

Fast relaxation of a viscous vortex in an external flow

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I Introduction : The incompressible Navier-Stokes eq. in \mathbb{R}^2

$u(x, t) = (u_1(x, t), u_2(x, t))$: velocity of the fluid at point $x \in \mathbb{R}^2$ and time $t \geq 0$

$p(x, t)$ = pressure / density

$\nu > 0$ = kinematic viscosity = viscosity / density $[10^{-6} \text{ m}^2/\text{s} \text{ for water}]$

$$\begin{cases} \partial_t u(x, t) + (u(x, t) \cdot \nabla) u(x, t) = \nu \Delta u(x, t) - \nabla p(x, t) \\ \operatorname{div} u(x, t) = 0. \end{cases} \quad (\text{NS})$$

1st eq: evolution of the momentum $(\frac{1}{m} \sum F = a)$

2nd eq: incompressibility condition

Trajectories of the fluid particles:

$$\begin{cases} x'(t) = u(x(t), t) \\ x(t_0) = x_0 \in \mathbb{R}^2 \end{cases} \Rightarrow x(t) = \bar{\varphi}_{t, t_0}(x_0).$$

The flow map $\bar{\varphi}_{t, t_0}$ is a volume preserving diffeomorphism of \mathbb{R}^2 :

$$\det(D\bar{\varphi}_{t, t_0})(x_0) = \exp\left(\int_{t_0}^t \operatorname{div}(u(x(\tau)), \tau) d\tau\right) = 1.$$

Vorticity formulation $\omega := \partial_1 u_2 - \partial_2 u_1 = \operatorname{curl} u.$

Observe that $(u \cdot \nabla) u = \frac{1}{2} \nabla |u|^2 + u^\perp \omega$, $u^\perp = \begin{pmatrix} -u_2 \\ u_1 \end{pmatrix}$
 $\Rightarrow \operatorname{curl} (u \cdot \nabla) u = \partial_1(u_1 w) + \partial_2(u_2 w) = u \cdot \nabla w$ since $\operatorname{div} u = 0$.

So taking the curl of (NS) we get the vorticity equation:

$$[\partial_t \omega(x, t) + u(x, t) \cdot \nabla \omega(x, t)] = \nu \Delta \omega(x, t). \quad (\text{VE})$$

Not a closed equation for ω , because (VE) involves the velocity field u .

Biot-Savart formula To express u in terms of ω , we have to solve:

$$\begin{cases} \operatorname{div} u = \partial_1 u_1 + \partial_2 u_2 = 0 \\ \operatorname{curl} u = \partial_1 u_2 - \partial_2 u_1 = \omega \end{cases}$$

Stream function: $u = \nabla^\perp \psi = \begin{pmatrix} -\partial_2 \psi \\ \partial_1 \psi \end{pmatrix} \Rightarrow \begin{cases} \operatorname{div} u = 0 \\ \Delta \psi = \omega \end{cases}$

Poisson formula:

$$\psi(x) = \frac{1}{2\pi} \int_{\mathbb{R}^2} \log|x-y| \omega(y) dy$$

Taking the curl we thus obtain the Biot-Savart formula: $u = \text{BS}[\omega]$

$$|| u(x) = \frac{1}{2\pi} \int_{\mathbb{R}^2} \frac{(x-y)^\perp}{|x-y|^2} \omega(y) dy. \quad (\text{BS})$$

(VE) + (BS) is a closed evolution system for the vorticity ω .

⚠ u is a linear but nonlocal function of ω ! Incompressible fluid mechanics is always nonlocal.

The calculations so far are formal, see below for sufficient conditions on ω so that (VE), (BS) make sense.

Radially symmetric vortices

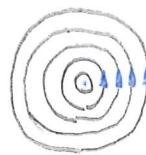
We use polar coordinates : $x = (r \cos \theta, r \sin \theta)$, and we denote

$$e_r = \frac{x}{|x|}, \quad e_\theta = \frac{x^\perp}{|x|}.$$

If $\omega = \omega(|x|)$ is radially symmetric, so is $\psi = \psi(|x|)$, hence

$$u = \nabla^\perp \psi(|x|) = \psi'(|x|) \frac{x^\perp}{|x|} \Rightarrow u = V(|x|) e_\theta \quad (V = \psi')$$

$$\operatorname{div} u = \frac{1}{r} \partial_r(r u_r) + \frac{1}{r} \partial_\theta u_\theta = 0$$



$$\operatorname{curl} u = \frac{1}{r} \partial_r(r u_\theta) - \frac{1}{r} \partial_\theta u_r = \frac{1}{r} (r V)',$$

$$\Rightarrow V(r) = \frac{1}{r} \int_0^r s \omega(s) ds. \quad \| \quad p'(r) = \frac{1}{r} V(r)^2 \quad (\text{pressure})$$

In particular : $u \cdot \nabla \omega = \frac{1}{r} V \partial_\theta \omega = 0$.

It follows that ω is a radially symmetric solution of the heat equation:

$$[\partial_t \omega(x, t) = \nu \Delta \omega(x, t)].$$

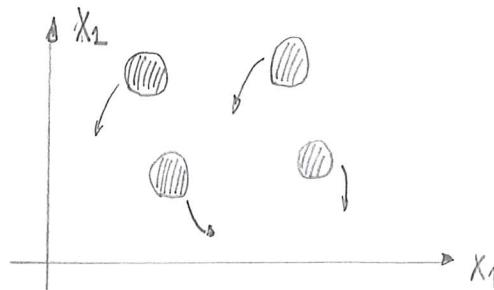
Example 1 : Rankine's vortex

$$\left\{ \begin{array}{l} \omega(r) = \frac{\Gamma}{\pi r^2} \mathbb{1}_{[0, R]} \Rightarrow \Gamma = \int_{\mathbb{R}^2} \omega(x) dx \\ \omega(r) = \frac{\Gamma}{2\pi r^2} \begin{cases} r & \text{if } r \leq R \\ \frac{R^2}{r} & \text{if } r \geq R \end{cases} \begin{array}{l} ; \text{ rigid rotation} \\ ; \text{ irrotational flow} \end{array} \end{array} \right. \quad u = \frac{\Gamma x^\perp}{2\pi} \begin{cases} \frac{1}{r^2} & |x| \leq R \\ \frac{1}{|x|^2} & |x| \geq R \end{cases}$$

Example 2 : Lamb-Oseen vortex

$$\left\{ \begin{array}{l} \omega = \frac{\Gamma}{4\pi r^2} e^{-|x|^2/4R^2} \Rightarrow \Gamma = \int_{\mathbb{R}^2} \omega(x) dx \\ \omega = \frac{\Gamma}{2\pi} \frac{x^\perp}{|x|^2} \left(1 - e^{-|x|^2/4R^2} \right), \quad V = \frac{\Gamma}{2\pi r} \left(1 - e^{-R^2/4R^2} \right). \end{array} \right.$$

Interaction of vortices



Consider the interesting situation where the vorticity is a superposition of a finite number of well-separated vortices

$$\omega(x, t) = \sum_{i=1}^N \omega_i(x, t) \Rightarrow u(x, t) = \sum_{i=1}^N u_i(x, t)$$

where $u_i = BS[\omega_i] \quad \forall i \in \{1, \dots, N\}$. The decomposition of ω is not unique, but we postulate that the ω_i satisfy:

$$\left[\partial_t \omega_i + u \cdot \nabla \omega_i = \nu \Delta \omega_i \quad \forall i \in \{1, \dots, N\} \right] \quad (*)$$

\uparrow the full velocity field

In particular, given a decomposition of ω at initial time $t = 0$, eq. (*) univocally defines ω_i at later times. We can rewrite (*) in the equivalent form:

$$\partial_t \omega_i + (u_i + f_i) \cdot \nabla \omega_i = \nu \Delta \omega_i \quad \forall i \in \{1, \dots, N\} \quad (**)$$

where $u_i = BS[\omega_i]$ and $f_i = \sum_{j=1, j \neq i}^N BS[\omega_j]$.

In (**), the term $u_i \cdot \nabla \omega_i$ describes the self-interaction of the i^{th} vortex, and the term $f_i \cdot \nabla \omega_i$ the interaction with the other vortices.

In what follows, to study the interactions of vortices, we consider eq. (**) for a given velocity field f_i satisfying appropriate estimates, and we study the behavior of a single vortex ω_i . This simplified model keeps all important features of the general case, and is somewhat easier to study.

Phenomenology of vortex interactions

If the vortices $\omega_i(x, t)$ have a definite sign, we can consider the center of vorticity $x_i(t)$ given by:

$$x_i(t) = \frac{1}{\Gamma_i} \int_{\mathbb{R}^2} x \omega_i(x, t) dx, \quad \text{where } \Gamma_i = \int_{\mathbb{R}^2} \omega_i(x, t) dx.$$

Using (***) a direct calculation shows that Γ_i is a conserved quantity, whereas

$$x_i'(t) = \frac{1}{\Gamma_i} \int_{\mathbb{R}^2} f_i(x, t) \omega_i(x, t) dx, \quad \left\{ \begin{array}{l} \text{Vortices move due to mutual} \\ \text{interactions, not self-interaction!} \end{array} \right.$$

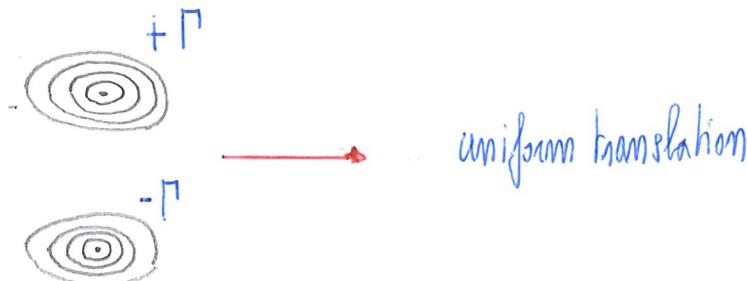
In the (formal) limit where $\omega_i(x, t) \rightarrow \Gamma_i \delta(x - x_i(t))$, we find:

$$\begin{aligned} x_i'(t) &= f_i(x_i(t), t) = \sum_{j \neq i} \text{BS}[\omega_j](x_i(t), t) \\ &= \sum_{j \neq i} \frac{\Gamma_j}{2\pi} \frac{(x_i(t) - x_j(t))^{\perp}}{|x_i(t) - x_j(t)|^2} \quad \parallel \quad \text{Point vortex system (PV)} \end{aligned}$$

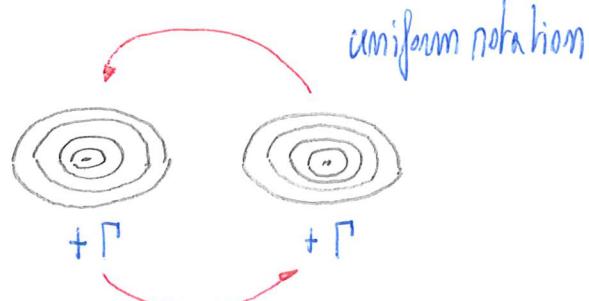
N.B. The argument above, based on the center of vorticity, is the only reasonable one that explains why we should disregard the self-interaction of vortices when deriving (PV).

Beyond the point vortex approximation, one may want to compute the deformation of vortices under the shear stress created by the other vortices:

Vortex dipole



Constantine vortex pair



II A viscous vortex in an external flow

From now on we consider the following vorticity equation:

$$[\partial_t \omega(x,t) + (u(x,t) + f(x,t)) \cdot \nabla \omega(x,t) = \nu \Delta \omega(x,t) \quad x \in \mathbb{R}^2 \quad t \geq 0] \quad (\text{Vf})$$

Where: • $u = \text{BS}[\omega]$ is the velocity field associated with ω .
• f is a given external field.

We assume that:

- $\text{div } f = \partial_1 f_1 + \partial_2 f_2 = 0$. (essential!)
- f is smooth: $f \in C_b^\infty(\mathbb{R}^2 \times [0,T], \mathbb{R}^2)$ (can be relaxed)

In the particular case $f=0$ we recover the usual vorticity eq. (VE). The following results are obtained by adapting the theory for NS to the modified eq. (Vf).

[Proposition 1: The Cauchy problem for (Vf) is globally well posed in $L^1(\mathbb{R}^2)$.

For any $\omega_0 \in L^1(\mathbb{R}^2)$, there exists a unique mild solution

$$\omega \in C([0,T], L^1(\mathbb{R}^2)) \cap C([0,T], L^\infty(\mathbb{R}^2))$$

with $\omega(0) = \omega_0$. This solution is a locally Lipschitz function of $w \in L^1(\mathbb{R}^2)$.

The integral eq. associated with (Vf) is:

$$\begin{cases} \omega(t) = S(\nu t)\omega_0 - \int_0^t S(\nu(t-s)) \text{div}((u(s) + f(s))\omega(s)) ds, \\ S(t) = e^{t\Delta} : \text{heat kernel in } \mathbb{R}^2 \end{cases}$$

Prop. 1 can be proved following the same lines as in Ben-Artzi 1993,
where the case $f \equiv 0$ is considered.

Conserved quantity: $\Gamma := \int_{\mathbb{R}^2} w(x, t) dx$ (total circulation)

We are interested in w describing a vortex, so we assume henceforth that $\Gamma \neq 0$, for instance $\Gamma > 0$.

△ This implies that $u \notin L^2(\mathbb{R}^2)$, because of slow decay at infinity!

⇒ Exercise: If $u \in L^2(\mathbb{R}^2)^2$ and $w := J_1 u_2 - J_2 u_1 \in L^1(\mathbb{R}^2)$, then $\int_{\mathbb{R}^2} w dx = 0$.

If we assume further that $(1+|x|)w \in L^1(\mathbb{R}^2)$, the solution of (v) satisfies $(1+|x|)w(\cdot, t) \in L^1 \quad \forall t \geq 0$ and one can define the center of vorticity:

$$\left[\bar{x}(t) = \frac{1}{\Gamma} \int_{\mathbb{R}^2} x w(x, t) dx, \quad t \in [0, T]. \right]$$

$$\text{Lemma: } \bar{x}'(t) = \frac{1}{\Gamma} \int_{\mathbb{R}^2} f(x, t) w(x, t) dx, \quad t \in [0, T].$$

Proof: For $t > 0$ the solution is smooth and we can compute

$$\begin{aligned} \bar{x}'(t) &= \frac{1}{\Gamma} \int_{\mathbb{R}^2} x \partial_t w(x, t) dx \\ &= \frac{1}{\Gamma} \int_{\mathbb{R}^2} x \left(\nu \Delta w(x, t) - (u(x, t) + f(x, t)) \cdot \nabla w(x, t) \right) dx. \end{aligned}$$

But:

- $\int x \Delta w dx = 0$ (int. by parts)
- $-\int x (u+f) \cdot \nabla w dx = -\int x \operatorname{div}((u+f)w) dx = \int (u+f) w dx$
- $\int u(x) w(x) dx = \frac{1}{2\pi} \iint \underbrace{\frac{(x-y)^\perp}{|x-y|^2}}_{\text{odd}} \underbrace{w(y)w(x)}_{\text{even}} dy dx = 0.$

So $x'(t) = \frac{1}{\Gamma} \int_{\mathbb{R}^2} f(x, t) w(x, t) dx$ for $t > 0$, and the result holds for $t = 0$ too by continuity. □

Finite measures as initial data

let $\mathcal{M}(\mathbb{R}^2)$ be the space of all finite, signed Radon measures on \mathbb{R}^2 .

If $\mu \in \mathcal{M}(\mathbb{R}^2)$, we have the Jordan decomposition

$$\mu = \mu_+ - \mu_- \quad (\mu_{\pm} \text{ are "minimal" positive measures})$$

and the total variation measure $|\mu| = \mu_+ + \mu_-$. We denote

$$\|\mu\|_{TV} = |\mu|(\mathbb{R}^2) \quad (\text{total variation norm}).$$

Equipped with $\|\cdot\|_{TV}$, $\mathcal{M}(\mathbb{R}^2)$ is a Banach space which contains $L^1(\mathbb{R}^2)$ as a closed subspace.

Relevant examples for fluid mechanics:

i) Absolutely continuous measures: $\mu = \omega dx$, $\omega \in L^1(\mathbb{R}^2)$

Ex: vortex patch $\omega = \chi_{\Omega}$, $\Omega \subset \mathbb{R}^2$ smooth and bounded

ii) Singularly continuous measures: Ex: vortex sheet

$$\langle \mu, \varphi \rangle = \int_C \varphi dl, \quad C \subset \mathbb{R}^2 \text{ smooth curve}$$

iii) Point vortices: $\mu = \sum_{i=1}^N \Gamma_i \delta_{x_i}$

It is known that the Cauchy problem for (VE) with $f \equiv 0$ is globally well-posed in the space $\mathcal{M}(\mathbb{R}^2)$. If $\|\mu\|_{TV} \leq C_* \nu$: fixed point argument!

- existence can be proved by regularizing the initial data

- Cotter 1986

- Giga-Miyakawa-Osada 1988

- Kato 1994

- uniqueness requires a special argument to deal with large Dirac masses:

- Gallay-Wayne 2005

- Bedrossian-Masmoudi 2014

- Gallagher-Gallay 2005

Example: (still with $f \equiv 0$) Lamb-Oseen vortex

If $w_0 = \Gamma \delta_0$, the unique solution of (VE) is

$$\omega(x,t) = \frac{\Gamma}{\nu F} \Omega_0 \left(\frac{x}{\sqrt{\nu F}} \right), \quad u(x,t) = \frac{\Gamma}{\sqrt{\nu F}} U_0 \left(\frac{x}{\sqrt{\nu F}} \right)$$

where

$$\Omega_0(\varphi) = \frac{1}{4\pi} e^{-|\varphi|^2/4}, \quad U_0(\varphi) = \frac{1}{2\pi} \frac{\varphi^\perp}{|\varphi|^2} (1 - e^{-|\varphi|^2/4}).$$

We now return to the equation (Vf) with $f \neq 0$. The lower order term $f \cdot \nabla w$ in (Vf) does not change the nature of the equation, and we expect that:

[Proposition 2: The Cauchy problem for (Vf) is globally well-posed in $H(\mathbb{R}^2)$.

Exercise (for a good master student or a young PhD student): prove Proposition 2!

In what follows we assume that (Vf) has a unique global solution if

[$w_0 = \Gamma \delta_{z_0}$, for some $\Gamma \in \mathbb{R}$ and $z_0 \in \mathbb{R}^2$]

Why this choice? The external field creates a shear stress that deforms the vortex $w(x,t)$ solution of (Vf). In particular, radially symmetric vortices such as (L0) are not possible. Starting with a point vortex allows us to see the deformations occur gradually, since the initial vortex has zero extension. In that sense the initial data above are well-prepared. In contrast, starting with a radially symmetric vortex of non-zero extension gives rise to a time-layer near $t=0$ where the vortex undergoes damped oscillations to adapt its shape to the external strain; we speak of ill-prepared initial data in such a case. See the last chapter IV for a discussion of this situation.

Relevant physical parameters (assume $\Gamma > 0$)

- Circulation Reynolds number : $Re = \frac{\Gamma}{\nu}$.

We assume henceforth that $Re \gg 1$ and we set $\delta = \frac{1}{Re} = \frac{\nu}{\Gamma}$.

The assumption $\delta \ll 1$ ensures that the vortex moves over a long distance (if $f \neq 0$) before spreading due to viscosity.

Jacobian matrix

- Characteristic time : $\frac{1}{T_0} = \sup_{0 \leq t \leq T} \sup_{x \in \mathbb{R}^2} |Df(x, t)|$

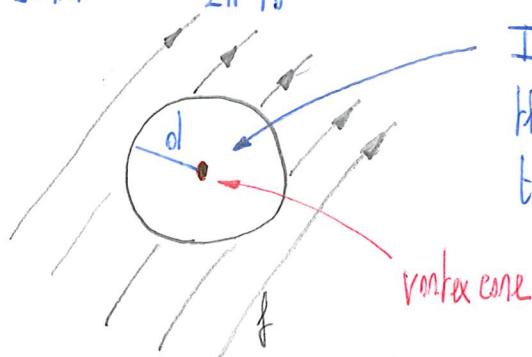
Nearby trajectories of the ODE $z' = f(z, t)$ separate at rate $O(e^{t/T_0})$.

- Effective size of the vortex: $d = \sqrt{\Gamma T_0}$

The velocity field of a vortex of circulation $\Gamma > 0$ located at the origin behaves like

$u = \frac{\Gamma}{2\pi} \frac{x^\perp}{|x|^2}$ as $|x| \rightarrow \infty$. The corresponding strain satisfies:

$$|Du(x)| \approx \frac{\Gamma}{2\pi|x|^2} = \frac{1}{2\pi T_0} \text{ when } |x| = d,$$



Inside the disk the strain of the velocity field is essentially due to the vortex.

- Aspect ratio : $\varepsilon(t) = \frac{\sqrt{\nu t}}{d} = \frac{\text{size of the vortex cone}}{\text{effective size of the vortex}}$

Important relation:

$$\varepsilon(t)^2 = \frac{\nu t}{d^2} = \frac{\nu t}{\Gamma T_0} = \delta \frac{t}{T_0}.$$

\Rightarrow As long as t is comparable to T_0 we have $\varepsilon(t)^2 \approx \delta \ll 1$.

Theorem 1: Fix $\Gamma > 0$ and $z_0 \in \mathbb{R}^2$. There exist $k_0 > 0$ and $\delta_0 > 0$ such that, if $0 < \nu < \Gamma \delta_0$, the unique solution of (Vf) with initial data $w_0 = \Gamma \delta_{z_0}$ satisfies:

$$\frac{1}{\Gamma} \int_{\mathbb{R}^2} \left| w(x, t) - \frac{\Gamma}{\sqrt{\nu f}} \Omega_0 \left(\frac{x-z(t)}{\sqrt{\nu f}} \right) \right| dx \leq k_0 \frac{\sqrt{\nu f}}{\nu}, \quad 0 < t \leq T$$

where $z(t)$ is the solution of the ODE:

$$z'(t) = f(z(t), t), \quad z(0) = z_0.$$

For a fixed $\Gamma > 0$, the large constant k_0 and the small constant $\delta_0 > 0$ only depend on the ratio T/T_0 and on the bounds of f and its derivatives. In particular, the result holds uniformly in ν provided $0 < \nu < \delta_0$.

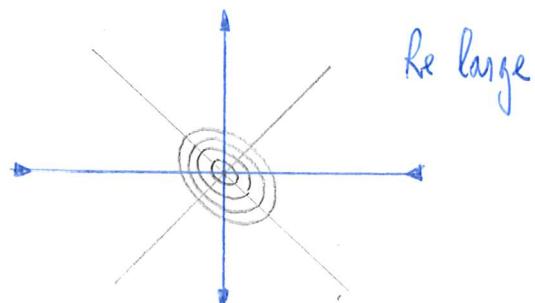
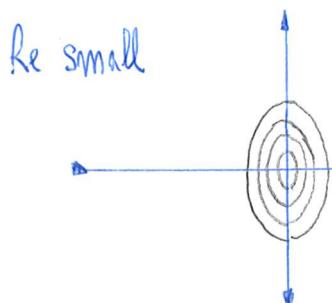
⚠ The formulation above is not appropriate to study the limit $\Gamma \rightarrow 0$ or $\Gamma \rightarrow +\infty$!

The conclusion of Thm 1 is very intuitive:

- due to diffusion, the point vortex evolves into a Lamb-Oseen vortex
- due to the external field, the vortex center follows the ODE $z' = f(z, t)$
- both effects do not interact at this level of approximation.

However, it is not clear how to prove Thm 1 without computing a much more precise approximation of the solution, taking into account the deformation of the vortex under the strain of the external field f .

Deformation of a vortex in a strain field $f(x) = \gamma(-x_1, x_2)$

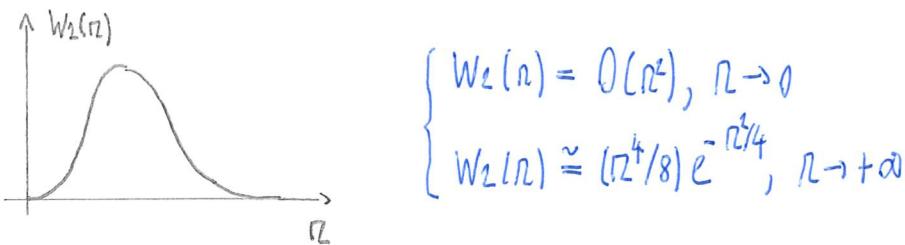


Ansatz for a Gaussian vortex of circulation $\Gamma > 0$ and core size $\ell > 0$
located at point $z \in \mathbb{R}^2$, in the external field f :

$$[W_{\text{app}}(\Gamma, \ell, z, f; x) = \frac{\Gamma}{\ell^2} \Omega_0\left(\frac{x-z}{\ell}\right) + W_2(r) (\alpha(z) \sin(2\theta) - b(z) \cos(2\theta)) \quad (\text{A})$$

where:

- $\xi = \frac{x-z}{\ell} = (r \cos \theta, r \sin \theta)$ (rescaled variable in the vortex core)
- $\alpha(z) = \frac{1}{2} (\partial_1 f_1 - \partial_2 f_2)(z), \quad b(z) = \frac{1}{2} (\partial_1 f_2 + \partial_2 f_1)(z)$ (strain rates)
- $W_2(r) > 0$ solution of a differential equation



Rem: $\frac{1}{\Gamma} \int_{\mathbb{R}^2} \frac{\Gamma}{\ell^2} \Omega_0\left(\frac{x-z}{\ell}\right) dx = 1$

$$\frac{1}{\Gamma} \int_{\mathbb{R}^2} \left| W_2\left(\frac{|x-z|}{\ell}\right) \right| |\alpha \sin(2\theta) - b \cos(2\theta)| dx \leq C \frac{\ell^2}{\Gamma T_0} = C \frac{\ell^2}{d^2}$$

\Rightarrow the correction term in (A) is relatively smaller if $\frac{\ell}{d} \ll 1$, $d = \sqrt{\Gamma T_0}$.

Theorem 2: Fix $\Gamma > 0$ and $z_0 \in \mathbb{R}^2$. There exist $k_0 > 0$ and $\delta_0 > 0$ such that, if $0 < \nu < \Gamma \delta_0$, the unique solution of (Vf) with initial data $\omega_0 = \Gamma \delta_{z_0}$ satisfies:

$$\frac{1}{\Gamma} \int_{\mathbb{R}^2} \left| \omega(x, t) - W_{\text{app}}(\Gamma, \sqrt{\nu t}, z(t), f(t); x) \right| dx \leq k_0 \varepsilon(t)^2 (\varepsilon(t) + \delta), \quad 0 < t \leq T$$

where $\varepsilon(t) = \sqrt{\nu t}/d$ and $z(t)$ is the solution of the modified ODE:

$$z'(t) = f(z(t), t) + \nu t \Delta f(z(t), t), \quad z(0) = z_0.$$

Rem: Theorem 2 \Rightarrow Theorem 1!

Remarks on Thm 2:

- 1) The approximation is much more precise than in Thm 1: $O(\varepsilon^3)$ instead of $O(\varepsilon)$. In particular the $O(\varepsilon^2)$ term in ω_{app} (involving w_2 and a, b) cannot be absorbed in the error terms \Rightarrow our result allows us to describe to leading order the deformation of the vortex.
- 2) The ODE for $z(t)$ contains a (small) additional term $\nu t \Delta f(z(t), t)$, which vanishes if f is irrotational: $\Delta f = \nabla^\perp (\partial_1 f_2 - \partial_2 f_1)$. Otherwise it modifies the solution $z(t)$ by $O(\varepsilon^2 d)$.
- 3) The origin of the correction term $\nu t \Delta f$ can be understood as follows.

To leading order we have:

$$\omega(x, t) = \frac{\Gamma}{\nu t} \Omega_0 \left(\frac{x-z(t)}{\sqrt{\nu t}} \right).$$

Taking this approximation for granted we compute the center of vorticity:

$$\begin{aligned} \cdot \quad \bar{x}(t) &= \frac{1}{\Gamma} \int_{\mathbb{R}^2} x \omega(x, t) dx = \frac{1}{\Gamma} \int_{\mathbb{R}^2} x \frac{\Gamma}{\nu t} \Omega_0 \left(\frac{x-z(t)}{\sqrt{\nu t}} \right) dx \quad x = z(t) + \sqrt{\nu t} \varphi \\ &= \int_{\mathbb{R}^2} (z(t) + \sqrt{\nu t} \varphi) \Omega_0(\varphi) d\varphi = z(t) \\ \cdot \quad \bar{x}'(t) &= \frac{1}{\Gamma} \int_{\mathbb{R}^2} f(x, t) \omega(x, t) dx = \int_{\mathbb{R}^2} f(z(t) + \sqrt{\nu t} \varphi, t) \Omega_0(\varphi) d\varphi \\ &= \int_{\mathbb{R}^2} \left\{ f(z(t), t) + \sqrt{\nu t} Df(z(t), t)[\varphi] + \frac{1}{2} (\nu t) D^2 f(z(t), t)[\varphi, \varphi] + O((\nu t)^{3/2}) \right\} \Omega_0(\varphi) d\varphi \\ &= f(z(t), t) + 0 + \nu t \Delta f(z(t), t) + O((\nu t)^{3/2}), \end{aligned}$$

because

$$\int_{\mathbb{R}^2} \varphi_1^2 \Omega_0(\varphi) d\varphi = \int_{\mathbb{R}^2} \varphi_2^2 \Omega_0(\varphi) d\varphi = 2, \quad \int_{\mathbb{R}^2} \varphi_1 \varphi_2 \Omega_0(\varphi) d\varphi = 0,$$

- 4) Under the assumptions of Thm 2, one can show that $|\bar{x}(t) - z(t)| \leq C_0 \varepsilon^3 (\varepsilon + \delta)$.

III The well-prepared case: proof of Theorem 2

Step 1: Self-similar variables

The solution of (Vf) that we consider is very singular near initial time.

To desingularize the Cauchy problem, we make the change of variables:

$$\left[\omega(x,t) = \frac{\Gamma}{\sqrt{t}} \Omega\left(\frac{x-z(t)}{\sqrt{t}}, t\right), \quad u(x,t) = \frac{\Gamma}{\sqrt{t}} U\left(\frac{x-z(t)}{\sqrt{t}}, t\right), \right]$$

where $z(t)$ is the vortex center (to be determined later). The new space variable

$$\xi = \frac{x-z(t)}{\sqrt{t}} \quad \text{is centered at } z(t), \text{ and measures distances}$$

in units of the diffusion length \sqrt{t} .

Since $\int_{\mathbb{R}^2} \omega(x,t) dx = \Gamma$, we have $\int_{\mathbb{R}^2} \Omega(\xi,t) d\xi = 1 \quad \forall t > 0$.

The evolution equation (Vf) becomes: $U = \text{BS}[\Omega]!$

$$\left[\varepsilon \partial_t \Omega(\xi,t) + \frac{1}{8} (U(\xi,t) + E(\xi,t)) \cdot \nabla \Omega(\xi,t) = \mathcal{L} \Omega(\xi,t) \quad \begin{matrix} \xi \in \mathbb{R}^2 \\ t > 0 \end{matrix} \right] \quad (\text{Req})$$

where:

• $\mathcal{L} = \Delta_\xi + \frac{1}{2} \xi \cdot \nabla_\xi + 1$ is the rescaled diffusion operator;

• $\frac{1}{8} E(\xi,t) = \sqrt{\frac{\varepsilon}{\nu}} \left(f(z(t) + \sqrt{\nu t} \xi, t) - z'(t) \right)$.

ext. field

vortex speed

Recalling that $\delta = \frac{\nu}{\Gamma}$, $\varepsilon = \frac{\sqrt{\nu t}}{d}$, $d = \sqrt{\Gamma T_0}$, we see that

$$\delta \sqrt{\frac{\varepsilon}{\nu}} = \frac{\delta \sqrt{\nu t}}{\nu} = \frac{\sqrt{\nu t}}{\Gamma} = \frac{\sqrt{\nu t}}{d^2} T_0 = \frac{T_0}{d} \varepsilon$$

typical speed

hence:

$$E(\xi,t) = \frac{\varepsilon T_0}{d} \left(f(z(t) + \underbrace{\sqrt{\nu t} \xi}_{=\varepsilon d}, t) - z'(t) \right).$$

The vortex speed $z'(t)$ will be chosen so as to make $E(\xi,t)$ as small as possible,

The initial position is $z(0) = z_0 \in \mathbb{R}^2$.

$O(\varepsilon^2)$

Remark: The Cauchy pb for (2eq) is not well-posed at initial time $t=0$, because one has $t\partial_t \Omega$ instead of $\partial_t \Omega$ in the right-hand side!

In fact, setting formally $t=0$ in (2eq) and recalling that $\varepsilon(0)=0$, we get

$$\left| \frac{1}{\delta} u \cdot \nabla \Omega = \Omega, \quad u = BS[\Omega] \right.$$

This is the eq. satisfied by the profile Ω of a self-similar solution of the vorticity eq. (VE) with $f=0$. If $\Omega \in L^1(\mathbb{R}^2)$, it was shown by ThG & Waeyen (2005) that necessarily $\Omega = \alpha \Omega_0$ (the Gaussian vortex), $\alpha \in \mathbb{R}$. Normalization forces $\alpha=1$, hence the only possible initial data are:

$$\Omega_0(\xi) = \frac{1}{4\pi} e^{-|\xi|^2/4}, \quad u_0(\xi) = \frac{1}{2\pi} \frac{\xi^\perp}{|\xi|^2} \left(1 - e^{-|\xi|^2/4} \right).$$

Step 2: Construction of an approximate solution

We look for an approximate solution of (2eq) in the form:

$$\begin{cases} \Omega_{app}(\xi, t) = \Omega_0(\xi) + \varepsilon(t)^2 \Omega_2(\xi, t) + \varepsilon(t)^3 \Omega_3(\xi, t) + \varepsilon(t)^4 \Omega_4(\xi, t) \\ u_{app}(\xi, t) = u_0(\xi) + \varepsilon(t)^2 u_2(\xi, t) + \varepsilon(t)^3 u_3(\xi, t) + \varepsilon(t)^4 u_4(\xi, t) \end{cases} \quad (1)$$

where $u_i = BS[\Omega_i]$ and the profiles $\Omega_2, \Omega_3, \Omega_4$ have to be determined.

Remarks:

- expansion in $\varepsilon(t) = \frac{\sqrt{dt}}{\alpha}$, but starts at order ε^2 . Order 4 is sufficient!
- all quantities also depend on $\delta = \frac{\nu}{\Gamma}$ (not indicated).

We also have to expand the quantity $E(\xi, t)$ in (2eq). Anticipating that $\Xi(t) = f(z(t), t) + \nu t \Delta f(z(t), t)$, we obtain by Taylor expansion:

$$E(\xi, t) = \varepsilon^2 E_2(\xi, t) + \varepsilon^3 E_3(\xi, t) + \varepsilon^4 E_4(\xi, t), \quad \text{where} \\ + O(\varepsilon^5)$$

$$\left\{ \begin{array}{l} E_2(\xi, t) = T_0 Df(z(t), t)[\xi] \\ E_3(\xi, t) = T_0 \partial_t \left(\frac{1}{2} D^2 f(z(t), t)[\xi, \xi] - \Delta f(z(t), t) \right) \\ E_4(\xi, t) = \frac{1}{6} T_0 \partial_t^2 D^3 f(z(t), t)[\xi, \xi, \xi]. \end{array} \right. \quad (2)$$

We now replace (1) and (2) into (2eq) and determine the profiles Ω_i order by order.

Calculations at order 2: N.B. $t \partial_t \varepsilon = \varepsilon/2$, $t \partial_t \varepsilon^2 = \varepsilon \dots$

- $E \partial_t \Omega_{app} = \varepsilon^2 (t \partial_t \Omega_1 + \Omega_2) + O(\varepsilon^3)$
- $\mathcal{L} \Omega_{app} = \varepsilon^2 (\Omega_2 + O(\varepsilon^3))$
- $U_{app} \cdot \nabla \Omega_{app} = \varepsilon^2 (U_0 \cdot \nabla \Omega_1 + U_2 \cdot \nabla \Omega_0) + O(\varepsilon^3)$
- $E \cdot \nabla \Omega_{app} = \varepsilon^2 E_2 \cdot \nabla \Omega_0 + O(\varepsilon^3)$

Summarizing, we get at order ε^2 : N.B. $\delta t = \varepsilon^2 T_0 = O(\varepsilon^2)$!

$$\parallel S(1-\mathcal{L}) \Omega_2 + \Lambda \Omega_2 + E_2 \cdot \nabla \Omega_0 = 0 \quad (\Omega_2)$$

where Λ is the integro-differential operator defined by:

$$\parallel \Lambda \Omega = U_0 \cdot \nabla \Omega + BS[\Omega] \cdot \nabla \Omega_0.$$

We shall see that (Ω_2) determines uniquely the profile Ω_2 . Similar calculations allow one to compute Ω_3 and Ω_4 too.

Step 3: Inverting the linear operator Λ

It is convenient to introduce the Hilbert space Y defined by

$$Y = \left\{ \Omega \in L^2(\mathbb{R}^2); \int_{\mathbb{R}^2} |\Omega(\xi)|^2 e^{|\xi|^4/4} d\xi < \infty \right\}.$$

We equip Y with the natural scalar product.

We recall the remarkable properties of the operators \mathcal{L} and Λ acting on \mathcal{Y} .

Prop 1: \mathcal{L} is self-adjoint in \mathcal{Y} with discrete spectrum:

$$\Gamma(\mathcal{L}) = \{0, -1/2, -1, -3/2, \dots\}. \text{ Moreover:}$$

- $\ker(\mathcal{L})$ is spanned by Ω_0 ;
- $\ker(\mathcal{L} + 1/2)$ is spanned by $\mathcal{J}_1 \Omega_0$ and $\mathcal{J}_2 \Omega_0$;
- $\ker(\mathcal{L} + m/2)$ is spanned by $\mathcal{J}^\alpha \Omega_0$ with $\alpha = (\alpha_1, \alpha_2) \in \mathbb{N}^2$, $\alpha_1 + \alpha_2 = m$.

Proof: $e^{|\mathcal{L}|^2/8} \mathcal{L} e^{-|\mathcal{L}|^2/8} = \Delta - \frac{|\mathcal{L}|^2}{16} + \frac{1}{2}$; harmonic oscillator in \mathbb{R}^2 ! \square

Prop 2: Λ is skew-adjoint in \mathcal{Y} , and

$$\ker(\Lambda) = \mathcal{Y}_0 \oplus \{\beta_1 \mathcal{J}_1 \Omega_0 + \beta_2 \mathcal{J}_2 \Omega_0; \beta_1, \beta_2 \in \mathbb{R}\}.$$

Proof: Cf. Gallay-Wayne 2005, Maekawa 2011. (\mathcal{Y}_0 = radially symmetric elements of \mathcal{Y})

Returning to (Ω_2) : The operator $\delta(1-\mathcal{L}) + \Lambda$ is invertible in \mathcal{Y} $\forall \delta > 0$, but $\|(\delta(1-\mathcal{L}) + \Lambda)^{-1}\|_{\mathcal{Y} \rightarrow \mathcal{Y}} \leq C\delta^{-1}$ in general. To have a solution that depends regularly of δ , we need to check that $E_2 \cdot \nabla \Omega_0 \in \text{Ran}(\Lambda)$.

By a direct calculation:

$$E_2 \cdot \nabla \Omega_0 = -T_0 \frac{|\mathcal{L}|^2}{2} \Omega_0 (\alpha(t) \cos(2t) + b(t) \sin(2t)), \text{ where}$$

$$\alpha(t) = \frac{1}{2} (\mathcal{J}_1 f_1 - \mathcal{J}_2 f_2)(z(t), t), \quad b(t) = \frac{1}{2} (\mathcal{J}_1 f_2 + \mathcal{J}_2 f_1)(z(t), t).$$

Thus $E_2 \cdot \nabla \Omega_0 \in \ker(\Lambda)^\perp = \text{Ran}(\Lambda)$, and in fact $E_2 \cdot \nabla \Omega_0 \in \text{Ran}(\Lambda)$.
 $\uparrow \Lambda \text{ is skew-adjoint}$

$$\bullet \exists! \bar{\Omega}_2 \in \ker(\Lambda)^\perp \text{ s.t. } \Lambda \bar{\Omega}_2 + E_2 \cdot \nabla \Omega_0 = 0$$

$$\bullet \exists! \tilde{\Omega}_2 \in \ker(\Lambda)^\perp \text{ s.t. } \Lambda \tilde{\Omega}_2 + (1-\mathcal{L}) \bar{\Omega}_2 = 0$$

Setting $\Omega_2 = \bar{\Omega}_2 + \delta \tilde{\Omega}_2$, we conclude $\delta(1-\mathcal{L}) \Omega_2 + \Lambda \Omega_2 + E_2 \cdot \nabla \Omega_0 = \frac{\delta^2 (1-\mathcal{L}) \tilde{\Omega}_2}{\ll 1}$

Step 4: Estimate on the remainder

Having constructed the profiles $\Omega_1, \Omega_3, \Omega_4$ we consider the remainder

$$R_{\text{app}} := S(t) \Omega_{\text{app}} - Q \Omega_{\text{app}} + (U_{\text{app}} + E) \cdot \nabla \Omega_{\text{app}}.$$

Lemma: $\exists N \in \mathbb{N} \quad \exists C > 0$ such that

$$|R_{\text{app}}(\xi, t)| \leq C(\varepsilon^5 + \delta^2 \varepsilon^2) (1+|\xi|)^N e^{-|\xi|^2/4}.$$

↑ because we used a 4th order expansion

Rem: To construct the profile Ω_3 , one needs that $E_3 \cdot \nabla \Omega_0 \in \text{Ran}(A)$.

This is not the case if $z'(t) = f(z(t), t) \Rightarrow$ we added the small correction $\nu t \Delta f$ in the evolution eq. for $z(t)$.

\Rightarrow The vortex speed $z'(t)$ is chosen so as to ensure solvability conditions in the elliptic eq. for the vortex profiles $\Omega_3, \Omega_5, \Omega_7 \dots$

Rem: To leading order we have

$$\Omega_{\text{app}}(\xi, t) = \Omega_0(\xi) + \varepsilon^2 \bar{\Omega}_2(\xi, t) + O(\varepsilon^3 + \varepsilon^2 \delta) \Rightarrow \text{expression of } w_{\text{app}}!$$

A direct calculation shows that

$$\bar{\Omega}_2(\xi, t) = T_0 W_2(|\xi|) (a(t) \sin(2\xi) - b(t) \cos(2\xi))$$

where:

- $W_2(r) = h(r) \left(\varphi_2(r) + \frac{r^2}{2} \right), \quad h(r) = \frac{r^2/4}{e^{r^2/4} - 1}$ (Arnold function)

- $\varphi_2(r)$ is the unique sol. of the ODE:

$$-\varphi_2'' - \frac{1}{r^2} \varphi_2' + \left(\frac{4}{r^2} - h \right) \varphi_2 = \frac{r^2}{2} h(r)$$

such that $\varphi_2(r) = O(r^2)$ as $r \rightarrow 0$ and $\varphi_2(r) = O(1/r^2)$ as $r \rightarrow +\infty$.

Step 5: Correction to the approximate solution

Finally we decompose the exact solution of (2eq) as:

$$\Omega(\xi, t) = \Omega_{\text{app}}(\xi, t) + \delta W(\xi, t), \quad U(\xi, t) = U_{\text{app}}(\xi, t) + \delta V(\xi, t)$$

The factor δ here is a choice, anticipating that the correction should be small.

The equation for W takes the form: $V = BS[W]$

$$t \partial_t W + \frac{1}{\delta} \Delta W + \frac{1}{\delta} A[W] + B[W, W] = \mathcal{L} W - \frac{1}{\delta^2} R_{\text{app}} \quad (\text{Weq})$$

where:

- $\mathcal{L} = \Delta + \frac{1}{2} \xi \cdot \nabla + 1$: diffusion operator
- ΔW = $U_0 \cdot \nabla W + BS[W] \cdot \nabla \Omega_0$: linearization of Euler at Ω_0
- $A[W] = (U_{\text{app}} - U_0) \cdot \nabla W + BS[W] \cdot \nabla (\Omega_{\text{app}} - \Omega_0) + E(f, z) \cdot \nabla W$
- $B[W, W] = BS[W] \cdot \nabla W$ (---- : added and subtracted terms)

and R_{app} is the remainder defined in Step 4.

Rem:

- there is no factor $\frac{1}{\delta}$ in front of $B[W, W]$ because the perturbation is δW
- for the same reason, there is a factor $\frac{1}{\delta^2}$ in front of R_{app} .
- Eq. (Weq) has to be solved with zero initial data, because $\Omega(\xi, 0) = \Omega_{\text{app}}(\xi, 0) = \Omega_0(\xi)$. Also $\int_{\mathbb{R}^2} W d\xi = 0$.
- The source term is small:

$$\left| \frac{1}{\delta^2} R_{\text{app}} \right| \leq C \left(\frac{\varepsilon^5}{\delta^2} + \varepsilon^2 \right) (1 + |\xi|)^N e^{-|\xi|^2/4}, \quad \text{and}$$

$$\varepsilon^2 = \delta \frac{t}{T_0} \Rightarrow \frac{\varepsilon^5}{\delta^2} = \varepsilon \left(\frac{t}{T_0} \right)^2 \ll 1.$$

The main difficulty is to prove that the vorticity correction $w(\varphi, t)$ does not get amplified by the linear terms in $(w\varphi)$ involving $1/\delta$. This can be done using energy estimates.

Simple case: $T \ll T_0 \Rightarrow$ energy estimates in \mathcal{Y}

$$\begin{aligned} \mathcal{E}[w] &= \|w\|_{\mathcal{Y}}^2 = \int_{\mathbb{R}^2} |w|^2 e^{|\varphi|^2/4} d\varphi \\ \mathcal{F}[w] &= \int_{\mathbb{R}^2} \left\{ |\nabla w|^2 + |\varphi|^2 |w|^2 + |w|^2 \right\} e^{|\varphi|^2/4} d\varphi \geq \mathcal{E}[w] \end{aligned}$$

$$\begin{aligned} \frac{1}{2} t \partial_t \mathcal{E}[w] &= \langle w, t \partial_t w \rangle_{\mathcal{Y}} \\ &= \langle w, \varphi w \rangle_{\mathcal{Y}} - \frac{1}{\delta} \langle w, A[w] \rangle_{\mathcal{Y}} - \langle w, B[w, w] \rangle_{\mathcal{Y}} - \frac{1}{\delta^2} \langle w, R_{app} w \rangle_{\mathcal{Y}}. \end{aligned}$$

N.B.: $\frac{1}{\delta} \langle w, \Lambda w \rangle_{\mathcal{Y}} = 0$ because Λ is skew-symmetric in \mathcal{Y}

• diffusion term: since $\int w d\varphi = 0$, $\exists k > 0$ s.t. $\langle w, \varphi w \rangle_{\mathcal{Y}} \leq -k \mathcal{F}[w]$.

• advection terms: $p := e^{|\varphi|^2/4}$, $\nabla p = (\varphi/2)p$

$$\begin{aligned} \int_{\mathbb{R}^2} p w (U_{app} - U_0) \cdot \nabla w d\varphi &= -\frac{1}{2} \int_{\mathbb{R}^2} W^2 (U_{app} - U_0) \cdot \nabla p d\varphi \\ &= \frac{1}{4} \int_{\mathbb{R}^2} W^2 \underbrace{(U_{app} - U_0) \cdot \varphi}_{\leq C\varepsilon^2} p d\varphi \end{aligned}$$

$$\Rightarrow \frac{1}{\delta} |\langle w, (U_{app} - U_0) \cdot \nabla w \rangle_{\mathcal{Y}}| \leq C \frac{\varepsilon^2}{\delta} \|w\|_{\mathcal{Y}}^2 = C \frac{t}{T_0} \|w\|_{\mathcal{Y}}^2$$

$$\text{Idem: } \frac{1}{\delta} |\langle w, V \cdot \nabla (R_{app} - R_1) \rangle_{\mathcal{Y}}| \leq C \frac{\varepsilon^2}{\delta} \|w\|_{\mathcal{Y}}^2$$

$$|E(f, z; \frac{\varepsilon}{\delta} t)| \leq \varepsilon^2 |\varphi| + C \varepsilon^3$$

$$\Rightarrow \frac{1}{\delta} \langle w, E(f, z) \cdot \nabla w \rangle \leq \frac{\varepsilon^2}{\delta} \mathcal{F}[w] = \frac{t}{T_0} \mathcal{F}[w].$$

- Nonlinear term: $\| \langle w, v \cdot \nabla w \rangle_y \| \leq C \bar{F}[w]^{1/2} \mathcal{E}[w]$ classical estimates

- remainder term:

$$\frac{1}{\delta^2} |\langle w, R_{app} \rangle| \leq C \left(\frac{\varepsilon^5}{\delta^2} + \varepsilon^2 \right).$$

Summarising: $\exists k > 0 \ \exists C > 0$

$$E \partial_t \mathcal{E}[w] + 2 \left(k - \frac{E}{T_0} \right) \bar{F}[w] \leq C \frac{E}{T_0} \mathcal{E}[w] + C \bar{F}[w]^{1/2} \mathcal{E}[w] + C \left(\frac{\varepsilon^5}{\delta^2} + \varepsilon^2 \right)^2.$$

Assuming that $E/T_0 \leq T/T_0 \leq k/2$, we can integrate the differential inequality to obtain the estimate:

$$\|w(\tau)\|_y = \mathcal{E}[w(\tau)]^{1/2} \leq C \left(\frac{\varepsilon^5}{\delta^2} + \varepsilon^2 \right), \quad 0 < t \leq T.$$

In particular $\delta \|w(\tau)\|_y \leq C \left(\frac{\varepsilon^5}{\delta^2} + \delta \varepsilon^2 \right) \leq C \varepsilon^2 (\varepsilon + \delta)$. Since

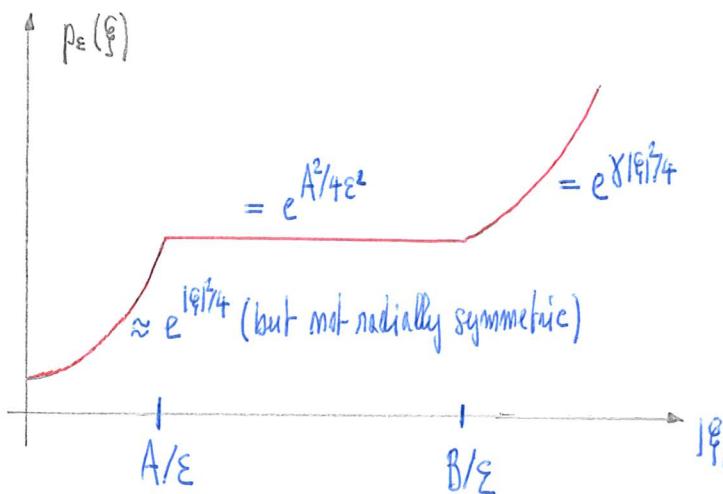
$\|w(\cdot, \tau)\|_1 \leq C \|w(\cdot, \tau)\|_y$, this gives the estimate in Thm 2.

General case: T/T_0 potentially large

- The advection term $\frac{1}{\delta} E(f, z) \cdot \nabla w$ cannot be controlled as before
 \Rightarrow one has to modify the weight function so that it is constant on the streamlines of $U_0 + E(f, z)$. This can be done if $|q| \leq A/\varepsilon$, $A \ll 1$
- For $A \leq |q|/\varepsilon \leq B$ with $B \gg 1$, the weight function is taken constant.
- For $|q| \geq B/\varepsilon$ one takes the weight $\exp(\gamma |q|^2/4)$ with $\gamma = A^2/B^2 \ll 1$.

The calculations are (much) more complicated, but lead to a similar differential inequality for $\mathcal{E}[w]$.

The weight function in the general case



$$\begin{aligned} A &\ll 1 \ll B \\ \gamma &= A^2/B^2 \ll 1 \end{aligned}$$

$$\mathcal{E}_\varepsilon[W] = \int_{\mathbb{R}^2} |W(\xi)|^2 p_\varepsilon(\xi) d\xi, \quad \mathcal{F}_\varepsilon[W] = \int_{\mathbb{R}^2} \{ |\nabla W|^2 + \chi_\varepsilon W^2 + W^2 \} p_\varepsilon(\xi) d\xi$$

Inner region: $|\xi| \leq A/\varepsilon$ $p_\varepsilon(\xi, t) = \exp(q_\varepsilon(\xi, t))$, $\chi_\varepsilon = |\xi|^2$

$$[q_\varepsilon(\xi, t) = \frac{|\xi|^2}{4} + \frac{\varepsilon^2 T_0}{4 V_0(\xi)} (b(H)(\xi_1^2 - \xi_2^2) - 2a(H)\xi_1 \xi_2), \quad V_0(\xi) = \frac{1}{2\pi|\xi|^2} (1 - e^{-|\xi|^2/4})].$$

Has the property that $U_0 \cdot \nabla q_\varepsilon + \varepsilon^2 E_2 \cdot \nabla q_\varepsilon = O(|\xi|^2 + |\xi|^4 \varepsilon^4)$; partial cancellation,
or: $U_0 \cdot \nabla q_\varepsilon + \varepsilon^2 E_2 \cdot \nabla q_0 = 0$.

Intermediate region: $p_\varepsilon(\xi) = \exp(A^2/4\varepsilon^2)$, $A/\varepsilon \leq |\xi| \leq B/\varepsilon$, $\chi_\varepsilon = A^2/\varepsilon^2$

\Rightarrow all advection terms give zero contribution to $\mathcal{F}_\varepsilon[\mathcal{E}_\varepsilon[W]]$.

Far-field region: $|\xi| \geq B/\varepsilon$, $p_\varepsilon(\xi) = e^{\gamma|\xi|^2/4}$, $\chi_\varepsilon = \gamma|\xi|^2$.

This region is dominated by the diffusion operator \mathcal{L} .

$$\text{Since } \frac{1}{\delta} |E(\xi, t)| \leq C \frac{\varepsilon}{\delta} = \frac{C}{\varepsilon} \frac{t}{T_0} \leq \frac{C}{\varepsilon} \frac{T}{T_0},$$

the contribution of $\frac{1}{\delta} E(\xi, t) \cdot \nabla$ is smaller than that of $\frac{1}{2} \xi \cdot \nabla$, provided $B \gg 1$. \square

IV The ill-prepared case : Gaussian initial data

We now investigate, at least on an example, what happens if we consider sharply concentrated initial data which differ from a point vortex. To simplify the comparison with Thm 2, we choose some time $t_0 \in (0, T)$ and we assume that:

$$\boxed{W(x, t_0) = \frac{\Gamma}{\nu t_0} \Omega_0 \left(\frac{x - z_0}{\sqrt{\nu t_0}} \right), \quad x \in \mathbb{R}^2} \quad (*)$$

for some $z_0 \in \mathbb{R}^2$.

Thm 3: Fix $\Gamma > 0$, $z_0 \in \mathbb{R}^2$, $0 < t_0 < T$. There exist positive constants k_0, δ_0, c_0 such that, if $0 < \nu/\Gamma < \delta_0$, the solution of (Vf) with initial data (*) at time t_0 satisfies; for $t_0 \leq t \leq T$:

$$\frac{1}{\pi} \int_{\mathbb{R}^2} |W(x, t) - W_{app}(\Gamma, \sqrt{\nu t}, z(t), f(\cdot, t); x)| dx \leq k_0 \varepsilon^2 \left(\delta^{1/6} \log \frac{1}{\delta} + \left(\frac{t_0}{t} \right)^\beta \right)$$

where $\delta = \nu/\Gamma$, $\varepsilon = \sqrt{\nu t}/\delta$, $\beta = c_0 \delta^{-1/3}$, and z is the unique solution of the ODE

$$z'(t) = f(z(t), t) + \nu t \Delta f(z(t), t), \quad z(t_0) = z_0.$$

Remark: At time t_0 , in view of (*), we have

$$\frac{1}{\pi} \| W(\cdot, t_0) - W_{app}(\Gamma, \sqrt{\nu t_0}, z_0, f(\cdot, t_0); \cdot) \|_{L^1} = O(\varepsilon(t_0)^2) \quad \text{if } a(t_0), b(t_0) \neq (0, 0).$$

If $t \geq t_0 + O(\delta^{1/3} \log \frac{1}{\delta})$, the estimate in Thm 3 shows that

$$\frac{1}{\pi} \| W(\cdot, t_0) - W_{app}(\Gamma, \sqrt{\nu t}, z(t), f(\cdot, t)) \|_{L^1} \leq k \varepsilon^2 \delta^{1/6} \log \frac{1}{\delta} \ll k \varepsilon^2.$$

During that short interval, the initially radially symmetric vortex adapts its shape to the strain of the external field. The relaxation rate $\beta = c_0 \delta^{-1/3}$ becomes very large as $\delta \rightarrow 0+$: enhanced dissipation effect!

The strategy of the proof of Thm 3 is very similar to that of Thm 2. We use self-similar variables and decompose the variationality as above:

$$\Omega(\xi, t) = \Omega_{\text{app}}(\xi, t) + \delta W(\xi, t), \quad t \geq t_0.$$

We thus arrive at the evolution equation

$$t \partial_t W + \frac{1}{\delta} \Lambda W + \frac{1}{\delta} A[W] + B[W, W] = \mathcal{L}W - \frac{1}{\delta^2} R_{\text{app}}, \quad t \geq t_0, \quad (\text{Weg})$$

⚠ The Cauchy pb for (Weg) is well-posed at time $t_0 > 0$! No problem with the time derivative $t \partial_t$ \Rightarrow We can impose arbitrary initial data,

In view of (*) we have:

$$W(\xi, t_0) = \varphi_0(\xi) := \frac{1}{\delta} (\Omega_0(\xi) - \Omega_{\text{app}}(\xi, t_0)) = O\left(\frac{\varepsilon_0^2}{\delta}\right) = O\left(\frac{t_0}{T_0}\right)$$

where $\varepsilon_0 = \sqrt{t_0 T_0} / d \ll 1$. This is in contrast with the proof of Thm 1 where $W(\xi, 0) = 0$.

The idea is now to make another decomposition:

$$W(\xi, t) = W_0(\xi, t) + \tilde{W}(\xi, t), \quad V(\xi, t) = V_0(\xi, t) + \tilde{V}(\xi, t),$$

where:

i) W_0 solves a linear equation with nonzero initial data:

$$\begin{cases} t \partial_t W_0(\xi, t) + \frac{1}{\delta} \Lambda W_0(\xi, t) = \mathcal{L}W_0(\xi, t), & t \geq t_0 \\ W_0(\xi, t_0) = \varphi_0(\xi) \end{cases}$$

ii) \tilde{W} solves a nonlinear equation with zero initial data:

$$\begin{cases} t \partial_t \tilde{W} + \frac{1}{\delta} \Lambda \tilde{W} + \frac{1}{\delta} A[W_0 + \tilde{W}, V_0 + \tilde{V}] + B[W_0 + \tilde{W}, V_0 + \tilde{V}] = \mathcal{L}\tilde{W} - \frac{1}{\delta^2} R_{\text{app}} \\ \tilde{W}(\xi, t_0) = 0. \end{cases}$$

Idea: W_0 decays rapidly to zero, \tilde{W} stays small.

Step 1: Enhanced dissipation estimates

To study the evolution equation for W_0 , it is convenient to introduce the logarithmic time

$$\tilde{\tau} = \log(t/t_0) \Leftrightarrow t = t_0 e^{\tilde{\tau}} \quad \begin{cases} t > t_0 \\ \tilde{\tau} \geq 0 \end{cases}$$

The equation becomes:

$$\partial_{\tilde{\tau}} W_0(\xi, \tilde{\tau}) + \frac{1}{\delta} \Lambda W_0(\xi, \tilde{\tau}) = \mathcal{L} W_0(\xi, \tilde{\tau}) \quad \xi \in \mathbb{R}^2, \tilde{\tau} \geq 0.$$

The solution can be written in the form:

$$W_0(\tilde{\tau}) = e^{\tilde{\tau}(L - 1/\delta \Lambda)} \varphi_0, \quad \tilde{\tau} \geq 0.$$

Remark: Since $W_0 \in Y$ and $\int_{\mathbb{R}^2} W_0 d\xi = 0$, we have

$$\begin{aligned} \frac{1}{2} \frac{d}{d\tilde{\tau}} \|W_0(\tilde{\tau})\|_Y^2 &= \langle W_0(\tilde{\tau}), \partial_{\tilde{\tau}} W_0(\tilde{\tau}) \rangle_Y \\ &= \langle W_0(\tilde{\tau}), \mathcal{L} W_0(\tilde{\tau}) \rangle_Y - \frac{1}{\delta} \langle W_0(\tilde{\tau}), \Lambda W_0(\tilde{\tau}) \rangle_Y \\ &\leq -\frac{1}{2} \|W_0(\tilde{\tau})\|_Y^2, \quad \text{cf. Prop 1. on page 17.} \end{aligned}$$

$$\Rightarrow \|W_0(\tilde{\tau})\|_Y \leq e^{-\tilde{\tau}/2} \|\varphi_0\|_Y, \quad \forall \tilde{\tau} \geq 0.$$

This simple energy estimate does not take into account the "mixing effect" of the skew-symmetric operator Λ , which is important if $\delta \ll 1$.

Thm: (Te Li, Dongyi Wei, Zhiwei Zhang, 2020)

There exist positive constants $C_0 > 0, c_0 > 0$ such that; for $0 < \delta < 1$:

$$\|W_0(\tilde{\tau})\|_Y \leq C_0 e^{-c_0 \delta^{-1/3} \tilde{\tau}} \|\varphi_0\|_Y, \quad \forall \tilde{\tau} \geq 0 \quad \Delta \varphi_0 \in \ker(\Lambda)^\perp!$$

The decay rate here is $C_0 \delta^{-1/3} \gg 1$ if δ is small: enhanced dissipation effect.

N.B. An exponential decay in the logarithmic time \tilde{T} corresponds to a polynomial decay in the original time t .

Remark: The decay rate $c_0 \delta^{-1/3}$ is optimal for general initial data, but might be improved for the particular data φ_0 considered here. To compare with:

- decay rate for monotone shear flows: $\propto \delta^{-2/3}$ (Coutette)
- decay rate for shear flows with a non-degenerate stagnation point: $\propto \delta^{-1/2}$

Enhanced dissipation estimates can be used to study the size of the basin of attraction of the Lamb-Oseen vortex, see ThG 2018.

[Corollary 1 (easy): $\int_0^\infty \|W_0(\tilde{\tau})\|_y^2 d\tilde{\tau} \leq C \delta^{1/3}$,

N.B. No such estimate exists for $\nabla W_0(\tilde{\tau})$: One can show that

$$\int_0^\infty \|\nabla W_0(\tilde{\tau})\|_y^2 d\tilde{\tau} \geq \frac{1}{2} \|\varphi_0\|_y^2 !$$

[Corollary 2 (more difficult): If $\gamma > 1/8$, there exists $C > 0$ such that
 $\forall \varphi_0 \in \ker(\Lambda)^\perp$:

$$\int_0^\infty \||\xi|W_0(\tilde{\tau})\|_y^2 d\tilde{\tau} \leq C \delta^{1/3} \log\left(\frac{1}{\delta}\right) \underbrace{\sup_{\xi \in \mathbb{R}^2} e^{2\gamma|\xi|^2} |\varphi_0(\xi)|^2}_{< \infty \text{ if } \gamma < 1/4}.$$

Idea of the proof:

- In the region where $|\xi| \leq N \log(1/\delta)^{1/2}$: use corollary 1
- In the region where $|\xi| > N \log(1/\delta)^{1/2}$: The operator Λ can be replaced by $\Lambda_0 = U_0 \cdot \nabla$, because $|\Omega_0| \leq C \delta^{17/4}$ (\Rightarrow the nonlinear term is small).

The advection operator Λ_0 can be handled by energy estimates for any radial weight.

Step 2 : Energy estimates

We return to the equation for \tilde{w} :

$$\begin{cases} E \partial_t \tilde{w} + \frac{1}{\delta} \Delta \tilde{w} + \frac{1}{\delta} A[w_0 + \tilde{w}] + B[v_0 + \tilde{w}, w_0 + \tilde{w}] = \mathcal{L}\tilde{w} - \frac{1}{\delta^2} R_{app} \\ \tilde{w}(t_0) = 0 \end{cases}$$

The particular case where $w_0 = 0$ has been treated in Thm 2.

All terms involving w_0 are considered as additional source terms, and estimated using Corollaries 1 and 2 above. This leads to an estimate of the form:

$$\| \mathcal{E}[\tilde{w}(\cdot, t)]^{1/2} \| \leq C \left(\frac{\varepsilon^5}{\delta^2} + \varepsilon^2 \right) + C \delta^{1/6} \left(\log \frac{1}{\delta} \right)^{1/2} \frac{t}{T_0}, \quad t_0 \leq t \leq T.$$

As in Thm 2, we can take $\mathcal{E}[\tilde{w}] = \|\tilde{w}\|_Y^2$ if $T \ll T_0$, but in the general case a more complicated energy functional has to be used.

Summarizing, we have shown:

$$\begin{aligned} \| \mathcal{L}(t) - \mathcal{L}_{app}(t) \|_{L^1} &= \delta \| w(t) \|_{L^1} \leq \delta \| w_0(t) \|_{L^1} + \delta \| \tilde{w}(t) \|_{L^1} \\ &\leq C \delta \| w_0(t) \|_Y + C \delta \mathcal{E}[\tilde{w}(\cdot, t)]^{1/2} \\ &\leq C \delta \left(\frac{t_0}{t} \right)^\beta \frac{t_0}{T_0} + C \delta \frac{t}{T_0} \delta^{1/6} \left(\log \frac{1}{\delta} \right)^{1/2} \\ &\leq C \varepsilon^2 \left(\left(\frac{t_0}{E} \right)^\beta + \delta^{1/6} \left(\log \frac{1}{\delta} \right)^{1/2} \right), \quad \text{where } \beta = c_0 \delta^{-1/3} \gg 1. \end{aligned}$$

Returning to the original variables, this implies the approximation property stated in Thm 3. \square

