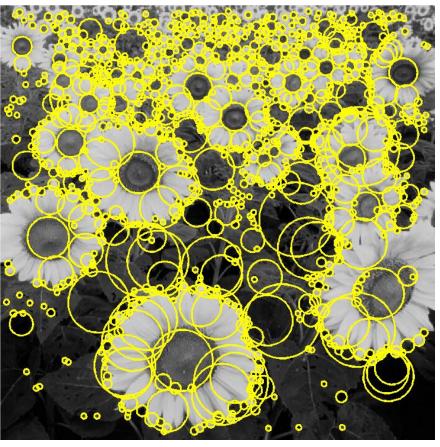
CS 231

Feature detection and matching

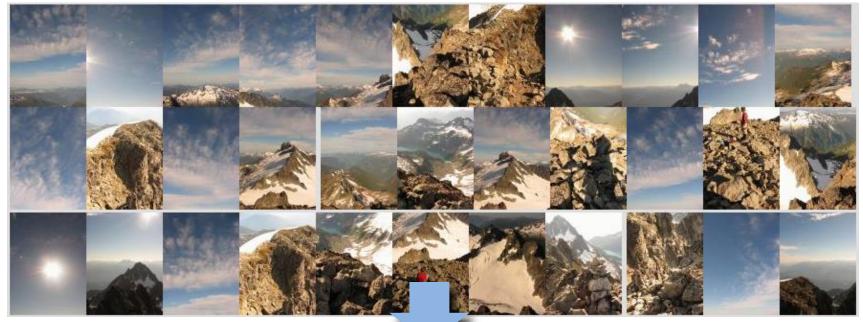


Feature extraction: Corners and blobs





Motivation: Automatic panoramas





Motivation: Automatic panoramas



HD View

http://research.microsoft.com/en-us/um/redmond/groups/ivm/HDView/HDGigapixel.htm

Also see GigaPan:

http://gigapan.org/

Why extract features?

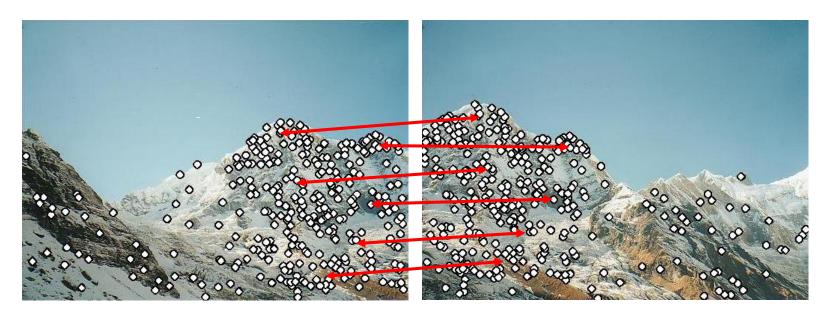
- Motivation: panorama stitching
 - We have two images how do we combine them?





Why extract features?

- Motivation: panorama stitching
 - We have two images how do we combine them?



Step 1: extract features Step 2: match features

Why extract features?

- Motivation: panorama stitching
 - We have two images how do we combine them?



Step 1: extract features

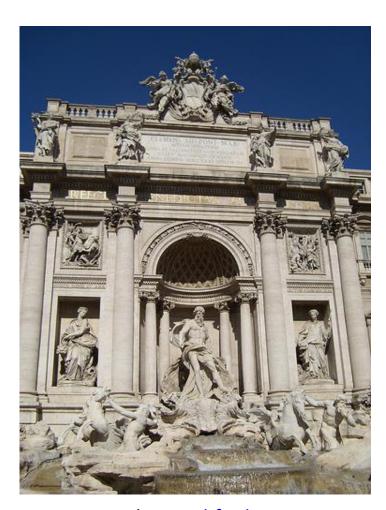
Step 2: match features

Step 3: align images

Image matching



by <u>Diva Sian</u>



by <u>swashford</u>

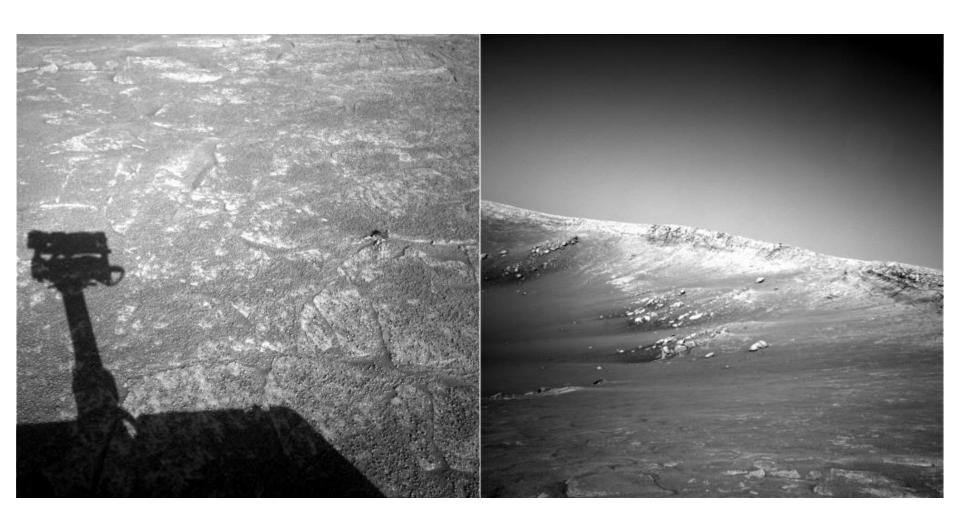
Harder case



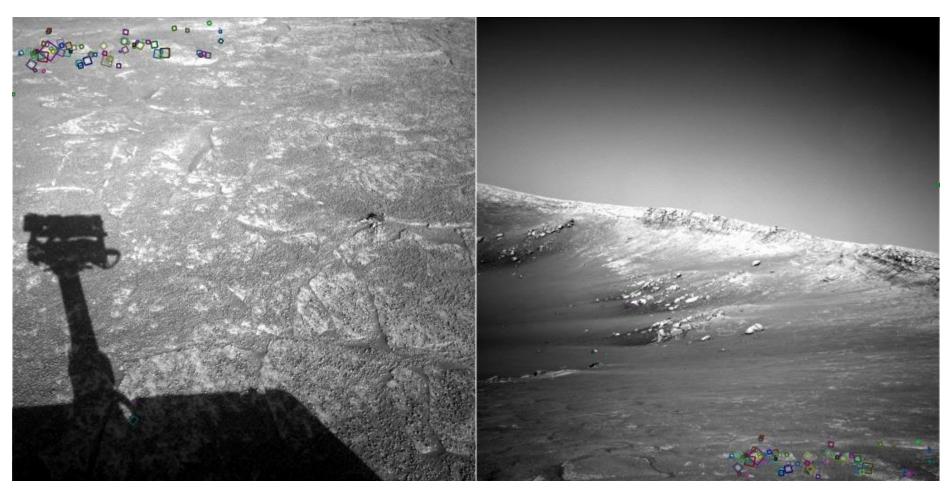


by <u>Diva Sian</u> by <u>scgbt</u>

Harder still?

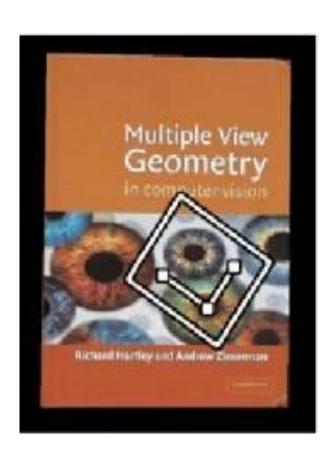


Answer below (look for tiny colored squares...)



NASA Mars Rover images with SIFT feature matches

Feature Matching





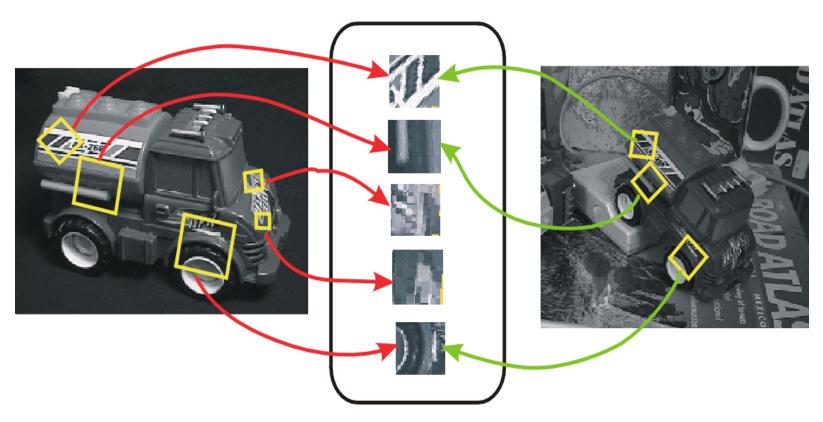
Feature Matching



Invariant local features

Find features that are invariant to transformations

- geometric invariance: translation, rotation, scale
- photometric invariance: brightness, exposure, ...



Feature Descriptors

Advantages of local features

Locality

features are local, so robust to occlusion and clutter

Quantity

hundreds or thousands in a single image

Distinctiveness:

can differentiate a large database of objects

Efficiency

real-time performance achievable

More motivation...

Feature points are used for:

- Image alignment (e.g., mosaics)
- 3D reconstruction
- Motion tracking
- Object recognition
- Indexing and database retrieval
- Robot navigation
- ... other



Want uniqueness

Look for image regions that are unusual

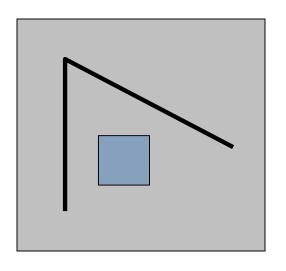
Lead to unambiguous matches in other images

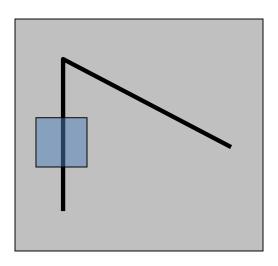
How to define "unusual"?

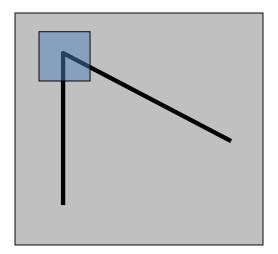
Local measures of uniqueness

Suppose we only consider a small window of pixels

— What defines whether a feature is a good or bad candidate?

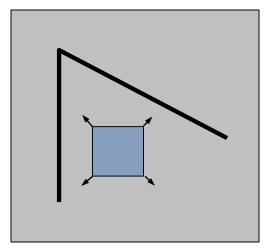




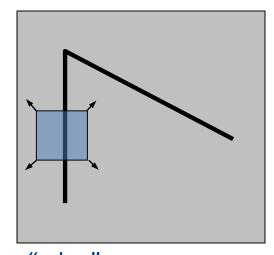


Local measure of feature uniqueness

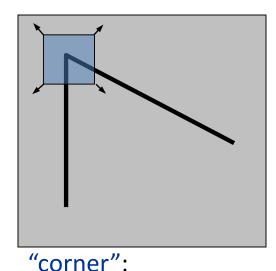
- How does the window change when you shift it?
- Shifting the window in any direction causes a big change



"flat" region: no change in all directions



"edge": no change along the edge direction



significant change in all directions