



GoDroid

Developer Guide



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Preface

Overview

This manual aims to provide detailed guidance to developers on how to perform software development by using GoDroid package. It describes how to configure and compile each component of GoDroid, how to develop and debug applications, and so on. It is comprised of the following chapters:

Chapter 1: Installation

This chapter mainly introduces how to access the source codes and toolchains, the software and hardware requirements, and how to install the toolchains.

• Chapter 2: Compilation

This chapter introduces how to compile each components of the GoDroid to generate the image files for burn purpose.

• Chapter 3: Starting up GoDroid

This chapter provides information on starting up GoDroid and how to get serial console via serial tools for control over the TIGER Board.

Chapter 4: Application Development and Debugging

This chapter introduces commonly used functions of Android Debug Bridge (abbreviated to ADB).

Chapter 5: FAQ

This chapter lists frequently asked questions and answers.

Audience

This manual is primarily written to provide complete guidance for those who wants to exploit the GoWarrior platform, such as makers, tinkers, innovators, students, etc.

Applicable Products

This manual is applicable for the GoWarrior TIGER Board.



Reference Documents

- GoWarrior_GoDroid_Programming Guide_Ext-Recovery
- GoWarrior_GoDroid_ Programming Guide _Ext-Uboot
- GoWarrior_GoDroid_Application Notes_How to Build Customized Projects
- GoWarrior_GoDroid_Application Notes_Customization of Boot Logo and Animation
- GoWarrior_GoDroid_Application Notes_Recovery Upgrade Package Making
- GoWarrior_GoDroid_Application Notes_Compiling Server Installation and Configuration Guide
- GoWarrior_GoDroid_Release Notes



Conventions

Typographical Conventions

Item	Format
codes, keyboard input commands, file names, equations, and math	Courier New, Size 10.5
Variables, code variables, and code comments	Courier New, Size, Italic
Menu item, buttons, tool names	Ebrima, Size 10.5, Bold e.g. Select USB Debugging
Screens, windows, dialog boxes, and tabs	Ebrima, Size 10.5, Bold Enclosed in double quotation marks e.g. Open the "Debug Configuration" dialog box

Table 1. Typographical Conventions

Symbol Conventions

Item	Description
<u> </u>	Indicates a potential hazard or unsafe practice that, if not avoided, could result in data loss, device performance degradation, or other unpredictable results.
♦ Note	Indicates additional and supplemental information for the main contents.
9 Тір	Indicates a suggestion that may help you solve a problem or save your time.

Table 2. Symbol Conventions



How to Contact Us

Submit all your comments and error reports to the author at:

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For questions regarding GoWarrior, contact our support team at the email listed below:

support@gowarriorosh.com



1 Introduction

This chapter focuses on requirements of the host PC and the TIGER Board, for development based on GoDroid, also how to obtain GoDroid package, and how to install toolchains.

1.1 Introduction

GoDroid is an Android development kit of the GoWarrior platform, which is based on AOSP (Android Open Source Project). It is mainly applicable for Android and Linux developers. GoWarrior is a compact, open-source, community-supported embedded Android/Linux computing platform geared toward maker/hacker/entrepreneur/dreamer/artist/student/inventor/hobbyist/tinker. It brings together a rich feature set of innovative building blocks with cloud-driven back-end service deployment. It can be used to build complex applications that interact high-level software and low-level electronic circuits, helping you from idea through prototype to commercial mass production delivery.

GoDroid Development Kit includes some important components, such as U-Boot, Embedded Media Engine, Androidized Linux Kernel and GoWarrior-customized AOSP source codes.

1.2 Preparation for Installation

GoDroid can only run on TIGER Board with ALi M3733 chipset.

Essential software needs to be installed on the host PC for operations such as development, compilation, and debugging based on GoDroid.



1.2.1 Hardware Requirements

The table below lists the device where GoDroid can run.

Device	Chipset	Components
	M3733-AFAAA	5V/2A stabilized power adapter,
		Micro USB cable,
		HDMI cable or 3.5mm to RCA composite video and stereo audio cable,
TIGER Board		USB keyboard, USB mouse,
		Remote controller,
		Monitor,
		Ethernet cable if need wired network,
		USB to TTL Serial cable

Table 3. Hardware Requirements

1.2.2 Host (PC) Requirement

For development and compilation environment of GoDroid, please refer to "GoWarrior_GoDroid_Application Notes_Compiling Server Installation and Configuration Guide".

The host development environment of GoDroid is based on 64-bit Ubuntu, for instance Ubuntu 12.04

(http://www.ubuntu.com/desktop/get-ubuntu/download) and Oracle JDK 6 tool.

1.3 Getting Source Code

1.3.1 Getting GoDroid Source Code

Procedure:

1. Download GoDroid patch and Android source code from GitHub by



executing the following commands:

```
$ git clone https://github.com/GoWarrior/GoDroid_V1.0_patch
$ repo init -u https://github.com/GoWarriorGoDroid/manifest -b
android-4.4.4_r2
$ repo sync
```

2. Unzip the patch by executing the following commands:

```
$ unrar e GoDroid_V1.0_patch.tar.part01.rar
$ xz -d GoDroid_V1.0_patch.tar.xz
$ tar -xvf GoDroid_V1.0_patch.tar
$ cd GoDroid_V1.0_patch/
$ ls
GoDroid_V1.0.patch patch runpatch.sh
```

3. Copy *GoDroid_V1.0.patch*, *runpatch.sh* and the *patch* folder to the android-4.4.4 r2 folder:

```
$ cp -rf GoDroid_V1.0_patch/* ../android-4.4.4_r2
$ cd ../android-4.4.4_r2
$ ls
abi bionic build dalvik development docs frameworks hardware
libnativehelper ndk patch prebuilts sdk tools
art bootable cts developers device external GoDroid_V1.0.patch
libcore Makefile packages pdk runpatch.sh system
```

4. Run the patch by executing the following command:

```
$ sh runpatch.sh
```

1.3.2 Getting PDK Source Code

Procedure:

1. Download the GoDroid PDK source code by executing the following



command:

```
git clone https://github.com/GoWarrior/PDK GoDroid.git
```

2. After downloading, switch to the root directory of PDK, and then change its branch to *godroid-1.0* by executing the following command:

```
git checkout godroid-1.0
```

1.4 Toolchain Installation

1.4.1 Installing ARM Toolchain

Procedure:

1. Download the ARM cross compiling toolchain package by executing the following commands:

```
# mkdir -p $HOME/ali_toolchain
# cd $HOME/ali_toolchain
# git clone https://github.com/GoWarrior/tools_arm-linux-gnueabi.git
arm_toolchain
# cd arm_toolchain
# ls
gcc-linaro-arm-linux-gnueabi-2012.01-20120125_linux.tar.gz
```

2. Unzip the package and configure the environment variable PATH by executing the following commands:

```
# tar xzvf gcc-linaro-arm-linux-gnueabi-2012.01-20120125_linux.tar.gz
# PATH=$HOME/ali_toolchain/arm_toolchain/arm-linux-gnueabi/bin:$PATH
# export PATH
```

1.4.2 Installing MIPS Toolchains

Procedure:

1. Download the MIPS cross compiling toolchain package by executing



the following commands:

```
# cd $HOME/ali_toolchain

# git clone https://github.com/GoWarrior/mips-sde-elf.git
mips_toolchain

# cd mips_toolchain

# ls

mips-4.3-221-mips-sde-elf-i686-pc-linux-gnu.tar.bz2
```

2. Unzip the package and configure the environment variable PATH by executing the following commands:

```
# tar xjvf mips-4.3-221-mips-sde-elf-i686-pc-linux-gnu.tar.bz2
# PATH=$HOME/ali_toolchain/mips_toolchain/mips-4.3/bin:$PATH
# export PATH
```

1.4.3 Installing AOSP Toolchains

Please refer to "GoWarrior_GoDroid_Compiling Server Installation and Configuration Guide".



2 Compilation

The sections below describe how to compile each component.

2.1 Compiling Bootloader (U-Boot)

Procedure:

1. Access the U-Boot directory.

\$ cd uboot

2. Configure U-Boot version

Update the U-Boot version number in the file include/configs/ali_3921.h if there is any update in U-Boot.

```
$ vim include/configs/ali_3921.h
#define BOOTLOADER_VERSION "ALiBoot1.2.0"
```



The naming rule of U-Boot version is customizable according to actual requirements.

3. Compile.

```
$ make rebuild_3921
```

4. Output.

Upon completion of compilation, the following four files will be generated in the directory $/{\tt uboot}$.

```
u-boot.bin,
u-boot.dis,
u-boot.map,
```



u-boot.out

5. View output files

All the u-boot file versions will be generated in the directory: uboot/uboot merger/uboot output.

```
$cd uboot/uboot_merger/uboot_output
$ls
uboot_unify_1GB_training.abs...
```

2.2 Compiling Audio Engine

Procedure:

1. Switch to the audio engine directory by executing the following command:

```
$ cd /tds/ae_sdk/src/ae/m36f_linux
```

2. Compile the audio engine module by executing the following commands:

```
$ make path
$ make config_3921_release
$ make generate_ae
```

2.3 Compiling SEE

Procedure:

1. Switch to the SEE directory by executing the following command:

```
$ cd /tds/see_sdk/src/see/m36f_linux
```

2. Compile the SEE module by executing the following commands:

```
$ make path
$ make config_3921_release
$ make generate_see
```



2.4 Compiling Android Linux Kernel

Procedure:

1. Kernel configuration

For information on configuring Android Linux kernel, please refer to "GoWarrior_GoDroid_Application Notes_How to Build Customized Projects".

This step is performed only when necessary. As Android has made some expansion and customization of Linux kernel, refer to http://source.android.com/devices/tech/kernel.html for kernel configuration items recommended by Android.

To add or delete a configuration item for kernal, modify the file linux/kernel/boards/TIGER_BOARD/defkernelconfig_linux-linaro-3.4-rc3, or execute the following command:

```
$ cd /linux
$ make BOARD=TIGER_BOARD linux-config
```

 Run the following script to copy the files (uboot_*.abs, ae_bin.abs and see bin.abs) required by kernel compilation:

```
$ cd /linux
$./ cp_bootabs_release.sh TIGER_BOARD
```

3. Execute the following commands to compile the kernel:

```
$ cd /linux
$ make BOARD= TIGER_BOARD
```

Upon completion of compilation, the output files will be generated in the directory: /linux/install/bin. The files required by generating Flash burning files are listed below. They need to be copied to different directories according to the Flash type.

```
ae_bin.abs
main_bin.abs
see_bin.abs
uboot unify 1GB training.abs
```

4. Move the files by executing the following commands:



cp /linux/install/bin/see_bin.abs AOSP/device/gowarrior/tigerboard
/image/bin/

cp /linux/install/bin/ae_bin.abs AOSP/device/gowarrior/tigerboard
/image/bin/

cp /linux/install/bin/main_bin.abs AOSP/device/gowarrior/tigerboard
/image/fs ubi/main bin.abs

cp /linux/install/bin/ uboot unify 1GB training.abs

AOSP/device/gowarrior/tigerboard/image/fs_ubi/

2.5 Compiling Android File System

2.5.1 GoDroid Configuration

For GoDroid configuration, please refer to "GoWarrior_GoDroid_Application Notes_How to Build Customized Projects". The configuration files are located in the directory device/gowarrior/tigerboard, and include several main configuration files listed in the table below.

File	Description
shell/tigerboard_init.sh	The GoDroid custom configuration script after Android is started.
<pre>input/tigerboard_ir.conf, input/tigerboard_panel.kl,</pre>	They are the key configuration files of remote controller and front panel. For more information, visit the official website at: http://source.android.com/devices/tech/input/index.html
<pre>input/tigerboard_remote.idc, input/tigerboard_remote.kl</pre>	tigerboard_ir.conf is the mapping table between the physical key values and key codes of the remote controller and front panel. It can be modified according to the TIGER Board and remote controller.



File	Description	
BoardConfig.mk	It is one of the main configuration files. It defines the arguments related to Board during compilation, such as IC type, instruction sets supported, and some Board definitions.	
device.mk	It is very important, because the variables in it define lots of information related to Board, and almost all the project settings are included in this file. For variables in this file, please refer to build/core/product.mk.	
fstab.tigerboard.ubifs	The mount argument list of file system. It includes some partitions' mount arguments of NAND Flash UBIFS file system type and mount arguments of USB external USB flash disk or mobile hard disk.	
	For more information , please refer to the introduction in the official website: http://source.android.com/devices/tech/storage/index.html	
fstab.tigerboard.recovery	The mount argument list used by Recovery.	
init.tigerboard.rc	It is a very important Android start script.	
init.tigerboard.recovery.rc	It is the start script of Recovery system.	
init. tigerboard.rt18723.rc	This is the script to enable Wi-Fi.	
system.prop	System attributes configurations, such as time zone.	
version.mk	It is the version configuration file used to set the version number for bootloader, recovery, and system.	

Table 4. GoDroid Configuration File



2.5.2 Compiling GoDroid

GoDroid compilation mode is very similar with the native Android compilation mode. The only difference is that GoDroid compilation mode requires selection of <code>aosp_tigerboard-eng</code> during lunch, as shown in Compilation Step 2.

Preparation:

If you need to modify SDK configurations after compiling, you need to make clean first.

```
$ make clean
```

Procedure:

1. Execute \$. build/envsetup.sh in the directory where AOSP is located.

```
$ . build/envsetup.sh

including device/generic/armv7-a-neon/vendorsetup.sh
including device/gowarrior/tigerboard/vendorsetup.sh
including sdk/bash_completion/adb.bash
```

2. Execute \$ lunch

```
$ lunch
You're building on Linux

Lunch menu... pick a combo:
    1. aosp_arm-eng
    2. aosp_x86-eng
    3. aosp_mips-eng
    4. vbox_x86-eng
    5. mini_armv7a_neon-userdebug
```



- 6. aosp_tigerboard-eng
- 7. aosp_tigerboard-userdebug
- 8. aosp tigerboard-user

Which would you like? [aosp arm-eng]

3. Select aosp tigerboard-eng as shown the figure above.

```
Which would you like? [aosp_arm-eng] 6
_____
PLATFORM VERSION CODENAME=REL
PLATFORM_VERSION= 4.4.4
TARGET_PRODUCT= aosp_tigerboard
TARGET BUILD VARIANT=eng
TARGET BUILD TYPE=release
TARGET BUILD APPS=
TARGET_ARCH=arm
TARGET ARCH VARIANT=armv7-a-neon
TARGET CPU VARIANT=cortex-a9
HOST ARCH=x86
HOST_OS=linux
HOST OS EXTRA=Linux-3.2.0-29-generic-x86 64-with-Ubuntu-12.04-precis
HOST BUILD TYPE=release
BUILD ID= KTU84Q
OUT DIR=out
Source
/shsa022/usrhome/bobby.zhou/work/SDK6.0ha.1.3.4 AAND/device/gowarrio
r/tigerboard/shell/build slot.sh...
Run
/shsa022/usrhome/bobby.zhou/work/SDK6.0ha.1.3.4 AAND/device/gowarrio
```



r/tigerboard/shell/build_pre.sh...
python
/shsa022/usrhome/bobby.zhou/work/SDK6.0ha.1.3.4_AAND/build/tools/hos

ttools/python/genpartsizemk.py

/shsa022/usrhome/bobby.zhou/work/SDK6.0ha.1.3.4_AAND/image/Ali_nand_desc.xml

/shsa022/usrhome/bobby.zhou/work/SDK6.0ha.1.3.4_AAND/device/gowarroir/tigerboard/image/fs_ubi/partsize.mk

4. Compile make

```
$ make -j8
```

-j8 in the make parameter indicates that eight threads are used to compile AOSP. The make –j I usually gotten by cat /proc/cpuinfo |grep -c 'processor'. AOSP compilation may takes some time. It usually takes about 40 to 50 minutes in case of quad-core and eight threads, and takes about ten minutes in case of 48 cores and 48 threads.

5. Output

The output of AOSP compilation is located in the directory

/out/target/product/tigerboard/ which mainly includes the following three directories.

data/
root/
system/

2.5.3 Compiling GoDroid Recovery

You can compile recovery after compiling GoDroid.

Compiling command:

\$ make recoveryimage

Compiled Recovery is outputted in this directory:

out/target/product/tigerboard/. It mainly includes:

recovery/



recovery_system/

2.6 Generating Image Files

After completing the compilation steps above, you need to generate other files like <code>cache.img</code> and <code>ALI.ini.A</code> complete burn package can be generated by just running the build image command from the root directory of Android compilation. The burn package directory is located in the image directory of the root directory.

```
$ build image
$cd image/burn
$1s
cache.img
ALI.ini
deviceinfo.abs
recovery.ubosdram C3921 BGA462 1GB 1600Mbps.abs
backup.abs
baseparams.abs
kernel.ubo
system.img
bootargs.abs
uboot unify 1GB training.abs
bootmedia.ubo
NandList v2.ran
userdata.img
```

2.7 Burning GoDroid Image Files

After compiling all the components of GoDroid and generating corresponding image files, you can burn all the image files to the TIGER



Board. For more information, please refer to "GoWarrior_ GoDroid_GoDroid Installation".



3 Starting up GoDroid

3.1 Starting up GoDroid

You can start up GoDroid after connect TIGER Board and monitor by the following steps.

Procedure:

1. Connect a HDMI cable to the HDMI interface of the TIGER Board and to HDMI input port on Monitor; or connect the CVBS video cable to CVBS output port and video input port on Monitor. Besides, ensure that the correct Monitor video input port is selected.

Turn on the Monitor and ensure that correct Monitor input port (HDMI or video) is selected.

- 2. Connect the Ethernet cable (optional).
- 3. Connect one end of the serial debugging daughter board to TTL serial port of the TIGER Board and the other end to the host, the connection is shown in Figure 1. Run a serial console on the host and set information like serial port and baud rate (115200) as shown in the figure below.



Figure 1. Connecting Serial Port



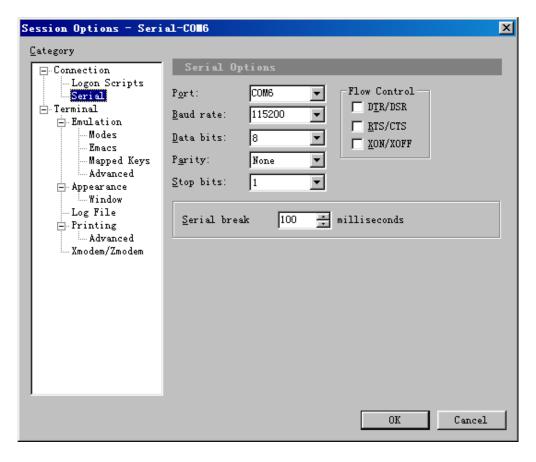


Figure 2. Serial Port Setup



"Parity" needs to be set according to the actual situation, like the status of board and serial port daughter board.

- 4. Insert a USB flash disk or portable HDD to USB Port1 or Port2 (optional).
- 5. Connect the USB keyboard or USB mouse to USB Port1 or Port2 (optional).
- 6. Connect the USB cable to USB port0.





Figure 3. USB Port0

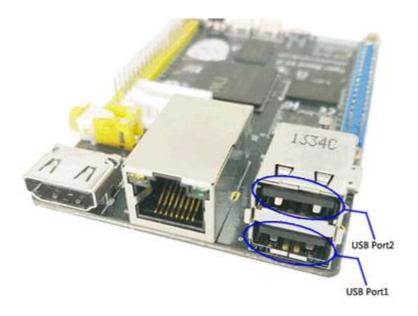


Figure 4. USB Port1/Port2

3.2 Serial Console

After the TIGER Board is powered on and GoDroid starts up, the serial console will print the GoDroid boot processes. The printed information is as shown below:



```
U-Boot 2012.04.01 (Dec 12 2014 - 10:20:39)

CPU : ALi M3921 BGA package

Board: S3921 SB/DB

Top of RAM usable for U-Boot at: 8bff0000

Reserving 780k for U-Boot at: 8bf2c000

Reserving 12288k for malloc() at: 8b32c000

Reserving 36 Bytes for Board Info at: 8b32bfdc

Reserving 120 Bytes for Global Data at: 8b32bf64

New Stack Pointer is: 8b32bf58

DRAM: 192 MiB

Now running in RAM - U-Boot at: 8bf2c000
```

Until the GoDroid startup is completed, after TV displays the home screen, you can enter control commands on serial console to display system information or to control system operation. For example, you can use some commonly-used commands such as cd, ls, and logcat.

" 1s" command is running as below:

```
~ # ls
acct
cache
config
data
default.prop
dev
etc
file contexts
fstab.tigerboard
init.environ.rc
init.rc
init.tigerboard.rc
init.tigerboard.rtlwifi.rc
init.tigerboard.usb.rc
init.trace.rc
```



```
init.usb.rc
initlogo.rle.bak
mnt
proc
property_contexts
root
sbin
sdcard
seapp_contexts
sepolicy
storage
sys
system
tmp
ueventd.rc
ueventd.tigerboard.rc
usbdrive
vendor
~ #
```



4 Application Development and Debugging

4.1 Using ADB Debugger

ADB is a versatile tool that lets you manage the state of the Android-powered device. For more information about what is possible with ADB, see Android Debug Bridge page at

http://developer.android.com/tools/help/adb.html.

The ADB tool can be used to

- Download an application from a host machine, install and run it on the target board.
- Start a remote shell in the target instance.
- Debug applications running on the device using the debugging tool DDMS (Dalvik Debug Monitor Server) which runs on top of ADB connection.
- Copy files from and to the board.

4.1.1 ADB over Ethernet

Procedure:

- 1. Select "**USB debugging**" from "**Developer options**" in the system settings menu.
- 2. Type the "start adbd" command in the serial output of the target table.
- 3. Make sure that the host PC and the TIGER Board is properly connected via a network cable and can be pinged mutually.
- 4. Type the "netcfg" command in the serial output of the target table,



the IP address: 192.168.1.100 is the IP address of the TIGER Board.

```
~ # netcfg
                                             127.0.0.1/8
                                                           0x00000049
00:00:00:00:00:00
                                               0.0.0.0/0
                                                           0x00001002
p2p0
        DOWN
5a:63:56:10:d6:e2
eth0
        UP
                                         192.168.1.100/24 0x00001043
00:41:4c:69:a0:27
                                               0.0.0.0/0
                                                           0x00001002
wlan0
        DOWN
58:63:56:10:d6:e2
```

5. On the host PC, use the following commands to establish ADB connection.

```
$ adb connect <target_ip_address>
```

- 6. Verify device connectivity by executing the command "\$ adb devices". If connected, you can find the device name list.
- 7. If the device isn't displayed, please restart ADB server to reconnect the TIGER Board.

```
$ adb kill-server
$ adb start-server
$ adb connect <target_ip_address>
```

4.1.2 ADB over USB

For Detail Information of ADB over USB, please refer to "GoWarrior_GoDroid_Application Notes_USB ADB Debugging".

4.2 Operations over ADB

Once after ADB on host PC has been connected to the TIGER Board, ADB tool can be used to do some operations as follows.



4.2.1 Installing Application (.apk files)

You can use ADB tool for package installation from the host PC.

```
$ adb install <package.apk>
```

4.2.2 Uninstalling Application (.apk) Using ADB

To uninstall an application (.apk), firstly execute the following command on the host machine.

```
$ adb shell pm list packages
```

Then view what packages (application) there are, and execute the following command to uninstall the package (application) what you want.

```
$ adb uninstall <package name>
```

4.2.3 Copying Files From and To the Board over ADB

Use the ADB commands "push" and "pull" to copy files to and from the board.

To copy a file or directory (recursively) from the board, use

```
$ adb pull <remote> <local>
```

To copy a file or directory (recursively) to the board, use

```
$ adb push <local> <remote>
```

In the above commands, for <local> and <remote>, please refer to the paths of the file or directory on your development host (local) and on the target instance (remote).

Here's an example:

```
$ adb push Antutu_4.1.5.apk /data/app/Antutu_4.1.5.apk
```

It means that Antutu_4.1.5.apk under the local directory will be copied to the /data/app/directory on the target board.



4.3 Bootloader Development

GoDroid bootloader uses open source project of U-Boot. For more information on modification in U-Boot, please refer to "GoWarrior_GoDroid_Programming Guide_Ext-Uboot".

4.4 Recovery Development

GoDroid provides a complete recovery (system upgrade) solution that supports OTA/IP/USB. This recovery module possesses enhanced functionalities based on Android native Recovery module. For detailed information, please refer to "GoWarrior_GoDroid_Programming Guide Exit-Recovery".

For information on making a recovery upgrade package, please refer to "GoWarrior_GoDroid_Application Notes_Recovery Package Making".

4.5 Customization of Android Boot Logo and Animation

For details, please refer to "GoWarrior_GoDroid_Application Notes_ Customization of Boot Logo and Animation".

4.6 Using GoDroid SDK's Android Java Library in Android Studio

Android Studio can use different versions of SDK that can be downloaded from Google website by SDK Manager. APP developers can use the downloaded SDK to develop APP to run on GoDroid. But if you want to use the extra features which are provided by GoDroid, you need to use the GoDroid SDK's Android Java library instead of the standard one from Google.

To use the GoDroid SDK's Android Java library, it's only requires to replace the Android Java library file in Android Studio SDK with the GoDroid. The location of Android SDK in Android Studio is displayed in the dialog of SDK manager.



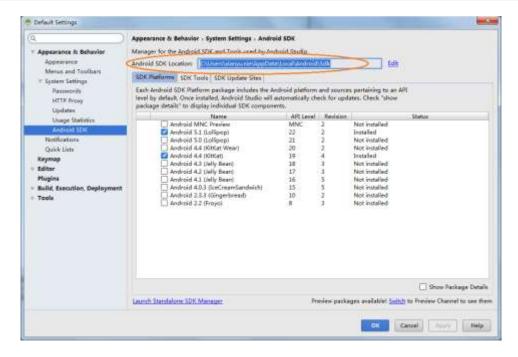


Figure 5. SDK Manager

As GoDroid is based on Android 4.4 (KitKat), so you only need to replace the android.jar for API level 19. Which is to replace the Android SDK's following path platforms\android-19\android.jar with the android.jar from GoDroid SDK.

In the example of Figure 5, the file needs to be replaced with
C:\Users\xianyu.nie\AppData\Local\Android\Sdk\platforms
\android-19\android.jar.



5 FAQ

No.	Problem Description	Solution
1	Cannot compile \$ make BOARD=TIGER_BOARD when building Kernel	Check if the compiler path of /linux/kernel/boards/TIGER_BOARD variables.mak file is the compiler path of your compiling server. If it is not the following default path, please change it to the compiler path of your compiling server. export DEV_CROSS_COMPILE_PATH =
		/opt/arm-linux-gnueabi
2	No printout for TTL serial of board	Please confirm your serial board and check out whether your serial line is a parallel or crossover cable. Besides, please make sure that the serial console configuration items like Baud rate and Parity are set correctly.
3	No response for ADB	First check if the ADB tool has been connected to the TIGER Board using the Ebrima\$ adb devices" command. If not connected, please use the "\$ ADB connect" command, or re-plug the USB cable to confirm whether connection has been established.
5	commands	ADB may be unstable sometimes. Use the following commands to restart ADB.
		\$ adb kill-server
		\$ adb start-server

Table 5. FAQ List



Appendix: Glossary

Abbr.	Full Name
ADB	Android Debug Bridge
AOSP	Android Open Source Project
GoDroid	GoWarrior Android Development Kit

Table 6. List of Abbreviations



Revision History

Document Change History

Revision	Changes	Date
v1.01	Updated GoDroid and PDK source code download commands. Updated the Kernel compile steps.	March 11, 2016
v1.0	Initial Release	September 07, 2015

Table 7. Document Change History

Software Changes

Revision	Changes	Date
v1.0	Initial Release	September 07, 2015

Table 8. Software Change History



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