

Deep Learning & Applied AI

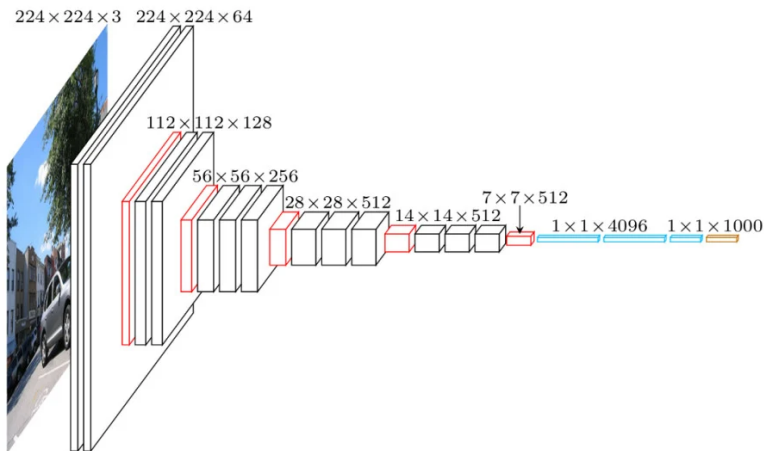
Multi-layer perceptron and back-propagation

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A glimpse into neural networks

In deep learning, we deal with **highly parametrized models** called **deep neural networks**:



Deep composition

The simplest example of a nonlinear parametric model:

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More in general, consider other **activation functions** than logistic:

$$\sigma(x) = \frac{1}{1 + e^{-x}} \qquad \sigma(x) = \max\{0, x\}$$

continuous

discontinuous
gradient

Multi-layer perceptron

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Remark: The **bias** can be included in the weight matrix by writing:

$$\mathbf{W} \mapsto (\mathbf{W} \quad \mathbf{b}) , \quad \mathbf{x} \mapsto \begin{pmatrix} \mathbf{x} \\ 1 \end{pmatrix} ,$$

because each f is **linear in the parameters** just like in linear regression.

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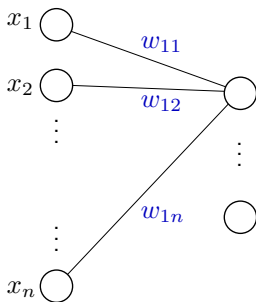
- 1 Each layer is a vector-to-vector function $\mathbb{R}^p \rightarrow \mathbb{R}^q$.
- 2 Each layer has q units acting **in parallel**.
Each unit acts as a scalar function $\mathbb{R}^p \rightarrow \mathbb{R}$.

Single layer illustration

$$\sigma(\mathbf{W}\mathbf{x}) = \sigma \circ \begin{pmatrix} w_{11} & w_{12} & \cdots & w_{1n} \\ w_{21} & w_{22} & \cdots & w_{2n} \\ \vdots & \cdots & \ddots & \vdots \\ w_{m1} & w_{m2} & \cdots & w_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \sigma \circ \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}$$

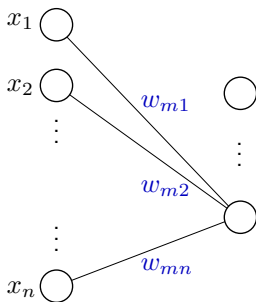
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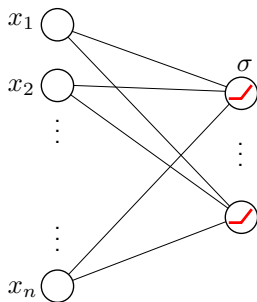
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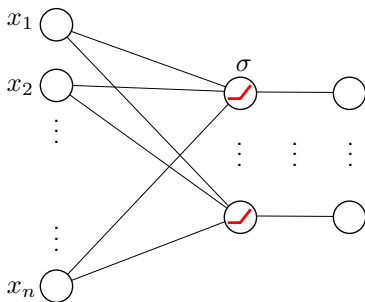
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For generality, it is common to have a **linear** layer at the output:

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Deep ReLU networks

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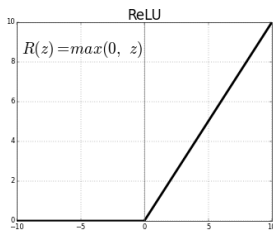
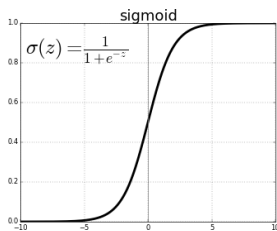
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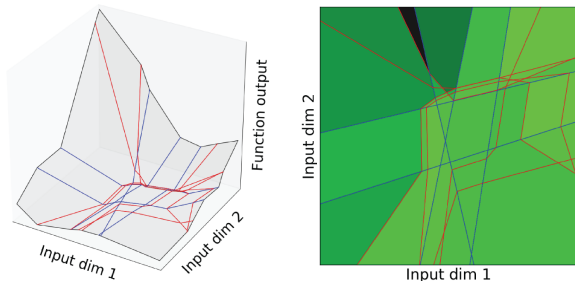
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The blue and red edges are produced by the **first** and **second** layer.

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Universal Approximation Theorem For any compact set $\Omega \subset \mathbb{R}^p$, the space spanned by the functions $\phi(\mathbf{x}) = \sigma(\mathbf{W}\mathbf{x} + \mathbf{b})$ is dense in $\mathcal{C}(\Omega)$ for the uniform convergence.

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For large enough q , the training error can be made **arbitrarily small**.

Training

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$$\ell_{\Theta}(\{\mathbf{x}_i, \mathbf{y}_i\}) = \frac{1}{n} \sum_{i=1}^n \|\mathbf{y}_i - g_{\Theta}(\mathbf{x}_i)\|_2^2$$

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- One layer, sigmoid activation, logistic loss (\Rightarrow logistic regression).

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We want to automatize this **computational step** efficiently.

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x
●

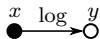
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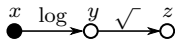
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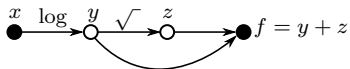
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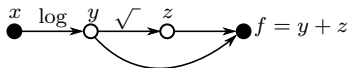
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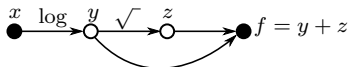
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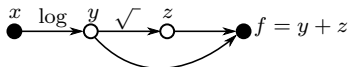
Computational graphs

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A **computational graph** is a directed acyclic graph representing the computation of $f(x)$ with **intermediate** variables.

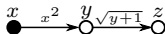
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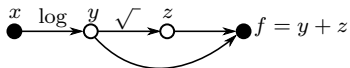
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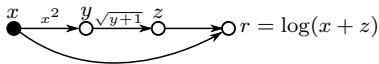
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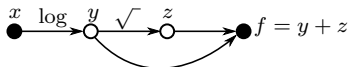
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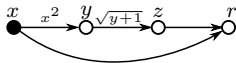
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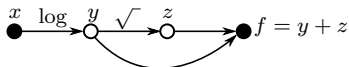
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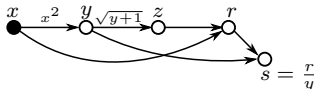
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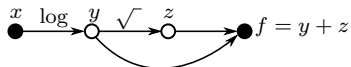
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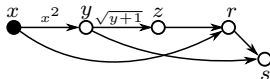
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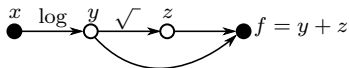
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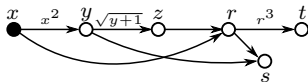
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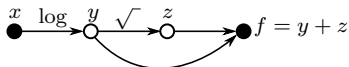
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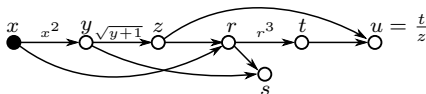
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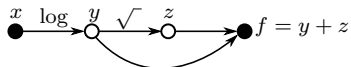
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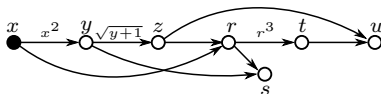
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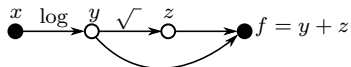
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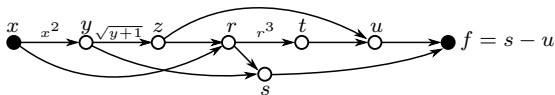
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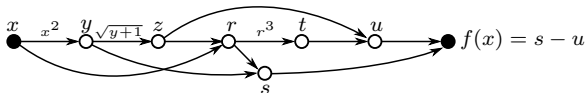
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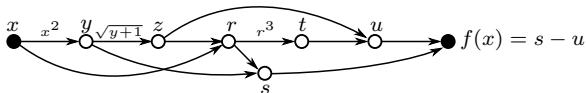
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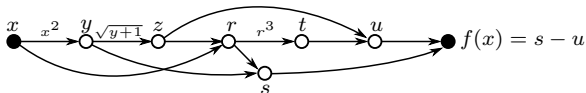


The graph is constructed programmatically, for example:

```
z = sqrt(sum(square(x), 1));
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Computational graphs

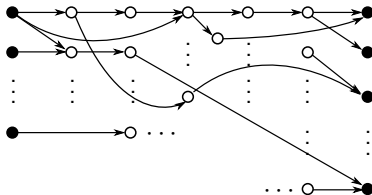
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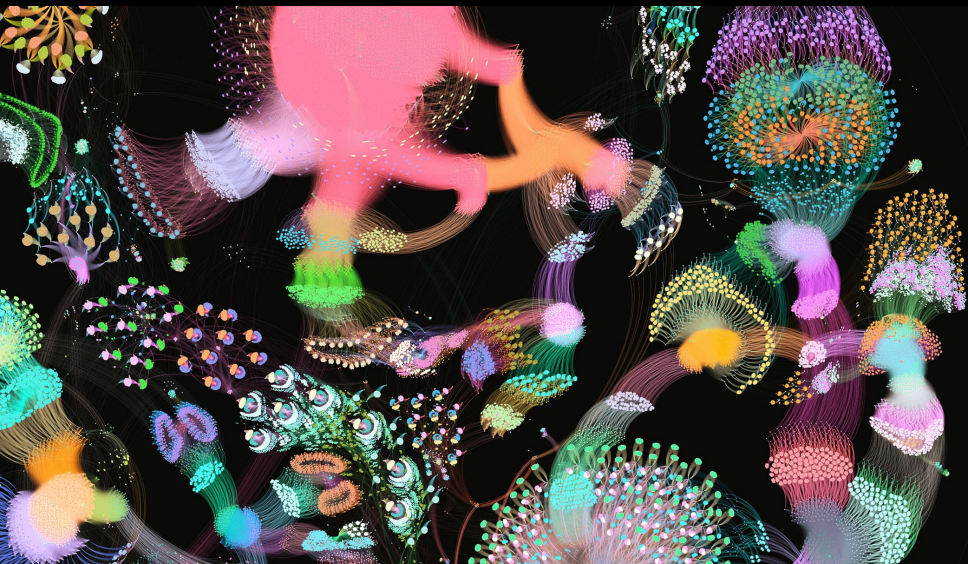
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For **high-dimensional** input/output, the graph may be more complex:



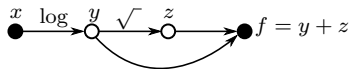
The computational graph gets big quickly.



Poplar visualization, see <https://www.graphcore.ai/products/poplar>

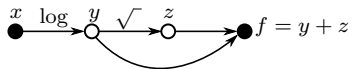
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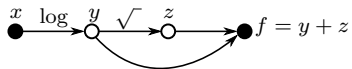
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$$\frac{\partial x}{\partial x} = 1$$

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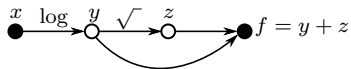


$$\frac{\partial x}{\partial x} = 1$$

$$\frac{\partial y}{\partial x} = \frac{\partial y}{\partial x} \frac{\partial x}{\partial x}$$

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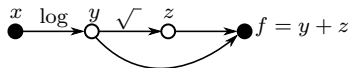


$$\frac{\partial x}{\partial x} = 1$$

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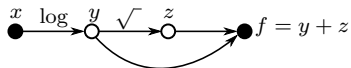


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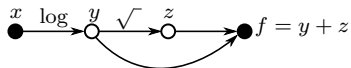
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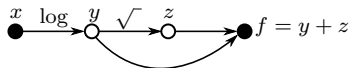
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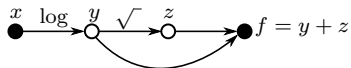
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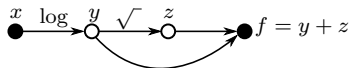
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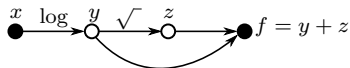
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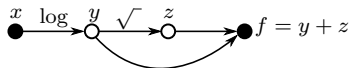
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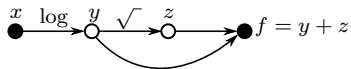
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Automatic differentiation: Forward mode

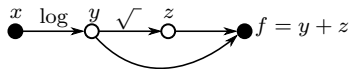
$$f(x) = \log x + \sqrt{\log x} \qquad \frac{\partial f}{\partial x} = \frac{1}{2\sqrt{y}} \frac{1}{x} + \frac{1}{x}$$



Assumption: Each partial derivative is a “primitive” accessible in **closed form** and can be computed on the fly.

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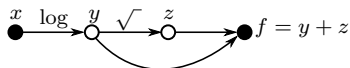


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$$\text{cost of computing } \frac{\partial f}{\partial x}(x) = \text{cost of computing } f(x)$$

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Assumption: Each partial derivative is a “primitive” accessible in **closed form** and can be computed on the fly.

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However, if the input is high-dimensional, i.e. $f : \mathbb{R}^p \rightarrow \mathbb{R}$:

$$\text{cost of computing } \nabla f(\mathbf{x}) = p \times \text{cost of computing } f(\mathbf{x})$$

since partial derivatives must be computed w.r.t. each input dimension.

Automatic differentiation: Forward mode

The forward mode computes all the partial derivatives $\frac{\partial y}{\partial x}, \frac{\partial z}{\partial x}, \dots$ with respect to the **input** x .

Straightforward application of the **chain rule**.

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(e.g. autograd) (e.g. Mathematica)

We accumulate values during code execution to generate numerical derivative **evaluations** rather than derivative **expressions**.

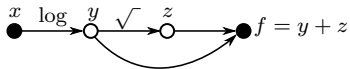
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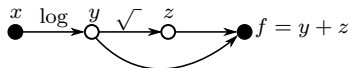
We accumulate values during code execution to generate numerical derivative **evaluations** rather than derivative **expressions**.



Reverse mode: compute all the partial derivatives $\frac{\partial f}{\partial z}, \dots, \frac{\partial f}{\partial x}$ with respect to the **inner nodes**.

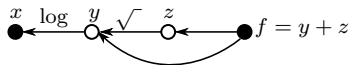
Automatic differentiation: Reverse mode

$$f(x) = \log x + \sqrt{\log x}$$



Automatic differentiation: Reverse mode

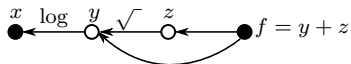
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$$\frac{\partial f}{\partial f} = 1$$

Automatic differentiation: Reverse mode

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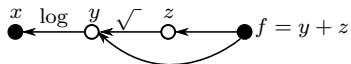
$$\frac{\partial f}{\partial z} =$$

$$\frac{\partial f}{\partial y} =$$

$$\frac{\partial f}{\partial x} =$$

Automatic differentiation: Reverse mode

$$f(x) = \log x + \sqrt{\log x}$$



$$\frac{\partial f}{\partial f} = 1$$

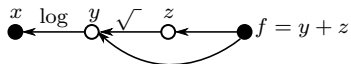
$$\frac{\partial f}{\partial z} = \frac{\partial f}{\partial f} \frac{\partial f}{\partial z}$$

$$\frac{\partial f}{\partial y} =$$

$$\frac{\partial f}{\partial x} =$$

Automatic differentiation: Reverse mode

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$$\frac{\partial f}{\partial f} = 1$$

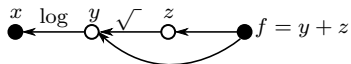
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$$\frac{\partial f}{\partial y} =$$

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Automatic differentiation: Reverse mode

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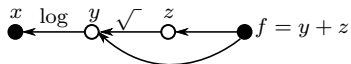
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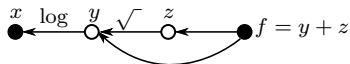
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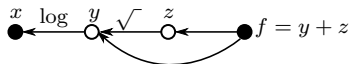
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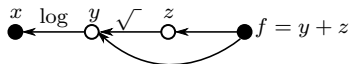
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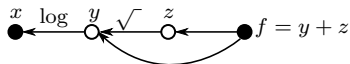
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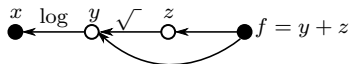
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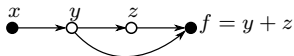
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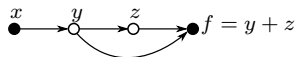
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ϵ computes the actual scalar error for the loss.

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Backprop through computational graph of the loss

\approx

Backprop “through the network”

Suggested reading

Nice, accessible survey on automatic differentiation:

<https://arxiv.org/pdf/1502.05767>