 -
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- Consistent with the data, the RBC model has
 - ▶ positive comovement of all GDP components
 - ▶ big swings in investment and small swings in consumption
- In contrast to the data, the model has
 - ▶ too little amplification
 - ▶ no persistence beyond that inherited by TFP process
 - ▶ way too little volatility in hours worked
 - ▶ too much volatility in prices

Simulation results: what did we just look at?

- We computed moments from a time series of our endogenous variables $[\mathbf{x}_t]_{t=0}^{\infty}$
- This time series $[\mathbf{x}_t]$ solved

$$\mathbf{x}_t = \mathbf{A}E_t \mathbf{x}_{t+1} + \mathbf{B}\epsilon_t$$

when feeding a sequence of shocks $\{\epsilon_0, \epsilon_1, \dots\}$

- Since the system is linear, the solution is linear in the underlying shocks:

$$\mathbf{x}_t = \sum_{s=0}^t \mathbf{a}_{t-s} \epsilon_s,$$

i.e.,

$$\mathbf{x}_0 = \mathbf{a}_0 \epsilon_0,$$

$$\mathbf{x}_1 = \mathbf{a}_1 \epsilon_0 + \mathbf{a}_0 \epsilon_1,$$

$$\mathbf{x}_2 = \mathbf{a}_2 \epsilon_0 + \mathbf{a}_1 \epsilon_1 + \mathbf{a}_0 \epsilon_2, \dots$$

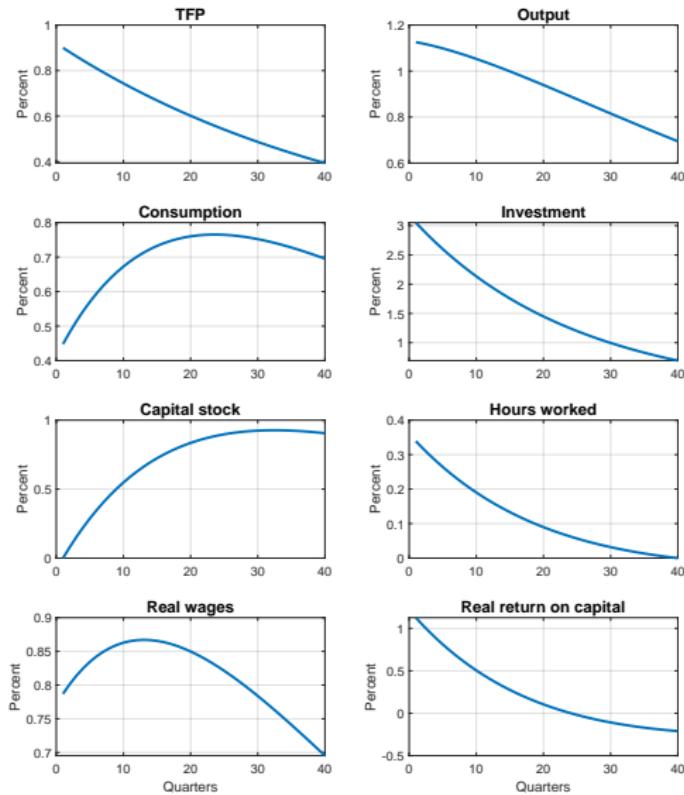
Simulation = superimposing IRFs

- Define the **impulse-response function** as

$$\begin{aligned} F(\epsilon) &= [a_0\epsilon, a_1\epsilon, a_2\epsilon, \dots] \\ &= \epsilon[a_0, a_1, a_2, \dots] \end{aligned}$$

- ▶ IRF = vector of responses in period $t, t+1, t+2, \dots$ to a singular shock in period t
- ▶ Note: A linear IRF scales linearly with the size of the shock ϵ
- Boppart-Krusell-Mitman (JEDC 2018): the simulation solution is a **superimposition** of IRFs:
$$\begin{aligned} [\mathbf{x}_t] &= [a_0\epsilon_0, a_1\epsilon_0 + a_0\epsilon_1, a_2\epsilon_0 + a_1\epsilon_1 + a_0\epsilon_2, \dots] \\ &= F(\epsilon_0) + [0, F(\epsilon_1)] + [0, 0, F(\epsilon_2)] + \dots \\ &= \epsilon_0 F(1) + \epsilon_1 [0, F(1)] + \epsilon_2 [0, 0, F(1)] + \dots \end{aligned}$$
- $\Rightarrow F(1)$ is a **sufficient statistic** for the model simulation results
- Put differently, the mechanism of the model revealed by studying the **impulse-response function** to a unitary single-period shock

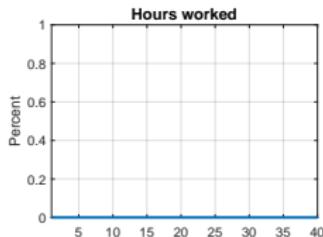
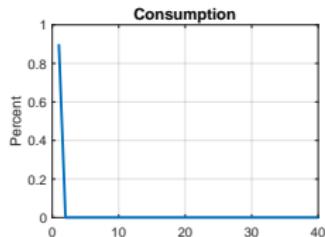
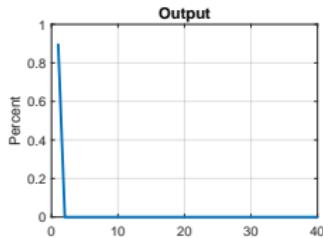
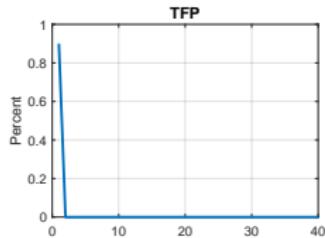
IRFs to single persistent TFP shock



How to unpack the responses?

- When staring at IRFs, it can be hard to discern the mechanism and to discern *impulse* from *propagation*
- How to unpack any model: simplify as much as you can, and then build the model gradually up again
- Two simplifications:
 - ① $\alpha = 0$ (such that $I = K = 0$, and therefore $Y = F(N) = C$)
 - ② $\rho_a = 0$ (no persistence in the impulse)

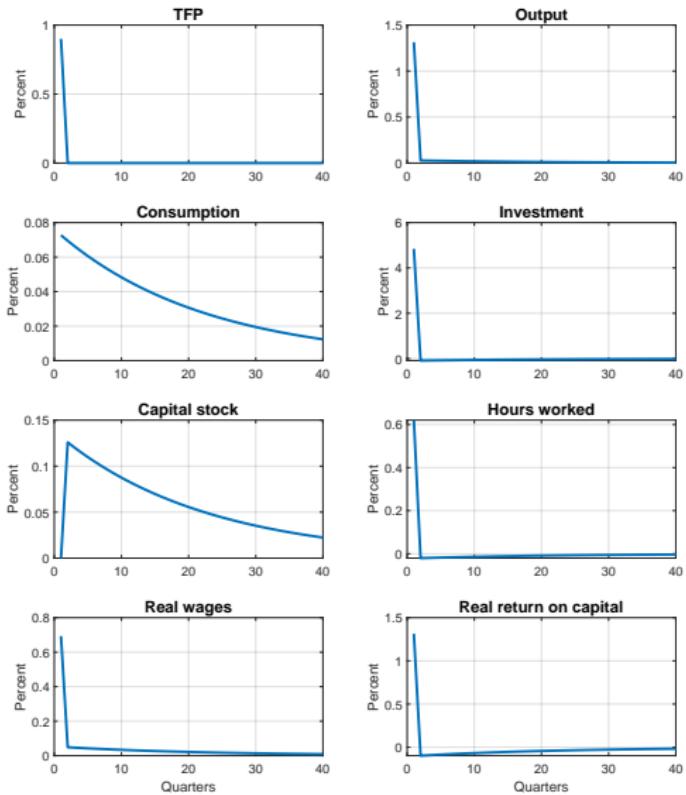
IRFs using a blip shock in model without capital



What's going on?

- When TFP increases; output, consumption and wages jump
 - ▶ Production function: $y_t = a_t + n_t$
 - ▶ Market clearing: $c_t = y_t$
 - ▶ Firm F.O.C.: $w_t = a_t$
- Why is hours worked flat?
- Household intratemporal F.O.C: $w_t = c_t + \varphi n_t$
- Holding marginal utility of consumption fixed, hours increase as wages increase (substitution effect)
- But in equilibrium, consumption increases, dampening hours (income effect)
- Balance-growth path preferences: income and substitution effect cancels
- This model has no internal propagation!

IRFs using a blip shock with capital



What's going on?

- With capital, household can now smooth consumption

$$\hat{c}_t = -\beta R^r E_t \hat{r}_{t+1}^r + E_t \hat{c}_{t+1}$$

- TFP up, households feel wealthier, consumption increases (but much less so compared to previous model)
- Consumption smoothing \Rightarrow investment jumps

$$\frac{C}{Y} \hat{c}_t + \frac{I}{Y} \hat{i}_t = \hat{y}_t$$

- When TFP increases, wages and current interest rate jumps

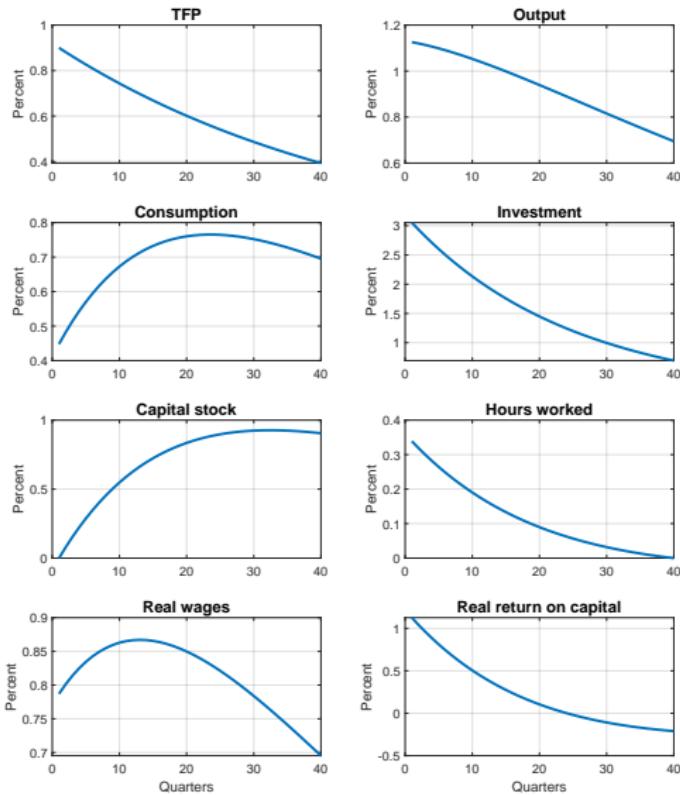
$$\begin{aligned}\hat{r}_t^r &= \hat{a}_t - (1 - \alpha)(\hat{k}_t - \hat{n}_t) \\ \hat{w}_t &= \hat{a}_t + \alpha(\hat{k}_t - \hat{n}_t)\end{aligned}$$

- Moreover, higher capital stock means that wages (rental rate) will be persistently higher (lower)
- Now, because of lower consumption response, hours worked increases

$$\hat{w}_t = \hat{c}_t + \varphi \hat{n}_t$$

- Now there is some propagation!

IRFs in core model (persistent shock and capital)



What's going on?

- With a persistent shock, all responses become more persistent
- Some, in particular household consumption, even hump-shaped
- Now there is an additional motive for investing besides consumption smoothing: future capital is unusually productive
- Households face trade-off when saving: smoothing consumption vs. maximizing lifetime consumption
- Turns out hump-shape is the optimal path

Summing up

- RBC = minimal GE model to get started with business cycles analysis
 - ▶ Abstracts from a lot of things, but this was intentional
- Key features:
 - ▶ No distortions
 - ▶ TFP is the only driving process
 - ▶ Propagation happens through equilibrium responses of hours worked and investment
- Underlying philosophy:
 - ▶ Business cycles analyzed in the same framework as long-run growth
 - ▶ GE models can be calibrated and used to quantitatively interpret the data
- Results:
 - ▶ The model can seemingly explain a whole lot of business cycle moments
 - ▶ Fails in some key aspects
- Next up:
 - ▶ RBC as a diagnosis tool
 - ▶ Thinking deeper about mechanisms and model fit