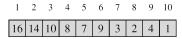
Algorithms

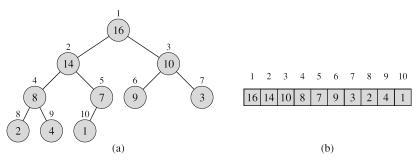
Heaps and priority queues

Emanuele Rodolà rodola@di.uniroma1.it

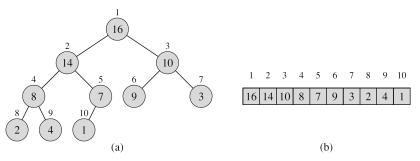


$$(1,2,3,4,9,10,7,16,8,14) \qquad \xrightarrow{\text{build}} \qquad \boxed{16\,\, |\, 4\,\, |\, 10\,\, |\, 8\,\, |\,\, 7\,\, |\,\, 9\,\, |\,\, 3\,\, |\,\, 2\,\, |\,\, 4\,\, |\,\, 1}$$



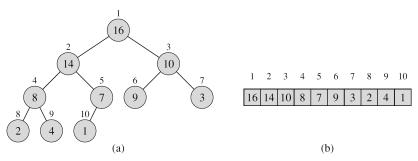


- left(i) = 2i
- right(i) = 2i + 1



- left(i) = 2i
- right(i) = 2i + 1
- parent $(i) = \lfloor i/2 \rfloor$

Data structures allow us to organize data for efficient use.

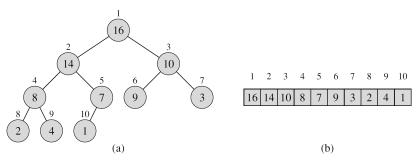


max-heap property:

$$A[\operatorname{parent}(i)] \geq A[i]$$

which means that root = largest element.

Data structures allow us to organize data for efficient use.

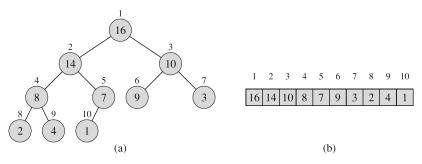


min-heap property:

$$A[\operatorname{parent}(i)] \leq A[i]$$

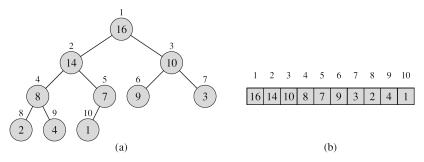
which means that root = smallest element.

Data structures allow us to organize data for efficient use.



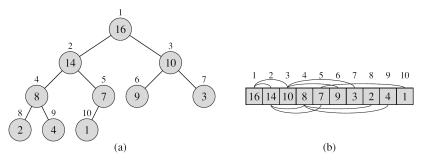
height of a node: # edges of the longest path to a leaf

Data structures allow us to organize data for efficient use.



height of a node: # edges of the longest path to a leaf height of the heap = height of the root = $\Theta(\lg n)$

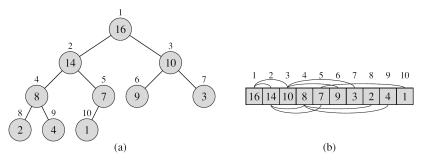
Data structures allow us to organize data for efficient use.



The heap can be seen as a binary tree or as an array.

Неар

Data structures allow us to organize data for efficient use.

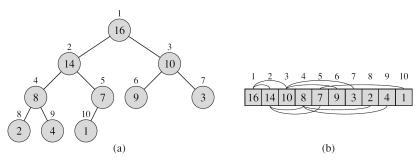


The heap can be seen as a binary tree or as an array.

Each level (except the last one) must be filled completely left-to-right.

Неар

Data structures allow us to organize data for efficient use.

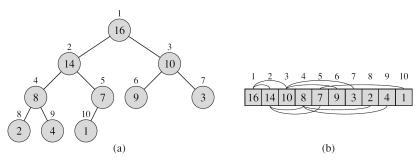


The heap can be seen as a binary tree or as an array.

Each level (except the last one) must be filled completely left-to-right.

The number of leaves is $n - \lfloor \frac{n}{2} \rfloor$.

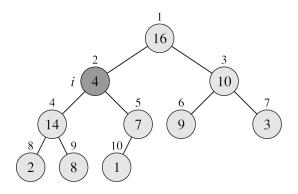
Data structures allow us to organize data for efficient use.



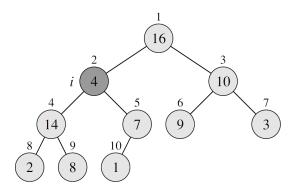
We will see the following operations:

- Build a (max-)heap from some input array.
- Maintain the (max-)heap property.
- Construct a priority queue on top of a heap.

We are given as input the root index i of the sub-tree to check.

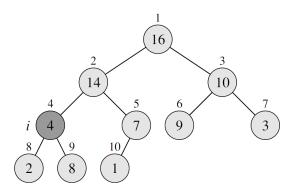


We are given as input the root index i of the sub-tree to check.



Assumption: left(i) and right(i) are roots of valid heaps.

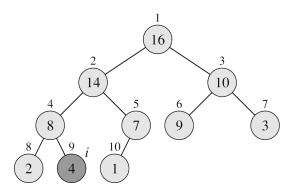
We are given as input the root index i of the sub-tree to check.



Assumption: left(i) and right(i) are roots of valid heaps.

Recursively exchange the violating node with its largest child.

We are given as input the root index i of the sub-tree to check.



Assumption: left(i) and right(i) are roots of valid heaps.

Recursively exchange the violating node with its largest child.

```
Max-Heapify(A, i)
 1 l \leftarrow \text{LEFT}(i)
 2 r \leftarrow RIGHT(i)
 3 if l \le heap\text{-}size[A] and A[l] > A[i]
 4
         then largest \leftarrow l
         else largest \leftarrow i
     if r \leq heap\text{-}size[A] and A[r] > A[largest]
         then largest \leftarrow r
 8
     if largest \neq i
 9
         then exchange A[i] \leftrightarrow A[largest]
10
                MAX-HEAPIFY(A, largest)
```

If A[i] is the largest, then the sub-tree is already a max heap.

```
\Theta(1) \begin{tabular}{lll} $1$ & $l \leftarrow \operatorname{LEFT}(i)$ \\ $2$ & $r \leftarrow \operatorname{RIGHT}(i)$ \\ $3$ & $\mathbf{if} \ l \leq heap\text{-}size[A] \ \text{and} \ A[l] > A[i]$ \\ $4$ & $\mathbf{then} \ largest \leftarrow l$ \\ $5$ & $\mathbf{else} \ largest \leftarrow i$ \\ $6$ & $\mathbf{if} \ r \leq heap\text{-}size[A] \ \text{and} \ A[r] > A[largest]$ \\ $7$ & $\mathbf{then} \ largest \leftarrow r$ \\ $8$ & $\mathbf{if} \ largest \neq i$ \\ $9$ & $\mathbf{then} \ \text{ovelow}. \end{tabular}
                                   Max-Heapify(A, i)
                                                                   then exchange A[i] \leftrightarrow A[largest]
                                    10
                                                                                           MAX-HEAPIFY(A, largest)
```

```
Max-Heapify(A, i)
                        \Theta(1) \begin{vmatrix} 1 & l \leftarrow \text{LEFT}(i) \\ 2 & r \leftarrow \text{RIGHT}(i) \\ 3 & \text{if } l \leq heap\text{-}size[A] \text{ and } A[l] > A[i] \\ 4 & \text{then } largest \leftarrow l \\ 5 & \text{else } largest \leftarrow i \\ 6 & \text{if } r \leq heap\text{-}size[A] \text{ and } A[r] > A[largest] \\ 7 & \text{then } largest \leftarrow r \\ 8 & \text{if } largest \neq i \\ 9 & \text{then } \text{exchange } A[i] \leftrightarrow A[largest] \\ 0 & \text{then } \text{exchange } A[i] \leftrightarrow A[largest] \end{vmatrix}
T(2n/3) \rightarrow 10 Max-Heapify (A, largest)
```

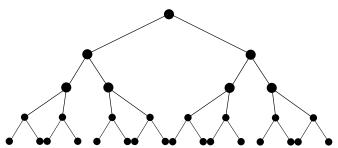
```
Max-Heapify(A, i)
                                                                                                    \Theta(1) \begin{tabular}{lll} $1$ &$l \leftarrow \operatorname{LEFT}(i)$ \\ $2$ &$r \leftarrow \operatorname{RIGHT}(i)$ \\ $3$ &$\textbf{if } l \leq heap\text{-}size[A] \text{ and } A[l] > A[i]$ \\ $4$ &$\textbf{then } largest \leftarrow l$ \\ $5$ &$\textbf{else } largest \leftarrow i$ \\ $6$ &$\textbf{if } r \leq heap\text{-}size[A] \text{ and } A[r] > A[largest]$ \\ $7$ &$\textbf{then } largest \leftarrow r$ \\ $8$ &$\textbf{if } largest \neq i$ \\ $9$ &$\textbf{then } \operatorname{exchange } A[i] \leftrightarrow A[largest]$ \\ $\theta(2) > 10$ &$\text{May Heapter}(A, largest)$ \\ $\theta(3) > 10$ &$\text{May Heapter}(A, largest)$ \\ $\theta(4) > 10
T(2n/3) \rightarrow 10 MAX-HEAPIFY (A, largest)
```

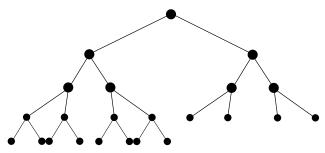
$$T(n) \le T(2n/3) + \Theta(1)$$

```
Max-Heapify(A, i)
\Theta(1) \begin{vmatrix} 1 & l \leftarrow \text{LEFT}(i) \\ 2 & r \leftarrow \text{RIGHT}(i) \\ 3 & \text{if } l \leq heap\text{-}size[A] \text{ and } A[l] > A[i] \\ 4 & \text{then } largest \leftarrow l \\ 5 & \text{else } largest \leftarrow i \\ 6 & \text{if } r \leq heap\text{-}size[A] \text{ and } A[r] > A[largest] \\ 7 & \text{then } largest \leftarrow r \\ 8 & \text{if } largest \neq i \\ 9 & \text{then } \text{exchange } A[i] \leftrightarrow A[largest] \\ T(2n/3) \rightarrow 10 & \text{MAX-HEAPIFY}(A, largest) \end{vmatrix}
```

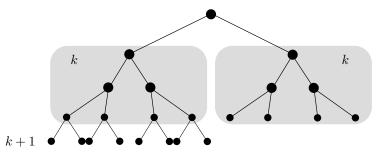
$$T(n) = O(\lg n)$$

by case (2) of the master theorem.

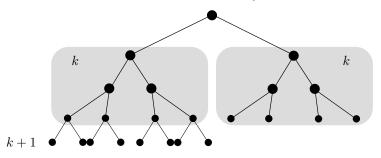




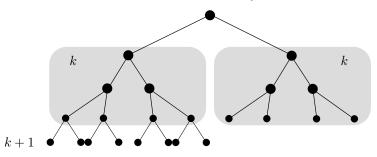
• A valid heap tree must be completely filled at each level.



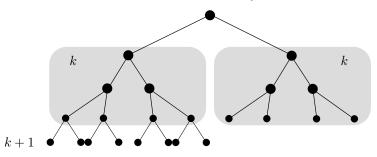
- A valid heap tree must be completely filled at each level.
- \bullet The largest sub-tree has $\leq k+(k+1)$ nodes.



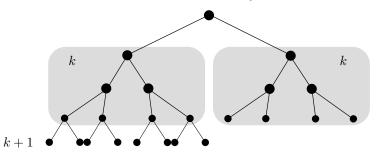
- A valid heap tree must be completely filled at each level.
- \bullet The largest sub-tree has $\leq 2k+1$ nodes.



- A valid heap tree must be completely filled at each level.
- The largest sub-tree has $\leq 2k+1$ nodes.
- $\bullet \ \ \text{The entire tree has} \ n=1+2k+(k+1)=3k+2 \ \text{nodes}.$



- A valid heap tree must be completely filled at each level.
- The largest sub-tree has $\leq 2k+1$ nodes.
- The entire tree has n=1+2k+(k+1)=3k+2 nodes.
- Thus, the largest sub-tree has $\leq \frac{2k+1}{3k+2}n$ nodes.

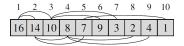


- A valid heap tree must be completely filled at each level.
- The largest sub-tree has $\leq 2k+1$ nodes.
- The entire tree has n = 1 + 2k + (k+1) = 3k + 2 nodes.
- Thus, the largest sub-tree has $\leq \frac{2k+1}{3k+2}n$ nodes.
- For arbitrary k, we get $\lim_{k\to\infty}\frac{2k+1}{3k+2}n=\frac{2}{3}n$.

How to convert a given input array into a (max-)heap?

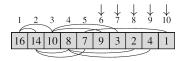
How to convert a given input array into a (max-)heap?

The leaf indices are known a priori: $(\lfloor n/2 \rfloor + 1) \cdots n$



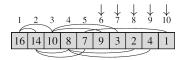
How to convert a given input array into a (max-)heap?

The leaf indices are known a priori: $(|n/2|+1)\cdots n$



How to convert a given input array into a (max-)heap?

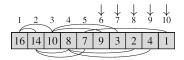
The leaf indices are known a priori: $(|n/2|+1)\cdots n$



General idea: run max-heapify on the internal nodes.

How to convert a given input array into a (max-)heap?

The leaf indices are known a priori: $(\lfloor n/2 \rfloor + 1) \cdots n$



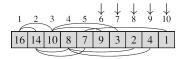
General idea: run max-heapify on the internal nodes.

BUILD-MAX-HEAP(
$$A$$
)

- 1 heap- $size[A] \leftarrow length[A]$
- 2 **for** $i \leftarrow \lfloor length[A]/2 \rfloor$ **downto** 1
- 3 **do** Max-Heapify(A, i)

How to convert a given input array into a (max-)heap?

The leaf indices are known a priori: $(\lfloor n/2 \rfloor + 1) \cdots n$



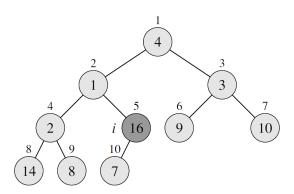
General idea: run max-heapify on the internal nodes.

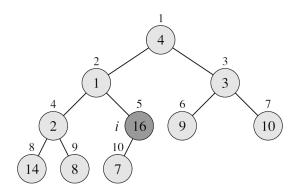
BUILD-MAX-HEAP(
$$A$$
)

- 1 heap- $size[A] \leftarrow length[A]$
- 2 **for** $i \leftarrow \lfloor length[A]/2 \rfloor$ **downto** 1
- 3 **do** MAX-HEAPIFY (A, i)

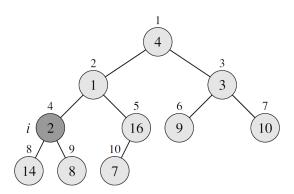
O(n) calls to a $O(\lg n)$ algorithm: $T(n) = O(n \lg n)$.

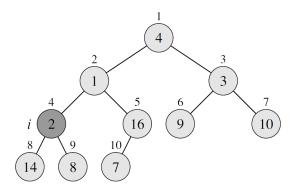
A 4 1 3 2 16 9 10 14 8 7



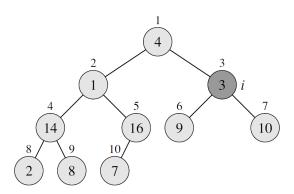


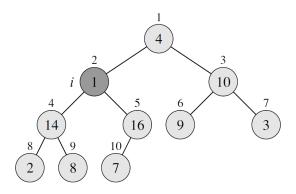
The sub-tree is already a heap.





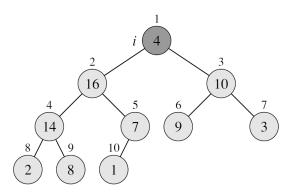
The sub-tree does not satisfy the heap property – run heapify.





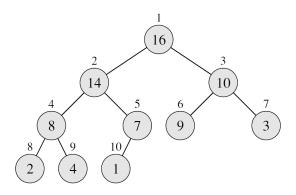
By proceeding bottom-up, we can always run heapify, which assumes that the sub-trees rooted at $\operatorname{left}(i)$ and $\operatorname{right}(i)$ are valid.

This way, after heapify we can guarantee that i is the root of a heap.



By proceeding bottom-up, we can always run heapify, which assumes that the sub-trees rooted at $\operatorname{left}(i)$ and $\operatorname{right}(i)$ are valid.

This way, after heapify we can guarantee that i is the root of a heap.



By proceeding bottom-up, we can always run heapify, which assumes that the sub-trees rooted at $\operatorname{left}(i)$ and $\operatorname{right}(i)$ are valid.

This way, after heapify we can guarantee that i is the root of a heap.

Example:

Let us be given a set of tasks, each with a priority.

When a task is done, pass to the next with highest priority.

Example:

Let us be given a set of tasks, each with a priority. When a task is done, pass to the next with highest priority.

A priority queue is an efficient data structure to do this.

Example:

Let us be given a set of tasks, each with a priority. When a task is done, pass to the next with highest priority.

A priority queue is an efficient data structure to do this.

We need to support the following operations:

- Insert a new element + priority.
- Find the highest-priority element.
- Extract the highest-priority element.
- Increase the priority of a given element.

Example:

Let us be given a set of tasks, each with a priority.

When a task is done, pass to the next with highest priority.

A priority queue is an efficient data structure to do this.

We need to support the following operations:

- Insert a new element + priority.
- Find the highest-priority element.
- Extract the highest-priority element.
- Increase the priority of a given element.

We will implement the priority queue on top of a heap.

The heap stores the priority values of each element. In practice the element itself is also attached, but we ignore it here.

The heap stores the priority values of each element. In practice the element itself is also attached, but we ignore it here.

Find the highest priority element in $\Theta(1)$ time:

HEAP-MAXIMUM(A)1 **return** A[1]

The heap stores the priority values of each element. In practice the element itself is also attached, but we ignore it here.

Find the highest priority element in $\Theta(1)$ time:

HEAP-MAXIMUM(
$$A$$
)
1 return A [1]

Extract the highest-priority element in $O(\lg n)$ time:

```
HEAP-EXTRACT-MAX(A)

1 if heap-size[A] < 1

2 then error "heap underflow"

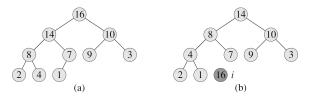
3 max \leftarrow A[1]
discard 4 A[1] \leftarrow A[heap-size[A]]
the root 5 heap-size[A] \leftarrow heap-size[A] - 1
6 MAX-HEAPIFY(A, 1)
7 return max
```

The heap stores the priority values of each element. In practice the element itself is also attached, but we ignore it here.

Find the highest priority element in $\Theta(1)$ time:

HEAP-MAXIMUM(
$$A$$
)
1 return A [1]

Extract the highest-priority element in $O(\lg n)$ time:



discarding the root

Increase the priority of a given element in $O(\lg n)$ time:

```
HEAP-INCREASE-KEY (A, i, key)

1 if key < A[i]

2 then error "new key is smaller than current key"

3 A[i] \leftarrow key

4 while i > 1 and A[PARENT(i)] < A[i]

5 do exchange A[i] \leftrightarrow A[PARENT(i)]

6 i \leftarrow PARENT(i)
```

Increase the priority of a given element in $O(\lg n)$ time:

```
HEAP-INCREASE-KEY(A, i, key)

1 if key < A[i]

2 then error "new key is smaller than current key"

3 A[i] \leftarrow key

4 while i > 1 and A[PARENT(i)] < A[i]

5 do exchange A[i] \leftrightarrow A[PARENT(i)]

6 i \leftarrow PARENT(i)
```

Line 3 can violate the max-heap property, depending on the value of key.

Increase the priority of a given element in $O(\lg n)$ time:

```
HEAP-INCREASE-KEY (A, i, key)

1 if key < A[i]

2 then error "new key is smaller than current key"

3 A[i] \leftarrow key

4 while i > 1 and A[PARENT(i)] < A[i]

5 do exchange A[i] \leftrightarrow A[PARENT(i)]

6 i \leftarrow PARENT(i)
```

Line 3 can violate the max-heap property, depending on the value of key.

If so, the correct index for key must be up in the tree.

Lines 4-6 find the correct index by moving the value in an upward path.

Insert a new element + priority in $O(\lg n)$ time:

MAX-HEAP-INSERT(A, key)

- 1 heap- $size[A] \leftarrow heap$ -size[A] + 1
- 2 $A[heap-size[A]] \leftarrow -\infty$
- 3 HEAP-INCREASE-KEY (A, heap-size[A], key)

Insert a new element + priority in $O(\lg n)$ time:

Max-Heap-Insert(A, key)

- 1 heap- $size[A] \leftarrow heap$ -size[A] + 1
- 2 $A[heap-size[A]] \leftarrow -\infty$
- 3 HEAP-INCREASE-KEY (A, heap-size[A], key)

The value of $-\infty$ ensures that line 1 of increase is false.

Insert a new element + priority in $O(\lg n)$ time:

Max-Heap-Insert(A, key)

- 1 heap- $size[A] \leftarrow heap$ -size[A] + 1
- 2 $A[heap-size[A]] \leftarrow -\infty$
- 3 HEAP-INCREASE-KEY (A, heap-size[A], key)

The value of $-\infty$ ensures that line 1 of increase is false.

To summarize:

operation	cost
find	$\Theta(1)$
extract	$O(\lg n)$
increase	$O(\lg n)$
insert	$O(\lg n)$

Suggested reading

Chapters 6.1, 6.2, 6.3 and 6.5 of:

"Introduction to Algorithms – 2nd Ed.", Cormen et al.