main code

November 14, 2024

```
[]: # from google.colab import drive
     # drive.mount('/content/drive')
     # !cp /content/drive/MyDrive/CA4/*.py .
     # !cp -r /content/drive/MyDrive/CA4/conf .
[]: !pip install hydra-core --no-binary :all:
     !pip install wandb
[]: %load_ext autoreload
     %autoreload 2
     from train import run
     import os
     import os.path as osp
     from hydra import initialize, initialize config module, initialize config dir,
      compose
     from omegaconf import OmegaConf
[]: with initialize(version_base=None, config_path="conf"):
         cfg = compose(config_name="config")
         print(cfg)
         data_root = cfg.data.data_root
         if not osp.exists(data_root):
             os.makedirs(data_root, exist_ok=True)
             data_root_father = osp.dirname(data_root)
             | wget https://www.cis.upenn.edu/~jshi/ped_html/PennFudanPed.zip -O__

⟨data_root_father⟩/data.zip

             !unzip {data_root_father}/data.zip -d {data_root_father}
[]: # wandb
     import wandb
     wandb.login()
```

1 Define a sweep

```
[]: sweep_configuration = {
         "name": "sweep-hyperparams",
         "method": "bayes",
         "metric": {"goal": "maximize", "name": "epoch_val_dice_score"},
         "parameters": {
             "learning_rate": {
                 "values": [1e-4, 1e-5],
             },
             "batch_size": {"values": [8, 16, 32]},
             "epochs": {"values": [30, 120, 300]},
             "img_size": {
                 "values": [64, 128],
             },
         },
     }
     # sweep_id = wandb.sweep(sweep=sweep_configuration,_
      ⇒project="pedestrian-detection")
     sweep_id = "bp8sw90v"
     print(sweep_id)
```

2 Sweep run

```
[]: wandb.agent(sweep_id, function=sweep_train, project="pedestrian-detection")
```