

8.11) $t < 0$:

$$V_0 = 100 \text{ V}$$

$$I_0 = 5 \text{ A}$$

$t > 0$:

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \cdot 50 \cdot (2 \pi \times 10^{-3})} = 400 \text{ rad/s}$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{(160 \times 10^{-3}) \cdot (2 \pi \times 10^{-6})}} = 500$$

$$\omega_d = \sqrt{\omega_0^2 - \alpha^2} = \sqrt{500^2 - 400^2} = 300 \text{ rad/s}$$

$$V_0 = B_1 e^{-400t} \cos 300t + B_2 e^{-400t} \sin 300t$$

$$V_0(0) = B_1 = 100$$

$$\frac{dV_0}{dt} = -\alpha B_1 + \omega_d B_2 = \frac{1}{C} \left(-I_0 - \frac{V_0}{R} \right)$$

$$= -(400) \cdot (100) + 300 B_2 = \frac{1}{2 \pi \times 10^{-6}} \cdot \left(-5 - \frac{100}{50} \right)$$

$$= B_2 = -800$$

$$V_0 = 100 e^{-400t} \cos 300t - 800 e^{-400t} \sin 300t \quad t > 0.$$

8.27) $\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{(2 \pi \times 10^{-3}) \cdot (62.5 \times 10^{-6})}} = 800 \text{ rad/s}$

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \cdot (12.5) \cdot (62.5 \times 10^{-6})} = 640 \text{ rad/s}$$

$$\omega_d = \sqrt{\omega_0^2 - \alpha^2} = 480 \text{ rad/s}$$

$$I_f = 2 \text{ A}$$

$$I_L = 2 + B_1' e^{-640t} \cos 480t + B_2' e^{-640t} \sin 480t$$

$$I_L(0) = 2 + B_1' = 1$$

N
(-1)

①

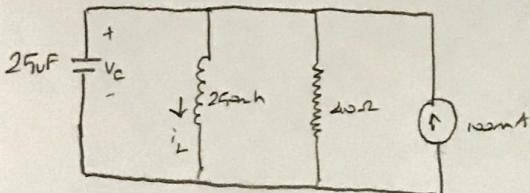
$$\frac{di_L}{dt}(0) = -\alpha B_1' + \omega_d \cdot B_2' = \frac{V_0}{L}$$

$$B_2' = 2.83$$

$$-640(-1) + 480B_2' = \frac{50}{25 \times 10^{-3}}$$

$$i_L(t) = 2 - e^{-640t} \cos 480t + 2.83 e^{-640t} \sin 480t \quad t > 0$$

8.35) $t > 0$



$$\alpha = \frac{1}{2RC} = \frac{1}{2 \cdot 40 \cdot (25 \times 10^{-3})} = 500 \text{ rad/s}$$

$$\alpha^2 > \omega_0^2$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{(250 \times 10^{-3}) \cdot (25 \times 10^{-3})}} = 400$$

overdamped

$$\tilde{\omega}_1, \tilde{\omega}_2 = -500 \pm \sqrt{500^2 - 400^2} = -200, -800$$

$$a) i_L = 1f + A_1 e^{-200t} + A_2 e^{-800t}$$

$$If = 100 \text{ mA}$$

$$i_L(0) = 0.1 + \underbrace{A_1 + A_2}_{0} = 0.1$$

$$\frac{di_L}{dt}(0) = -200A_1 - 800A_2 = \frac{V_0}{L}$$

$$\frac{75}{0.25} = \frac{V_0}{L} \leq 300$$

$$A_1 = 0.1 \quad A_2 = -0.1$$

$$b) V_C(t) = V_L(t)$$

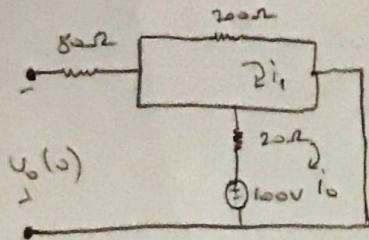
$$i_L(t) = 0.1 + 0.1e^{-200t} - 0.1e^{-800t} \text{ A}$$

$$L \cdot \frac{di_L}{dt} = 0.25 \cdot (-100e^{-200t} + 400e^{-800t})$$

$$= -25e^{-200t} + 100e^{-800t} \quad \checkmark$$

$\times 70$

847) L < 0

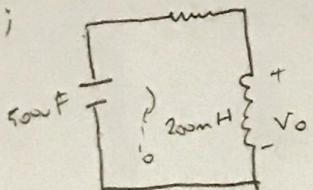


$$\begin{aligned} 100i_1 + 100i_0 &= 0 \\ -100i_1 + 120i_0 &= 100 \\ i_1 &= 0.2\text{A} \\ i_0 &= 1\text{A} \end{aligned}$$

$$V_o = -100 + 20i_0 + 100i_1 = -60\text{V}$$

$$\frac{20}{20} \quad 20$$

L > 0 ;



$$\alpha = \frac{R}{2L} = \frac{200}{2 \cdot (0.2)} = 500$$

$$\alpha^2 > \omega_0^2$$

$$\omega_0 = \sqrt{\frac{1}{LC}} = \sqrt{\frac{1}{(0.2)(36.25 \times 10^{-6})}} = 400 \quad \text{over damped}$$

$$S_{1,2} = -100 \pm \sqrt{500^2 - 400^2} = -200, -800 \text{ rad/s}$$

$$i_0 = A_1 e^{-200t} + A_2 e^{-800t}$$

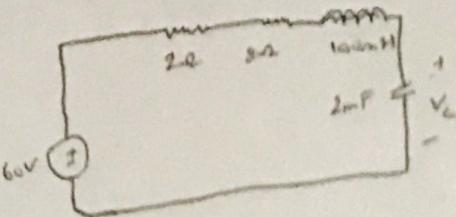
$$i_0(0) = A_1 + A_2 = 1$$

$$\frac{di_0}{dt}(0) = -100A_1 - 800A_2 = \frac{1}{2}(-V_o - RI_o) = -700$$

$$A_1 = 166.67 \text{ mA}$$

$$A_2 = 833.33 \text{ mA}$$

8.54) L < 0 :



$$\omega = \frac{R}{2L} = \frac{10}{2(0.1 \cdot 10^{-3})} = 50 \text{ rad/s}$$

$$\omega_0^2 > \omega^2$$

underdamped

$$\omega_0^2 = \frac{1}{LC} = \frac{1}{(0.1)(2 \times 10^{-3})} = 5000$$

$$\sigma_{1,2} = -\omega \pm \sqrt{\omega^2 - \omega_0^2} = -50 \pm \sqrt{50^2 - 5000} = -50 \pm j50$$

$$V_C = 60 + B_1 e^{-50t} \cos 50t + B_2 e^{-50t} \sin 50t = -90$$

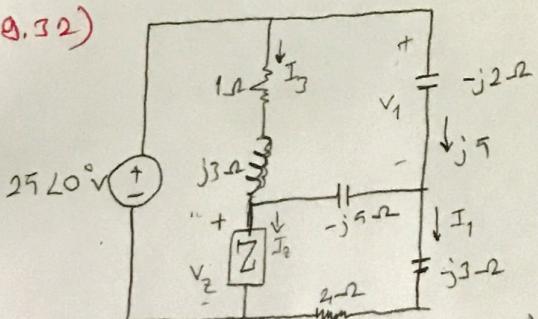
$$B_1' = -150$$

$$C: \frac{dV_C}{dt} (0) = -5; \quad \frac{dV_C}{dt} (0) = \frac{-5}{2 \times 10^{-3}} = -2500$$

$$\frac{dV_C}{dt} (0) = -50 B_1' + 50 B_2 = -2500 \quad B_2' = -200$$

$$V_C = 60 - 150 e^{-50t} \cos 50t - 200 e^{-50t} \sin 50t \text{ V}, \quad L > 0$$

Q.32)



$$V_1 = j5(-j2) = 10V$$

$$-25 + 10 + (4-j3)I_1 = 0$$

$$I_1 = \frac{15}{4-j3} = 2.4 + j1.8A$$

$$I_b = I_1 - j5 = (2.4 + j1.8) - j5 = 2.4 - j3.2A$$

$$V_2 = j5I_2 + (4-j3)I_1 = j5(2.4 - j3.2) + (4-j3)(2.4 + j1.8) = -1-j12V$$

$$I_3 = 6.2 - j6.6A \quad - 23 + (1+j3)I_3 + (-1-j12) = 0$$

$$I_2 = I_3 - I_1 = 3.8 - j3.4A$$

$$Z = \frac{V_2}{I_2} = 1.42 - j1.88\Omega$$

②

$$9.45) \text{ First step: } (0.12 \angle 0^\circ)(2 \angle 90^\circ) = 30 \angle 10^\circ$$

$$\text{Second step: } 2 \angle 90^\circ - j400 + j150 = 2 \angle 90^\circ - j250 \angle 2$$

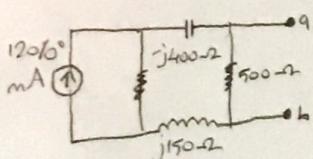
$$\frac{30 \angle 10^\circ}{2 \angle 90^\circ - j250} = 60 - j60 \text{ mA}$$

Third Step: $\xrightarrow{\text{to short}}$

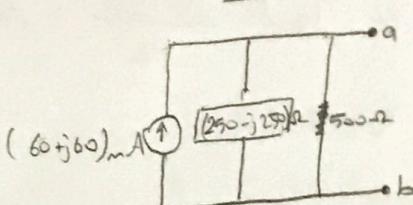
$$(2 \angle 90^\circ - j250) \parallel 500 = 200 - j100 \angle 2$$

$$(200 - j100) \cdot (0.06 - j0.06) = 18 - j6 \text{ V}$$

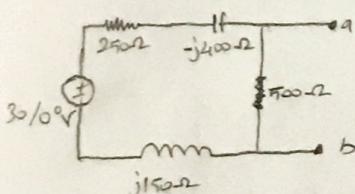
Step 1



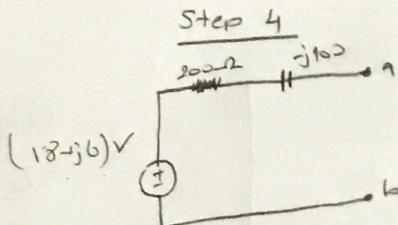
Step 3



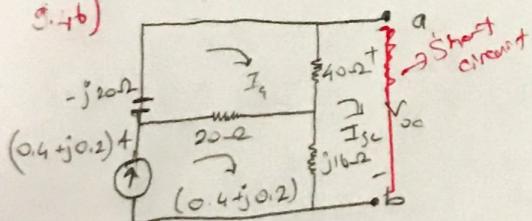
Step 2



Step 4



9.46)



$$-j20I_q + 40I_q + 20(I_q - 0.4 - j0.2) = 0$$

$$I_q = \frac{20 \cdot (0.4 + j0.2)}{60 - j20} = 0.1 + j0.1 \text{ A}$$

Open Circuit

$$V_{oc} = 40I_q + j16(I_q - 0.4 - j0.2) = 0.8 + j10.4 \text{ V}$$

Short Circuit:

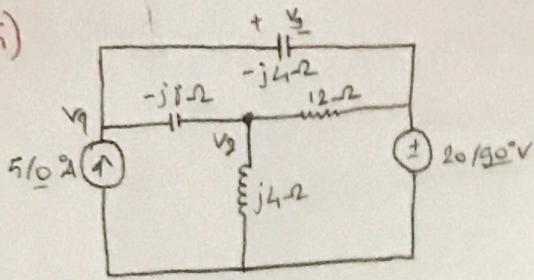
$$-j20I_q + 40(I_q - I_{sc}) + 20(I_q - 0.4 - j0.2) = 0$$

$$40(I_{sc} - I_q) + j16(I_{sc} - 0.4 - j0.2) = 0$$

$$I_{sc} = 0.3 + j0.5 \text{ A} \quad , \quad Z_{Th} = \frac{V_{Th}}{I_{sc}} = \frac{0.8 + j10.4}{0.3 + j0.5} = 16 + j8 \angle 2$$

⑦

3.55)



$$V_1 = -5\angle 0^\circ + \frac{V_1 - V_2}{-j8} + \frac{V_2 - 20\angle 90^\circ}{-j4} = 0, \quad V_2 = \frac{V_2 - V_1}{-j8} + \frac{V_2}{j4} + \frac{V_2 - 20\angle 90^\circ}{12} = 0$$

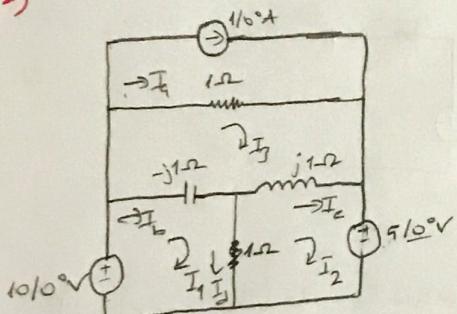
$$V_1 \left(\frac{1}{-j8} + \frac{1}{j4} \right) + V_2 \left(-\frac{1}{-j8} \right) = 5\angle 0^\circ + \frac{20\angle 90^\circ}{-j4}$$

$$V_1 \left(-\frac{1}{j8} \right) + V_2 \left(\frac{1}{-j8} + \frac{1}{j4} + \frac{1}{12} \right) = \frac{20\angle 90^\circ}{12}$$

$$V_1 = -\frac{8}{3} + j\frac{4}{3}, \quad V_2 = -8 - j4$$

$$V_g = V_1 - 20\angle 90^\circ = -\frac{8}{3} - j\frac{56}{3} V$$

3.62)



$$10\angle 0^\circ = (1-j1)I_1 - I_2 + j1I_3$$

$$-5\angle 0^\circ = -I_1 - ((1+j1)I_2 - j1I_3)$$

$$j1I_1 - j1I_2 + I_3 = 1$$

$$I_1 = 11 + j10 A$$

$$I_g = I_3 - I_2 = 5 A$$

$$I_2 = 11 + j5 A$$

$$I_b = I_1 - I_3 = 5 + j10 A$$

$$I_3 = 6 A$$

$$I_c = I_2 - I_3 = 5 + j5 A$$

$$I_d = I_1 - I_2 - j5 A$$

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