

# Numerical Methods

## (MTH4002)

### Lecture 03: Curve Fitting

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# Outline

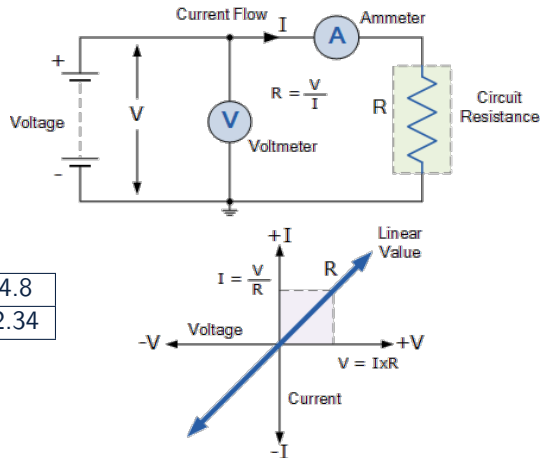
- ① Introduction to curve fitting
- ② Linear function
- ③ Nonlinear Equation
- ④ References

# Introduction

- In many scientific and engineering experiments, observations of physical quantities are measured and recorded.
- For example, measuring the current through the circuit by changing the voltage across resistor.

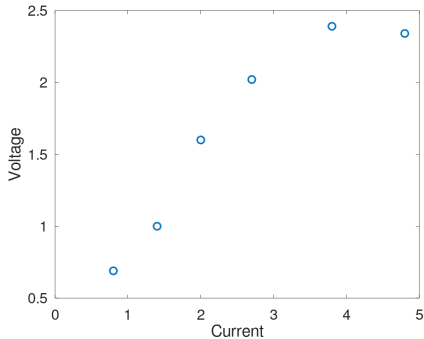
$V$ (volt)	0.8	1.4	2.0	2.7	3.8	4.8
$I$ (amp)	0.69	1.00	1.6	2.02	2.39	2.34

- The experimental records are typically referred to as **data points**.



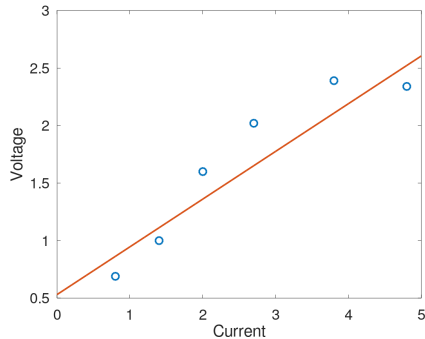
# Introduction

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# Introduction

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- The curve fits the general trend of the data but does not match any of the data points exactly.
- Generally, all experimental measurements have built-in errors or uncertainties, and requiring a curve fit to go through every data point is not beneficial.
- The objective is to find a function that fits the data points overall.

# Introduction

- Often the data is used for developing or evaluating mathematical formulas (equations) that represent the data.
- This is done by **curve fitting** in which a **specific form of an equation** is assumed, or provided by a **guiding theory**, and then the **parameters of the equation are determined** such that the **equation best fits the data points**.
- Curve fitting can be carried out with many types of functions and with polynomials of various orders.
  - Linear function, e.g.  $y = mx + c$
  - Nonlinear function, e.g.  $y = cx^2$ ,  $y = Ce^{Ax}$

## Curve fitting using linear function

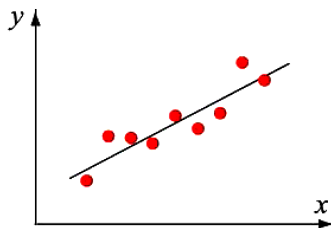
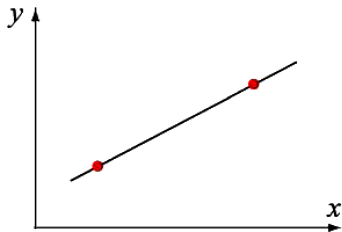
# Curve fitting with a linear function

- Curve fitting using a **linear equation** (first degree polynomial) is the process by which an equation of the form:

$$y = a_1x + a_0$$

is used to best fit given data points.

- This is done by determining the constants  $a_1$  and  $a_0$  that give the smallest error when the data points are substituted in the equation.

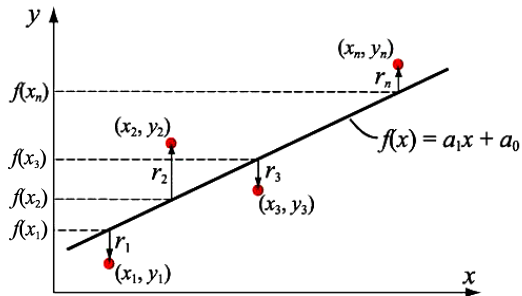




# Measuring how good is a fit

- The fit between given data points and an approximating linear function is determined by first calculating the error, also called the **residual**, which is the difference between a **data point** and the **value of the approximating function**, at each point.
- Subsequently, the residuals are used for calculating a total error for all the points.
- The residual  $r_i$  at a point,  $(x_i, y_i)$ , is the difference between the value  $y_i$  of the data point and the value of the function  $f(x_i)$  used to approximate the data points:

$$r_i = y_i - f(x_i)$$



# Measuring how good is a fit

- A **criterion** that measures how well the approximating function fits the given data can be obtained by calculating a total error  $E$  **in terms of the residuals**.

$$E = \sum_{i=1}^n r_i = \sum_{i=1}^n [y_i - (a_1 x_i + a_0)]$$

or 
$$E = \sum_{i=1}^n |r_i| = \sum_{i=1}^n |y_i - (a_1 x_i + a_0)|$$

or 
$$E = \sum_{i=1}^n r_i^2 = \sum_{i=1}^n [y_i - (a_1 x_i + a_0)]^2$$

- A **smaller  $E$  indicates a better fit**. This measure can be used to evaluate or compare proposed fits, and last equation can be used to calculate the coefficients  $a_1$  and  $a_0$  in the linear function.

# Example

**Question:** Compare the maximum error, average error, and root-mean-square error for the linear approximation  $f(x) = 8.6 - 1.6x$  to the data points  $(-1, 10)$ ,  $(0, 9)$ ,  $(1, 7)$ ,  $(2, 5)$ ,  $(3, 4)$ ,  $(4, 3)$ ,  $(5, 0)$ , and  $(6, -1)$ .

# Linear least-squares regression

- An experiment produces a set of data points  $(x_1, y_1), \dots, (x_n, y_n)$ , where the abscissas  $\{x_k\}$  are distinct.
- One **goal of numerical methods** is to determine a formula  $y = f(x)$  that relates these variables.

$$y = f(x) = a_1x + a_0$$

- **Linear least-squares regression** is a procedure in which the coefficients  $a_1$  and  $a_0$  of a linear function  $y = a_1x + a_0$  are determined such that the function has the **best fit** to a given set of data points.
- The best fit is defined as the **smallest possible total error** that is calculated by adding the squares of the residuals.

$$E = \sum_{i=1}^n [y_i - (a_1x_i + a_0)]^2$$

# Linear least-squares regression

- Take the partial derivative of above equation, we get

$$\frac{\partial E}{\partial a_0} = -2 \sum_{i=1}^n (y_i - a_1 x_i - a_0) = 0 \quad (1)$$

$$\frac{\partial E}{\partial a_1} = -2 \sum_{i=1}^n (y_i - a_1 x_i - a_0) x_i = 0 \quad (2)$$

- Above two equations are a system of two linear equations for the unknowns  $a_1$  and  $a_0$ , and can be rewritten in the form as

$$n a_0 + \left( \sum_{i=1}^n x_i \right) a_1 = \sum_{i=1}^n y_i \quad (3)$$

$$\left( \sum_{i=1}^n x_i \right) a_0 + \left( \sum_{i=1}^n x_i^2 \right) a_1 = \sum_{i=1}^n x_i y_i \quad (4)$$

# Linear least-squares regression

- Solution can be written as

$$a_1 = \frac{n \sum_{i=1}^n x_i y_i - (\sum_{i=1}^n x_i) (\sum_{i=1}^n y_i)}{n \sum_{i=1}^n x_i^2 - (\sum_{i=1}^n x_i)^2} \quad (5)$$

$$a_0 = \frac{(\sum_{i=1}^n x_i^2) (\sum_{i=1}^n y_i) - (\sum_{i=1}^n x_i y_i) (\sum_{i=1}^n x_i)}{n \sum_{i=1}^n x_i^2 - (\sum_{i=1}^n x_i)^2} \quad (6)$$

- The values of  $a_1$  and  $a_0$  in the equation  $y = a_1 x + a_0$  that has the best fit to  $n$  data points  $(x_i, y_i)$

$$a_1 = \frac{nS_{xy} - S_x S_y}{nS_{xx} - (S_x)^2} \quad a_0 = \frac{S_{xx} S_y - S_{xy} S_x}{nS_{xx} - (S_x)^2}$$

where,

$$S_x = \sum_{i=1}^n x_i, \quad S_y = \sum_{i=1}^n y_i, \quad S_{xy} = \sum_{i=1}^n x_i y_i, \quad S_{xx} = \sum_{i=1}^n x_i^2$$

# Example

**Question:** Find the least-squares line for the data points  $(-1, 10)$ ,  $(0, 9)$ ,  $(1, 7)$ ,  $(2, 5)$ ,  $(3, 4)$ ,  $(4, 3)$ ,  $(5, 0)$ , and  $(6, -1)$ .

# Algorithm for the linear least-square regression

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## Algorithm 1: Algorithm for Linear Least-Square Regression

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**Result:** Find the linear function  $f(x) = a_1x + a_0$  which best fit the given data points  $(x_i, y_i)$ , i.e., find the parameter  $a_0$  and  $a_1$  for which the Sum-of-Squared Error is minimum.

**Initialization:** Initialize the values of  $x$ ,  $y$ .

1. Compute the length of  $x$  and  $y$ .
2. If the length of  $x$  and  $y$  is not equal then terminate the program.
3. Compute the value of  $s_x$ ,  $s_y$ ,  $s_{xx}$ , and  $s_{xy}$  as

$$S_x = \sum_{i=1}^n x_i, \quad S_y = \sum_{i=1}^n y_i, \quad S_{xy} = \sum_{i=1}^n x_i y_i, \quad S_{xx} = \sum_{i=1}^n x_i^2$$



# Algorithm for the linear least-square regression

4. Compute  $a_0$  and  $a_1$

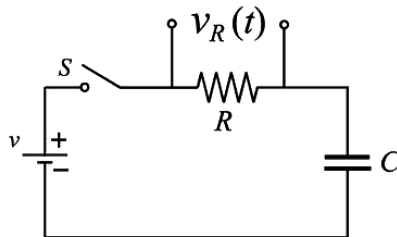
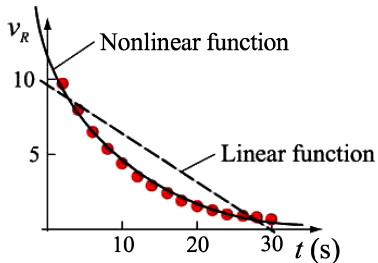
$$a_1 = \frac{nS_{xy} - S_x S_y}{nS_{xx} - (S_x)^2} \qquad a_0 = \frac{S_{xx} S_y - S_{xy} S_x}{nS_{xx} - (S_x)^2}$$

5. Plot the data points and the linear function.

# Curve Fitting with Nonlinear Equation

# Curve fitting with nonlinear equation

- Many situations in science and engineering show that the relationship between the quantities that are being considered is **not linear**.
- For example, the data points measured in RC circuit.



- It is obvious from the plot that curve fitting the data points with a **nonlinear function gives a much better fit** than curve fitting with a linear function.

# Curve fitting with nonlinear equation

- There are many **kinds of nonlinear functions** which can be used with linear-squares regression method to determine the coefficients that gives the best fit. For examples

$$y = bx^m \quad (\text{power function}) \quad (7)$$

$$y = be^{mx} \text{ or } y = b10^{mx} \quad (\text{exponential function}) \quad (8)$$

$$y = \frac{1}{mx + b} \quad (\text{reciprocal function}) \quad (9)$$

- In order to be able to use linear regression, the form of a nonlinear equation of two variables is **changed such that the new form is linear** with terms that contain the original variables.
- For example, the power function  $y = bx^m$  can be put into **linear form by taking the natural logarithm (ln)** of both sides:

$$\ln(y) = \ln(bx^m) = m \ln(x) + \ln(b)$$

# Writing a nonlinear equation in linear form

- The equation is linear for  $\ln(y)$  in terms  $\ln(x)$ .
- The equation is in the form

$$\begin{array}{ccccccc} \ln(y) & = & m \ln(x) & + & \ln(b) \\ \underbrace{\hspace{1.5cm}} & & \underbrace{\hspace{1cm}} & & \underbrace{\hspace{1cm}} \\ \underbrace{\hspace{1cm}} & & \underbrace{\hspace{0.5cm}} & & \underbrace{\hspace{0.5cm}} \\ Y & = & a_1 X & + & a_0 \end{array}$$

- This means that linear least-squares regression can be used for curve fitting an equation of the form  $y = bx^m$  to a set of data points  $(x_i, y_i)$ .
- Once  $a_1$  and  $a_0$  are known, the constants  $b$  and  $m$  in the exponential equation are calculated by:

$$m = a_1 \quad \text{and} \quad b = e^{a_0}$$

# Transforming nonlinear equations to linear form

Nonlinear equation	Linear form	Relationship to $Y = a_1X + a_0$	Values for least-squares regression	Plot where data points appear to fit a straight line
$y = bx^m$	$\ln(y) = m\ln(x) + \ln(b)$	$Y = \ln(y), X = \ln(x)$ $a_1 = m, a_0 = \ln(b)$	$\ln(x_i)$ and $\ln(y_i)$	$y$ vs. $x$ plot on logarithmic $y$ and $x$ axes. $\ln(y)$ vs. $\ln(x)$ plot on linear $x$ and $y$ axes.
$y = be^{mx}$	$\ln(y) = mx + \ln(b)$	$Y = \ln(y), X = x$ $a_1 = m, a_0 = \ln(b)$	$x_i$ and $\ln(y_i)$	$y$ vs. $x$ plot on logarithmic $y$ and linear $x$ axes. $\ln(y)$ vs. $x$ plot on linear $x$ and $y$ axes.
$y = b10^{mx}$	$\log(y) = mx + \log(b)$	$Y = \log(y), X = x$ $a_1 = m, a_0 = \log(b)$	$x_i$ and $\log(y_i)$	$y$ vs. $x$ plot on logarithmic $y$ and linear $x$ axes. $\log(y)$ vs. $x$ plot on linear $x$ and $y$ axes.
$y = \frac{1}{mx + b}$	$\frac{1}{y} = mx + b$	$Y = \frac{1}{y}, X = x$ $a_1 = m, a_0 = b$	$x_i$ and $1/y_i$	$1/y$ vs. $x$ plot on linear $x$ and $y$ axes.
$y = \frac{mx}{b + x}$	$\frac{1}{y} = \frac{b}{mx} + \frac{1}{m}$	$Y = \frac{1}{y}, X = \frac{1}{x}$ $a_1 = \frac{b}{m}, a_0 = \frac{1}{m}$	$1/x_i$ and $1/y_i$	$1/y$ vs. $1/x$ plot on linear $x$ and $y$ axes.

# Example

**Question:** Use the least-squares method and determine the exponential fit  $y = Ce^{Ax}$  for the five data points (0, 1.5), (1, 2.5), (2, 3.5), (3, 5.0), and (4, 7.5).

# Choose an appropriate nonlinear function for curve fitting

- A plot of the given data points can give an intuitive relationship between the quantities whether the relationship is linear or nonlinear.
- Prior knowledge from a guiding theory of the physical phenomena and the form of the mathematical equation associated with the data points.
- Other fundamental concepts can be used
  - Exponential functions cannot pass through the origin.
  - Exponential functions can only fit data with all positive  $y$ s, or all negative  $y$ s.
  - Logarithmic functions cannot include  $x = 0$  or negative values of  $x$ .
  - For power function  $y = 0$  when  $x = 0$ .
  - The reciprocal equation cannot include  $y = 0$ .



# Example

**Question:** Students collected the experimental data points  $(t,d)$  at different instance of time as  $(0.200,0.1960)$ ,  $(0.400,0.7850)$ ,  $(0.600,1.7665)$ ,  $(0.8,3.1405)$ , and  $(1,4.9075)$ . The relation is  $d = \frac{1}{2}gt^2$ , where  $d$  is distance in meters and  $t$  is time in seconds. Find the gravitational constant  $g$ .

## Curve fitting with quadratic and higher order polynomials

# Curve fitting with quadratic and higher order polynomials

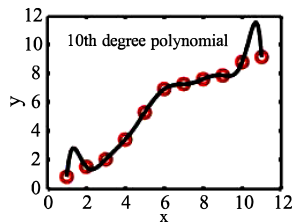
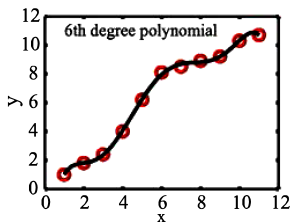
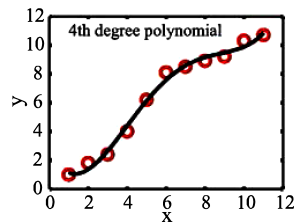
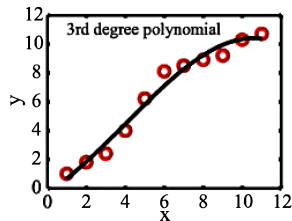
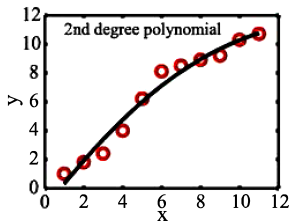
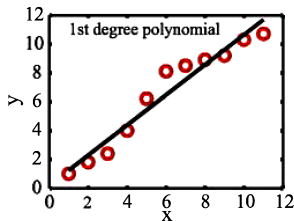
- Polynomials are functions that have the form

$$f(x) = a_m x^m + a_{m-1} x^{m-1} + \cdots + a_0.$$

The coefficients  $a_m, a_{m-1}, \dots, a_1, a_0$  are real numbers and  $m$  is a non-negative integer called **degree or order** of the polynomial.

- A plot of the polynomial is a curve. A first-order polynomial is a **linear function**, and its plot is a **straight line**. Higher-order polynomials are **nonlinear functions**, and their plots are **curves**.
- A **quadratic (second-order) polynomial** is a curve that is either concave up or down (parabola).
- A **third-order polynomial** has an inflection point such that the curve can be concave up (or down) in one region, and concave down (or up) in another.

# Curve fitting with polynomials of different order



# Curve fitting with quadratic and higher order polynomials

- A given set of  $n$  data points can be curve-fit with polynomials of different order up to an order of  $(n - 1)$ .
- The coefficients of a polynomial can be determined such that the polynomial best fits the data by minimizing the error in a least squares sense.
- For  $n$  points, the polynomial that passes through all of the points is one of order  $(n - 1)$ .

# Polynomial regression

- **Polynomial regression** is a procedure for determining the coefficients of a polynomial of a second degree, or higher, such that the polynomial best fits (minimizing the total error) a given set of data points.
- If the polynomial of order  $m$ , that is used for curve fitting is

$$f(x) = a_m x^m + a_{m-1} x^{m-1} + \dots + a_1 x + a_0.$$

- Then, for a given set of  $n$  data points  $\{(x_i, y_i)\}_{i=1}^n$  ( $m$  is smaller than  $n - 1$ ), the total error is given by

$$E = \sum_{i=1}^n \left[ y_i - (a_m x_i^m + a_{m-1} x_i^{m-1} + \dots + a_1 x_i + a_0) \right]^2$$

- The **function  $E$  has a minimum** at the values of  $a_0$  through  $a_m$ , where the **partial derivatives** of  $E$  with respect to each of the variables is **equal to zero**.

# Polynomial regression

- For the simplicity, let us consider the case of  $m = 2$  (Quadratic polynomial)

$$E = \sum_{i=1}^n [y_i - (a_2 x_i^2 + a_1 x_i + a_0)]^2$$

- Taking the partial derivatives with respect to  $a_0$ ,  $a_1$ , and  $a_2$ , and setting them equal to zero gives:

$$\frac{\partial E}{\partial a_0} = -2 \sum_{i=1}^n (y_i - a_2 x_i^2 - a_1 x_i - a_0) = 0 \quad (10)$$

$$\frac{\partial E}{\partial a_1} = -2 \sum_{i=1}^n (y_i - a_2 x_i^2 - a_1 x_i - a_0) x_i = 0 \quad (11)$$

$$\frac{\partial E}{\partial a_2} = -2 \sum_{i=1}^n (y_i - a_2 x_i^2 - a_1 x_i - a_0) x_i^2 = 0 \quad (12)$$

# Polynomial regression

$$\begin{aligned} na_0 + \left( \sum_{i=1}^n x_i \right) a_1 + \left( \sum_{i=1}^n x_i^2 \right) a_2 &= \sum_{i=1}^n y_i \\ \left( \sum_{i=1}^n x_i \right) a_0 + \left( \sum_{i=1}^n x_i^2 \right) a_1 + \left( \sum_{i=1}^n x_i^3 \right) a_2 &= \sum_{i=1}^n x_i y_i \\ \left( \sum_{i=1}^n x_i^2 \right) a_0 + \left( \sum_{i=1}^n x_i^3 \right) a_1 + \left( \sum_{i=1}^n x_i^4 \right) a_2 &= \sum_{i=1}^n x_i^2 y_i \end{aligned} \quad (13)$$

- The solution of the system of equations gives the values of the coefficients  $a_0$ ,  $a_1$ , and  $a_2$  of the polynomial  $y = a_2x_i^2 + a_1x_i + a_0$  that best fits then data points  $\{(x_i, y_i)\}_{i=1}^n$ .
- The coefficients for higher-order polynomials are derived in the same way.



# Examples

**Example:** Find the least-squares parabola for the four points  $(-3, 3)$ ,  $(0, 1)$ ,  $(2, 1)$ , and  $(4, 3)$ .

# Polynomial of higher order




- A polynomial of the fourth order can be written as

$$f(x) = a_4x^4 + a_3x^3 + a_2x^2 + a_1x + a_0$$

- The values of the five coefficients  $a_0$ ,  $a_1$ ,  $a_2$ ,  $a_3$ , and  $a_4$  are obtained by solving a system of five linear equations.

$$\begin{aligned} na_0 + \left(\sum_{i=1}^n x_i^1\right) a_1 + \left(\sum_{i=1}^n x_i^2\right) a_2 + \left(\sum_{i=1}^n x_i^3\right) a_3 + \left(\sum_{i=1}^n x_i^4\right) a_4 &= \sum_{i=1}^n x_i y_i \\ \left(\sum_{i=1}^n x_i\right) a_0 + \left(\sum_{i=1}^n x_i^2\right) a_1 + \left(\sum_{i=1}^n x_i^3\right) a_2 + \left(\sum_{i=1}^n x_i^4\right) a_3 + \left(\sum_{i=1}^n x_i^5\right) a_4 &= \sum_{i=1}^n x_i^2 y_i \\ \left(\sum_{i=1}^n x_i^2\right) a_0 + \left(\sum_{i=1}^n x_i^3\right) a_1 + \left(\sum_{i=1}^n x_i^4\right) a_2 + \left(\sum_{i=1}^n x_i^5\right) a_3 + \left(\sum_{i=1}^n x_i^6\right) a_4 &= \sum_{i=1}^n x_i^3 y_i \\ \left(\sum_{i=1}^n x_i^3\right) a_0 + \left(\sum_{i=1}^n x_i^4\right) a_1 + \left(\sum_{i=1}^n x_i^5\right) a_2 + \left(\sum_{i=1}^n x_i^6\right) a_3 + \left(\sum_{i=1}^n x_i^7\right) a_4 &= \sum_{i=1}^n x_i^4 y_i \\ \left(\sum_{i=1}^n x_i^4\right) a_0 + \left(\sum_{i=1}^n x_i^5\right) a_1 + \left(\sum_{i=1}^n x_i^6\right) a_2 + \left(\sum_{i=1}^n x_i^7\right) a_3 + \left(\sum_{i=1}^n x_i^8\right) a_4 &= \sum_{i=1}^n x_i^5 y_i \end{aligned}$$

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-  Numerical Methods for Engineers and Scientists An Introduction with Applications using  
MATLAB, Third Edition, Amos Gilat and Vish Subramaniam, John Wiley & Sons



*Thank you!*