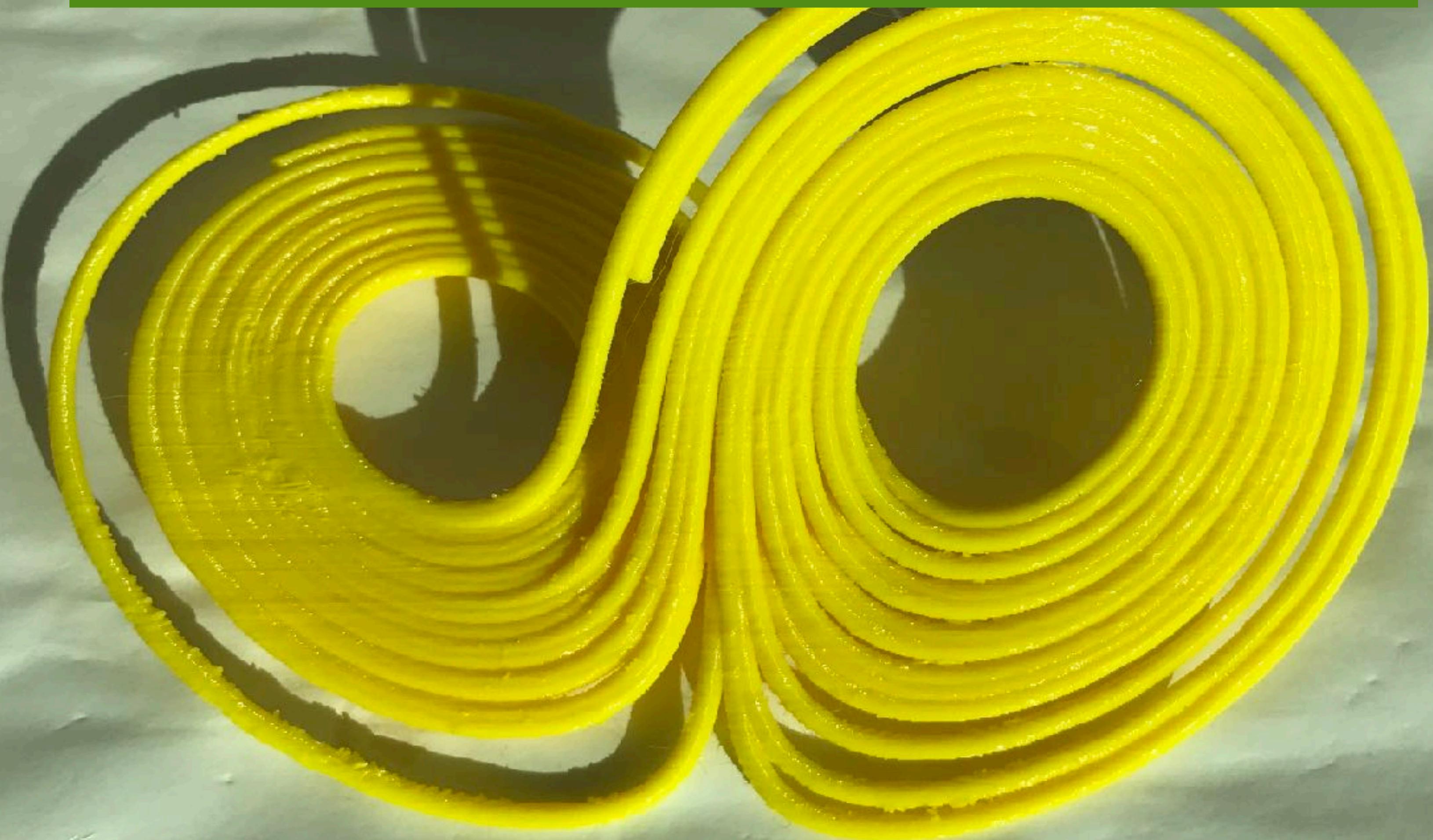


EVELYN SANDER, GEORGE MASON UNIVERSITY

PRINTING DYNAMICAL SYSTEMS AND CHAOS





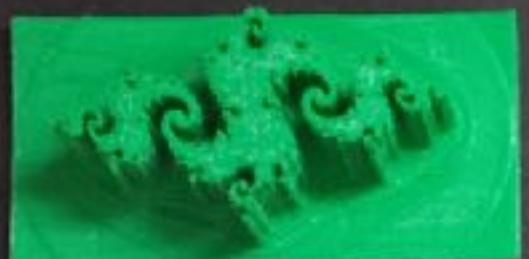
- Assistant: Ratna Khatri
- Accessibility: Tactile Graphs
- Outreach:
 - Middle School Girls Camp
 - USASEF Festival
- Education:
 - Multivariable Calculus
 - Mathematics Through 3D Printing

[HTTP://GMUMATHMAKER.BLOGSPOT.COM](http://gmumathmaker.blogspot.com)

GMU MATH MAKER LAB

Mandelbrot and Julia Sets

Math 493: Mathematics through 3D Printing
Course Instructor: Dr. Evelyn Sander



Nicole Van Oort



Jonathan Farr

Kope Roberts



Henry Delgado



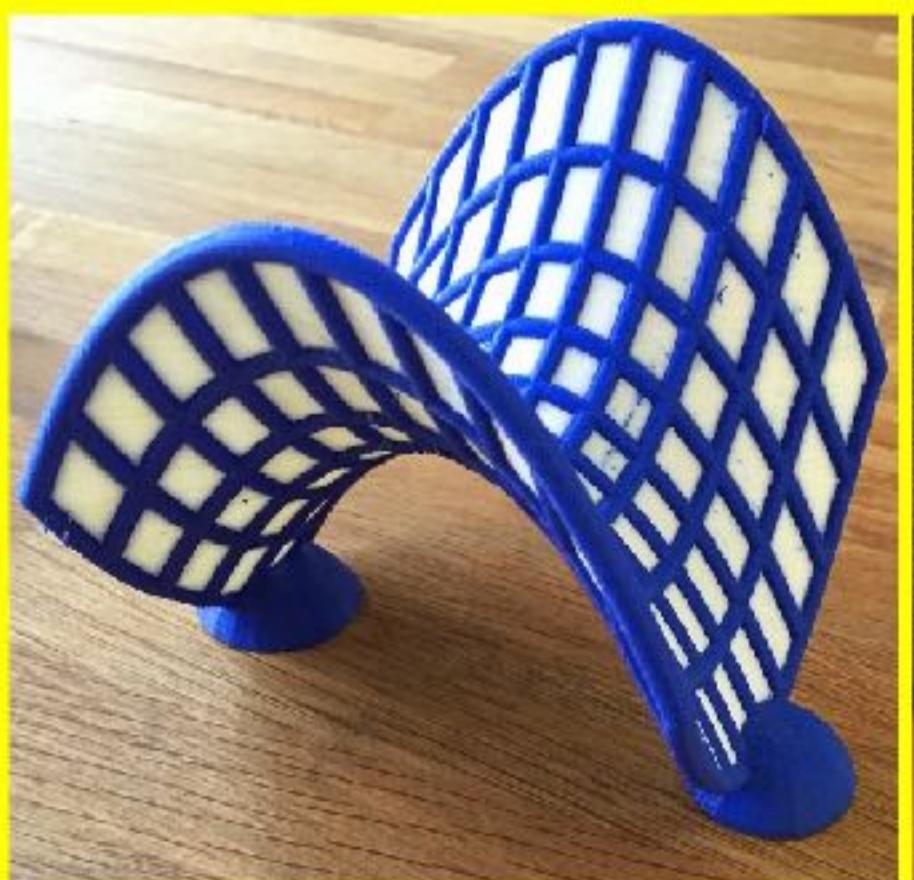
Annabelle Slatton



Mandelbrot and Julia Sets indicate the behavior of iterated polynomial maps in the complex plane. The Mandelbrot set is the set of parameter values such that iterates of the origin stay bounded under the quadratic map $x_{n+1} = x_n^2 + c$. The Julia sets are the sets of points whose iterates escape to infinity under the same map.



5 THINGS DESIGNED AND PRINTED BY STUDENTS, 1 THAT WAS NOT.
GOAL: BEYOND TRADITIONAL GEOMETRY



2. ITERATED FUNCTION SYSTEMS



3. CHAOTIC ATTRACTORS



CONTENTS OF TALK

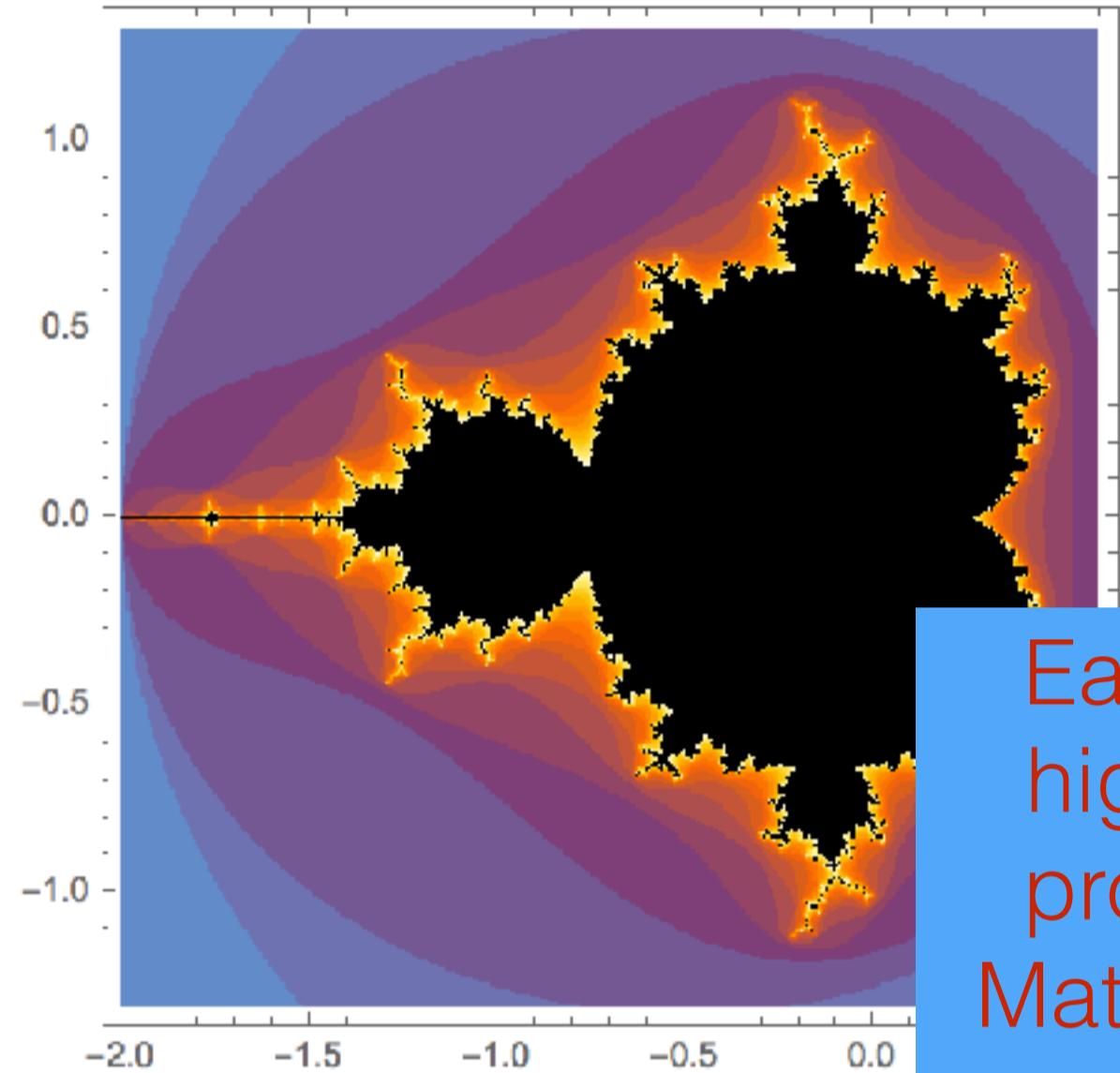


4. EVOLUTION EQUATIONS

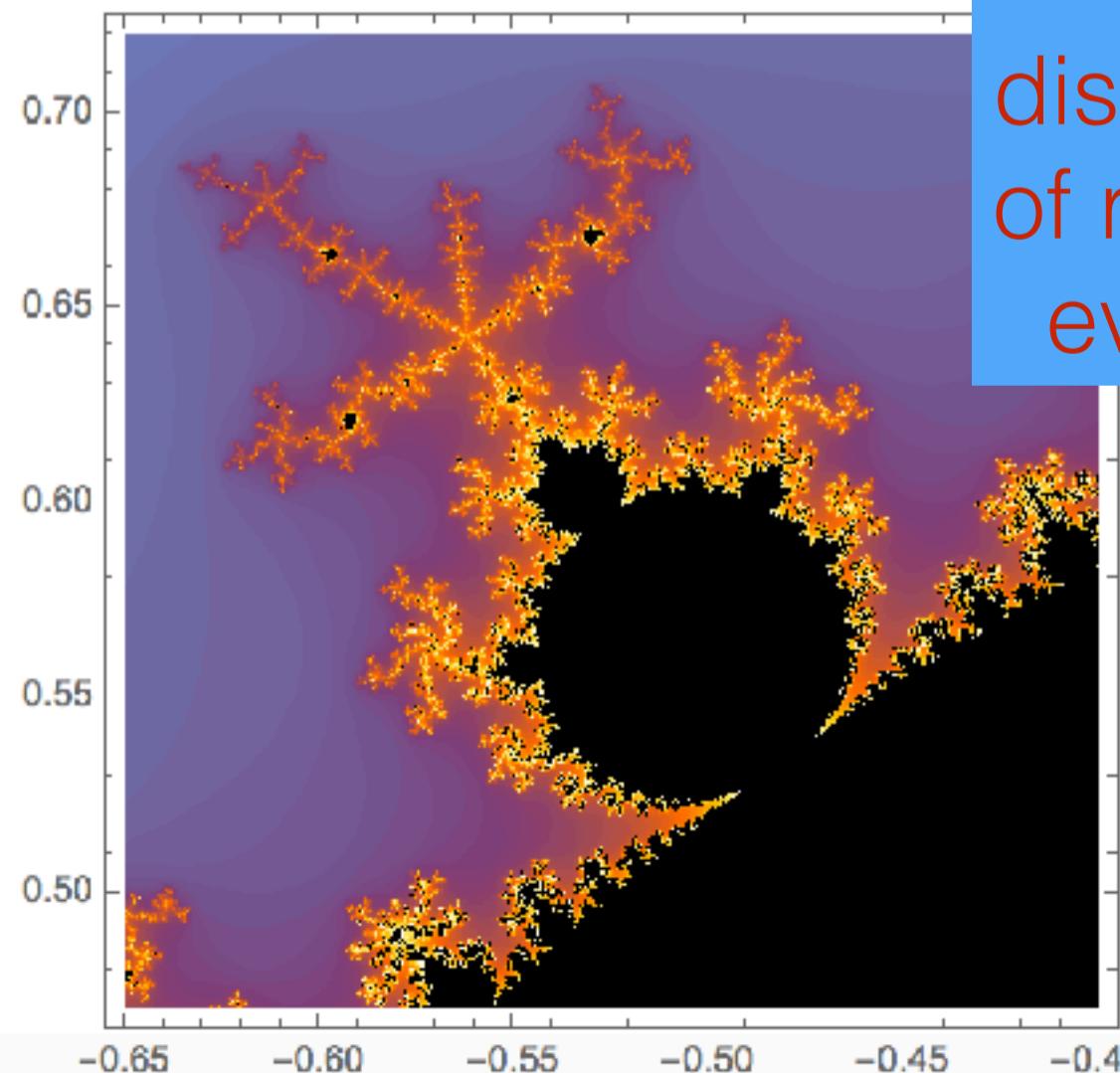
1. MANDELBROT AND JULIA SETS

1. MANDELBROT AND JULIA SETS

MandelbrotSetPlot [MaxIterations → 20]



MandelbrotSetPlot[{-0.65 + 0.47 I,

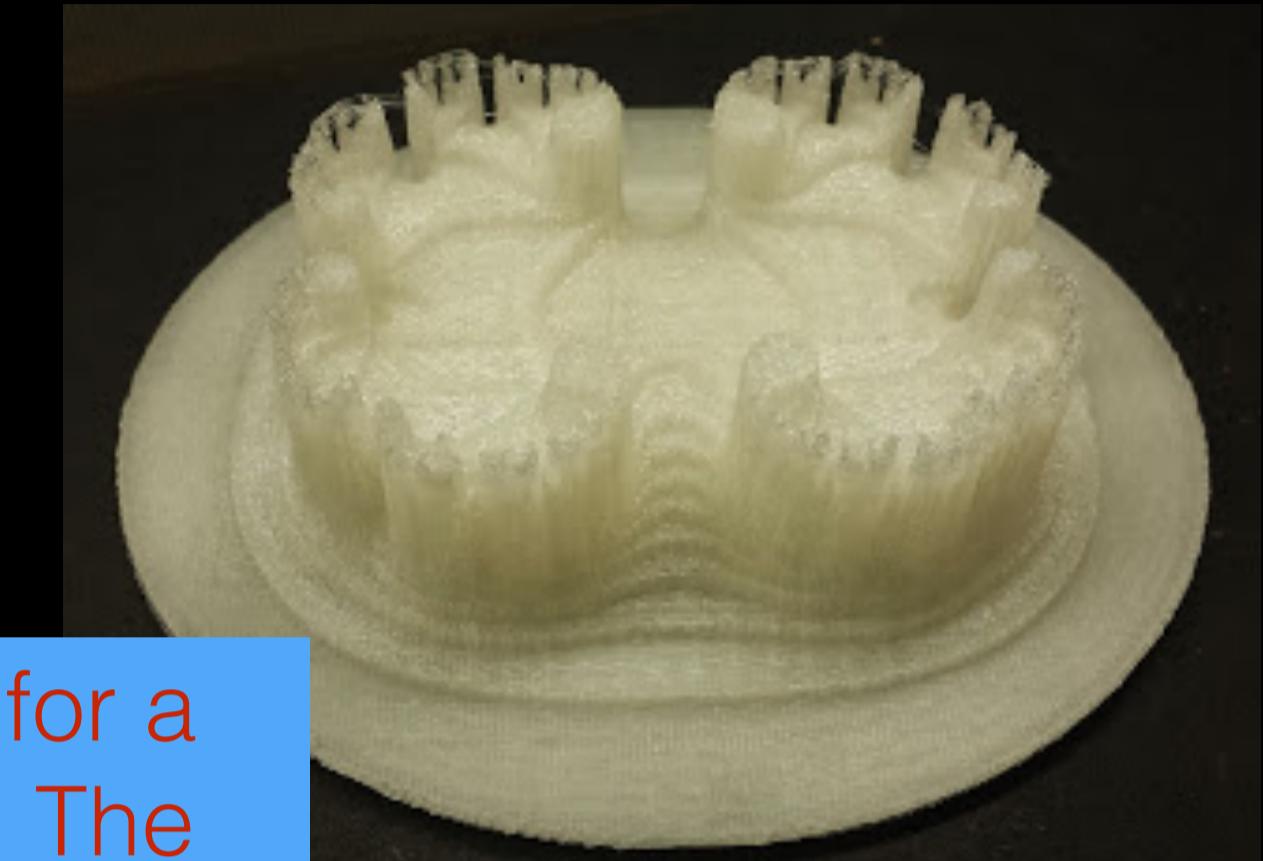


Easy to define even for a high school student. The process is automated by Mathematica. A good topic when starting complex numbers. Leads to a discussion of iteration. Plenty of room to add sophistication even at the graduate level.

plex numbers c such stays bounded under $f(z) = z^2 + c$

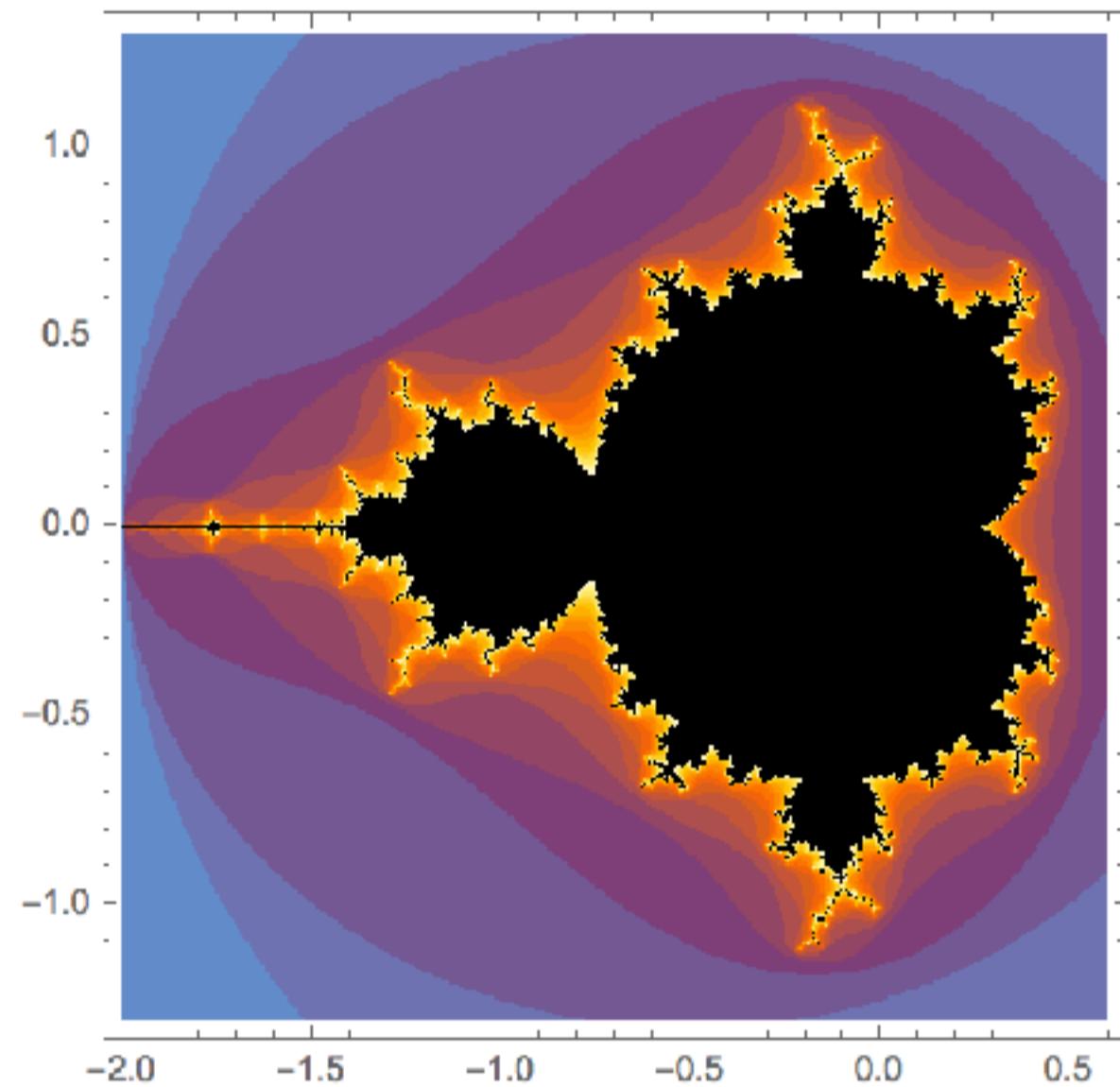
Mathematica allows for the creation of STL files:

```
a = ParametricPlot3D[...]
Export["mymesh.stl", a]
```

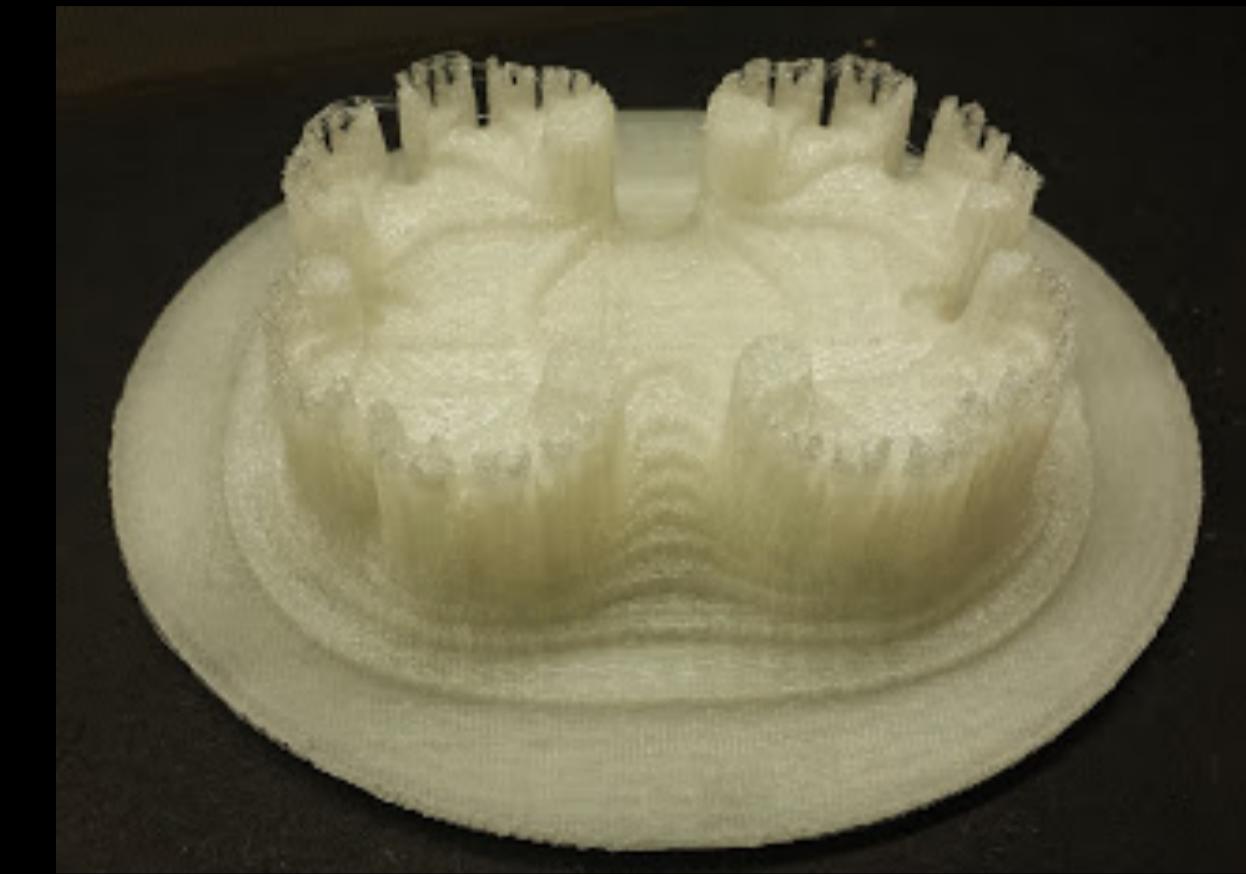
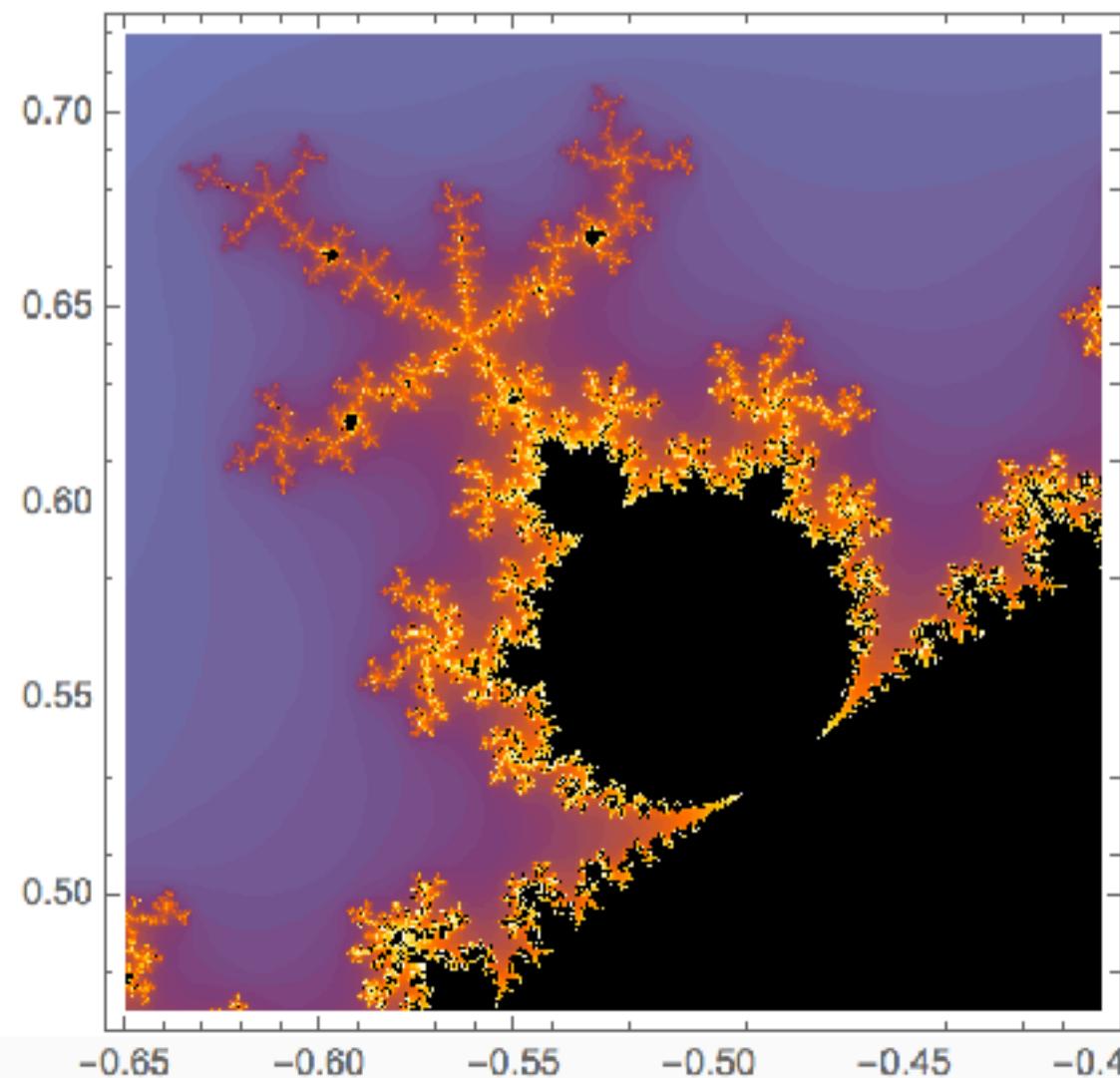


1. MANDELBROT AND JULIA SETS

MandelbrotSetPlot [MaxIterations → 20]



MandelbrotSetPlot[{-0.65 + 0.47 I, -0.4 + 0.72 I}, MaxIterations → 100]



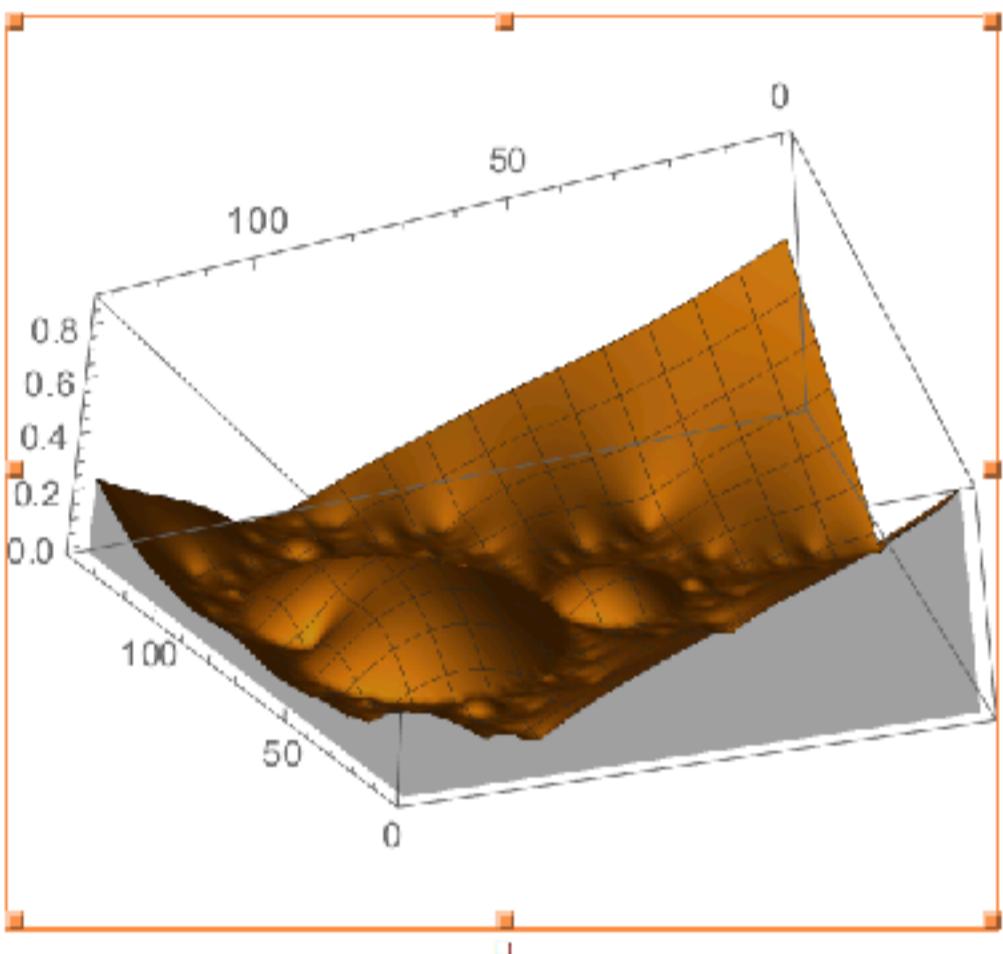
Complex numbers c such
that 0 stays bounded under
 $f(z) = z^2 + c$

Mathematica allows for the
creation of STL files:

```
a = ParametricPlot3D[...]  
Export["mymesh.stl", a]
```

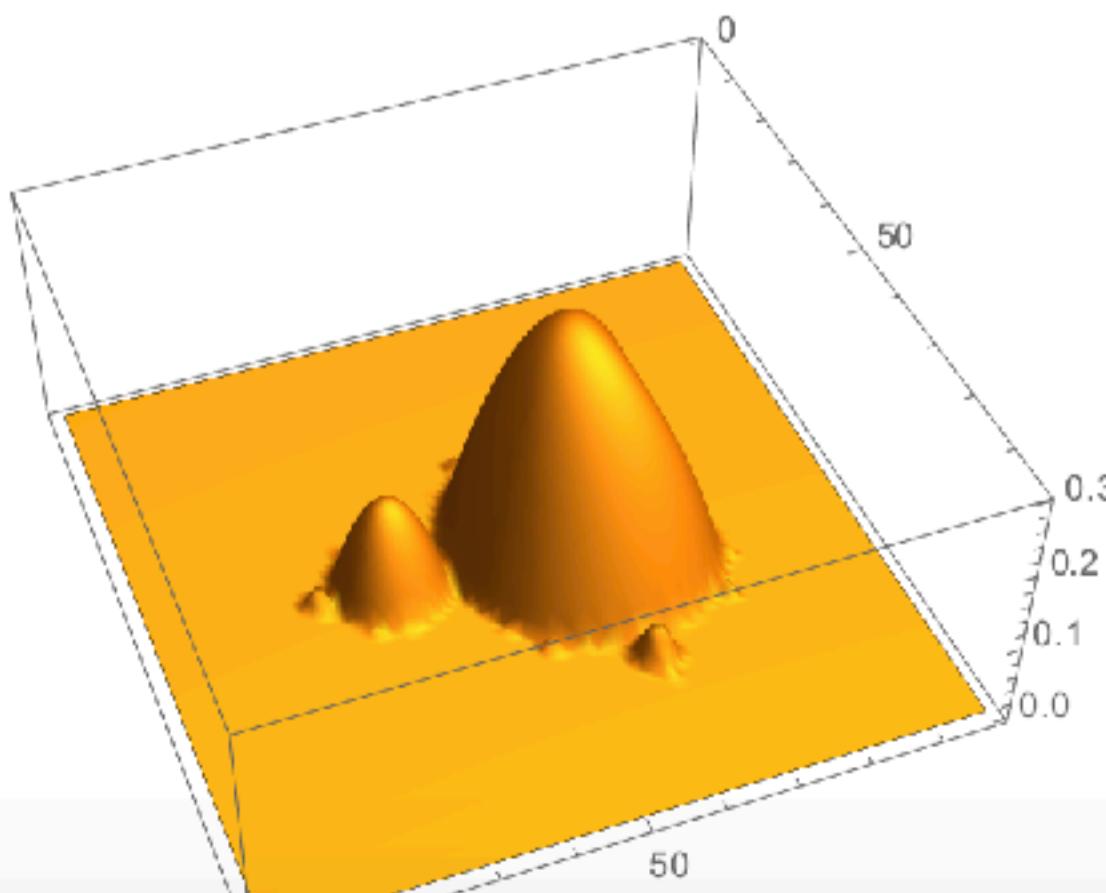
1. MANDELBROT AND JULIA SETS

```
data = Table[Max[MandelbrotSetDistance[#, "Interior"], MandelbrotSetDistance[#] / 4] &[x + I*y],  
{y, -1.5, 1, .02}, {x, -2, .6, .02}];  
ListPlot3D[data, Filling -> Bottom]
```



The distance to
the edge of the
Mandelbrot set

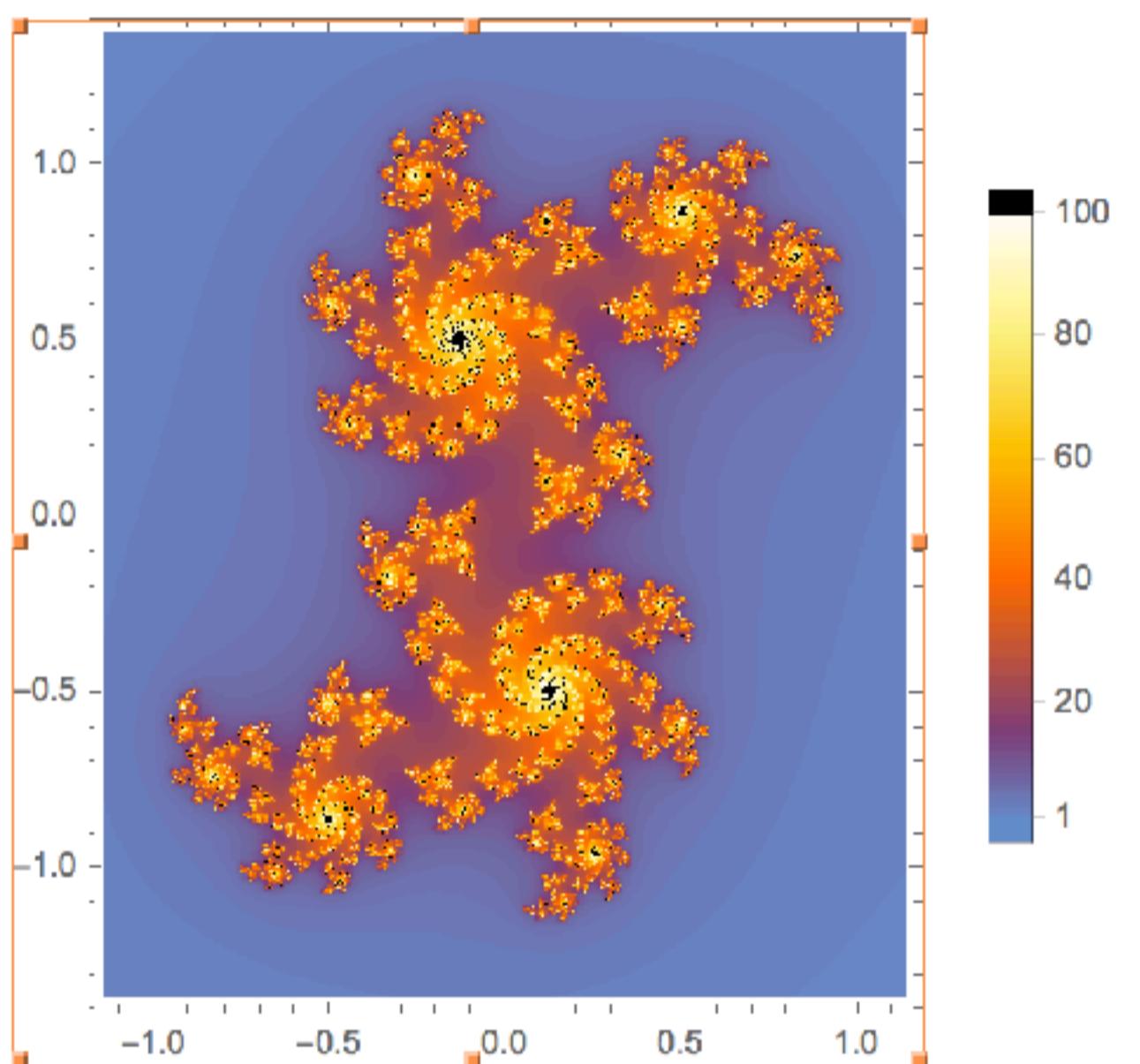
```
data = Table[MandelbrotSetDistance[x + I*y, "Interior", MaxIterations -> 40], {x, -2., 1., .031},  
{y, -1.5, 1.5, .031}];  
ListPlot3D[data, Mesh -> None, PlotRange -> Full, Filling -> Bottom]
```



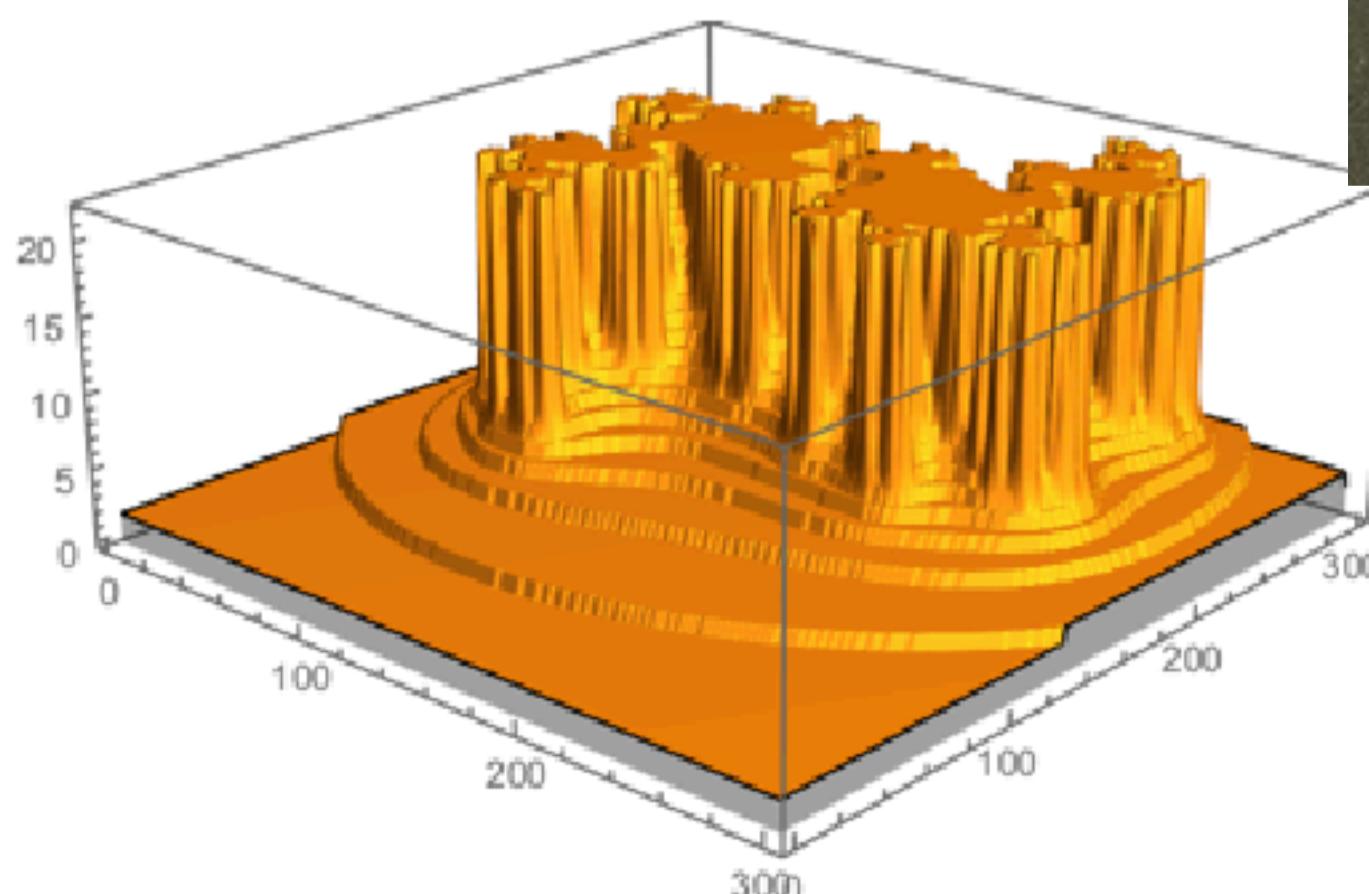
The distance to
the exterior of
Mandelbrot set

1. MANDELBROT AND JULIA SETS

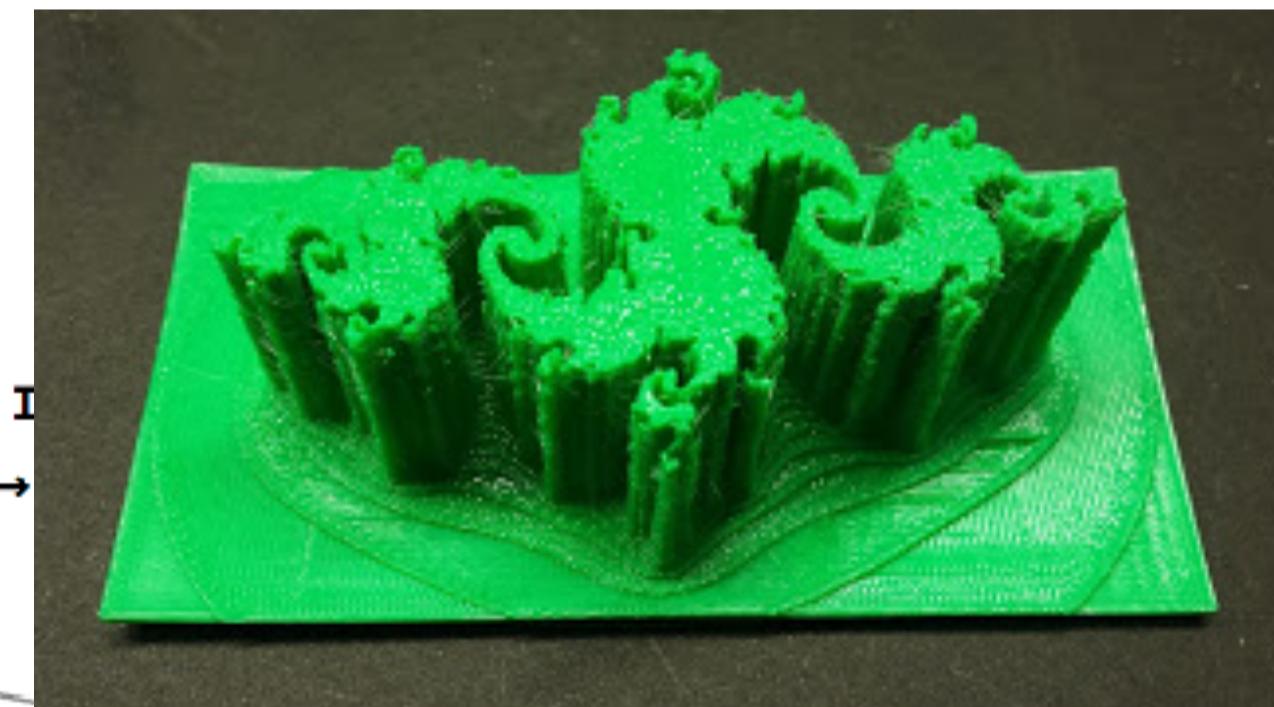
JuliaSetPlot[0.365 - 0.37 i, PlotLegends → Automatic]



ListPlot3D[
JuliaSetIterationCount[0.365 - 0.37 i, Table[x + I
MaxIterations → 20] + 1, Mesh → False, Filling →

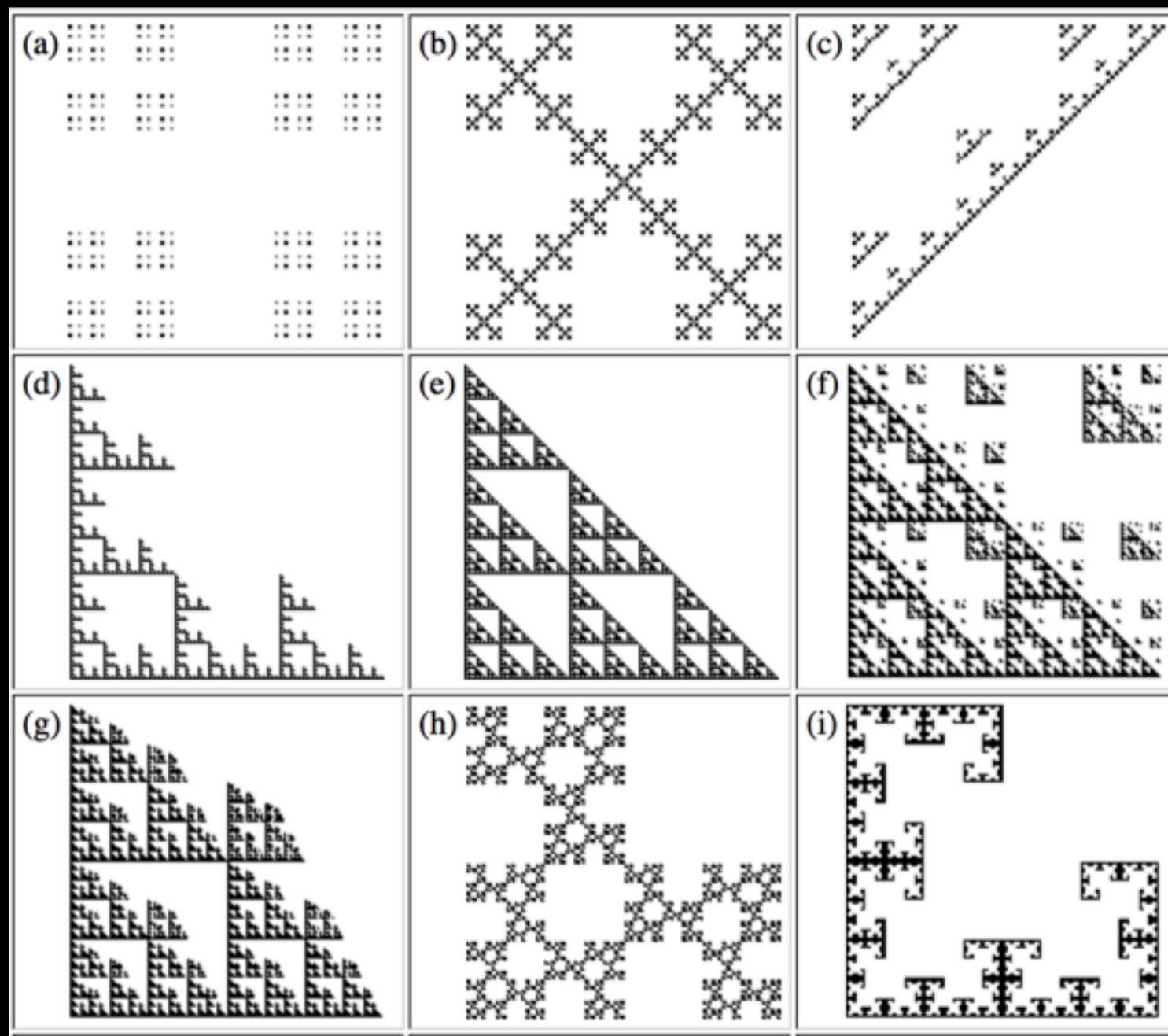


Filled Julia set: set of points z that stays bounded under $f(z) = z^2 + c$



Number of iterates to divergence

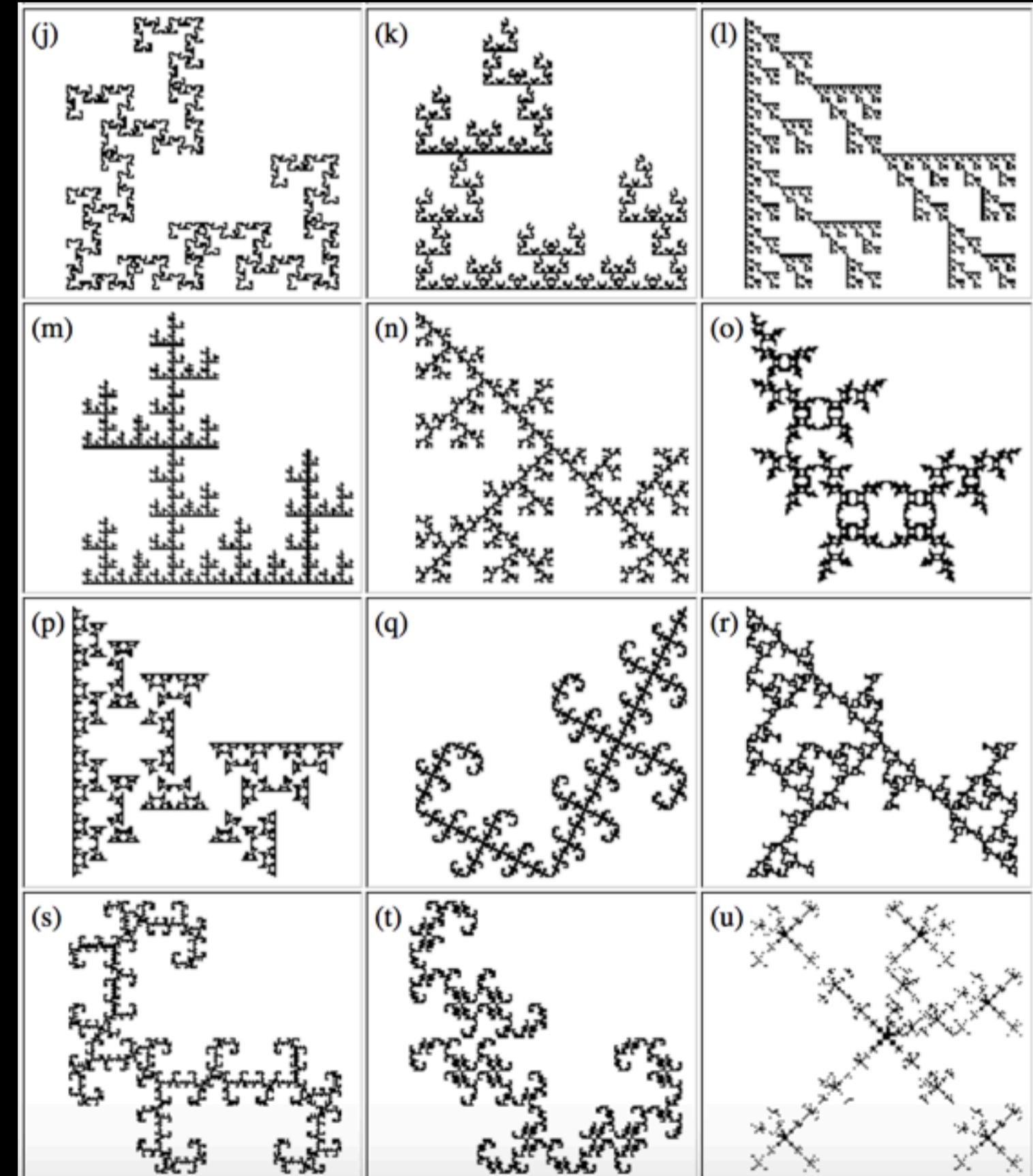
2. ITERATED FUNCTION SYSTEMS



A type of fractal

Examples from Fractal Worlds @ Yale

Leads to discussion of transformations and dimension
- even with high school geometry students. At the college level, can learn to compute fractal dimension and other dynamical concepts.

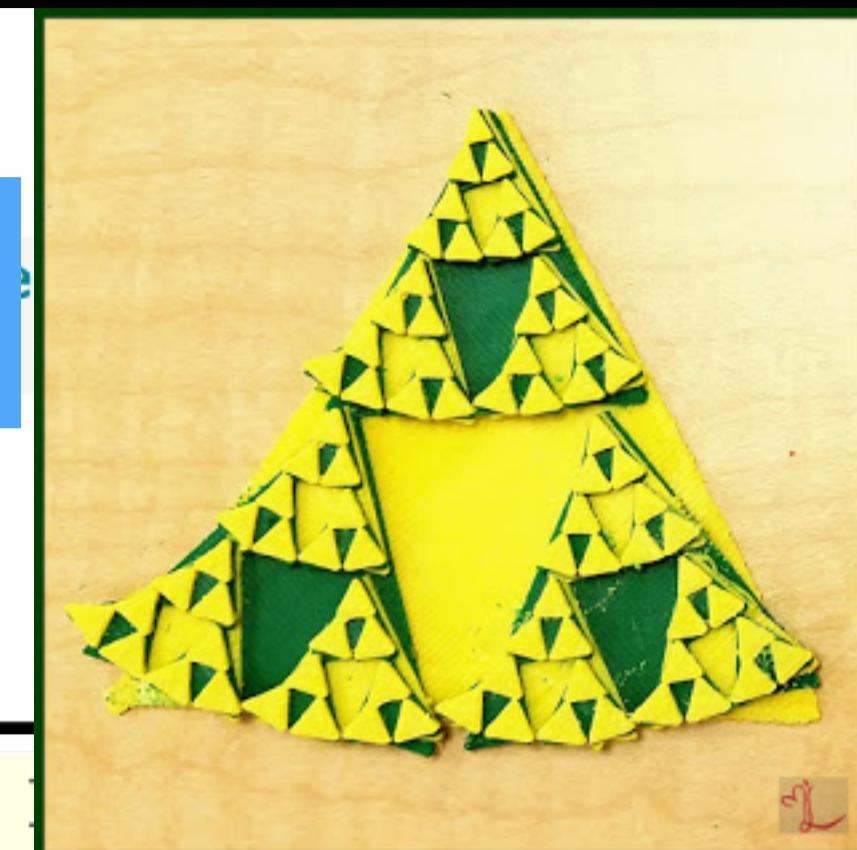


2. ITERATED FUNCTION SYSTEMS

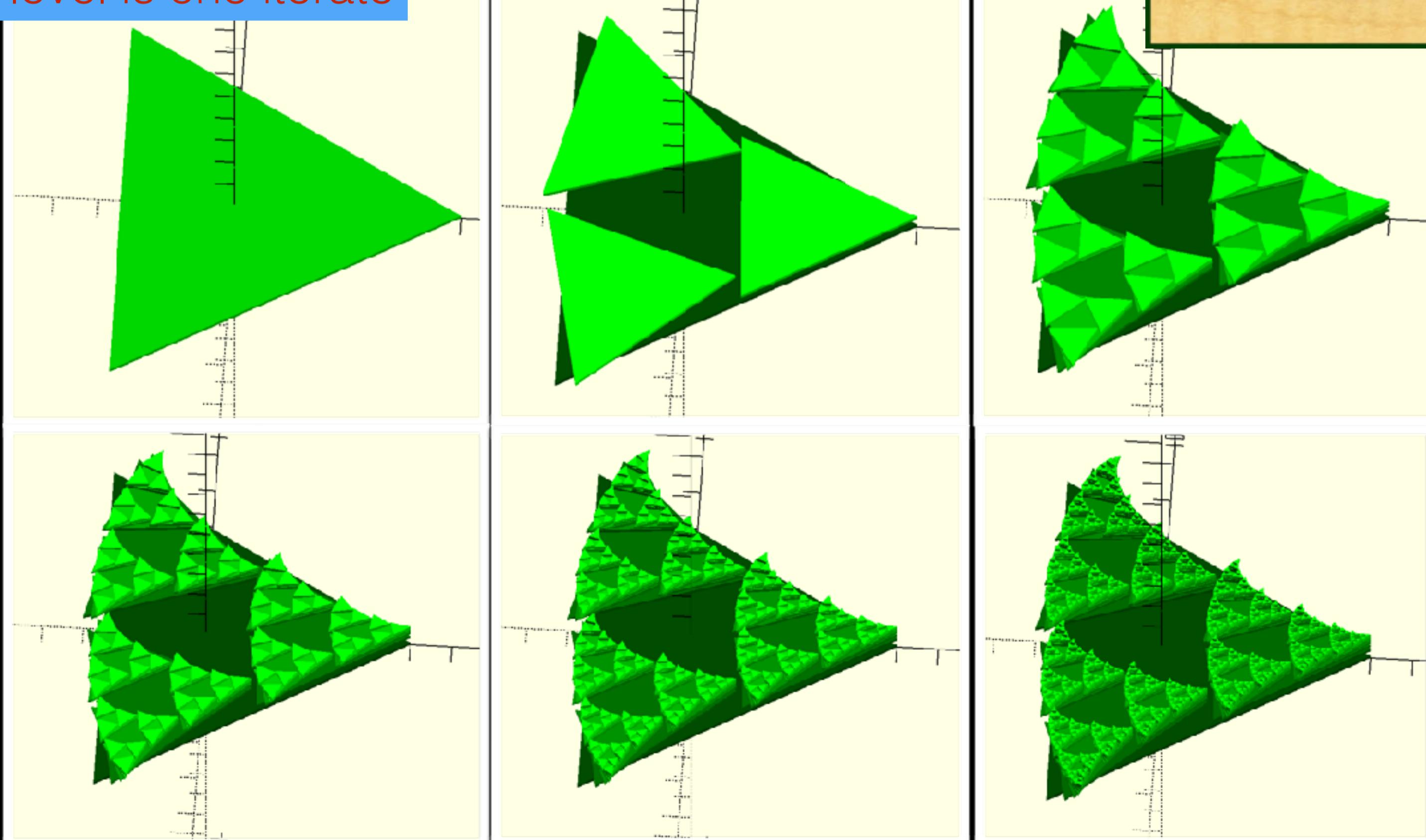
// We create fractals! Modify the numbers below to change the final look.

```
// Here we make the size and shape  
levels = 0; // number of levels for th  
you will WAIT!  
height = 1.0; // height of the first layer  
len = 50; // length of the first segment  
si = 3; // number of sides to the polygon of the starting shape
```

Generates a fractal using
OpenSCAD

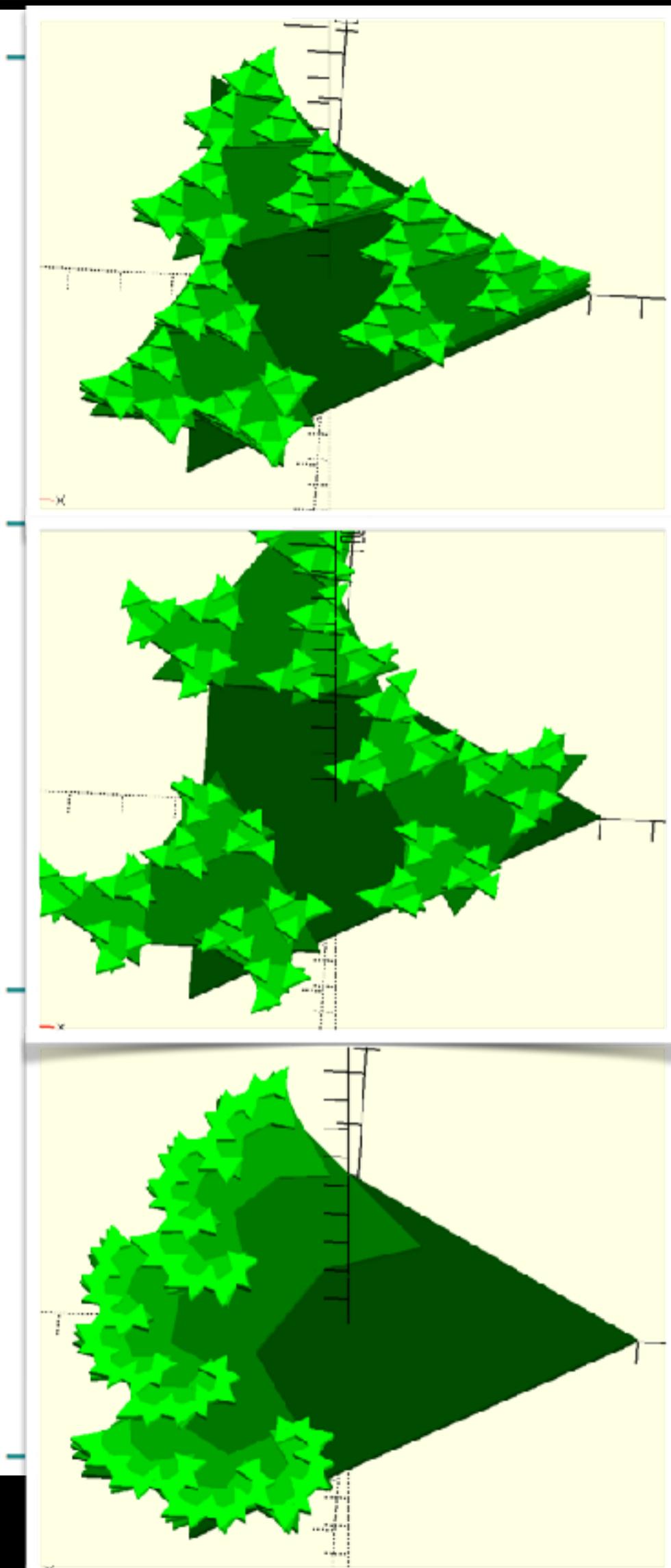


Each level is one iterate



2. ITERATED FUNCTION SYSTEMS

```
//-----  
// The first transformation  
scale1x = 0.5; // Scaling in direction x  
scale1y = 0.5; // Scaling in direction y  
theta1 = 11; // Angle of rotation in degrees  
trans1x = -0.25*len; // Translation in direction x  
trans1y = -0.4*len; // Translation in direction y  
//-----  
// The second transformation  
scale2x = 0.5; // Scaling in direction x  
scale2y = 0.45; // Scaling in direction y  
theta2 = 3; // Angle of rotation in degrees  
trans2x = 0.5*len; // Translation in direction x  
trans2y = 0*len; // Translation in direction y  
//-----  
// The third transformation  
scale3x = 0.5; // Scaling in direction x  
scale3y = 0.53; // Scaling in direction y  
theta3 = -14; // Angle of rotation in degrees  
trans3x = -0.25*len; // Translation in direction x  
trans3y = 0.43*len; // Translation in direction y  
//-----
```



parameters control transformation

3. CHAOTIC ATTRACTORS

```
In[44]:= rho = 28; sig = 10; beta = 8 / 3;
```

```
TubeThickness = 0.52;
```

```
Tmax = 50;
```

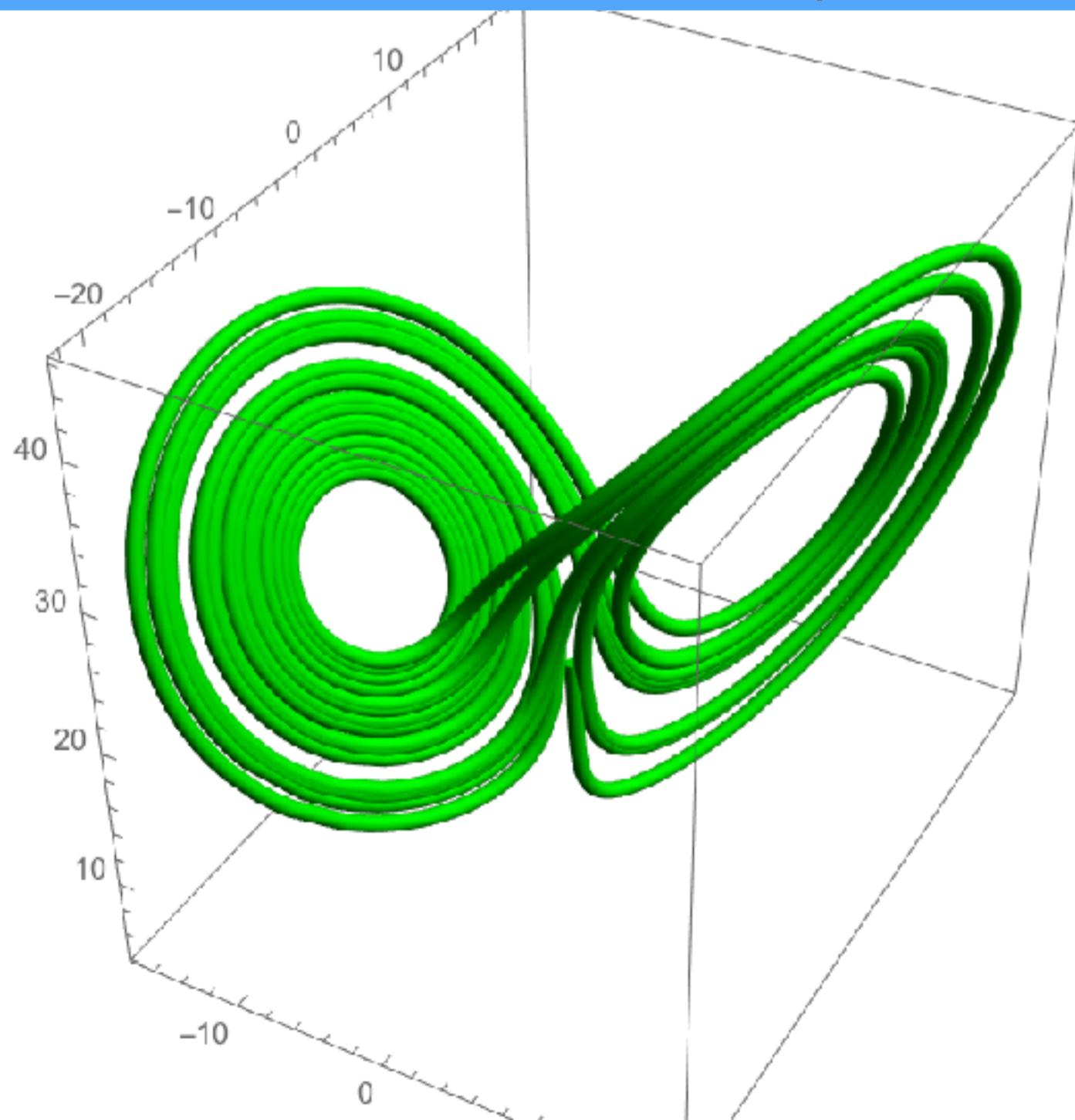
```
xinit = 11.13261;
```

```
yinit = 17.5124;
```

```
zinit = 21.0398;
```

```
In[48]:= q = NDSolve[{x'[t] == (sig*(y[t] - x[t])), y'[t] == (x[t]*(rho - z[t]) - y[t]), z'[t] == (x[t]*y[t] - beta*z[t]), x[0] == xinit, y[0] == yinit, z[0] == zinit}, {x, y, z}, {t, 0, Tmax}, MaxSteps -> Infinity];
```

This topic involves understanding of solutions to differential equations. It is a good lecture demonstration for an first ODE class, but further discussion would require learning about chaos and its properties.



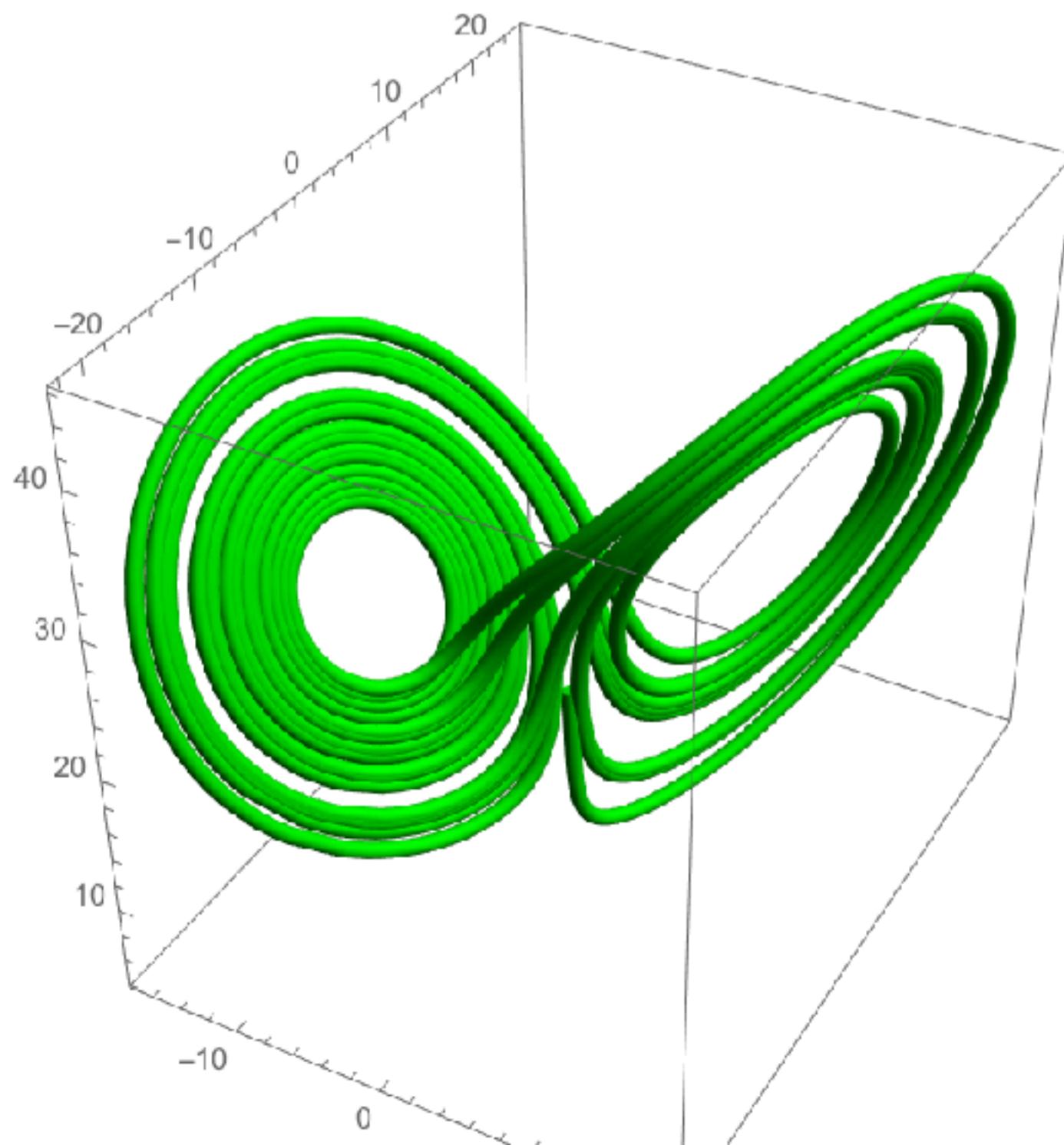
3. CHAOTIC ATTRACTORS

```
In[44]:= rho = 28; sig = 10; beta = 8 / 3;  
TubeThickness = 0.52;  
Tmax = 50;  
xinit = 11.13261;  
yinit = 17.5124;  
zinit = 21.0398;
```



```
In[48]:= q = NDSolve[{x'[t] == (sig*(y[t] - x[t])), y'[t] == (x[t]*(rho - z[t]) - y[t]), z'[t] == (x[t]*y[t] - beta*z[t])},  
x[0] == xinit, y[0] == yinit, z[0] == zinit}, {x, y, z}, {t, 0, Tmax}, MaxSteps -> Infinity];
```

```
In[49]:= fig1 = ParametricPlot3D[Evaluate[{x[t], y[t], z[t]} /. q], {t, 5, Tmax/2},  
PlotStyle -> {Tube[TubeThickness, PlotPoints -> Tmax], Green}, PlotRange -> All];  
Show[fig1]
```



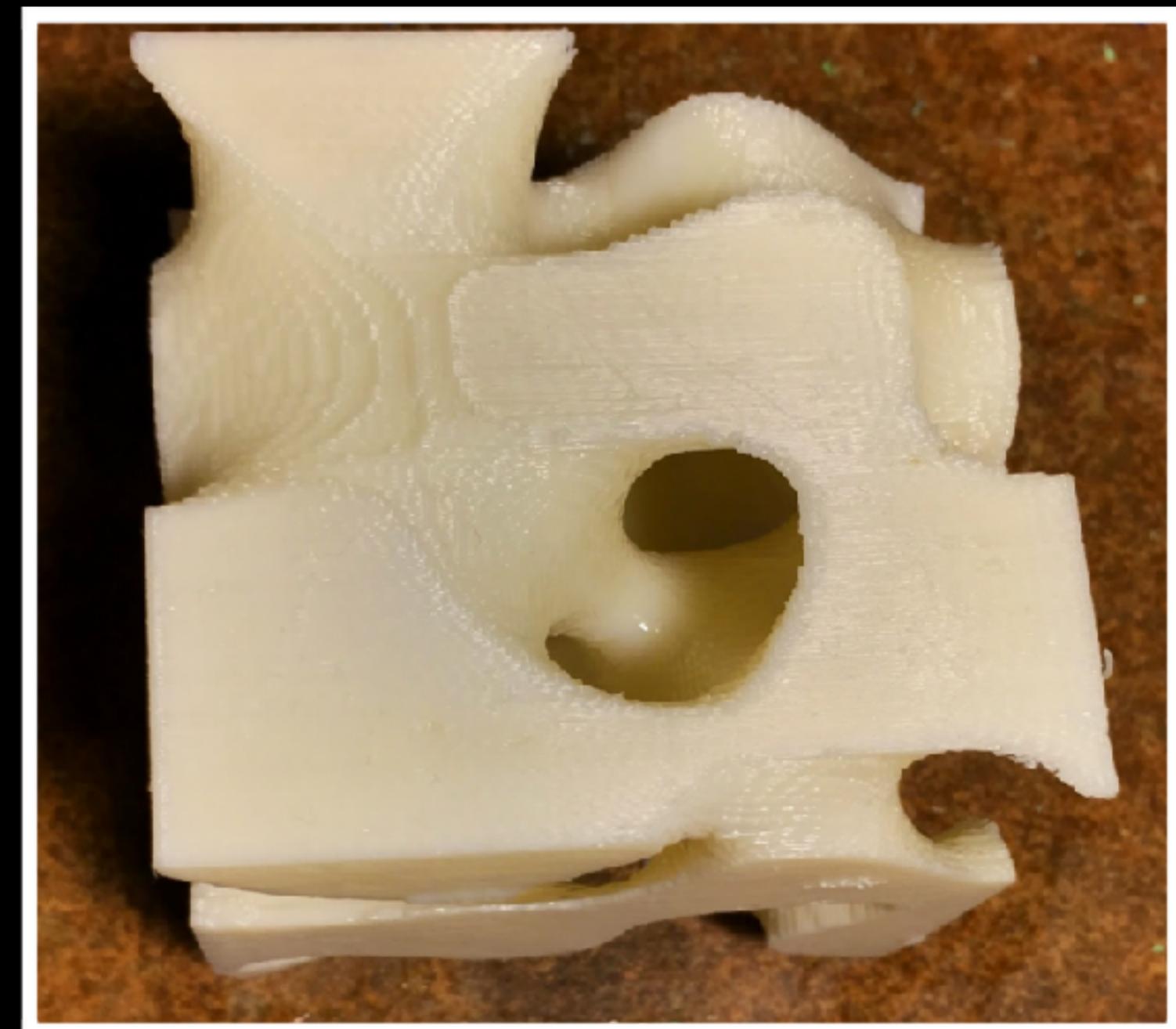
Mathematica NDSolve solves a differential equation. We put a Tube around the solution curve to make it 3D.

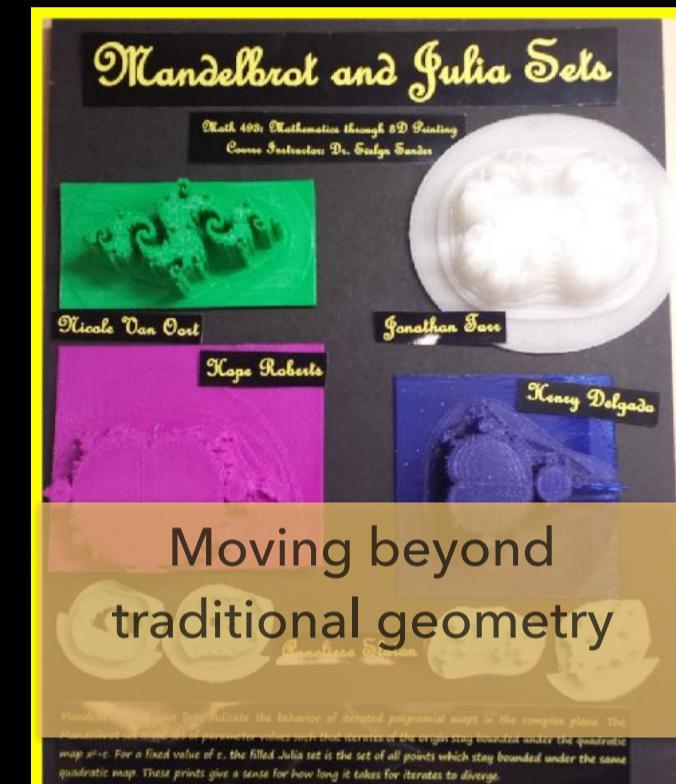
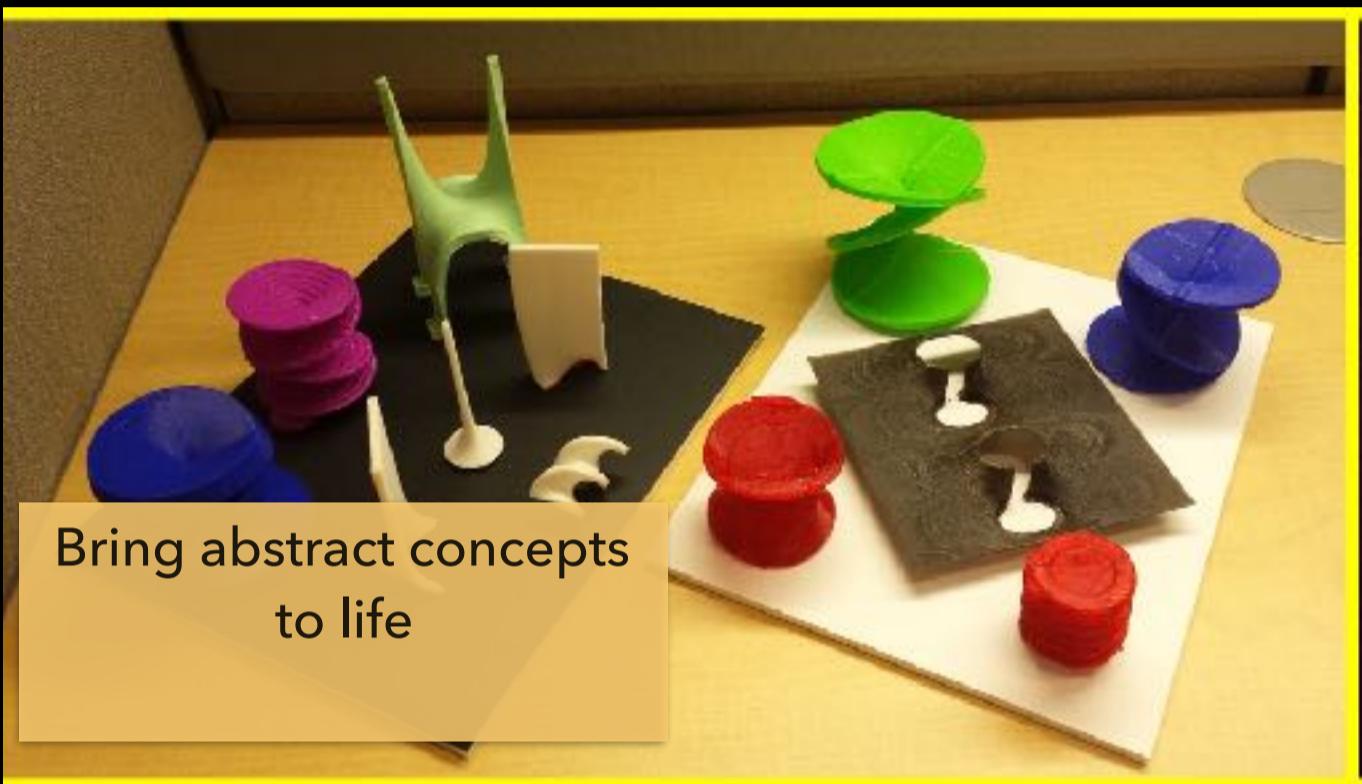
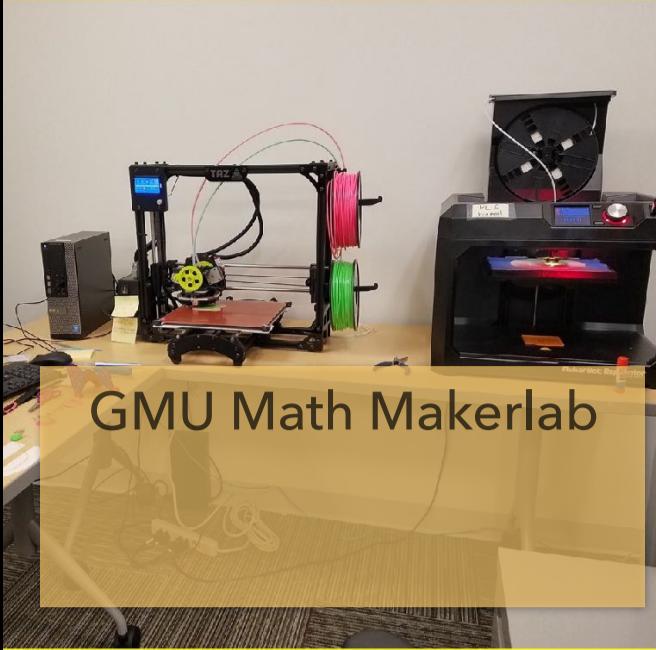
Number of iterates
to divergence

4. EVOLUTION EQUATIONS

Computation beyond the capabilities of a standard interpreted code language. Generated by solving a partial differential equation using C++ code. The data is a set of points in a solid set. Create a mesh from data using ParaView. Printed with dissolvable filament.

Spinodal decomposition for the Cahn-Hilliard equation.





Dynamical systems and chaos
Evelyn Sander esander@gmu.edu
GMU Math Makerlab
<http://gmumathmaker.blogspot.com>



SPECIAL THANKS TO RATNA KHATRI

THANK YOU!

