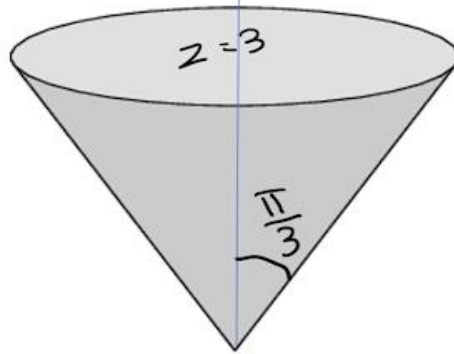


- 1 Determine the flux of  $\vec{F} = \rho^2 \cos^2 \phi \hat{e}_\rho + z \sin \phi \hat{e}_\phi$  over the closed cylinder  $0 \leq z \leq 1, \rho=4$ . Show that  $\iiint_V \nabla \cdot \vec{F} dV = \iint_S \vec{F} \cdot d\vec{S}$ . All relevant steps carry marks

4 marks

- 2 Find the volume of a cone whose angle is  $\frac{\pi}{3}$  and below the plane  $z = 3$  using the **spherical polar coordinate system**.



4 marks

- 3 Express the below mentioned integral into cylindrical polar co-ordinate system. Note: No need to work out the integral, but simply express the integral.

$$\int_{y=-1}^{y=1} \int_{x=0}^{x=\sqrt{1-y^2}} \int_{z=x^2+y^2}^{z=\sqrt{x^2+y^2}} xyz dz dx dy$$

The range of limits are

$$-1 \leq y \leq 1$$

$$0 \leq x \leq \sqrt{1-y^2}$$

$$x^2 + y^2 \leq z \leq \sqrt{x^2 + y^2}$$

4 marks

- 4 A force is described by

$$\vec{F} = -\hat{e}_x \frac{y}{x^2+y^2} + \hat{e}_y \frac{x}{x^2+y^2}$$

- (a) Express  $\vec{F}$  in cylindrical polar co-ordinates  
(b) Calculate curl of  $\vec{F}$  in cylindrical polar co-ordinates

3 marks

Cylindrical Coordinates

$$q_1 = \rho, \quad q_2 = \phi, \quad q_3 = z; \quad h_1 = h_\rho = 1, \quad h_2 = h_\phi = \rho, \quad h_3 = h_z = 1,$$

Spherical Polar Coordinates

$$q_1 = r, \quad q_2 = \theta, \quad q_3 = \phi; \quad h_1 = h_r = 1, \quad h_2 = h_\theta = r, \quad h_3 = h_\phi = r \sin \theta,$$

$$\begin{aligned} \nabla \cdot \vec{F} &= \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial q_1} (F_1 h_2 h_3) + \frac{\partial}{\partial q_2} (F_2 h_3 h_1) + \frac{\partial}{\partial q_3} (F_3 h_1 h_2) \right] \\ \nabla^2 V &= \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial q_1} \left( \frac{h_2 h_3}{h_1} \frac{\partial V}{\partial q_1} \right) + \frac{\partial}{\partial q_2} \left( \frac{h_3 h_1}{h_2} \frac{\partial V}{\partial q_2} \right) + \frac{\partial}{\partial q_3} \left( \frac{h_1 h_2}{h_3} \frac{\partial V}{\partial q_3} \right) \right] \\ \nabla \times \vec{F} &= \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \hat{q}_1 & h_2 \hat{q}_2 & h_3 \hat{q}_3 \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial q_3} \\ h_1 F_1 & h_2 F_2 & h_3 F_3 \end{vmatrix} \end{aligned}$$