

CONFIGURATION FORM ROBOTIC

Company
Name
Date:

Robot brand

Robot model

Power source welding power

400A

500A

Other

Robot interface location

In cabinet

On power source

Communication type

Analog

Digital

Communication protocol

Profibus DP

Ethernet IP

Can-open

Devicenet

Interbus

Profinet

Ethercat

Wire supply

Drum

Spool

Optionals

Torch/Anticollision

Wire-End device

Pallet (GT)

Power source-robot distance (m)

Power supply-cabinet distance (m)

Wire drum-robot distance (m)

Welding process

Standard MIG/MAG

DC TIG

Pulsed MIG/MAG

AC TIG

Filler material

Unalloyed steel

High alloyed steel

Aluminum

Nickel alloys

Copper alloys

Hardfacing

Wire diameter

0.8 mm

1.2 mm

1.0 mm

1.6 mm

Other requests

Cleaning station

Nozzle sensing

Other

Application industry

Notes