# Metodi Numerici dell'Informatica

Orthogonality and QR decomposition

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# Motivation

For any  $\mathbf{A} \in \mathbb{R}^{n \times m}$ , the linear problem:

Ax = b

can be seen as:

"write  ${\bf b}$  as a linear combination of the columns of  ${\bf A}$  with coefficients stored in  ${\bf x}$ ".

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$$\mathbf{A}\mathbf{x} = \begin{pmatrix} | & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots \\ | & | \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \end{pmatrix} = x_1 \begin{pmatrix} | \\ \mathbf{a}_1 \\ | \end{pmatrix} + x_2 \begin{pmatrix} | \\ \mathbf{a}_2 \\ | \end{pmatrix} + \cdots$$

#### Numerical instability

Consider the following situation:

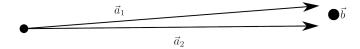
$$\mathbf{A} = \begin{pmatrix} | & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots \\ | & | \end{pmatrix} = \begin{pmatrix} 0 & 0.0001 \\ \vdots & \vdots & \cdots \\ 1 & 1.0001 \end{pmatrix}$$

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The columns are almost linearly dependent:



This problem is poorly conditioned, since we can write either:

$$\mathbf{b} \approx x_1 \mathbf{a}_1 + x_2 \mathbf{a}_2$$

$$\mathbf{b} \approx x_2 \mathbf{a}_1 + x_1 \mathbf{a}_2$$

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- A solution might not exist
- The solution might be unique

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It ultimately depends on the structure of the column space of A, which we define as  $\operatorname{col} A = \operatorname{span}(\mathbf{a}_1, \mathbf{a}_2, \dots)$ .

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Can we find a simpler representation for the column space?

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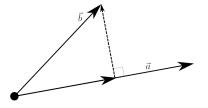
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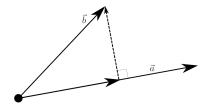
Can we deal with numerical instability explicitly?

# Orthogonality

Consider two vectors  ${\bf a}$  and  ${\bf b}$ . Which multiple of  ${\bf a}$  is closest to  ${\bf b}$ ?



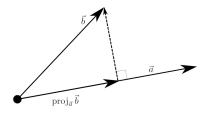
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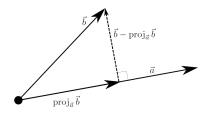


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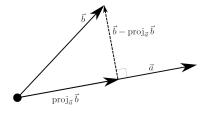


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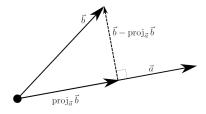
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Further, the complement  $\mathbf{b} - \mathrm{proj}_{\mathbf{a}}\mathbf{b}$  is orthogonal to  $\mathrm{proj}_{\mathbf{a}}\mathbf{b}$ .



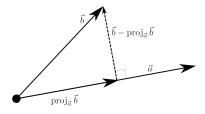
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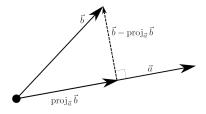
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Therefore:

$$\operatorname{proj}_{\mathbf{a}} \mathbf{b} = \frac{\mathbf{a}^{\top} \mathbf{b}}{\|\mathbf{a}\|_{2}^{2}} \mathbf{a}$$

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Assume we are given an orthonormal basis  $\{a_1,\ldots,a_k\}$ ; then, we can project onto its span by solving the problem:

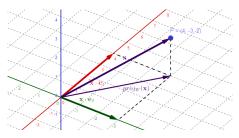
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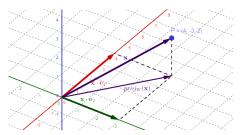


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The projection is:  $\operatorname{proj}_{\operatorname{span}(\mathbf{a}_1,\dots,\mathbf{a}_k)}\mathbf{b} = (\mathbf{a}_1^{\top}\mathbf{b})\mathbf{a}_1 + \dots + (\mathbf{a}_k^{\top}\mathbf{b})\mathbf{a}_k$ 

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In the lucky case where  $\mathbf{A}^{\top}\mathbf{A}=\mathbf{I}$  (i.e. matrix  $\mathbf{A}$  is orthogonal), we boil down to the trivial case. Further, this implies that  $\mathbf{A}^{-1}=\mathbf{A}^{\top}$ .

Let's analyze this more carefully.

For clarity, let us call  $\mathbf{Q}$  the orthogonal matrices.

The product  $\mathbf{Q}^{\mathsf{T}}\mathbf{Q}$  has the structure:

$$Q^{\top}Q = \begin{pmatrix} - & \vec{q}_1^{\top} & - \\ - & \vec{q}_2^{\top} & - \\ \vdots \\ - & \vec{q}_n^{\top} \end{pmatrix} \begin{pmatrix} \mid & \mid & & \mid \\ \vec{q}_1 & \vec{q}_2 & \cdots & \vec{q}_n \\ \mid & \mid & & \mid \end{pmatrix} = \begin{pmatrix} \vec{q}_1 \cdot \vec{q}_1 & \vec{q}_1 \cdot \vec{q}_2 & \cdots & \vec{q}_1 \cdot \vec{q}_n \\ \vec{q}_2 \cdot \vec{q}_1 & \vec{q}_2 \cdot \vec{q}_2 & \cdots & \vec{q}_2 \cdot \vec{q}_n \\ \vdots & \vdots & \ddots & \vdots \\ \vec{q}_n \cdot \vec{q}_1 & \vec{q}_n \cdot \vec{q}_2 & \cdots & \vec{q}_n \cdot \vec{q}_n \end{pmatrix}$$

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- The identity matrix I is orthogonal
- Any permutation matrix is orthogonal

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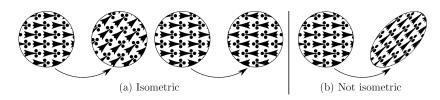
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In particular, suppose we can write:

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Then, the operation

$$\mathbf{A}\mathbf{R}^{-1} = \mathbf{Q}$$

can be seen as transforming the columns of  ${\bf A}$  to make them orthogonal.

It turns out that any matrix  ${\bf A}$  admits the factorization:

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Since 
$$\mathbf{Q} = \mathbf{A}\mathbf{R}^{-1}$$
, then

$$\operatorname{col} \mathbf{Q} = \operatorname{col} \mathbf{A}$$

means that the columns of  ${\bf Q}$  are an orthonormal basis for  ${\rm col}~{\bf A}.$ 

### Better conditioning

How does this help us?

Recall the "almost parallel" numerical issue we encountered before:

$$\mathbf{A} = \begin{pmatrix} | & | \\ \mathbf{a}_1 & \mathbf{a}_2 & \cdots \\ | & | & \end{pmatrix} = \begin{pmatrix} 0 & 0.0001 \\ \vdots & \vdots & \cdots \\ 1 & 1.0001 \end{pmatrix}$$

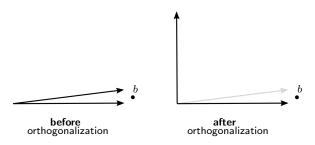
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With orthogonalization, we make the problem better conditioned by simply applying invertible transformations to the columns of A.



Using QR factorization, the normal equations:

$$\mathbf{A}^{\top}\mathbf{A}\mathbf{x} = \mathbf{A}^{\top}\mathbf{b}$$

$$(\mathbf{Q}\mathbf{R})^{\top}\mathbf{Q}\mathbf{R}\mathbf{x} = (\mathbf{Q}\mathbf{R})^{\top}\mathbf{b}$$

Using QR factorization, the normal equations:

$$\mathbf{A}^{\mathsf{T}}\mathbf{A}\mathbf{x} = \mathbf{A}^{\mathsf{T}}\mathbf{b}$$

$$\mathbf{R}^{\top}\mathbf{Q}^{\top}\mathbf{Q}\mathbf{R}\mathbf{x} = \mathbf{R}^{\top}\mathbf{Q}^{\top}\mathbf{b}$$

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And since  $\mathbf{R}$  is invertible:

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And since **R** is invertible:

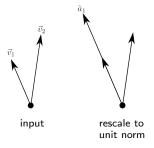
$$\mathbf{R}\mathbf{x} = \mathbf{Q}^{\top}\mathbf{b}$$

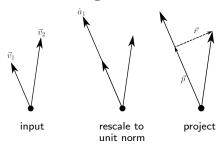
One additional property of matrix  ${f R}$  in QR decomposition, is that it is upper triangular.

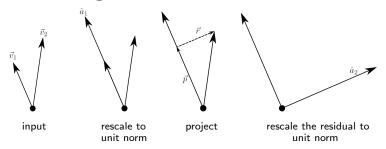
$$U = egin{bmatrix} u_{1,1} & u_{1,2} & u_{1,3} & \dots & u_{1,n} \ & u_{2,2} & u_{2,3} & \dots & u_{2,n} \ & & \ddots & \ddots & dots \ & & & \ddots & \ddots & dots \ & & & \ddots & u_{n-1,n} \ 0 & & & u_{n,n} \end{bmatrix}$$

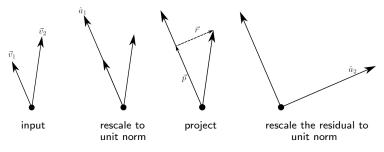
This makes the system immediate to solve by back-substitution.





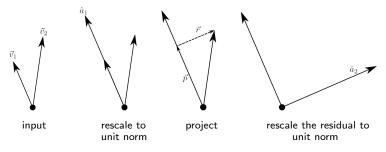






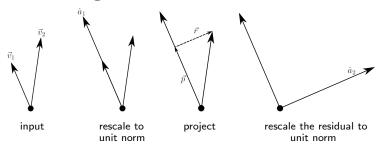
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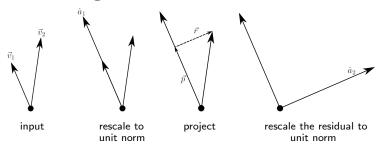
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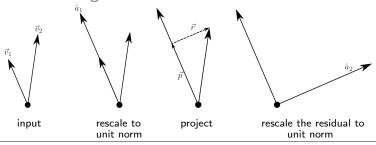
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- We can introduce more input vectors one at a time, and orthogonalize them with respect to the previous ones
- If the input vectors are columns of A, the orthogonalized vectors are the columns of Q. Further, we can compute  $R = Q^{T}A$ .



function GRAM-SCHMIDT
$$(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k)$$
  $ightharpoonup$  Computes an orthonormal basis  $\hat{a}_1, \dots, \hat{a}_k$  for span  $\{\vec{v}_1, \dots, \vec{v}_k\}$   $ightharpoonup$  Assumes  $\vec{v}_1, \dots, \vec{v}_k$  are linearly independent.

$$\hat{a}_1 \leftarrow \vec{v}_1 / \|\vec{v}_1\|_2$$
 > Nothing to project out of the first vector

for 
$$i \leftarrow 2, 3, \dots, k$$

$$\vec{p} \leftarrow \vec{0}$$

for 
$$j \leftarrow 1, 2, \dots, i-1$$

$$\vec{p} \leftarrow \vec{p} + (\vec{v}_i \cdot \hat{a}_j)\hat{a}_j$$

$$\vec{r} \leftarrow \vec{v}_i - \vec{p}$$

$$\hat{a}_i \leftarrow \vec{r}/\|\vec{r}\|_2$$

return 
$$\{\hat{a}_1,\ldots,\hat{a}_k\}$$

$$\triangleright \text{ Projection of } \vec{v}_i \text{ onto span } \{\hat{a}_1, \dots, \hat{a}_{i-1}\}$$

Normalize this residual and add it to the basis

Let us take a closer look at the dimensions:

$$Ax = b$$

In general, A will be tall with size  $m \times n$ .

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- ullet ...therefore, we can discard the last n-k columns of  ${f Q}$

# Suggested reading

Read Sections 5.1 - 5.4 of the book:

J. Solomon, "Numerical Algorithms"