

# TP 1 - Apprentissage Statistique Appliqué

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## 1 Part 1

### 1.1 Cross-Validation with GridSearchCV

**Question:** Explain in your report what happens when we run `clf.fit(X_train, Y_train)`. What is the complexity for each of the three following cases?

The line `clf.fit(X_train, Y_train)` here uses the fit method on the object `clf` and taking the train sample. We give the features `X` and the outputs `Y`. The object `clf` is from the class `GridSearchCV` which allows us to find the best hyperparameters among a list we chose. It is taking as parameter an object named `knn` of the class `KNeighborsClassifier()`, a dictionary named `parameters` containing the number of neighbors to be tested in the knn algorithm (1 to 5 here) and the `cv` parameter referring to the number of folds to be used in the cross-validation. Basically it will perform a 3-folds cross-validation on a kNN model with 1 to 5 neighbors on the train sample and it will allow us to keep the best model. The kNN algorithm is parametered with the default metric which is the Euclidean distance :  $\sqrt{\sum_{i=1}^n (x_i - y_i)^2}$ . The functions are all part of the sklearn package.

Complexity can be divided into two kinds of complexity i.e: 1) time complexity, deal with how long the algorithm is executed, and 2) space complexity, deal with how much memory is used by it's algorithm.

Table 1: Complexity

	kNN	Linear SVC	Log Reg
Time Training	$O(n*k*d)$	$O(m*n)$	$O(n*d)$
Space	$O(n*d)$	$O(l)$	$O(d)$

With `n` : size of the training sample, `d` : dimension of the data, `k` : number of neighbors, `m` : number of features, `l` : support vectors.

**Question:**What is the test accuracy? What would be the accuracy of random guess?

The test accuracy is the measure of how often the points are correctly classified. In our case the accuracy is 0.875. It means that 87.5% of the time, the points are correctly classified on the test sample. It is computed as the number of well classified individuals over the sample size. If we did a random guess we would randomly choose an output in the range 0 to 9 so the accuracy would converge towards  $\frac{1}{10}$  according to the LLN.

**Question:** What is `LinearSVC()` classifier? Which kernel are we using? What is `C`? (this is a tricky question, try to find the answer online )

`LinearSVC` means Linear Support Vector Classification, which is supervised learning methods used for classification. `LinearSVC` are classes capable of performing binary and multi-class classification on a dataset. This classifier tries to find a line that separates the True labels from the False labels<sup>1</sup>. We are using a linear kernel. The parameter `C` represents the regularisation weights, ie the penalty applied on the loss function. The loss function used here is the Squared Hinge Loss :  $L(y, \hat{y}) = \sum_{i=0}^N (\max(0, 1 - y_i \cdot \hat{y}_i))^2$

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<sup>1</sup>Appendix 3.1.1, figure 1

**Question : What is the outcome of `np.logspace(-8, 8, 17, base=2)`? More generally, what is the outcome of `np.logspace(-a, b, k, base=m)`?**

The outcome of `np.logspace(-8, 8, 17, base=2)` is a logarithmic space going from  $2^{-8}$  to  $2^8$  with 17 numbers equally spaced on log scale. The `logspace` function from the numpy package will return k numbers going from  $m^{-a}$  to  $m^b$  spaced on a log scale with a log base m.

**Question : What is the meaning of the warnings? What is the parameter responsible for its appearance?**

The warning tells us that the algorithm did not converge, it did not reach the stop criterion. The parameter responsible for its appearance is the `max_iter` parameter. Its value is not sufficient for the algorithm to converge. The data variance is maybe too large for the algorithm to efficiently perform the SVM.

**Question : What did we change with respect to the previous run of `LinearSVC()`?**

We are running the `svc` function which is by default a RBF SVC and not a linear SVC. RBF means radial basis function. We added a parameter `MaxAbsScaler()` to scale the absolute data between 0 and 1 and thus reduce the variance of the data<sup>2</sup>.

**Question : Explain what happens if we execute**

```
pipe.fit(X_train, y_train)
pipe.predict(X_test, y_test)
```

Those lines will execute the pipeline defined with a `MaxAbsScaler` preprocessing on the features and fit a SVM but with no C parameter defined which will be 1.0 by default.

**Question : what is the difference between `StandardScaler()` and `MaxAbsScaler()`? What are other scaling options available in sklearn?**

`StandardScaler` will standardize the data :  $\frac{x-m}{\sigma}$  with m the mean and  $\sigma$  the standard deviation of data. It differs from `MaxAbsScaler` because in this case we map the absolute value of data in a [0,1] range.

The other scaling option available in sklearn are :

- `MinMaxScaler` which transform features by scaling each feature to a given range [min, max].
- `RobustScaler`, this scale is used if your data contains many outliers.

**Question : Using the previous code as an example achieve test accuracy  $\geq 0.9$  . You can use any method from sklearn package. Give a mathematical description of the selected method. Explain the range of considered hyper-parameters.**

We tried the Random Forest algorithm which is a method creating a fixed number of random trees (CART algorithm). The randomness in this algorithm comes with the selection of features used to create the trees. Each tree is created with a fixed number of features but these features are randomly drawn from the whole range of available

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<sup>2</sup>See Part 2. detailed explanation of SVC.

features. In our case, the dataset has 784 features and the algorithm choses  $\sqrt{784} = 28$  features for each tree. This function also uses the bagging method for the elements of the sample. It means that for each tree it takes a random sample of the same size as the initial sample. In this case we fit a train sample of size 2000 so the bootstrap bags will have 2000 random elements (they can appear multiple times). In each tree the method is to successively split the features into 2 groups. The choice of the feature and threshold for the split is made by minimising a criterion : the gini coefficient or the entropy. In our case we put both hyper-parameters for the Grid Search to find the best one. We used the method `RandomForestClassifier()` from the `skLearn` package in the pipeline along with a `StandardScaler` preprocessing on features to normalise the data and reduce the variance so we avoid divergence of the algorithm. The number of trees to generate and the split quality criterion are the two hyper-parameters we chose to exploit. The default number of trees is 100 so we tried with 50 and 150. We used the accuracy scoring for the grid search and cross-validation. This configuration resulted in accuracy  $> 0.9$ .

## 1.2 Visualising errors

The error in the chunk of code was because the `predict_proba` method returns an array of probabilities within an array. We must then pick the first element of the array (index 0) to retrieve the probabilities array<sup>3</sup>.

## 1.3 Changing the loss function

**Question: What is balanced \_accuracy \_score? Write its mathematical mathematical description.**

The balanced accuracy in binary and multi-class classification problems is used to deal with imbalanced datasets. It is defined as the arithmetic mean of the sensitivity (also called recall or true positive rate) and the specificity (also called true negative rate). As a consequence, it represents the average accuracy per class.

$$recall = \frac{tp}{tp + fp}$$

with tp: true positive and fn: false negative

$$specificity = \frac{tn}{tn + fn}$$

Instead of calculating the regular score which is  $\frac{tp+tn}{sampleSize}$ , the balanced score is

$$\frac{recall + specificity}{2}$$

If the number in each category of prediction is the same, regular score = balanced score. Otherwise, the good predictions of an over represented class will not inflate the balanced score unlike the regular one.

**Question: What is the confusion matrix? What are the conclusions that we can draw from the confusion\_matrix(y\_test, clf4.predict(X\_test))?**

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<sup>3</sup>See Jupyter Notebook File

The general idea is to count the number of times instances of class A are classified as class B. For example, to know the number of times the classifier confused images of 5s with 2s, you would look in the 5th row and 2nd column of the confusion matrix. In row the actual class and in columns the predicted class given by algorithm.

As we can see in our case<sup>4</sup>, 8s are often confused with 5s (3/17=18% of the time when the actual class is 8) and 3s are also confused with 5s 13% of the time (3/23). Also, 5s are detected only 57% (8/14) of the time. 0s and 9s seem well detected with respectively 100% (22/22) and 92% (24/26) recall/true positive rate.

Regarding the scores, the balanced is slightly inferior to the regular one (83% vs 84%) due to the underrepresentation of the worst predicted class (ie 5s). Because there are several classes, it could be interesting to transform the confusion matrix into a heat map.

On the heat map we can check that the algorithm is good at predicting classes since the brighter cells are on the main diagonal. Even though, 5s are darker than other classes explained by the under-representation of the class and a few errors. 1s are well predicted given its bright square on the main diagonal but it can be partly explained by the over-representation of 1s in the dataset.

## 2 Part 2

### 2.1 Loss Function

Our custom loss function is an accuracy score with a penalty on inter-class errors. If the predicted value is different than the true value then the error count will increase +1. We decided to separate the data into two classes :

Label	0	1	2	3	4	5	6	7	8	9
Class	0	0	0	0	0	1	1	1	1	1

The counts for each class or label i are as follows :

		Predicted	
		True	False
Actual	True	$tp_i$	$fn_i$
	False	$fp_i$	$tn_i$

We define the Recall score for one class or label i as :

$$Recall_i = \frac{tp_i}{tp_i + fn_i}$$

which is the well classified individuals on the number of individuals actually in this class. We compute a weighted accuracy on the labels (0:9) and one on the classes (0-1). The formula we use is :

$$Weighted\_Accuracy = \frac{\sum_{i=1}^K Recall_i}{K}$$

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<sup>4</sup>Appendix 3.1.2, figure 4

We join both metrics by multiplying them to have a penalised weighted accuracy of the labels :

$$Score = Weighted\_Accuracy_{Label} * Weighted\_Accuracy_{Class}$$

By this mean, our score will decrease when errors are made between two classes. For example if two algorithms show the same number of misclassified labels, it will allow to figure out which one had the most class errors and then choose the other one.

## 2.2 Pipeline

To scales the features, we chose to use a MaxAbsScaler on the data because we want to minimize their variance knowing by constraining them to be between 0 and 1. In fact, we have 784 features which represent a color code that goes from 0 to 255 which can be easily scaled to a [0,1] interval without any loss of information. We train a random forest and a linear SVM model (using the SVC function). It resulted in a better score for the SVM model which is the one we are detailing next. The Jupyter Notebook file contains the entire code with ou trials.

## 2.3 Algorithm

The Gaussian Radial Basis Function, or Gaussian RBF uses a similarity function that measures how much each instance resembles a particular landmark. It will create a landmark at each instance of the dataset and calculate the similarity function :

$$\varphi_{\gamma}(x, l) = \exp(-\gamma ||x - l||^2) \quad (1)$$

It is a bell-shaped function varying from 0 (very far away from the landmark) to 1 (at the landmark). The idea is to transform the dataset and by doing so, make it linearly separable through non-linear methods<sup>5</sup> . The metrics of the distance is usually the euclidean.

However, using the Gaussian RBF can be computationally expensive especially for large datasets given it transforms the training dataset with m instances and n features into a m instances and m features dataset.  $\gamma$  and C both play the role of regularisation hyperparameter. Increasing  $\gamma$  makes the bell-shape narrower so it reduces the instance's range of influence which makes the decision boundary more irregular, going back and forth around individual instances. If the model is overfitting, trying to diminish the value of  $\gamma$  could solve the problem.

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<sup>5</sup>Appendix 3.2.1, figure 3

## 3 Appendix

### 3.1 Part 1

#### 3.1.1 SVM illustration

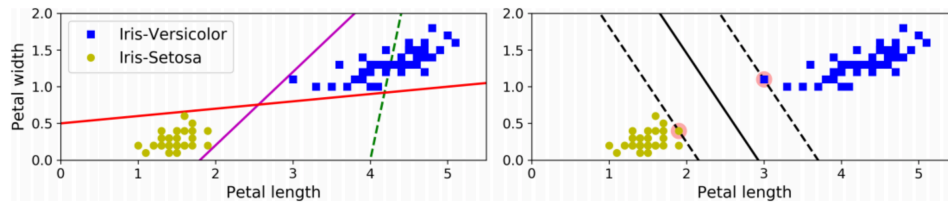


Figure 1: SVM illustration

#### 3.1.2 Changing the loss function : confusion matrix / heatmap

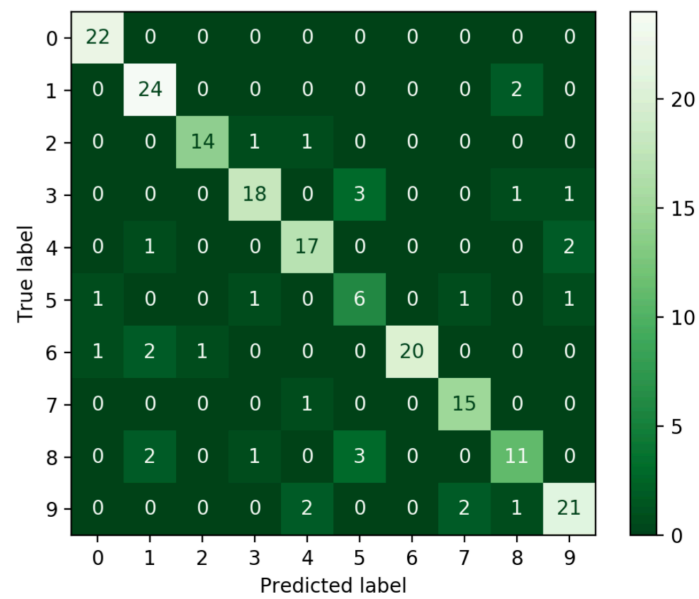


Figure 2: Confusion matrix for the SVM classifier



## 3.2 Part 2

### 3.2.1 Algorithm

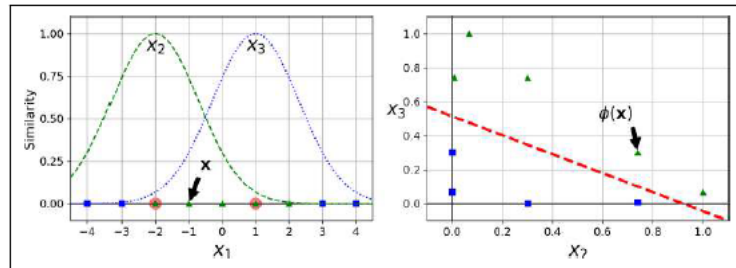


Figure 3: Similarity features using the Gaussian RBF

### 3.2.2 Final confusion matrix

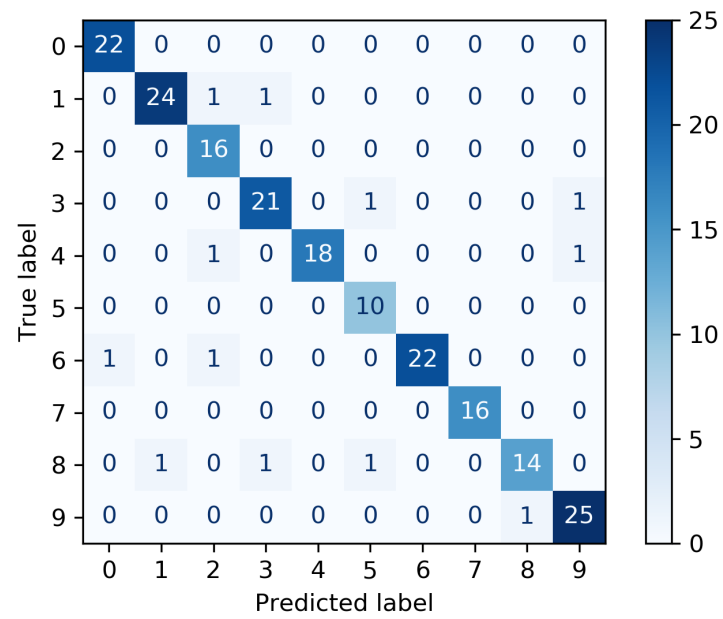


Figure 4: Confusion matrix part 2

## References

- [1] scikit-learn: machine learning in Python — scikit-learn 0.23.2 documentation.
- [2] Aurélien Géron. *Hands-on machine learning with Scikit-Learn, Keras, and Tensor-Flow: concepts, tools, and techniques to build intelligent systems*. O'Reilly Media, Inc., Sebastopol, CA, 2019. OCLC: 1135343456.
- [3] The Kernel Trip. Computational complexity of machine learning algorithms, 2018.