ESEN YEL

Website: esenyel.github.io/personal Email address: esenyel@virginia.edu

EDUCATION

Ph.D., Systems Engineering

2016 - 2021 (expected)

University of Virginia

Charlottesville, VA

Dissertation: Online Predictive Monitoring and Planning for Safe Autonomous Robotic Systems

M.S., Electrical and Electronics Engineering

2014 - 2016

Bogazici University

Istanbul, Turkey

Thesis: Appearance-based Self Localization and Navigation Using Place Memory

B.S., Electrical and Electronics Engineering

2009 - 2014

Bogazici University, Istanbul, Turkey

RESEARCH EXPERIENCE

Graduate Research Assistant

2016 - Current

University of Virginia

Charlottesville, VA

Advisor: Nicola Bezzo

Graduate Research Assistant

2014 - 2016

Bogazici University

Istanbul, Turkey

Advisor: H. Işıl Bozma

RESEARCH INTERESTS

- Assured autonomy Safe motion planning Reachability analysis Machine learning
- Runtime monitoring and recovery Self-triggered scheduling Unmanned aerial vehicles

PUBLICATIONS

Journal and Magazine Articles

- E. Yel, T. X. Lin, N. Bezzo, "Computation-Aware Adaptive Planning and Scheduling for Safe Unmanned Airborne Operations" Journal of Intelligent and Robotic Systems, 2020 (impact factor: 2.259)
- E. Yel, T. Carpenter, C. di Franco, R. Ivanov, Y. Kantaros, I. Lee, J. Weimer, N. Bezzo, "Assured Run-time Monitoring and Planning: Towards Verification of Deep Neural Networks for Safe Autonomous Operations" Robotics and Automation Magazine, Special Issue on Deep Learning and Machine Learning in Robotics, 2020 (impact factor: 4.250)

Conference Papers

- E. Yel, N. Bezzo, "GP-based Runtime Planning, Learning, and Recovery for Safe UAV Operations under Unforeseen Disturbances" IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2020
- E. Yel and N. Bezzo, "Fast Run-time Monitoring, Replanning, and Recovery for Safe Autonomous System Operations" 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Macau, China, pp. 1661-1667.
- E. Yel, T. X. Lin and N. Bezzo, "Self-triggered Adaptive Planning and Scheduling of UAV Operations," IEEE International Conference on Robotics and Automation (ICRA), Brisbane, 2018
- T. X. Lin, E. Yel and N. Bezzo, "Energy-aware Persistent Control of Heterogeneous Robotic Systems," American Control Conference (ACC), Milwaukee, WI, 2018
- E. Yel, T. X. Lin and N. Bezzo, "Reachability-based self-triggered scheduling and replanning of UAV operations," NASA/ESA Conference on Adaptive Hardware and Systems (AHS), Pasadena, CA, 2017, pp. 221-228.

Workshop and Symposium Papers

- E. Yel and N. Bezzo, "Reachability-based Adaptive UAV Scheduling and Planning in Cluttered and Dynamic Environments" ICRA Workshop on Informative Path Planning and Adaptive Sampling, Brisbane, 2018
- E. Yel, T. X. Lin and N. Bezzo, "Reachability-based Self-triggered UAV Motion Planning," International Symposium on Aerial Robotics, Philadelphia, PA, 2017
- E. Yel and H.I. Bozma, "Verifying the Recognized Place Through Localization," IROS Workshop on Introspective Methods for Reliable Autonomy, Vancouver 2017

TEACHING EXPERIENCE

Graduate Teaching Assistantship	Bogazici University
System Dynamics and Control (Discussion and Grading TA)	Spring 2015, Spring 2016
Control Technology and Design (Lab and Grading TA)	Fall 2015
Introduction to Electrical Engineering (Discussion TA)	Fall 2015
Undergraduate Teaching Assistantship	Bogazici University
System Dynamics and Control (Discussion TA)	Spring 2014
Orientation to Electrical Engineering (Lab TA)	Fall 2013

A

WARDS	
Link Lab Student Seminar Award Link Lab, University of Virginia	2020
SDC Travel Award IEEE/RSJ International Conference on Intelligent Robots and Systems	2019
Ruthie Oxford Memorial Award - Promising Graduate Student University of Virginia, Department of Systems and Information Engineering	2018
Travel Award IEEE International Conference on Robotics and Automation PhD Forum	2018
Dean's Honor List Bogazici University, School of Engineering	2014

INVITED PRESENTATIONS

	0000
UVA Link Lab Student Seminars, Talk	2020
UVA Link Lab Student Flash Talks, Talk	2020
UVA ESE Graduate Symposium, Poster	2018, 2020
ICRA PhD Forum, Poster	2018
UVA ECE Student Research Session, Poster	2017

PROFESSIONAL ACTIVITIES AND LEADERSHIP

Professional Service

Co-organizer, UVA INFORMS Alumni Panel 2020
President, UVA Student Chapter of INFORMS 2020
Vice President, UVA Student Chapter of INFORMS 2018-2019
Session Chair, IEEE Systems and Information Engineering Design Symposium 2019

Review Activities

IEEE International Conference on Robotics and Automation (ICRA) $\,$

IEEE/RSJ International Conference on Intelligent Robots (IROS)

IEEE Robotics and Automation Letters (RA-L)

Conference on Robot Learning (CoRL)

IEEE Conference on Decision and Control (CDC)

American Control Conference (ACC)

ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS) (subreviewer)

International Conference on Runtime Verification (RV)

IEEE Computer Magazine

Mentorship Activities

Graduate Mentor, Society of Women Engineers at University of Virginia

2017

PROFESSIONAL EXPERIENCE

Engineering Intern	Aug. 2013 - Sept. 2013
RMK Marine	Istanbul, Turkey
-Automation systems analysis of coast guard ships	

Engineering Intern

Turkish Aerospace Industries
-Automation system modeling for missile fuses

June 2013 - July 2013

Ankara, Turkey

Engineering InternLely Industries

June 2012 - July 2012
Istanbul, Turkey

-Vision-based object recognition algorithm for an agricultural cleaning robot

SKILLS

Programming: C/C++, ROS, Matlab, Python Tools: Latex, Microsoft Office, HitFilm (video editor) Languages: Turkish (Native), English (Proficient)