

## INFORMATION SHEET 2024 ELEC4401 Part II

### Tableau Equations

$$\begin{bmatrix} \mathbf{0} & \mathbf{0} & \mathbf{S} \\ -\mathbf{S}^T & \mathbf{I} & \mathbf{0} \\ \mathbf{0} & \mathbf{M}_0\mathbf{p} + \mathbf{M}_1 & \mathbf{N}_0\mathbf{p} + \mathbf{N}_1 \end{bmatrix} \begin{bmatrix} \mathbf{e}(t) \\ \mathbf{v}(t) \\ \mathbf{i}(t) \end{bmatrix} = \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{u}_s(t) \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{0} & \mathbf{0} & \mathbf{Q} \\ -\mathbf{Q}^T & \mathbf{I} & \mathbf{0} \\ \mathbf{0} & \mathbf{M}_0\mathbf{p} + \mathbf{M}_1 & \mathbf{N}_0\mathbf{p} + \mathbf{N}_1 \end{bmatrix} \begin{bmatrix} \mathbf{v}_t(t) \\ \mathbf{v}(t) \\ \mathbf{i}(t) \end{bmatrix} = \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{u}_s(t) \end{bmatrix}$$

$$\begin{bmatrix} -\mathbf{B}^T & \mathbf{0} & \mathbf{I} \\ \mathbf{0} & \mathbf{B} & \mathbf{0} \\ \mathbf{0} & \mathbf{M}_0\mathbf{p} + \mathbf{M}_1 & \mathbf{N}_0\mathbf{p} + \mathbf{N}_1 \end{bmatrix} \begin{bmatrix} \mathbf{i}_L(t) \\ \mathbf{v}(t) \\ \mathbf{i}(t) \end{bmatrix} = \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{u}_s(t) \end{bmatrix}$$

### R L C V-I Relations in Laplace Domain

$$i = C \frac{dv}{dt} \quad v = L \frac{di}{dt} \quad v = iR$$

$$, V(s) = \left( \frac{1}{Cs} \right) I(s) + \frac{v(0^-)}{s}, \quad V(s) = LsI(s) - Li(0^-), \quad V(s) = RI(s)$$

### The Origin of Initial Conditions

$$\int_a^x \frac{df(t)}{dt} dt = f(x) - f(a) \quad f(x) = \int_a^x \frac{df(t)}{dt} dt + f(a)$$

### SOLUTION TO FIRST ORDER LINEAR DIFFERENTIAL EQUATION

$$\tau \frac{dx}{dt} + x(t) = B \quad x(t) = Ae^{\left(-\frac{t}{\tau}\right)} + B$$

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### TRANSMISSION LINES

$v(x,t) = v_o + v_1 \left( t - \frac{x}{u_p} \right) + v_2 \left( t + \frac{x}{u_p} \right)$	forward backward wave decomposition
$i(x,t) = i_o + i_1 \left( t - \frac{x}{u_p} \right) + i_2 \left( t + \frac{x}{u_p} \right)$	forward backward wave decomposition
$i_1(x,t) - i_1(x,t_o) = \frac{1}{Z_0} (v_1(x,t) - v_1(x,t_o))$	
$i_2(x,t) - i_2(x,t_o) = -\frac{1}{Z_0} (v_2(x,t) - v_2(x,t_o))$	
Voltage Reflection Coefficient for a lossless line at an impedance $R$ $\rho = \frac{R - Z_0}{R + Z_0}$	
Transfer of an impedance $Z$ from $x=0$ to $x=l$ on a lossless transmission line in the frequency domain. $Z_l = Z_0 \left( \frac{Z \cos(\beta l) + jZ_0 \sin(\beta l)}{Z_0 \cos(\beta l) + jZ \sin(\beta l)} \right)$	
Transfer of source with impedance $Z_s$ at $x=0$ to $x=l$ on a lossless transmission line in the frequency domain. $V_{SE} = \frac{Z_0 V_s}{Z_0 \cos(\beta l) + jZ_s \sin(\beta l)}$	
$V_x = V_+ e^{-j\beta x} + V_- e^{j\beta x}$	
$\beta = \omega \sqrt{LC} \quad Z_0 = \sqrt{\frac{L}{C}} \quad u_p = \frac{1}{\sqrt{LC}}$	
$\rho(s) = \frac{Z(s) - Z_0(s)}{Z(s) + Z_0(s)}$	Reflection coefficient at an impedance $Z(s)$
<b>Uniform Loaded Line Equations Approximations</b> Load $C_x$ at spacing $l_x$ . Unloaded line capacitance $C_0$ F/m $a = \left( 1 + \frac{C_x}{l_x C_0} \right) = \left( 1 + \frac{Z_0 C_x}{T_x^{Unloaded}} \right)$	

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$$\tau_d^{Loaded} = \tau_d^{Unloaded} \sqrt{a} \quad Z_0^{Loaded} = \frac{Z_0^{Unloaded}}{\sqrt{a}}$$

### Approximate Second Order Modelling of Loaded Lossless Line

**Backward or Source  
end damping**

$$\omega_n = \frac{1}{\sqrt{Z_0 C_L T_d}}, \quad \xi = \frac{R_s (Z_0 C_L + T_d)}{2 Z_0 \sqrt{Z_0 C_L T_d}} \approx \frac{R_s}{2 Z_0} \sqrt{\frac{Z_0 C_L}{T_d}}$$

**Forward or Destination  
end damping**

$$\omega_n = \frac{1}{\sqrt{Z_0 C_L T_d}}, \quad \xi = \frac{Z_0}{2 R_L} \sqrt{\frac{T_d}{Z_0 C_L}}$$

### Two Port Model of Transmission Line



$$\begin{bmatrix} V_2(s) \\ -I_2(s) \end{bmatrix} = \begin{bmatrix} \cosh(\gamma(s)l) & -Z_0(s) \sinh(\gamma(s)l) \\ -\frac{1}{Z_0(s)} \sinh(\gamma(s)l) & \cosh(\gamma(s)l) \end{bmatrix} \begin{bmatrix} V_1(s) \\ I_1(s) \end{bmatrix}$$

$$Z_0(s) = \sqrt{\frac{(R + sL)}{(G + sC)}} \quad \gamma(s) \triangleq \sqrt{(R + sL)(G + sC)}$$

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### INCIDENCE MATRIX CONVENTION

$$\begin{cases} +1 & \text{edge } k \text{ leaves vertex } i \\ -1 & \text{edge } k \text{ enters vertex } i \\ 0 & \text{edge } k \text{ does not touch vertex } i \end{cases}$$

1. Given a connected digraph **G**, a **loop** **L** is defined to be a connected *subgraph* of **G** in which precisely two edges (branches) are incident with each node.
2. Any loop formed by branches of a circuit is called a **mesh** iff the loop encloses no other branches, or wires in its interior.
3. Given a connected digraph **G**, a subset of branches **C** of **G** is called a **cut set** iff the following two conditions are satisfied:
  - the removal of all the branches of the cut set results in a digraph that is not a connected digraph, and
  - the removal of all but any one branch of **G** leaves the digraph connected.
4. A (spanning) **tree** **T** of a connected graph **G** is a subgraph which satisfies three fundamental properties:
  - It is connected.
  - It contains all connected vertices of **G**.
  - It has no loops (circuits).
5. Given a tree **T**, the edges of **G** can be partitioned into two disjoint sets:
  - Edges which belong to **T**, called tree branches or **twigs** for short
  - Edges which do not belong to **T**, called *links* or chords or cotrees branches.
6. Every twig of **T** together with some links defines a unique cut set, called the **fundamental cut set** associated with the twig.
7. Every link of **T** and the unique path on the tree between its two nodes constitutes a unique loop, called the **fundamental loop** associated with the link.
8. If **S** is the incidence for a given connected digraph **G** contained with one node used as the datum, a theorem due to Kirchoff states that the number of spanning trees is given by  $\det(\mathbf{SS}^T)$ .

## LAPLACE TRANSFORMS

$F(s)$	$f(t), t > 0$
$Y(s) = \int_0^{\infty} \exp(-st)y(t) dt$	$y(t)$
$Y(s)$	$y(t) = \frac{1}{j2\pi} \int_{c-j\infty}^{c+j\infty} \exp(st) Y(s) ds$
$s^n Y(s) - s^{n-1} [y(0)]$ $- s^{n-2} [y'(0)] - \dots - s [y^{(n-2)}(0)]$ $- [y^{(n-1)}(0)]$	$y^{(n)}(t)$
$(1/s) F(s)$	$\int_0^t Y(\tau) d\tau$
$F(s)G(s)$	$\int_0^t f(t-\tau)g(\tau) d\tau$
$\frac{1}{\alpha} F\left(\frac{s}{\alpha}\right)$	$f(\alpha t)$
$F(s - \alpha)$	$\exp(-\alpha t) f(t)$
1	$\delta(t)$
$\exp(-\alpha s), \alpha \geq 0$	$\delta(t-\alpha)$
1/s	$u(t)$
$\frac{1}{s} \exp(-\alpha s)$	$u(t-\alpha)$
$\frac{1}{s^n}, n = 1, 2, 3, \dots$	$\frac{t^{n-1}}{(n-1)!}$
$\frac{1}{(s + \alpha)^n}, n = 1, 2, 3, \dots$	$\left[ \frac{t^{n-1}}{(n-1)!} \right] \exp(-\alpha t)$
$\frac{\alpha}{s(s + \alpha)}$	$1 - \exp(-\alpha t)$
$\frac{1}{(s + \alpha)(s + \beta)}, \beta \neq \alpha$	$\frac{1}{(\beta - \alpha)} [\exp(-\alpha t) - \exp(-\beta t)]$

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$\frac{s}{(s + \alpha)(s + \beta)}, \quad \beta \neq \alpha$	$\frac{1}{(\alpha - \beta)} [\alpha \exp(-\alpha t) - \beta \exp(-\beta t)]$
$\frac{\alpha}{s^2 + \alpha^2}$	$\sin(\alpha t)$
$\frac{s}{s^2 + \alpha^2}$	$\cos(\alpha t)$
$\frac{s^2 - \alpha^2}{[s^2 + \alpha^2]^2}$	$t \cos(\alpha t)$
$\frac{\alpha}{s^2 (s + \alpha)}$	$t - \frac{1}{\alpha} [1 - \exp(-\alpha t)]$
$\frac{s + \lambda}{(s + \alpha)^2 + \beta^2}$	$\exp(-\alpha t) \left\{ \cos(\beta t) + \left[ \frac{\lambda - \alpha}{\beta} \right] \sin(\beta t) \right\}$
$\frac{s + \alpha}{s^2 + \beta^2}$	$\frac{\sqrt{\alpha^2 + \beta^2}}{\beta} \sin(\beta t + \phi), \quad \phi = \arctan\left(\frac{\beta}{\alpha}\right)$

$$f(0^+) = \lim_{s \rightarrow \infty} sF(s)$$

$$f(\infty) = \lim_{s \rightarrow 0} sF(s)$$

## DIFFERENTIATION

$$\frac{d(g(h(x)))}{dx} = \frac{d(g(h(x)))}{dh} \frac{d(h(x))}{dx}$$

$$\frac{d}{dx}(f(x) \cdot g(x)) = f(x) \cdot g'(x) + g(x) \cdot f'(x)$$

$$\frac{d}{dx} \left( \frac{f(x)}{g(x)} \right) = \frac{g(x) \cdot f'(x) - f(x) \cdot g'(x)}{(g(x))^2}$$

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$

$$\frac{d}{dx}(a^x) = \ln a \cdot a^x$$

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\frac{d}{dx}(\tan x) = \sec^2 x$$

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$$\frac{d}{dx}(\cot x) = -\csc^2 x$$

$$\frac{d}{dx}(\sec x) = \sec x \tan x$$

$$\frac{d}{dx}(\arcsin x) = \frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}(\arctan x) = \frac{1}{1+x^2}$$

$$\frac{d}{dx}(\operatorname{arcsec} x) = \frac{1}{x\sqrt{x^2-1}}$$

$$\frac{d}{dx}(\sinh x) = \cosh x$$

## INTEGRATION

$$\int x^n dx = \frac{1}{n+1} x^{n+1} + c, \quad n \neq -1$$

$$\int \frac{1}{x} dx = \ln|x| + c$$

$$\int a^x dx = \frac{1}{\ln a} a^x + c$$

$$\int \sin x dx = -\cos x + c$$

$$\int \cos x dx = \sin x + c$$

$$\int \csc^2 x dx = -\cot x + c$$

$$\int \frac{dx}{1+x^2} = \arctan x + c$$

$$\int \frac{dx}{\sqrt{1-x^2}} = \arcsin x + c$$

$$\int \frac{dx}{ax^2 + bx + c} = \begin{cases} \frac{1}{\sqrt{b^2 - 4ac}} \ln \left( \frac{2ax + b - \sqrt{b^2 - 4ac}}{2ax + b + \sqrt{b^2 - 4ac}} \right) & , b^2 - 4ac \geq 0 \\ \frac{2}{\sqrt{4ac - b^2}} \tan^{-1} \left( \frac{2ax + b}{\sqrt{4ac - b^2}} \right) & , b^2 - 4ac < 0 \end{cases}$$