

ESEN YEL

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PROFESSIONAL EXPERIENCE

Rensselaer Polytechnic Institute Position: Assistant Professor Department of Electrical, Computer and Systems Engineering	Troy, NY 2024 – Present
Stanford University Position: Postdoctoral Scholar Affiliations: Stanford Intelligent Systems Lab (SISL), Stanford Center for AI Safety Advisor: Mykel Kochenderfer	Stanford, CA 2021 – 2023
University of Virginia Position: Graduate Research Assistant Affiliations: Autonomous Mobile Robots Lab, Link Lab Advisor: Nicola Bezzo	Charlottesville, VA 2016 – 2021
Bogazici University Position: Graduate Research Assistant Affiliations: Intelligent Systems Lab (ISL) Advisor: H. Işıl Bozma	Istanbul, Turkey 2014 – 2016

EDUCATION

University of Virginia Ph.D., Systems Engineering Dissertation: <i>Online predictive monitoring and proactive planning for safe autonomous robot operations</i>	Charlottesville, VA 2021
Bogazici University M.S., Electrical and Electronics Engineering Thesis: <i>Appearance based self localization and navigation using place memory</i>	Istanbul, Turkey 2016
B.S., Electrical and Electronics Engineering Graduated with High Honors Certificate	2014

RESEARCH INTERESTS

The main objective of my research is to achieve safe, generalizable, and trustworthy autonomy for systems under uncertainty. My research uses concepts from reachability analysis, machine learning, verification, motion planning, and transfer learning to develop safe planning and runtime monitoring techniques.

AWARDS & HONORS

Rising Stars in Electrical Engineering and Computer Science	2022
Link Lab Outstanding Graduate Research Award Link Lab, University of Virginia “This award was established as a way for faculty to recognize Link Lab students who have demonstrated excellence in research during the academic year.”	2021
Robotics: Science and Systems (RSS) Pioneers Workshop Participant “RSS Pioneers brings together a cohort of the world’s top early-career researchers.”	2021
Link Lab Student Seminar Award Link Lab, University of Virginia	2020

“The Link Lab Graduate Seminar provides a prestigious honor and award for a PhD student to showcase the highest quality research happening at Link Lab conveying impact and relevance in the CPS field”

Ruthie Oxford Memorial Award

2018

University of Virginia, Department of Systems and Information Engineering

PUBLICATIONS

Preprint

- H. Delecki, M. Vazquez-Chanlatte, **E. Yel**, K. Wray, T. Arnon, S. Witwicki, M. J. Kochenderfer, “Entropy-regularized Point-based Value Iteration”, arXiv preprint arXiv:2402.09388, 2024.

Journal and Magazine Articles

- N. Rober, S. M. Katz, C. Sidrane, **E. Yel**, M. Everett, M. J. Kochenderfer, and J. P. How. “Backward reachability analysis of neural feedback loops: Techniques for linear and nonlinear systems”, IEEE Open Journal of Control Systems, vol. 2, pp. 108-124, 2023.
- **E. Yel***, S. Gao*, N. Bezzo, “Meta-learning-based proactive online planning for UAVs under degraded conditions”, (*equal contribution), Robotics and Automation Letters (RA-L), 2022, vol. 7, no. 4, pp. 10320–10327.
- **E. Yel**, T. X. Lin, N. Bezzo, “Computation-aware adaptive planning and scheduling for safe unmanned airborne operations”, Journal of Intelligent and Robotic Systems, 2020, vol. 100, no. 2, pp. 575–596.
- **E. Yel**, T. Carpenter, C. di Franco, R. Ivanov, Y. Kantaros, I. Lee, J. Weimer, N. Bezzo, “Assured runtime monitoring and planning: Towards verification of neural networks for safe autonomous operations”, Robotics and Automation Magazine, June 2020, vol. 27, no. 2, pp. 102–116.

Conference Papers

- M. Toyungyernsub, **E. Yel**, J. Li, M. Kochenderfer, “Predicting future spatiotemporal occupancy grids with semantics for autonomous driving”, Intelligent Vehicles, 2024.
- S. M. Katz, A. L. Corso, **E. Yel**, and M. J. Kochenderfer, “Efficient Determination of Safety Requirements for Perception Systems”, IEEE/AIAA Digital Avionics Systems Conference (DASC), 2023, pp. 1-10
- A. Yildiz, **E. Yel**, A. Corso, K. Wray, S. Witwicki and M. J. Kochenderfer, “Experience filter: Transferring past experiences to unseen tasks or environments”, IEEE Intelligent Vehicles Symposium (IV), 2023.
- M. Toyungyernsub, **E. Yel**, J. Li, M. J. Kochenderfer, “Dynamics-aware spatiotemporal occupancy prediction in urban environments”, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2022, pp. 10836-10841.
- M. Cleaveland, **E. Yel**, Y. Kantaros, I. Lee, N. Bezzo, “Learning enabled fast planning and control in dynamic environments with intermittent information”, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2022, pp. 10290-10296.
- L. Kruse, **E. Yel**, R. Senanayake, M. J. Kochenderfer, “Uncertainty-aware online merge planning with learned driver behavior”, IEEE International Conference on Intelligent Transportation Systems (ITSC), 2022, pp. 1202-1207.
- **E. Yel**, N. Bezzo, “A meta-learning-based trajectory tracking framework for UAVs under degraded conditions”, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2021, pp. 6884–6890.
- **E. Yel**, N. Bezzo, “GP-based runtime planning, learning, and recovery for safe UAV operations under unforeseen disturbances”, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2020, pp. 2173–2180.

- E. Yel and N. Bezzo, “Fast run-time monitoring, replanning, and recovery for safe autonomous system operations”, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2019, pp. 1661–1667.
- E. Yel, T. X. Lin and N. Bezzo, “Self-triggered adaptive planning and scheduling of UAV operations”, IEEE International Conference on Robotics and Automation (ICRA), 2018, pp. 7518–7524.
- T. X. Lin, E. Yel and N. Bezzo, “Energy-aware persistent control of heterogeneous robotic systems”, Annual American Control Conference (ACC), 2018, pp. 2782–2787.
- E. Yel, T. X. Lin and N. Bezzo, “Reachability-based self-triggered scheduling and replanning of UAV operations”, NASA/ESA Conference on Adaptive Hardware and Systems (AHS), 2017, pp. 221–228.

Workshop Papers

- E. Yel and N. Bezzo, “Reachability-based adaptive UAV scheduling and planning in cluttered and dynamic environments”, ICRA Workshop on Informative Path Planning and Adaptive Sampling, Brisbane, 2018.
- E. Yel and H.I. Bozma, “Verifying the recognized place through localization”, IROS Workshop on Intropective Methods for Reliable Autonomy, Vancouver 2017.

TEACHING EXPERIENCE/TRAINING

Instructor	Rensselaer Polytechnic Institute
Decision Making under Uncertainty (ECSE 4964/6964, CSCI 6968, ISYE 6964)	Fall 2024
Robotics II (ECSE 4490/6490, CSCI 4969/6969, MANE 4963/6963)	Spring 2024
Guest Lectures	Stanford University
Engineering Design Optimization	Spring 2023
• Gave a guest lecture on linear constrained optimization.	
Decision Making under Uncertainty	Winter 2023
• Gave two guest lectures on representation and inference.	
Advanced Topics in Sequential Decision Making	Winter 2022
• Gave a guest lecture on applications areas of partially observable Markov decision processes.	
Pedagogical Training	
CIRTL@Stanford Teaching Certificate Program (Associate Level)	2023
Stanford Scientific Teaching Summer Institute	2022
• Attended a 3-day workshop to explore the core principles of Scientific Teaching (inclusion and equity, active learning, assessment, and effective lesson planning).	
Graduate Teaching Assistantship	Bogazici University
System Dynamics and Control	Spring 2015, Spring 2016
Control Technology and Design	Fall 2015
Introduction to Electrical Engineering	Fall 2015
• Teaching responsibilities included grading and leading lab and discussion sessions.	
Undergraduate Student Assistantship	Bogazici University
System Dynamics and Control (Assisted discussion sessions)	Spring 2014
Orientation to Electrical Engineering (Assisted lab sessions)	Fall 2013

MENTORSHIP EXPERIENCE

Rensselaer Polytechnic Institute

- *Doctoral Students*
Mehmet Taha Bekar *Fall 2024 - Present*
Jainik Mehta *Fall 2024 - Present*
- *Masters Student Experience*
Andy Ma, World model representations *2024*
- *Undergraduate Student Experience*
Curran Flaunders, Controller design for aerial vehicles *2024*

Stanford University

- *Graduate Student Research*
Anil Yildiz, Transfer learning and validation for autonomous driving tasks *2021 – 2023*
Liam Kruse, Safe planning for autonomous vehicles *2021 – 2023*
Dylan Asmar, Out-of-distribution detection *2022 – 2023*
Sydney Katz, Backward reachability for nonlinear systems *2022 – 2023*
Maneekwan Toyungyernsub, Occupancy grid prediction *2021 – 2022*
Alexandros Tzikas, Trajectory verification for autonomous driving *2022*
Chelsea Sidrane, Backward reachability for nonlinear systems *2022*
- *Stanford Undergraduate Research Fellowship (SURF)* *Summer 2022*
Research mentor for an 8-week program to promote diversity within the engineering and science student body in the USA. I advised an undergraduate student on her research topic, monitored her research progress, and advised research alongside a graduate student. Student: Michelle Ho.
- *Undergraduate Student Research*
Ellie Talius, Trajectory verification for autonomous driving *2022*

University of Virginia

- *Graduate Mentor for Capstone Project* *Spring 2021*
Co-mentoring four undergraduate students on a robot navigation project
- *Graduate Mentor for Society of Women Engineers* *Spring 2017*
Graduate student mentor for undergraduate engineering students associated with the Society of Women Engineers. This mentorship program involved helping a student navigate her early engineering education and career.

PRESENTATIONS

Ford Otosan, Talk	2024 Stanford Center for AI Safety Workshop, Talk	2023
Bay Area Robotics Symposium, Poster		2022
Stanford SystemX 2021 Fall Conference, Poster		2021
UVA Link Lab Student Seminars, Talk		2020
UVA Link Lab Student Flash Talks, Talk		2020
UVA ESE Graduate Symposium, Poster		2018, 2020
ICRA PhD Forum, Poster		2018
UVA ECE Student Research Session, Poster		2017

PROFESSIONAL ACTIVITIES

Journal, Conference and Workshop Service

- Associate Editor, IEEE Conference on Automation Science and Engineering (CASE) *2024*

Editorial Board Associate Chair, Journal of Artificial Intelligence Research (JAIR)	<i>2023-Present</i>
Co-chair, Learning for Dynamics & Control Conference (L4DC)	<i>2022</i>
Program Committee Member, RSS Pioneers Workshop	<i>2022</i>
Session Co-chair, IEEE/RSJ International Conference on Intelligent Robots (IROS)	<i>2021</i>
Session Chair, IEEE Systems and Information Engineering Design Symposium	<i>2019</i>

Internal Service

Stanford University

Member, Stanford Center for AI Safety Working Group	<i>2022-2023</i>
Moderator, Stanford Center for AI Safety Workshop Industry Panel	<i>2023</i>

University of Virginia

Panelist, UVA Link Lab Student Panel: Writing and Publishing in Graduate School	<i>2021</i>
Co-organizer, UVA Systems Engineering Alumni Panel	<i>2020</i>

Review Activities

Journals

IEEE Robotics and Automation Letters (RA-L)
Journal of Artificial Intelligence Research (JAIR)
Journal of Aerospace Information Systems
IEEE Computer Magazine

Conferences

IEEE/RSJ International Conference on Intelligent Robots (IROS)
Conference on Robot Learning (CoRL)
IEEE Conference on Decision and Control (CDC)
American Control Conference (ACC)
IEEE International Conference on Robotics and Automation (ICRA)
ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS)
IEEE International Conference on Intelligent Transportation Systems (ITSC)
AAAI Conference on Artificial Intelligence