

The Laplace Transform

$$F(s) = \mathcal{L}[f(t)] = \int_{0^-}^{\infty} f(t)e^{-st} dt$$

$$f(t) = \mathcal{L}^{-1}[F(s)] = \frac{1}{j2\pi} \int_{\sigma_1 - j\infty}^{\sigma_1 + j\infty} F(s)e^{st} ds$$

Properties of the Laplace Transform (one sided)

Linearity: $\mathcal{L}[af_1(t) + bf_2(t)] = a\mathcal{L}[f_1(t)] + b\mathcal{L}[f_2(t)]$

Time Differentiation:

$$\mathcal{L}\left[\frac{df}{dt}\right] = sF(s) - f(0)$$

$$\mathcal{L}\left[\frac{d^n f}{dt^n}\right] = s^n F(s) - s^{n-1}f(0) - s^{n-2}\left.\frac{df}{dt}\right|_{t=0} - \dots - \left.\frac{d^{n-1}f}{dt^{n-1}}\right|_{t=0}$$

Time Integration: $\mathcal{L}\left[\int_{0^-}^t f(t')dt'\right] = F(s)/s$

Scaling: $\mathcal{L}[f(at)] = \frac{1}{|a|}F\left(\frac{s}{a}\right)$

Time Shift: $\mathcal{L}[f(t-\tau)] = F(s)e^{-\tau s}$

Frequency Shift: $\mathcal{L}[e^{-at}f(t)] = F(s+a)$

Initial Value: $\lim_{s \rightarrow \infty} sF(s) = f(0)$

Final Value: $\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s)$

R L C V-I Relations in the Laplace domain

$$i = C \frac{dv}{dt} \quad v = L \frac{di}{dt} \quad v = iR$$

$$V(s) = \left(\frac{1}{Cs}\right)I(s) + \frac{v(0^-)}{s} \quad V(s) = LsI(s) - Li(0^-) \quad V(s) = RI(s)$$

Solution to first order Differential Equation

$$\tau \frac{dx}{dt} + x(t) = B \quad x(t) = Ae^{\left(-\frac{t}{\tau}\right)} + B$$

$$\tau = RC \text{ or } L/R$$

$$B = x(\infty), \quad A = x(0) - x(\infty)$$

Roots of a Quadratic equation

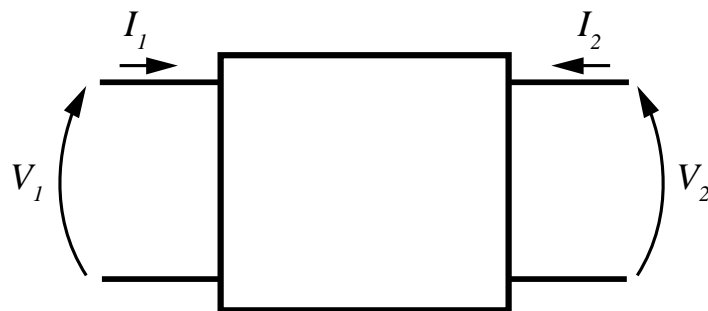
$$ax^2 + bx + c = 0 \text{ has roots } \alpha, \beta = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Laplace Transform Pairs

$f(t)$	$F(s)$	$f(t)$	$F(s)$
$u(t)$	$\frac{1}{s}$	$\left(\frac{1}{\omega} \sin \omega t\right) u(t)$	$\frac{1}{s^2 + \omega^2}$
$t.u(t)$	$\frac{1}{s^2}$	$\cos \omega t.u(t)$	$\frac{s}{s^2 + \omega^2}$
$\frac{t^{n-1}}{(n-1)!} u(t)$	$\frac{1}{s^n}$	$(1 - \cos \omega t) u(t)$	$\frac{\omega^2}{s(s^2 + \omega^2)}$
$e^{at}.u(t)$	$\frac{1}{s-a}$	$\sin(\omega t + \theta).u(t)$	$\frac{s \sin \theta + \omega \cos \theta}{s^2 + \omega^2}$
$t.e^{at}.u(t)$	$\frac{1}{(s-a)^2}$	$\cos(\omega t + \theta).u(t)$	$\frac{s \cos \theta - \omega \sin \theta}{s^2 + \omega^2}$
$\frac{t^{n-1}}{(n-1)!} e^{at} u(t)$	$\frac{1}{(s-a)^n}$	$e^{-at} \sin \omega t.u(t)$	$\frac{\omega}{(s+\alpha)^2 + \omega^2}$
$\frac{1}{(a-b)} (e^{at} - e^{bt}) u(t)$	$\frac{1}{(s-a)(s-b)}$	$e^{-at} \cos \omega t.u(t)$	$\frac{s+\alpha}{(s+\alpha)^2 + \omega^2}$
$\left[\frac{e^{-at}}{(b-a)(c-a)} + \frac{e^{-bt}}{(a-b)(c-b)} + \frac{e^{-ct}}{(a-c)(b-c)} \right] u(t)$	$\frac{1}{(s+a)(s+b)(s+c)}$	$\sinh \alpha t.u(t)$	$\frac{\alpha}{s^2 - \alpha^2}$
$(1 - e^{at}) u(t)$	$\frac{-a}{s(s-a)}$	$\cosh \alpha t.u(t)$	$\frac{s}{s^2 - \alpha^2}$

Two Port Parameters

Name	Function		Equation
	Express	In terms of	
Impedance (z)	V_1, V_2	I_1, I_2	$V_1 = z_{11}I_1 + z_{12}I_2$ $V_2 = z_{21}I_1 + z_{22}I_2$
Admittance (y)	I_1, I_2	V_1, V_2	$I_1 = y_{11}V_1 + y_{12}V_2$ $I_2 = y_{21}V_1 + y_{22}V_2$
Transmission (T)	V_1, I_1	$V_2, -I_2$	$V_1 = AV_2 - BI_2$ $I_1 = CV_2 - DI_2$
Inverse transmission (t)	V_2, I_2	$V_1, -I_1$	$V_2 = A'V_1 - B'I_1$ $I_2 = C'V_1 - D'I_1$
Hybrid (h)	V_1, I_2	V_2, I_1	$V_1 = h_{11}I_1 + h_{12}V_2$ $I_2 = h_{21}I_1 + h_{22}V_2$
Inverse hybrid (g)	V_2, I_1	V_1, I_2	$I_1 = g_{11}V_1 + g_{12}I_2$ $V_2 = g_{21}V_1 + g_{22}I_2$



RLC circuits

Resonant frequency: $\omega_0 = \frac{1}{\sqrt{LC}}$,

Series circuit: $\alpha = \frac{R}{2L}$, Parallel circuit: $\alpha = \frac{1}{2RC}$

Response to a DC forcing function V_f : $v(t) = v_f(t) + v_n(t) = V_f + A_1 e^{s_1 t} + A_2 e^{s_2 t}$

Where: $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$

Miller's Theorem:

$$Z_1 = \frac{Z}{1-K}, Z_2 = \frac{KZ}{K-1}, K = \frac{V_2}{V_1}$$

Impedance and Frequency Scaling:

$$R^* = bR, L^* = \frac{b}{a}L, C^* = \frac{1}{ab}C$$

Differentiation

$$\frac{d(g(h(x)))}{dx} = \frac{d(g(h(x)))}{dh} \frac{d(h(x))}{dx}$$

$$\frac{d}{dx}(f(x) \cdot g(x)) = f(x) \cdot g'(x) + g(x) \cdot f'(x)$$

$$\frac{d}{dx}\left(\frac{f(x)}{g(x)}\right) = \frac{g(x) \cdot f'(x) - f(x) \cdot g'(x)}{(g(x))^2}$$

$$\frac{d}{dx}e^x = e^x$$

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(a^x) = \ln a \cdot a^x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\frac{d}{dx}(\cot x) = -\csc^2 x$$

$$\frac{d}{dx}(\arcsin x) = \frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}(\operatorname{arcsec} x) = \frac{1}{x\sqrt{x^2-1}}$$

$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\tan x) = \sec^2 x$$

$$\frac{d}{dx}(\sec x) = \sec x \tan x$$

$$\frac{d}{dx}(\arctan x) = \frac{1}{1+x^2}$$

$$\frac{d}{dx}(\sinh x) = \cosh x$$

Integration

$$\int x^n dx = \frac{1}{n+1} x^{n+1} + c, \quad n \neq -1$$

$$\int a^x dx = \frac{1}{\ln a} a^x + c$$

$$\int \cos x dx = \sin x + c$$

$$\int \frac{dx}{1+x^2} = \arctan x + c$$

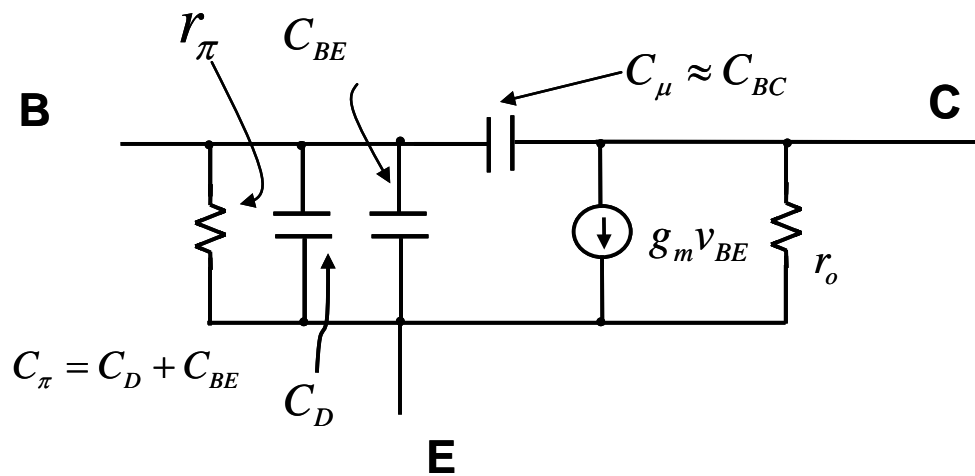
$$\int \frac{1}{x} dx = \ln|x| + c$$

$$\int \sin x dx = -\cos x + c$$

$$\int \csc^2 x dx = -\cot x + c$$

$$\int \frac{dx}{\sqrt{1-x^2}} = \arcsin x + c$$

BJT Forward Active Region Hybrid π Model



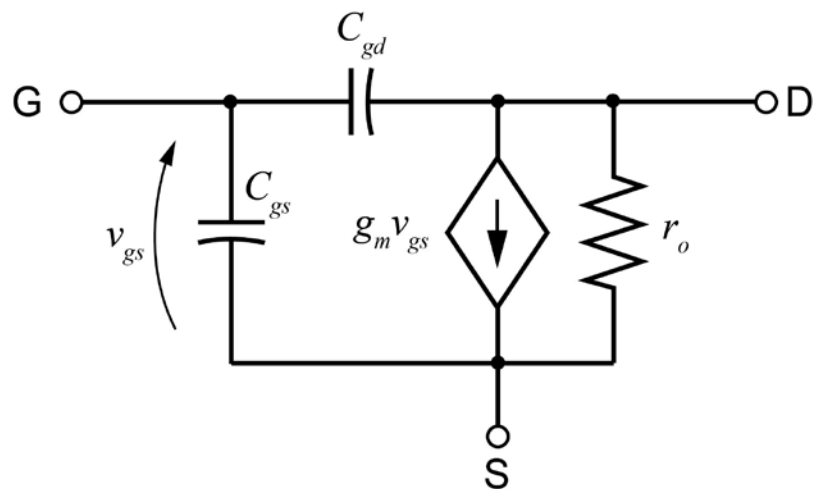
$I_E = (\beta + 1)I_B$	$I_C = \beta I_B$ $I_E = (\beta + 1)I_B$	$g_m = \frac{I_c}{V_T}$	$V_T = \frac{kT}{q}$
$r_\pi = \frac{\beta}{g_m}$	$\frac{1}{r_o} \approx \frac{I_C}{V_A}$	$f_T = \frac{g_m}{2\pi(C_\pi + C_\mu)}$	V_A Early Voltage

Enhancement FET Model

NMOS Transistor	PMOS Transistor
$K_n' = \mu_n C_{ox} = \mu_n \frac{\epsilon_{ox}}{t_{ox}}$	$K_p' = \mu_p C_{ox} = \mu_p \frac{\epsilon_{ox}}{t_{ox}}$
The cutoff region ($V_{GS} < V_t$): $I_{DS} = 0$	The cutoff region ($V_{GS} > V_t$): $I_{DS} = 0$
The linear region ($0 < V_{DS} < V_{GS} - V_t$) $I_{DS} = K_n' \frac{W}{L} [(V_{GS} - V_t)V_{DS} - \frac{V_{DS}^2}{2}]$	The linear region ($0 > V_{DS} > V_{GS} - V_t$) $I_{DS} = -K_p' \frac{W}{L} [(V_{GS} - V_t)V_{DS} - \frac{V_{DS}^2}{2}]$
The saturation region ($0 < V_{GS} - V_t < V_{DS}$) $I_{DS} = \frac{K_n'}{2} \frac{W}{L} (V_{GS} - V_t)^2 (1 + \lambda V_{DS})$	The saturation region ($0 > V_{GS} - V_t > V_{DS}$) $I_{DS} = -\frac{K_p'}{2} \frac{W}{L} (V_{GS} - V_t)^2 (1 + \lambda V_{DS})$

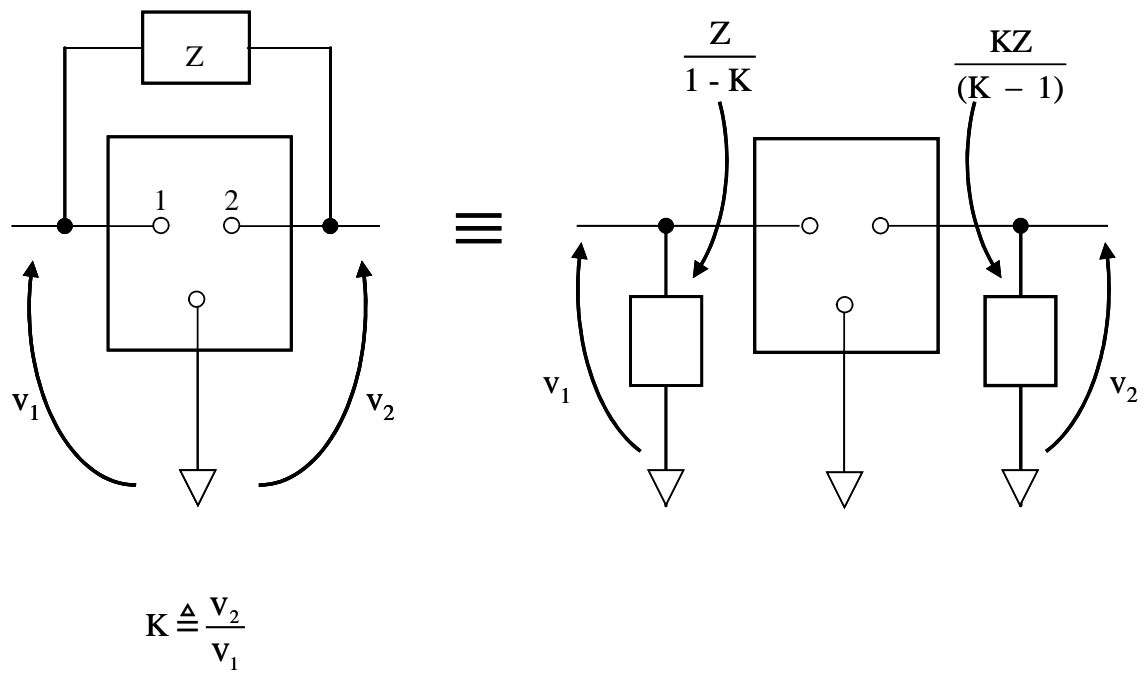
Enhancement N Channel FET Saturated Region Small Signal Model

(Source connected to substrate)

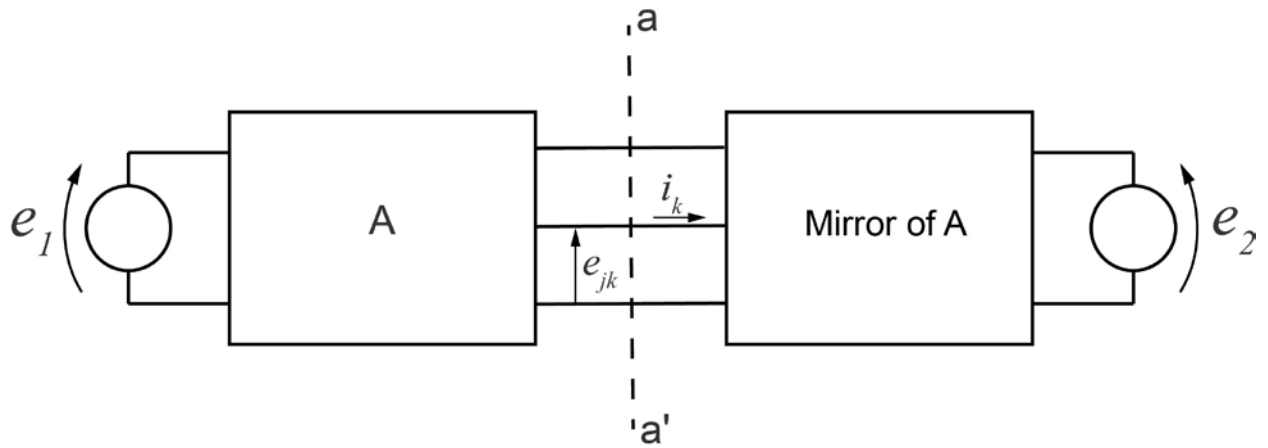


$g_m = \frac{2I_D}{V_{OV}}$	$r_o = \frac{1}{\lambda I_D}$
$V_{OV} \triangleq V_{GS} - V_T$ (overdrive voltage)	

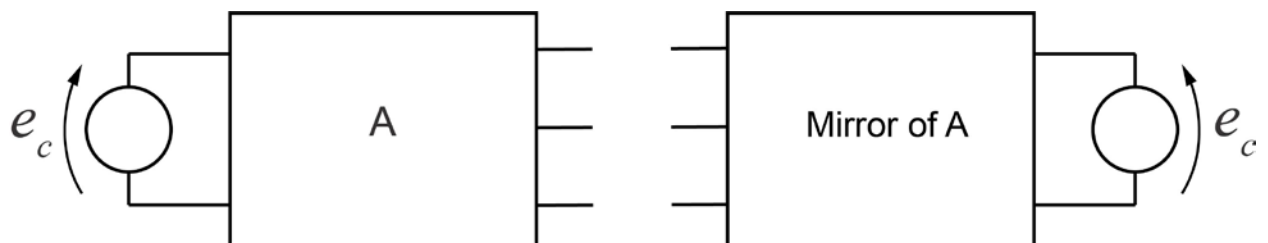
Miller's Theorem



Bisection Theorem



(a) Bisection Theorem Common Mode Equivalence



(b) Bisection Theorem Differential Mode Equivalence

