

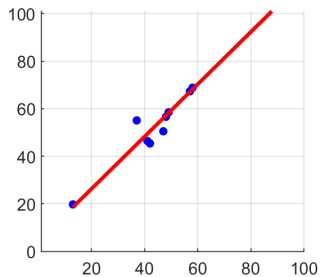
# Deep Learning & Applied AI

Overfitting and going nonlinear

Emanuele Rodolà  
[rodola@di.uniroma1.it](mailto:rodola@di.uniroma1.it)

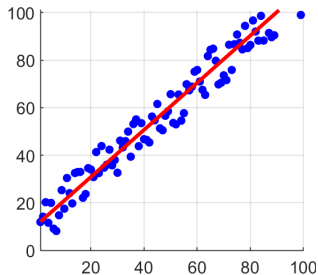
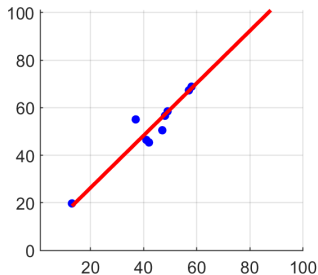


# Data distribution



Assumption: **linear** model

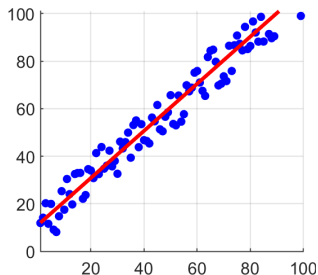
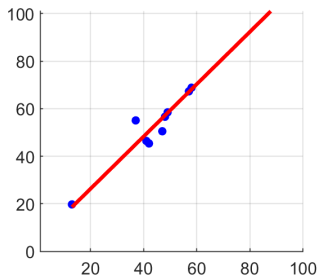
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More data allows us to improve our prediction

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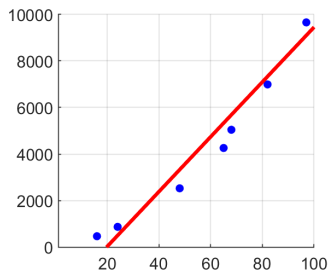


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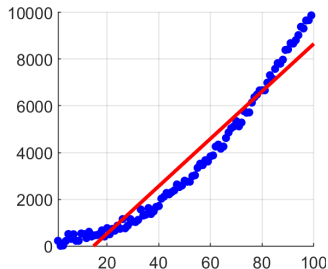
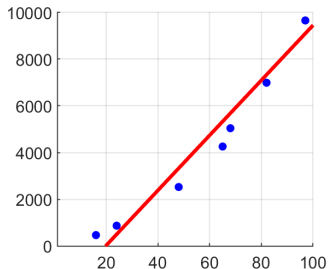
What if the assumption (i.e. linear prior here) is **wrong**?

# Data distribution



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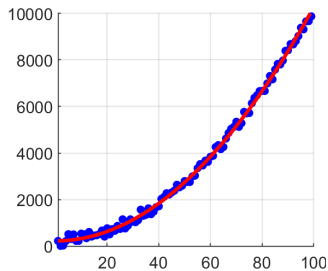
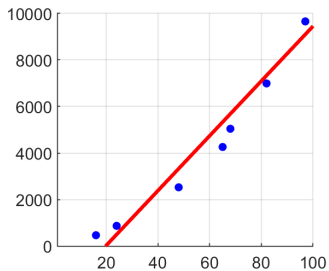
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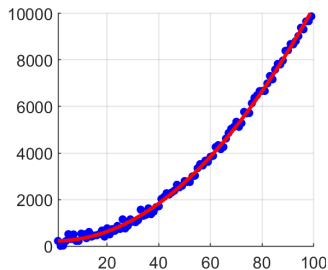
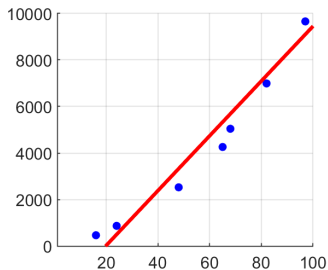
More data **confutes** our assumptions

# Data distribution



Assumption: quadratic model

# Data distribution



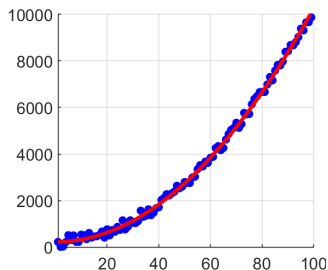
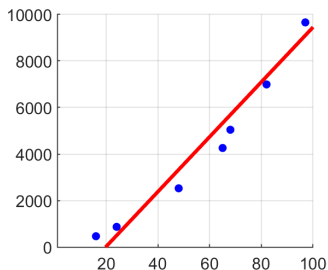
Assumption: **quadratic** model

Key questions:

- How to select the **correct** distribution?



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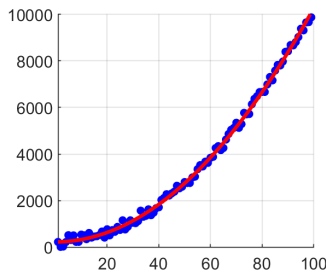
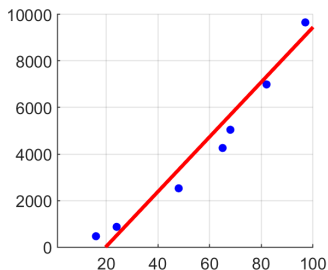


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- **How much data** do we need?

# Data distribution



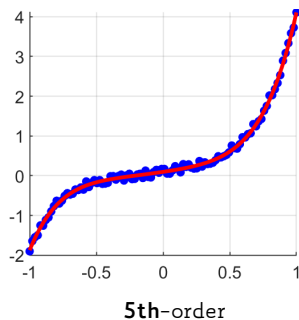
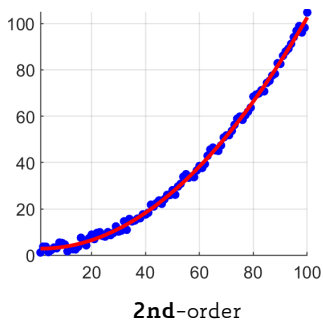
Assumption: **quadratic** model

Key questions:

- How to select the **correct distribution**?
- **How much data** do we need?
- What if the correct distribution does not admit a **simple expression**?

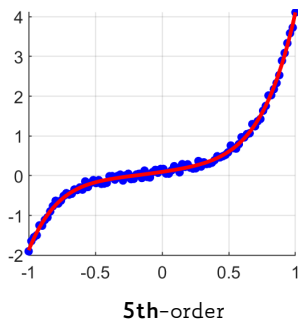
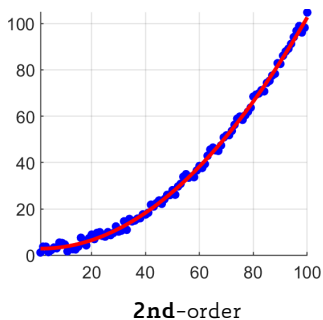
# Polynomial regression

After the linear model, the simplest thing is a **polynomial model**.



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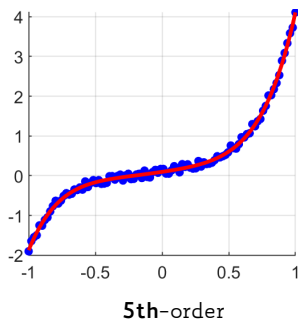
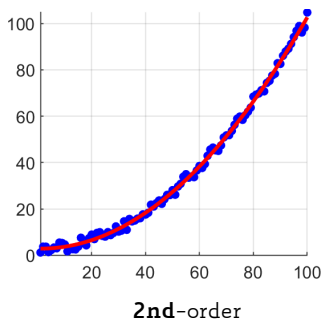
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The number of **parameters** grows with the order.

**More data** are needed to make an informed decision on the order.

# Polynomial regression

**Remark:** Despite the name, polynomial regression is still **linear in the parameters**. It is polynomial with respect to the data.

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In matrix notation:

$$\underbrace{\begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}}_{\mathbf{y}} = \underbrace{\begin{pmatrix} x_1^k & x_1^{k-1} & \cdots & x_1 & 1 \\ x_2^k & x_2^{k-1} & \cdots & x_2 & 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_n^k & x_n^{k-1} & \cdots & x_n & 1 \end{pmatrix}}_{\mathbf{X}} \underbrace{\begin{pmatrix} a_k \\ a_{k-1} \\ \vdots \\ a_1 \\ b \end{pmatrix}}_{\boldsymbol{\theta}}$$

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The same exact **least-squares** solution as with linear regression applies, with the requirement that  $k < n$ .

# Polynomial fitting

An application of the Stone-Weierstrass theorem tells us:

If  $f$  is continuous on the interval  $[a, b]$ , then for every  $\epsilon > 0$  there exists a polynomial  $p$  such that  $|f(x) - p(x)| < \epsilon \ \forall x$ .

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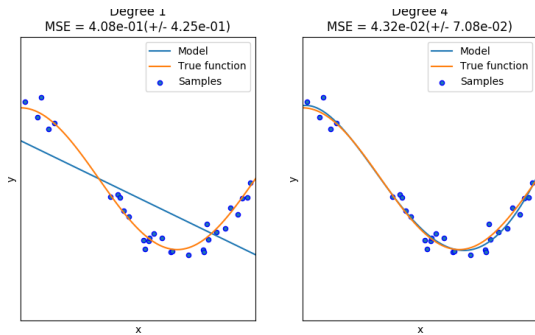
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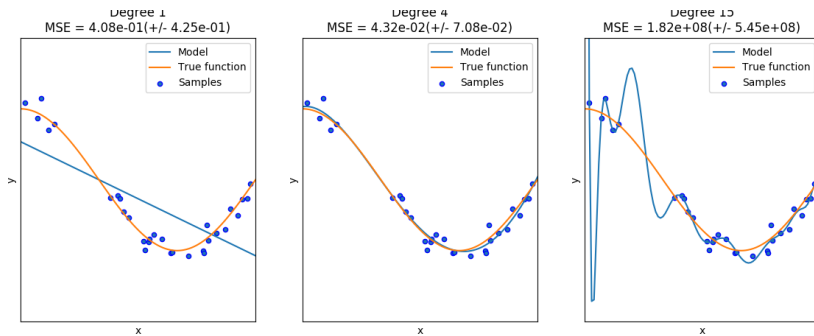


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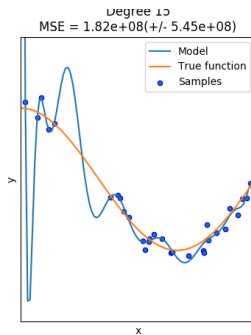
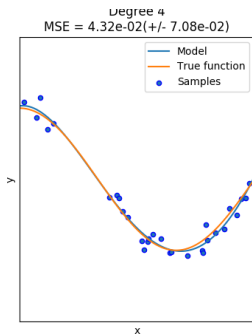
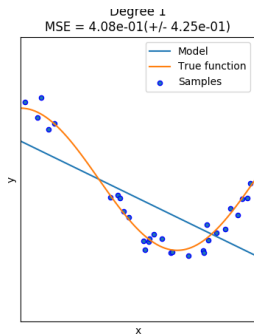
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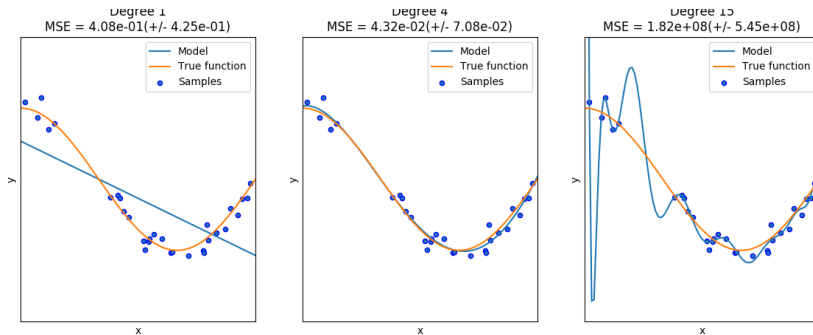




# Underfitting vs. Overfitting

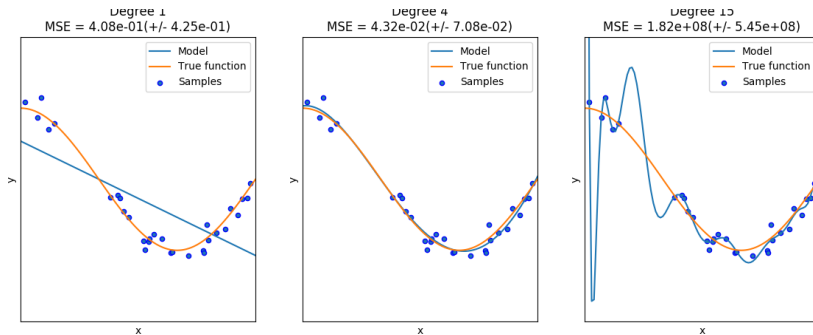


# Underfitting vs. Overfitting



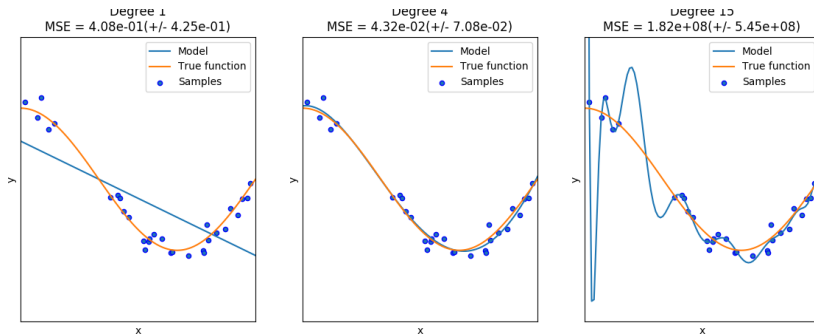
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Adding complexity can lead to **overfitting** and thus worse **generalization**.

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To recap, **overfitting** happens with small training error and large validation error

# Not done yet

So is polynomial regression all we need?

Not really!

- Different loss than MSE
- Regularization
- Additional priors
- Intermediate features
- Regression (predict a value) vs. classification (predict a category)

# Classification

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Let's see how to modify the loss to minimize over **categorical** values directly.

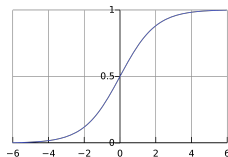
# Logistic regression

New loss:

$$\ell_{\Theta}(\{x_i, y_i\}) = \sum_{i=1}^n (y_i - \underbrace{\sigma(ax_i + b)}_{\text{linear}})^2$$

Here,  $\sigma$  is the nonlinear **logistic sigmoid**:

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



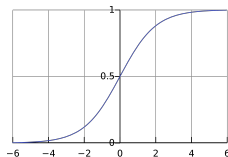
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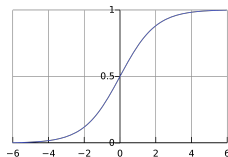
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$$\ell_{\Theta}(\{x_i, y_i\}) = \sum_{i=1}^n (y_i - \underbrace{\sigma(ax_i + b)}_{\text{linear}})^2 \quad \text{non-convex in } a, b$$

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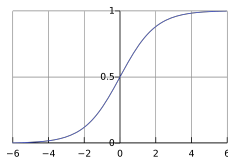
New loss:

$$\ell_{\Theta}(\{x_i, y_i\}) = \sum_{i=1}^n c(x_i, y_i), \quad \text{with}$$

$$c(x_i, y_i) = \begin{cases} -\ln(\sigma(ax_i + b)) & y_i = 1 \\ -\ln(1 - \sigma(ax_i + b)) & y_i = 0 \end{cases} \quad \text{convex}$$

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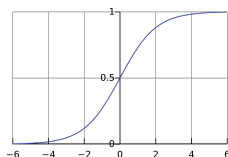
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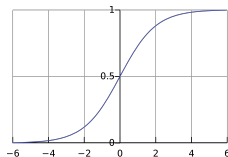
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New **convex** loss:

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Consider the gradient of each term in the summation:

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Apply the **chain rule** to each partial derivative:

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Apply the **chain rule** to each partial derivative:

$$\frac{\partial}{\partial a} f(g(h(a, b))) = \frac{\partial f}{\partial g} \cdot \frac{\partial}{\partial (ax_i + b)} \frac{1}{1 + e^{-(ax_i + b)}} \cdot x_i$$

# Logistic regression: Finding a solution

Since the loss is convex, the first-order conditions apply:

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...and so on for the **second term** and for parameter  $b$ .

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By looking at the partial derivative:

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we see that the parameters enter the gradient in a **nonlinear** way.

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model	loss	solution
linear regression linear regression + Tikhonov logistic regression		

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linear regression	convex	
linear regression + Tikhonov	convex	
logistic regression	convex	

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linear regression	convex	least squares
linear regression + Tikhonov	convex	
logistic regression	convex	

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linear regression + Tikhonov	convex	least squares
logistic regression	convex	



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linear regression	convex	least squares
linear regression + Tikhonov	convex	least squares
logistic regression	convex	<b>nonlinear optimization</b>

# Suggested reading

On polynomial regression vs. neural nets:

<https://arxiv.org/pdf/1806.06850>

Proof that the logistic loss is convex:

<https://math.stackexchange.com/questions/1582452/>

logistic-regression-prove-that-the-cost-function-is-convex