Parallelising K-means Algorithm with OpenMP

Ernesto Palchetti

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Section 1

Introduction

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■ **serial** implementation in C++

K-means

Introduction

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Introduction

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The goal is to implement two version of the **K-Means** algorithm.

- **serial** implementation in C++
- **parallel** implementation in C++ with OpenMP

The aim is to compare them in terms of **speedup**.

$$speedup := \frac{serial time}{parallel time with pthreads}$$
 (1)



Introduction 0000

Robey and Zamora [2, p. 11-12]

For fixed-size problems

$$SpeedUp(N) = \frac{1}{S + \frac{P}{N}}, \qquad P + S = 1.$$
 (2)

Robey and Zamora [2, p. 12-13]

Introduction

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$$SpeedUp(N) = N - S(N - 1), \tag{3}$$

when the size of the problem grows proportionally to the number of processors.



Section 2

K-means 00000

K-means



■ **Clustering** algorithm

- **Clustering** algorithm
- Quantitative variables



- **Clustering** algorithm
- Quantitative variables
- distance-based clustering

K-means Algorithm

- **Clustering** algorithm
- Quantitative variables
- distance-based clustering
- k centroids



K-means Algorithm

K-means

- **Clustering** algorithm
- Quantitative variables
- distance-based clustering
- k centroids
- Convergence criterion



Centroids Initialization

We select k random points of the dataset

$$c_j = x_{i_j}, \quad i_1, ..., i_k \in \{1, ..., N\}$$
 (4)

Centroids Initialization

We select k random points of the dataset

$$c_j = x_{i_j}, \quad i_1, ..., i_k \in \{1, ..., N\}$$
 (4)

Other option: we can assign random points to clusters and skip the first step, or set them according to previous analysis.



Compute distances

We compute the Euclidean distance between every point and every centroid.

$$d(\boldsymbol{x}_i, \boldsymbol{c}_j) = \sqrt{\sum_{l=1}^{D} (\boldsymbol{x}_{il} - \boldsymbol{c}_{jl})^2}$$
 (5)

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We can use different distances (see Chapter 14 of Hastie, Tibshirani, and Friedman (2009) [1]).



We assign a point to the cluster represented by the closest centroid.

$$\mathbf{x}_i \in \mathcal{C}_j \iff j = \operatorname*{arg\,min}_{t=1,\dots,k} d(\mathbf{x}_i - \mathbf{c}_t)$$
 (6)

New Centroids

New centroids are computed as the average point of every cluster

$$\boldsymbol{c}_{j} = \frac{1}{|\{i : \boldsymbol{x}_{i} \in \boldsymbol{c}_{j}\}|} \sum_{i=1}^{N} \boldsymbol{x}_{i} \mathbb{I}_{[\boldsymbol{x}_{i} \in \boldsymbol{c}_{j}]}$$
(7)

Section 3

Serial Implementation



Centroids Selection

```
int p;
for (int i = 0; i < k; ++i) {
    p=distrib(gen);
    C[i][0]=v[p][0];
    C[i][1]=v[p][1];
}
```

Choose k centroids by randomly selecting them from the dataset.

Number of iterations

```
int soglia=0.01*N;
//int soglia=0.01*N;
while (change > soglia){
```

The algorithm stops when the number of points that change classification after one step is less than 1% of N.

Reset counters

```
for (j=0; j< k; ++j) {
    sums[j][0]=0.0;
    sums[j][1]=0.0;
    contatori[j]=0;
}
change = 0;
```

At every step, we reset to 0 every counter and partial sum.

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```
for (i=0;i<N;i++) { // loop on every point
    dmin=distanza_punto_punto(v[i][0],C[0][0],v[i][1],C[0][1]);
    kmin=0;
        d=distanza_punto_punto(v[i][0],C[j][0],v[i][1],C[j][1]);
        if (d<dmin) {</pre>
             dmin=d:
             kmin=j;
                                   We compute all distances, storing
                                   the index of the closest centroid.
    }
```

Classification

```
if (ass[i]!=kmin) {
         change++;
         ass[i]=kmin;
}
sums[kmin][0]+=v[i][0];
sums[kmin][1]+=v[i][1];
contatori[kmin]++;
}
```

We assign the point to the cluster of the closest centroid. Then we update change counter, the counter of points in the relative cluster, and a sum containing all points in that cluster.

Computing new centroids

```
for (j=0;j<k;j++) {
    C[j][0]=sums[j][0]/contatori[j];
    C[j][1]=sums[j][1]/contatori[j];
}</pre>
```

We compute new centroids by dividing the sums by the counters.

Section 4

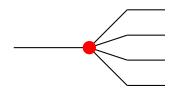
Parallel Implementation

Centroids Selection

```
int p;
for (int i = 0; i < k; ++i) {
    p=distrib(gen);
    C[i][0]=v[p][0];
    C[i][1]=v[p][1];
}
int change=N;
int soglia=0.01*N;
```

Choose k centroids by randomly selecting them from the dataset in a serial way. Initialize the shared threshold and counter.

Robey and Zamora [2] Chapter 7



Create threads_number threads and define private counters and sums.



```
while (change > soglia) {
    changet=0;
    for (int j=0; j< k; j++) {
        contatorit[j]=0;
        sumst[j][0]=0.0;
        sumst[j][1]=0.0;
#pragma omp barrier
```

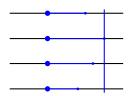
Start while loop and initialize private counters. Make sure every thread enters the loop.

Resetting shared counter

A single core changes the value of the counter.

Parallel Implementation 00000000000

```
#pragma omp for
    for (int j=0; j< k; j++) {
        sums[j][0]=0.0;
        sums[j][1]=0.0;
        contatori[j]=0;
```



Every thread resets a portion of shared counters (no risk of race conditions)



Parallel Loop over points

```
#pragma omp for nowait
for (int i=0;i<N;i++) {
    dmin=distanza_punto_punto(v[i][0],C[0][0],v[i][1],C[0][1
    kmin=0;
    for (int j=1; j < k; j++) {
        d=distanza_punto_punto(v[i][0],C[j][0],v[i][1],C[j][
        if (d<dmin) {
                        minimum
             dmin=d:
                                 Every thread computes distances
             kmin=j;
                                 between points and centroids.
                                 equally splitting points to treat.
```

Parallel Implementation 00000000000

Parallel Implementation 00000000000

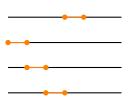
Parallel Loop over points

```
if (ass[i]!=kmin) {
        changet++;
        ass[i]=kmin;
   }
    sumst[kmin][0]+=v[i][0];
    sumst[kmin][1]+=v[i][1];
    contatorit[kmin]++; points
```

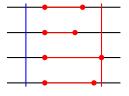
If the point is assigned to a different cluster, the counter is updated. Then, the private (no race condition) counter and sum for the relative cluster are updated.

Assignment

In a critical section, every thread updates shared sums and counters one at a time, avoiding a race condition.

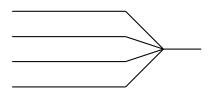


```
#pragma omp barrier
                                 After a barrier to ensure that
#pragma omp for
                                 every counter is ready, centroids
    #pragma omp for
                                 are computed in a parallel for.
    for (int i=0;i<k;i++) {
        C[i][0]=sums[i][0]/contatori[i];
        C[i][1]=sums[i][1]/contatori[i];
```



Parallel Implementation

At the end of the parallel section, threads join.



Section 5

Experiments



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- I applied the two algorithm on a Kaggle dataset of 21600 2D points;
- I applied the two algorithms on 9 randomly generated datasets with different values of *N* and *k*.

For both, I computed **times** for serial and parallel algorithms, and I evaluated the **speedup**, checking that the resulting clusters are the same. The analysis is performed in RStudio.



Kaggle Example I

For this experiment, I applied both algorithms, setting a varying number of threads

$$n_{threads} = 2^p, p = 0, 1, ..., 8.$$
 (8)

I repeated every test $N_{rep} = 100$ times.



Kaggle Example II

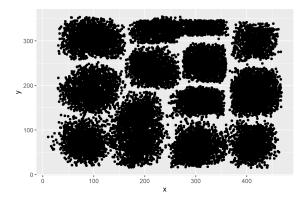


Figura 1: Input data of the experiment.



Kaggle Example III

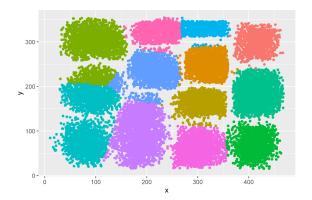


Figura 2: Output clusters of the experiment.

Kaggle Example IV

Threads	Mean Speedup	Lower	Upper
1	1.00	0.988	1.01
2	1.70	1.70	1.73
4	2.76	2.74	2.79
8	2.99	2.96	3.01
16	2.79	2.77	2.81
64	2.43	2.42	2.45
128	1.99	1.97	2.00
256	1.41	1.40	1.41

Tabella 1: Speedups for the Kaggle dataset.

Kaggle Example V

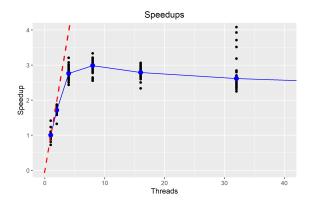


Figura 3: Speedups of the experiments of the Kaggle dataset.



Random Datasets I

I repeated 10 tests for every combination of $N=10^4$, 10^5 , and 10^6 , and k=10, 20 and 40.



Random Datasets II

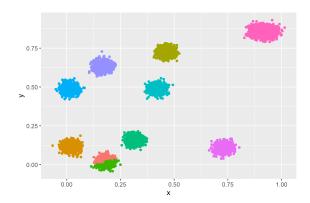


Figura 4: Randomly generated dataset and relative clusters for k = 10 and $N = 10^4$.



Random Datasets III

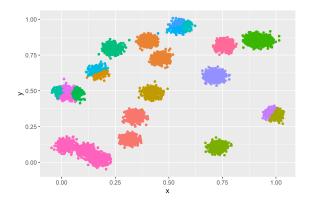


Figura 5: Randomly generated dataset and relative clusters for k = 20 and $N = 10^4$.



Random Datasets IV

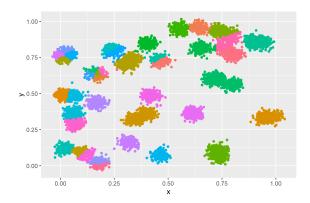


Figura 6: Randomly generated dataset and relative clusters for k=40 and $N=10^4$.



Random Datasets V

Threads	$N = 10^4$	$N = 10^5$	$N = 10^6$
1	0.974	1.00	0.994
2	1.76	1.44	1.70
4	2.21	2.07	2.49
8	2.65	3.38	3.00
16	2.69	3.30	2.92
32	2.47	3.24	2.96
64	1.92	3.29	3.00
128	1.36	2.96	3.04
256	0.768	2.59	3.25

Tabella 2: Speedups for K = 10.



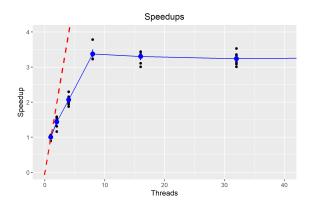


Figura 7: Speedups for $N = 10^5$ for k = 10.

Random Datasets VII

Threads	$N = 10^4$	$N = 10^5$	$N = 10^6$
1	1.01	1.00	0.982
2	1.84	1.73	1.71
4	2.70	2.57	2.52
8	3.01	3.18	2.95
16	2.55	3.58	2.89
32	2.63	3.02	2.90
64	2.18	3.03	2.92
128	1.64	2.87	2.91
256	1.22	2.63	2.88

Tabella 3: Speedups for K = 20.



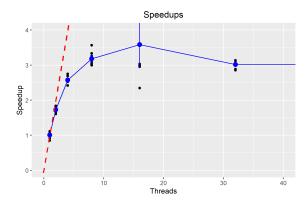


Figura 8: Speedups for $N = 10^5$ for k = 20.

Random Datasets IX

Threads	$N = 10^4$	$N = 10^5$	$N = 10^6$
1	1.01	1.00	1.01
2	1.70	1.73	1.71
4	2.08	2.58	2.54
8	3.33	2.98	2.92
16	3.37	2.90	2.91
32	3.09	2.94	2.91
64	2.97	2.93	2.90
128	2.41	2.88	2.90
256	1.85	2.77	2.89

Tabella 4: Speedups for K = 40.



Random Datasets X

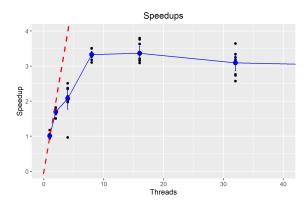


Figura 9: Speedups for $N = 10^4$ for k = 40.

Section 6

Conclusions

The speedup I obtained is good (not excellent);

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- The speedup I obtained is good (not excellent);
- it increases with the dimensions of the dataset:
- The management cost of threads has to be balanced.

I can reach better results with a better distribution of data in memory using the **first touch** principle.





T. Hastie, R. Tibshirani, and J. Friedman.

The elements of statistical learning: data mining, inference, and prediction.

Springer series in statistics. New York, 2nd ed edition, 2009.



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Parallel and High Performance Computing. Manning Publications Co. LLC, New York, 2021.

