Metodi Numerici dell'Informatica

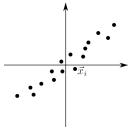
Spectral decomposition

Emanuele Rodolà rodola@di.uniroma1.it



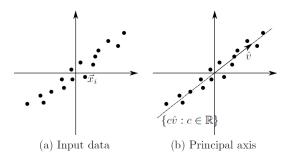
Motivation

Consider the two-dimensional data in this plot:



(a) Input data

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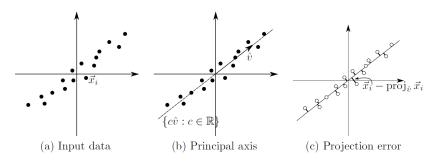


 ${f Q}$: Find the vector ${f v}$ such that each data point ${f x}_i$ can be written as

$$\mathbf{x}_i = c_i \mathbf{v}$$

where each \mathbf{x}_i has its own c_i

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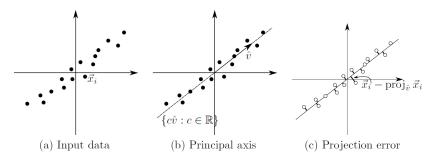


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$$\min_{\mathbf{v}} \sum_{i} \|\mathbf{x}_{i} - \operatorname{proj}_{\mathbf{v}} \mathbf{x}_{i}\|_{2}^{2}$$
s.t. $\|\mathbf{v}\|_{2} = 1$

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$$\min_{\mathbf{v}} \sum_{i} \|\mathbf{x}_{i} - (\mathbf{x}_{i}^{\top} \mathbf{v}) \mathbf{v}\|_{2}^{2}$$
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$$\min_{\mathbf{v}} \sum_{i} (\mathbf{x}_{i} - (\mathbf{x}_{i}^{\top} \mathbf{v}) \mathbf{v})^{\top} (\mathbf{x}_{i} - (\mathbf{x}_{i}^{\top} \mathbf{v}) \mathbf{v})$$
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$$\min_{\mathbf{v}} \sum_{i} (\|\mathbf{x}_{i}\|_{2}^{2} - 2(\mathbf{x}_{i}^{\top}\mathbf{v})(\mathbf{x}_{i}^{\top}\mathbf{v}) + (\mathbf{x}_{i}^{\top}\mathbf{v})^{2}\|\mathbf{v}\|_{2}^{2})$$
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$$\begin{split} \min_{\mathbf{v}} \;\; & \sum_{i} (\|\mathbf{x}_i\|_2^2 - 2(\mathbf{x}_i^{\top}\mathbf{v})^2 + (\mathbf{x}_i^{\top}\mathbf{v})^2 \|\mathbf{v}\|_2^2) \\ \text{s.t.} \;\; & \|\mathbf{v}\|_2 = 1 \end{split}$$

$$\min_{\mathbf{v}} \sum_{i} (\|\mathbf{x}_i\|_2^2 - (\mathbf{x}_i^{\top} \mathbf{v})^2)$$

s.t. $\|\mathbf{v}\|_2 = 1$

$$\min_{\mathbf{v}} - \sum_{i} (\mathbf{x}_{i}^{\top} \mathbf{v})^{2}$$

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$$\min_{\mathbf{v}} \ - \|\mathbf{X}^{\top}\mathbf{v}\|_{2}^{2}$$

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where matrix ${f X}$ contains the vectors ${f x}_i$ as its columns.

$$\max_{\mathbf{v}} \|\mathbf{X}^{\top}\mathbf{v}\|_{2}^{2}$$

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where matrix X contains the vectors x_i as its columns.

This can also be written as

$$\begin{aligned} \max_{\mathbf{v}} \ \mathbf{v}^{\top} \underbrace{\mathbf{X} \mathbf{X}^{\top}}_{\mathrm{symmetric}} \mathbf{v} \\ \mathrm{s.t.} \ \|\mathbf{v}\|_{2} &= 1 \end{aligned}$$

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The global maximizer v^* of this problem is the principal component of the data contained in the matrix X.

Eigenvectors and eigenvalues

An eigenvector $\mathbf x$ of a square matrix $\mathbf A$ is any vector satisfying

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for some (possibly complex) number $\boldsymbol{\lambda}$ that we call eigenvalue.

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The scale of an eigenvector is not important. In particular:

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Clearly, x and -x are both eigenvectors with the same eigenvalue.

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In other words, x is an eigenvector of $T^{-1}AT$ with eigenvalue λ .

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We say that ${\bf B}={\bf T}^{-1}{\bf A}{\bf T}$ is a similarity transformation. ${\bf A}$ and ${\bf B}$ have the same eigenvalues.

A few more basic facts that will become useful later:

$$\mathbf{Q}\mathbf{x} = \lambda\mathbf{x}$$

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$$\|\mathbf{Q}\mathbf{x}\|_2^2 = \|\lambda\mathbf{x}\|_2^2$$

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- Diagonal and upper-triangular matrices
 The eigenvalues are the entries along the main diagonal.
- Commuting matrices
 Consider two matrices A and B. One can prove:

 $\mathbf{AB} = \mathbf{BA} \quad \Leftrightarrow \quad \mathbf{A} \text{ and } \mathbf{B} \text{ have the same eigenvectors}$

Big questions

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- What to do with them?

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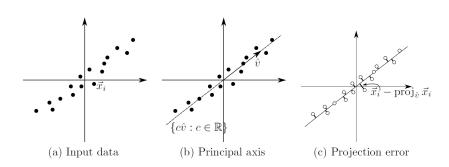
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$$\mathbf{A}\mathbf{y} = \sum_{i} \alpha_{i} \lambda_{i} \mathbf{x}_{i}$$

Back to our motivation:

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The ratio $\frac{\mathbf{v}^{\top} \mathbf{A} \mathbf{v}}{\|\mathbf{v}\|_2^2}$ is called Rayleigh quotient.

A matrix A is symmetric if $A = A^{\top}$.

A matrix **A** is symmetric if $\mathbf{A} = \mathbf{A}^{\top}$.

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$$\lambda_i \mathbf{x}_i^{\top} \mathbf{x}_j = \lambda_j \mathbf{x}_i^{\top} \mathbf{x}_j$$

For the equality to hold, it must be $\mathbf{x}_i^{\top}\mathbf{x}_j=0$, i.e. \mathbf{x}_i and \mathbf{x}_j are orthogonal.

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Observe the similarity with our motivational problem. We can modify it to solve for all eigenvectors and eigenvalues:

$$\begin{aligned} \min_{\mathbf{X}} \ \mathrm{tr}(\mathbf{X}^{\top} \mathbf{A} \mathbf{X}) \\ \mathrm{s.t.} \ \mathbf{X}^{\top} \mathbf{X} &= \mathbf{I} \end{aligned}$$

Finding eigenvalues

Power iteration

Very simple algorithm to find the largest eigenvalue/eigenvector:

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```
function Normalized-Iteration(A) \vec{v} \leftarrow \text{Arbitrary}(n) for k \leftarrow 1, 2, 3, \dots \vec{w} \leftarrow A\vec{v} \vec{v} \leftarrow \vec{w}/\|\vec{w}\| return \vec{v}
```

The normalization is needed to reduce the numerical error.

Without normalization, it will still converge to the principal eigenvector (but with a very large scale).

Inverse iteration

To find the smallest eigenvalue/eigenvector, we first observe that:

$$\mathbf{A}\mathbf{x} = \lambda\mathbf{x} \implies \mathbf{A}^{-1}\mathbf{x} = \frac{1}{\lambda}\mathbf{x}$$

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In practice, you don't invert ${\bf A}$ but apply LU decomposition.

For a matrix ${\bf A}$, we have eigenvalues $\{\lambda_i\}$ and eigenvectors $\{{\bf x}_i\}$.

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For example, we could first compute

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and then overwrite:

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and still have the guarantee that the eigenvalues stay the same.

Now observe:

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In other words, this operation preserves the eigenvalues:

$$\mathbf{A} \leftarrow \mathbf{RQ}$$

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If we keep doing this iteratively, we get the algorithm:

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• In other words, the eigenvalues of A_{∞} (and hence of A) equal the diagonal elements of R_{∞} up to sign.

Suggested reading

Read Sections 6.1.1, 6.2, 6.2.1, 6.3.1, 6.3.2, 6.3.3, 6.4.2 of the book:

J. Solomon, "Numerical Algorithms"