

# Deep Learning & Applied AI


Overfitting and going nonlinear

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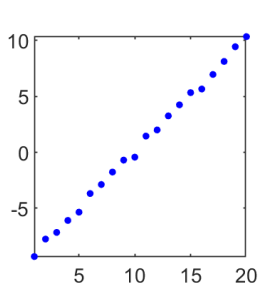
# A glimpse into neural networks

In deep learning, we deal with **highly parametrized models** called **deep neural networks**:

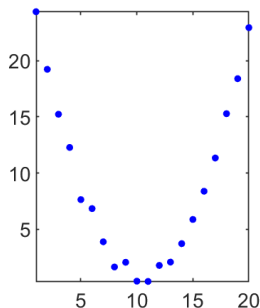

$$f_{\Theta}(\mathbf{x}) = \mathbf{y}$$

# Parametrized models

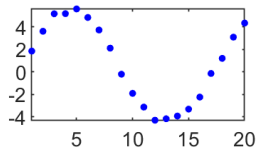
The parameters describe the behavior of the network, and must be **solved for**.



$$y = ax + b$$



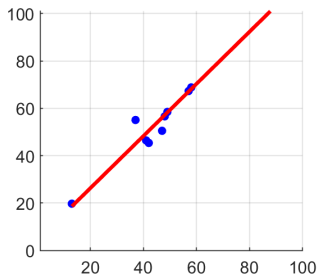
$$y = ax^2 + bx + c$$



$$y = a \sin(x) + bx + c$$

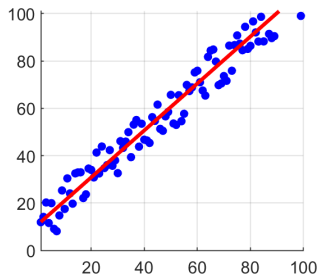
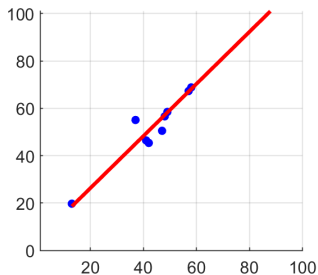
From a technical standpoint, our task is to determine the parameters  $\Theta$ .

# Data distribution



Assumption: **linear** model

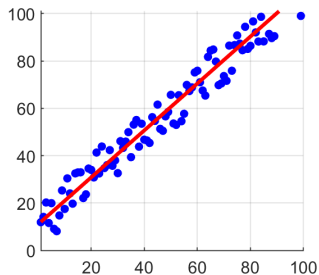
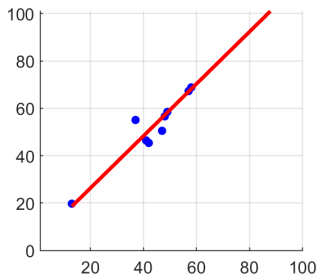
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More data allows us to improve our prediction

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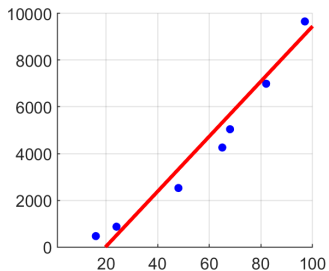


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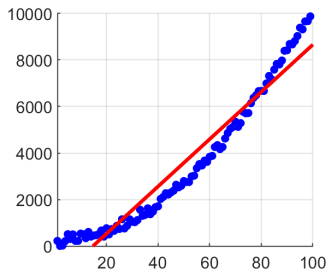
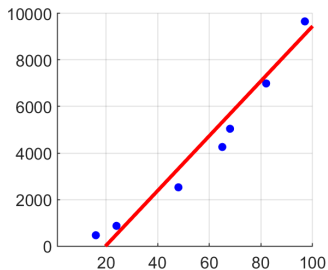
What if the assumption (i.e. linear prior here) is **wrong**?

# Data distribution



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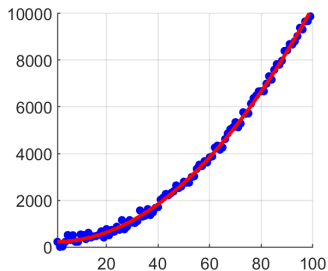
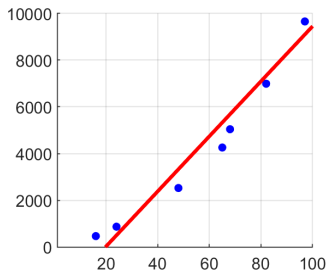


Assumption: **linear** model

More data **confutes** our assumptions

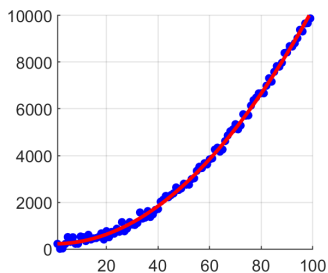
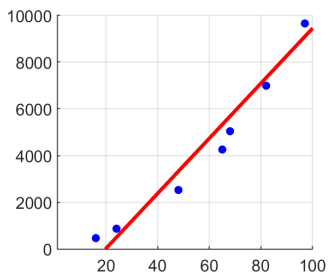


# Data distribution



Assumption: quadratic model

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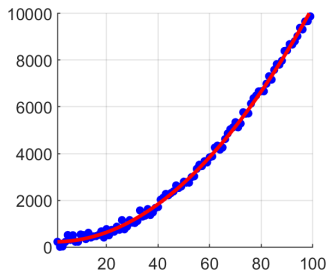
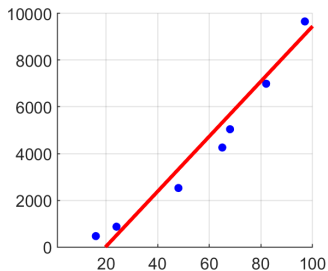


Assumption: **quadratic** model

Key questions:

- How to select the **correct distribution**?

# Data distribution

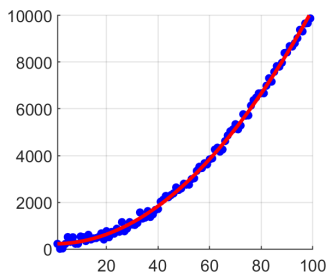
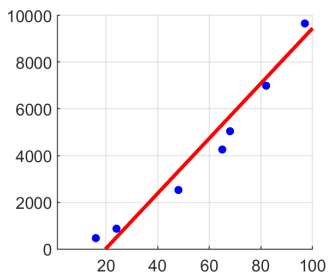


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# Data distribution



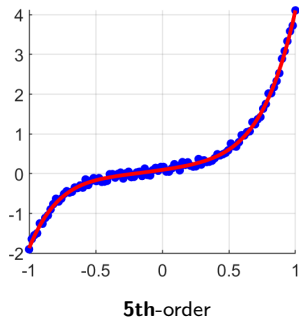
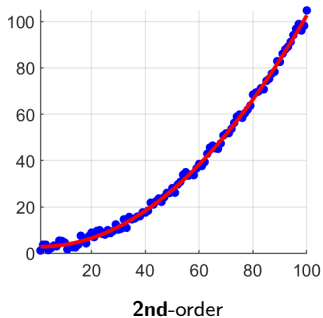
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Key questions:

- How to select the **correct distribution**?
- **How much data** do we need?
- What if the correct distribution does not admit a **simple expression**?

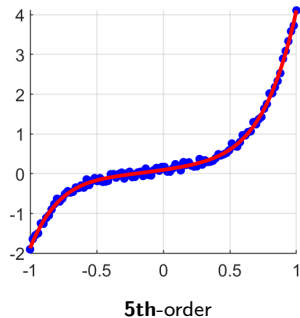
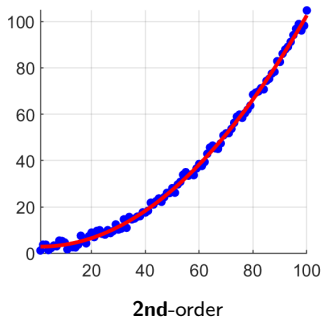
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After the linear model, the simplest thing is a **polynomial model**.



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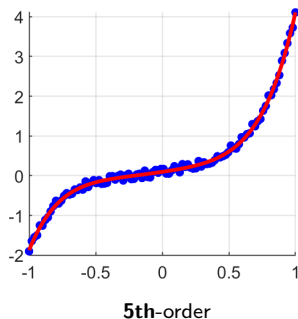
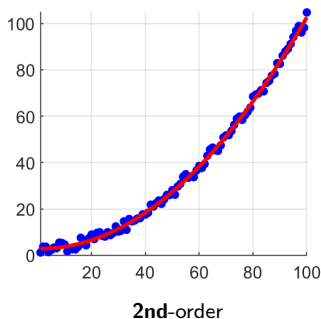
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The number of **parameters** grows with the order.

**More data** are needed to make an informed decision on the order.

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In matrix notation:

$$\underbrace{\begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}}_{\mathbf{y}} = \underbrace{\begin{pmatrix} x_1^k & x_1^{k-1} & \cdots & x_1 & 1 \\ x_2^k & x_2^{k-1} & \cdots & x_2 & 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_n^k & x_n^{k-1} & \cdots & x_n & 1 \end{pmatrix}}_{\mathbf{X}} \underbrace{\begin{pmatrix} a_k \\ a_{k-1} \\ \vdots \\ a_1 \\ b \end{pmatrix}}_{\boldsymbol{\theta}}$$

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The same exact **least-squares** solution as with linear regression applies, with the requirement that  $k < n$ .

# Polynomial fitting

An application of the [Stone-Weierstrass theorem](#) tells us:

If  $f$  is continuous on the interval  $[a, b]$ , then for every  $\epsilon > 0$  there exists a polynomial  $p$  such that  $|f(x) - p(x)| < \epsilon$  for all  $x$ .

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Thus, we can try to fit a polynomial in many cases.

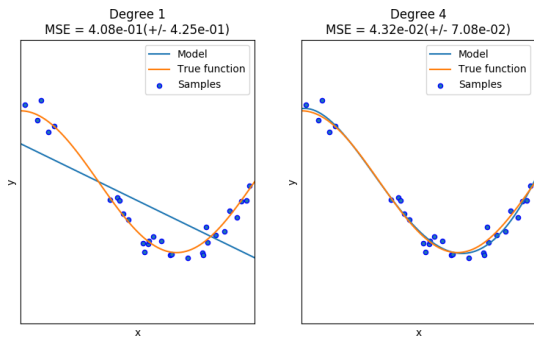


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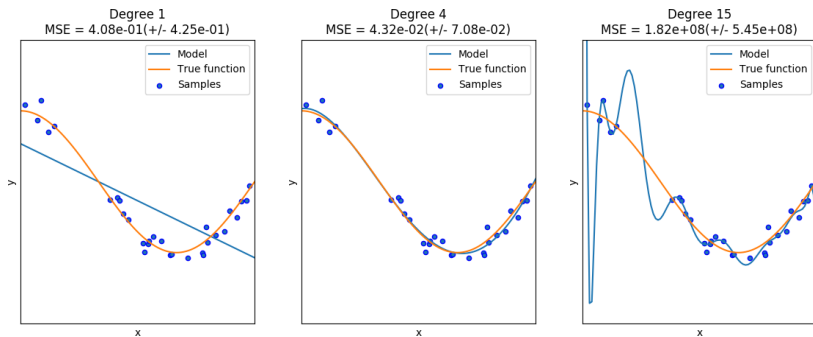


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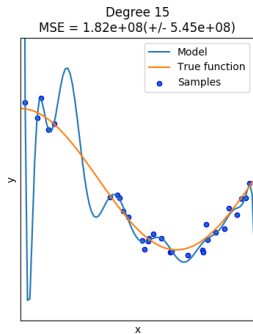
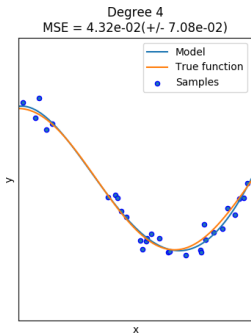
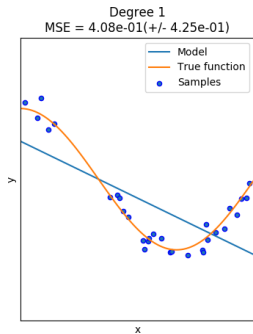
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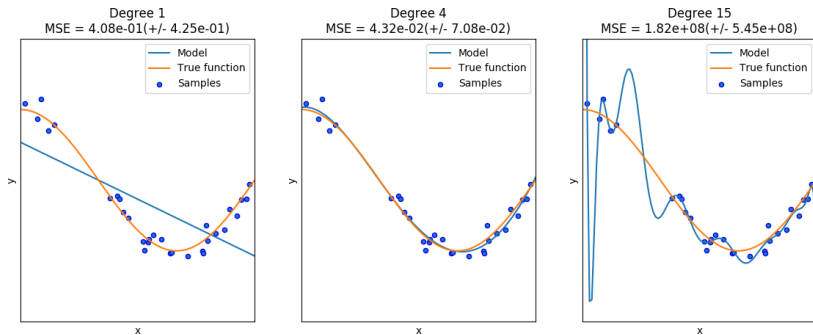
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# Underfitting vs. Overfitting

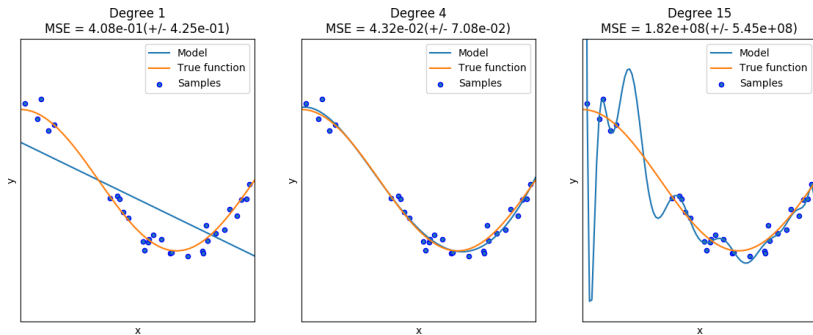


# Underfitting vs. Overfitting



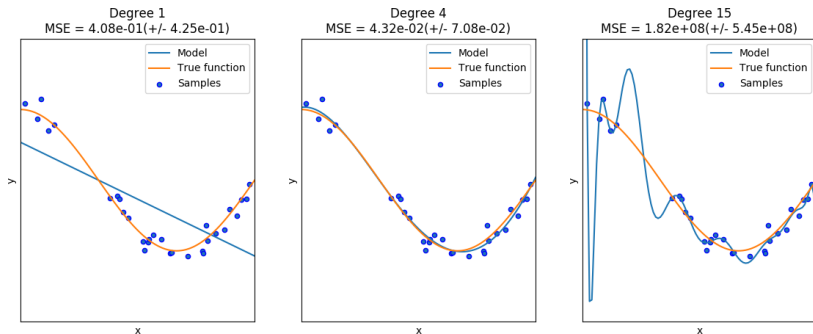
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Adding complexity can lead to **overfitting** and thus worse **generalization**.

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large training error, large validation error

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(very) small training error, large validation error

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- Regularization
- Additional priors
- Intermediate features
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From now on, we embrace the idea that many natural phenomena of interest are **nonlinear**.

# Regularization penalties

Sometimes our prior knowledge can be expressed in terms of an **energy**.

For example, avoid **large** parameters to **counteract overfitting**:

$$\min_{\Theta} \underbrace{\ell_{\Theta}}_{\text{data term}} + \underbrace{\lambda}_{\text{trade-off}} \cdot \underbrace{\|\Theta\|_F^2}_{\text{regularizer}}$$

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More in general:

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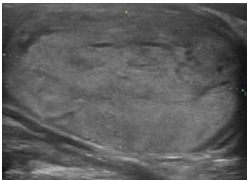
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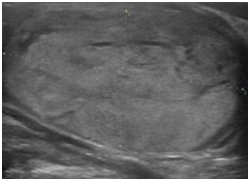
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Instead: Modify the loss to minimize over **categorical values directly**.

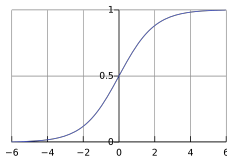
# Logistic regression

New loss:

$$\ell_{\Theta}(\{x_i, y_i\}) = \sum_{i=1}^n (y_i - \underbrace{\sigma(ax_i + b)}_{\text{linear}})^2$$

Here,  $\sigma$  is the nonlinear **logistic sigmoid**:

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



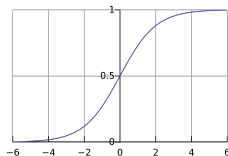
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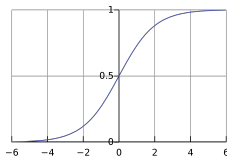
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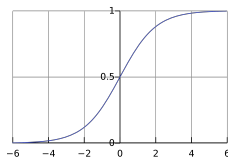
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$$\ell_{\Theta}(\{x_i, y_i\}) = \sum_{i=1}^n c(x_i, y_i), \quad \text{with}$$
$$c(x_i, y_i) = \begin{cases} -\ln(\sigma(ax_i + b)) & y_i = 1 \\ -\ln(1 - \sigma(ax_i + b)) & y_i = 0 \end{cases} \quad \text{convex}$$

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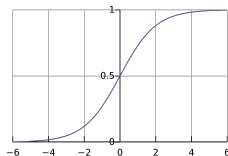
New loss:

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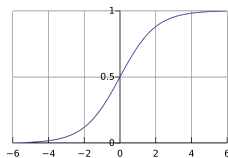
# Logistic regression

New **convex** loss:

$$\ell_{\Theta}(\{x_i, y_i\}) = - \sum_{i=1}^n y_i \ln(\sigma(ax_i + b)) + (1 - y_i) \ln(1 - \sigma(ax_i + b))$$

Here,  $\sigma$  is the nonlinear **logistic sigmoid**:

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



$\sigma$  has a **saturation** effect as it maps  $\mathbb{R} \mapsto (0, 1)$ .



# Logistic regression: Finding a solution

Since the loss is convex, the first-order conditions apply:

$$\nabla_{\Theta} \ell_{\Theta} = 0$$

# Logistic regression: Finding a solution

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$$\nabla_{\Theta} \sum_{i=1}^n y_i \ln(\sigma(ax_i + b)) + (1 - y_i) \ln(1 - \sigma(ax_i + b)) = 0$$

where  $\Theta = \{a, b\}$ .

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Consider the gradient of each term in the summation:

$$\nabla_{\Theta} (y_i \ln(\sigma(ax_i + b)) + (1 - y_i) \ln(1 - \sigma(ax_i + b)))$$

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$$\nabla_{\Theta} y_i \ln(\sigma(ax_i + b)) + \nabla_{\Theta} (1 - y_i) \ln(1 - \sigma(ax_i + b))$$

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Consider the gradient of each term in the summation:

$$y_i \nabla_{\Theta} \underbrace{\ln(\sigma(ax_i + b))}_{f(g(h(\Theta)))} + (1 - y_i) \nabla_{\Theta} \ln(1 - \sigma(ax_i + b))$$

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Apply the **chain rule** to each partial derivative:

$$\frac{\partial}{\partial \mathbf{a}} f(g(h(\mathbf{a}, b))) = \frac{\partial f}{\partial g} \cdot \frac{\partial g}{\partial h} \cdot \frac{\partial h}{\partial \mathbf{a}}$$

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Apply the **chain rule** to each partial derivative:

$$\frac{\partial}{\partial a} f(g(h(a, b))) = \frac{\partial f}{\partial g} \cdot \frac{\partial}{\partial (ax_i + b)} \frac{1}{1 + e^{-(ax_i + b)}} \cdot x_i$$

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Apply the **chain rule** to each partial derivative:

$$\frac{\partial}{\partial a} f(g(h(a, b))) = \frac{\partial f}{\partial g} \cdot \frac{e^{-(ax_i + b)}}{(1 + e^{-(ax_i + b)})^2} \cdot x_i$$

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Apply the **chain rule** to each partial derivative:

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And similarly for the **second term** and for parameter  $b$ .

# Logistic regression: Finding a solution

By looking at the partial derivative:

$$\frac{\partial}{\partial a} \ln(\sigma(ax_i + b)) = (1 - \sigma(ax_i + b))x_i$$

we see that the parameters enter the gradient in a **nonlinear** way.

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model	loss	solution
linear regression linear regression + Tikhonov logistic regression		

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model	loss	solution
linear regression	convex	
linear regression + Tikhonov	convex	
logistic regression	convex	

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model	loss	solution
linear regression	convex	least squares
linear regression + Tikhonov	convex	
logistic regression	convex	

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model	loss	solution
linear regression	convex	least squares
linear regression + Tikhonov	convex	least squares
logistic regression	convex	

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model	loss	solution
linear regression	convex	least squares
linear regression + Tikhonov	convex	least squares
logistic regression	convex	<b>nonlinear optimization</b>

## Suggested reading

On polynomial regression vs. neural nets:

<https://arxiv.org/pdf/1806.06850>

Proof that the logistic loss is convex:

<https://math.stackexchange.com/questions/1582452/>

logistic-regression-prove-that-the-cost-function-is-convex