VIP Cheatsheet: Unsupervised Learning

Afshine Amidi and Shervine Amidi

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Introduction to Unsupervised Learning

□ Motivation – The goal of unsupervised learning is to find hidden patterns in unlabeled data $\{x^{(1)},...,x^{(m)}\}.$

 \square Jensen's inequality – Let f be a convex function and X a random variable. We have the following inequality:

$$E[f(X)] \geqslant f(E[X])$$

Expectation-Maximization

 \Box Latent variables – Latent variables are hidden/unobserved variables that make estimation problems difficult, and are often denoted z. Here are the most common settings where there are latent variables:

	Setting	Latent variable z	x z	Comments
	Mixture of k Gaussians	$Multinomial(\phi)$	$\mathcal{N}(\mu_j, \Sigma_j)$	$\mu_j \in \mathbb{R}^n, \phi \in \mathbb{R}^k$
l	Factor analysis	$\mathcal{N}(0,I)$	$\mathcal{N}(\mu + \Lambda z, \psi)$	$\mu_j \in \mathbb{R}^n$

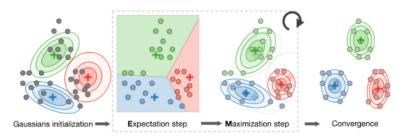
 \square Algorithm – The Expectation-Maximization (EM) algorithm gives an efficient method at estimating the parameter θ through maximum likelihood estimation by repeatedly constructing a lower-bound on the likelihood (E-step) and optimizing that lower bound (M-step) as follows:

• E-step: Evaluate the posterior probability $Q_i(z^{(i)})$ that each data point $x^{(i)}$ came from a particular cluster $z^{(i)}$ as follows:

$$Q_i(z^{(i)}) = P(z^{(i)}|x^{(i)};\theta)$$

• M-step: Use the posterior probabilities $Q_i(z^{(i)})$ as cluster specific weights on data points $\overline{x^{(i)}}$ to separately re-estimate each cluster model as follows:

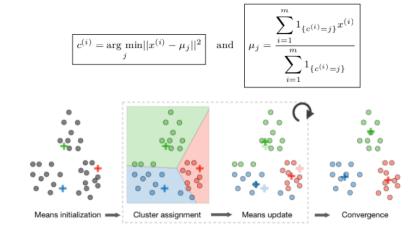
$$\theta_i = \underset{\theta}{\operatorname{argmax}} \ \sum_i \int_{z^{(i)}} Q_i(z^{(i)}) \log \left(\frac{P(x^{(i)}, z^{(i)}; \theta)}{Q_i(z^{(i)})} \right) dz^{(i)}$$



k-means clustering

We note $c^{(i)}$ the cluster of data point i and μ_i the center of cluster j.

 \square Algorithm – After randomly initializing the cluster centroids $\mu_1, \mu_2, ..., \mu_k \in \mathbb{R}^n$, the k-means algorithm repeats the following step until convergence:



 \square Distortion function – In order to see if the algorithm converges, we look at the distortion function defined as follows:

$$J(c,\mu) = \sum_{i=1}^{m} ||x^{(i)} - \mu_{c^{(i)}}||^2$$

Hierarchical clustering

 \square Algorithm – It is a clustering algorithm with an agglomerative hierarchical approach that build nested clusters in a successive manner.

 \square Types – There are different sorts of hierarchical clustering algorithms that aims at optimizing different objective functions, which is summed up in the table below:

Ward linkage	Average linkage	Complete linkage	
$\begin{array}{c} {\rm Minimize~within~cluster} \\ {\rm distance} \end{array}$	Minimize average distance between cluster pairs	Minimize maximum distance of between cluster pairs	

Clustering assessment metrics

In an unsupervised learning setting, it is often hard to assess the performance of a model since we don't have the ground truth labels as was the case in the supervised learning setting.

 \Box Silhouette coefficient – By noting a and b the mean distance between a sample and all other points in the same class, and between a sample and all other points in the next nearest cluster, the silhouette coefficient s for a single sample is defined as follows:

$$s = \frac{b - a}{\max(a, b)}$$

 \Box Calinski-Harabaz index – By noting k the number of clusters, B_k and W_k the between and within-clustering dispersion matrices respectively defined as

$$B_k = \sum_{j=1}^k n_{c^{(i)}} (\mu_{c^{(i)}} - \mu) (\mu_{c^{(i)}} - \mu)^T, \qquad W_k = \sum_{i=1}^m (x^{(i)} - \mu_{c^{(i)}}) (x^{(i)} - \mu_{c^{(i)}})^T$$

the Calinski-Harabaz index s(k) indicates how well a clustering model defines its clusters, such that the higher the score, the more dense and well separated the clusters are. It is defined as follows:

$$s(k) = \frac{\operatorname{Tr}(B_k)}{\operatorname{Tr}(W_k)} \times \frac{N-k}{k-1}$$

Principal component analysis

It is a dimension reduction technique that finds the variance maximizing directions onto which to project the data.

□ Eigenvalue, eigenvector – Given a matrix $A \in \mathbb{R}^{n \times n}$, λ is said to be an eigenvalue of A if there exists a vector $z \in \mathbb{R}^n \setminus \{0\}$, called eigenvector, such that we have:

$$Az = \lambda z$$

□ Spectral theorem – Let $A \in \mathbb{R}^{n \times n}$. If A is symmetric, then A is diagonalizable by a real orthogonal matrix $U \in \mathbb{R}^{n \times n}$. By noting $\Lambda = \operatorname{diag}(\lambda_1, ..., \lambda_n)$, we have:

$$\exists \Lambda \text{ diagonal}, \quad A = U \Lambda U^T$$

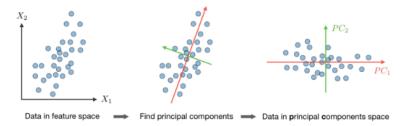
Remark: the eigenvector associated with the largest eigenvalue is called principal eigenvector of matrix A.

 \square Algorithm – The Principal Component Analysis (PCA) procedure is a dimension reduction technique that projects the data on k dimensions by maximizing the variance of the data as follows:

• Step 1: Normalize the data to have a mean of 0 and standard deviation of 1.

$$\boxed{x_j^{(i)} \leftarrow \frac{x_j^{(i)} - \mu_j}{\sigma_j}} \quad \text{where} \quad \boxed{\mu_j = \frac{1}{m} \sum_{i=1}^m x_j^{(i)}} \quad \text{and} \quad \boxed{\sigma_j^2 = \frac{1}{m} \sum_{i=1}^m (x_j^{(i)} - \mu_j)^2}$$

- Step 2: Compute $\Sigma = \frac{1}{m} \sum_{i=1}^{m} x^{(i)} x^{(i)^T} \in \mathbb{R}^{n \times n}$, which is symmetric with real eigenvalues.
- Step 3: Compute $u_1, ..., u_k \in \mathbb{R}^n$ the k orthogonal principal eigenvectors of Σ , i.e. the orthogonal eigenvectors of the k largest eigenvalues.
- Step 4: Project the data on span_R(u₁,...,u_k). This procedure maximizes the variance among all k-dimensional spaces.



Independent component analysis

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It is a technique meant to find the underlying generating sources.

□ **Assumptions** – We assume that our data x has been generated by the n-dimensional source vector $s = (s_1, ..., s_n)$, where s_i are independent random variables, via a mixing and non-singular matrix A as follows:

$$x = As$$

The goal is to find the unmixing matrix $W = A^{-1}$ by an update rule.

 \square Bell and Sejnowski ICA algorithm – This algorithm finds the unmixing matrix W by following the steps below:

• Write the probability of $x = As = W^{-1}s$ as:

$$p(x) = \prod_{i=1}^{n} p_s(w_i^T x) \cdot |W|$$

• Write the log likelihood given our training data $\{x^{(i)}, i \in [\![1,m]\!]\}$ and by noting g the sigmoid function as:

$$l(W) = \sum_{i=1}^{m} \left(\sum_{j=1}^{n} \log \left(g'(w_{j}^{T} x^{(i)}) \right) + \log |W| \right)$$

Therefore, the stochastic gradient ascent learning rule is such that for each training example $x^{(i)}$, we update W as follows:

$$W \longleftarrow W + \alpha \begin{pmatrix} \begin{pmatrix} 1 - 2g(w_1^T x^{(i)}) \\ 1 - 2g(w_2^T x^{(i)}) \\ \vdots \\ 1 - 2g(w_n^T x^{(i)}) \end{pmatrix} x^{(i)^T} + (W^T)^{-1} \end{pmatrix}$$