CME341 HDL Class Notes

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INTRODUCTION 2

1 Introduction

Designing a digital circuit is almost always divided into several distinct tasks. The flow chart shown in Figure 1 illustrates the general design process (also referred to as design flow). The boldface text represents the step in the design process and the normal text shows the tools used for that step. One of these tasks (block 4) involves synthesizing circuits with HDL tools. This class concentrates on developing skills for synthesizing circuits with Verilog HDL. It also introduces some techniques that are used in the last three blocks.

The process described in Figure 1 is simplified but captures the essence of a practical process. The chart indicates that the design and synthesis is completed before the circuit is debugged in the simulator. Clearly the synthesis must be completed before the debugging can be completed. However, one of the tasks in the debugging process is usually completed before the circuit is designed and synthesized. That task is writing the HDL that generates the signals that will be used to excite the design when it is being debugged.

1 INTRODUCTION 3

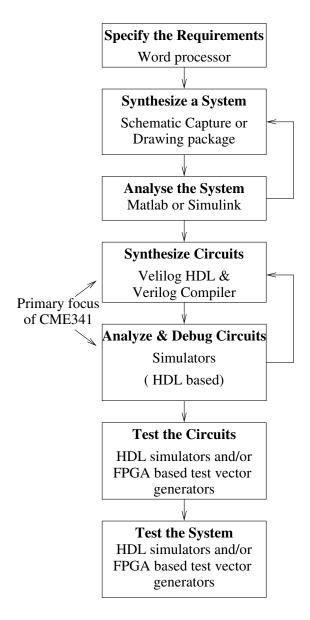


Figure 1: Design Process

2 Wiring

2.1 Motivation

Most engineering students have looked inside a personal computer or stereo amplifier and seen the printed circuit boards that hold electronic components and the printed tracks that act as the wires connecting the components together. While they are not visible, there are wiring tracks inside Integrated Circuits (ICs) that connect the electronic components fabricated inside the IC.

Originally wiring plans for integrated circuits, for example first generation microprocessors, were in the form of schematic diagrams. Now the wiring plans for ICs are done with an HDL like Verilog HDL.

FPGAs have been steadily increasing in size while their cost per gate has been decreasing. The size of circuit at which they become cost competitive with ASICs (Application Specific Integrated Circuits) is steadily increasing. While FPGAs are in themselves ICs, they are special in that they are programmable. They contain thousands of a few different types of circuits (like "look-up-tables" and "flip/flops") that can be interconnected by programming the wiring connections, which by the way can be done in the field. The wiring plans for FPGAs are derived from the HDL.

The purpose of this section is to show how the Verilog HDL is used to specify the logical wiring connections. (The physical wiring plan is generated by a separate software program called a router. The router uses the output of the Verilog compiler to make the physical wiring plan.)

2.2 Block Diagrams in Schematic Diagram Form

2.2.1 Pulse Width Modulator

To explain how wiring information is embedded in schematic diagrams an example is used. The example is a pulse width modulator circuit. There are two inputs: a square clock and a 10 bit unsigned binary number. The output is a pulse train with the width of the pulse determined by the 10 bit input. (in other words the output is a periodic rectangular wave with a controlled duty cycle). The inputs and outputs as well as a simple timing diagram are shown in Figure 2.

2.2.2 Block Diagram of PULSE WIDTH MODULATOR

A Block diagram for a pulse width modulator circuit is shown in Figure 3. The master clock is called clk. It drives a 10-bit counter that runs continuously—counting from 000H to 3FFH then rolling over to 000H and so on.

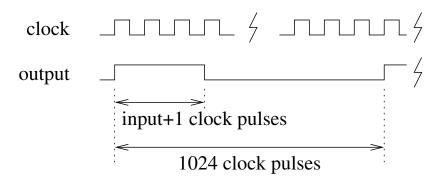
The pulse width control word is loaded into a register (reg_1) with the same clock edge that rolls counter_1 to 000H. This is done by enabling the reg_1 when counter_1 is all ones (i.e. counter = 3FFH).

The output, PWM_signal, is always set (i.e. forced high) with the same clock edge that rolls counter_1 to zero. The PWM signal is cleared "PW_cntl + 1" clock pulses later. Therefore, if

input 10 pulse_width_control output PWM_signal

clk

clock [



note: 'input' is 10 lines representing a 10-bit unsigned binary number

Figure 2: Inputs and Outputs for a pulse width modulator

 $PW_control = 000H$ then PWM_signal is high for 1 clock period. If $PW_cntl = 3FFH$, then PWM is not cleared and is high for 1024 clock periods.

Note: PWM is not cleared when PW_cntl = 3FFH. The reason is set/clear flip/flop circuit (i.e. sc_ff_1) is designed to have 'set' override 'clear'.

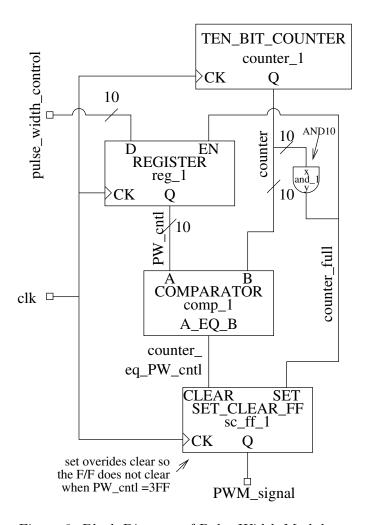


Figure 3: Block Diagram of Pulse Width Modulator

2.2.3 Symbols & Conventions used in Schematic Diagrams

Edge sensitive inputs

The convention shown in Figure 4 is used when indicating an input is edge sensitive.

Wire Connections

Figures 5 and 6 show examples of connected and unconnected wires in a schematic diagram.

Pins (input/output pins)

Input and output pins are always square. Input pins must be oriented such that the wire attaches to the bottom or the right side of the square (see Figure 7). Output pins are indicated by attaching

 $2 \quad WIRING$

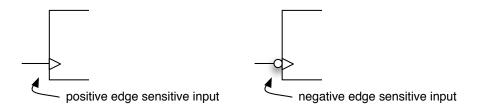


Figure 4: Edge Sensitive Inputs



Figure 5: Connected Wires

the wire to the top or left side of the square (see Figure 8).

On-Page connections

Line connectors are used to save the clutter that arises from drawing several long lines on a page (these lines represent the wires). The wire leaving a source is connected to a triangular symbol that looks like the tip of an arrow as shown in Figure 9 The arrows always point in the direction of power flow. The signal source connects to the base of the line connector arrow. The signal sink connects to the tip of the line connector arrow.

Note: There one source can be connected to several sinks.

Off-Page connections

Off-page connectors, as shown in Figures 10 and 11, are used to indicate the connection (i.e. the wire) extends to another page in the schematic diagram. Off-page connectors are shown in Figures 12 and 13 Again the arrow tip part of the connector points in the direction of power flow.



Figure 6: Wires with no connection

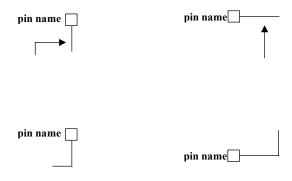


Figure 7: Input Pins

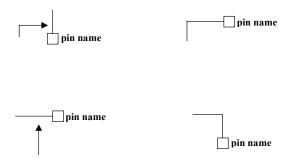


Figure 8: Output Pins



Figure 9: On-page Line Connectors (source on the right and sinks on the left)



Figure 10: An output (source) off-page connector.



Figure 11: An input (sink) off-page connector.

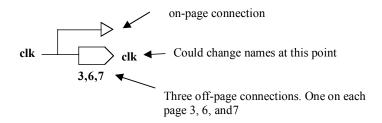


Figure 12: Line Connectors Example 1

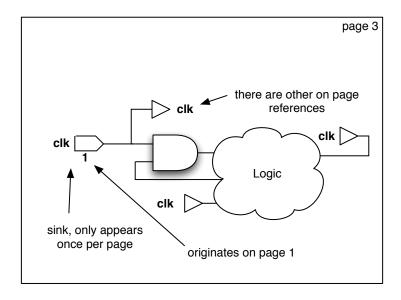


Figure 13: Line Connectors Example 2

2.3 Describing Block Diagrams in Verilog HDL

A verilog description of the Pulse Width Modulator (shown in Figure 3) is given below

```
module PWM_chip (clk, pulse_width_control, PWM_signal);
 input clk;
 input [9:0] pulse_width_control;
 output PWM_signal;
wire counter_full, counter_eq_PW_cntl;
wire [9:0] PW_cntl, counter;
REGISTER reg_1(.D(pulse_width_control),
                .CK(clk),
                .EN(counter_full),
                .Q(PW_cntl));
TEN_BIT_COUNTER counter_1(.CK(clk),
                            .Q(counter));
 COMPARATOR comp_1(.A(PW_cntl),
                     .B(counter),
                      .A_EQ_B(counter_eq_PW_cntl)
AND10 and_1(.x(counter),
             .y(counter_full)
              );
SET_CLEAR_FF sc_ff_1(.clear(counter_eq_PW_cntl),
            .set(counter_full),
            .CK(clk),
            .Q(PWM_signal));
endmodule
```

- **REGISTER** is a prototype definition. It defines the circuit in sufficient detail for it to be built. There will be a verilog module called **REGISTER** in a separate file that completely defines its operation in terms of its inputs and outputs.
- reg_1 is the name of one instance of REGISTER. That is to say, reg_1 is the name of a hardware circuit that implements the functionality described in the verilog module called REGISTER. The verilog module called REGISTER, i.e. the definition of the prototype called REGISTER, can be used to make several identical circuits. When that is done each

must be given a different instance name.

ullet The text $.Q(PW_control)$ specifies that the Q of the instance reg_1 is connected to a wire called pw_control

3 Block Design with schematics and Verilog prototype specification

3.1 Synchronous Set/Clear Flip/Flop

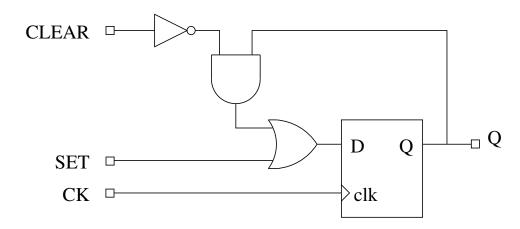


Figure 14: Set/Clear Flip/Flop with 'set' over riding 'clear'

In the above circuit, inputs and outputs are shown as pins on a chip. The behavior of the circuit of **Figure 14** is as follows:

- If set and clear are both low then D = Q and the f/f is loaded with the same value as it had before.
- If set = 1 then D = 1 and the f/f is set on the next clock edge regardless of "clear" and "Q".
- If clear = 1 and set = 0, then regardless of Q, D = 0. Therefore the f/f is cleared on the next clock edge.

A Verilog description for the synchronous set/clear flip/flop is

```
module SET_CLEAR_FF(CK,CLEAR,SET,Q);
input CK, CLEAR, SET;
output Q;
reg Q;
always @(posedge CK)
if (SET == 1'b1) Q => 1'b1;
else if (CLEAR == 1'b1) Q => 1'b0;
else Q => Q;
endmodule
```

3.2 Comparator

A 10-bit comparator is a simple circuit. The A_EQ_B output is asserted if and only if the 10 bits of input B are equal to the corresponding 10 bits of input A. The schematic diagram is shown in

Figure 15.

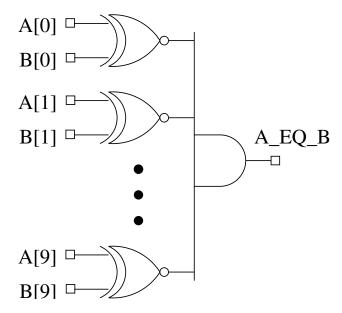


Figure 15: 10-Bit comparator

A verilog description for the comparator is

```
module COMPARATOR (A, B, A_EQ_B);
input [9:0] A, B;
output A_EQ_B;
assign A_EQ_B = &(A^^B);
endmodule
```

 $4 ext{ TESTING}$ 14

4 Testing

Approaches:

• Build and test with lab equipment (only an option for FPGA or discrete circuit boards)

- Build and test using special FPGA circuits to excite the circuit under test
- Simulate the circuit under test. Also need to write an HDL that will generate the excitation signals for the circuit under test.

5 Specification of a Prototype

In verilog the word prototype is used to mean "definition of a circuit", which is equivalent to a schematic diagram. Prototypes are specified (i.e. described in Verilog HDL) inside keywords'module - endmodule'. Prototypes can be specified in two different styles or manners: in a structural manner or a behavioral manner.

A structural description is one that indicates exactly how functional blocks are connected to make the system work. A block diagram, which is a schematic diagram at the system level, is a structural description of a system. In large systems each block in the system block diagram could be viewed as a subsystem that could be described by a block diagram. There could be several hierarchical layers of block diagrams. However many hierarchical levels there may be, the lowest level blocks must be described in terms of basic circuit elements like 'inverters', 'and' gates and 'or' gates. These lowest level blocks are therefore described by schematic diagrams that show the basic circuit elements are how they are connected. These schematic diagrams are structural descriptions of the bottom level blocks.

In verilog, fundamental circuit elements called primitives must be explicitly connected. Therefore, any circuit described in Verilog HDL by primitives must be a structural description. The set of primitive include: not, and, nand, or, nor, xor and xnor gates.

5.1 Primitives

Primitives are low level logic functions built into the verilog language. They are instantiated like prototypes (i.e. like blocks in a block diagram), but don't have to be defined.

The port connections for primitives are made by position association. The output is always the first (i.e. on the left of) the port list. For example the verilog statement

```
or or_gate_1(output, input1, input2);
```

places a two input or gate in the circuit. It connects the output of the or gate to a wire named 'output' and connects the two inputs to wires called 'input1' and 'input2'.

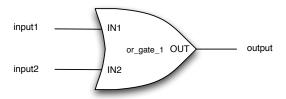


Figure 16: or Gate Instance

Additional primitives (more to the point these are pseudo primitives) available through Quartus and associated syntax can be found by typing "primitive" in the help index of QUARTUS (see Figure 17).

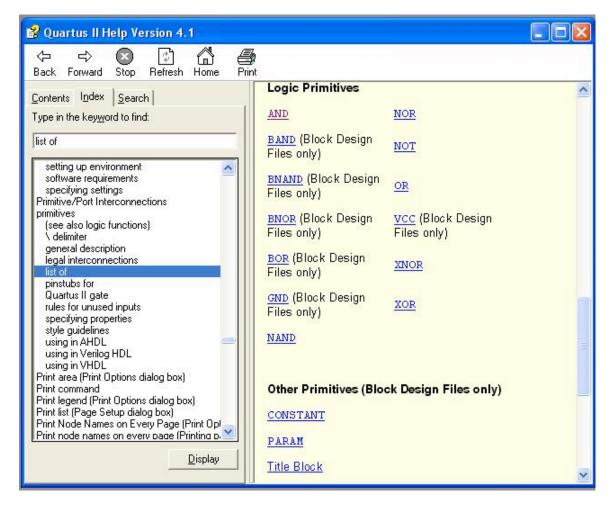


Figure 17: QUARTUS Primitive Help File

Example: 4-Bit Comparator

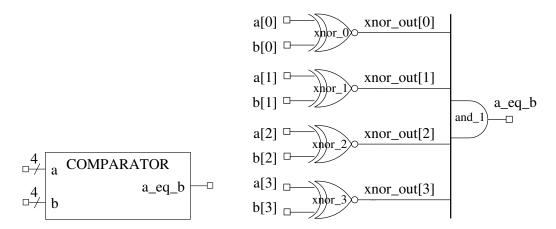


Figure 18: 4-Bit Comparator Pin-Out and Schematic

The schematic diagram given in Figure 18 is called an explicit structural description. It is called structural because the implementation is defined by specifying the elements to be used and the connections between them.

All of the gates used in the schematic of Figure 18 are verilog primitives. The equivalent explicit structural description in Verilog is:

```
module comparator(a, b, a_eq_b);
input [3:0] a, b;
output a_eq_b;

wire [3:0] xnor_out;

xnor xnor_0(xnor_out[0], a[0], b[0]);
xnor xnor_1(xnor_out[1], a[1], b[1]);
xnor xnor_2(xnor_out[2], a[2], b[2]);
xnor xnor_3(xnor_out[3], a[3], b[3]);
and and_1(a_eq_b, xnor_out[0], xnor_out[1], xnor_out[2], xnor_out[3]);
endmodule
```

5.2 The assign statement

The assign statement is used to define an output in terms of boolean logic. The symbol used for the 'exclusive-nor' function is ~^ and the & is used for the 'and' function. When a circuit is described by a boolean equation it built from and/or/ex-or gates in the way specified by the expression. Therefore circuits expressed as boolean equations are called implicit structural descriptions.

An implicit structural verilog HDL description for the comparator is

```
module comparator(a, b, a_eq_b);
input [3:0] a, b;
output a_eq_b;
wire [3:0] xnor_out;
assign xnor_out = a ~^ b;
assign a_eq_b = &xnor_out;
endmodule
```

Note: When an operator is placed between two vectors it builds multiple two-input one-output gates. One gate for each signal (each bit) in the vector. An operator so placed is called a bit-wise operator. In this case the xnor operator ~^ is a bitwise operator. **Note:** The expression '&xnor_out' is equivalent to '(xnor_out[0] & xnor_out[1] & xnor_out[2] & xnor_out[3])'. When an operator, in this case the and symbol &, is placed in front of a vector it is called a reduction operator. It builds a multiple input - single output gate where the inputs are the individual signals in the vector.

Note: The two assign statements could have been combined, in which case the xnor_out wire would not have to be defined. The verilog description would simplify to

```
assign a_{eq_b} = \&(a^{\circ} b);
```

The following logical operations can be used in assign statements

```
inverter (not) (reduction only)
and
and
and (reduction only)
or
in nor (reduction only)
axor
axnor
axnor
```

6 Building Fundamental Circuits

6.1 Schematic and verilog description for a set_clear latch

The schematic diagram for a set_clear latch is given in Figure 19.

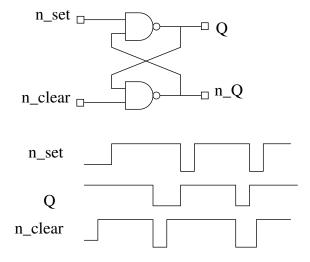


Figure 19: Set/Clear Latch

The verilog description for a set_clear latch (or set_clear flip/flop) follows.

This is an explicit structural description using the primitive 'nand'. The connection is determined by position (for primitives the output is always the left most in the list).

6.2 Schematic diagram and verilog description for a transparent latch

The schematic diagram for a transparent latch is given in Figure 20

The verilog description of a transparent latch uses a 'set_clear' latch. The prototype for the 'set_clear_latch' can be and usually is in another file. This file must be included into the 'transparent_latch' project. This is done by selecting:

Project → Add/Remove Files in Project... and adding the path of the file you wish to add.

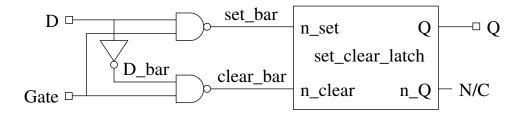


Figure 20: Transparent Latch

A verilog description for the transparent latch follows.

```
module transparent_latch(D, Gate, Q);
input D, Gate;
output Q;
wire D_bar, set_bar, clear_bar;
assign set_bar = ~(D & Gate);
assign clear_bar = ~((~D) & Gate);
set_clear_latch latch_1(.n_set(set_bar),
                        .n_clear(clear_bar),
                        .Q(Q)); // n_Q output not used
```

endmodule

7 Compiling a Verilog HDL Description Using QUARTUS

The operation of the Quartus compiler will be demonstrated using a set_clear latch built from two nand gates. The instructions parallel that of assignment 2 where the students are asked to build, compile and simulate a set_clear latch built from two nor gates. The difference is the inputs are active low for the 'nand gate' implementation and active high for the 'nor gate' implementation.

1. Open Quartus by selecting $\mathbf{start} \to \mathbf{all}$ programs $\to \mathbf{electrical}$ engineering $\to \mathbf{Quartus}$ 12.X. There will be two items named $\mathbf{Quartus}$ 12.X one will be a folder and the other executable. Select the executable. It will have a blue icon.

The intention for the near future is to make Quartus available as a web application that runs on a server in the engineering building. This web-app can be run from any computer in the computer labs or from home providing your home computer has a windows operating system and the explorer web browser. The current problem with the web-app version is that it can not be used to configure the FPGA on the DE-2 board. This means the web-app version can not be used to do the laboratories.

The web-app version is opened as follows:

- (a) Open the web app by typing the URL www.engr.usask.ca/engr-apps into the web browser.
- (b) When the window opens (it may take a while) scroll down to "electrical engineering" and click on "quartus 12". This will bring up another window. Click on open.
- (c) Yet another window will open requesting a user name and password (you may need to click on "other account" to get a chance to enter your user name). The user name must be your NSID preceded by USASK\ (i.e. user name = USASK\NSID). The password is the login password for your NSID.
- (d) After entering the user name and password you will be connected to a virtual machine. The desktop for the virtual machine will take over your screen. NOTE: Should at any time you need to access your computer the desktop for the virtual machine can be minimized.
- (e) If the "Quartus II 12.X (64bit)" shortcut does not appear on the virtual desktop it can be found by: **start** → **computer** → **local disk (C:)** and double clicking on "Quartus shortcut".

Once found, double click on the shortcut "Quartus II 12.0 (64bit)".

- 2. A "Getting Started With Quartus II Software" window should appear. In that window select "Create a New Project (New Project Wizard)" If the "Getting Started With Quartus II Software" window does not appear, then pull down the file menu and select "New Project Wizard".
- 3. Read the introduction page for some general information and then click Next to move to page 1 of the New Project Wizard. Choose/create an appropriate directory for this project.

The project must be in a folder on one of your system drives, preferably the H-drive. **Do not** make the folder on any of the drives on the virtual machine as any files saved on these drives will be lost upon log out or if the virtual machine crashes. To set up a folder click on the ellipses on the right hand side of the entry line for the project name. After clicking on the ellipses select the (H:) drive (near the bottom left corner of the window).

Name the project folder "set_clear_latch". Give the project and the top-level entity the same name, which is "set_clear_latch". Click Next.

- 4. Click Next to skip page 2. On page 3, pull down the selection list for the 'family' box.
 - (a) If the development board you intend to use is the DE2 board select Cylcone II, next select the radio button to assign a specific device and then in the device section select **EP2C35F672C6**, which is the part number of the FPGAs on the DE2 printed circuit boards used in the CME341 Labs.
 - (b) If the development board you intend to use is the DE2-115 board select Cylcone IV E, next select the radio button to assign a specific device and then in the device section select **EP4CE115F29C7**, which is the part number of the FPGAs on the DE2-115 printed circuit boards that are also used in the CME341 Labs. The DE-115 board are used in the DSP technology stream labs.

Then click next.

- 5. On page 4 on the line where the tool type is simulation, select "Modelsim-Altera" for tool name and "Verilog" for format. Click next.
- 6. This page summarizes the settings for the project. Take a quick look and then click finish.
- 7. From the Quartus II window select "File" from the top menu, then "New". This will open a window. In that window Under "Design Files", select "Verilog HDL File". Click OK. This will open a editor window.
- 8. In the editor window, write an explicit structural description the 'nand gate' set/clear latch shown earlier in the notes. (NOTE: The module must have the same name that was listed in the "the top level entity" box in the New Project Wizard i.e. it must be named "set_clear_latch"). Save the file as "set_clear_latch.v". The file name is always the same as the top level module name (the name and appropriate folder should come up automatically and the .v extension will be added automatically).

- 9. Compile the project by selecting "Processing" from the top menu. Click on "Start Compilation". If there are any errors (red print), alter your Verilog code appropriately. Otherwise, click OK in the information box telling you the compilation was successful.
- 10. While the compiler is running it will print information (green print), warnings (blue print) and errors (red print). Most of the of the time a warning means something is wrong. In this case there will be a few warnings that will be explained at a later time. One of the warnings indicates that the circuit that was built has feedback and appears be a latch. There is always the potential for circuits with feedback to oscillate so when this is detected by the compiler it prints a warning.
- 11. Upon successful completion of a compilation, Quartus II creates a couple of new folders. The first folder/directory it creates is called "simulation" and it is located inside the project folder. It creates a second folder/directory called "modelsim" inside the simulation folder. Several files are placed in this folder including an output file named "set_clear_latch.vo". The .vo file contains worst case propagation delay information so the simulator can simulate the circuit that was constructed by the compiler. Other .vo files are also created, the number of which depend on the FPGA family selected. Only two .vo files are produced for the Cyclone II family while four are produced by the Cyclone IV E family. In both cases the file that will be imported into the simulator is "set_clear_latch.vo".

8 Simulation: Test Bench and Software Tool

8.1 Test Bench

The Quartus II compiler produces a Verilog HDL file that has the same name as the top-entity input file, but with the extension .vo. The .vo file differs from the .v file in that it describes the circuit implemented by the compiler in complete detail, which means it includes all the propagation delays. The .vo file can be used in a Verilog simulator to exactly model the circuit that was built by the compiler.

This .vo file can not in compiled in Quartus II because it will contain Verilog HDL instructions that can not be synthesized, e.g. the propagation delay instructions.

A Verilog HDL simulator is of great help in debugging a circuit (i.e. finding and correcting flaws in the design). The circuit being debugged is sometimes called the "device under test" or "DUT".

A simulator has three functions:

- 1. It generates the input signals (i.e. the stimuli) for the circuit being debugged. That is it acts like a signal generator.
- 2. It models the DUT i.e. the circuit that is being debugged. That is it simulates the circuit that was built by the Quartus II compiler.

The circuit can be modelled with or without all the propagation delays included.

- (a) The simplest and the one that runs the fastest is one that does not include the propagation delays. This is called a functional model. The DUT is modelled without consideration for propagation delay.
 - A functional model does not need to know anything about the target technology. The functional model does not include propagation delays and so can not be used to check timing. The file used by the simulator is the .v file (i.e. the same file that is used by Quartus II).
- (b) The model that include propagation delays is called a timing model. It models the circuit that is to be debugged exactly as it is implemented in the target technology complete with all propagation delays. This model is used to check if the circuit meets timing.
 - The timing model will be used for all the assignments in this class. The circuits built in this class are so small the computation time is not significant so there is no need to run a functional simulation.

The .vo file produced by a Quartus compilation is a timing model of the circuit. In fact Quartus II produces two .vo files. One takes on the name of the top entity. This models a circuit using the worst case (longest possible) propagation delays. The other takes on the name of the top entity with a _fast appended to it. The _fast file models the

circuit using the best case (smallest possible) propagation delays. The worst case model will be used as the input to the simulator for all assignments in this class.

3. It displays the simulated output waveforms (also displays the input waveforms (stimuli)).

The simulator is an executable program (most likely a C program) with a GUI interface. The simulator is controlled through the GUI.

The top entity (i.e. top module), which is the Verilog HDL input to the compiler, is referred to as a test bench so the name of the top module often includes the word "testbench" or "test_bench".

While a simulator and Quartus both compile Verilog HDLs, the compiler in the simulator is very different than the compiler in Quartus. The compiler in Quartus produces two things:

- 1. A file that can be downloaded to the FPGA to configure it (i.e. programs it) to implement the circuit described by the Verilog HDL.
- 2. Another Verilog HDL with a .vo extension that describes the circuit that was built in complete detail, which includes all the propagation delays.

The operation of the Modelsim-Altera simulator will be demonstrated with a test bench for the set_clear_latch circuit. The simulator will use set_clear_latch.vo, which was generated by Quartus when the project set_clear_latch was compiled.

The Verilog HDL for the test bench is given below.

```
'timescale 1 ns / 1 ps // compiler directive that must be included
                       // the first time listed is used for the unit
                       // of time on waveform plots
                       // the second time listed indicates precision.
                       // All delays are rounded to the "precision time".
       // allowable units of time are ms, us, ns, and ps
       // allowable numbers are 1, 10, 100
module set_clear_latch_testbench(); // no inputs or outputs
reg n_set, n_clear;
wire Q, n_Q;
initial
#150 $stop; // stop the simulation at 150 ns
initial
begin
#10 n_{set} = 1'b0;
                    // schedule n_set to be 0 at t=10 ns
#10 n_{set} = 1'b1;
                    // schedule n_set to be 1 at t=10+10=20 ns
#55 n_set = 1'b1;
                    // schedule n_set to be 1 at t=20+55=75 ns
end
initial
#65 n_{set} = 1'b0;
                    // schedule n_set to be 0 at t=65 ns
```

```
initial
begin
n_{clear} = 1'b1;
                      // schedule n_clear to be 1 at t=0
#50 n_clear = 1'b0;
                      // schedule n_clear to be 0 at t=50 ns
#5 n_clear = 1'b1;
                     // schedule n_clear to be 1 at t=50+5=55 ns
#10 n_{clear} = 1'b0;
                      // schedule n_clear to be 0 at t=55+10=65 ns
#15 n_clear = 1'b1;
                      // schedule n_clear to be 0 at t=65+15=80 ns
end
// instantiate the prototype for the set clear latch
set_clear_latch latch_1(.n_set(n_set),
                         .n_clear(n_clear),
                         Q(Q),
                         .n_Q(N_Q)
                        );
```

endmodule

**It is pointed out the text that follows a double slash, i.e. //, is a comment.

The testbench module declaration must be preceded with a compiler directive that indicates the unit size for time and the round off precision that should be used in the calculations. The line preceding the module declaration above contains the compiler directive 'timescale 1 ns / 1 ps. Two times are listed. The first is 1 ns. The second is 1 ps. The first indicates the units that will be specify time and delay in the testbench module. The second indicates the precision to which all times and delay will be rounded off. For the testbench above all numbers that indicate time are multiplied by 1 ns and after this multiplication the number is rounded to 1 ps. There are restrictions on the numbers and units of time that can be used in the 'timescale directive. The number must be either 1, 10, or 100. The units of time can be ms, us, ns and ps.

Next notice that the port list in the testbench module declaration does not list any inputs or outputs.

The first two lines inside the module declare signals to be a certain type. The signals "n_clear" and "n_set" must be declared type "reg" because they are created with a "initial" procedure. The signals "Q" and "n_Q" must be declared type "wire" because they are created inside an instantiation. Signal types will be explained more fully later.

The next line consists of the key word "initial", which signifies a procedure. The instruction that follows an initial is executed once. In this case the #150 \$stop instruction is executed once. The instruction has two parts. The first part, which is #150, creates a delay of 150 ns. The second part is \$stop which stops the simulation. The entire instruction reads wait 150 ns and then stop the simulation.

The second initial procedure is followed by several instruction inside a begin-end wrapper. All instruction inside the begin-end wrapper are executed once. This sequences of instructions changes the signal "n_set" at different times. The instructions makes "n_set" low at time t = 10 ns, high

10 ns later at t = 20 ns, high again 55 ns later at time t = 75 ns.

The third initial procedure also modifies "n_set" as well. It makes "n_set" low at t = 65 ns. Notice "n_set" is not defined before a time of 10 ns.

The fourth initial procedure defines signal "n_clear". If makes "n_clear" high at t = 0, low at t = 50 ns, high at t = 55 ns, low at t = 65 ns and finally high at t = 80 ns.

After the third initial procedure the Verilog HDL model for the set clear latch is instantiated. The signals "n_clear" and "n_set" generated in the test bench are connected to "n_clear" and "n_set" inputs of the set_clear_latch. The outputs of the set_clear_latch are connected to the wires Q and n_Q in the test bench.

Simulation with Modelsim-Altera

1. Open Modelsim-Altera by selecting start \rightarrow all programs \rightarrow electrical engineering \rightarrow Modelsim-Altera.

The intention for the near future is to make Modelsim-Altera available as a web application that runs on a server in the engineering building. This web-app can be run from any computer in the computer labs or from home providing your home computer has a windows operating system and the explorer web browser.

The web-app version is opened as follows:

- (a) If you are already running the desktop for the virtual machine that was used for Quartus II, bring the desktop to the foreground and jump to instruction **1f**. If not then proceed to the next instruction.
- (b) Open the web app by typing the URL www.engr.usask.ca/engr-apps into the web browser.
- (c) When the window opens (it may take a while) scroll down to "electrical engineering" and click on "quartus 12". This will bring up another window. Click on open.
- (d) Yet another window will open requesting a user name and password (you may need to click on "other account" to get a chance to enter your user name). The user name must be your NSID preceded by USASK\ (i.e. user name = USASK\NSID). The password is the login password for your NSID.
- (e) After entering the user name and password you will be connected to a virtual machine. The desktop for the virtual machine will take over your screen. NOTE: Should at any time you need to access your computer, the desktop for the virtual machine can be minimized.
- (f) 'If the 'Modelsim-Altera 10.0d'" shortcut does not appear on the virtual desktop it can be found by: **start** → **computer** → **local disk (C:)** and double clicking on the folder "Quartus shortcut".

Once the shortcut called "Modelsim-Altera 10.0d" is found, double click on it.

- 2. Modelsim-Altera opens and brings up a pop-up window with license information. Inside this window there is a rectangular button called "jumpstart". Click on the "jumpstart" button to enter into Modelsim-Altera.
- 3. Upon entry a window will pop-up asking if you wish to create a new project or open an existing project. Select the new project option. This will bring up a "new project" window.

Note: A new project can also be created by selecting file \rightarrow new \rightarrow project.

- 4. The "new project" window has four fields.
 - (a) In the "Project Name" field enter set_clear_latch_testbench.
 - (b) In the "Project Location" field browse to find the directory where Quartus placed the .vo file "set_clear_latch.vo". That directory will be a sub directory of the Quartus project directory. It should be
 - · · · set_clear_latch/simulation/modelsim.
 - (c) Do not change the "Default Library Name" field. The default library name must be "work".
 - (d) Do not change the "Copy Settings From" field.

After filling in the "Project name" and "Project Location" fields, click OK.

- 5. A window will appear with four options. Choose "add an existing file". Then, in the window that pops up browse to select the file set_clear_latch.vo. Then click OK. Then close the window.
- 6. Create the test bench module using the text editor in Modelsim-Altera. Start the editor by selecting

 $file \rightarrow new \rightarrow source \rightarrow Verilog.$

Type in the set_clear_latch_testbench module given above. Save the file as set_clear_latch_testbench.v.

- Add file set_clear_latch_testbench.v to the project by selecting
 Project → Add to Project → Existing File and completing the box.
- 8. Compile both files by selecting Compile \rightarrow compile all.
- 9. Load the simulation by selecting

Simulate \rightarrow Start Simulation.

This will bring up a window with several tabs. If the "Design" tab is not selected then select it. With the design tab selected the window will show a list of libraries.

- (a) Expand the "work" library, which should be the one at the top of the list. Expanding the work library should list the two source files associated with the project just beneath the work library.
- (b) Click on the top entity, which is set_clear_latch_testbench. (The top entity is the highest level module, i.e. the module that no other module instantiates.) The selection should get written into the dialog box near the bottom of the window that is titled "Design Unit(s)".

- (c) **IMPORTANT** The first time you load your design into the simulator you must select a library that contains support data for the FPGA that is being simulated. Select the "Libraries" tab, near the center of the top of the window.
 - i. This should change the contents of the window to show two panes: the top pane is titled "search libraries" the bottom pane is called "search libraries first". Click the "add" button associated with the "search libraries" pane. This will bring up a yet another window.
 - ii. In that window click on the down arrow (do not click on browse). This will allow you to select one of the libraries that was listed in the original window. Scan down and select either cycloneii_ver for the Cyclone II FPGA or cycloneive_ver for the Cyclone IV E FPGA. Then click O.K.
 - iii. This will add the library "cycloneii_ver" or "cycloneive_ver" to the pane titled "Search Libraries". Click OK at the bottom of the window. This will load the design.
- (d) Once the design is loaded a main window will be partitioned into three windows. The window on the top left is called the "objects" window. It will contain a list of the signals. Select the signals (hold down cntl and click on them one at a time) then right click and select:
 - $Add \rightarrow To Wave \rightarrow Selected Signals$. This will open a new tab called "Wave" in the window on the right and it will transfer the selected signals to that tab.
- (e) To run the simulation select

$Simulate \rightarrow Run \rightarrow Run \text{ -All}.$

- This will run the simulation until it reaches a stop command. Once the simulation is completed the "set_clear_latch_testbench.v" file will be displayed in the left window with a big blue arrow pointing to the command that stopped the simulation.
- (f) Select the "Wave" tab on the window. Right click in this window (on the black part) and select "Zoom Full". This will display the waveforms for the length of the entire simulation, which is from 0 to 150 ns.

Navigating in the Wave Window

On the memu bar at the top of Modelsim-Alter 10.0d window there is a symbol that looks like a set of traffic lights. To the right of that set of traffic lights is a set of 8 symbols used to control the cursors. Clicking on the yellow symbol annotated with a + will add a cursors. Clicking on the yellow symbol annotated with a - will remove the active cursor. The other 6 symbols are used to move the active cursor. These symbols only act when one or more of the waveforms are highlighted (i.e. selected). The cursor can be moved to coincide with one the edges of the selected signals. The symbols in order from left to right move the active cursor to: nearest edge to the left, nearest edge to the right, nearest falling edge to the left, nearest falling edge to the right.

The units on the time axis in the wave window can be changed by right clicking just below the axis and selecting **Grid and timeline properties** This brings up a window that has a box labeled "time units". Select the units you want and click OK.

Debugging a circuit involves cycling through the processes of modifying the Verilog HDLs, compiling them in Quartus, loading the simulator and then running the simulator. Every time the simulator is loaded (i.e. the start simulation command is executed) the configuration of the wave window is lost. This means the signals of interest must be added to the wave window again and any changes made to the radix must be respecified, etcetera. The wave window can be reconfigured very quickly by saving the configuration of the wave window in a .do file and then running that file right after the "start simulation" command is executed.

Save the configuration of the wave window by first activating the wave window (i.e. click on the wave tab) and then selecting file \rightarrow save format. This will bring up a window that asks for the directory path and name of the file in which you wish to save the configuration information. The default path is the project directory (to be specific the Modelsim-Altera project directory) and the default name is wave.do. Do not change the default settings. Just click OK.

To reload the configuration file after the simulation has been restarted type do wave.do in the transcript window. The transcript window is the window at the bottom with the prompt VSIM 15>.

9 Configuring the DE2 board

Quartus can not generate a configuration file until the signals in the port list have been assigned to pins on the FPGA. Of course the tracking on the DE2 printed circuit board connects the FPGA pins to chips, leds, switches and such that are mounted on the DE2. For purposes assigning pins to the

set_clear_latch project it is only necessary to the FPGA pins connected to two LEDs and two keys (momentary push button switches that are active low). The FPGA on the DE2 board has a different pinout than the FPGA on the DE2-115 board so different pins need to be assigned.

The first step in assigning pins is to create a comma separated file (a text file) by selecting **File** \rightarrow **New** \rightarrow **Other Files** \rightarrow **text file**. Enter one of the following text stings into the file and then save the file in the project directory as **set_clear_latch.csv**. Make sure to check mark the box that asks if the file is to be added to the project. For the Cyclone II FPGA on the DE2 board enter:

```
To, Assignment Name, Value n_set, Location, PIN_G26 n_clear, Location, PIN_N23 Q, Location, PIN_AE22 n_Q, Location, PIN_V18
```

For the Cyclone IV E on the DE2-115 board enter:

```
To, Assignment Name, Value
```

```
n_set, Location, PIN_M23
n_clear, Location, PIN_M21
Q, Location, PIN_E21
n_Q, Location, PIN_E22
```

It is also important to make sure any FPGA pin connected to the output of device on the DE2 or DE2-115 board, is not programmed to be an output pin. There are a large number of FPGA pins that are connected to such drivers. To make sure that none of these FPGA pins are programmed as outputs, all the unused pins, i.e. the pins not assigned in the current project, should be programmed as "". The is done by selecting **Assignments** \rightarrow **Device** to bring up the "Device" window. Make sure the device is FPGA on either the DE2 or DE2-115 board, whichever board is to be used. Click on Device and Pin Options to pop up the "device and pin options" window. Select **Unused Pins** in the category list on the left and then pull down the list associated with the "Reserve all unused ins:" box and select **As input tri-stated with week pull-up**. Then click OK to take down the "device and pin options" window. Click OK again to take down the "Device" window.

The FPGA is programmed by transferring the configuration fileset_clear_latch.sof file to the FPGA. This is done as follows:

- 1. Connect the power to the DE2 or DE2-115 board.
- 2. Connect the USB cable to DE2 or DE2-115 board through the connector closes to the power supply.
- 3. Connect other end of the USB cable to the PC.
- 4. Press the red power on switch. If the board is properly powered lights will start flashing.
- 5. Select **Tools** → **programmer**. This will bring up a window. If the "Start" button is made active the FPGA is programmed by clicking "start". Otherwise Click on the "Hardware Setup" button. This will bring up another window. Pull down the options for the "currently selected hardware" box and select **USB-blaster**. Close the window. The start button in the programmer window should now be activated. Click "Start" to program the FPGA.

10 Exercise on Using Quartus and Modelsim Altera

- 1. Design a transparent latch in Verilog HDL and compile it in Quartus.
- 2. Write a test bench in Verilog HDL for the transparent latch.
- 3. Verify the operation of the transparent latch via simulation with Modelsim-Altera.

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11 D Flip/Flop

11.1 Schematic

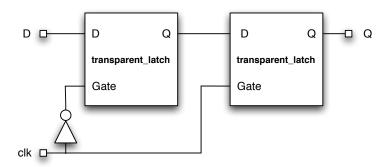


Figure 21: D Flip/Flop

There are many ways to make a D Flip/Flop. This one uses two transparent latches in a master/slave configuration.

11.2 Exercise

Below is a partially complete Verilog HDL of the D flip-flop shown in Figure 21. It is a structural description of a D flip flop. There are other structures that also describe a D flip-flop, but they will not be discussed here.

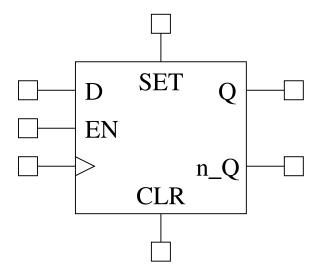
Please complete the Verilog HDL below. The structural description in Figure 21 is not fully annotated. Two wires need to have names assigned for the purposes of completing the Verilog HDL given below.

```
module D_FF ( ...
input ...
output ...
wire ...
not inverter_1 ( ...
transparent_latch latch_1 ( ...
transparent_latch latch_2 ( ...
endmodule
```

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11.3 D Flip-Flop with enable

A D flip-flop can be constructed with an extra input that, when high, enables the clock input. It is referred to as the clock enable or simply the enable. While the clock enable input is high the D flip-flop works as usual. While the clock enable is low, the clock input is ignored and the output remains unchanged.



Converting an ordinary D-flip-flop to one with a clock enable is the subject of a question in assignment 1. For that reason the circuity needed for the conversion is not given in these notes. However, it will be discussed in class after assignment 1 is due.