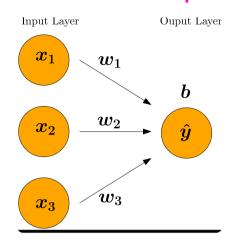
## CH3.2 Multiple Linear Repression



Multiple linear repression:

$$\hat{y} = \omega_1 \chi_1 + \omega_2 \chi_2 + \omega_3 \chi_3 + b$$

w<sub>1</sub>, w<sub>2</sub>, w<sub>3</sub> → weights b → bias

Consider the input points in the form  $(X_1, X_2, X_3)$  and the output points  $y_i$  for i=1,2,...,N. Our deato may look like

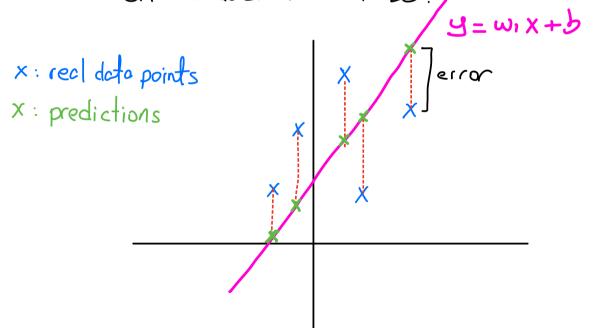
$$\frac{x_{1}}{x_{2}}$$
  $\frac{x_{2}}{x_{3}}$   $\frac{x_{3}}{x_{4}}$   $\frac{x_{2}}{x_{3}}$   $\frac{x_{3}}{x_{4}}$   $\frac{x_{4}}{x_{5}}$   $\frac{x_{2}}{x_{5}}$   $\frac{x_{3}}{x_{5}}$   $\frac{x_{5}}{x_{5}}$   $\frac{x_{5}}{x$ 

Define a loss function to measure the error between the prediction and the reel labeled value. The most common one could be "the mean-squae" loss function

$$C(\hat{y}) := \frac{1}{N} \underbrace{\sum_{i=1}^{N} (\hat{y}_{i} - y_{i})^{2}}_{\text{real value}} \text{ real value}$$

$$= \frac{1}{N} \underbrace{\sum_{i=1}^{N} (\omega_{i} \chi_{i}^{(i)} + \omega_{2} \chi_{2}^{(i)} + \omega_{3} \chi_{3}^{(i)} + b - y_{i})^{2}}_{\text{prediction}}$$

Remorks: (1) Notice that we measure the error for each point for i=1,2,... N and overgre them out. We can better understood this in 2D.



(2) There are various types of loss functions (cross extropy, L, loss, Huber loss etc.). They all sever the same purpose

## Then we can stock our problem as follows find w, wz, wz and b thered minimizes ((ŷ))

We will use gradient deant so we need partial derivatives  $\frac{\partial C}{\partial w_1}$ ,  $\frac{\partial C}{\partial w_2}$  and  $\frac{\partial C}{\partial b}$ 

From (x) C is a function of  $\hat{y}_1, \hat{y}_2, \dots \hat{y}_k$  and every each of these prediction one function of  $w_1, w_2, w_3, b$  We can display this as

$$\hat{y}_{1} \qquad \hat{y}_{2} \qquad \hat{y}_{3} \qquad \hat{y}_{N}$$

$$\omega_{1} \qquad \omega_{3} \qquad \omega_{3} \qquad \omega_{4}$$

$$C = \frac{1}{N} \left( (\hat{y}_1 - y_1)^2 + (\hat{y}_2 - y_2)^2 + \dots (\hat{y}_i - y_i)^2 + \dots (\hat{y}_N - y_N)^2 \right)$$
where  $\hat{y}_i = \omega_i x_1 + \omega_2 x_2 + \omega_3 x_3 + b$ 

$$\frac{\partial c}{\partial \omega_{i}} = \frac{\partial c}{\partial \hat{y}_{i}} \cdot \frac{\partial \hat{y}_{i}}{\partial \omega_{i}} + \frac{\partial c}{\partial \hat{y}_{i}} \cdot \frac{\partial \hat{y}_{i}}{\partial \omega_{i}} + \cdots + \frac{\partial c}{\partial \hat{y}_{i}} \cdot \frac{\partial \hat{y}_{i}}{\partial \omega_{i}} = \frac{1}{N} \cdot \frac{N}{i=1} \cdot \frac{N}{\partial \hat{y}_{i}} \cdot \frac{\partial \hat{c}}{\partial \omega_{i}} \cdot \frac{\partial \hat{y}_{i}}{\partial \omega_{i}}$$

$$= 2 \left( \hat{y}_{1} - y_{1} \right) \chi_{1}^{(i)} + 2 \left( \hat{y}_{2} - y_{2} \right) \chi_{1}^{(i)} + \cdots + 2 \left( \hat{y}_{N} - y_{N} \right) \chi_{1}^{(N)}$$

$$=\frac{1}{N}\sum_{i=1}^{N}2(\hat{y}_{i}-y_{i})\times_{i}^{(i)}=\frac{2}{N}\sum_{i=1}^{N}(\hat{y}_{i}-y_{i})\times_{i}^{(i)}$$

Repeat the some procedure for Wz, Wz and L to obtain

$$\frac{\partial C}{\partial \omega_{i}} = \frac{\partial}{\partial x} \sum_{i=1}^{n} (\hat{y}_{i} - y_{i}) x_{i}^{(i)}$$

$$\frac{\partial C}{\partial \omega_{2}} = \frac{\partial}{\partial x} \sum_{i=1}^{n} (\hat{y}_{i} - y_{i}) x_{2}^{(i)}$$

$$\frac{\partial C}{\partial \omega_{3}} = \frac{\partial}{\partial x} \sum_{i=1}^{n} (\hat{y}_{i} - y_{i}) x_{3}^{(i)}$$

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Note that we can have a more compact notation

$$\nabla C := \begin{bmatrix} \partial c/\partial w_1 \\ \partial c/\partial w_2 \\ \partial c/\partial w_3 \\ \partial c/\partial w_3 \\ \partial c/\partial w_3 \end{bmatrix} = \frac{2}{n} \sum_{i=1}^{n} \begin{bmatrix} (\hat{y}_i - y_i) x_1^{(i)} \\ (\hat{y}_i - y_i) x_2^{(i)} \\ (\hat{y}_i - y_i) x_3^{(i)} \\ (\hat{y}_i - y_i) x_3^{(i)} \end{bmatrix}$$

Then we can express the gradient decent as follows.

For 
$$W = (W_1, W_2, W_3, b)$$
 and learning rate  $\Gamma$ 

$$W = (W_1, W_2, W_3, b)$$
 and learning rate  $\Gamma$ 

$$W = W - \Gamma \nabla C(W)$$
,  $i = 0.11, 2...N$ 

$$W = W - r \nabla C(W), \quad i = 0, 1, 2, ... N$$

Ex: Consider the data set

Build a linear repression model of the form

$$\hat{y} = \omega_1 \times_1 + \omega_2 \times_2 + b$$

for this data set. Do not include the lost data point in your model and keep it for testing. It your model is good enough, given the inputs  $x_1 = 4$ ,  $x_2 = 9$  the output  $\hat{y}$  should be close to 46. Let's pick r = 0.01

Sel: let's do this step on step. let's perform gradient descent for the first desto point  $\chi''_1=3$ ,  $\chi''_2=3$ ,  $y_1=27$ 

1) Initialize the weight and the bias (only once)  $w_1 = 5$ ,  $w_2 = 2$ , b = 3

2) Forward Poss:

(b) Get the predictions for 
$$\hat{9}_1$$
.  
 $\hat{9}_1 = w_1 \chi_1'' + w_2 \chi_2'' + b_1 = 5 \cdot 3 + 2 \cdot 3 + 3 = 24$ 

2

(c) Exclude the cost  $C(\hat{y})$ .  $C(\hat{y}) = (\hat{y}_1 - y_1)^2 = (24 - 17)^2 = 9$ 

3) Back propagation

(0) Exclute the gradients

$$\frac{\partial C}{\partial w_i} = \frac{\partial C}{\partial \hat{y}_i} \frac{\partial \hat{y}_i}{\partial w_i} = 2(\hat{y}_i - y_i) \hat{y}_i^{(i)} = 2(24 - 27) \cdot 3 = -18$$

$$\frac{\partial C}{\partial w_1} = \frac{\partial C}{\partial \hat{y}_1} = \frac{\partial \hat{y}_1}{\partial w_2} = \frac{\partial C}{\partial \hat{y}_1} = \frac{\partial C}{\partial \hat{y}_2} = \frac{\partial C}{\partial \hat{y}_2} = \frac{\partial C}{\partial \hat{y}_1} = \frac{\partial C}{\partial \hat{y}_2} = \frac{\partial C}{\partial \hat{y$$

$$\underbrace{\mathcal{Z}}_{0} = \underbrace{\partial \mathcal{C}}_{0} \underbrace{\partial \mathcal{C}}_{0} = \underbrace{\partial \mathcal{C}}_{0} \underbrace{\partial \mathcal{C}}_{0} - \underbrace{\partial \mathcal{C}}_{0$$

(5) Update the weights and the bics using predient descent.

$$\omega_1 = \omega_1 - \Gamma \frac{\partial C}{\partial \omega_1} = 5 - 0.01 (-18) = 5.18$$

$$\omega_2 = \omega_1 - r \partial c / \partial \omega_2 = 2 - 0.01 (-18) = 2.18$$

## $b = b - r \cdot \partial c/\partial b = 3 - 0.01(-6) = 3.06$

Repect the same procedure for the other doto points except the lost are. Once we are done, this will make up our first epoch. Depoct the same predecure for several epochs.

When we from our model for 100 epochs, we obtain

 $\omega_1 = 6.944$ ,  $\omega_2 = 2.012$ , b = 0.372, loss = 0.07

let's test the model for the last date point (4,9) - 46

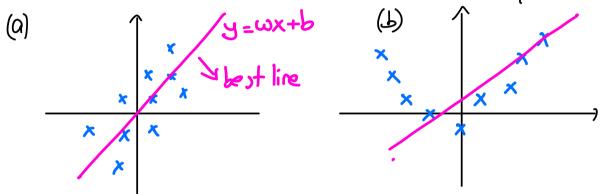
 $\hat{y} = 6.944 \times 4 + 2.012 \times 9 + 0.372 \approx 46.256$ 

This mean our model is sting o post job.

Note: (a) This is actually a tay detaset. The output is 7 times the first coloumn + 2 times the second coloumn + 0. In other word,  $7X_1 + 2X_2 + 0 = Y$ 

Premarks: (1) We repeat the some operations in this procedure, which begs for a more modulor opproach such as "outomatic differentiation".

(2) As the none supposts, we can only describe "linear" or "near-linear" doctor with multiple linear repression.



In (a), y=wx+b is a posed representative of the data. In (b), no line can desvise the data as it looks like y=ax²+sx+c quedratic duta.

Linear repression is missing two ingredients

- (1) Few number of parameters: In our riginal example, we have only 4 parameters (wi, wz, w, and b). Imagine our data has IM mus. There is no way we can describe IM data points with 4 parameters
- (2) <u>Linevity</u>: life itself is NOT linev. As we observ

above ever a couple of deta point, resulting from a quadratic function is a big challege for linear regression.

These two weaknesses will be the Lasis of our motivation to study neural retworks.

CH3.4 Neural Networks

More parameters + nonlinear activation