Rigidity expander graphs

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Abstract

Jordán and Tanigawa recently introduced the d-dimensional algebraic connectivity $a_d(G)$ of a graph G. This is a quantitative measure of the d-dimensional rigidity of G which generalizes the well-studied notion of spectral expansion of graphs. We present a new lower bound for $a_d(G)$ defined in terms of the spectral expansion of certain subgraphs of G associated with a partition of its vertices into d parts. In particular, we obtain a new sufficient condition for the rigidity of a graph G. As a first application, we prove the existence of an infinite family of k-regular d-rigidity-expander graphs for every $d \geq 2$ and $k \geq 2d+1$. Conjecturally, no such family of 2d-regular graphs exists. Second, we show that $a_d(K_n) \geq \frac{1}{2} \left \lfloor \frac{n}{d} \right \rfloor$, which we conjecture to be essentially tight. In addition, we study the extremal values $a_d(G)$ attained if G is a minimally d-rigid graph.

1 Introduction

Graph expansion is one of the most influential concepts in modern graph theory, with numerous applications in discrete mathematics and computer science (see [13, 18]). Intuitively speaking, an expander is a "highly-connected" graph, and a standard way to quantitatively measure the connectivity, or expansion, of a graph uses the spectral gap in its Laplacian matrix. A main theme in the study of expander graphs deals with the construction of sparse expanders. In particular, bounded-degree regular expander graphs have been studied extensively in various areas of mathematics [8, 19, 23, 7, 20]. This paper studies a generalization of spectral graph expansion that was

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recently introduced by Jordán and Tanigawa via the theory of graph rigidity [14].

A d-dimensional framework is a pair (G, p) consisting of a graph G = (V, E) and a map $p : V \to \mathbb{R}^d$. The framework is called d-rigid if every continuous motion of the vertices starting from p that preserves the distance between every two adjacent vertices in G, also preserves the distance between every pair of vertices; see e.g. [4, 9] for background on framework rigidity.

Asimow and Roth showed in [1] that if the map p is generic (e.g. if the d|V| coordinates of p are algebraically independent over the rationals), then the framework rigidity of (G,p) does not depend on the map p. Moreover, they showed that for a generic p, rigidity coincides with the following stronger linear-algebraic notion of infinitesimal rigidity.

For every $u, v \in V$ we define $d_{uv} \in \mathbb{R}^d$ by

$$d_{uv} = \begin{cases} \frac{p(u) - p(v)}{\|p(u) - p(v)\|} & \text{if } p(u) \neq p(v), \\ 0 & \text{otherwise,} \end{cases}$$

and $\mathbf{v}_{u,v} := (1_u - 1_v) \otimes d_{uv} \in \mathbb{R}^{d|V|}$, where $\{1_u\}_{u \in V}$ is the standard basis of $\mathbb{R}^{|V|}$ and \otimes denotes the Kronecker product. Equivalently,

$$\mathbf{v}_{u,v}^T = \begin{pmatrix} 0 & \dots & 0 & d_{uv}^T & 0 & \dots & 0 & d_{vu}^T & 0 & \dots & 0 \end{pmatrix}.$$

The (normalized) rigidity matrix $R(G,p) \in \mathbb{R}^{d|V|\times|E|}$ is the matrix whose columns are the vectors $\mathbf{v}_{u,v}$ for all $\{u,v\} \in E$. We always assume that the image p(V) does not lie on any affine hyperplane in \mathbb{R}^d . In such a case, it is possible to show (see [1]) that $\operatorname{rank}(R(G,p)) \leq d|V| - \binom{d+1}{2}$. The framework (G,p) is called infinitesimally rigid if this bound is attained, that is, if $\operatorname{rank}(R(G,p)) = d|V| - \binom{d+1}{2}$.

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A graph G is called rigid in \mathbb{R}^d , or d-rigid, if it is infinitesimally rigid with respect to some map p (or, equivalently, if it is infinitesimally rigid for all generic maps [1]).

For d = 1 and an injective map $p : V \to \mathbb{R}^d$, the rigidity matrix R(G, p) is equal to the incidence matrix of G, hence both notions of rigidity coincide with graph connectivity. One can extend this analogy and define a higher dimensional version of the graph's Laplacian matrix, that is called the *stiffness matrix* of (G, p), and is defined by

$$L(G, p) = R(G, p)R(G, p)^T \in \mathbb{R}^{d|V| \times d|V|}$$

We denote by $\lambda_i(A)$ the *i*-th smallest eigenvalue of a symmetric matrix A. Since $\operatorname{rank}(L(G,p)) = \operatorname{rank}(R(G,p)) \leq d|V| - \binom{d+1}{2}$, the kernel of L(G,p) is of dimension at least $\binom{d+1}{2}$. Therefore, $\lambda_{\binom{d+1}{2}+1}(L(G,p)) \neq 0$ if and only if (G,p) is infinitesimally rigid.

In [14], Jordán and Tanigawa defined the d-dimensional algebraic connectivity of G, $a_d(G)$, as

$$a_d(G) = \sup \left\{ \lambda_{\binom{d+1}{2}+1}(L(G,p)) \middle| p: V \to \mathbb{R}^d \right\}.$$

For d=1, L(G,p) coincides with the graph Laplacian matrix L(G), and $a_1(G)=a(G)$ is the usual algebraic connectivity, or Laplacian spectral gap, of G, introduced by Fiedler in [6]. For every $d \geq 1$, $a_d(G) \geq 0$ since L(G,p) is positive semi-definite, and $a_d(G) > 0$ if and only if G is d-rigid.

The following notion of rigidity expander graphs extends the classical notion of (spectral) expander graphs, corresponding to the d = 1 case:

Definition 1.1. Let $d \geq 1$. A family of graphs $\{G_i\}_{i \in \mathbb{N}}$ of increasing size is called a *family of d-rigidity expander graphs* if there exists $\epsilon > 0$ such that $a_d(G_i) \geq \epsilon$ for all $i \in \mathbb{N}$.

It is well known that, for every $k \geq 3$, there exist families of k-regular (1-dimensional) expander graphs (see e.g. [13]). Our main result is an extension of this fact to general d:

Theorem 1.2. Let $d \ge 1$ and $k \ge 2d + 1$. Then, there exists an infinite family of k-regular d-rigidity expander graphs.

It was conjectured by Jordán and Tanigawa that families of 2d-regular d-rigidity expanders do not exist (see [14, Conj. 2] for the statement in the d=2 case, and see [16, Conj. 6.2] for the general case), and clearly families of k-regular d-rigidity expanders do not exist for k < 2d since, for n large enough, such graphs have less than $dn - {d+1 \choose 2}$ edges, and are therefore not even d-rigid. Therefore, assuming this conjecture, our result is sharp.

Our main tool for the proof of Theorem 1.2 is a new lower bound on $a_d(G)$, given in terms of the (1-dimensional) algebraic connectivity of certain subgraphs of G associated with a partition of its vertex set into d parts. For convenience, we let $a(G) = \infty$ if G consists of a single vertex.

Let G = (V, E) be a graph, and let $A, B \subset V$ be two disjoint sets. We denote by G[A] the subgraph of G induced on A, and by G(A, B) the subgraph of G with vertex set $A \cup B$ and edge set $E(A, B) = \{e \in E : |e \cap A| = |e \cap B| = 1\}$. In addition, we say that a partition $V = A_1 \cup \cdots \cup A_d$ is non-trivial if $A_i \neq \emptyset$ for all $i = 1, \ldots, d$.

Theorem 1.3. Let $d \geq 2$. For every graph G = (V, E) and a non-trivial partition $V = A_1 \cup \cdots \cup A_d$ there holds

$$a_d(G) \ge \min\left(\left\{a(G[A_i])\right\}_{1 \le i \le d} \bigcup \left\{\frac{1}{2}a(G(A_i, A_j))\right\}_{1 \le i < j \le d}\right).$$

In particular, if $G[A_i]$ is connected for all $i \in [d]$ and $G(A_i, A_j)$ is connected for all $1 \le i < j \le d$, then G is d-rigid.

Remark 1.4. In the d=2 dimensional case, the statement in Theorem 1.3 can be slightly improved (by removing the constant 1/2) to

$$a_2(G) \ge \min\{a(G[A_1]), a(G[A_2]), a(G(A_1, A_2))\},\$$

for every non-trivial partition A_1, A_2 of V.

In the case d=2, we can think of Theorem 1.3 as a quantitative version of (a special case of) a theorem of Crapo [5, Theorem 7]. For $d \geq 3$, Theorem 1.3 seems to give, in addition to a lower bound on $a_d(G)$, a new sufficient condition for d-rigidity, which we believe to be of independent interest (this sufficient condition could also be derived from [17, Theorem 5.5]).

To derive Theorem 1.2 from Theorem 1.3 we consider a balanced partition of the vertex set, and construct each of the $\binom{d+1}{2}$ subgraphs induced by the partition in separate. In the main case k=2d+1, our "building blocks" are (1-dimensional) expander graphs with maximum degree 3 and a large proportion of vertices of degree 2. Such graphs are constructed by subdividing edges in classical constructions of 3-regular expander graphs. In Theorem 4.1 below, we hedge the effect of edge subdivision on the algebraic connectivity of the graph.

For another application of Theorem 1.3, we derive a slight improvement of the previously known lower bound for $a_d(K_n)$ from [16, Theorem 1.5].

Corollary 1.5. Let $d \geq 3$ and $n \geq d+1$. Then

$$a_d(K_n) \ge \frac{1}{2} \left| \frac{n}{d} \right|.$$

In addition, we establish the following upper bound on $a_d(G)$, generalizing the case d=2 proved by Jordán and Tanigawa in [14, Theorem 4.2].

Theorem 1.6. Let $d \geq 2$, and let G be a graph. Then,

$$a_d(G) < a(G)$$
.

Theorem 1.6 was proved recently and independently in [22]. Our proof is different, using the probabilistic method, and we believe it to be of independent interest.

Finally, we study how small and how large can $a_d(G)$ be provided that G is a minimally d-rigid graph. A graph G is called *minimally* d-rigid if it is d-rigid, but $G \setminus e$ is not d-rigid for every edge $e \in E$. For d = 1, these are exactly spanning trees. This question is related to the aforementioned conjecture that no 2d-regular d-rigidity expanders exist (see Conjecture 8.2).

Among the minimally d-rigid graphs, $a_d(G)$ is maximized by a d-analog of the star graph. For every $d \geq 1$ and $n \geq d + 1$, let $S_{n,d}$ be the graph consisting of a clique of size d, and n - d additional vertices, each adjacent to all of the vertices of the clique, and not adjacent to any other vertex. It is easy to check that $S_{n,d}$ is minimally d-rigid.

Theorem 1.7. For every $d \ge 1$ and $T \ne K_2, K_3$ a minimally d-rigid graph there holds

$$a_d(T) < 1$$
,

and equality holds if $T = S_{n,d}$.

This extends a result of Fiedler (see [6, 4.1], more explicitly stated by Merris in [21, Cor. 2]) corresponding to the case d = 1. Note that for $T = K_2$ (which is a minimally 1-rigid graph), we have $a_1(K_2) = 2$, and for $T = K_3$ (which is a minimally 2-rigid graph), we have $a_2(K_3) = \frac{3}{2}$ (see [14, Theorem 4.4]).

Considering the other extreme, of minimizers of a_d among all n-vertex d-rigid graphs, it was shown by Fiedler in [6] that $a(G) \geq a(P_n) = 2(1 - \cos(\pi/n))$ for every connected graph G, where P_n is the n-vertex path (see [11] for an explicit statement). We conjecture that a similar situation holds in higher dimensions: in Subsection 7.1 we define generalized path graphs $P_{n,d}$, which are certain n-vertex minimally d-rigid graphs, and provide in Proposition 7.6 bounds on their d-dimensional algebraic connectivity implying that $a_d(P_{n,d}) = \Theta_d(1/n^2)$. We conjecture that these graphs are extremal:

Conjecture 1.8. Let G be a d-rigid graph on n vertices. Then,

$$a_d(G) \geq a_d(P_{n,d}).$$

The paper is organized as follows: In Section 2 we present some results about stiffness matrices that are used later. In particular, we recall the definition of the lower stiffness matrix $L^-(G,p)$ introduced in [16]. In Section 3 we prove Theorem 1.3. In Section 4 we study the effects of edge subdivisions on the spectral gap of a graph. Section 5 contains the proof of our main result, Theorem 1.2, showing the existence of k-regular d-rigidity expanders for $k \geq 2d+1$. In Section 6 we give a proof of the upper bound $a_d(G) \leq a(G)$ (Theorem 1.6). In Section 7 we study the d-dimensional algebraic connectivity of minimally d-rigid graphs. We conclude in Section 8 with several open problems and directions for further research.

2 Preliminaries

Occasionally, it is simpler to work with the *lower stiffness matrix* of the framework (G, p), defined by

$$L^{-}(G, p) = R(G, p)^{T} R(G, p) \in \mathbb{R}^{|E| \times |E|}.$$

By standard linear algebra, we have that $\operatorname{rank}(L(G,p)) = \operatorname{rank}(L^{-}(G,p)) = \operatorname{rank}(R(G,p))$ and that the non-zero eigenvalues of L(G,p), with multiplicities, coincide with those of $L^{-}(G,p)$. In particular, assuming that

$$|E| \ge d|V| - {d+1 \choose 2}$$
, we have

$$\lambda_k(L(G,p)) = \lambda_{|E|-d|V|+k}(L^-(G,p)),\tag{1}$$

for every $k \ge {d+1 \choose 2} + 1$. In addition, the entries of $L^-(G, p)$ are given explicitly by the following lemma.

Lemma 2.1 ([16, Lemma 2.1]). Let (G, p) be a d-dimensional framework. Then, for every $e, e' \in E(G)$,

$$L^{-}(G, p)_{e,e'} = \begin{cases} 2 & \text{if } e = e' = \{u, v\} \text{ and } p(u) \neq p(v), \\ d_{uv} \cdot d_{uw} & \text{if } e = \{u, v\}, \ e' = \{u, w\} \\ 0 & \text{otherwise,} \end{cases}$$

where $d_{uv} \cdot d_{uw}$ denotes the dot product. In the case that $e = \{u, v\}$ and $e' = \{u, w\}$, we denote by $\theta(e, e')$ the angle between d_{uv} and d_{uw} . Hence, $L^-(G, p)_{e,e'} = \cos(\theta(e, e'))$ (by convention, $\cos(\theta(e, e')) = 0$ if $d_{uv} = 0$ or $d_{uw} = 0$).

3 A lower bound on $a_d(G)$

We turn to the proof of Theorem 1.3, starting with the following very simple lemma about the eigenvalues of a block diagonal matrix.

For convenience, given a " 0×0 " matrix M, we define $\lambda_1(M) = \infty$.

Lemma 3.1. Let $M \in \mathbb{R}^{n \times n}$ be a block diagonal matrix, with blocks M_1, \ldots, M_k , where $M_i \in \mathbb{R}^{n_i \times n_i}$ is symmetric for every $1 \leq i \leq k$. Then, for every $1 \leq m \leq n$ and r_1, \ldots, r_k satisfying $m = 1 - k + \sum_{i=1}^k r_i$ there holds

$$\lambda_m(M) \ge \min\{\lambda_{r_i}(M_i) : 1 \le i \le k\}.$$

$$Proof.$$
 TOPROVE 0

Remark 3.2. Note that, under the convention $\lambda_1(M_i) = \infty$ for $M_i \in \mathbb{R}^{0 \times 0}$, Lemma 3.1 holds also if we allow values $n_i = 0$ and $r_i = 1$ for one or more $i \in [k]$.

To derive the stronger bound in the case d=2 mentioned in Remark 1.4, we note that in this case L^- itself is a block diagonal matrix with 3 blocks which are the 1-dimensional lower stiffness matrices $L^-(G[A_1], q_1)$, $L^-(G[A_2], q_2)$ and $L^-(G(A_1, A_2), q_{12})$ (that is, there is no need for the "correction" term Q). Therefore, by the same reasoning we applied to M in the general case, we find that

$$a_2(G) \ge \lambda_m(L^-) \ge \min(\{a_2(G[A_1]), a_2(G[A_2]), a_2(G(A_1, A_2))\}),$$

where $m = |E| - 2|V| + {2+1 \choose 2} + 1.$

Remark 3.3. The criterion for d-rigidity given by Theorem 1.3 is minimal in terms of the edge count. Namely, the assumption that all the $\binom{d+1}{2}$ graphs in the partition are connected implies that there are at least $|A_i| - 1$ edges in $G[A_i]$ for $i \in [d]$, and at least $|A_i| + |A_j| - 1$ edges in $G(A_i, A_j)$, for $1 \le i < j \le d$. In total, there needs be at least

$$\sum_{i=1}^{d} (|A_i| - 1) + \sum_{1 \le i < j \le d} (|A_i| + |A_j| - 1) = d|V| - \binom{d+1}{2}$$

edges in G — precisely the number of edges in a minimally d-rigid graph.

As a consequence of Theorem 1.3, we obtain a simple proof of Corollary 1.5, giving a lower bound on the d-dimensional algebraic connectivity of K_n .

Remark 3.4. For d=2, it was shown by Jordán and Tanigawa in [14], relying on a result by Zhu ([25]), that $a_2(K_n)=n/2$. Dividing the vertex set into two parts of sizes $\lfloor n/2 \rfloor$ and $\lceil n/2 \rceil$ respectively, we obtain a bound of $a_2(K_n) \geq \lfloor \frac{n}{2} \rfloor$. This gives a simple proof of the sharp lower bound in the case that n is even.

We conjecture that the lower bound we obtained in Corollary 1.5 is almost tight:

Conjecture 3.5. Let $d \ge 3$ and $n \ge d + 1$. Then,

$$a_d(K_n) = \begin{cases} 1 & \text{if } d+1 \le n \le 2d, \\ \frac{n}{2d} & \text{if } n \ge 2d. \end{cases}$$

Note that this is a strong version of Conjecture 6.1 in [16].

4 Expansion under edge subdivisions

The goal of this section is to prove the following theorem regarding the effect of edge subdivision on the algebraic connectivity of a graph. Let G = (V, E) be a graph without isolated vertices. Given an edge e in G, replacing e with an induced path containing $m \geq 0$ new internal vertices is called a subdivision of e with m vertices.

Theorem 4.1. Let G be a connected graph with minimum degree at least 2 and maximum degree Δ , and let G' be obtained from G by a subdivision of each edge of G with at most m vertices. Then,

$$a(G') \ge \frac{\min\left\{\frac{1}{\Delta}a(G), 4\right\}}{2(m+1)^2}.$$

Let D(G) be the diagonal matrix with $D(G)_{i,i} = \deg_G(i)$, and $\mathcal{L}(G) = D(G)^{-\frac{1}{2}}L(G)D(G)^{-\frac{1}{2}}$ be the normalized Laplacian of G. The effect of edge subdivision on the normalized Laplacian was studied by Xie, Zhang and Comellas in [24]. Denote by s(G) the subdivision of G, that is, the graph obtained from G subdividing each edge of G with 1 vertex, thus subdividing each edge into two edges. Furthermore, let $s^k(G)$ be the k-th iterated subdivision. That is, $s^k(G) = s(s^{k-1}(G))$ (where $s^0(G) = G$).

Lemma 4.2 ([24, Lemma 3.1]). If $\lambda \neq 1$ is an eigenvalue of $\mathcal{L}(s(G))$ then $2\lambda(2-\lambda)$ is an eigenvalue of $\mathcal{L}(G)$.

In order to relate the spectral gap of the normalized Laplacian to the one of the unnormalized Laplacian, we will use the following result due to Higham and Cheng [12].

Lemma 4.3 ([12, Theorem 3.2]). Let $A \in \mathbb{R}^{n \times n}$ be a symmetric matrix, and let $X \in \mathbb{R}^{n \times m}$, for some $m \leq n$. Then, for every $1 \leq i \leq m$,

$$\lambda_i(X^T A X) = \theta_i \mu_i,$$

where

$$\lambda_i(A) \le \mu_i \le \lambda_{i+n-m}(A)$$

and

$$\lambda_1(X^T X) \le \theta_i \le \lambda_m(X^T X).$$

Lemma 4.4. Let G be a graph on n vertices, with minimum degree $\delta > 0$ and maximum degree Δ . Then, for all $2 \leq i \leq n$,

$$\delta \le \frac{\lambda_i(L(G))}{\lambda_i(\mathcal{L}(G))} \le \Delta.$$

Proof. TOPROVE 3

Proposition 4.5. Let G be a connected graph with minimum degree at least 2 and maximum degree Δ . Then,

$$a(s^k(G)) \geq \frac{\min\left\{\frac{2}{\Delta}a(G), 8\right\}}{4^k}.$$

Proof. TOPROVE 4

The next lemma establishes that algebraic connectivity is monotone with respect to edge subdivision.

Lemma 4.6. Suppose that G' = (V', E') is obtained from G = (V, E) by a subdivision of an edge e = uv of G with 1 new vertex w. Then, $a(G') \le a(G)$.

Proof. TOPROVE 6

Next, we apply Theorem 4.1 to show the existence of (1-dimensional) expander graphs with a desired degree sequence that are used subsequently as building blocks in the construction of d-dimensional rigidity expanders in the proof of Theorem 1.2.

Corollary 4.7. For every $d \ge 1$ there exists c = c(d) > 0 and an infinite family of 2dn-vertex bipartite graphs $(H_n)_{n=3}^{\infty}$ such that $a(H_n) \ge c$ and each part consists of n vertices of degree n and n vertices of degree n.

Proof. TOPROVE 7

5 Existence of rigidity expander graphs

We turn to combine the results in the previous sections to establish the existence of a family of k-regular d-rigidity expanders for every $k \ge 2d + 1$.

Proof. TOPROVE 8

6 An upper bound on $a_d(G)$

In this section we give a proof of Theorem 1.6, stating that for every graph G, $a_d(G) \leq a(G)$. In Section 8 below we discuss whether this theorem is tight.

We will need the following simple result about stiffness matrices.

Lemma 6.1 (Jordán-Tanigawa [14, 3.2]). Let G = (V, E) be a graph, and let $p: V \to \mathbb{R}^d$ and $x \in \mathbb{R}^{d|V|}$. Then

$$x^{T}L(G, p)x = \sum_{\{u,v\} \in E} \langle x(u) - x(v), d_{uv} \rangle^{2},$$

where $x(u) \in \mathbb{R}^d$ consists of the d coordinates of x corresponding to the vertex u.

We will also need the following lemma from [16], that states that when computing $a_d(G)$, it is enough to consider maps $p: V \to \mathbb{R}^d$ that are embeddings (that is, injective).

Lemma 6.2 ([16, Lemma 2.4]). Let G = (V, E) be a graph, and $d \ge 1$. Then

$$a_d(G) = \sup \left\{ \lambda_{\binom{d+1}{2}+1}(L(G,p)) \middle| p: V \to \mathbb{R}^d, \ p \ \textit{is injective} \right\}.$$

Proof. TOPROVE 9 □

7 Minimally rigid graphs

In this section we study the extremal values of the d-dimensional algebraic connectivity of minimally d-rigid graphs. In Proposition 7.1 we prove the upper bound $a_d(T) \leq 1$ for minimally d-rigid graphs, and in Proposition 7.5 we show that the upper bound is attained for "generalized star" graphs. This establishes the proof of Theorem 1.7. The section is concluded with a discussion about generalized path graphs and their algebraic connectivity.

Proposition 7.1. Let $d \geq 1$, and let $T \neq K_2, K_3$ be a minimally d-rigid graph. Then,

$$a_d(T) \leq 1$$
.

For the proof of Proposition 7.1 we will need the following results.

Lemma 7.2 (Jordán-Tanigawa [14, Lemma 4.5]). Let $d \ge 1$. Let G = (V, E) and $v \in V$. Then,

$$a_d(G \setminus v) \ge a_d(G) - 1.$$

Theorem 7.3 ([16, Theorem 1.2]). Let $d \geq 3$. Then

$$a_d(K_{d+1}) = 1.$$

Proof. TOPROVE 10

Let $d \geq 1$ and $n \geq d + 1$. Let $S_{n,d}$ be the graph on vertex set [n] with edge set

$$E(S_{n,d}) = \{\{i, j\} : i \in [d], j \in [n] \setminus \{i\}\}.$$

It is easy to check that $S_{n,d}$ is minimally d-rigid.

We consider the following mapping of the vertices of $S_{n,d}$ to \mathbb{R}^d : Let $e_1, \ldots, e_d \in \mathbb{R}^d$ be the standard basis vectors. We define $p^* : [n] \to \mathbb{R}^d$ by

$$p^*(i) = \begin{cases} e_i & \text{if } 1 \le i \le d, \\ 0 & \text{if } d < i \le n. \end{cases}$$

Proposition 7.4. The spectrum of $L(S_{n,d}, p^*)$ is

$$\left\{0^{\left(\binom{d+1}{2}\right)},1^{\left(dn-\binom{d+1}{2}-d\right)},(n-d/2)^{(d-1)},n^{(1)}\right\}$$

(where the superscript (m) indicates multiplicity m of the corresponding eigenvalue). In particular, $\lambda_{\binom{d+1}{2}+1}(L(S_{n,d},p^*))=1$.

Proposition 7.5. Let $d \ge 1$ and $n \ge d + 1$. Then, unless d = 2 and n = 3, we have

$$a_d(S_{n,d}) = 1.$$

It would be interesting to determine whether the graphs $S_{n,d}$ are the only extremal cases in Theorem 1.7 (for d = 1 this is a result of Merris, [21, Cor. 2]).

7.1 Generalized path graphs

Let $n \ge d + 1$. Let $P_{n,d}$ be the graph on vertex set [n] with edges

$$\{\{i,j\}: 1 \le i < j \le n, j-i \le d\}.$$

Note that, for d=1, $P_n=P_{n,1}$ is just the path with n vertices. It is not hard to check that, for $n \geq d+1$, $P_{n,d}$ is minimally rigid in \mathbb{R}^d .

As mentioned in the introduction, Fiedler [6] showed that $a_1(G) \ge a_1(P_n) = 2(1 - \cos(\pi/n))$ for every connected graph G. For d > 1, we do not know the exact value of $a_d(P_{n,d})$, but the following result gives us its order of magnitude:

Proposition 7.6. Let $d \ge 2$ and $n \ge d + 1$. Then

$$1 - \cos\left(\frac{\pi}{2} \left\lceil \frac{n}{d} \right\rceil^{-1}\right) \le a_d(P_{n,d}) \le 2d - 2\sum_{k=1}^d \cos(2k\pi/n).$$

For d=2 we have a slightly better lower bound, $a_2(P_{n,2}) \geq 2(1-\cos(\pi/n))$.

For large n, we have $1 - \cos\left(\frac{\pi}{2} \left\lceil \frac{n}{d} \right\rceil^{-1}\right) \approx 1 - \cos\left(\frac{d\pi}{2n}\right) \approx \frac{d^2\pi^2}{8n^2}$. Moreover, $2d - 2\sum_{k=1}^d \cos(2k\pi/n) \leq \frac{2\pi^2d(d+1)(2d+1)}{3n^2}$. Therefore, $a_d(P_{n,d}) = \Theta_d(1/n^2)$. Proof. TOPROVE 13

8 Concluding remarks

Many fascinating open problems suggest themselves. In this paper, we showed that families of k-regular d-rigidity expanders exist for k > 2d, and it is natural to seek for the best possible construction.

Problem 8.1. Let $d \ge 2$ and k > 2d be integers. What is

$$c_d(k) := \sup_{(G_n)_{n \in \mathbb{N}}} \liminf_n a_d(G_n),$$

where $(G_n)_{n\in\mathbb{N}}$ runs over families of k-regular graphs of increasing size?

The 1-dimensional case of this problem is perhaps the most important question in the theory of expander graphs. The Alon-Boppana Theorem asserts an upper bound of $c_1(k) \leq k - 2\sqrt{k-1}$, and constructions attaining this bound are known as (one-sided) Ramanujan graphs [19, 20]. For $d \geq 2$, the proof of Theorem 1.2 gives a lower bound for $c_d(k)$ which applies to all $k \geq 2d+1$, and whose rate of decay is in the order of $1/d^2$ as $d \to \infty$. If $k \geq td$ for some $t \geq 3$, one can easily adapt our methods and attain a lower bound for $c_d(k) \geq c_1(t)/2$ that is independent of d. That is, by using t-regular bipartite Ramanujan graphs in Section 5 instead of the subdivided graphs from Corollary 4.7. The question whether $c_d(2d+1) \to 0$ as $d \to \infty$ remains open.

It is known that a(T) = O(1/n) if T is a bounded-degree tree [15], and we conjecture that this phenomenon extends to higher dimensions.

Conjecture 8.2. Fix integers $d, b \ge 1$. Then,

$$\max_{G_n} a_d(G_n) \to 0 \quad as \ n \to \infty,$$

where G_n runs over all minimally d-rigid n-vertex graphs of max-degree b.

A stronger but still plausible conjecture — that

$$\sup_{(G_n, p_n)} \lambda_{d(d+1)+1}(L(G_n, p_n)) \to 0 \quad \text{as } n \to \infty,$$

where (G_n, p_n) runs over all d-frameworks of minimally d-rigid n-vertex graphs of maximum degree b — would imply that no 2d-regular d-rigidity expanders exist, via interlacing of spectra under adding an edge to a graph (see [16, Theorem 2.3]).

Regarding the relations between the values $a_d(G)$, for G fixed and d that varies, we propose the following strengthening of Theorem 1.6:

Conjecture 8.3. (Monotonicity) Let $1 \le d' < d$ be integers and G a graph on n vertices. Then, $a_d(G) \le a_{d'}(G)$.

In addition, the fact that we do not know if the bound in Theorem 1.6 is tight raises the following problem:

Problem 8.4. What is $\sup_G(a_d(G)/a(G))$ over all connected graphs G?

The best lower bound that we currently have for this problem that applies to every d is 1/d which is given by the generalized star graph $S_{n,d}$. Indeed, $a_d(S_{n,d}) = 1$ and $a(S_{n,d}) = d$. For the special case d = 2 we obtained by computer calculations $a_2(P_{12,2}) \ge 0.667 \cdot a(P_{12,2})$ (where $P_{n,d}$ is the generalized path graph). It remains a possibility that Theorem 1.6 is tight, and we suspect that generalized paths might be the extremal examples.

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