

# TMT-APS Use Case Development

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# TMT-APS Use Case Development

## 1 Use Case Development Introduction

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This document covers how use cases and activities for Alignment and Phasing System (APS) are developed. Use cases are high level procedures APS uses to perform various telescope alignments and calibrations. In general, use cases are made up of one or more *activities*.

### 1.1 Purpose

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The purpose of developing use cases is to capture high level procedures the Alignment and Phasing System (APS) uses to perform various telescope alignments and calibrations. The use cases verify requirements on the performance of the telescope such as timing, electrical power, and pointing errors. The identified use cases cover a spectrum of interactions with other subsystems of TMT, and to accurately predict the performance of APS. The use cases are developed according to the principles of the Executable Systems Engineering Method (ESEM) which prescribes the functional and physical decomposition of the system into a nested tree of components, and the specification of the behavior of each. The primary model elements that are used to develop TMT use cases are state machines, activities, sequence diagrams, simulation configurations, instance tables, and views. The process for developing use cases consists of extending the behavior of the Procedure Executive and Analysis Software through state machines and activities, specifying a context for automated analysis, specifying the behavior for a particular use case through sequence diagrams, configuring simulation configurations for system execution, exposing instance results to a view, and evaluating simulation results. The TMT use case, Post Segment Exchange Alignment, will provide context on each of these steps below.

Operational scenarios and specific scenarios in which it will be operated. test, nominal, part of it's operational life-cycle.

### 1.2 Overview

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The following list provides an overview of the APS use cases:

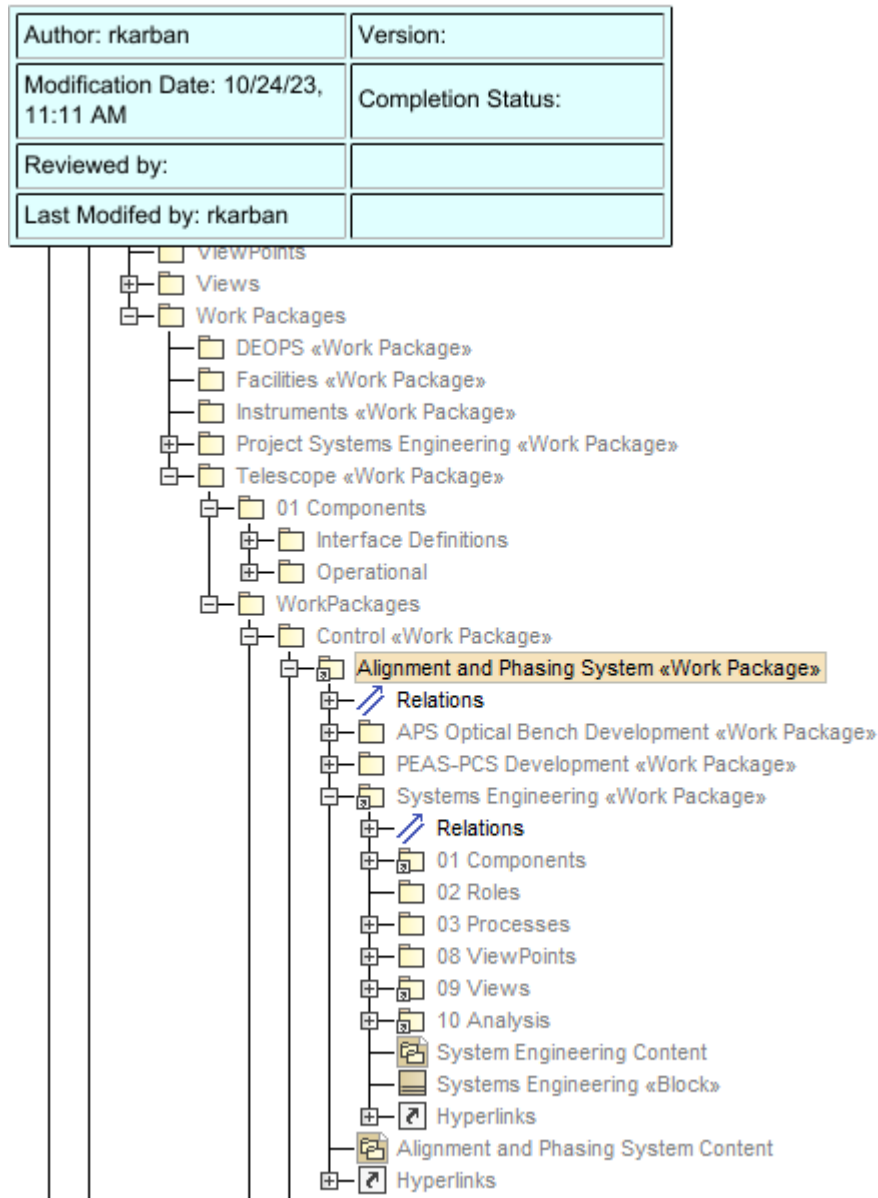
1. Post segment-exchange alignment
2. Maintenance alignment
3. Rigid body M3 alignment
4. Off-axis wavefront measurements
5. Measurement of segment warping harness influence functions
6. APS pre-observing checkout
7. M1CS Sensor Calibration with Post Segment-Exchange Alignment
8. Collection of M2 and M3 gravity calibration data
9. APS pre-observing internal calibrations

For detailed explanations of each use case, see [TMT-APS OCDD](#).

## 2 Model Organization

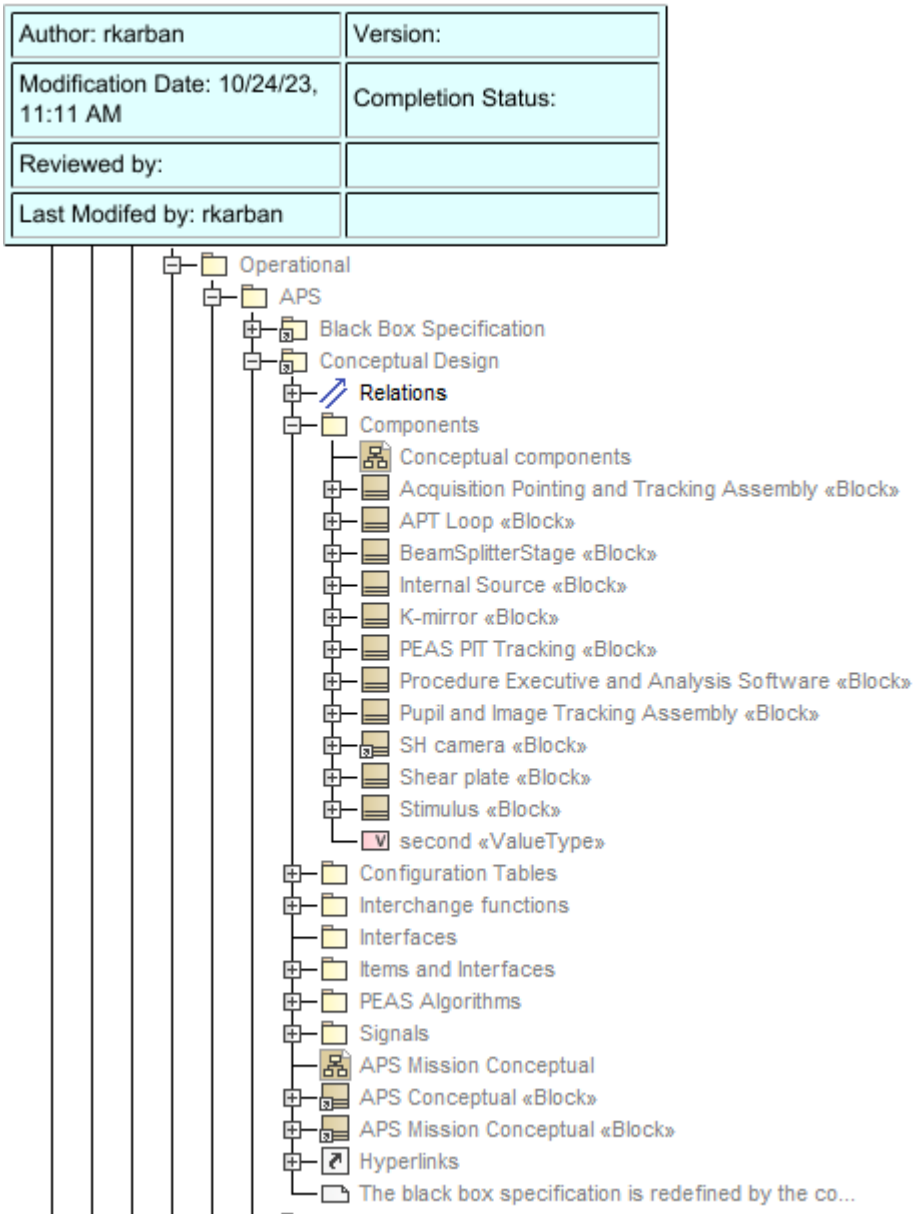
The TMT model structure supports different levels of abstraction and deeply nested system hierarchies. All model elements that are required to develop a Use Case will be shown in the context of the Containment Tree.

## TMT Model Organization



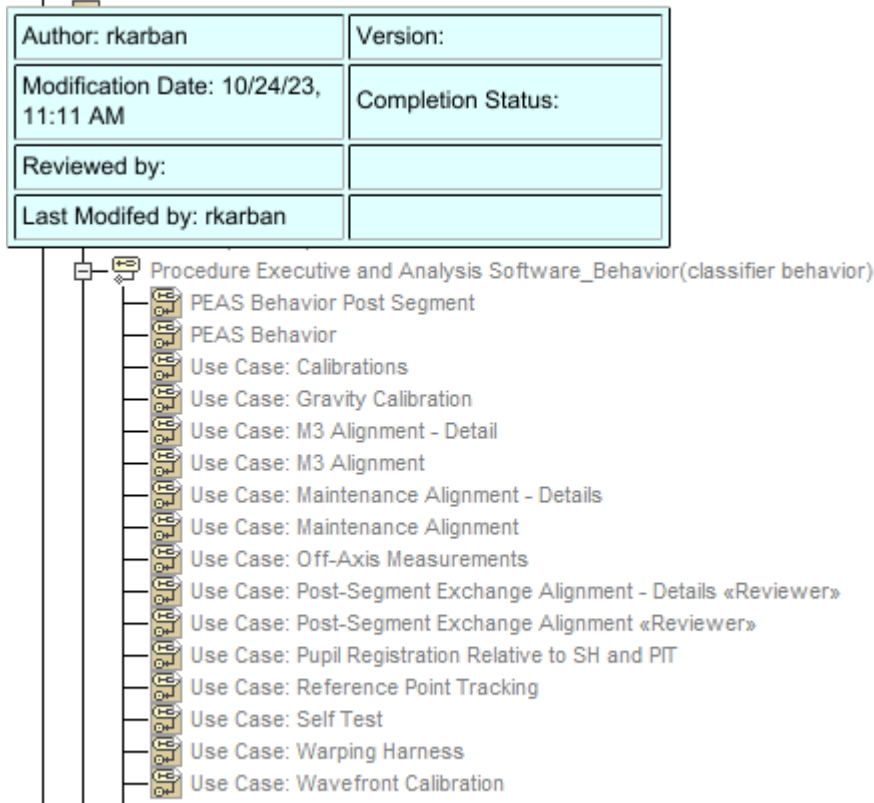
## Navigating to APS

Logical Design Components

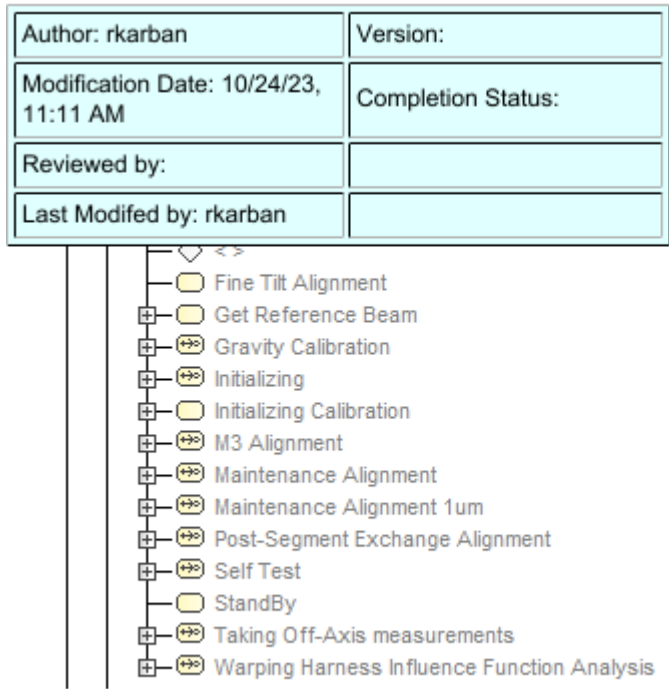


Navigating to PEAS

PEAS Use Case Diagrams



PEAS Use Case States



PEAS Activities

Author: rkarban

Version:

Modification Date: 10/24/23, 11:11 AM

Completion Status:

Reviewed by:

Last Modified by: rkarban

ment1, parameter : Boolean )

Mirror, success : Boolean )

Boolean, doGuide : Boolean )

Check for existing reference beam map( mapsExist : Boolean )

Check If All Spots Present( parameter : Boolean )

Check if Cameras Cooled Down( result : Boolean )

Coarse Tilt Alignment

Configure APS for SH Test( shMask : SH Mask, shFilter : SH Filter )

Configure APT Subsystem

Create Zero Vector( length : Integer ) : Integer [0..\*]

Determine Next Search Circle Location

Extract Filter and Mask from Table Entry( shMask : SH Mask, shFilter : SH Filter, lookupTa

Get SH Self Test Integration Time( dit : Integer )

Home All Mechanisms

Home Mechanisms

Load Averaged SH Images

Load Averaged SH Images( images : SH\_Image [63] )

Load M1CS Configuration( m1PTTPositions : M1SegmentsPositions )

Measure WH Influence Function

MeasureZernikes

MeasureZernikesLoop

Minimize Sensor Readings

Move All nth WH Motors( stroke : Integer, whMotorID : Integer )

Move to Previous M1CS Configuration

Narrow Band Phasing

Perform APT Self Test

Perform PIT Self Test

Perform SH Self Test

Perform WH Influence Function Analysis

Proceed

Reset Strain Gauges

RestoreM2M3AxisBSSPositions

Retrieve Filter and SH Mask Combinations from Lookup Table( lookupTableEntries : SelfTe

Retrieve Reference Beam Map

Rigid Body and Segment Figure correction( doAcquisition : Boolean, doGuide : Boolean, c

SelectNextTarget

Setup APS, Acquire and Start Guiding( doAcquisition : Boolean, doStartPITTrack : Boolea

SubtractZernikes

Take Multiple SH Exposures( dit : Integer )

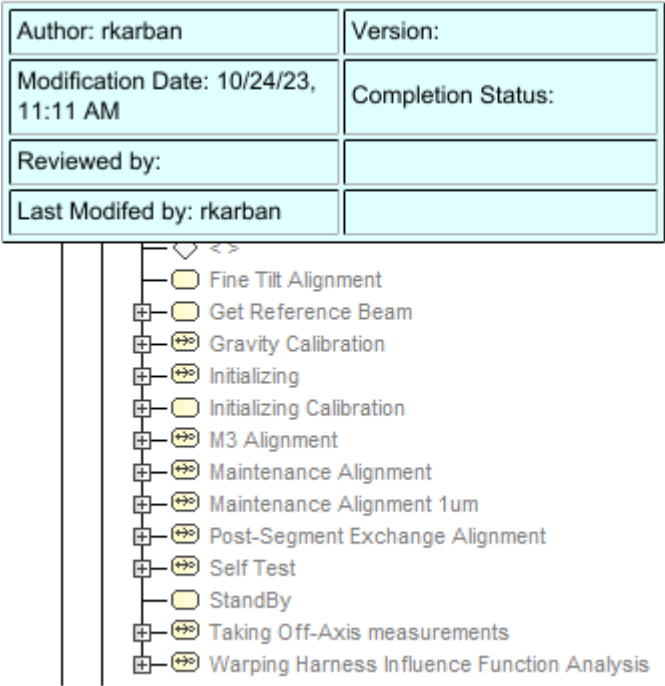
3 Defining Behavior in State Machines and Activites

The behavior of components are distinguished between life-cycle behavior and distinct isolated activities of a component. State machines are used to specify the life-cycle behavior of components. The life-cycle behavior describes the behavior of a component from beginning to end-of-life, and describes the state of a component at any instant in its operational lifetime. State machines a method to specify the various available modes of a system using states, and the conditions for transitioning between them. Activities capture specific tasks that represent only a part of the overall behavior of a component. The flow charts

allow for the specification of sequential and parallel behavior, and decision points and synchronization points for an intuitive description of intended behavior.

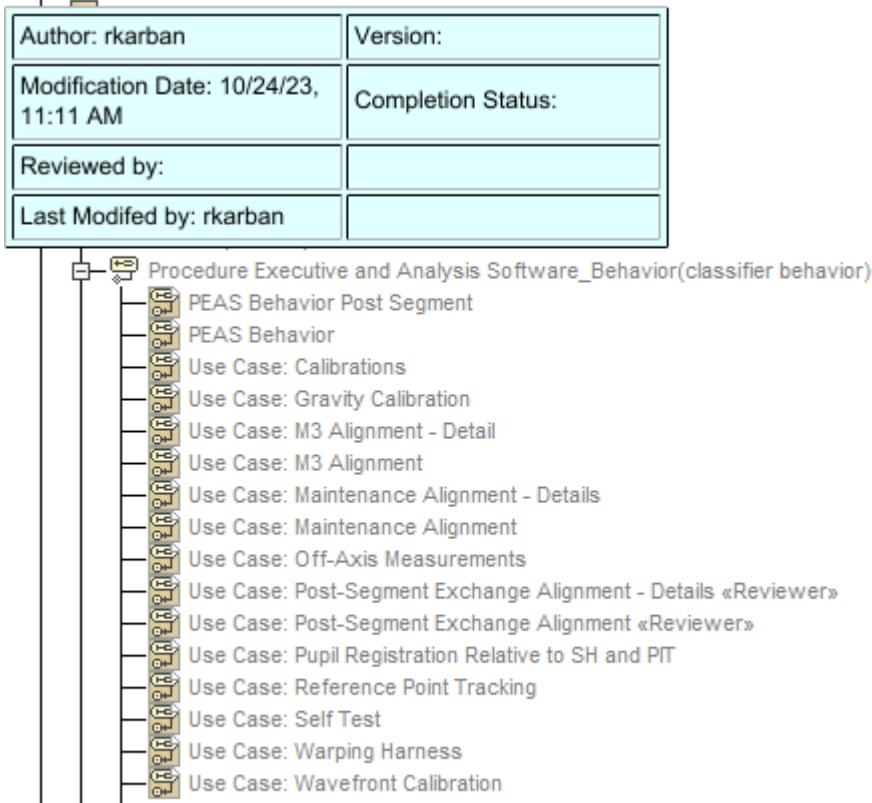
A use case state machine begins [Initializing](#) will the do-activity [InitializePEAS](#). When transitioning to state *StandBy*, a signalEvent of *InitComplete* will occur. An external signal that is specific to the use case (which may be provided by a user) causes a trigger to transition from *StandBy* to the use case specific state. Within this use case specific state, the primary states of the use case are specified. PEAS is specified to only be able to leave the primary use case state if an *Abort* signal is provided (internally or externally), and will return to the state *StandBy*. This can be seen below in the [Use Case: Maintenance Alignment](#) diagram.

PEAS Use Case States

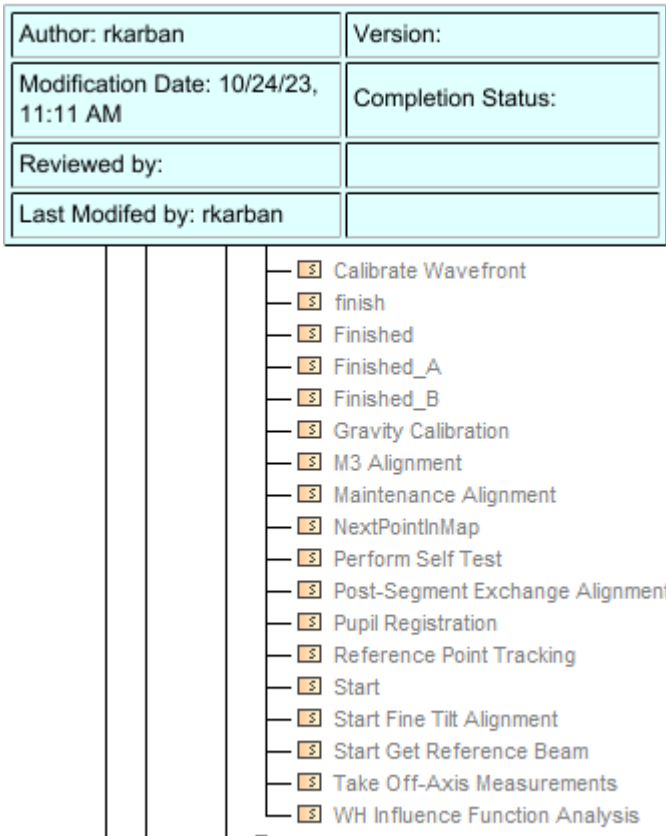




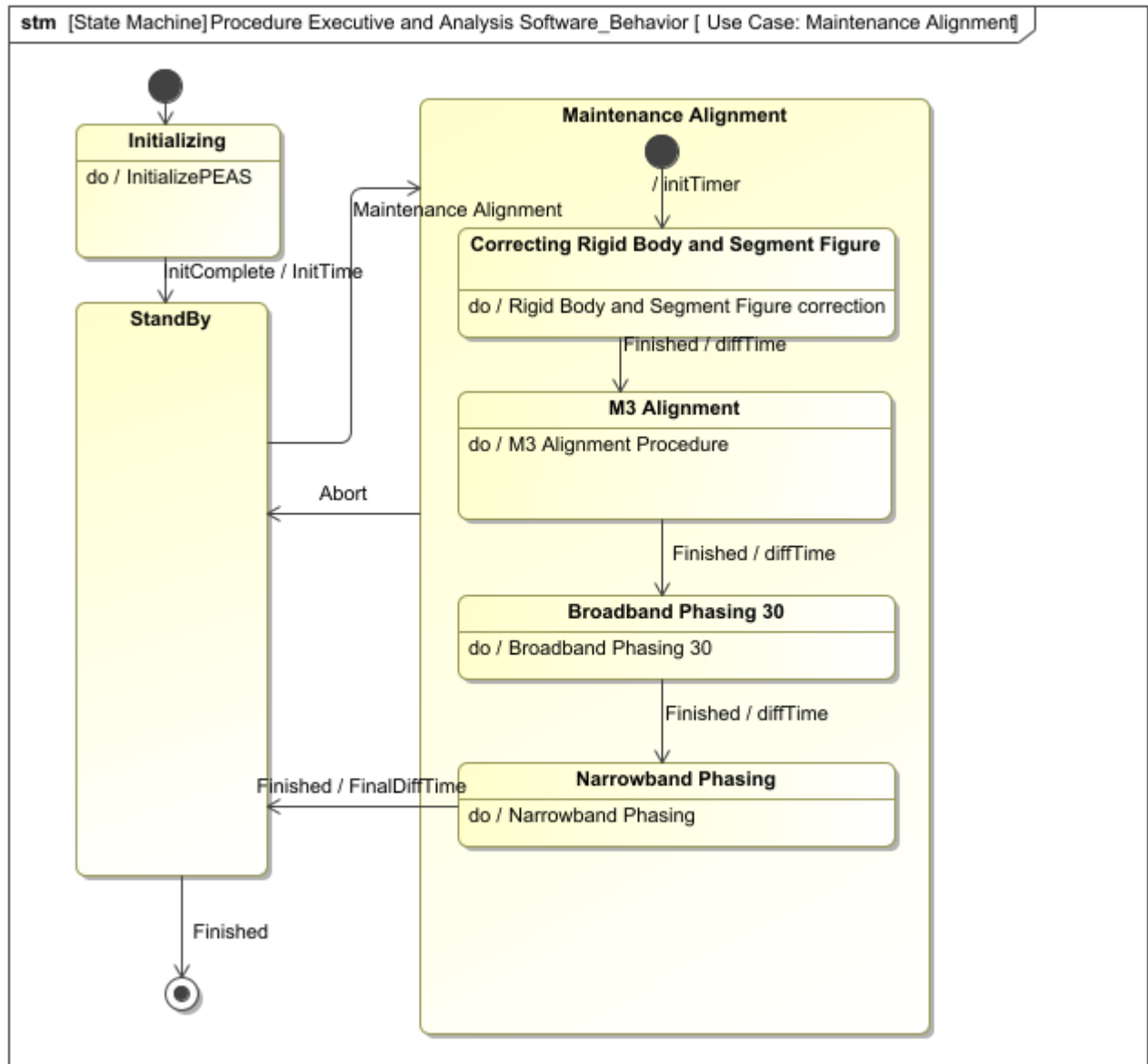
PEAS Use Case Diagrams



Use Case Signals































## Use Case: Maintenance Alignment



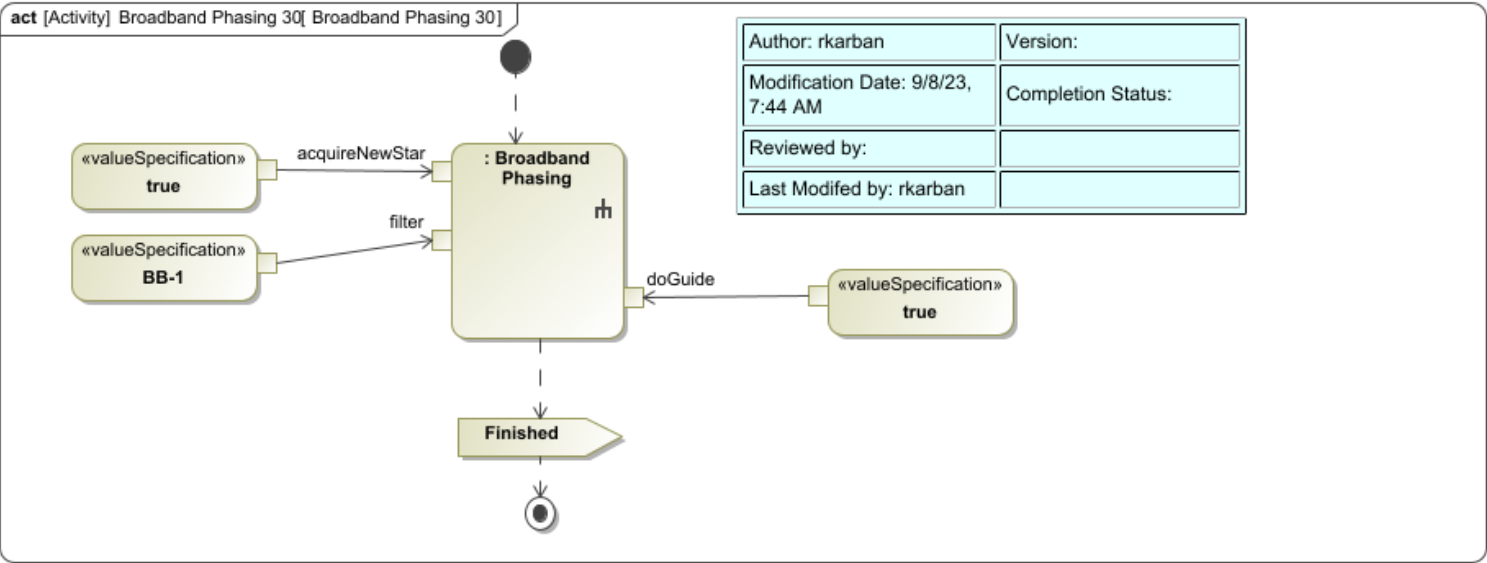
## PEAS Activities

Author: rkarban	Version:
Modification Date: 10/24/23, 11:11 AM	Completion Status:
Reviewed by:	
Last Modified by: rkarban	

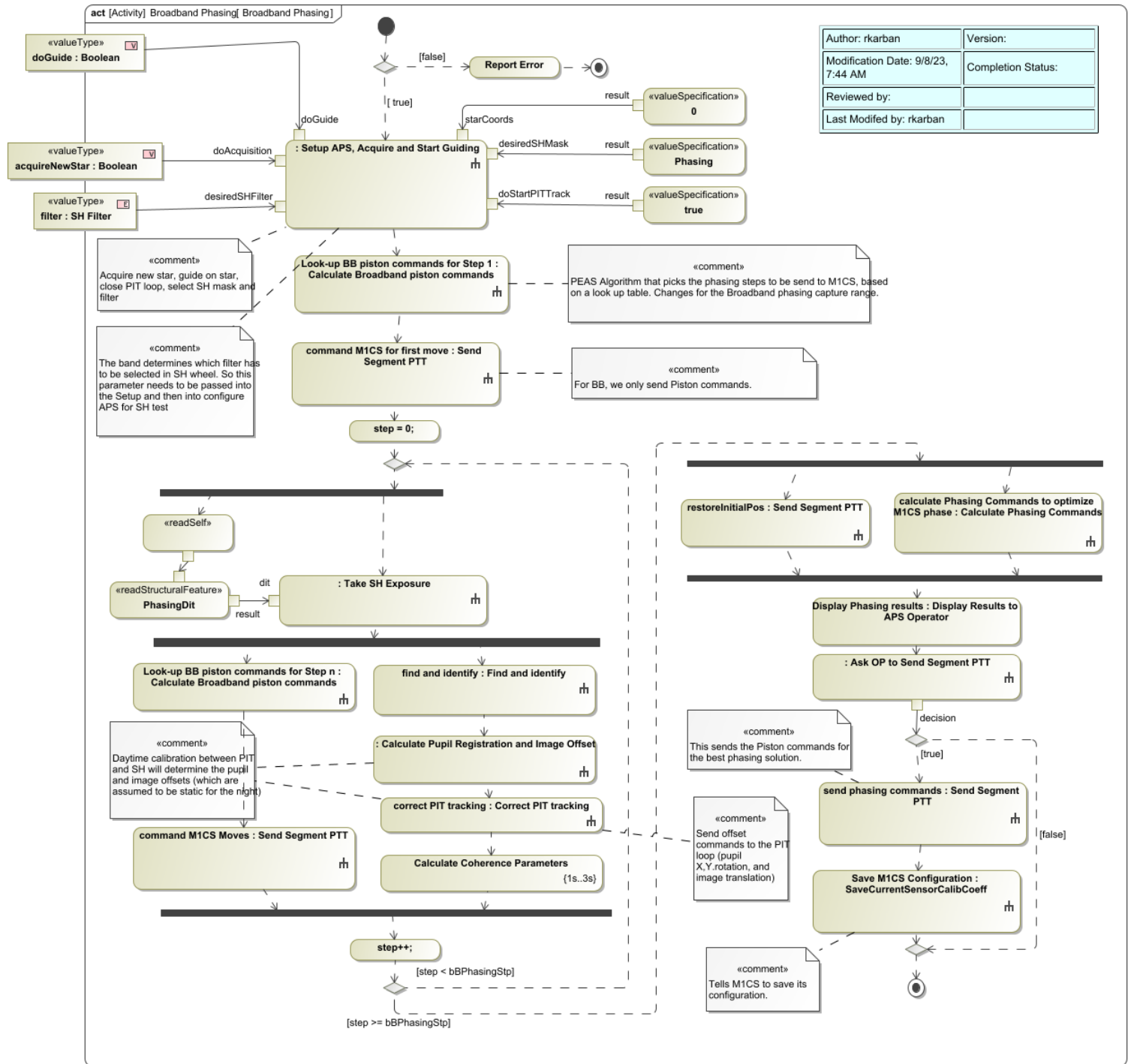
  

	Check for existing reference beam map( mapsExist : Boolean )	
	Check If All Spots Present( parameter : Boolean )	ment1, parameter : Boolean )
	Check if Cameras Cooled Down( result : Boolean )	
	Coarse Tilt Alignment	
	Configure APS for SH Test( shMask : SH Mask, shFilter : SH Filter )	Mirror, success : Boolean )
	Configure APT Subsystem	Boolean, doGuide : Boolean )
	Create Zero Vector( length : Integer ) : Integer [0..*]	
	Determine Next Search Circle Location	
	Extract Filter and Mask from Table Entry( shMask : SH Mask, shFilter : SH Filter, lookupTa	
	Get SH Self Test Integration Time( dit : Integer )	
	Home All Mechanisms	
	Home Mechanisms	
	Load Averaged SH Images	
	Load Averaged SH Images( images : SH_Image [63] )	
	Load M1CS Configuration( m1PTTPositions : M1SegmentsPositions )	
	Measure WH Influence Function	
	MeasureZernikes	
	MeasureZernikesLoop	
	Minimize Sensor Readings	
	Move All nth WH Motors( stroke : Integer, whMotorID : Integer )	
	Move to Previous M1CS Configuration	
	Narrow Band Phasing	
	Perform APT Self Test	
	Perform PIT Self Test	
	Perform SH Self Test	
	Perform WH Influence Function Analysis	
	Proceed	
	Reset Strain Gauges	
	RestoreM2M3AxisBSSPositions	
	Retrieve Filter and SH Mask Combinations from Lookup Table( lookupTableEntries : SelfTe	
	Retrieve Reference Beam Map	
	Rigid Body and Segment Figure correction( doAcquisition : Boolean, doGuide : Boolean, c	
	SelectNextTarget	
	Setup APS, Acquire and Start Guiding( doAcquisition : Boolean, doStartPITTrack : Boolea	
	SubtractZernikes	
	Take Multiple SH Exposures( dit : Integer )	

Broadband Phasing 30



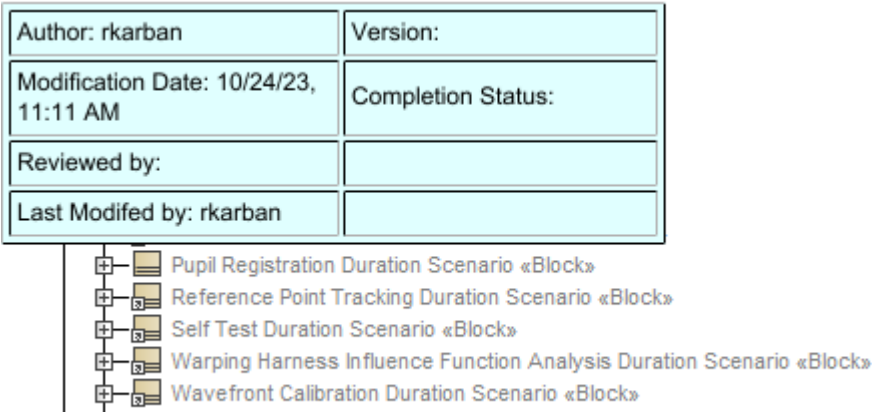
## Broadband Phasing



## 4 Defining Behavior in Sequence Diagrams

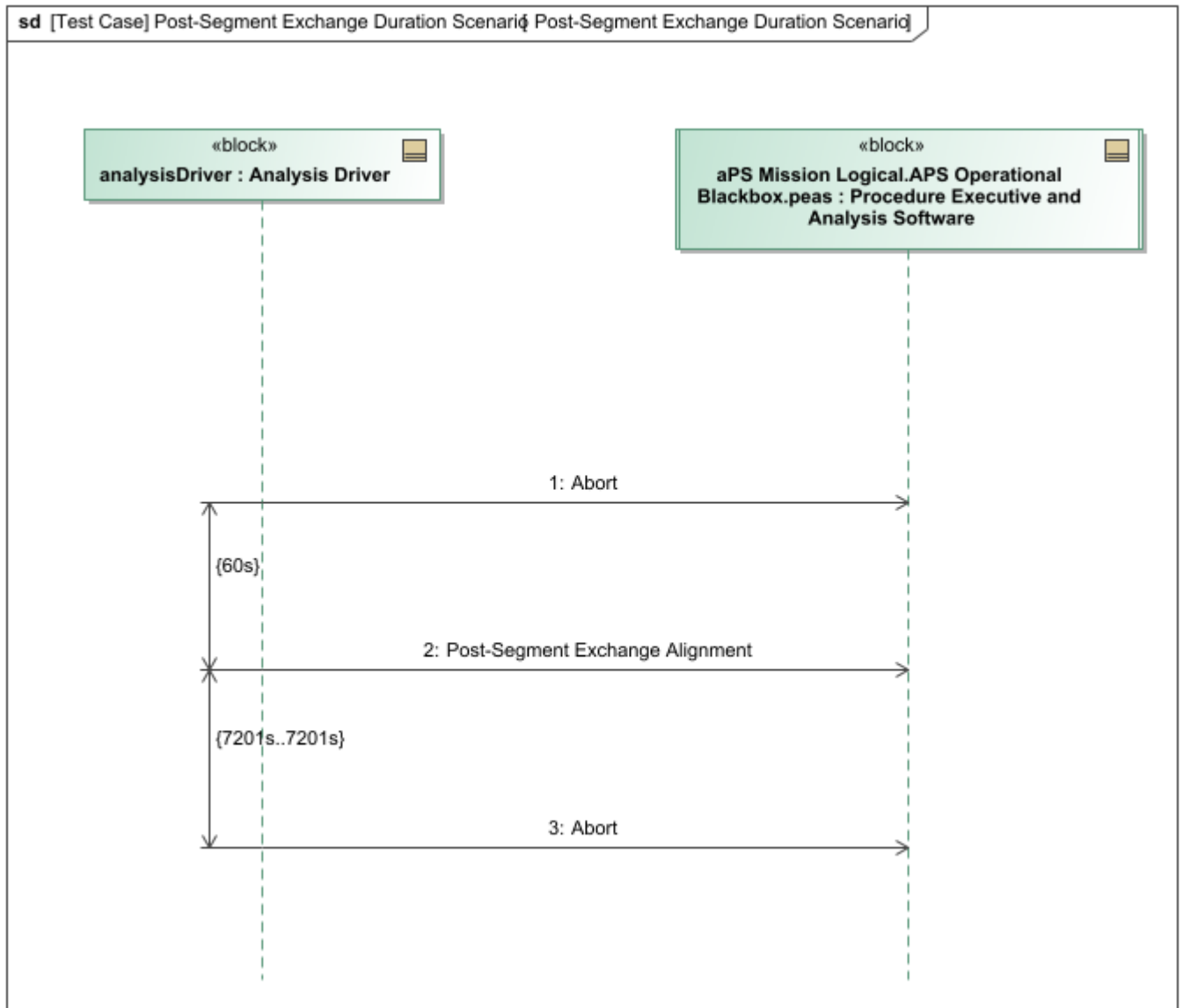
The purpose of operational scenarios is to provide a method to model variations and configurations of a system, and allows for analysis to be performed. Operational scenarios for each Use Case are specified and provide a context for duration analysis. Requirements that define a time frame for a behavior can be verified by performing a duration analysis to calculate a time value that is compared to a required value through parametric relations. The Use Case scenarios evaluate whether the performance of the APS meets a specified duration requirement.

Use Case Duration Scenario Blocks



Each corresponding Use Case duration scenario of the PEAS is represented by a SysML block. The naming convention for a Duration Scenario block is Use Case name + "Duration Scenario". The classifier behavior of the duration scenario block is a sequence diagram, and additionally owns a parametric diagram. The Use Case Duration Scenario blocks can be found in the model at the following location TMT::Project::Work Packages::Telescope::WorkPackages::Control::Alignment and Phasing System::Systems Engineering::10 Analysis::Duration Analyses::Automatic Duration Analysis.

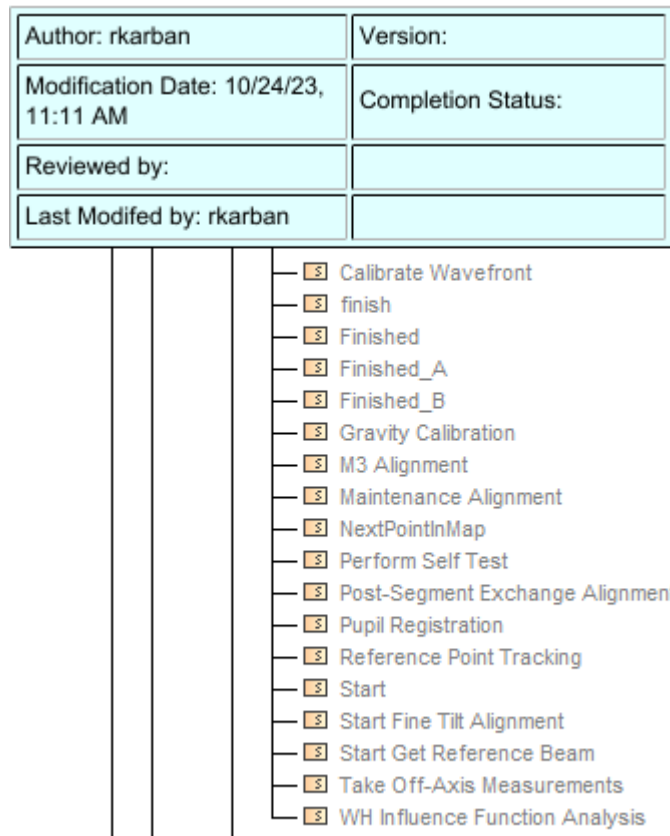
## Post-Segment Exchange Duration Scenario



To simulate an operator initiating a particular operational scenario, signals must be injected that trigger appropriate behavior of the various components. Signals are sent from an Analysis Driver (the operator) to the Procedure Executive and Analysis Software. For all interactions of the Use Case Duration Scenarios, the asynch signals that must be sent in the exact order from the Analysis Driver are "Abort ", a Use Case specific signal, and "Abort". Duration constraints are specified between the each signal, and will vary depending on the Use Case.

For example, the Post-Segment Exchange Alignment signal is triggered in the Post-Segment Exchange Duration Scenario as seen above.

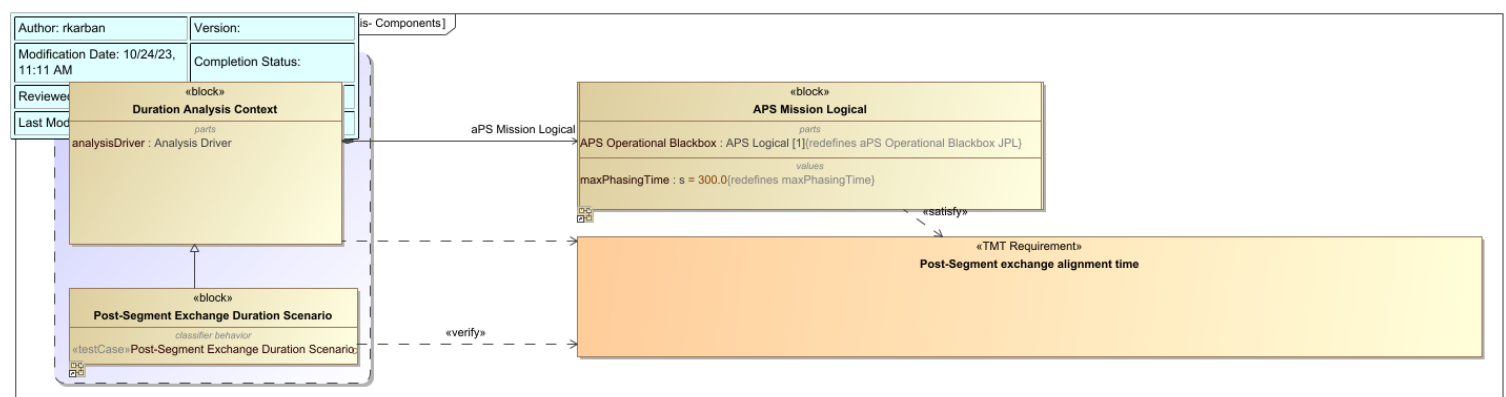
## Use Case Signals



## 5 Requirement Verification

The process for verifying TMT requirements is the following: formalization of requirements, defining an analysis context, connecting system value properties to constraint parameters, evaluating system configurations through analysis, verifying the system requirements, and capturing the verification test results.

## Duration Analysis- Components

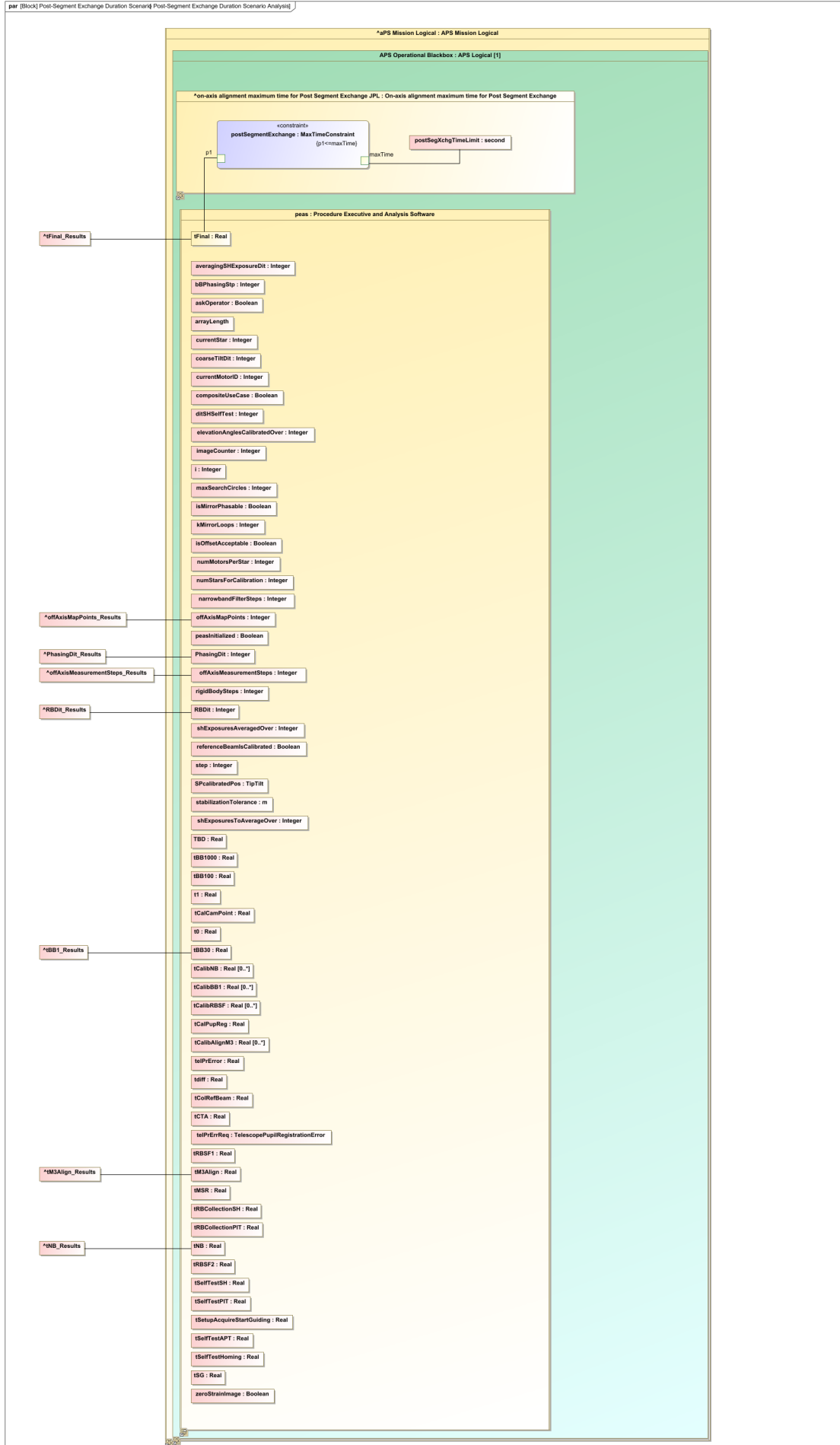


All Use Case Duration Scenario blocks that are described in Defining Behavior in Sequence Diagrams specialize the Duration Analysis Context block, and inherit its owned behavior. The Duration Analysis Context owns a part, Analysis Driver, which acts as an operator in the interaction of the Use Case



Duration Scenarios. If a use case should verify a requirement a <<verify>> relation should exist between the Test Case and the Requirement. This is demonstrated in the above diagram. The APS Requirements can be found in the model at the following location: TMT::Project::Work Packages::Project Systems Engineering::01 Components::Operational::TMT Observatory System::Black Box Specification::TMT Requirements imported from DOORS::APS::APS Requirements.

# Post-Segment Exchange Duration Scenario Analysis



All Use Case Duration Scenarios should own a parametric diagram. The purpose of the Use Case duration scenarios is to determine the final time and overall duration of a particular use case. Therefore, each duration scenario block should own a parametric diagram. Depending on the use case, the tFinal value property of the Procedure Executive and Analysis Software could be constrained to a constraint of the APS Operational Blackbox for requirement verification purposes. All current and future constraints in APS should be found in the model at the following location: TMT::Project::Work Packages::Telescope::WorkPackages::Control::Alignment and Phasing System::Systems Engineering::01 Components::Operational::APS::Black Box Specification::Requirements::10 Formalized Requirements.

## 6 Simulation Components

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The operational scenario blocks, sequence diagrams, parametric diagrams, and simulation configurations can be found in the model at the following location: TMT::02 JPL::System Model::APS::02 APS Analyses::Duration Analyses::Automatic Duration Analysis.

### Use Case Simulation Configurations

Author: rkarban	Version:	
Modification Date: 10/24/23, 11:11 AM	Completion Status:	«SimulationConfig»
Reviewed by:		«SimulationConfig»
Last Modified by: rkarban		«SimulationConfig»

APS Reference Point Tracking Duration Analysis «SimulationConfig»APS Self Test Duration Analysis «SimulationConfig»APS Warping Harness Influence Function Analysis Duration Analysis «SimulationConfig»APS Wavefront Calibration Duration Analysis «SimulationConfig»

A simulation configuration is created for each Alignment and Phasing System (APS) Use Case. The naming convention for the simulation configurations are "APS" + Use Case name + "Duration Analysis". The execution targets of the simulation configurations are the Use Case Duration Scenario blocks.

## Use Case Simulation Configuration Specifications

Author: rkarban	Version:	Document Exchange Duration Analysis [Read-Only] <span style="float: right;">✕</span>	
Modification Date: 10/24/23, 11:11 AM	Completion Status:	<div style="border: 1px solid #ccc; padding: 5px; margin-bottom: 10px;">             e properties specification table. Choose the more properties.             <div style="border: 1px solid #ccc; width: 100px; height: 100px; margin: 10px auto; position: relative;"> <span style="position: absolute; top: -10px; right: -10px; background: white; padding: 2px;">✎</span> </div> </div>	
Reviewed by:			
Last Modified by: rkarban			

✕
APS Post Segment Exchange Duration Analysis

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🔍
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Properties: All

- Web Server Properties
- Traceability
- Timing Properties
- Usage in Diagrams
- Usage In
- Documentation/Hyperlink
- Attributes
- Ports
- Operations
- Signal Receptions
- Behaviors
- Template Parameters
- Inner Elements
- Relations
- Tags
- Constraints
- Instances
- Language Properties

📄
🔍
🔄

Properties: All

Simulation Configuration
APS Post Segment Exchange Duration Analysis

Name	Post-Segment Exchange Duration Scena...
Execution Target	<span style="background-color: #f0f0f0;"> </span> Post-Segment Exchange Duration Scena...
Auto Start	<input checked="" type="checkbox"/> true
Silent	<input checked="" type="checkbox"/> true
Result Location	<span style="background-color: #f0f0f0;"> </span> Post-Segment Exchange [TMT::Project::W...
Animation Speed	<undefined>
UI	
Execution Listeners	
Solve After Initialization	<input type="checkbox"/> <undefined>
Clone References	<input checked="" type="checkbox"/> true
Constraint Failure As Breakpoint	<input type="checkbox"/> false
Decimal Places	<undefined>
Fire Value Change Event	<input checked="" type="checkbox"/> true
Initialize References	<input type="checkbox"/> false
Run Forks In Parallel	<input checked="" type="checkbox"/> true
Treat All Classifiers As Active	<input checked="" type="checkbox"/> true
Autostart Active Objects	<input checked="" type="checkbox"/> true
Engines Priority	
Log	

**Clone References**

If true, create new instances for all objects recursively, if not, only first level - others remain in original locations.

⏪  ⏩

Close
Back
Forward
Help

In the specification of the simulation configuration, it must be decided whether the simulation should run Silent or using animations. The decision to run the simulation with or without animations can affect the values of the value properties. The choice to run with or without animations can be determined by executing a Use Case and evaluating whether the output aligns with the expected values for the Use Case. For example, the Post Segment Exchange Duration Analysis simulation configuration has been specified to run Silent.

Use Case Simulation Configuration Timing Properties

Author: rkarban	Version:
Modification Date: 10/24/23, 11:11 AM	Completion Status:
Reviewed by:	
Last Modified by: rkarban	

APS Maintenance Alignment Duration Analysis [Rea... X]

Timing Properties

APS Maintenance Alignment

Web Server Properties

Traceability

Timing Properties

Usage in Diagrams

Usage In

Documentation/Hyperlin

Attributes

Ports

Operations

Signal Receptions

Behaviors

Template Parameters

Inner Elements

Relations

Tags

Constraints

Instances

Language Properties

Timing Properties

Clock ratio	
Start Time	0
End Time	<undefined>
Step Delay	0.1
Step Size	1.0
Time Unit	second
Time Value	
Time Variable Name	simtime
Number Of Steps	<undefined>
Duration Simulation Mode	max

(Name)  
(Description)

Type here to filter properties

Close

Back

Forward

Help

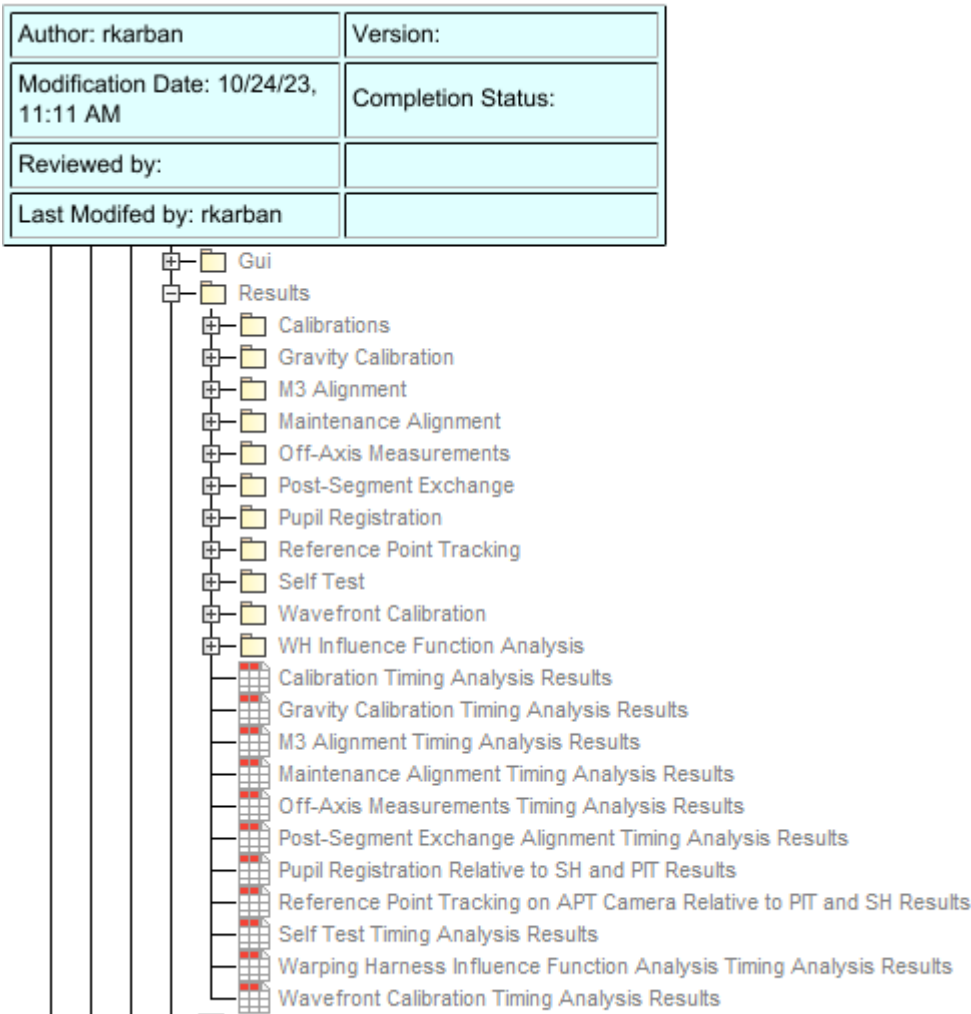
The timing properties of the Use Case simulation configurations must also be specified. The following should be configured in order to complete the simulation configuration set up. The Step Delay property should be specified and the value varies for each Use Case. The Step Delay ranges between .01 to .15. The Step Size property for all simulation configurations should be set to 1.0. The Time Unit property should be specified as "second". For example, the APS Maintenance Alignment Duration Analysis is configured to have a Step Delay of 0.1 and a Step Size of 1.0.

7 Evaluating Results

Through simulation, the conceptual design is automatically evaluated, and verifies whether the system conforms to a requirement. The exposed instance tables display whether the instances have passed or failed a requirement. The values of the resulting instances should be identical or have minimal differences. Therefore, the simulation is run more than once to confirm that the values can be reproduced.

In addition, a manual baseline estimation should be available for comparison to ensure there are no model, simulation, or tooling errors.

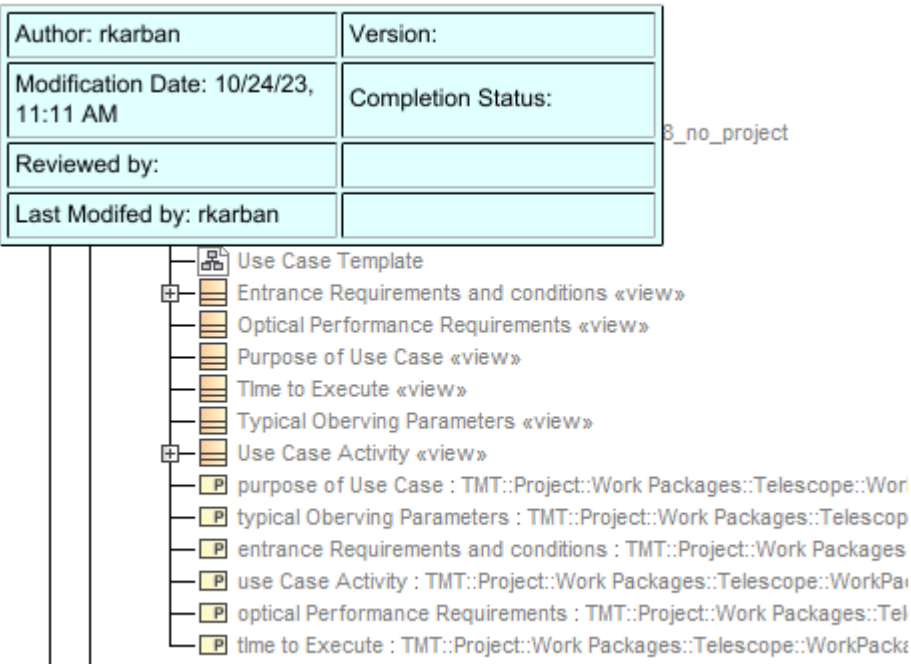
Analysis Results



8 Document Generation

The model development kit (MDK) is utilized to sync the TMT model with the model management system (MMS) and implement the DocGen language, which allows for document generation using the view and viewpoint concept. The standard view structure for a TMT use case is composed of the following views: Purpose of use case, Typical observing parameters, Entrance requirements and conditions, Use Case activity, Optical Performance Requirements, and Time to Execute. In MagicDraw, views are created using a template, and expose diagrams containing simulation results and key activities. The documentation of the Use Case is done within ViewEditor.

Use Case Template



The Use Case Template can be found in the model at the following location:TMT::Project::Work Packages::Telescope::WorkPackages::Control::Alignment and Phasing System::Systems Engineering::09 Views::TMT-APS-SE::TMT-APS Use Cases::Templates::Use Case Template

9 Overview of Components

In conclusion all the components that should be created include:

A BDD that displays all components of a PEAS Use Case should be created in the model at the following location: TMT::02 JPL::System Model::APS::02 APS Analyses::Duration Analyses.

This should include the Duration Scenario, Duration Analysis Context, APS Mission Conceptual, the Use Case parametric diagram (if needed), the appropriate TMT Requirement (if needed), the Use Case instance table, and the Use Case simulation configuration. Refer to the below diagram as an example.

An example template workflow is provided for reference at this location: TMT::02 JPL::System Model::APS::02 APS Analyses::Duration Analyses::Automatic Duration Analysis::Template.

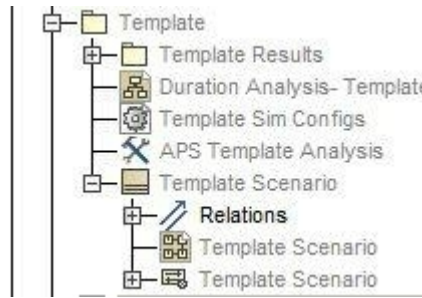
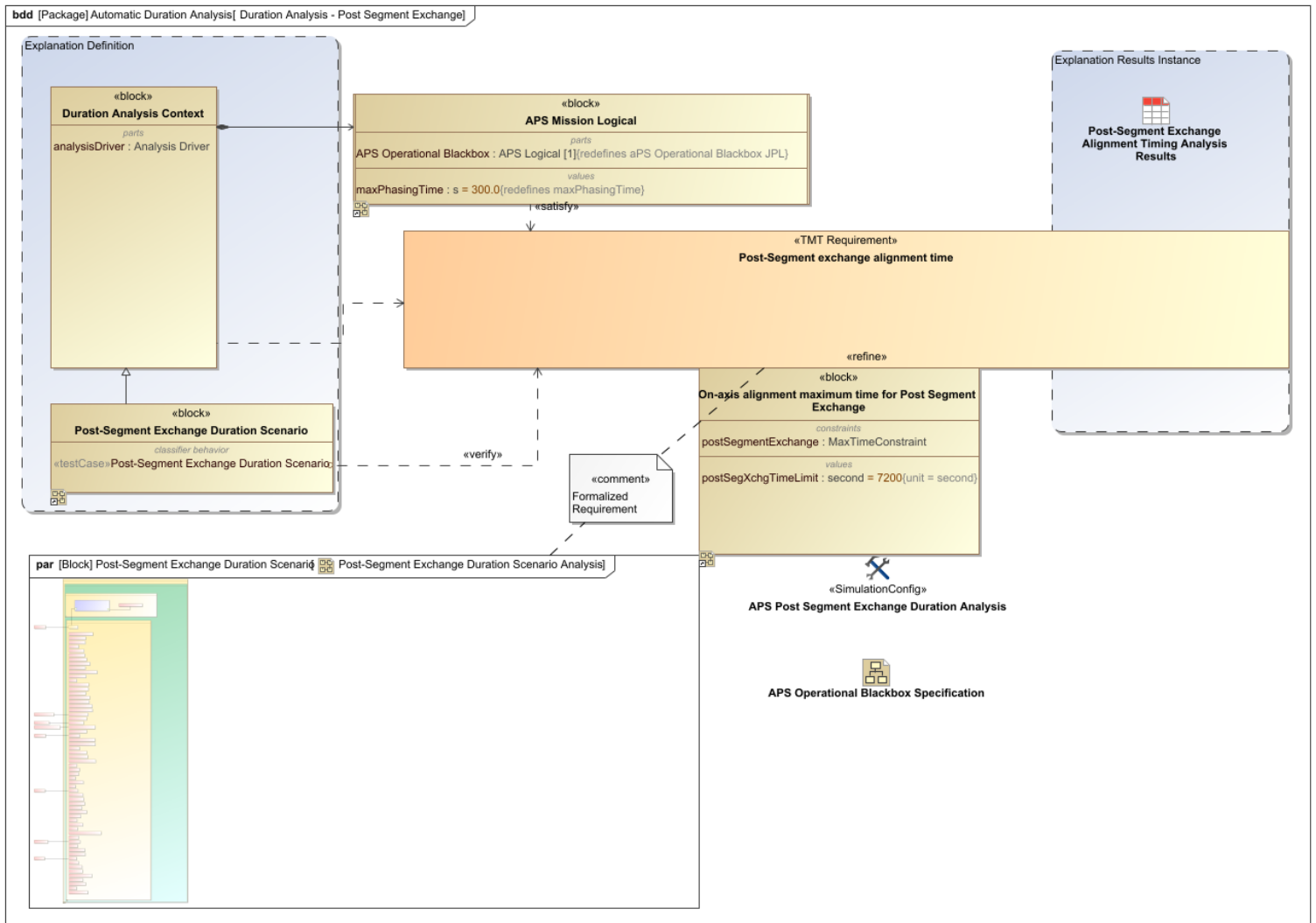


Fig. 1 Template Workflow

## Duration Analysis - Post Segment Exchange



The duration performance of the Logical design is analyzed w/r/t to the black box specification.