

Lecture 15 Sampling II

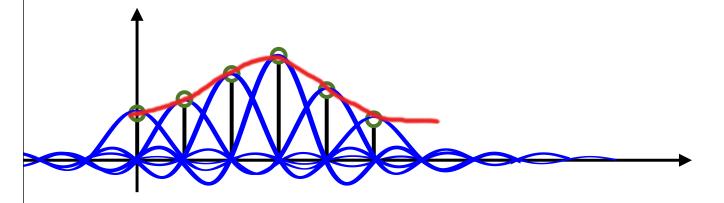
Topics

- Last time
 - Ideal Sampling model C/D
 - Impulse sampling $x_c(t) \Rightarrow x_s(t)$
 - Impulses to discrete samples $x_s(nT) \Rightarrow x[n]$
 - Relationship $X_c(j\Omega) \Leftrightarrow X_s(j\Omega) \Leftrightarrow X(e^{j\omega})$
 - -Ideal reconstruction D/C
- Today
 - D.T processing of C.T signals
 - C.T processing of D.T signals (ha?????)
 - -Downsampling

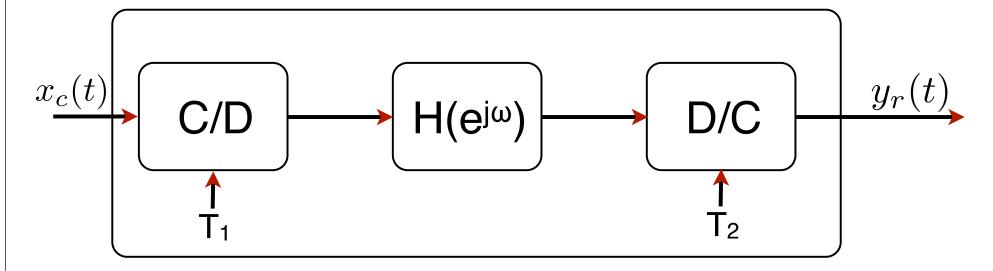
Reconstruction in Time Domain

$$x_r(t) = x_s(t) * h_r(t) = \left(\sum_n x[n]\delta(t - nT)\right) * h_r(t)$$
$$= \sum_n x[n]h(t - nT)$$

The sum of sincs gives $x_r(t) \Rightarrow$ Unique signal bandlimited by Ω_s

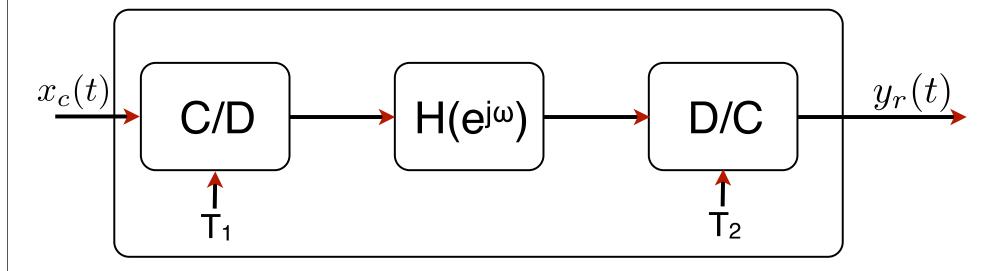


Discrete-Time Processing of C-T Signals



• Q: If h[n] is LTI, $H(e^{j\omega})$ exists, Is the whole system LTI?

Discrete-Time Processing of C-T Signals

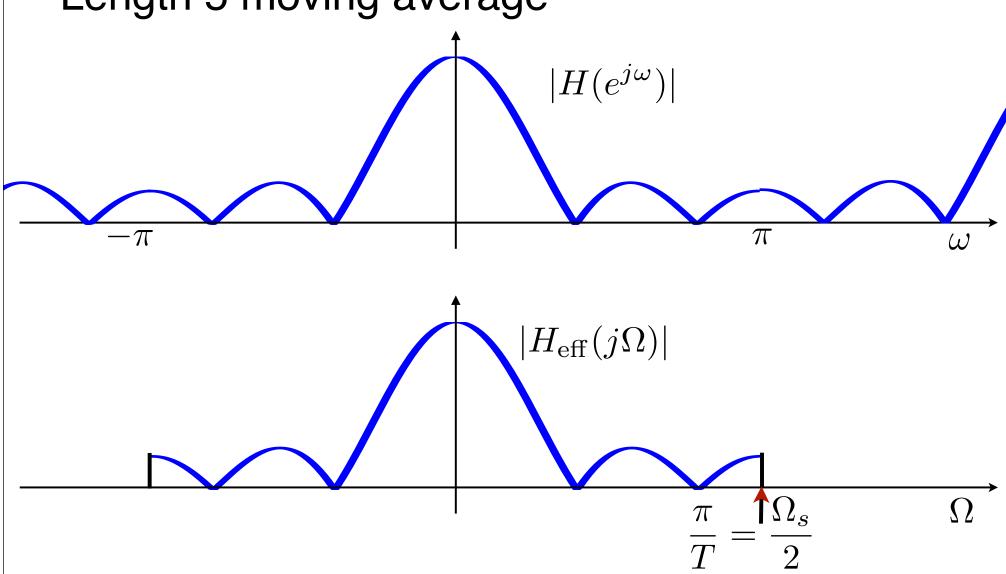


- Q: If h[n] is LTI, $H(e^{j\omega})$ exists, Is the whole system LTI?
- A: If xc(t) is bandlimited by $\frac{\Omega_s}{2} = \frac{\pi}{T}$ then,

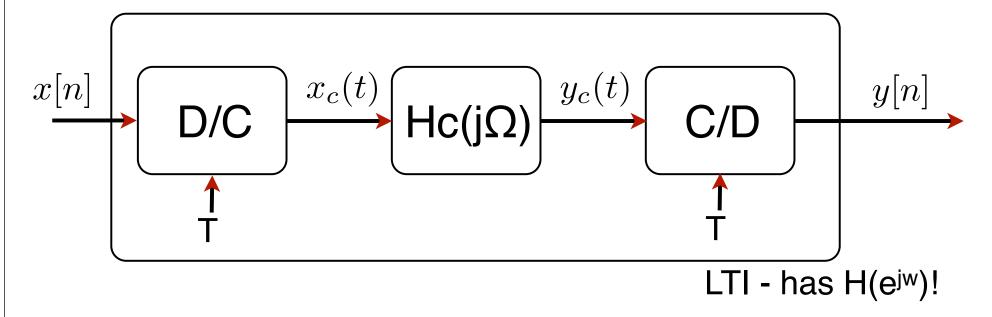
$$\frac{Y_r(j\Omega)}{X_c(j\Omega)} = H_{\text{eff}}(j\Omega) = \begin{cases} H(e^{j\omega})|_{\omega = \Omega T} & |\Omega| < \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

Example:

Length 5 moving average



C.T Processing of D.T Signals



 Useful to interpret D.T. systems with no simple interpretation in discrete domain.

• Tool: recall:
$$x_c(t) = \sum_{n=-\infty}^{\infty} x[n] \operatorname{sinc}\left(\frac{t-nT}{T}\right)$$

Derivation

$$X_c(j\Omega) = \begin{cases} TX(e^{j\omega})|_{\omega=\Omega T} & |\Omega| \le \Omega_s/2 \\ 0 & \text{otherwise} \end{cases}$$

$$Y_c(j\Omega) = H_c(j\Omega) X_c(j\Omega) \;\; \Rightarrow \; {\rm also \; bandlimited}$$
 so,

$$Y(e^{j\omega}) = \frac{1}{T} \sum_{k} Y_c(j(\Omega - k\Omega_s)) \bigg|_{\Omega = \frac{\omega}{T}} = \frac{1}{T} Y_c(j\Omega) \bigg|_{\Omega = \frac{\omega}{T}}$$
 no aliasing!

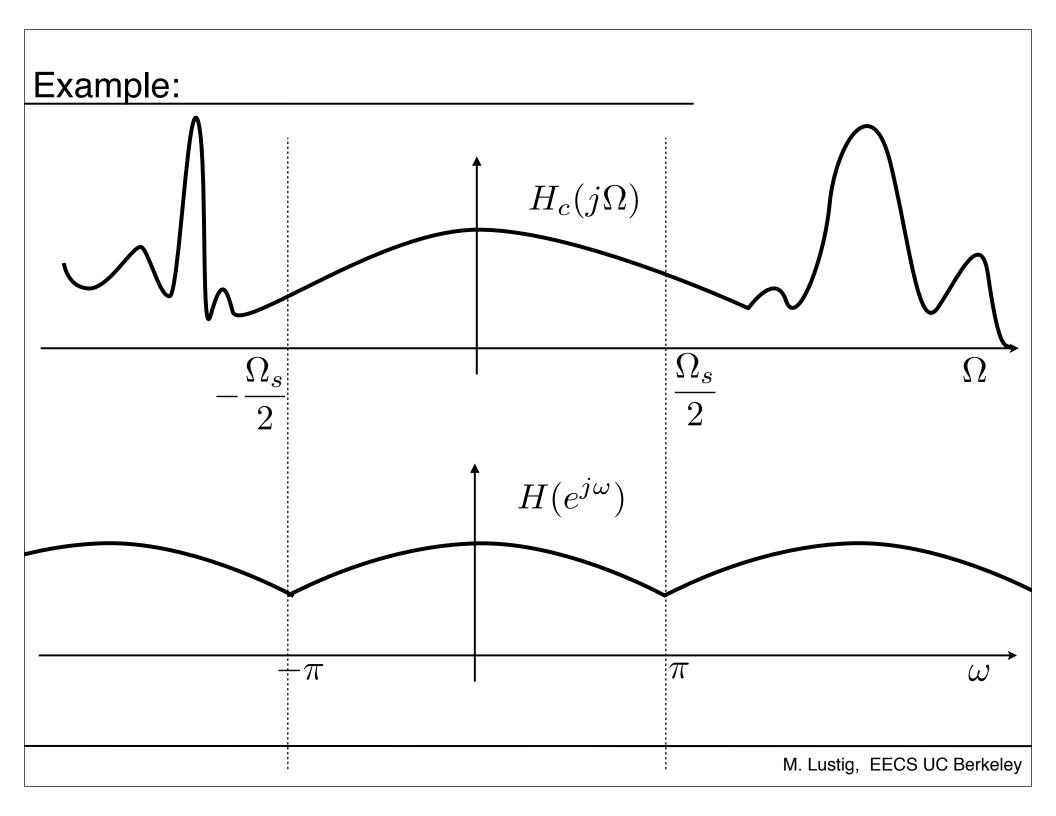
Derivation

$$Y_c(j\Omega) = H_c(j\Omega)X_c(j\Omega)$$

$$Y(e^{j\omega}) = \frac{1}{T} \left. \sum_{k} Y_c(j(\Omega - k\Omega_s)) \right|_{\Omega = \frac{\omega}{T}} = \left. \frac{1}{T} Y_c(j\Omega) \right|_{\Omega = \frac{\omega}{T}}$$

Combining the result:

$$Y(e^{j\omega}) = \underbrace{H_c(j\Omega)|_{\Omega = \frac{\omega}{T}}}_{H(e^{j\omega})} X(e^{j\omega}) \qquad |\omega| < \pi$$



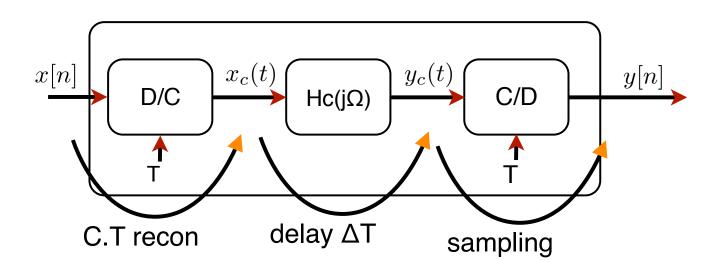
Example:

Non-integer delay:

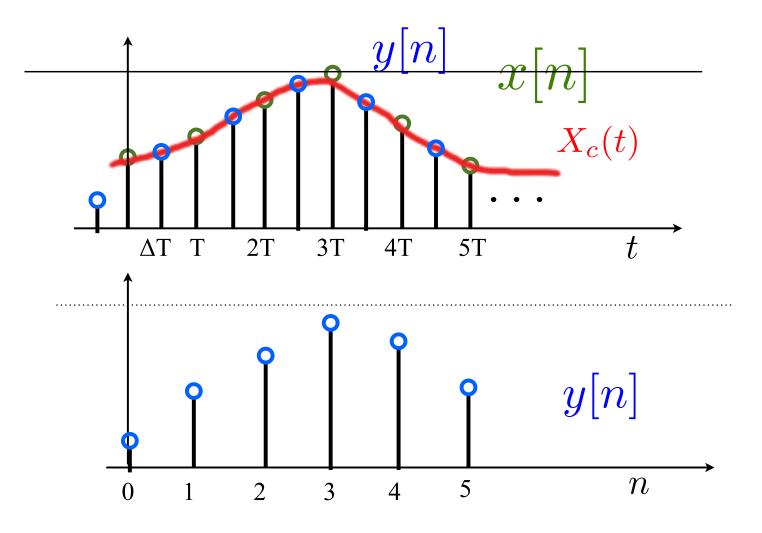
$$H(e^{j\omega}) = e^{-j\omega\Delta}$$

• What is the time-domain operation when Δ is not an integer (Δ =1/2)?

Let: $H_c(j\Omega) = e^{-j\Omega\Delta T}$ delay of ΔT in time



Example: Non Integer Delay



Example: Non Integer Delay

The block diagram is only for interpretation!

$$y_c(t) = x_c(t - T\Delta)$$

$$y[n] = y_c(nT) = x_c(nT - T\Delta)$$

$$= \sum_{k} x[k] \operatorname{sinc}\left(\frac{t - kT - T\Delta}{T}\right) \Big|_{t=nT}$$

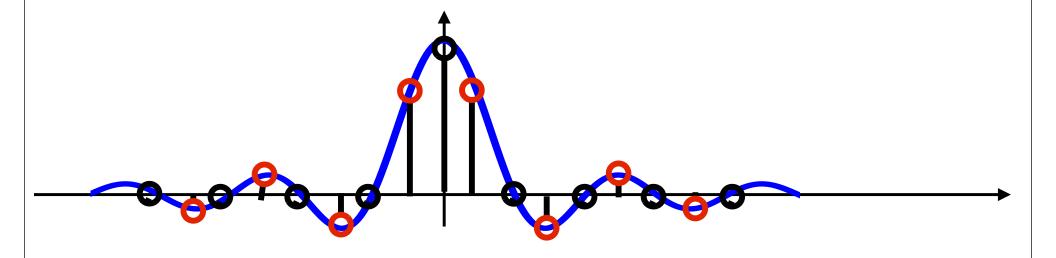
T's cancel!

$$= \sum_{k} x[k] \operatorname{sinc}(n - k - \Delta)$$

Example: Non Integer Delay

$$h[n] = \operatorname{sinc}(n - \Delta)$$

Example: a discrete delta is a representation of a sampled sinc



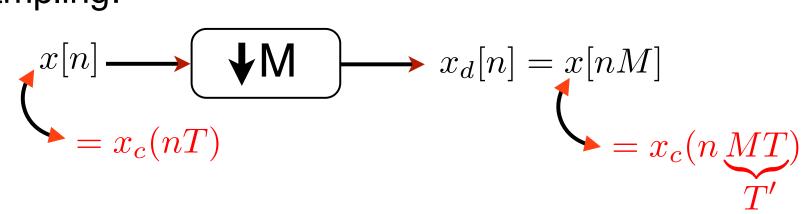
shifted by partial samples results in many coefficients!

DownSampling

- Much like C/D conversion
- Expect similar effects:
 - -Aliasing
 - -mitigate by antialiasing filter

- Finely sampled signal ⇒ almost continuous
 - -Downsample in that case is like sampling!

Downsampling:



The DTFT:

$$X(e^{j\omega}) = \frac{1}{T} \sum_{k} X_{c} \left(j \left(\underbrace{\frac{\omega}{T}}_{\Omega} - \underbrace{\frac{2\pi}{T}}_{\Omega_{s}} k \right) \right)$$

$$X_d(e^{j\omega}) = \frac{1}{MT} \sum_k X_c \left(j \left(\frac{\omega}{MT} - \frac{2\pi}{MT} k \right) \right)$$

The DTFT:

$$X(e^{j\omega}) = \frac{1}{T} \sum_{k} X_c \left(j \left(\underbrace{\frac{\omega}{T}}_{\Omega} - \underbrace{\frac{2\pi}{T}}_{\Omega_s} k \right) \right)$$

$$X_d(e^{j\omega}) = \frac{1}{MT} \sum_k X_c \left(j \left(\frac{\omega}{MT} - \frac{2\pi}{MT} k \right) \right)$$

we would like to bypass X_c and go from $X(e^{j\omega}) \Rightarrow X_d$ $(e^{j\omega})$

substitute
$$r = kM + i$$
 $i=0,1,...,M-1$ $k=-\infty,...,\infty$

two counters

e.g., k: hours, i: minutes

$$X_d(e^{j\omega}) = \frac{1}{MT} \sum_k X_c \left(j \left(\frac{\omega}{MT} - \frac{2\pi}{MT} k \right) \right)$$

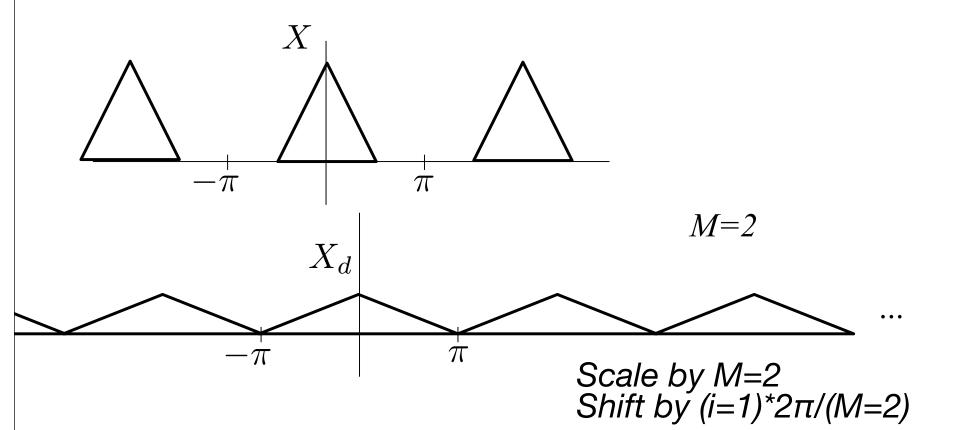
$$= \frac{1}{M} \sum_{i=0}^{M-1} \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c \left(j \left(\frac{\omega}{MT} - \frac{2\pi}{MT} i - \frac{2\pi}{T} k \right) \right)$$

$$X(e^{j\omega}) = \frac{1}{T} \sum_{k} X_c \left(j \left(\underbrace{\frac{\omega}{T}}_{} - \underbrace{\frac{2\pi}{T}}_{} k \right) \right)$$

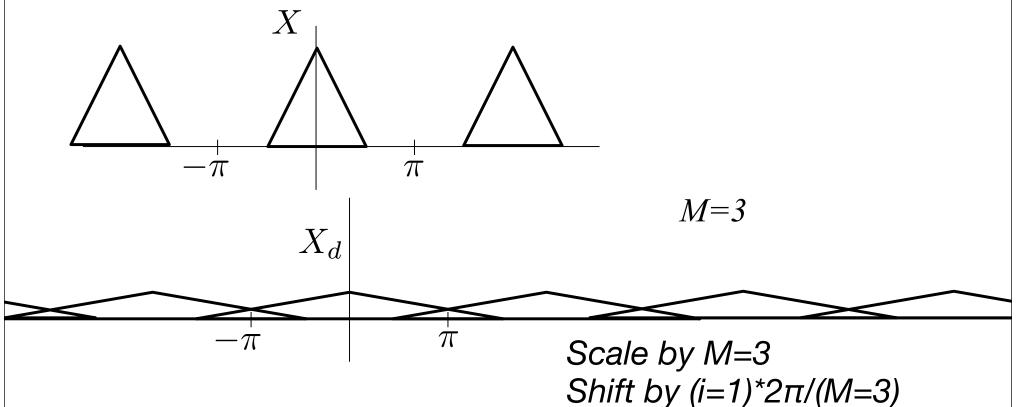
$$X \left(e^{j\left(\frac{\omega}{M} - \frac{2\pi}{M}i\right)} \right)$$

$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X(e^{j(\frac{\omega}{M} - \frac{2\pi}{M}i)})$$
 stretch replicate by M

$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0} X\left(e^{j(\boldsymbol{w}/M - 2\pi i/M)}\right)$$



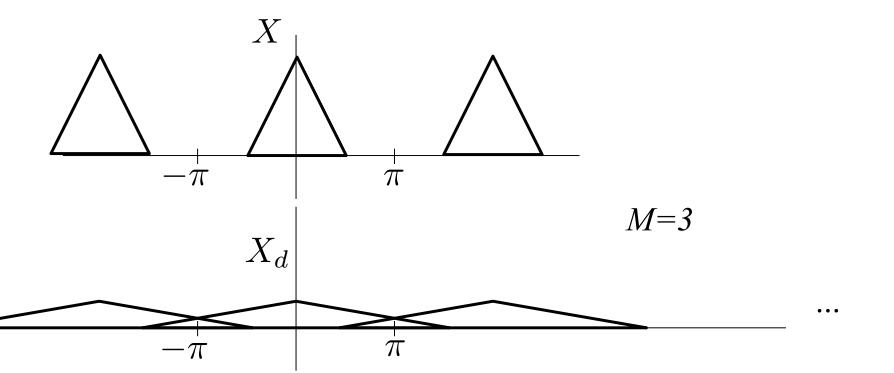
$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0} X\left(e^{j(\mathbf{w}/M - 2\pi i/M)}\right)$$



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Shift by $(i=2)*2\pi/(M=3)$

$$X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{\infty} X\left(e^{j(\mathbf{w}/M - 2\pi i/M)}\right)$$



Anti-Aliasing

