02 Parameter optimisation

March 29, 2020

1 Parameters optimisation analysis

Computational notebook 02 for Morphological tessellation as a way of partitioning space: Improving consistency in urban morphology at the plot scale.

Fleischmann, M., Feliciotti, A., Romice, O. and Porta, S. (2020) 'Morphological tessellation as a way of partitioning space: Improving consistency in urban morphology at the plot scale', Computers, Environment and Urban Systems, 80, p. 101441. doi: 10.1016/j.compenvurbsys.2019.101441.

Contact: martin@martinfleischmann.net

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Note: notebook has been cleaned and released retroactively. It is likely that different versions of packages were initially used, but we made sure that the results remained unaltered.

Data

The source of the data used within the research is the Amtliche Vermessung dataset accessible from the Zurich municipal GIS open data portal (https://maps.zh.ch). From it can be extracted the cadastral layer (Liegenschaften_Liegenschaft_Area) and the layer of buildings (all features named Gebäude). All data are licensed under CC-BY 4.0.

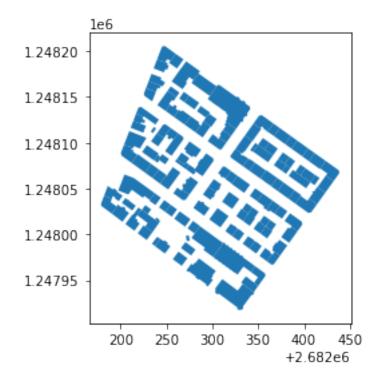
Source data: Vektor-Übersichtsplan des Kantons Zürich, 13.03.2018, Amt für Raumentwicklung Geoinformation / GIS-Produkte, Kanton Zürich, https://opendata.swiss/de/dataset/vektor-ubersichtsplan1

```
[32]: import numpy as np
  import pandas as pd
  import geopandas as gpd
  from tqdm import tqdm
  from osgeo import ogr
  from shapely.wkt import loads
  import scipy as sp
  from scipy.spatial import Voronoi
  from shapely.geometry import *
  from time import time
  import matplotlib.pyplot as plt
  import seaborn as sns
```

```
[33]: np.__version__, pd.__version__, gpd.__version__, sp.__version__
```

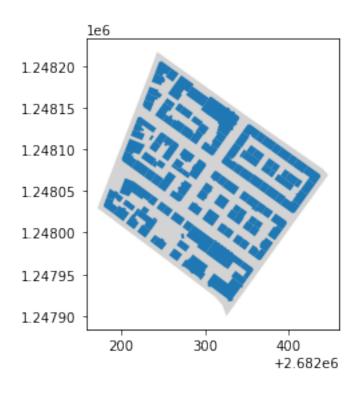
```
[33]: ('1.18.1', '1.0.3', '0.7.0', '1.4.1')
[10]: folder = 'data/'
[4]: buildings = gpd.read_file(folder + 'args_test.gpkg', layer='buildings')
[5]: buildings.plot()
```

[5]: <matplotlib.axes._subplots.AxesSubplot at 0x11dc500d0>



```
[7]: case = gpd.read_file(folder + 'args_test.gpkg', layer='case')
ax = case.plot(color='lightgrey')
buildings.plot(ax=ax)
```

[7]: <matplotlib.axes._subplots.AxesSubplot at 0x123ea8c10>



```
[8]: def _get_centre(gdf):
         bounds = gdf['geometry'].bounds
         centre_x = (bounds['maxx'].max() + bounds['minx'].min()) / 2
         centre_y = (bounds['maxy'].max() + bounds['miny'].min()) / 2
        return centre_x, centre_y
    # densify geometry before Voronoi tesselation
    def _densify(geom, segment):
        poly = geom
        wkt = geom.wkt # shapely Polygon to wkt
        geom = ogr.CreateGeometryFromWkt(wkt) # create ogr geometry
        geom.Segmentize(segment) # densify geometry by 2 metres
        geom.CloseRings() # fix for GDAL 2.4.1 bug
        wkt2 = geom.ExportToWkt() # ogr geometry to wkt
        try:
            new = loads(wkt2) # wkt to shapely Polygon
            return new
        except:
            return poly
    def _point_array(objects, unique_id):
        points = []
```

```
ids = []
    for idx, row in objects.iterrows():
        poly_ext = row['geometry'].boundary
        if poly_ext is not None:
            if poly_ext.type == 'MultiLineString':
                for line in poly_ext:
                    point_coords = line.coords
                    row_array = np.array(point_coords).tolist()
                    for i in range(len(row array)):
                        points.append(row_array[i])
                        ids.append(row[unique_id])
            elif poly_ext.type == 'LineString':
                point_coords = poly_ext.coords
                row_array = np.array(point_coords).tolist()
                for i in range(len(row_array)):
                    points.append(row_array[i])
                    ids.append(row[unique_id])
            else:
                raise Exception('Boundary type is {}'.format(poly_ext.type))
    return points, ids
def _regions(voronoi_diagram, ids, unique_id, crs):
    # generate DataFrame of results
    regions = pd.DataFrame()
    regions[unique id] = ids # add unique id
    regions['region'] = voronoi_diagram.point_region # add region id for each_
\rightarrow point
    # add vertices of each polygon
    vertices = []
    for region in regions.region:
        vertices.append(voronoi_diagram.regions[region])
    regions['vertices'] = vertices
    # convert vertices to Polygons
    polygons = []
    for region in regions.vertices:
        if -1 not in region:
            polygons.append(Polygon(voronoi_diagram.vertices[region]))
        else:
            polygons.append(None)
    # save polygons as geometry column
    regions['geometry'] = polygons
    # generate GeoDataFrame
    regions_gdf = gpd.GeoDataFrame(regions.dropna(), geometry='geometry')
```

```
regions_gdf = regions_gdf.loc[regions_gdf['geometry'].length < 1000000] #__

→ delete errors

regions_gdf = regions_gdf.loc[regions_gdf[unique_id] != -1] # delete__

→ hull-based cells

regions_gdf.crs = crs

return regions_gdf
```

```
[]: def tess_test(gdf, unique_id, inset, segment, case):
        objects = gdf.copy()
        centre = _get_centre(objects)
        objects['geometry'] = objects['geometry'].translate(xoff=-centre[0],__
     →yoff=-centre[1])
        objects['geometry'] = objects.geometry.apply(lambda g: g.buffer(-inset,_
     objects = objects.explode()
        objects.reset_index(inplace=True, drop=True)
        objects['geometry'] = objects['geometry'].apply(_densify, segment=segment)
        points, ids = _point_array(objects, unique_id)
        case = case.copy()
        case['geometry'] = case['geometry'].translate(xoff=-centre[0],__
      →yoff=-centre[1])
        infinity_fix = case.iloc[0].geometry.buffer(50)
        array = np.array(_densify(infinity_fix, segment).boundary.coords).tolist()
        for i in range(len(array)):
            points.append(array[i])
            ids.append(-1)
        voronoi_diagram = Voronoi(np.array(points))
        regions_gdf = _regions(voronoi_diagram, ids, unique_id, crs=gdf.crs)
        morphological_tessellation = regions_gdf[[unique_id, 'geometry']].

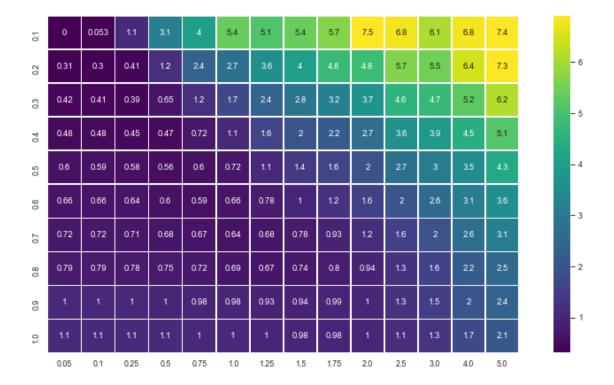
→dissolve(by=unique_id, as_index=False)
         clipped = gpd.overlay(morphological_tessellation, case, how='intersection')
        clipped['geometry'] = clipped['geometry'].translate(xoff=centre[0],__
     →yoff=centre[1])
        return clipped, len(points)
```

```
[]: s = time()
ideal, ideal_pts = tess_test(buildings, 'uID', 0.1, 0.05, case)
ideal_time = time() - s
```

```
ideal_areas = ideal.geometry.area
     ideal_perimeter = ideal.geometry.length
 []: insets = [0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1]
     segs = [0.05, 0.1, 0.25, 0.5, 0.75, 1, 1.25, 1.5, 1.75, 2, 2.5, 3, 4, 5]
     times = pd.DataFrame(index=insets, columns=segs)
     points_count = pd.DataFrame(index=insets, columns=segs)
     areas = pd.DataFrame(index=insets, columns=segs)
     peris = pd.DataFrame(index=insets, columns=segs)
 []: for inset in insets:
         for seg in segs:
             print('inset: ' + inset, 'segment:' + seg)
             s = time()
             test, pts = tess_test(buildings, 'uID', inset, seg, case)
              end = time() - s
             times.loc[inset, seg] = end
             points_count.loc[inset, seg] = pts
             ars = test.geometry.area
             diff = abs(ideal_areas - ars) / (ideal_areas)
             areas.loc[inset, seg] = diff
             lens = test.geometry.length
             diff = abs(ideal_perimeter - lens) / (ideal_perimeter)
             peris.loc[inset, seg] = diff
             test.to_file(folder + 'args_test.gpkg', layer='{in}_{s}'.

→format(in=inset, s=seg), driver='GPKG')
 []: times.to_csv(folder + 'times.csv')
     points_count.to_csv(folder + 'points.csv')
     areas.to_csv(folder + 'areas.csv')
     peris.to_csv(folder + 'perimeters.csv')
[20]: times = pd.read_csv(folder + 'times.csv', index_col=0)
     points = pd.read_csv(folder + 'points.csv', index_col=0)
     areas = pd.read_csv(folder + 'areas.csv', index_col=0)
     peris = pd.read_csv(folder + 'perimeters.csv', index_col=0)
[12]: sns.set_style('ticks', {'xtick.bottom': False, 'ytick.left': False})
     sns.set_context(context='paper', font_scale=1, rc=None)
[13]: f, ax = plt.subplots(figsize=(14, 7))
      sns.heatmap(peris * 100, annot=True, linewidths=.5, ax=ax, robust=True,
```

[13]: <matplotlib.axes. subplots.AxesSubplot at 0x1243b3a30>



```
[14]: from matplotlib import colors
    class MidpointNormalize(colors.Normalize):
        def __init__(self, vmin=None, vmax=None, midpoint=None, clip=False):
            self.midpoint = midpoint
            colors.Normalize.__init__(self, vmin, vmax, clip)

        def __call__(self, value, clip=None):
            # I'm ignoring masked values and all kinds of edge cases to make a
            # simple example...
            x, y = [self.vmin, self.midpoint, self.vmax], [0, 0.5, 1]
            return np.ma.masked_array(np.interp(value, x, y))
```

[17]: [Text(196.9320000000013, 0.5, 'Inward offset distance'), Text(0.5, 41.7, 'Discretization interval')]



```
[18]: norm2 = MidpointNormalize(midpoint=np.median(areas.values))

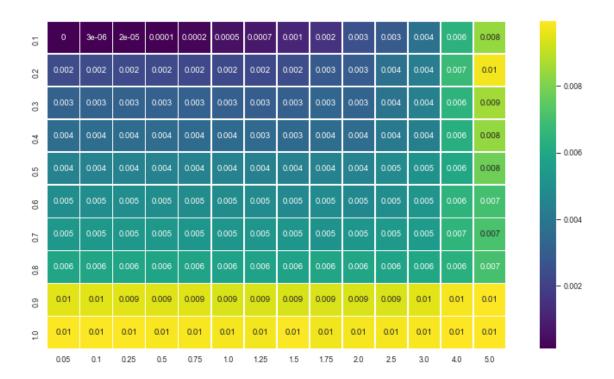
f, ax = plt.subplots(figsize=(14, 7))

sns.heatmap(areas, annot=True, linewidths=.5, ax=ax, robust=True,

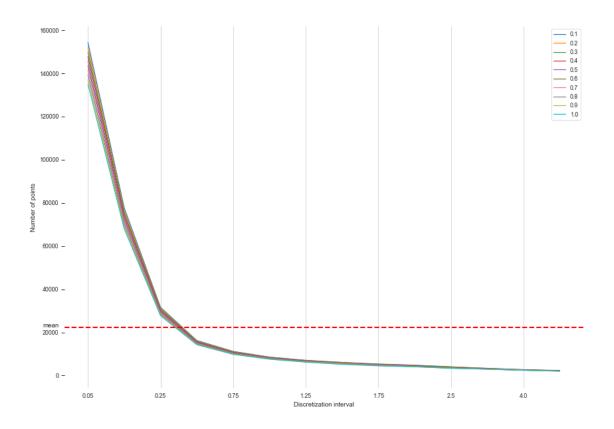
cmap='viridis', square=True, norm=norm2, fmt='.1g')

#plt.savefig('areas_heatmap.svg')
```

[18]: <matplotlib.axes._subplots.AxesSubplot at 0x124b99370>

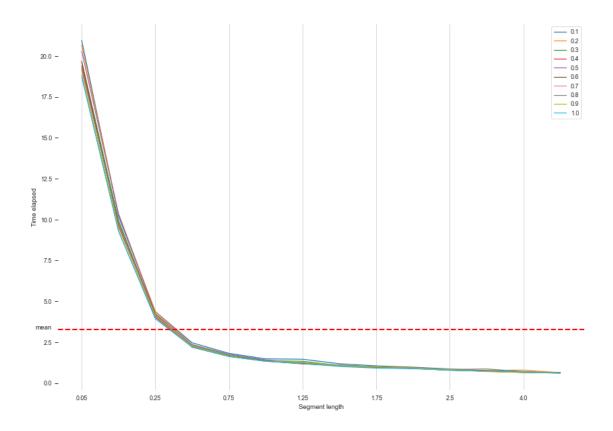


[26]: Text(-1.25, 22425.54285714286, 'mean')

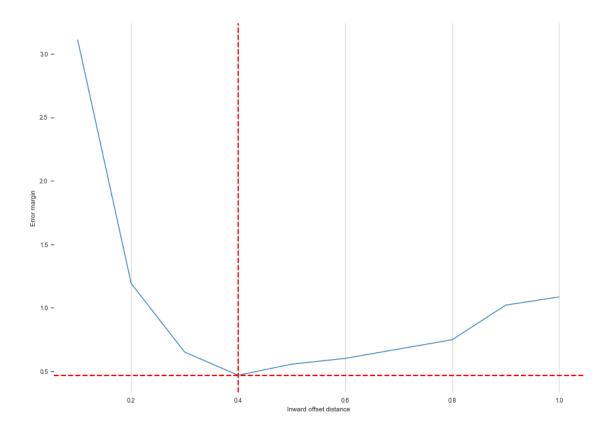


```
f, ax = plt.subplots(figsize=(14, 10))
times.T.plot(ax=ax)
ax.set(xlabel="Segment length", ylabel="Time elapsed")
ax.axhline(y=times.mean().mean(), xmin=0, xmax=1, color='r', linestyle='--', \( \to \) \( \to \)
```

[27]: Text(-1.25, 3.291670674937112, 'mean')



```
[28]: f, ax = plt.subplots(figsize=(14, 10))
    perc.T.loc['0.5'].plot(ax=ax)
    ax.set(xlabel="Inward offset distance", ylabel="Error margin")
    ax.axhline(y=perc.T.loc['0.5'].min(), color='r', linestyle='--', lw=2)
    ax.axvline(x=0.4, color='r', linestyle='--', lw=2)
    plt.grid(True, which='major', axis='x')
    sns.despine(offset=10, trim=False, left=True, bottom=True)
    #plt.savefig('05_segment.svg')
```



[29]: 0.46896443802393606

The best combination of inset distance and maximum segment length in discretisation, regarding effectivity of computation and minimisation of error margin is 0.4 meters inset and 0.5 meters maximum segment length.