Metodi Numerici dell'Informatica

Orthogonality and QR decomposition

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Motivation

For any $\mathbf{A} \in \mathbb{R}^{n \times m}$, the linear problem:

Ax = b

can be seen as:

"write ${\bf b}$ as a linear combination of the columns of ${\bf A}$ with coefficients stored in ${\bf x}$ ".

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$$\mathbf{A}\mathbf{x} = \begin{pmatrix} | & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots \\ | & | \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \end{pmatrix} = x_1 \begin{pmatrix} | \\ \mathbf{a}_1 \\ | \end{pmatrix} + x_2 \begin{pmatrix} | \\ \mathbf{a}_2 \\ | \end{pmatrix} + \cdots$$

Numerical instability

Consider the following situation:

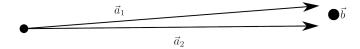
$$\mathbf{A} = \begin{pmatrix} | & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots \\ | & | \end{pmatrix} = \begin{pmatrix} 0 & 0.0001 \\ \vdots & \vdots & \cdots \\ 1 & 1.0001 \end{pmatrix}$$

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The columns are almost linearly dependent:



This problem is poorly conditioned, since we can write either:

$$\mathbf{b} \approx x_1 \mathbf{a}_1 + x_2 \mathbf{a}_2$$

$$\mathbf{b} \approx x_2 \mathbf{a}_1 + x_1 \mathbf{a}_2$$

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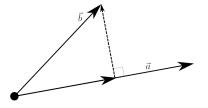
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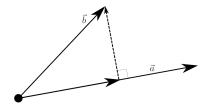
Can we deal with numerical instability explicitly?

Orthogonality

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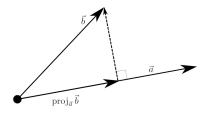
Consider two vectors ${\bf a}$ and ${\bf b}$. Which multiple of ${\bf a}$ is closest to ${\bf b}$?



This can be phrased as a projection problem:

$$\min_{c} \|c\,\mathbf{a} - \mathbf{b}\|_2^2$$

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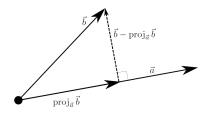


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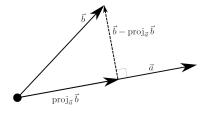


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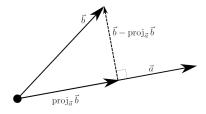
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Further, the complement $\mathbf{b} - \mathrm{proj}_{\mathbf{a}}\mathbf{b}$ is orthogonal to $\mathrm{proj}_{\mathbf{a}}\mathbf{b}$.



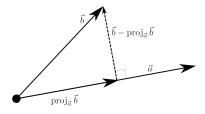
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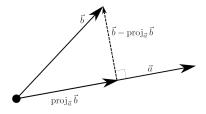
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Therefore:

$$\operatorname{proj}_{\mathbf{a}} \mathbf{b} = \frac{\mathbf{a}^{\top} \mathbf{b}}{\|\mathbf{a}\|_{2}^{2}} \mathbf{a}$$

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Assume we are given an orthonormal basis $\{a_1,\ldots,a_k\}$; then, we can project onto its span by solving the problem:

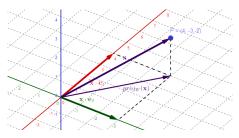
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Example in \mathbb{R}^3 and k=2:

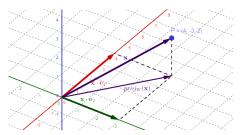


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In the lucky case where $\mathbf{A}^{\top}\mathbf{A}=\mathbf{I}$ (i.e. matrix \mathbf{A} is orthogonal), we boil down to the trivial case. Further, this implies that $\mathbf{A}^{-1}=\mathbf{A}^{\top}$.

Let's analyze this more carefully.

For clarity, let us call \mathbf{Q} the orthogonal matrices.

The product $\mathbf{Q}^{\mathsf{T}}\mathbf{Q}$ has the structure:

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- The standard basis of indicator vectors is an orthonormal basis
- The identity matrix I is orthogonal
- Any permutation matrix is orthogonal

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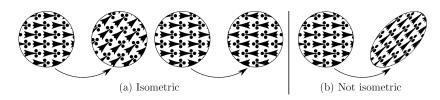
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Then, the operation

$$\mathbf{A}\mathbf{R}^{-1} = \mathbf{Q}$$

can be seen as transforming the columns of ${\bf A}$ to make them orthogonal.

It turns out that any matrix ${\bf A}$ admits the factorization:

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Since
$$\mathbf{Q} = \mathbf{A}\mathbf{R}^{-1}$$
, then

$$\operatorname{col} \mathbf{Q} = \operatorname{col} \mathbf{A}$$

means that the columns of ${\bf Q}$ are an orthonormal basis for ${\rm col}~{\bf A}.$

Better conditioning

How does this help us?

Recall the "almost parallel" numerical issue we encountered before:

$$\mathbf{A} = \begin{pmatrix} | & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots \\ | & | & \end{pmatrix} = \begin{pmatrix} 0 & 0.0001 \\ \vdots & \vdots & \cdots \\ 1 & 1.0001 \end{pmatrix}$$

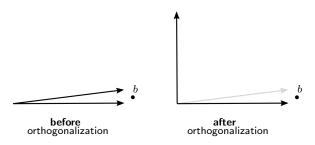
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With orthogonalization, we make the problem better conditioned by simply applying invertible transformations to the columns of A.



Using QR factorization, the normal equations:

$$\mathbf{A}^{\top}\mathbf{A}\mathbf{x} = \mathbf{A}^{\top}\mathbf{b}$$

$$(\mathbf{Q}\mathbf{R})^{\top}\mathbf{Q}\mathbf{R}\mathbf{x} = (\mathbf{Q}\mathbf{R})^{\top}\mathbf{b}$$

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$$\mathbf{A}^{\mathsf{T}}\mathbf{A}\mathbf{x} = \mathbf{A}^{\mathsf{T}}\mathbf{b}$$

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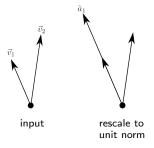
$$\mathbf{R}\mathbf{x} = \mathbf{Q}^{\top}\mathbf{b}$$

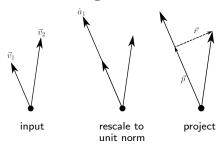
One additional property of matrix ${f R}$ in QR decomposition, is that it is upper triangular.

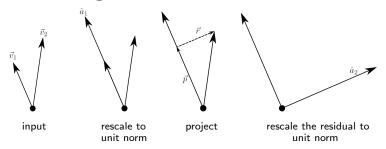
$$U = egin{bmatrix} u_{1,1} & u_{1,2} & u_{1,3} & \dots & u_{1,n} \ & u_{2,2} & u_{2,3} & \dots & u_{2,n} \ & & \ddots & \ddots & dots \ & & & \ddots & \ddots & dots \ & & & \ddots & u_{n-1,n} \ 0 & & & u_{n,n} \end{bmatrix}$$

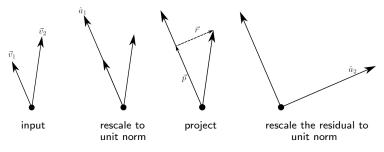
This makes the system immediate to solve by back-substitution.





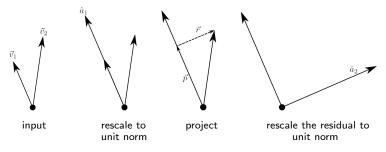






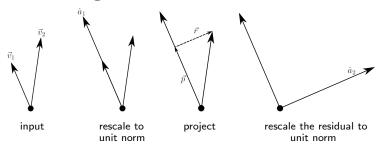
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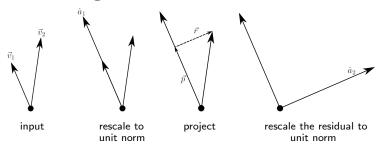
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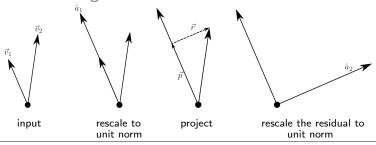
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- We can introduce more input vectors one at a time, and orthogonalize them with respect to the previous ones
- If the input vectors are columns of A, the orthogonalized vectors are the columns of Q. Further, we can compute $R = Q^{T}A$.



function GRAM-SCHMIDT
$$(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k)$$
 $ightharpoonup$ Computes an orthonormal basis $\hat{a}_1, \dots, \hat{a}_k$ for span $\{\vec{v}_1, \dots, \vec{v}_k\}$ $ightharpoonup$ Assumes $\vec{v}_1, \dots, \vec{v}_k$ are linearly independent.

$$\hat{a}_1 \leftarrow \vec{v}_1 / \|\vec{v}_1\|_2$$
 > Nothing to project out of the first vector

for
$$i \leftarrow 2, 3, \dots, k$$

$$\vec{p} \leftarrow \vec{0}$$

for
$$j \leftarrow 1, 2, \dots, i-1$$

$$\vec{p} \leftarrow \vec{p} + (\vec{v}_i \cdot \hat{a}_j)\hat{a}_j$$

$$\vec{r} \leftarrow \vec{v}_i - \vec{p}$$

$$\hat{a}_i \leftarrow \vec{r}/\|\vec{r}\|_2$$

return
$$\{\hat{a}_1,\ldots,\hat{a}_k\}$$

$$\triangleright \text{ Projection of } \vec{v}_i \text{ onto span } \{\hat{a}_1, \dots, \hat{a}_{i-1}\}$$

Normalize this residual and add it to the basis

Let us take a closer look at the dimensions:

$$Ax = b$$

In general, A will be tall with size $m \times n$.

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- ullet ...therefore, we can discard the last n-k columns of ${f Q}$

Suggested reading

Read Sections 5.1 - 5.4 of the book:

J. Solomon, "Numerical Algorithms"