

ALGORITHM *Height(T)*
 //Computes recursively the height of a binary tree
 //Input: A binary tree *T*
 //Output: The height of *T*
 if *T* = ∅ return -1
 else return max(*Height(T_{left})*, *Height(T_{right})*) + 1

ALGORITHM *Mergesort(A[0..n-1])*
 //Sorts array *A[0..n-1]* by recursive mergesort
 //Input: An array *A[0..n-1]* of orderable elements
 //Output: Array *A[0..n-1]* sorted in nondecreasing order
 if *n* > 1
 copy *A[0..[n/2]-1]* to *B[0..[n/2]-1]*
 copy *A[[n/2]..n-1]* to *C[0..[n/2]-1]*
 Mergesort(B[0..[n/2]-1])
 Mergesort(C[0..[n/2]-1])
 Merge(B, C, A) //see below

ALGORITHM *Merge(B[0..p-1], C[0..q-1], A[0..p+q-1])*
 //Merges two sorted arrays into one sorted array
 //Input: Arrays *B[0..p-1]* and *C[0..q-1]* both sorted
 //Output: Sorted array *A[0..p+q-1]* of the elements of *B* and *C*
i ← 0; *j* ← 0; *k* ← 0
 while *i* < *p* and *j* < *q* do
 if *B[i]* ≤ *C[j]*
 A[k] ← *B[i]*; *i* ← *i* + 1
 else *A[k]* ← *C[j]*; *j* ← *j* + 1
 k ← *k* + 1
 if *i* = *p*
 copy *C[j..q-1]* to *A[k..p+q-1]*
 else copy *B[i..p-1]* to *A[k..p+q-1]*

ALGORITHM *BFS(G)*
 //Implements a breadth-first search traversal of a given graph
 //Input: Graph *G* = (*V*, *E*)
 //Output: Graph *G* with its vertices marked with consecutive integers
 // in the order they are visited by the BFS traversal
 mark each vertex in *V* with 0 as a mark of being "unvisited"
 count ← 0
 for each vertex *v* in *V* do
 if *v* is marked with 0
 bfs(v)

bfs(v)
 //visits all the unvisited vertices connected to vertex *v*
 //by a path and numbers them in the order they are visited
 //via global variable count
 count ← count + 1; mark *v* with count and initialize a queue with *v*
 while the queue is not empty do
 for each vertex *w* in *V* adjacent to the front vertex do
 if *w* is marked with 0
 count ← count + 1; mark *w* with count
 add *w* to the queue
 remove the front vertex from the queue

ALGORITHM *BinRec(n)*
 //Input: A positive decimal integer *n*
 //Output: The number of binary digits in *n*'s binary representation
 if *n* = 1 return 1
 else return *BinRec([n/2])* + 1

ALGORITHM *SequentialSearch(A[0..n-1], K)*
 //Searches for a given value in a given array by sequential search
 //Input: An array *A[0..n-1]* and a search key *K*
 //Output: The index of the first element in *A* that matches *K*
 // or -1 if there are no matching elements
i ← 0
 while *i* < *n* and *A[i]* ≠ *K* do
 i ← *i* + 1
 if *i* < *n* return *i*
 else return -1

ALGORITHM *HoarePartition(A[l..r])*
 //Partitions a subarray by Hoare's algorithm, using the first element
 // as a pivot
 //Input: Subarray of array *A[0..n-1]*, defined by its left and right
 // indices *l* and *r* (*l* < *r*)
 //Output: Partition of *A[l..r]*, with the split position returned as
 // this function's value
p ← *A[l]*
i ← *l*; *j* ← *r* + 1
 repeat
 repeat *i* ← *i* + 1 until *A[i]* ≥ *p*
 repeat *j* ← *j* - 1 until *A[j]* ≤ *p*
 swap(*A[i]*, *A[j]*)
 until *i* ≥ *j*
 swap(*A[i]*, *A[j]*) //undo last swap when *i* ≥ *j*
 swap(*A[l]*, *A[j]*)
 return *j*

ALGORITHM *Quickselect(A[l..r], k)*
 //Solves the selection problem by recursive partition-based algorithm
 //Input: Subarray *A[l..r]* of array *A[0..n-1]* of orderable elements and
 // integer *k* (1 ≤ *k* ≤ *r* - *l* + 1)
 //Output: The value of the *k*th smallest element in *A[l..r]*
s ← *LomutoPartition(A[l..r])* //or another partition algorithm
 if *s* = *k* - 1 return *A[s]*
 else if *s* > *l* + *k* - 1 Quickselect(*A[l..s-1]*, *k*)
 else Quickselect(*A[s+1..r]*, *k* - 1 - *s*)

ALGORITHM *BinarySearch(A[0..n-1], K)*
 //Implements nonrecursive binary search
 //Input: An array *A[0..n-1]* sorted in ascending order and
 // a search key *K*
 //Output: An index of the array's element that is equal to *K*
 // or -1 if there is no such element
l ← 0; *r* ← *n* - 1
 while *l* ≤ *r* do
 m ← (*l* + *r*) / 2
 if *K* = *A[m]* return *m*
 else if *K* < *A[m]* *r* ← *m* - 1
 else *l* ← *m* + 1
 return -1

ALGORITHM *BruteForceClosestPair(P)*
 //Finds distance between two closest points in the plane by brute force
 //Input: A list *P* of *n* (*n* ≥ 2) points *p₁(x₁, y₁), ..., p_n(x_n, y_n)*
 //Output: The distance between the closest pair of points
d ← ∞
 for *i* ← 1 to *n* - 1 do
 for *j* ← *i* + 1 to *n* do
 d ← min(*d*, sqrt((x_i - x_j)² + (y_i - y_j)²)) //sqrt is square root
 return *d*

ALGORITHM *BubbleSort(A[0..n-1])*
 //Sorts a given array by bubble sort
 //Input: An array *A[0..n-1]* of orderable elements
 //Output: Array *A[0..n-1]* sorted in nondecreasing order
 for *i* ← 0 to *n* - 2 do
 for *j* ← 0 to *n* - 2 - *i* do
 if *A[j+1]* < *A[j]* swap *A[j]* and *A[j+1]*

ALGORITHM *UniqueElements(A[0..n-1])*
 //Determines whether all the elements in a given array are distinct
 //Input: An array *A[0..n-1]*
 //Output: Returns "true" if all the elements in *A* are distinct
 // and "false" otherwise
 for *i* ← 0 to *n* - 2 do
 for *j* ← *i* + 1 to *n* - 1 do
 if *A[i]* = *A[j]* return false
 return true

ALGORITHM *Quicksort(A[l..r])*
 //Sorts a subarray by quicksort
 //Input: Subarray of array *A[0..n-1]*, defined by its left and right
 // indices *l* and *r*
 //Output: Subarray *A[l..r]* sorted in nondecreasing order
 if *l* < *r*
 s ← *Partition(A[l..r])* //s is a split position
 Quicksort(A[l..s-1])
 Quicksort(A[s+1..r])

ALGORITHM *LomutoPartition(A[l..r])*
 //Partitions subarray by Lomuto's algorithm using first element as pivot
 //Input: A subarray *A[l..r]* of array *A[0..n-1]*, defined by its left and right
 // indices *l* and *r* (*l* ≤ *r*)
 //Output: Partition of *A[l..r]* and the new position of the pivot
p ← *A[l]*
s ← *l*
 for *i* ← *l* + 1 to *r* do
 if *A[i]* < *p*
 s ← *s* + 1; swap(*A[s]*, *A[i]*)
 swap(*A[l]*, *A[s]*)
 return *s*

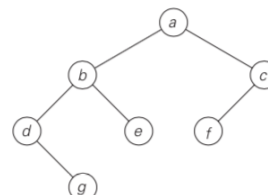
ALGORITHM *InsertionSort(A[0..n-1])*
 //Sorts a given array by insertion sort
 //Input: An array *A[0..n-1]* of *n* orderable elements
 //Output: Array *A[0..n-1]* sorted in nondecreasing order
 for *i* ← 1 to *n* - 1 do
 v ← *A[i]*
 j ← *i* - 1
 while *j* ≥ 0 and *A[j]* > *v* do
 A[j+1] ← *A[j]*
 j ← *j* - 1
 A[j+1] ← *v*

ALGORITHM *BruteForceStringMatch(T[0..n-1], P[0..m-1])*
 //Implements brute-force string matching
 //Input: An array *T[0..n-1]* of *n* characters representing a text and
 // an array *P[0..m-1]* of *m* characters representing a pattern
 //Output: The index of the first character in the text that starts a
 // matching substring or -1 if the search is unsuccessful
 for *i* ← 0 to *n* - *m* do
 j ← 0
 while *j* < *m* and *P[j]* = *T[i+j]* do
 j ← *j* + 1
 if *j* = *m* return *i*
 return -1

ALGORITHM *SelectionSort(A[0..n-1])*
 //Sorts a given array by selection sort
 //Input: An array *A[0..n-1]* of orderable elements
 //Output: Array *A[0..n-1]* sorted in nondecreasing order
 for *i* ← 0 to *n* - 2 do
 min ← *i*
 for *j* ← *i* + 1 to *n* - 1 do
 if *A[j]* < *A[min]* min ← *j*
 swap *A[i]* and *A[min]*

ALGORITHM *MatrixMultiplication(A[0..n-1, 0..n-1], B[0..n-1, 0..n-1])*
 //Multiplies two square matrices of order *n* by the definition-based algorithm
 //Input: Two *n* × *n* matrices *A* and *B*
 //Output: Matrix *C* = *A* * *B*
 for *i* ← 0 to *n* - 1 do
 for *j* ← 0 to *n* - 1 do
 C[i, j] ← 0
 for *k* ← 0 to *n* - 1 do
C[i, j] ← *C[i, j]* + *A[i, k]* * *B[k, j]*
 return *C*

Algorithm	Time Complexity			Space Complexity
	Best	Average	Worst	Worst
Quicksort	$O(n \log(n))$	$O(n \log(n))$	$O(n^2)$	$O(\log(n))$
Mergesort	$O(n \log(n))$	$O(n \log(n))$	$O(n \log(n))$	$O(n)$
Timsort	$O(n)$	$O(n \log(n))$	$O(n \log(n))$	$O(n)$
Heapsort	$O(n \log(n))$	$O(n \log(n))$	$O(n \log(n))$	$O(1)$
Bubble Sort	$O(n)$	$O(n^2)$	$O(n^2)$	$O(1)$
Insertion Sort	$O(n)$	$O(n^2)$	$O(n^2)$	$O(1)$
Selection Sort	$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(1)$
Tree Sort	$O(n \log(n))$	$O(n \log(n))$	$O(n^2)$	$O(n)$
Shell Sort	$O(n \log(n))$	$O(n(\log(n))^2)$	$O(n(\log(n))^2)$	$O(1)$
Bucket Sort	$O(n+k)$	$O(n+k)$	$O(n^2)$	$O(n)$
Radix Sort	$O(nk)$	$O(nk)$	$O(nk)$	$O(n+k)$
Counting Sort	$O(n+k)$	$O(n+k)$	$O(n+k)$	$O(k)$
Cubesort	$O(n)$	$O(n \log(n))$	$O(n \log(n))$	$O(n)$



preorder: *a, b, d, g, e, c, f*
 inorder: *d, g, b, e, a, f, c*
 postorder: *g, d, e, b, f, c, a*

