

Metodi Numerici dell'Informatica

Spectral decomposition

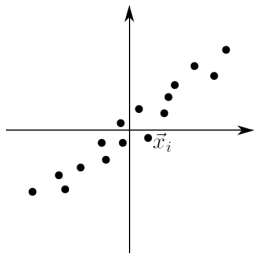
Emanuele Rodolà
rodola@di.uniroma1.it



Motivation

Principal axis

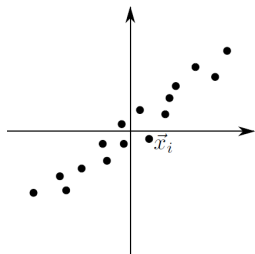
Consider the two-dimensional data in this plot:



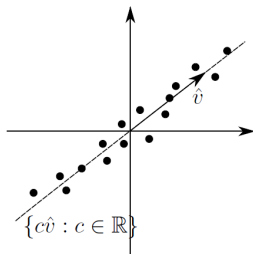
(a) Input data

Principal axis

Consider the two-dimensional data in this plot:



(a) Input data



(b) Principal axis

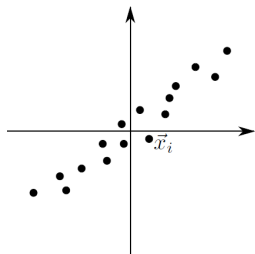
Q: Find the vector \mathbf{v} such that each data point \mathbf{x}_i can be written as

$$\mathbf{x}_i = c_i \mathbf{v}$$

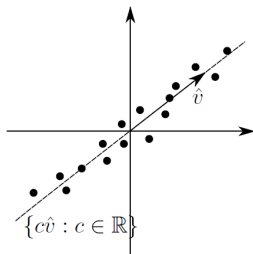
where each \mathbf{x}_i has its own c_i

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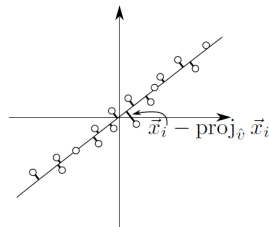
Consider the two-dimensional data in this plot:



(a) Input data



(b) Principal axis



(c) Projection error

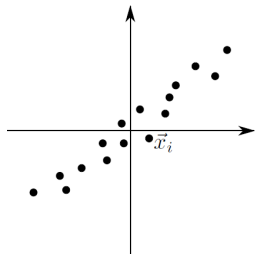
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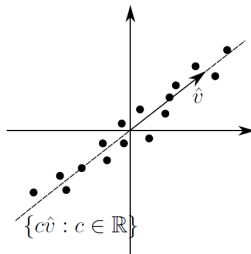
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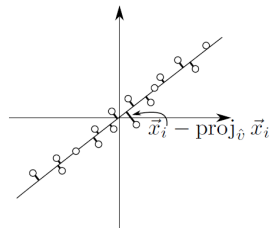
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$$\begin{aligned} \min_{\mathbf{v}} \quad & \sum_i \|\mathbf{x}_i - \text{proj}_{\mathbf{v}} \mathbf{x}_i\|_2^2 \\ \text{s.t.} \quad & \|\mathbf{v}\|_2 = 1 \end{aligned}$$

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where matrix \mathbf{X} contains the vectors \mathbf{x}_i as its columns.

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This can also be written as

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The global maximizer \mathbf{v}^* of this problem is the **principal component** of the data contained in the matrix \mathbf{X} .

Eigenvectors and eigenvalues

Eigenvalue equation

An **eigenvector** \mathbf{x} of a square matrix \mathbf{A} is any vector satisfying

$$\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$$

for some (possibly complex) number λ that we call **eigenvalue**.

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Clearly, \mathbf{x} and $-\mathbf{x}$ are both eigenvectors with the same eigenvalue.

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We say that $\mathbf{B} = \mathbf{T}^{-1}\mathbf{A}\mathbf{T}$ is a **similarity transformation**. \mathbf{A} and \mathbf{B} have the same eigenvalues.

More basic facts

A few more basic facts that will become useful later:

- Orthogonal matrices

Observe:

$$Q\mathbf{x} = \lambda\mathbf{x}$$

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$$(\mathbf{Q}\mathbf{x})^\top \mathbf{Q}\mathbf{x} = |\lambda|^2 \|\mathbf{x}\|_2^2$$

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- Commuting matrices

Consider two matrices **A** and **B**. One can prove:

$$\mathbf{AB} = \mathbf{BA} \quad \Leftrightarrow \quad \mathbf{A} \text{ and } \mathbf{B} \text{ have the same eigenvectors}$$

Big questions

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- What to do with them?

A tentative answer

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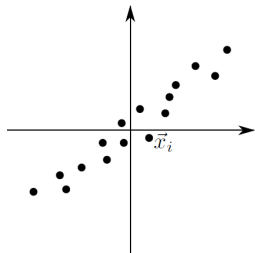
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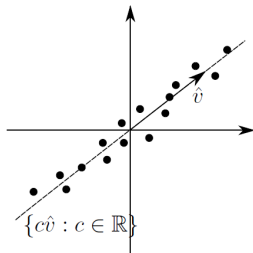
Min-max theorem

Back to our motivation:

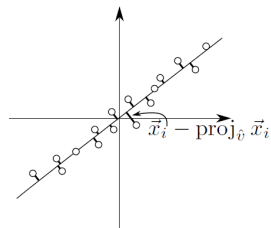
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Theorem If \mathbf{A} is symmetric, then its maximum eigenvalue is given by $\max_{\mathbf{v}} \frac{\mathbf{v}^\top \mathbf{A} \mathbf{v}}{\|\mathbf{v}\|_2^2}$, and \mathbf{v} is the corresponding eigenvector.

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$$\lambda_{\min} \leq \frac{\mathbf{v}^\top \mathbf{A} \mathbf{v}}{\|\mathbf{v}\|_2^2} \leq \lambda_{\max}$$

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The ratio $\frac{\mathbf{v}^\top \mathbf{A} \mathbf{v}}{\|\mathbf{v}\|_2^2}$ is called **Rayleigh quotient**.

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Consider an eigenvalue-eigenvector pair (λ, \mathbf{x}) , where $\|\mathbf{x}\|_2^2 = 1$.

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For the equality to hold, it must be $\mathbf{x}_i^\top \mathbf{x}_j = 0$, i.e. \mathbf{x}_i and \mathbf{x}_j are **orthogonal**.

Spectral theorem

The set of eigenvalues $\{\lambda_i\}$ of a matrix \mathbf{A} is called the **spectrum**.

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If \mathbf{A} is symmetric, then \mathbf{X} is an **orthogonal** matrix of eigenvectors, and $\mathbf{\Lambda}$ is a **diagonal** matrix of real eigenvalues.

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Observe the similarity with our motivational problem.

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We call it the **spectral decomposition** of \mathbf{A} .

Observe the similarity with our motivational problem. We can modify it to solve for **all** eigenvectors and eigenvalues:

$$\begin{aligned} \min_{\mathbf{X}} \quad & \text{tr}(\mathbf{X}^\top \mathbf{A} \mathbf{X}) \\ \text{s.t.} \quad & \mathbf{X}^\top \mathbf{X} = \mathbf{I} \end{aligned}$$

Finding eigenvalues

Power iteration

Very simple algorithm to find the **largest** eigenvalue/eigenvector:

```
function NORMALIZED-ITERATION( $A$ )  
   $\vec{v} \leftarrow \text{ARBITRARY}(n)$   
  for  $k \leftarrow 1, 2, 3, \dots$   
     $\vec{w} \leftarrow A\vec{v}$   
     $\vec{v} \leftarrow \vec{w} / \|\vec{w}\|$   
  return  $\vec{v}$ 
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The normalization is needed to reduce the numerical error.

Without normalization, it will still converge to the principal eigenvector (but with a very large scale).

Inverse iteration

To find the **smallest** eigenvalue/eigenvector, we first observe that:

$$\mathbf{Ax} = \lambda\mathbf{x} \implies \mathbf{A}^{-1}\mathbf{x} = \frac{1}{\lambda}\mathbf{x}$$

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```

In practice, you don't invert \mathbf{A} but apply LU decomposition.

Shifting

For a matrix \mathbf{A} , we have eigenvalues $\{\lambda_i\}$ and eigenvectors $\{\mathbf{x}_i\}$.

Then:

$$(\mathbf{A} - \sigma \mathbf{I})\mathbf{x}_i =$$

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If we think that σ is near an eigenvalue of \mathbf{A} , then $\mathbf{A} - \sigma \mathbf{I}$ has an eigenvalue close to 0.

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We can use this fact to estimate **portions of the spectrum**:

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- Apply the **inverse iteration** on \mathbf{B}

Finding multiple eigenvalues at once

Recall that if $\mathbf{B} = \mathbf{T}^{-1}\mathbf{A}\mathbf{T}$ then \mathbf{A} and \mathbf{B} have the same spectra.

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For example, we could first compute

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and then overwrite:

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In other words, this operation **preserves the eigenvalues**:

$$\mathbf{A} \leftarrow \mathbf{R} \mathbf{Q}$$

QR iteration

If we keep doing this iteratively, we get the algorithm:

```
function QR-ITERATION( $A \in \mathbb{R}^{n \times n}$ )  
  for  $k \leftarrow 1, 2, 3, \dots$   
     $Q, R \leftarrow \text{QR-FACTORIZE}(A)$   
     $A \leftarrow RQ$   
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- In other words, the eigenvalues of \mathbf{A}_∞ (and hence of \mathbf{A}) equal the diagonal elements of \mathbf{R}_∞ up to sign.

Suggested reading

Read Sections 6.1.1, 6.2, 6.2.1, 6.3.1, 6.3.2, 6.3.3, 6.4.2 of the book:

J. Solomon, “Numerical Algorithms”