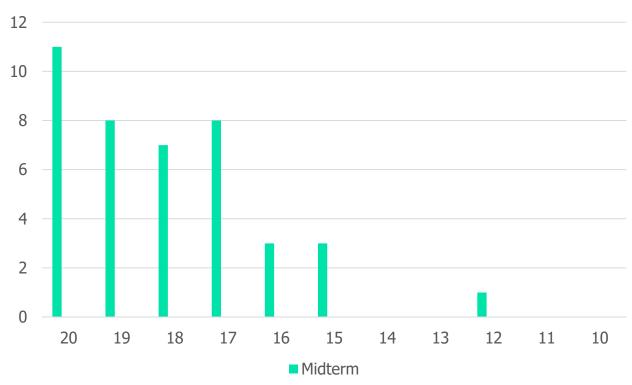


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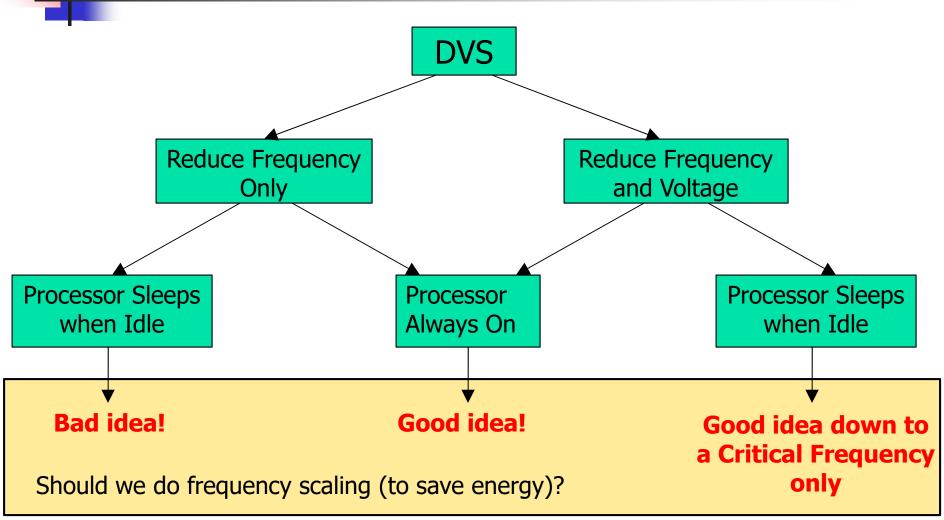
Midterm

Average grade = 18

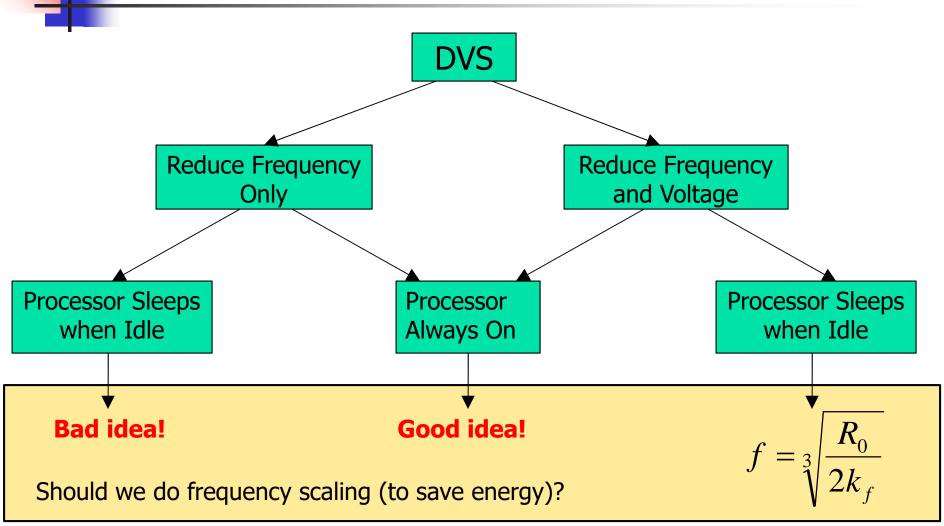












Advanced Configuration and Power Interface (ACPI)

- Defines different power saving states in a platform-independent manner
- The standard was originally developed by Intel, Microsoft, and Toshiba (in 1996), then later joined by HP, and Phoenix.
- The latest version is "Revision 6.1," published by UEFI (March 2016).



Global States

- **G0**: working
- G1: Sleeping and hibernation (several degrees available)
- **G2**:, *Soft Off*: almost the same as G3 *Mechanical Off*, except that the power supply still supplies power, at a minimum, to the power button to allow wakeup. A full reboot is required.
- **G3**, *Mechanical Off*: The computer's power has been totally removed via a mechanical switch.

Processor Performance States (P-States)

- P0 max power and frequency
- P1 less than P0, voltage/frequency scaled
- P2 less than P1, voltage/frequency scaled
- ...
- Pn less than P(n-1), voltage/frequency scaled

Processor "Sleep" States (C-states)

- C0: is the operating state.
- **C1** (often known as *Halt*): is a state where the processor is not executing instructions, but can return to an executing state instantaneously. All ACPI-conformant processors must support this power state.
- C2 (often known as Stop-Clock): is a state where the processor maintains all software-visible state, but may take longer to wake up. This processor state is optional.
- **C3** (often known as *Sleep*) is a state where the processor does not need to keep its cache, but maintains other state. This processor state is optional.



- ullet Energy expended on wakeup, E_{wake}
- To sleep or not to sleep?

Turning Processors Off The Cost of Wakeup

- ullet Energy expended on wakeup, E_{wake}
- To sleep or not to sleep?
 - Not to sleep (for time t):

$$E_{no\text{-sleep}} = (k_v V^2 f + R_0) t$$

■ To sleep (for time t) then wake up:

$$E_{sleep} = P_{sleep} t + E_{wake}$$

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■ To save energy by sleeping: $E_{sleep} < E_{no\text{-}sleep}$

$$t > \frac{E_{wake}}{k_{v}V^{2}f + R_{0} - P_{sleep}}$$

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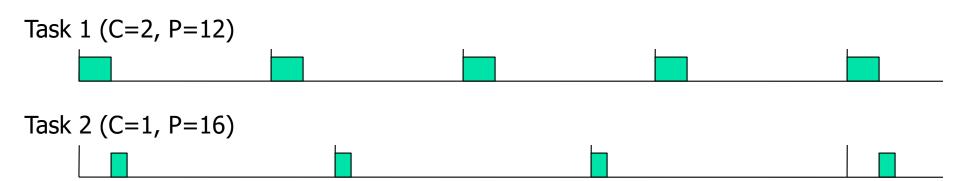
$$t > \frac{E_{wake}}{k_v V^2 f + R_0 - P_{sleep}} \qquad \qquad \text{Minimum sleep interval}$$



Dynamic Power Management

- DPM refers to turning devices off (or putting them in deep sleep modes)
- Device wakeup has a cost that imposes a minimum sleep interval (a breakeven time)
- DPM must maximize power savings due to sleep while maintaining schedulability

Example:

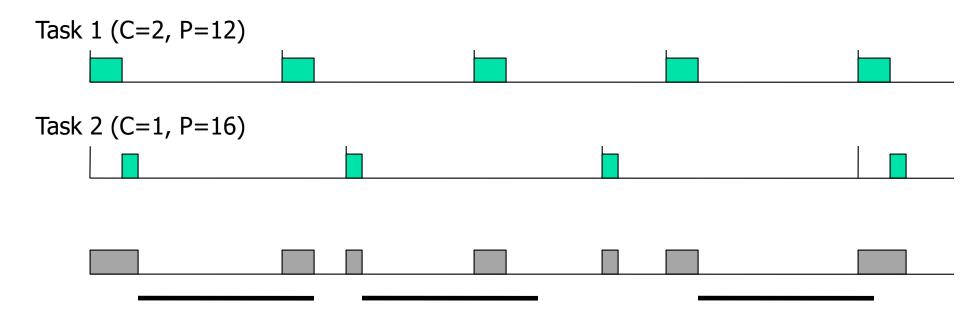


Example:

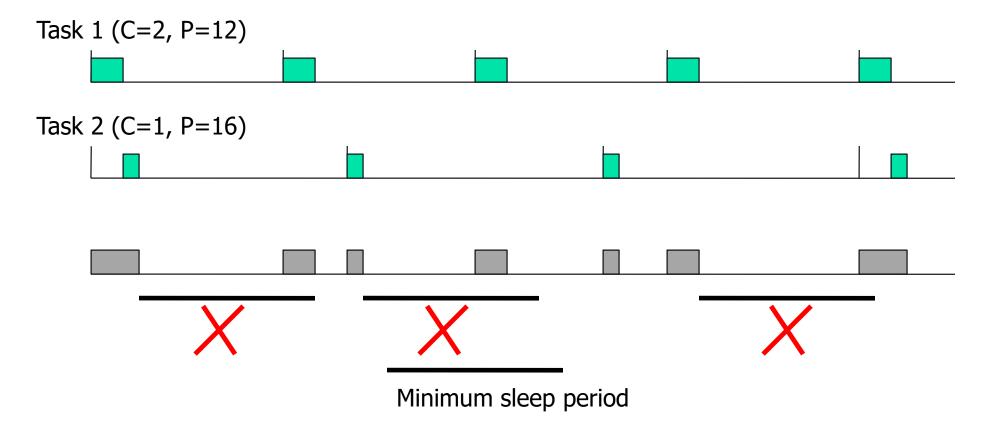
Task 1 (C=2, P=12)

Task 2 (C=1, P=16)

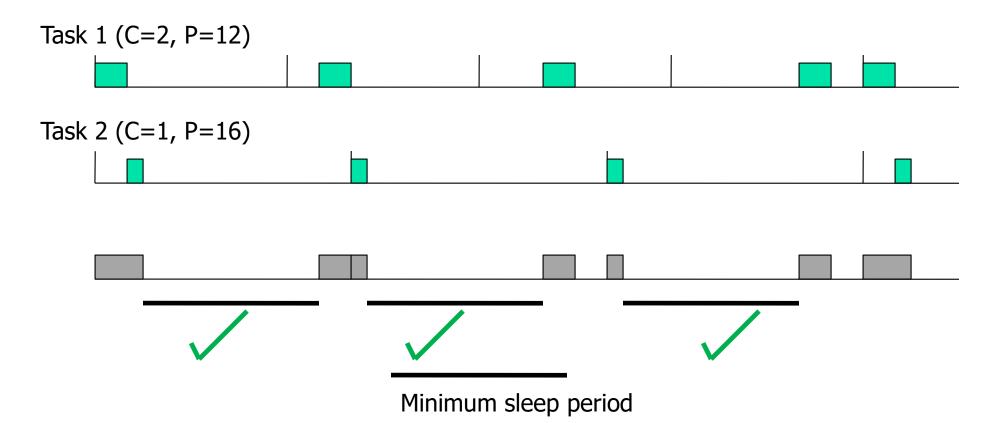
Example:



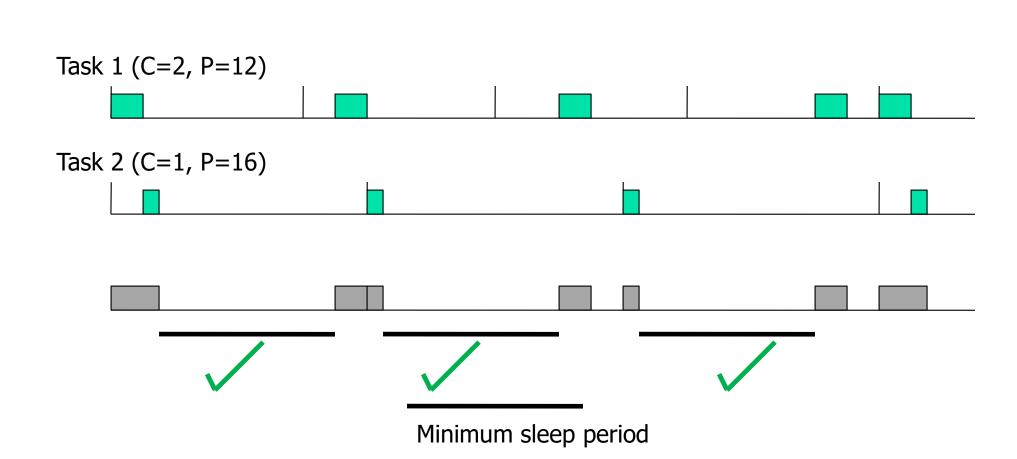
■ No opportunity to sleep ⊗



Must batch! <a> \omega\$

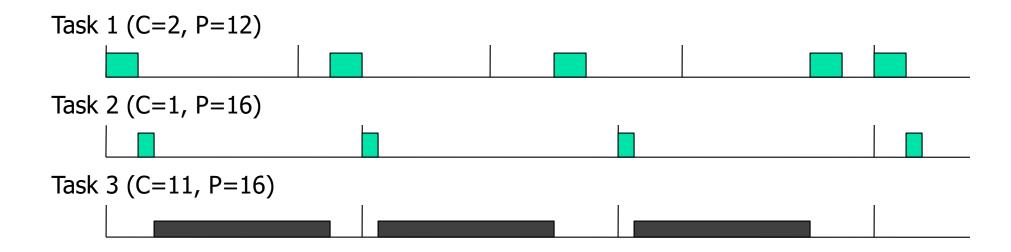


How to Analyze Schedules with Sleep Periods?



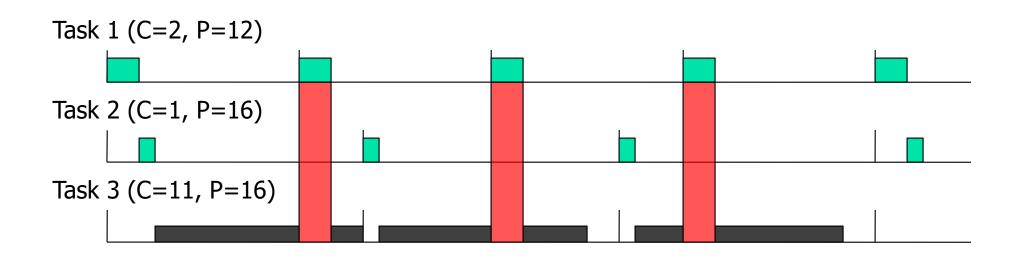
How to Analyze Schedules with Sleep Periods?

Option 1: Treat sleep periods like a sporadic task. Use the Liu and Layland utilization bound for schedulability. Problems?



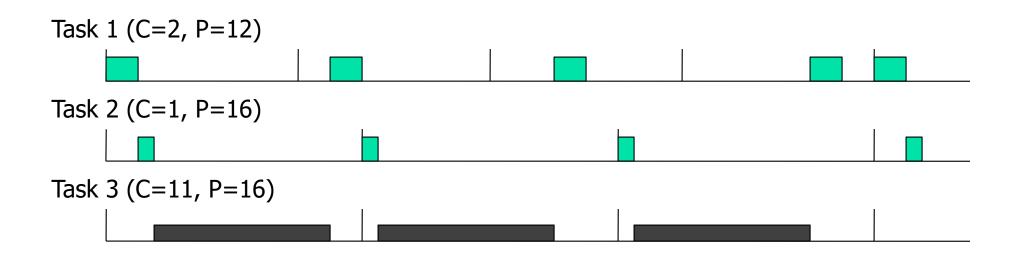
A Schedulability Question: How to Analyze Schedules with Sleep Periods?

- Option 1: Treat sleep periods like a periodic task. Use the Liu and Layland utilization bound for schedulability. Problems?
 - Does not work because the "sleep task" cannot be preempted, whereas the rest of the tasks are preemptible. The utilization bound works only for fully preemptive scheduling.



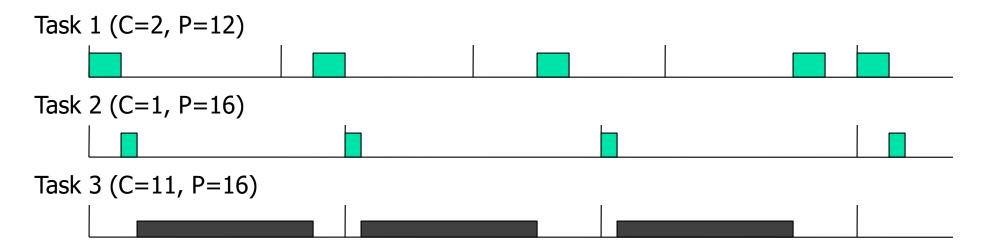
How to Analyze Schedules with Sleep Periods?

Option 2: Treat sleep periods like the highest-priority periodic task. Use the Liu and Layland utilization bound for schedulability. Problems?



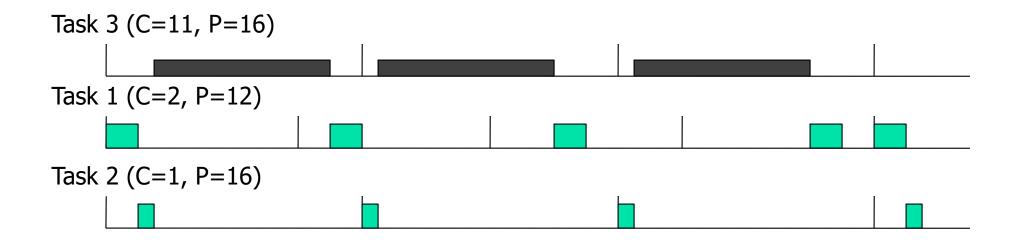


- Option 2: Treat sleep periods like the highest-priority periodic task. Use the Liu and Layland utilization bound for schedulability. Problems?
 - Does not work because the "sleep task" may need to have a larger period than the actual top-priority task, which contradicts ratemonotonic scheduling. The bound does not work.



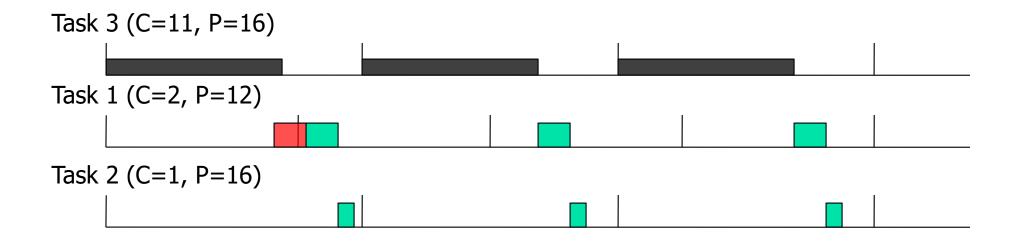
How to Analyze Schedules with Sleep Periods?

Option 3: Treat sleep periods like the highest-priority periodic task. Use exact response time analysis for schedulability. Problems?



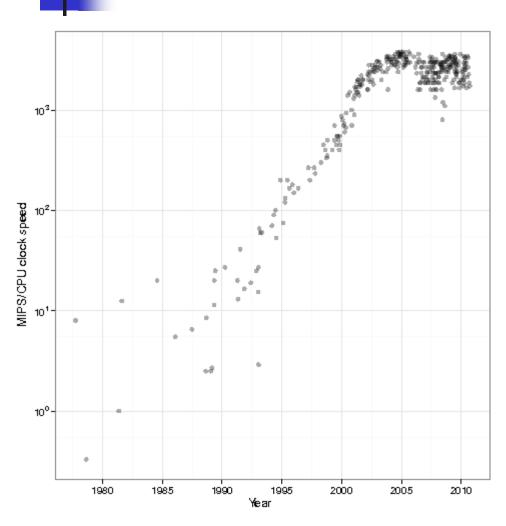
Device Forbidden Regions

- Option 3: Treat sleep periods like the highest-priority periodic task. Use exact response time analysis for schedulability. Problems?
 - A Valid solution, but pessimistic.
 (Called: Device Forbidden Regions. Published in RTAS 2008.)



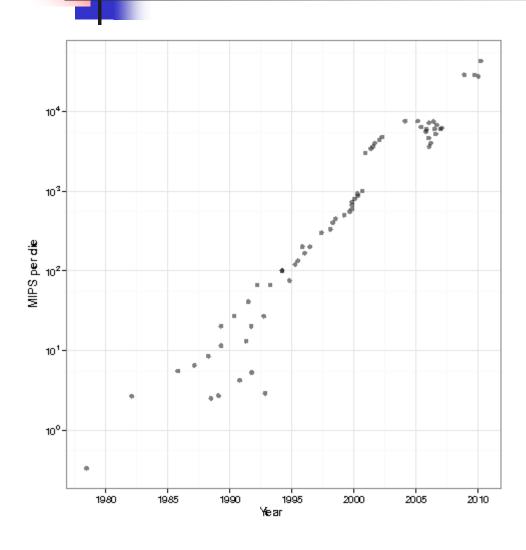


Intel CPU Clock Speed



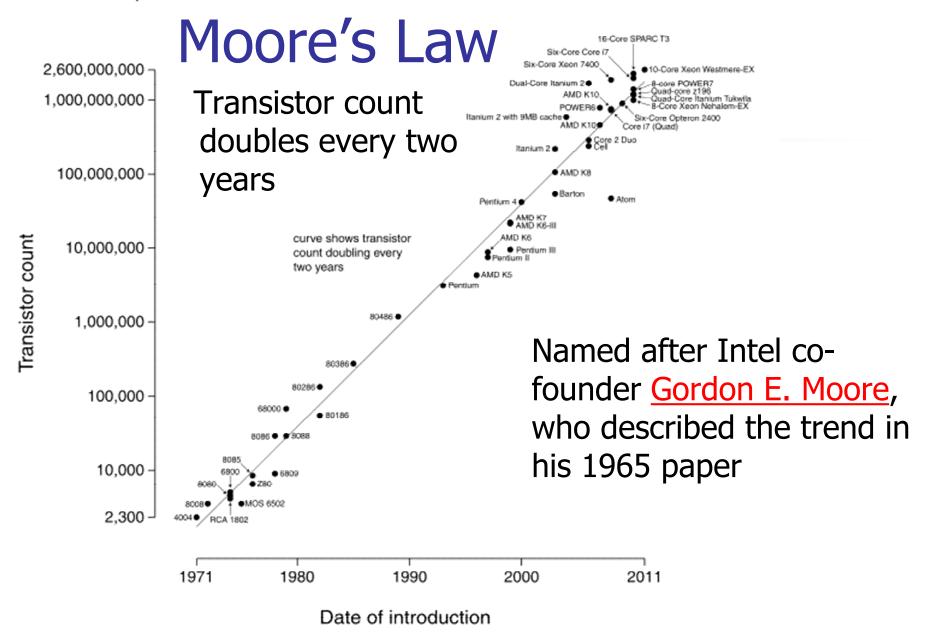
- Moore's Law (1980-2005)
- Question: Why did the speed curve saturate (around 2005)?

Computational Power (per Die)

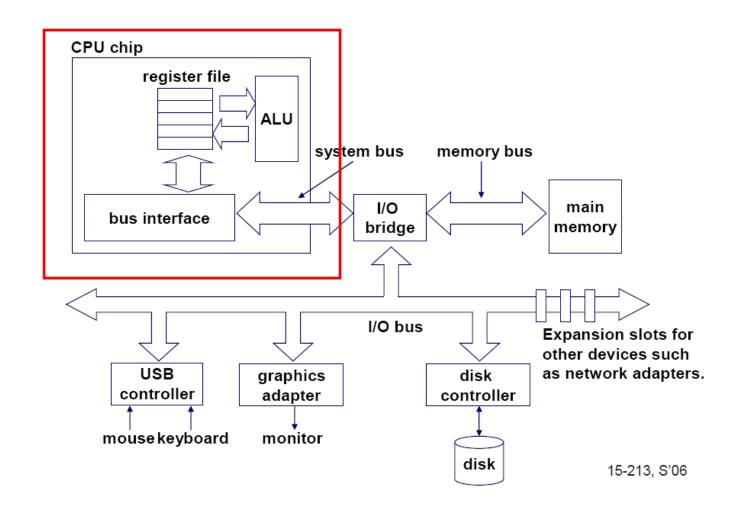


- Note the exponential rise in power consumption
- Question: how come it does not saturate?

Microprocessor Transistor Counts 1971-2011 & Moore's Law

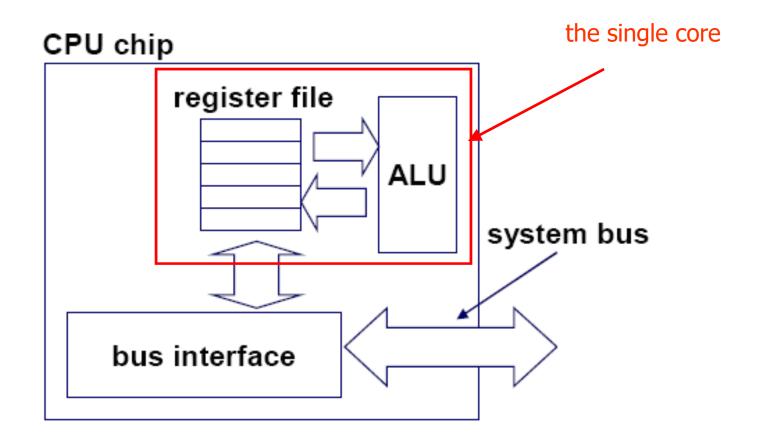


Single-core computer





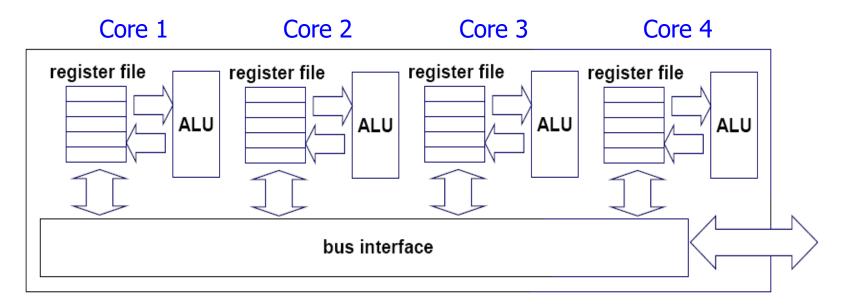
Single-core CPU chip





Multi-core Architectures

 Replicate multiple processor cores on a single die.





- OS perceives each core as a separate processor
- OS scheduler maps threads/processes to different cores
- Major OSes support multi-core today:
 Windows, Linux, Mac OS X, ...



DVS on Multiprocessors

- Consider a set of tasks, where task i has period P_i and total number of cycles C_i
 - Sort tasks from largest to smallest utilization C_i / P_i
 - Assign tasks one at a time (largest-first) to the least utilized processor
 - Apply one of the previous algorithms on each processor separately

Question

From the perspective of minimizing energy, is it always a good idea to use up all processors?

How Many Processors to Use?

- Consider using one processor at frequency f
 versus two at frequency f/2
- Case 1: Total power for one processor
 - $k_f f^3 + R_0$
- Case 2: Total power for two processors
 - $2 \{k_f (f/2)^3 + R_0\} = k_f f^3 / 4 + 2 R_0$

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- The general case: *n* processors
 - $n \{k_f (f/n)^3 + R_0\} = k_f f^3 / n^2 + n R_0$

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$$n = \sqrt[3]{\frac{2k_f f^3}{R_0}}$$

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What if n is not an integer?